# Learning Simulator User's Guide

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# 1 What is the Learning Simulator?

The Learning Simulator is a software for simulating a system consisting of two interacting dynamical systems – an *environment* and an *individual*. It can be used to simulate associative learning processes in animals.

The system operates in discrete time. In each time step, the environment presents a stimulus S to the individual that responds to this stimulus with a behavior B and as a result the environment presents S':

$$S \to B \to S'$$
.

The set of possible respones that the individual may present is called the individual's behavior repertoire. The presented stimulus S' may or may not depend on the response B to the previous stimulus S. The individual is assumed to have a pre-defined (genetic) value for each stimulus. It also has values for associations (associative strengths) between each stimulus in the environment and each response in the behavior repertoire. These values are updated in each time step. After  $S \to B \to S'$  has occurred, the associative value between S and B is updated, based on the pre-defined value of S'. If the individual's pre-defined value of the stimulus S' is high, the associative value between S and B increases more than if the pre-defined value of S' is low.

For example, if a mouse gets a reward after turning left in a T-maze (because there is food in the left arm of the maze), the associative value between the stimulus "intersection" and the response "turn left" increases. This in turn increases the probability that the mouse will turn left the next time it is presented with with the same stimulus "intersection".

The individual's response is determined by a decision function. This function computes a probability for each possible response to the presented

stimulus and then picks a response from the distribution defined by these probabilities. The probability of responding with the behavior B to the stimulus S increases with the associative value between S and B.

A typical example is an animal interacting in an experiment set up, for example a mouse that learns to press a lever to get a reward. In that case, the individual (the mouse) can be assumed to have two behaviors: press lever and don't press lever. The environment (the experiment set up) can present the stimuli lever, reward (presented to the mouse when lever is pressed), and no reward (presented when lever is not pressed).

In this case the Learning Simulator simulates how the mouse

# 2 Installation instructions

# 3 How to run the program

Use the control command lesim to run Learning Simulator. Below are the available options.

```
Listing 1: lesim syntax

python lesim.py
Short for "python lesim.py gui"

python lesim.py gui
Start the Learning Simulator gui

python lesim.py run file1 [file2, file3, ...]
Run the script files file1, file2, ...

python lesim.py help
Display this help and exit
```

# 4 Learning models

This section will introduce the learning models that can be simulated in the program. Figure 1 illustrates the system we want to study. The *organism* has an output function that generates behavior and state transition functions that update memories and other internal states. The world, which often is defined by an experiment, has an output function that generates stimuli and state transitions functions that update the state of the world, Both are

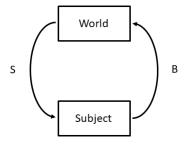


Figure 1: The world and the subject.

partly influenced by the behavior of the organism. Stimuli may not be fully informative about the state of the world.

A complete description of the whole system requires output functions and state transition functions for both the organism and the world including specifications of behavior and stimulus repertoires

The system will operate in discrete time steps and we need to specify a time scale. This scale could be different in different applications of the program and could be small. A natural time scale is the rate whereby the organism can respond or make decisions. An alternative is to alternate stimuli and responses:  $S_1 \to B_1 \to S_2 \to B_2 \to S_3 \to ...$ 

On top of this is the *experimental structure* in terms of trials and, training and test phases.

# 4.1 Stimuli and behavior

Stimuli may consist of combinations of *stimulus elements* (i.e. compound stimuli) and these elements must also be specified. There may also be variation in *stimulus intensity* (develop now or later?). Appendix 3 in Enquist et al. describes how combinations of elements and stimulus intensities can operate together.

#### 4.1.1 Notation

Table 1 shows the notation used.

## 4.2 The organism

The organism makes decisions about behavior B and learns from observations S. In dynamical systems terms decision making is an an output

Symbol	Description
E	A stimulus element
S	A stimulus which consists of one or more stimulus
	elements $\{E_1, E_2, \dots, E_k\}$ . The stimulus repertoire is a
	set of stimuli $\{S_1, S_2, \ldots, S_n\}$
I	Intensity?
B	A behavior. The behavior repertoire is a set of
	behaviors $\{B_1, B_2, \ldots, B_m\}$ .

Table 1: The notation for stimuli and behavior.

function and state transition functions updates memories and other state variables in the organism.

## 4.2.1 Notation

Table 2 shows the notation used.

