# Integral Equations Notes: [457]

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**Definition 1.** An integral equation is any equyation in which the unknown function is inside the integral sign.

#### Example 1.

$$\int_{a}^{b} k(x,y)u(y)dy = f(x), x \in (a,b)$$

Here k and f are given and u(x) is the unknown function.

### Example 2.

$$\int_0^\infty e^{-xt}u(t)dt = f(x), x \in (0, \infty)$$

f(x) is the laplace transform of u.

**Remark 1.** There is an inversion formula giving u from f but it involves an integral of f(x) over complex values of x. In practice we may only know f(x) for real values of x.

#### Example 3.

$$\int_{-1}^{1} u(t)dt = 1$$

One solution

$$u(t) = \frac{1}{2}, t \in (-1, 1)$$

Clearly there are lots of solutions, e.g.

$$u(t) = \frac{1}{2} + any \ odd \ funtion \ of \ t.$$

or

$$u(t) = \frac{1}{2} + \sum_{n=1}^{\infty} \{a_n cos(nt\pi) + b_n sin(nt\pi)\}$$

For any reasonable  $a_n$  and  $b_n$ .

#### Example 4.

$$\int_{-1}^{1} u(t)dt = f(x), x \in (-1, 1)$$

Now there are no solutions unless f(x) is constant.

#### Example 5.

$$\alpha u(x) + \beta \int_{-1}^{1} u(t)dt = f(x), x \in (-1, 1)$$
(1)

Where  $\alpha$  and  $\beta$  are given constants with  $\alpha \neq 0$  or example 4 put  $\int_{-1}^{1} u(t)dt = c$  a known constant. Then (1) gives

$$u(x) = \frac{1}{\alpha} \{ f(x) - \beta C \} \tag{2}$$

So we will have solved (1) and know C. Integrate (2) gives

$$C = \int_{-1}^{1} u(x)dx = \frac{1}{\alpha} \int_{-1}^{1} f(x)dx - \frac{\beta C}{\alpha} \int_{-1}^{1} dx$$

$$(1 + \frac{2\beta}{\alpha})C = \frac{1}{\alpha} \int_{-1}^{1} f(x)dx \tag{3}$$

$$C = \frac{1}{\alpha + 2\beta} \int_{-1}^{1} f(x) dx$$

then (2) gives unique solution of (1) real provided  $\alpha + 2\beta \neq 0$ . What happens if  $\alpha + 2\beta = 0$ ? As before we get to (3) which reduces to

$$0 = \int_{-1}^{1} f(x)dx \tag{4}$$

If f(x) satisfies (4) eg f could be odd then (2) solves (1) for any choice of the constant C: we have existence but not uniqueness. If f(x) does not satisfy (4) eg f(x) could by  $x^2$  then (1) does not have any solutions  $\alpha + 2\beta = 0$ . All this is reminicent of linear algebra (solving Ax = b).

**Exercise 1.** Put  $\frac{\beta}{\alpha} = -\lambda$  and f = 0 giving

$$u(x) = \int_{-1}^{1} u(t)dt = 0$$

A homogenous integral equation. Are there values of  $\lambda$  for which this integral equation has non trivial solution  $u \neq 0$ ?

#### Example 6.

$$\int_0^t u(\tau)d\tau = f(t), t > 0 \tag{5}$$

Differentiate with respect to x(t):

$$u(x) = f'(x)$$

Two anxieties. 1. (5) suggests that f(0)=0 in  $\lim_{x\to 0}$  (5) what happens if  $f(0)\neq 0$  eg  $f(x)=1, \forall x$  2. What happens if f is not differentiable? Try using laplace transform. Let  $U(s)=\mathcal{L}\{u\}$ 

$$\int_{0}^{\infty} u(t)e^{-st}dt$$

We have:

$$\mathcal{L}\left\{\int_{0}^{t} u(\tau)d\tau\right\} = \int_{t=0}^{\infty} e^{-st} \int_{0}^{\tau=t} u(\tau)d\tau$$

