

IX. Basic Implementation Techniques and Fast Algorithm

◎ 9-A 快速演算法設計的原則

- **Fast Algorithm Design**

- Goals: Saving Computational Time**

- Number of Additions

- Number of Multiplications

- Number of Time Cycles

- Saving the Hardware Cost for Implementation**

- Saving the buffer size

- Repeated Using a Structure

Four important concepts that should be learned from fast algorithm design:

(1) N -point DFT

N is not limited to 2^k , complexity: $\Theta(N \log N)$

(2) Complexity of LTI Systems

LTI = convolution
= 3 FTs

$y[n] = x[n] * h[n] = \text{IDFT}(\text{DFT}(x[n]) \text{DFT}(h[n]))$
complexity $\Theta(N \log N)$ $\xrightarrow{\text{reduced by sectioned convolution}}$ $\Theta(N)$

(3) Replacement of DFTs

(4) Simplification Techniques

discrete and linear

For an $M \times N$ matrix operation, MN multiplications and $M(N-1)$ additions are required.

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_M \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \cdots & \cdots & a_{1N} \\ a_{21} & a_{22} & \cdots & \cdots & a_{2N} \\ \vdots & \vdots & \ddots & & \vdots \\ \vdots & \vdots & & \ddots & \vdots \\ a_{M1} & a_{M2} & \cdots & \cdots & a_{MN} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix}$$

$$\begin{array}{r} 23 \\ 34 \\ \hline 92 \\ 69 \\ \hline 782 \end{array}$$

$$y_m = a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mN}x_N \quad N \text{ MULs, } N-1 \text{ ADDs}$$

$$m = 1, 2, \dots, M \quad \text{total: } MN \text{ MULs, } M(N-1) \text{ ADDs}$$

$$(a + jb)(c + jd) = \overset{1}{a}c - \overset{2}{b}d + j(\overset{3}{a}d + \overset{4}{b}c)$$

1 complex MUL = 4 real MULs

◎ 9-B 對於簡單矩陣快速演算法的設計

如何簡化下面四個運算

$$y_1 = [a \ 2a] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \checkmark$$

$$(1) y_1 = ax_1 + 2ax_2 = a(x_1 + 2x_2)$$

1 MUL, 1 ADD

$$(2) \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} a & a \\ a & a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

1 MUL, 1 ADD

$$(3) \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} a & b \\ b & a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

2 MULs, 4 ADDs

$$(4) \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} a & b \\ c & a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

3 MULs, 3 ADDs

trivial multiplications
 $x \pm 2^k$ (k is some integer)
 $x \pm j2^k$

$$y_1 = ax_1 + ax_2 = a(x_1 + x_2) \quad \checkmark$$

$$y_2 = y_1$$

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} \frac{a+b}{2} & \frac{a+b}{2} \\ \frac{a+b}{2} & \frac{a+b}{2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} \frac{a-b}{2} & -\frac{a-b}{2} \\ -\frac{a-b}{2} & \frac{a+b}{2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\text{If } \begin{bmatrix} y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} \frac{a+b}{2} & \frac{a+b}{2} \\ \frac{a+b}{2} & \frac{a+b}{2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \begin{bmatrix} y_5 \\ y_6 \end{bmatrix} = \begin{bmatrix} \frac{a-b}{2} & -\frac{a-b}{2} \\ -\frac{a-b}{2} & \frac{a+b}{2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\textcircled{1} y_3 = \frac{a+b}{2}(x_1 + x_2) \quad \textcircled{2} y_5 = \frac{a-b}{2}(x_1 - x_2) \quad \textcircled{3} y_1 = y_3 + y_5$$

$$y_4 = y_3$$

$$y_6 = -y_5$$

$$y_2 = y_4 + y_6$$

$\frac{a+b}{2}, \frac{a-b}{2}$ can be calculated in prior.

(4)

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} a & b \\ c & a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} a & a \\ a & a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 & b-a \\ c-a & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} a & a \\ a & a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \begin{bmatrix} z_3 \\ z_4 \end{bmatrix} = \begin{bmatrix} 0 & b-a \\ c-a & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

Case 2

(i) $z_1 = a[x_1 + x_2], \quad z_2 = z_1$

(ii) $z_3 = (b-a)x_2, \quad z_4 = (c-a)x_1$

(iii) $y_1 = z_1 + z_3, \quad y_2 = z_2 + z_4$

(5) $\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} a & b \\ a & b \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad y_1 = a(x_1 + x_2) \quad 2 \text{ MULs}, 1 \text{ ADD}$

(6) $\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} a & a \\ b & -b \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad y_1 = a(x_1 + x_2) \quad 2 \text{ MULs}, 2 \text{ ADD}$

(7) $\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} a & a \\ a & b \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \text{MUL? ADD?}$

問題思考：如何對 complex number multiplication 來做 implementation ?

$$(a + jb)(c + jd) = \underbrace{ac - bd}_e + j \underbrace{(ad + bc)}_f$$

$$\begin{bmatrix} e \\ f \end{bmatrix} = \begin{bmatrix} c & -d \\ d & c \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} c & c \\ c & c \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} + \begin{bmatrix} 0 & -d-c \\ d-c & 0 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