Symbol	Description		
$v_{S \to B}$	Learned value of choosing $B$ in response to $S$ (has		
	inborn start value)		
$u_S$	The inborn (primary, initial) value of $S$		
$w_S$	The learned contribution/modification to the value of $S$		
	(initial value 0)		
$u_S + w_S$	The value of choosing $B$ in response to $S$		
$r_S$	The value of choosing $B$ in response to $S$ without a $u$		
	and $w$ division		
$\alpha, \alpha_v, \alpha_w$	Learning rates.		

Table 2: The notation for stimuli and behavior.

Traditionally v is referred to a stimulus-response associations. We sometimes refer to stimulus-response value because v can be interpreted as an estimate of the value of responding with B towards S.

# 4.2.2 The output function (generates stimuli)

Stimulus representation: In all mechanisms developed so far, responding is only based on the current stimulus. Possible developments that would change this include the introductions of stimulus traces and stimulus

**sequences**. (we leave this for the future). For decision making (output function) we for now, use a version of the soft max rule:

$$\Pr(S \to B_i) = \frac{\operatorname{Support}(B_i)}{\sum_j \operatorname{Support}(B_j)} = \frac{\exp(\beta v_{S \to B_i})}{\sum_j \exp(\beta v_{S \to B_j})}$$

where  $\beta$  regulates the amount exploration or degree of variation in responding (lower  $\beta$  more exploration). If  $S = (E_1, E_2, ...)$  is a compound of stimulus elements the expression changes to

$$\Pr(S \to B_i) = \frac{\exp(\sum_k \beta v_{E_k \to B_i})}{\sum_j \exp(\sum_k \beta v_{E_k \to B_j})}$$

Possible developments (to be implemented later) include making the value of  $\beta$  dependent on E and/or B.

This would introduce genetic predispositions that could guide exploration in profitable directions. Other developments include adding internal states such a clocks and regulatory states.

# 4.2.3 State transition functions (memory updates etc.)

The learning described in the table occurs after observing

$$S \to B \to S'$$
.

# 4.2.4 Adding cost to behavior

In some cases it is important to add a cost to certain responses. This can be done in the following way in our model by replacing

$$\Delta v_{S \to B} = \alpha_v (u_{S'} + w_{S'} - v_{S \to B})$$

with

$$\Delta v_{S \to B} = \alpha_v (u_{S'} + w_{S'} - c_B - v_{S \to B})$$

<sup>&</sup>lt;sup>1</sup>Bush and Mosteller [1951], Rescorla & Wagner [1972]

<sup>&</sup>lt;sup>2</sup>Watkins [1989], Watkins & Dayan [1992]

<sup>&</sup>lt;sup>3</sup>Rummery & Niranjan [1994]

 $<sup>^4</sup>$ van Seijen & van Hasselt & Whiteson & Wiering [2009]

<sup>&</sup>lt;sup>5</sup>Witten [1977], Barto et al. [1983]

<sup>&</sup>lt;sup>6</sup>Enquist et al. [2016]

Mechanism	Memory	Memory updates
	states	
Stimulus-	$v_{S \to B}$	$\Delta v_{S \to B} = \alpha (r_{S'} - v_{S \to B})$
Response		
Learning <sup>1</sup>		
Q-Learning <sup>2</sup>	$v_{S \to B}$	$\Delta v_{S \to B} = \alpha (r_{S'} + \max_i v_{S' \to B'_i} - v_{S \to B})$
SARSA <sup>3</sup>	$v_{S \to B}$	$\Delta v_{S \to B} = \alpha (r_{S'} + v_{S' \to B'} - v_{S \to B}) *$
Expected	$v_{S \to B}$	$E(v_{S'\to B'}) = \sum_{i} \Pr(S'\to B'_i) v_{S'\to B'_i}$
SARSA <sup>4</sup>		$\Delta v_{S \to B} = \alpha (r_{S'} + E(v_{S' \to B'}) - v_{S \to B})$
		$\delta = u_{S'} + w_{S'} - w_S$
Actor-critic <sup>5</sup>	$v_{S\to B}, w_S$	$\Delta v_{S \to B} = \alpha_v \delta$
		$\Delta w_S = \alpha_w \delta$
Our model <sup>6</sup>	$v_{S\rightarrow B}, w_S$	$\Delta v_{S\to B} = \alpha_v (u_{S'} + w_{S'} - v_{S\to B})$
Car moder	$\downarrow^{c_S \to B}, w_S$	$\Delta w_S = \alpha_w (u_{S'} + w_{S'} - c_B - w_S)$

<sup>\*</sup> In SARSA, the updating is done after observing  $S \to B \to S' \to B'$ .

