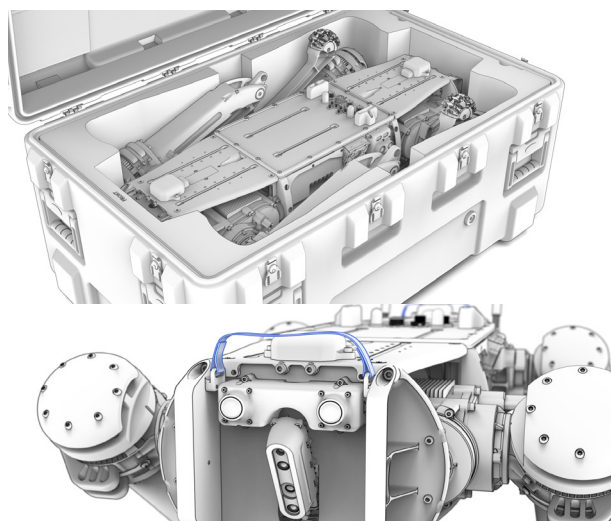# QUICKSTART GUIDE

The Vision 60 is a mid-sized foldable tele-operable and autonomous Quadrupedal Unmanned Ground Vehicle (Q-UGV) with a Software Development Kit (SDK) for various industry specific fields, including inspection, CBRN, EOD, and defense. Please review this guide before unpacking the robot. It contains important safety instructions to get your robot up and running.
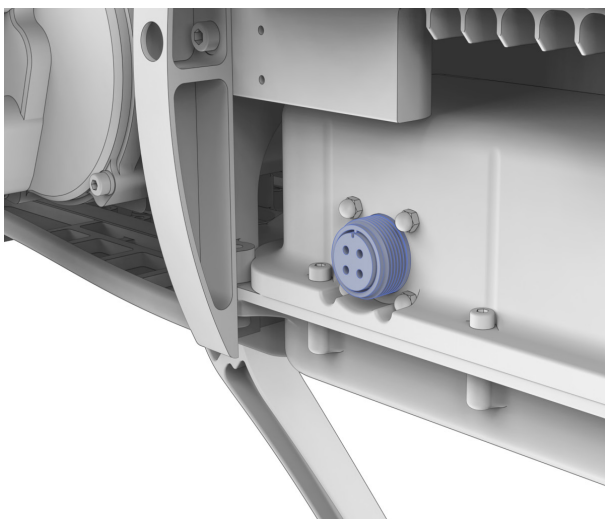
1. Unpack the Robot

The Vision 60 robot weighs over 100lbs, so two people are required to unpack it.

Push the back two legs inwards away from the sides, and lift the robot using the front and back strap handles directly up out of the box.

The legs may move due to gravity when lifting, so be careful to lift high enough to clear the box.
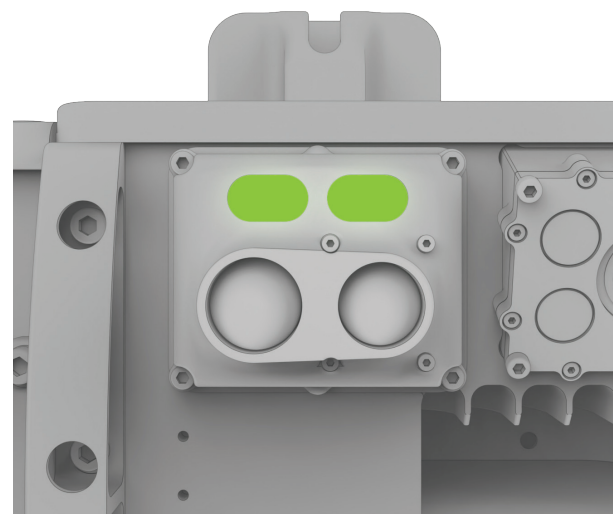
2. Charge the Battery

Unscrew the charge plug and cap on the lower side of the robot, and connect the charge cable to the charge port on the side of the robot.