If $\begin{bmatrix} e_1 \\ f_1 \end{bmatrix} = \begin{bmatrix} c & c \\ c & c \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$, $\begin{bmatrix} e_2 \\ f_2 \end{bmatrix} = \begin{bmatrix} 0 & -d-c \\ d-c & 0 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$ 3 MULs, 5 ADDs

① $e_1 = c(a+b)$ ② $e_2 = (-d-c)b$ ③ $e = e_1 + e_2$
 $f_1 = e_1$ $f_2 = (d-c)a$ $f = f_1 + f_2$

If $c = d$

$$\begin{bmatrix} c & -c \\ c & c \end{bmatrix} = \begin{bmatrix} c & c \\ c & c \end{bmatrix} + \begin{bmatrix} 0 & 2c \\ 0 & 0 \end{bmatrix} \quad 2 \text{ MULs}$$

$$\begin{matrix} d = -c \\ \begin{bmatrix} c & c \\ -c & c \end{bmatrix} = \begin{bmatrix} c & c \\ c & c \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ -2c & 0 \end{bmatrix} \quad 2 \text{ MULs} \end{matrix}$$

◎ 9-C General Way for Simplifying Calculation

假設一個 $M \times N$ sub-rectangular matrix S 可分解為 column vector 及 row vector 相乘

$$S = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_M \end{bmatrix} [b_1 \quad b_2 \quad \cdots \quad b_N]$$

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} = S \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix}$$

$$\begin{cases} z = b_1 x_1 + b_2 x_2 + \cdots + b_N x_N \\ y_n = a_n z \end{cases}$$

若 $[a_1, a_2, \dots, a_M]^T$ 有 M_0 個相異的 non-trivial values

$$(a_m \neq \pm 2^k, \quad a_m \neq \pm 2^k a_h \text{ where } m \neq h)$$

$[b_1, b_2, \dots, b_N]$ 有 N_0 個相異的 non-trivial values

則 S 共需要 $M_0 + N_0$ 個乘法

$$\begin{bmatrix} z[1] \\ z[2] \\ \vdots \\ z[N] \end{bmatrix} = \mathbf{S} \begin{bmatrix} x[1] \\ x[2] \\ \vdots \\ x[N] \end{bmatrix} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_M \end{bmatrix} \begin{bmatrix} b_1 & b_2 & \cdots & b_N \end{bmatrix} \begin{bmatrix} x[1] \\ x[2] \\ \vdots \\ x[N] \end{bmatrix}$$

Step 1 $z_a = b_1 x[1] + b_2 x[2] + \dots + b_N x[N]$

Step 2 $z[1] = a_1 z_a, z[2] = a_2 z_a, \dots, z[N] = a_M z_a$

簡化理論的變型

$$\mathbf{S} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_M \end{bmatrix} \begin{bmatrix} b_1 & b_2 & \cdots & b_N \end{bmatrix} + \mathbf{S}_1$$

\mathbf{S}_1 也是一個 $M \times N$ matrix

若 \mathbf{S}_1 有 P_1 個值不等於 0, 則 \mathbf{S} 的乘法量上限為 $M_0 + N_0 + P_1$

$$\mathbf{S} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_M \end{bmatrix} \begin{bmatrix} b_1 & b_2 & \cdots & b_N \end{bmatrix} + \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_M \end{bmatrix} \begin{bmatrix} d_1 & d_2 & \cdots & d_N \end{bmatrix} + \mathbf{S}_1$$

以此類推

思考：對於如下的情形需要多少乘法

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} a & b & c & d \\ e & f & f & e \\ f & e & e & f \\ d & c & b & a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

6 MULs

$$\begin{bmatrix} y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} e & f \\ f & e \end{bmatrix} \begin{bmatrix} x_1 + x_4 \\ x_2 + x_3 \end{bmatrix}$$

Case 3, 2 MULs

$$y_1 = z_1 + z_3$$

$$y_4 = z_2 + z_4$$

$$\begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} a & d \\ d & a \end{bmatrix} \begin{bmatrix} x_1 \\ x_4 \end{bmatrix} \quad \text{Case 3, 2 MULs}$$

$$\begin{bmatrix} z_3 \\ z_4 \end{bmatrix} = \begin{bmatrix} b & c \\ c & b \end{bmatrix} \begin{bmatrix} x_2 \\ x_3 \end{bmatrix} \quad \text{Case 3, 2 MULs}$$

◎ 9-D Examples

$$\begin{bmatrix} X[0] \\ X[1] \\ \vdots \\ X[N-1] \end{bmatrix} = \begin{bmatrix} F[m,n] \\ N \times N \text{ matrix} \end{bmatrix} \begin{bmatrix} X[0] \\ X[1] \\ \vdots \\ X[N-1] \end{bmatrix}, F[m,n] = e^{j \frac{2\pi mn}{N}}$$

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DFT: $X[m] = \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi mn}{N}}$
 N^2 complex MULs