Table 3: Learning mechanisms and their memory updates.

where  $c_B$  is the cost of B. I guess one should also change the updating of w and v to

$$\Delta w_S = \alpha_w (u_{S'} + w_{S'} - c_B - w_S)$$
$$\Delta v_{S \to B} = \alpha_{(v)} (\dots - c_B)$$

Such cost can also be introduced into the other models.

# 4.3 The world

The world receives behavior from the organism and responds with stimuli. A description of a world specifies how stimuli are generated and how state variables are updated.

# 4.3.1 Pavlovian world

## 4.3.2 Linear world

# 4.3.3 Social learning world

# 5 The scripting language

The input to Learning Simulator is a script. It is specified as plain text in the main window. If a script is stored in a text-file, this file can be opened into the main window using the **File**-menu. It is also possible to run the script in a text-file using the command line syntax

```
python lesim.py run file1 [file2, file3, ...]
```

as shown in Listing 1.

# 5.1 Lists

In several parts of the script, a list of items should be specified. What we mean by a list is a list of items separated by space, comma, tab, or new line. For example, a list of the stimulus elements S1, S2, S3, and S4 may look like

```
or
S1 S2, S3
S4
```

# 5.2 The script sections

A Learning Simulator script consists of a number of sections. Each section starts with a keyword and each keyword starts with c. The keywords are CVARIABLES, CPHASE, CRUN, and CFIGURE.

Below follows the description of each of these sections.

## 5.3 Comments

On each line in the script, any text to the right of a hash-character # is ignored, and may therefore be used to make your own comments to the script. For those of you familiar with the Python programming language, this corresponds to code comments. All leading and trailing spaces and tabs on each line are also ignored.

To make multi-line comments, use two triple-hashes ### on separate lines, one before the multi-line comment, and one after.

```
Listing 2: Script comments

@VARIABLES
stop_cond: 10  # The number of repeats
var1: 42  # Variable 1
# Here is another variable
var2: 33

###
This is a way to write
```

```
a multiline comment.

The three hashes must come in pairs.

###

# Of course, one can also do

# this for multiline comments.
```

#### 5.4 QVARIABLES

The @VARIABLES section sets the numeric values of variables that can be used throughout the script. The variables are specified as a list of name:value after the @VARIABLES statement. Thus, the line has the form

```
@VARIABLES name1:value1, name2:value2, ...
```

The variable names must start with a letter, followed by letters, digits, or underscores. The value walue must be interpretable as a number.

```
Listing 3: @VARIABLES example

@VARIABLES var1:1.2 var2:3.4 var_3:567
```

# 5.5 Parameters

The parameters to a simulation specifies which learning algorithm to use, how many subjects to simulate, the behavior repertoire of the subject, available stimulus elements in the world representation, etc. Each parameter specification has the form

```
parameter_name: parameter_value
```

and can be placed on a new line anywhere in the script. However, for readability, it may be a good idea to put them all together in a group in the beginning of the script. However, it is possible to change the value of any parameter anywhere in the script. The valid parameters and values can be found in Table 4. Parameters without a default value are required.

An example can be found in Listing 4.

Listing 4: An example of setting parameters

# Parameters
subjects : 10
mechanism : GA
behaviors : RO R1 R2

# 5.5.1 Stimulus elements and the behavior repertoire

The behavior repertoire behaviors as well as the stimulus elements stimulus\_elements are specified as a list of names. These names must be valid variable names (see Section 5.4), but they cannot be parameter names, e.g., u, beta, or bind. See listing 5 for an example that also uses comments.

```
Listing 5: behaviors and stimulus_elements

behaviors: escape, stay
stimulus_elements:
    snake  # Subject sees a snake
    neutral # A neutral stimulus
    warning # Warning sound
    bitten # Subject being bitten
```

#### 5.5.2 Initial *v*-values

The initial value for  $v_{S,B}$  is specified as S->B:val1 where S is a stimulus element, and B is a behavior. To specify several different values, use a list:

```
start_v: S1->B1:val1, S2->B2:val2, ...
```

The v-value for all remaining (S, B)-pairs is specified using the keyword default:

```
start_v: S1->B1:val1, S2->B2:val2, ..., default:default_value
```

This will set the v-values of each specified pair to the specified value, and all others to default\_value. If all initial v-values are the same, for example 1, use the form

```
start_v: default:1
```

or, shorter

start\_v: 1

```
Listing 6: start_v start_v: snake->escape:-1, warning->escape:-1, default:0.5
```

#### 5.5.3 Response requirements

Use the parameter response\_requirements if not all behaviors are possible responses to each stimulus element. For example, if the behavior B is a possible response to only a subset 1, S2, ...S1, S2, ... of the stimulus elements, this is specified as

```
B: S1, S2, S3, ...
```

Each behavior that is restricted to a subset of the stimulus elements is specified as a list of items of the above type, so for several behaviors it looks like this:

```
B1: S11, S12, S13, ...
B2: S21, S22, S23, ...
```

The behaviors in behaviors that are not included in this list are assumed to be possible responses to all stimulus element in stimulus\_elements.