$$= \int_{0}^{\infty} u(\tau) \int_{\tau}^{\infty} e^{-st}dtd\tau$$

$$= \frac{e^{st}}{s} \Big|_{\tau}^{infty} = \frac{e^{-s\tau}}{s}$$

$$= \int_{0}^{\infty} u(\tau) \frac{e^{-s\tau}}{s} d\tau$$

$$= \frac{1}{s} \int_{0}^{\infty} u(\tau)e^{-s\tau}d\tau$$

$$= \frac{1}{s}\mathcal{L}\left\{u\right\}$$

$$\mathcal{L}\left\{(5)\right\} = \frac{1}{s}U(s) = F(s)$$

$$\Longrightarrow$$

$$u(s) = sF(s)$$

$$\mathcal{L}\left\{f'\right\} = sF(s) - f(0)$$

$$\mathcal{L}\left\{u\right\} = U = sF(s) + sf(x) - f(0)$$

$$= \mathcal{L}\left\{f\right\} + f(0)$$

Question is is there a g(t) such that  $\mathcal{L}\{g\}=1$  Answer: It depends on what you mean by a function.

$$LHS = \mathcal{L}\{g\} = \int_0^\infty g(t)e^{st}dt = G(s)$$

Fact: If g is an ordinary integrable function then we must not have  $G(s) \to 0$  as  $s \to \infty$  As we want G(s) = 1. g can't be ordinary. Fact:  $\mathcal{L}\{\delta\} = 1$  Wwhere  $\delta = \text{dirac delta function. SO solution of } (5)$ .

$$u(x) = f'(x) + f(0)dx$$

In particular if  $f(0) \neq 0$  then (5) has no conbinuous solutions for  $x \geq 0$ . Second Anxiety: Consider (5) where f is not a continuous function.

#### Example 7.

$$f(x) = \begin{cases} 0, & 0 \le x < c \\ x - c, & x \ge c \end{cases}$$
$$= (x - c)H(x - c)$$

H(x) is the divided unit function. Then

$$\begin{split} \mathscr{L}\{(5)\} &= \frac{1}{s}u(s) = \mathscr{L}\{f\} = \mathscr{L}\{x-c)H(x-c)\} \\ &= \int_0^\infty (x-c)H(x-c)e^{-sx}dx \\ &= \int_0^\infty (x-c)e^{sx}dx, (x-c) = y \\ &= \int_0^\infty ye^{-s(y+c)}dy \\ &= e^{-sc}\int_0^\infty yce^{-sy}dy \\ &= e^{-sc}\mathscr{L}\{t\} = \frac{e^{-sc}}{s^2} \\ &\implies U(s) = se^{-sc} \\ u(x) &= H(x-c) \end{split}$$

### Example 8.

$$u(x) = \frac{\alpha}{\pi} \int_{-1}^{1} \frac{u(t)dt}{(x-2)^2 + \alpha^2} = 1, x \in (-1, 1)$$

The integral contains a parameter  $\alpha$ . It turns up in at least two distinct physical applications. One in electro statics. where it is called Love's equation and in quantum phases where it is called Lieb's equation. It looks simple byt no explicit solution is known. Soi what is known is that u(x) exists, its continuous, it's unique, and it's even. Numerical solutions are easy to compute unless  $\alpha$  is very small.

# 1 Abel's Equation

A bead starts from rest at P and slides down a smooth wire riching 0 at time  $t_0$  Find  $t_p$ . Motion is under gravity in a vertical plane put point P at (x,y) and Q at  $(\xi,\delta)$ . Let s denote the length from 0 to Q. Energy at P = Energy at Q. m = mass of the bead.

$$mgy = mg\delta + \frac{1}{2}m(\frac{ds}{dt})^{2}$$
$$\frac{ds}{dt} = -\sqrt{2gz(y - \delta)}$$

integrating

$$t_p = \int_0^{t_p} dt = \int_{\delta=y}^{\delta=0} \frac{ds}{\sqrt{2g(y-\delta)}}$$