Without any simplification, the DFT needs $4N^2$ real multiplications ($x[n]$ may be complex)

- 3×3 DFT 可以用特殊方法简化

$$\begin{matrix} & n & 0 & 1 & 2 \\ m & 0 & \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \\ & 1 & \begin{bmatrix} 1 & -1/2 & -1/2 \end{bmatrix} \\ & 2 & \begin{bmatrix} 1 & -1/2 & -1/2 \end{bmatrix} \end{matrix} + j \begin{bmatrix} 0 & 0 & 0 \\ 0 & -\sqrt{3}/2 & \sqrt{3}/2 \\ 0 & \sqrt{3}/2 & -\sqrt{3}/2 \end{bmatrix}$$

F_r
 $\cos(\frac{2\pi}{3}mn)$
 0 MUL

$j F_i$
 $-\sin(\frac{2\pi}{3}mn)$
 1 MUL

$$X = (F_r + j F_i) X$$

$$X = [X[0] \ X[1] \ \dots \ X[N-1]]^T$$

$$X = [X[0] \ X[1] \ \dots \ X[N-1]]^T$$

$$F_r[m,n] = \cos(\frac{2\pi mn}{N})$$

$$F_i[m,n] = -\sin(\frac{2\pi mn}{N})$$

$$m=0,1,\dots,N-1, \ n=0,1,\dots,N-1$$

$$X = (F_r + j F_i) (X_r + j X_i)$$

$$= F_r X_r - F_i X_i + j (F_r X_i + F_i X_r)$$

Number of MULs for F

$$= 2(\text{Number of MULs for } F_r + \text{Number of MULs for } F_i)$$

$$= 2(0+1) = 2 \text{ MULs}$$

$$\text{If } \begin{bmatrix} z_0 \\ z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & -a & a \\ 0 & a & -a \end{bmatrix} \begin{bmatrix} y_0 \\ y_1 \\ y_2 \end{bmatrix}$$

$$a = \frac{\sqrt{3}}{2}$$

$$z_0 = 0$$

$$z_1 = a(-y_1 + y_2)$$

$$z_2 = -z_1$$

- 5×5 DFT 的例子

$$\begin{array}{c}
 \text{real part} \\
 \text{imaginary part}
 \end{array}
 \begin{array}{c}
 n \ 0 \ 1 \ 2 \ 3 \ 4 \\
 m \ 0 \\
 1 \\
 2 \\
 3 \\
 4
 \end{array}
 \begin{bmatrix}
 1 & 1 & 1 & 1 & 1 \\
 1 & a & b & b & a \\
 1 & b & a & a & b \\
 1 & b & a & a & b \\
 1 & a & b & b & a
 \end{bmatrix}
 - j
 \begin{bmatrix}
 0 & 0 & 0 & 0 & 0 \\
 0 & c & d & -d & -c \\
 0 & d & -c & c & -d \\
 0 & -d & c & -c & d \\
 0 & -c & -d & d & c
 \end{bmatrix}
 \begin{array}{l}
 a = \cos(2\pi/5) \\
 b = \cos(4\pi/5) \\
 c = \sin(2\pi/5) \\
 d = \sin(4\pi/5)
 \end{array}$$

$$F_r = \cos\left(\frac{2\pi}{5}mn\right)$$

2 MULs

$$-F_i = \sin\left(\frac{2\pi}{5}mn\right)$$

3 MULs

$$2(2+3) = 10 \text{ MULs}$$

$$\text{If } \begin{bmatrix} z_0 \\ z_1 \\ z_2 \\ z_3 \\ z_4 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & a & b & b & a \\ 1 & b & a & a & b \\ 1 & b & a & a & b \\ 1 & a & b & b & a \end{bmatrix} \begin{bmatrix} y_0 \\ y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}$$

$$\text{If } \begin{bmatrix} z_5 \\ z_6 \\ z_7 \\ z_8 \\ z_9 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & c & d & -d & -c \\ 0 & d & -c & c & -d \\ 0 & -d & c & -c & d \\ 0 & -c & -d & d & c \end{bmatrix} \begin{bmatrix} y_0 \\ y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}$$

$$z_0 = y_0 + y_1 + y_2 + y_3 + y_4$$

$$z_5 = 0$$

$$\begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = y_0 + \begin{bmatrix} a & b \\ b & a \end{bmatrix} \begin{bmatrix} y_1 + y_4 \\ y_2 + y_3 \end{bmatrix}, \quad z_4 = z_1, \quad z_3 = z_2$$