See listing 7 for an example.

## 5.5.4 Bind learning between trials

When a phase (see Section 6) uses trials, use the parameter bind\_trials to control whether or not to update the v- and w-values also when reaching the first stimulus in a trial. In other words, in the situation

$$S \to B \to S'$$

where S' is the first stimulus in a trial, bind\_trials controls whether S' should affect the updating of  $v_{S\to B}$  and  $w_S$ .

In most cases, this updating should not be done, which corresponds to bind\_trials: off, which is the default.

## 6 QPHASE

A world, which presents stimuli to the subject (where a stimulus may or may not depend on the subject's response to the previous stimulus), consists of one or more *phases*. The **QPHASE** section in a script specifies which stimuli are presented, in which order and how they depend on responses. Each phase also has a *phase label* and a *stop condition*.

A @PHASE section consists of a number pf phase lines. Each phase line consists of a label, an optional stimulus and a logical part. The latter specifies the subsequent stimulus (through a phase line label) and how it depends on the subject's response (if it does). The phase starts at the phase line called @start\_trial, if there is one (see Section 6.1). Otherwise the phase starts at the first (topmost) phase line. The basic syntax of a @PHASE section is as follows:

```
Listing 8: The basic syntax of a @PHASE section

@PHASE phase_label
stop:stop_condition
lbl1 stimulus1 | logic1
lbl2 stimulus2 | logic2
lbl3 stimulus3 | logic3
...
```

The label (phase\_label in the above listing) should be a string (without separators such as commas and spaces) that provides a means of specifying which phases to include in a simulation (see the @RUN statement in Section 7). The stop condition ( $stop\_condition$  in the above listing) has the form str=N where str is an event (a stimulus element, a response, or a phase line label), and N is a positive integer. When the specified event has occurred N times, this condition is fulfilled and the phase ends. If there is a phase following the ended phase, the first line of that phase will be the current one. Otherwise it ends the simulation. For example, stop: reward=20 ends the phase after 20 exposures to the stimulus stop: reward=20 ends the stop condition is typically of the type  $start\_trial=N$ .

Each stimulus (stimulus1, stimulus2, ... in the above listing) is specified either as a single stimulus element or a compund stimulus consisting of a number of simultaneous stimulus elements. To specify a compond stimulus, separate the elements with comma, for example E1,E2.

Each logic part (logic1, logic2, ... in the above listing) consists of one or more cases, separated by |. Each case must have the form

condition: goto

or simply

#### goto

The format of condition and goto can be found in Tables 5 and Tables 6, respectively.

When using multiple cases, separated by |, this is interpreted as an if-else statement. For example, the interpretation of the logic part

```
R1:row1 | R2:row2 | row3
```

can be found in Listing 9.

```
Listing 9: Interpretation of R1:row1 | R2:row2 | row3

if the response was R1:
    go to row1

else if the response was R2:
    go to row2

else:
    go to row3
```

## Example 1 The phase line

#### L1 s1 | L2

exposes the subject to the stimulus element \$1, then proceeds to the phase line with label L2.

# **Example 2** The phase line

```
L1 s1 | countrow(5):L2(0.2),L3(0.8) | L1
```

exposes the subject to the stimulus element  ${\tt s1}$  five times, then proceeds to the phase line with label L2 with probability 20% and to L3 with probability 80%.

**Note** The three logical parts in Listing 10 are equivalent.

```
Listing 10: Three equivalent logical parts

row1(1/3),row2(1/3),row3(1/3)

row1(1/3) | row2(1/2),row3(1/2)

row1(1/3) | row2(1/2) | row3
```

#### 6.1 Trials

It is common to divide a phase into repeated *trials*. A trial is a sequence of stimulus-response pairs representing ...