Next specify the shape (equation) of the wire. Its convienient to suppost that  $s = S(\delta)$  for some function S. Thus  $ds = S(\gamma)d\gamma$ 

$$t_p = \int_y^0 \frac{s'(\gamma)d\gamma}{\sqrt{2g(y-\gamma)}}$$

This gives  $t_p$  if we know the shape of the wire. Abel asked given  $t_p$  can we find S? Put  $u(\gamma) = S'(\gamma)$  and  $f(y) = \sqrt{2g}t_p$  giving:

$$\int_0^y \frac{u(\gamma)d\gamma}{\sqrt{y-\gamma}} = f(y), y > 0 \tag{6}$$

This is Abel's integral equation. LHS of (6) is a laplace convolution. Recall:

$$(f * g)(t) = \int_0^t f(\gamma)g(t - \gamma)d\gamma$$
$$\mathcal{L}\{f * g\} = \mathcal{L}\{f\}\mathcal{L}\{g\}$$

Proof.

$$\begin{split} \mathcal{L}\{f*g\} &= \int_0^\infty e^{-st} (f*g)(t) dt \\ &= \int_0^\infty e^{-st} \int_0^t f(\gamma) g(t-\gamma) d\gamma dt \\ &= \int_0^\infty f(\gamma) \int_\delta^\infty e^{-st} g(t-\gamma) dt d\gamma \\ &= \int_0^\infty f(\gamma) \int_{x=0}^\infty e^{-s(\gamma+x)} g(x) dx d\gamma \\ &= \mathcal{L}\{f\} \mathcal{L}\{g\} \end{split}$$

$$\mathcal{L}\{(6)\}: U(s)\mathcal{L}\{\frac{1}{\sqrt{t}}\} = F(s) \tag{7}$$

Now:

$$\begin{split} \mathcal{L}\{t^{\nu}\} &= \int_0^\infty t^{\nu} e^{-st} dt \\ &= \int_0^\infty (\frac{x}{s})^{\nu} e^{-x} \frac{dx}{s} \\ \text{Put } st &= x \\ &= \frac{1}{st^{\nu+1}} \int_0^\infty x^{\nu} e^{-x} dx, \nu > -1 \end{split}$$

The remaining integral is denoted by  $\Gamma'(\nu+1)$  where  $\Gamma$  is the gamma function. We want  $\int_0^\infty x^{-1/2}e^{-x}dx = \Gamma(1/2) = 2\int_0^\infty e^{-w^2}dw = \sqrt{\pi}$ . SOo  $\mathcal{L}\{t^{-1/2}\} = \sqrt{\frac{\pi}{6}}$ . Returning to (7), we get

$$U(s) = \sqrt{\frac{s}{\pi}}F(s) \tag{8}$$

This looks like  $\mathscr{L}\{\text{Convolution}\}\$  but its not because  $\sqrt{s}$  is not the LT of an ordinary function. We know  $\mathscr{L}\{\text{Ordinary Function}\}\rightarrow 0$  as  $s\rightarrow\infty$  So we use a trick:

$$U(s) = \frac{1}{\sqrt{\pi s}} sF(s)$$

$$= \frac{1}{\pi} \sqrt{\frac{\pi}{s}} \{ sF(s) - f(0) + f(0) \}$$

$$= \frac{1}{\pi} \mathcal{L} \{ t^{-1/2} \} \{ \mathcal{L} \{ f' \} + f(0) \}$$

$$u(t) = \frac{1}{\pi} \{ t^{-1/2} * f' + \frac{f(0)}{\sqrt{t}} \}$$

$$= \frac{1}{\pi} \left\{ \int_0^t (t - \delta)^{-1/2} f'(\delta) d\delta + f(0) \frac{1}{\sqrt{t}} \right\}$$
 (9)

ie

$$S'(y) = \frac{1}{\pi} \left\{ \frac{f()}{\sqrt{y}} + \int_0^y \frac{f'(\delta)}{\sqrt{y - \delta}} d\delta \right\}$$

Note for Arbel's problem f(0) = 0. First Alternative method. We write (8) as  $\frac{1}{s}U(s) = \frac{1}{\pi s}F(s)$ . Invert:

$$\int_0^t u(x)dx = \frac{1}{\pi}t^{-1/2} * f \tag{10}$$

Differentiate (legal?)

$$u(t) = \frac{1}{\pi} \frac{d}{dt} \int_0^t (t - \delta)^{-1/2} f(\delta) d\delta$$

This is the same as (9). Second Alternative Method: Special and Sneaky Multiply (6) by  $\frac{1}{\sqrt{x-y}}$  and integrate from 0 to x with resepct to y.

$$\int_0^x f(y) \frac{1}{\sqrt{x-y}} = \int_0^x \frac{1}{\sqrt{x-y}} \int_0^y \frac{u(\delta)d\delta}{\sqrt{y-\delta}} dy$$
$$= \int_0^x u(\delta) \int_\delta^x \frac{dy}{\sqrt{x-y}\sqrt{y-\delta}} d\delta$$
$$y = \delta + (x-\delta) \sin^2(\theta)$$

This gets to (10).