Case 3, 2 MULs

$$\begin{bmatrix} z_6 \\ z_7 \end{bmatrix} = \begin{bmatrix} c & d \\ d & -c \end{bmatrix} \begin{bmatrix} y_1 - y_4 \\ y_2 - y_3 \end{bmatrix}, \quad z_8 = -z_7, \quad z_9 = -z_6$$

$$\text{Case 4, 3 MULs} \quad \begin{bmatrix} d & d \\ d & d \end{bmatrix} + \begin{bmatrix} c-d & 0 \\ 0 & -c-d \end{bmatrix}$$

$$\begin{bmatrix} y[0] \\ y[1] \\ y[2] \\ y[3] \\ y[4] \\ y[5] \\ y[6] \\ y[7] \end{bmatrix} = \begin{bmatrix} 0.3536 & 0.3536 & 0.3536 & 0.3536 & 0.3536 & 0.3536 & 0.3536 & 0.3536 \\ 0.4904 & 0.4157 & 0.2778 & 0.0975 & -0.0975 & -0.2778 & -0.4157 & -0.4904 \\ 0.4619 & 0.1913 & -0.1913 & -0.4619 & -0.4619 & -0.1913 & 0.1913 & 0.4619 \\ 0.4157 & -0.0975 & -0.4904 & -0.2778 & 0.2778 & 0.4904 & 0.0975 & -0.4157 \\ 0.3536 & -0.3536 & -0.3536 & 0.3536 & 0.3536 & -0.3536 & -0.3536 & 0.3536 \\ 0.2778 & -0.4904 & 0.0975 & 0.4157 & -0.4157 & -0.0975 & 0.4904 & -0.2778 \\ 0.1913 & -0.4619 & 0.4619 & -0.1913 & -0.1913 & 0.4619 & -0.4619 & 0.1913 \\ 0.0975 & -0.2778 & 0.4157 & -0.4904 & 0.4904 & -0.4157 & 0.2778 & -0.0975 \end{bmatrix} \begin{bmatrix} x[0] \\ x[1] \\ x[2] \\ x[3] \\ x[4] \\ x[5] \\ x[6] \\ x[7] \end{bmatrix}$$

觀察對稱性質之後，令

$$\begin{bmatrix} z[0] \\ z[1] \\ z[2] \\ z[3] \end{bmatrix} = \begin{bmatrix} x[0]+x[7] \\ x[1]+x[6] \\ x[2]+x[5] \\ x[3]+x[4] \end{bmatrix} \qquad \begin{bmatrix} z[4] \\ z[5] \\ z[6] \\ z[7] \end{bmatrix} = \begin{bmatrix} x[0]-x[7] \\ x[1]-x[6] \\ x[2]-x[5] \\ x[3]-x[4] \end{bmatrix}$$

Part 1:

$$\begin{bmatrix} y[0] \\ y[2] \\ y[4] \\ y[6] \end{bmatrix} = \begin{bmatrix} 0.3536 & 0.3536 & 0.3536 & 0.3536 \\ 0.4619 & 0.1913 & -0.1913 & -0.4619 \\ 0.3536 & -0.3536 & -0.3536 & 0.3536 \\ 0.1913 & -0.4619 & 0.4619 & -0.1913 \end{bmatrix} \begin{bmatrix} z[0] \\ z[1] \\ z[2] \\ z[3] \end{bmatrix}$$

$$\begin{bmatrix} z[0] \\ z[1] \\ z[2] \\ z[3] \end{bmatrix} = \begin{bmatrix} x[0]+x[7] \\ x[1]+x[6] \\ x[2]+x[5] \\ x[3]+x[4] \end{bmatrix}$$

Part 2:
$$\begin{bmatrix} y[1] \\ y[3] \\ y[5] \\ y[7] \end{bmatrix} = \begin{bmatrix} 0.4904 & 0.4157 & 0.2778 & 0.0975 \\ 0.4157 & -0.0975 & -0.4904 & -0.2778 \\ 0.2778 & -0.4904 & 0.0975 & 0.4157 \\ 0.0975 & -0.2778 & 0.4157 & -0.4904 \end{bmatrix} \begin{bmatrix} z[4] \\ z[5] \\ z[6] \\ z[7] \end{bmatrix}$$

$$\begin{bmatrix} z[4] \\ z[5] \\ z[6] \\ z[7] \end{bmatrix} = \begin{bmatrix} x[0]-x[7] \\ x[1]-x[6] \\ x[2]-x[5] \\ x[3]-x[4] \end{bmatrix}$$

[Ref] B. G. Lee, “A new algorithm for computing the discrete cosine transform,” *IEEE Trans. Acoust., Speech, Signal Processing*, vol. 32, pp. 1243-1245, Dec. 1984.

© 9-E Summary of the Complexity

- N -point DFT: $O(N \log_2 N)$
- N -point DCT, DST, DHT: $O(N \log_2 N)$
- Two-dimensional (2-D) $N_x \times N_y$ -point DFT: $O((N_x N_y) \log_2 (N_x N_y))$ **Why?**
- Convolution of an M -point sequence and an N -point sequence:

$O((M + N - 1) \log_2 (M + N - 1))$ when M/N and N/M are not large,

$O(N)$ when $N \gg M$ and M is a fixed constant.

$O(M)$ when $M \gg N$ and N is a fixed constant.