To use trials in a phase, label the phase line that starts the trial with <code>@new\_trial</code>. The phase will then start at this phase line. The parameter <code>bind\_trials</code> controls whether the *u*- and *w*-values will be updated between phases.

Example...

# 6.2 Counting events with count and countrow

During the course of a phase, all events (phase labels, stimulus elements, and behaviors) are counted. You can access these numbers using the count and countrow keywords. These may be used in the logic part of a phase line, in a condition for the subsequent phase line.

The function count counts the number of occurrences of an event since the beginning of the phase. You can reset this counter within a phase using the count\_reset keyword. The count\_reset keyword can only be used in a non-stimulus phase line, to the left of the | character.

The function count\_row counts the number of occurrences of an event since the current phase line was entered, and is automatically reset when leaving the phase line. This counter cannot be manually reset.

The functions count and countrow can be used in conditions in the logic part of a phase line:

```
ROW1 S1 | count(ROW1)=5:ROW2 | ROW1
```

which repeats the stimulus S1 five times, then proceeds to row ROW2.

Note that variables (see Section 5.4) may be used:

```
ROW1 | S1 | count(S1)=var1:ROW2 | ROW1
```

# 6.3 Generating a random integer

The function random can be used to set a variable (see Section 5.4) to a random integer. The syntax is

```
var = random(x,y)
```

which generates a random integer from x to y (including x and y) with equal probability, and sets var to that value. For example,

```
var1 = random(1,3)
var2 = random(10,11)
```

sets var1 to 1, 2 or 3, each with probability 1/3, and var2 to 10 or 11, each with probability 1/2.

# 6.4 Help lines

A phase line does not have to contain a stimulus. You may use a *help line* in a phase description to handle more complicated conditions than what is available using the if-elseif-else interpretation of repeated | (see Listing 9). The logical OR

```
if response was A OR B:
    go to ROW2
else:
    go to ROW1
```

can be accomplished without a help line:

```
ROW1 S1 | A:ROW2 | B:ROW2 | ROW1
```

However, to accomplish the logical AND

```
if response was A AND count(S1)=5:
    go to ROW2
else:
    go to ROW1
```

the following construction with the help line A\_TRUE can be used:

```
ROW1 S1 | A:A_TRUE | ROW1
A_TRUE | count(S1)=5:ROW2 | ROW1
```

A help line must also be used when resetting a counter using count\_reset, which cannot be done on a regular phase line. For example,

```
ROW1 count_reset(A) | ROW2
```

A help line must also be used when setting a variable defined in the @VARIABLES section. This cannot be done on a regular phase line. For example,

```
ROW1 count_reset(A) | ROW2
```

# 6.5 Phase examples

A few examples of **Ophase** sections can be found in Listings 11 to 18.

```
Listing 11: Three Ophase sections for classical conditioning
@phase {'labels':'pretraining', 'end':'reward=25'}
                          | 25:US | CONTEXT
CONTEXT 'context'
US
       ('US','context')
                          | 'R': REWARD | CONTEXT
REWARD ('reward','context') | CONTEXT
@phase {'label':'conditioning', 'end':'CS=25'}
CONTEXT 'context' | 25:CS | CONTEXT
       ('CS','context')
                          | US
CS
       ('US','context') | 'R': REWARD | CONTEXT
US
REWARD ('reward', 'context') | CONTEXT
@phase {'label':'test', 'end':'CS=25'}
CONTEXT 'context' | 25:CS | CONTEXT
CS
       'CS', 'context' | CONTEXT
```

```
Listing 12: A @phase section for fixed interval

@phase {'label':'fixed_interval', 'end':'reward=25'}

OFF 'lever' | 4:0N | OFF

ON 'lever' | 'R': REWARD | ON

REWARD 'reward' | OFF
```

```
Listing 13: A @phase section for fixed ratio

@phase {'label':'fixed_ratio', 'end':'reward=25'}

OFF 'lever' | 'R'=4: ON | OFF

ON 'lever' | 'R': REWARD | ON

REWARD 'reward' | OFF
```

```
Listing 14: A @phase section using a probability schedule

@phase {'label':'prob_schedule', 'end': 'reward=25'}

LEVER 'lever' | 'R': REWARD(0.2) | LEVER

REWARD 'reward' | LEVER
```

```
Listing 15: Two equivalent @phase sections for variable interval

@phase {'label':'variable_interval1', 'end': 'reward = 25'}

FI3 'lever' | FI3=2:0N | FI3

FI2 'lever' | FI2=1:0N | FI2

ON 'lever' | 'R':REWARD | ON

REWARD 'reward' | ON(1/3),FI2(1/3),FI3(1/3)
```

