

Andrew Tu

COMPUTER ENGINEER

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Available for Full Time Fall 2020

Education

Northeastern University | Boston, MA

May 2020

BACHELOR OF SCIENCE IN COMPUTER ENGINEERING, MINORS IN COMPUTER SCIENCE AND ROBOTICS

GPA: 3.9/4.0

- Coursework: Autonomous Field Robotics (Grad), Mobile Robotics (Grad), Robotics Sensing and Navigation (Grad), Computer Vision (Grad), High Performance Computing (Grad), AI, Object Oriented Design
- Involvement: MIT Ballroom Dance Team, Undergraduate Research, numerous hackathons, IEEE, Toastmasters, SASE, HKN, TBII

Skills

Interests Autonomous Robotics, Perception, Navigation, Mapping, Computer Vision
Languages Python, C++, C, CUDA, Java
Technologies ROS, OpenCV, OpenMP, MPI, MATLAB, Git, GDB, Linux, LCM, \LaTeX
Hardware IMUs, GPS, XBee Radio Modules, Teledyne Benthos Acoustic Smart Modems, Ethereum Miners

Technical Experience

Optimus Ride

Boston, MA

INCOMING ROBOTICS SOFTWARE CO-OP | MAPPING AND LOCALIZATION

Aug. 2019 - Dec. 2019

Amazon

Palo Alto, CA

SOFTWARE DEVELOPMENT ENGINEER INTERN | PERSONALIZED ALEXA CONVERSATION

May 2019 - Aug. 2019

Flex Innovation and Design Labs

Milpitas, CA

ROBOTICS SOFTWARE CO-OP

Jul. 2018 - Dec. 2018

- Primary software architect and developer of ROS based mobile robot in team of seven software and test engineers; project utilized six different languages, for seven unique pieces of hardware and ten different I/O peripherals.
- Integrated commercial SLAM system, fusing data from LIDAR, sonar, wheel encoders, and IMU. PoC for sensing and navigation software.
- Implemented several basic machine learning and deep neural net algorithms in Matlab to further technical understanding.

MIT Lincoln Laboratory

Lexington, MA

CO-OP TECHNICAL ASSISTANT, INTERIM SECRET CLEARANCE | GROUP 102 - OPEN AND EMBEDDED SYSTEMS

Jan. 2017 - Aug. 2017

- Independently parallelized radar signal processing chain in C++ using OpenMP and MPI to run in distributed multi-core Linux environments. Optimizations resulted in a **1700%** speedup and demonstrated hybridized MPI and OpenMP parallelizations met stringent performance requirements and reduced development costs.
- Automated benchmarking efforts through python and bash scripts to rapidly test and compare over **350** configurations.
- Leveraged analysis tools from the Intel Parallel Studio Suite and Allinea Forge for debugging and optimization.

Northeastern University Marine Observatory Network

Boston, MA

UNDERGRADUATE RESEARCH ASSISTANT (NSF REU)

Oct. 2015 - Jan. 2017

- Designed and implemented smart buoy and GUI control system using C++, QT framework, and XBee Radio modules to bridge above water radio network with subsea acoustic network.
- Implemented MAC protocols in MATLAB on Teledyne Benthos SM-975 Acoustic Smart Modems to advance understanding of modem interactions and compare efficacy of MAC protocols over acoustic channel.
- **Co-authored two papers and gave two major presentations** (see personal website for links)

Achievements

Spring 2019 **Tau Beta Pi**, Engineering Honor Society, Northeastern University
Spring 2018 **Eta Kappa Nu**, IEEE Student Honor Society, Gamma Beta Chapter, Northeastern University
Feb. 2017 **NU Talk 2017**, Presented to 300+ people on NU MONET underwater networking project
Dec. 2014 **Boy Scouts of America**, Eagle Scout (Bronze Palm)

Reference: Prof. Hanumant Singh, Northeastern University: ha.singh@neu.edu