- 2-D Convolution of an $(M_x \times M_y)$ -point matrix and an $(N_x \times N_y)$ -point matrix:

$$O\left((M_x + N_x - 1)(M_y + N_y - 1)\log_2\left((M_x + N_x - 1)(M_y + N_y - 1)\right)\right)$$

when $M_x M_y / N_x N_y$ and $N_x N_y / M_x M_y$ are not large,

$$O(M_x M_y) \quad \text{when } M_x M_y \gg N_x N_y$$

$$O(N_x N_y) \quad \text{when } N_x N_y \gg M_x M_y,$$

and M_x, M_y are fixed constants.

X. Fast Fourier Transform

- C. S. Burrus and T. W. Parks, “DFT / FFT and convolution algorithms,” John Wiley and Sons, New York, 1985.
- R. E. Blahut, *Fast Algorithm for Digital Signal Processing*, Addison Wesley Publishing Company.

$$X[m] = \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi mn}{N}}$$

N -point Fourier Transform: 運算量為 N^2

FFT (with the Cooley Tukey algorithm): 運算量為 $M \log N$

要學到的概念：(1)快速演算法不是只有 Cooley Tukey algorithm

(2) 不是只有 $N = 2^k$ 有時候才有快速演算法

© 10-A Other DFT Implementation Algorithms

- ✓(1) Cooley-Tukey algorithm (Butterfly form)
- ✓(2) Radix-4, 8, 16, Algorithms
- ✓(3) Prime Factor Algorithm
- (4) Goertzel Algorithm
- (5) Chirp Z transform (CZT)
- (6) Winograd algorithm

Reference

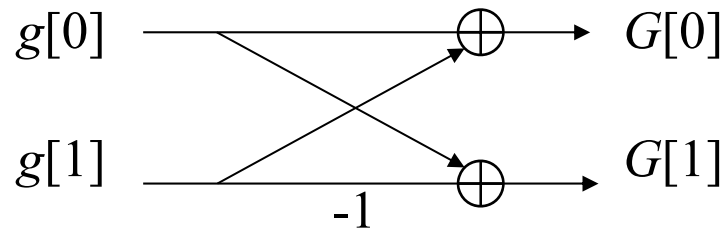
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$$G[m] = \sum_{n=0}^{N-1} g[n] e^{-j \frac{2\pi mn}{N}}$$

2-point DFT

$$\begin{bmatrix} G[0] \\ G[1] \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} g[0] \\ g[1] \end{bmatrix}$$

n=0 1
m=0 1



When $N=2$ $e^{-j \frac{2\pi}{2} mn} = (-1)^{mn}$ 369

$$G[m] = \sum_{n=0}^1 g[n] (-1)^{mn}$$

When $N=4$

$$G[m] = \sum_{n=0}^3 g[n] e^{-j \frac{\pi}{2} mn}$$

$$= \sum_{n=0}^3 g[n] (-j)^{mn}$$

$$\begin{bmatrix} G_0 \\ G_1 \\ G_2 \\ G_3 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} g_0 \\ g_1 \\ g_2 \\ g_3 \end{bmatrix}$$

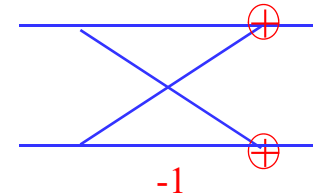
© 10-B Cooley Tukey Algorithm

When $N = 2^k$

$$\begin{aligned}
 X[m] &= \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi mn}{N}} \\
 &= \sum_{n=0}^{N/2-1} x[2n] e^{-j \frac{2\pi m(2n)}{N}} + \sum_{n=0}^{N/2-1} x[2n+1] e^{-j \frac{2\pi m(2n+1)}{N}} \\
 &= \sum_{n=0}^{N/2-1} x_1[n] e^{-j \frac{2\pi mn}{N/2}} + e^{-j \frac{2\pi m}{N}} \sum_{n=0}^{N/2-1} x_2[n] e^{-j \frac{2\pi mn}{N/2}}
 \end{aligned}$$

group 1 (even)
 group 2 (odd)
 $\frac{N}{2}$ -point DFT
 twiddle factors
 $\frac{N}{2}$ -point DFT