#### Listing 16: Two equivalent Cphase sections for variable ratio @phase {'label':'variable\_ratio1', 'end': 'reward = 25'} FR3 'lever' | 'R'=2:0N | FR3 FR2 'lever' | 'R'=1:ON | FR2 | 'R': REWARD | ON ON 'lever' REWARD 'reward' | ON(1/3), FR2(1/3), FR3(1/3)@phase {'label':'variable\_ratio2', 'end': 'reward = 25'} R3 'lever' | 'R':R2 | R3 R2 'lever' | 'R':ON | R2 ON 'lever' | R:REWARD | ON REWARD 'reward' | ON(1/3), R2(1/3), R3(1/3)

```
Listing 17: A @phase section for reward after a fixed time

@phase {'label':'fixed_time', 'end':'reward = 25'}

LEVER 'lever' | 5: REWARD | LEVER

REWARD 'reward' | LEVER
```

```
Listing 18: A @phase section for reversal learning

@phase {'label':'lever_1_rewarded', 'end': 'CHOICE = 100'}
CHOICE 'two_levers' | 'lever 1':REWARD | CHOICE
REWARD 'reward' | CHOICE

@phase {'label':'lever_2_rewarded', 'end': 'CHOICE = 100'}
CHOICE 'two_levers' | 'lever 2':REWARD | CHOICE
REWARD 'reward' | CHOICE
```

# 7 @RUN

The @RUN section specifies and runs a simulation. See Listing 19 for the syntax.

```
Listing 19: Syntax for a @RUN section
@RUN
```

```
@RUN run_label

@RUN run_label
phase1, phase2, ...
```

run\_label is the name of the simulation run. If there are several @RUN sections in a script, run\_label are used in the postprocessing commands to, e.g., plot the output from one specific run. If run\_label is omitted, the simulation will be given the automatic label run1, run2 and so on, numbered consecutively in order.

The phases to use in the simulation are specified as a list of phase names on a separate line within the QRUN section. This is optional – if there is no such line of phase names, all phases defined above the Qrun-statement will be used.

It is also possible to override any parameter in the QPARAMETERS section, which then is only used locally within this QRUN section. For example, in the QRUN section in Listing 20, the mechanism SR and the  $\beta$ -value 0.2 is used, despite any other values specified in QPARAMETERS.

```
Listing 20: Example of overriding parameters in a @RUN section

phase = phase1, phase2
mechanism: SR
beta: 0.2
@RUN
```

# 8 Visualization commands

The commands for visualizing simulation data can be found in Table 7.

The commands @vplot, @wplot, @pplot and @nplot produces plots in the current axes. Axes objects are created using the @subplot command (see section 8.4). If a plot command is not preceded by a @subplot command, a default axes is created.

# 8.1 @vplot, @wplot, @pplot

The syntax for Cvplot, Cwplot, and Cpplot can be found in Listing 21.

```
Listing 21: Syntax for @vplot, @pplot and @wplot

@vplot E->R options
@pplot S->R options
@pplot E->R options
@wplot E options
```

Here, E is a stimulus element, R is a behavior, and S a list of stimulus elements. The argument options is a list of option:value where possible options and values are described in section 8.1.1.

#### 8.1.1 The options

The supported options to the visualization commands can be found in Table 8.

The option subject only has effect if the option subjects is > 1. When specifying a certain subject, use a zero-based index. For example, if the parameter subjects is 4, the valid integer values for the option subject are 0, 1, 2 and 3. If subject is all, one plot per subject will be rendered. If subject is average, the plotted quantity is the average over the subjects.

When a simulation has been completed after a **@run** statement, the simulation history

$$H = (S_1, R_1, S_2, R_2, S_3, R_3, \dots)$$
 (1)

is a sequence of alternating stimuli and responses, where each  $R_i$  is the response to  $S_i$ . We call H the *history sequence* for the simulation.

Each stimulus-response pair constitutes a time-step in the simulation, starting with time step 0. Below, the time-steps in the sequence history (1) are indicated.

$$\begin{vmatrix} S_1, R_1, & S_2, R_2, & S_3, R_3, & \dots \\ t=0 & t=1 & t=2 & t=4 \end{vmatrix}$$

The option steps controls at which time-steps to plot the quantity in question. The first (time-step 0) and the last time step are always included. The default value is all which plots at each time-step, i.e. the value after each stimulus-response pair. In this case, the x-axis will be from 0 to the total number of time-steps. If steps is a string or a tuple of strings, the plot will only display the value after each occurence of this string/tuple (and at the first and at the last time-step). In this case, the value at x = i in the plot is the value after the ith occurence of the string/tuple in the history sequence. If steps is a list where every other element in a stimulus and ever other element a response, the plot will only reflect the value after each occurence of the stimulus-responses in the history sequence H.