## 2 ODEs

Ordinary Differential Equations (odes) Problems inboolving odes can often be rewritten as integral equations. This can be useful for tracking theoretical questions such as existence.

Example 9. 1st order inital value problem (ivp).

$$\frac{dy}{dt} = f(t, y(t)) \text{ with } y(0) = 0$$

Integrate:

$$\int_0^x \frac{dy}{dt} = \int_0^x f(t, y(t))dt$$
$$y(x) - y_0 = \int_0^x f(t, y(t))dt$$

In general this is a nonlinear integral equation because of the dependence of f on y.

Example 10. 2nd order IVP

$$y''(t) = f(t, y(t)), y(0) = y_0 \text{ and } y'(0) = y_1$$

Integrate:

$$y'(x) - y_1 = \int_0^x f(t, y(t))dt$$

Integrate:

$$\int_{0}^{s} (y'(x) - y_{1})ds = \int_{0}^{s} \int_{0}^{x} f(t, y(t))dtdx$$

$$\implies y(s) - y_{0} - y_{1}s = \int_{0}^{s} f(t, y(t)) \int_{t}^{s} dxdt$$

$$= \int_{0}^{s} (s - t)f(t, y(t))dt, s > 0$$
 (1)

Example 11. 2nd order boundary value problem (BVP)

$$y''(t) = f(t, y(t)), 0 < t < L \text{ with } y(0) = y_0, y(L) = y_L$$

We can still use (1) except we don't know  $y_1 = y'(0)$ . Put s=L in (1) we receive:

$$y_L - y_0 - y_1 L = \int_0^L (L - t) f(t, y(t)) dt$$

Write this as  $y_1 = ...$  and instert back into (1) gives:

$$y(s) = y_0 + \frac{s}{L} \{ y_L - y_0 - \int_0^L (L - t) f(t, y(t)) dt + \int_0^s (s - t) f(t, y(t)) dt \}$$

$$y(s) = y_0 (s - \frac{s}{L}) + y_L \frac{s}{L} - \frac{s}{L} \int_s^L (L - t) f(t, y(t)) dt - \int_0^S \{ \frac{s}{L} (L - t) - (s - t) \} f(t, y(t)) dt$$

$$= y_0 (1 - \frac{s}{L}) + y_L \frac{s}{L} - \int_0^L G(s, t) f(t, y(t)) dt$$

Where

$$G(s,t) = \begin{cases} \frac{s}{L}(L-t), t > s \\ \frac{t}{L}(L-s), t < s \end{cases}$$

G is known as a Green's Function. For linear eigenvalue problems (a Sturm-Liouville Problem) e.g. f(t,y(t)) but if its linear = (t),  $y_0 = 0$ ,  $y_L = 0$  We get the integral equation:

$$y(s) = -\lambda \int_0^L G(s, t)y(t)dt, 0 < s < L(2)$$

This eignevalue problem  $[y'' = \lambda y, y(0) = 0, y(L) = 0]$  is easy to solve:  $\lambda = (\frac{n\pi}{L})^2, y(t) = \sin(\frac{n\pi t}{L}), n \in \mathbb{N}$ 

# 3 Classification

 $\int_a^b K(x,y)u(y)dy=f(x), a \leq x \leq b$  This is called a Fredholm Integral Equation of the first kind. (FIE1). K is called the kernal, a b are constants with b  $\dot{b}$  a. Next f(x) is given for  $a \leq x \leq b$ . Often we may have f(x) for a¡x¡b, e.g. f(a) may not exist or  $a=-\infty$  or  $b=\infty$ . K(x,y) is a given function of two variables defined in a square in the x,y plane.  $\Omega=\{(x,y): a\leq x\leq b, a\leq y\leq b.$  If f(x) is not defined  $x\in [a,b]$  then the same applies to K.