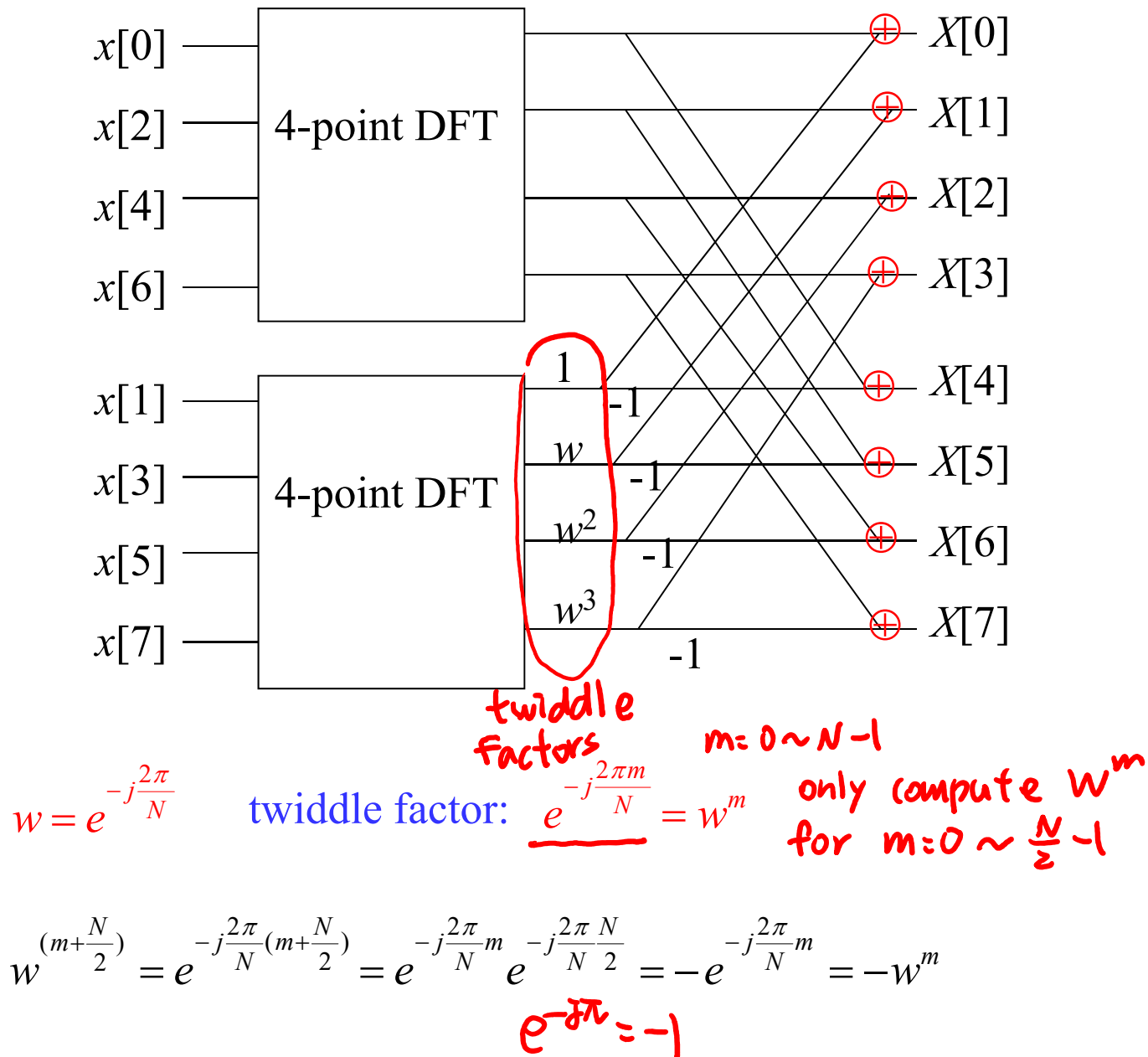
$x_1[n] = x[2n], \quad x_2[n] = x[2n+1]$



