

Drew McNeely

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Publications

Hidden Markov Models and the Bayes Filter in Categorical Probability Sept 2025
T. Fritz, A. Klingler, D. McNeely, A. Shah Mohammed, Y. Wang
[10.1109/TIT.2025.3584695](https://doi.org/10.1109/TIT.2025.3584695) (IEEE Transactions on Information Theory, vol. 71, no. 9, pp. 7052-7075)

technical projects

markovcats.jl Oct 2025–Present

Julia DSL for Categorical Probability

- A Julia DSL with discrete probability syntax and Markov category semantics
- Built on GATLab.jl and Catlab.jl within the AlgebraicJulia ecosystem

girypy Jan 2022

Python Library for Categorical Estimation

- Categorical Kalman filter implementation using Gaussian Markov categories
- Abstract base class interface for Markov categories with pseudo-DSL using infix operators
- Precursor to markovcats.jl

photometry Jan 2020

Satellite Photometry Visualization

- Interactive 3D visualization of photometric output from satellites in orbit
- Maps real-valued functions on spherical domains to HTML-based globe rendering

research experience

Independent Researcher, Independent Researcher 2023 – 2024

- Co-authored IEEE publication on categorical probability and Bayesian filtering (accepted Sept. 2025)
- Attended Applied Category Theory Conference 2023 (College Park, MD)

Adjoint School 2024, Student — Project: Modeling Uncertainty with Markov Categories Jan 2024 – June 2024

- Investigated monads for imprecise probability including Dempster-Shafer theory and inner/outer probability measures
- Presented preliminary findings at ACT 2024, Oxford, UK

University of Texas at Austin, Graduate Researcher — Categorical Probability (Advisor: Efsthios Bakolas) Austin, TX
2020 – 2023

- Developed polymorphic categorical formulation of recursive Bayesian filters
- Created novel framework merging category theory with dynamical systems estimation
- Resulted in IEEE Transactions on Information Theory publication

University of Texas at Austin, Graduate Researcher — Geometric Estimation (Advisor: Moriba Jah) Austin, TX
2017 – 2020

- Recursive estimation for dynamical systems with Riemannian state spaces
- Clustering analysis of resident space objects

community leadership

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| Adjoint School Organizing Committee , Organizing Committee Member | July 2024 – July 2026 |
| <ul style="list-style-type: none">• Two-year position organizing international applied category theory research program• Responsibilities: admissions review, mentor recruitment, sponsor outreach, website maintenance, liaison between Steering Committee and ACT Conference Organizing Committee• 2025: Organized school at University of Florida, Gainesville• 2026: Organizing school at Tallinn University of Technology, Estonia | |

Education

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|-----------|---|----------|
| MS | University of Texas at Austin , Aerospace Engineering | May 2023 |
| | <ul style="list-style-type: none">• Thesis: <i>Categorical Probability for Abstracting Filtering Algorithms on Stochastic Dynamical Systems</i>• Advisor: Efstathios Bakolas | |
| BS | Missouri University of Science & Technology , Aerospace Engineering | Dec 2015 |
| BS | Missouri University of Science & Technology , Mechanical Engineering | Dec 2015 |

teaching experience

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| Uncommon Schools, Camden Prep High School , Mathematics Teacher | Aug 2024 – present |
| <ul style="list-style-type: none">• Algebra 2, Accelerated Precalculus, AP Calculus AB | |
| UT Austin, University of Arizona , Teaching Assistant | 2017 – 2022 |
| <ul style="list-style-type: none">• Calculus 2, Calculus 3, Linear Algebra, Differential Equations, Intro to Computer Programming | |
| Self-Employed , Private Tutor | 2016 – 2023 |
| <ul style="list-style-type: none">• Math (4th grade through college), SAT/ACT/ISEE test prep | |

earlier experience

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| NASA Ames Research Center , Research Intern | Summer 2017 |
| <ul style="list-style-type: none">• Constrained optimal control for Variable Camber Continuous Trailing Edge Flap aircraft | |
| Missouri S&T Formula SAE , Controls & Data Acquisition Lead | 2014 – 2016 |
| <ul style="list-style-type: none">• 1st place overall Formula North 2016; 4th overall FSAE Lincoln 2016 | |

Skills

- Programming:** Julia, Python, MATLAB, Java
- Languages:** English (native), Dutch (B2)