The option xscale\_match only has effect when xscale is not all, in other words when xscale is a search pattern.

If  $xscale\_match$  is off, when searching for a string s, it is also counted as a hit if a tuple S in H (a stimuli composed of a number of stimulus

elements) includes s, i.e.  $s \in S$ . When searching for a tuple t, it is also counted as a hit if a tuple S in H includes t (as sets), i.e.  $t \subseteq S$ .

If  $xscale_match$  is on, the pattern searched for must exactly match the history sequence H.

For example, if the history sequence is

$$\begin{vmatrix} E_1, R_1, & E_1, E_2 \\ E_1, E_2, & E_3, & E_1, E_3 \\ E_2, & E_3, & E_4, & E_5 \\ E_3, & E_4, & E_5 \\ E_4, & E_5, & E_6 \\ \end{vmatrix}$$

and xscale is  $E_1$ , the plot will be rendered at time steps t=0,1,2,4,6 if xscale\_match is subset. If xscale\_match is exact, the plot will be rendered at time steps t=0,1,6.

### 8.2 Onplot

The command @nplot searches for specific elements in the history sequence H, counts the number of hits at time steps specified with the steps option, and plots the result.

The syntax of Onplot is

# Listing 22: Syntax for @nplot @nplot expr options

Here, the options are the same as in section 8.1.

The argument expr is either a stimulus element, a response, a list of stimulus elements (for a compound stimulus), or a consecutive subsequence  $S1\rightarrow R1\rightarrow S2\rightarrow R2\rightarrow \ldots$  of the history sequence H, where each Si is a stimulus element or a list of stimulus elements (a compund stimulus). In other words, it works similarly to the xscale property described in section 8.1.1. Thus, it can search for a specific stimulus element (for example reward), a specific response (for example R) or a specific compund stimulus consisting of several stimulus elements (for example E1,E2,E3) in H and plot the result.

Onplot can also search for any consecutive subsequence in H using a list (for example context,reward->R) which counts the number of times the compound stimulus context,reward got the response R.

As options options, @nplot supports the properties in Table 8. In addition, the properties in Table 9 are supported.

The property cumulative should be on (default) or off. This option controls whether the counting should be at each time-step (in which case each value on the y-axis in the plot is either 0 or 1) or cumulatively (in which case the resulting plot is a non-decreasing function).

The property match should be on (default) or off. It controls whether the searching for expr in H should be exactly fulfilled or only inclusive, just like the property xscale\_match described in section 8.1.1.

# 8.3 Ofigure

The Ofigure command creates a figure window.

```
Listing 23: Syntax for Offigure
Offigure title figure_options
```

where title is a string used as the title for the figure, and figure\_options is a dictionary with the keywords to matplotlib.figure.Figure controlling the figure size, the figure patch facecolor and edgecolor, etc.<sup>7</sup>

# 8.4 @subplot

The @subplot command creates an axes in which to plot.

```
Listing 24: Syntax for @subplot
@subplot grid subplot_options
```

where grid is three nonzero digits specifying (i) the number of rows, (ii) the number of columns in a grid of axes, and (iii) in which grid cell to place the axes. For example, 211 produces a subaxes in a figure which represents the top plot (i.e. the first) in a 2 row by 1 column notional grid. The options subplot\_options is a dictionary with the keywords to matplotlib.pyplot.subplot controlling, for example, the background color of the subplot.<sup>8</sup>

The @subplot command creates an axes in the figure created by the preceding @figure command. If a @subplot command is not preceded by a @figure command, a default figure window is created.

# 8.5 @legend

The **@legend** command places a legend on the current axes.

 $<sup>^7\</sup>mathrm{See}$  https://matplotlib.org/api/\_as\_gen/matplotlib.figure.Figure.html for the supported options.

<sup>&</sup>lt;sup>8</sup>See https://matplotlib.org/api/pyplot\_api.html#matplotlib.pyplot.subplot for the supported options.