Therefore,

one N -point DFT = two $(N/2)$ -point DFTs + twiddle factors

8-point DFT

When $N = 8$

$$w = e^{-j\frac{2\pi}{8}}$$

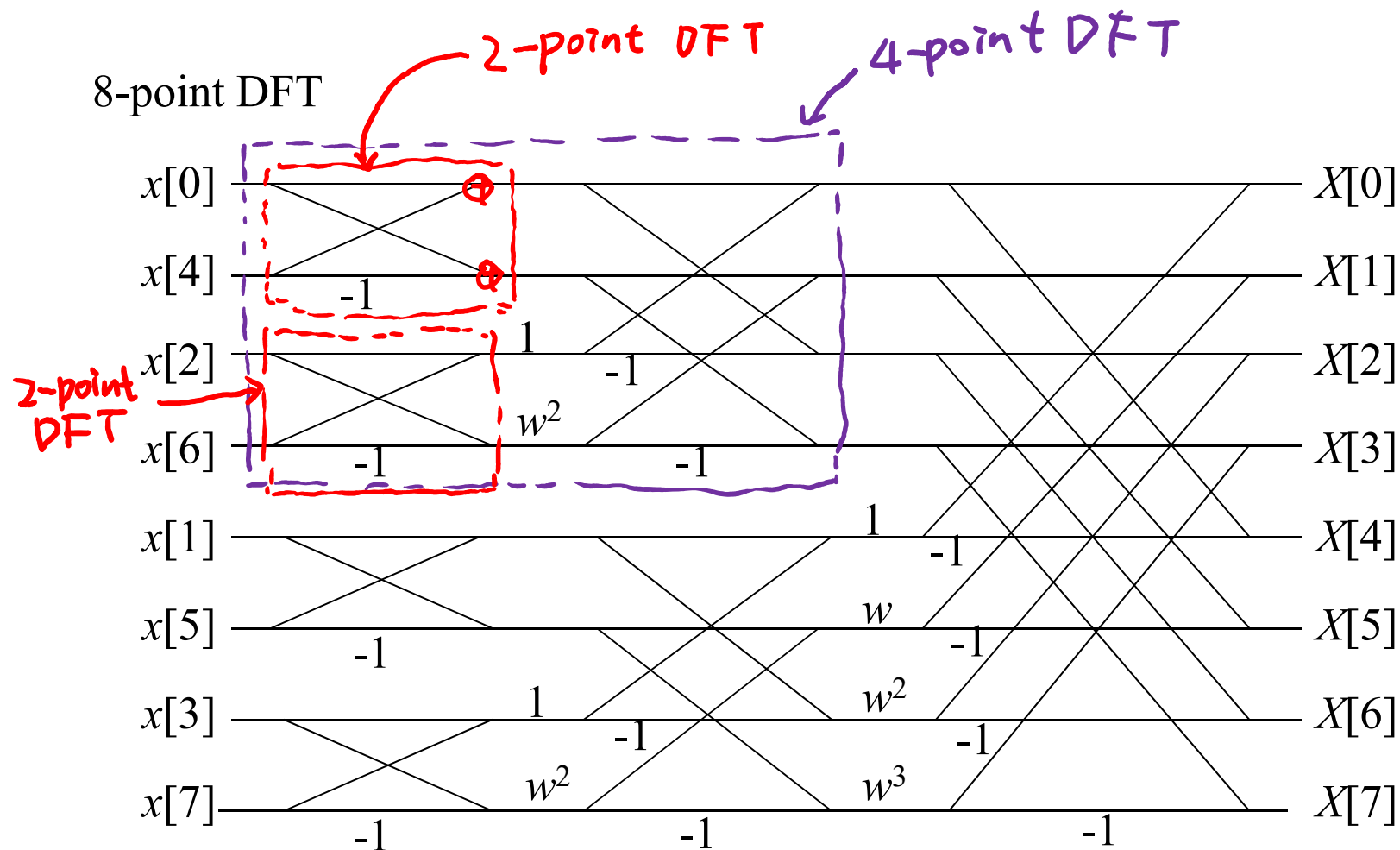
$$w^8 = 1$$

$$w^4 = -1$$

$$w^5 = -w$$

$$w^6 = -w^2$$

$$w^7 = -w^3$$



$$w = e^{-j\frac{2\pi}{8}}$$

$$w^2 = e^{-j\frac{2\pi}{4}} = -j$$

1, w^2 require no real multiplication

$$w = \frac{\sqrt{2}}{2} - j\frac{\sqrt{2}}{2} \rightarrow 2 \text{ real MULs}$$

$$w^3 = -\frac{\sqrt{2}}{2} - j\frac{\sqrt{2}}{2} \rightarrow 2 \text{ real MULs}$$

- Number of real multiplications 的估算 Only twiddle factors require multiplication. 373

2^k -point DFT 一共有 k 個 stages

k-1 次 decomposition

每個 stage 和下一個 stage 之間有 2^{k-1} 個 twiddle factors

所以，一共有 $2^{k-1}(k-1)$ 個 twiddle factors

一般而言，每個 twiddle factor 需要 3 個 real multiplications

$\therefore 2^k$ -point DFT 需要

$$3(2^{k-1}(k-1)) = \frac{3}{2} N (\log_2 N - 1) \quad \text{個 real multiplications}$$

$\simeq \frac{3}{2} N \log_2 N$

Complexity of the N -point DFT: $O(N \log_2 N)$ or $\mathcal{O}(N \log N)$

$N=8, \frac{3}{2} N (\log_2 N - 1) = 24$

$\log_2 N = \frac{\log N}{\log 2}$

- 8-point DFT 只需要 4 個 real multiplications (Why?)

- 更精確的分析，使用 Cooley-Tukey algorithm 時， N -point DFT 需要

$$\frac{3}{2}N \log_2 N - 5N + 8 \quad \text{個 real multiplications}$$

(Why?)

© 10-C Radix-4 Algorithm

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限制： $N = 4^k$

or $N = 2 \cdot 4^k$ (此時 Cooley-Tukey algorithm 和 radix-4 algorithm 並用)

$$\begin{aligned}
 X[m] &= \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi mn}{N}} \\
 &= \sum_{n=0}^{N/4-1} x[4n] e^{-j \frac{2\pi mn}{N/4}} + e^{-j \frac{2\pi m}{N}} \sum_{n=0}^{N/4-1} x[4n+1] e^{-j \frac{2\pi mn}{N/4}} \\
 &\quad + e^{-j \frac{2\pi(2m)}{N}} \sum_{n=0}^{N/4-1} x[4n+2] e^{-j \frac{2\pi mn}{N/4}} + e^{-j \frac{2\pi(3m)}{N}} \sum_{n=0}^{N/4-1} x[4n+3] e^{-j \frac{2\pi mn}{N/4}}
 \end{aligned}$$

twiddle factors

$2 \times 48 = 96$
 twiddle factors
 $64 = 2^6 = 4^3$
 $5 \times 32 = 160$ twiddle factors

One N -point DFT = four $(N/4)$ -point DFTs + twiddle factors

Note:

