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Education \_

Northeastern University | Boston, MA

May 2020

BACHELOR OF SCIENCE IN COMPUTER ENGINEERING, MINORS IN COMPUTER SCIENCE AND ROBOTICS

GPA: 3.9/4.0

• Coursework: Autonomous Field Robotics (Grad), Mobile Robotics (Grad), Robotics Sensing and Navigation (Grad), Computer Vision (Grad), High Performance Computing (Grad), AI, Object Oriented Design

• Involvement: MIT Ballroom Dance Team, Undergraduate Research, numerous hackathons, IEEE, Toastmasters, SASE, HKN, TBII

Skills

**Interests** Autonomous Robotics, Perception, Navigation, Mapping, Computer Vision

**Languages** Python, C++, C, CUDA, Java

Technologies ROS, OpenCV, OpenMP, MPI, MATLAB, Git, GDB, Linux, LCM, MTFX

**Hardware** IMUs , GPS , XBee Radio Modules , Teledyne Benthos Acoustic Smart Modems , Ethereum Miners

**Technical Experience** 

Optimus Ride Boston, MA

INCOMING ROBOTICS SOFTWARE CO-OP | MAPPING AND LOCALIZATION

Aug. 2019 - Dec. 2019

**Amazon**Bay Area

INCOMING SOFTWARE DEVELOPMENT ENGINEER INTERN

May 2019 - Jul. 2019

## **Flex Innovation and Design Labs**

Milpitas, CA

ROBOTICS SOFTWARE CO-OP

Jul. 2018 - Dec. 2018

- Primary software architect and developer of ROS based mobile robot in team of seven software and test engineers; project utilized six different languages, for seven unique pieces of hardware and ten different I/O peripherals.
- $\bullet \ \ \text{Integrated commercial SLAM system, fusing data from LIDAR, sonar, wheel encoders, and IMU. PoC for sensing and navigation software.}$
- Implemented several basic machine learning and deep neural net algorithms in Matlab to further technical understanding.

MIT Lincoln Laboratory

Lexington, MA

CO-OP TECHNICAL ASSISTANT, INTERIM SECRET CLEARANCE | GROUP 102 - OPEN AND EMBEDDED SYSTEMS

Jan. 2017—Aug. 2017

- Independently parallelized radar signal processing chain in C++ using OpenMP and MPI to run in distributed multi-core Linux environments. Optimizations resulted in a 1700% speedup and demonstrated hybridized MPI and OpenMP parallelizations met stringent performance requirements and reduced development costs.
- Automated benchmarking efforts through python and bash scripts to rapidly test and compare over 350 configurations.
- Leveraged analysis tools from the Intel Parallel Studio Suite and Allinea Forge for debugging and optimization.

## Northeastern University Marine Observatory Network

Boston, MA

Undergraduate Research Assistant (NSF REU)

Oct. 2015 - Jan. 2017

- Designed and implemented smart buoy and GUI control system using C++, QT framework, and XBee Radio modules to bridge above water radio network with subsea acoustic network.
- Implemented MAC protocols in MATLAB on Teledyne Benthos SM-975 Acoustic Smart Modems to advance understanding of modem interactions and compare efficacy of MAC protocols over acoustic channel.
- Co-authored two papers and gave two major presentations (see personal website for links)

## Achievements \_

Spring 2019 **Tau Beta Pi**, Engineering Honor Society, Northeastern University

Spring. 2018 **Eta Kappa Nu**, IEEE Student Honor Society, Gamma Beta Chapter, Northeastern University Feb. 2017 **NU Talk 2017**, Presented to 300+ people on NU MONET underwater networking project

Dec. 2014 **Boy Scouts of America**, Eagle Scout (Bronze Palm)

Reference: Prof. Hanumant Singh, Northeastern University: ha.singh@neu.edu