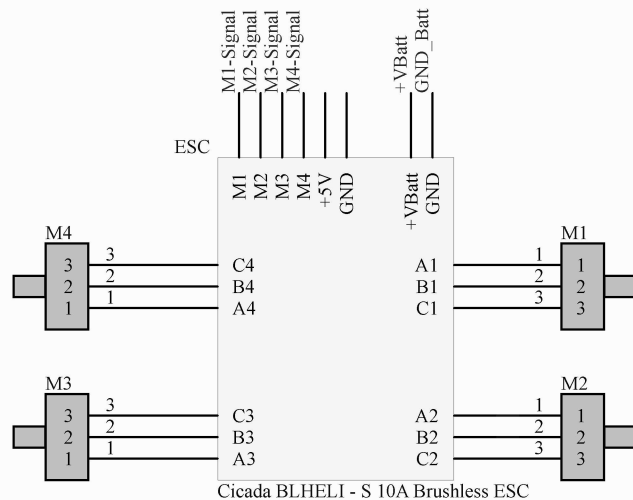


Note: It's recommended add a voltage regulator to supply +V-CF instead of using BT2. Unpredictable ESC behavior such as uncontrolled thrust can occur if the crazyflie loses power but the ESC does not.



Notes:
1. The pull-down resistors are used to extract a servo-type signal from the motor connectors for the purposes of controlling a brushless quad with the crazyflie 2.0. Needing to use the z-ranger and two PWM signals for the climbing servos, there were not enough PWM output pins on the crazyflie, so we enabled a special mode in the firmware that outputs brushless motor signals using the motor transistors. Pull downs are needed to change the transistor gate signal into a voltage for the ESC to read.

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