(1) radix-4 algorithm 最後可將 $N = 4^k$ -point DFT 拆解成 4-point DFTs 的組合

4-point DFTs 不需要任何的乘法

(2) 使用 radix-4 algorithm 時， N -point DFT 需要

$$\frac{9}{4}N \log_4 N - \frac{43}{12}N + \frac{16}{3} \quad \text{個 real multiplications}$$

- Number of real multiplications for the N -point DFT

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N	乘法數	加法數	N	乘法數	N	乘法數	N	乘法數
1	0	0	10	20	21	62	36	<u>64</u>
2	0	4	11	40	22	80	40	100
3	2	12	12	8	24	28	42	124
4	0	16	13	52	25	148	45	170
5	10	34	14	32	26	104	48	92
6	4	36	15	40	27	114	52	208
7	16	72	16	20	28	64	54	228
8	4	52	18	32	30	80	56	156
9	16	72	20	40	32	<u>72</u>	60	160

N	乘法數	N	乘法數	N	乘法數	N	乘法數
63	256	96	280	192	752	360	1540
64	<u>204</u>	104	468	204	976	420	2080
66	284	108	456	216	1020	480	2360
70	300	112	396	224	1016	504	2300
72	<u>164</u>	120	380	240	940	512	3180
80	260	128	560	252	1024	560	3100
81	480	144	436	256	1308	672	3496
84	248	160	680	288	1160	720	3620
88	364	168	580	312	1608	784	4412
90	340	180	680	336	1412	840	4580

N	乘法數	N	乘法數	N	乘法數	N	乘法數
1008	5356	1440	8680	2520	16540	4032	29488
1024	7436	1680	10420	2688	19108	4096	37516
1152	7088	2016	12728	2880	20060	4368	35828
1260	7640	2048	16836	3369	24200	4608	36812
1344	8252	2304	15868	3920	29900	5040	36860

附錄十二：論文英文常見的文法錯誤

(1) *** transform, *** equation, *** method, *** algorithm 在論文當中，當成是可數名詞，而非專有名詞 (除非是所有格的形態)。

可數名詞單數時，前面要冠詞 (a 或 the)

Fourier transform is important for signal processing. (錯誤)

The Fourier transform is important for signal processing. (正確)

A Fourier transform is important for signal processing. (正確)

Fourier transforms are important for signal processing. (正確)

I have written the Matlab program of Parks-McClellan algorithm (錯誤)

I have written the Matlab program of the Parks-McClellan algorithm (正確)

(2) 若是所有格的形態，不必加冠詞

I have written the Matlab program of the Parks-McClellan's algorithm (錯誤)

I have written the Matlab program of Parks-McClellan's algorithm (正確)

(3) 論文視同正式的文件，對 not, is, are 不用縮寫

they're (錯誤) they are (正確)

he's (錯誤) he is (正確)

aren't (錯誤) are not (正確)

don't (錯誤) do not (正確)

can't (錯誤) cannot (正確)

(4) Suppose, assume 後面要加關係代名詞

Suppose x is a large number. (錯誤)

Suppose **that** x is a large number. (正確)

(5) 每一個子句都有一個動詞，而且只有一個動詞

(6) In this paper, in this section, in this chapter 開頭的句子，應該用現在式，而非未來式

In this paper, the fast algorithm of DCT will be introduced. (錯誤)

In this paper, , the fast algorithm of DCT **is** introduced. (正確)

(7) 在 conclusion 當中回顧文章一內容，用過去式

(8) 敘述所引用的論文的内容，用過去式

In [10], the number theoretic transform **was** proposed.

(9) time domain, frequency domain 前面也加冠詞

in time domain (錯誤) in **the** time domain (正確)

(10) 不以 “this paper”, “section *”, “Ref. [*” 當主詞用

This paper describes several concepts. (錯誤)

In this paper, several concepts are described. (正確)

Ref. [1] proposed the method. (錯誤)

In Ref. [1], Parks and McClellan proposed the method. (正確)

(11) 提及某個 equation 時，直接括號加數字即可

in equation (3) (錯誤) in (3) (正確)

提及某個 section, table, or figure 時，前面不加冠詞，而且常用大寫

in the section 4 (錯誤) in Section 4 (正確)

in the table 5 (錯誤) in Table 4 (正確)

(12) 寫科技論文不是寫文學作品，不要用高明、漂亮、但沒有把握的文法。

儘量用簡單而有把握的文法。

(13) 科技論文英文講求「長話短說」，儘量用精簡的文字來表達意思

(14) 用字儘量避免重覆

(15) Equations 也當成是文章的一部分，所以通常也要加標點符號

The formula of Newton's 2nd law is

$$F = ma.$$

← 要加標點符號

(16) 解釋 parameters 和 symbols 時，用 **where** 當關係代名詞

$x = 10t$ **where** x is the location of the object and t is time.

(17) 很重要的論文，投稿至國際學術期刊，又對自己的英文文法沒有十足的把握時

可以用網路上的論文編修服務資源，來修改文法上的錯誤

本系以及台大語言中心也經常有英文論文寫作相關的訓練課程，有志將來在學術界奮鬥的同學，可以多參與相關的課程