If it isn't charging, press and hold the lower button on the charger to start charging. While the robot can be turned on while charging, we recommended waiting until charging is complete.

To charge the remote controller, simply use the provided USB-C charger.
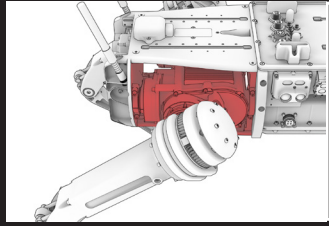
3. Turn on the Robot

To turn the robot on, rotate the RED Emergency Stop button on the back of the robot one quarter turn clockwise.
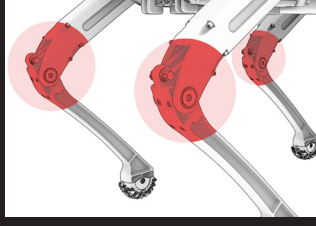
To turn the robot off, push the RED Emergency Stop button in.

All power is cut to the robot when turned off, so make sure it's not standing, otherwise the robot could fall.
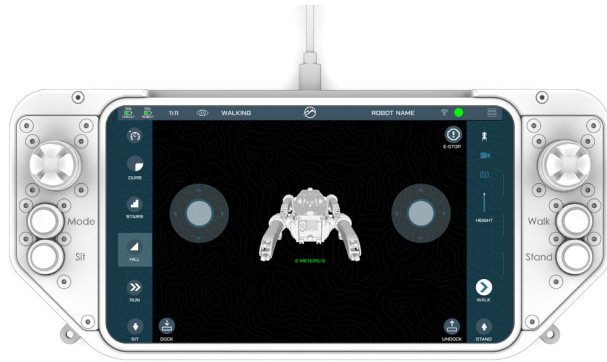
Warnings

Do not place your hands between the leg pods and the body plates, or injury may occur.

To avoid injury, keep hands and fingers away from joints and pivots whenever moving or adjusting the robot.

Make sure that your feet and arms are away from bottom of robot when pushing Emergency Stop button to avoid injury.
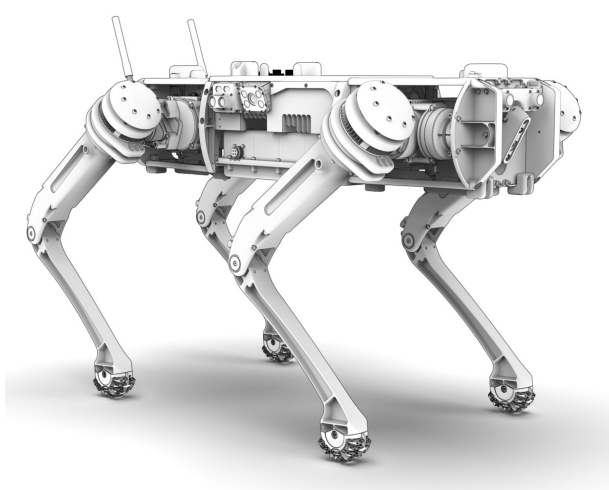
4. Turn on the Remote

Turn the tablet on by holding down the top black button for two seconds, and start the Ghost Controller app.

Tap the "Allow" button that pops up to allow the joysticks to connect.

5. Connect to WIFI

The robot broadcasts a WiFi access point named Vision60_* (where the * will be your robot number) one minute after it is turned on. The controller will connect to this WiFi network automatically.

The password is **vision60**

6. Get Going

1. Press the **STAND** button. The robot will stand up. Use the joysticks gently to look around.

2. Press the **WALK** button. Move the right joystick forward and the robot will take steps. Use the joysticks to walk around, pushing them only a small amount from their center.

3. Press the **SIT** button. When the robot is sitting on the ground, turn the robot off by pushing the red Emergency Stop button.

Ghost Robotics is here to help. For the fastest answers to your questions, email **support@ghostrobotics.io**