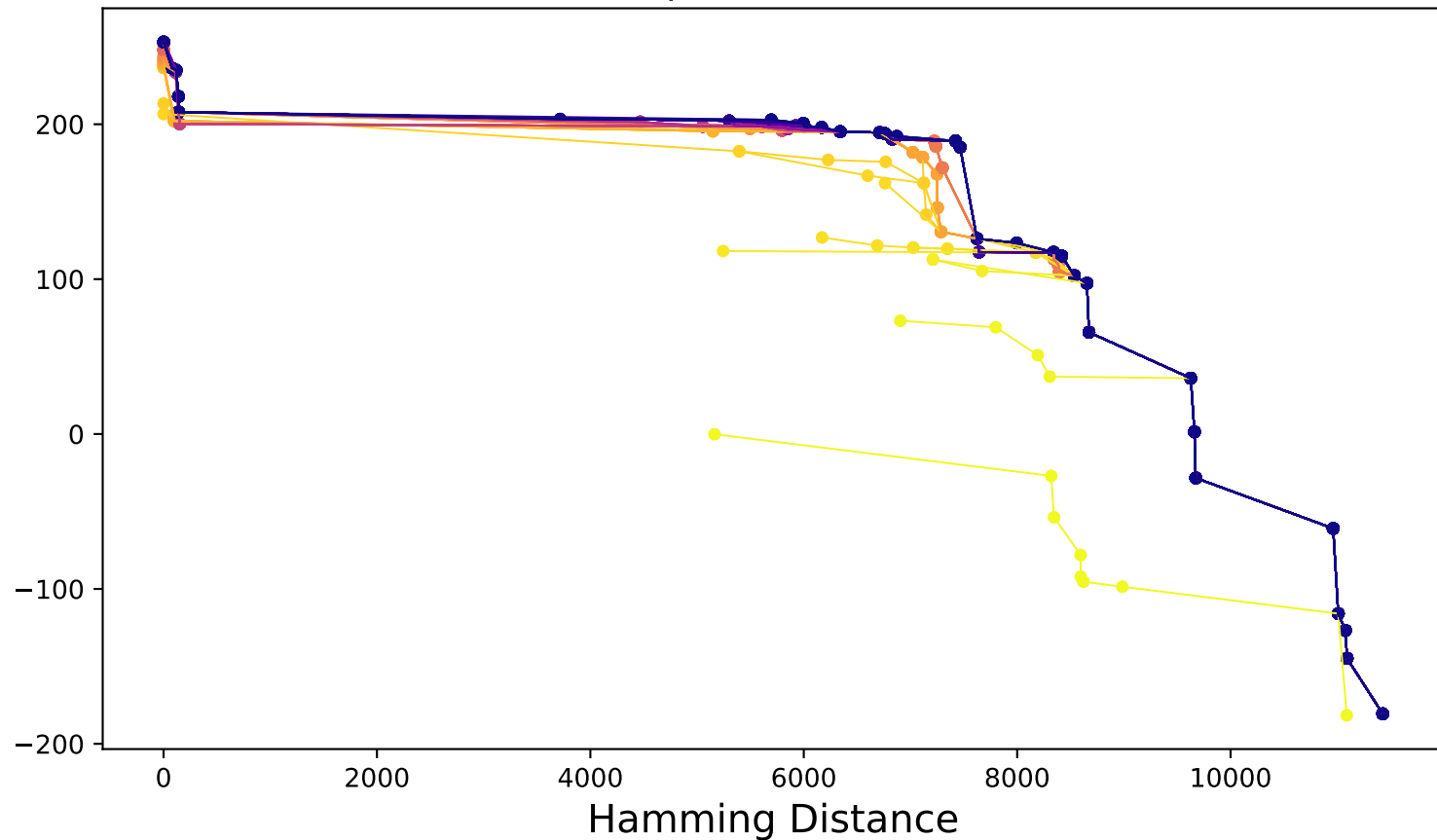


# Bipedal Walker

Task Performance



Generation