# Listing 25: Syntax for @legend

```
@legend labels legend_options
```

where labels is a string or a tuple of strings for custom labels. If not specified, automatic labels will be used. The options legend\_options is a dictionary with the keywords to matplotlib.pyplot.legend controlling the font size, the legend's background color, etc.<sup>9</sup>

# 8.6 Some examples of plotting commands

Listing 26 shows some examples of the use of the visualization commands Offigure, Osubplot, Ovplot, Ouplot, Onplot, and Olegend. It is assumed to be preceded by Orun run1 and Orun run2 that run two simulations.

```
Listing 26: Some examples of plotting commands
# Plot v(S,R) in a default axes in a default figure
@vplot S->R
# Plot v(S,R) as a red dashed line in the same axes as
# the above plot
@vplot S->RO linecolor:red, linestyle:dashed
# Plot w(S) with dot-markers in a blue axis in a yellow
# figure with figure title "Figure Title"
Ofigure Figure Title
facecolor: yellow
@subplot 111 facecolor:blue
Owplot S marker:.
# Plot p(S,R) from simulation run1 together with p(S,R)
# from simulation run2, and add a custom legend
@figure
@pplot S->R
    runlabel:run1
    label:p(S,R) run1
@pplot S->R runlabel:run2
    label:p(S,R) run2
@legend
# Plot n(R0) and n(R) in the same axes
@figure
nplot RO
nplot R
```

<sup>&</sup>lt;sup>9</sup>See https://matplotlib.org/api/pyplot\_api.html#matplotlib.pyplot.legend for the supported options.

```
# Plot n(R0) and n(R) in two subplots
@figure
@subplot 211
nplot R0
@subplot 212
nplot R
```

# 9 Exporting data

Each plotting command has a corresponding data export command, which exports the data to an external csv-file. In addition the **@hexport** command exports a history sequence of stimulus-response pairs. The export commands can be found in Table 10.

The syntax for the export commands can be found in Listing 27.

```
Listing 27: Syntax for @vplot, @pplot, @wplot and @nplot

@vexport (E,R) value_options

@pexport (E,R) value_options

@wexport E value_options

@nexport expr value_options

@hexport value_options
```

As value-options value\_options, the data export commands @vexport, @wexport, @pexport, and @nexport supports the same properties as the corresponding plot command (see Table 8 and Table 9). In addition, the properties in Table 11 are supported. The command @hexport only supports the parameters runlabel and filename.

# 9.1 Format of the csv-file

The data export commands exports the data as a csv-file with two or more columns. The first column contains step numbers (corresponding to the x-axis in the corresponding plot command). The second column onwards contains the data for the specified quantity for each subject (controlled by the subject parameter).

The @hexport command exports a csv-file with three or more columns. Column 1 contains step numbers. Columns 2 and 3 contains the stimulus and response, respectively, for subject 1. Column 4 and 5 contains the stimulus and response, respectively, for subject 2, etc. All subjects are included.

# 10 Changing individual parameters or phase lines

The scripting language supports editing individual parameters and phase lines. For example, after a simulation with a given set of parameter values, it is possible to change the value of one of them and run a simulation again. See Listing 28 for an example.

Listing 28: Changing an individual parameter @parameters 'subjects' : 1 : 'Enquist', : ['R','R1'], 'mechanism' 'behaviors' 'stimulus\_elements' : ['context','reward','US','CS','lever'], 'start\_v' : {'context':-1,'default':0}, 'start\_w' : {'default':0}, 'alpha\_v' : 1, 'alpha\_w' 'beta' 'behavior\_cost' : {'R':1,'default':0}, u', : {'reward':10, 'default': 0}, 'omit\_learning' : ['US', 'CS'] @phase {'label':'fixed\_time', 'end':'reward = 25'} 'lever' | 5: REWARD | LEVER LEVER REWARD 'reward' | LEVER @run {'label':'beta=1'} @parameters { 'beta':0.5 @run {'label':'beta=0.5'}

It is also possible to change an individual phase line without having to specify the entire phase again. See Listing 29.

Parameter name	Value	Default	Description
subjects	A positive integer	1	The number of
			subjects
mechanism	GA (Genetically Guided		Which learning
	Associative Learning),		mechanism to use
	SR (Stimulus-Response		(see Table 3)
	learning),		
	ES (Expected SARSA),		
	QL (Q-learning),		
	AC (Actor critic)		
behaviors	A list of behavior names		The behavior
			repertoire (see
			Section 5.5.1)
stimulus_elements	A list of stimulus element		The possible stimulus
	names		elements (see Section
	A 1 1 1 1 C		5.5.1)
start_v	A number, or a list of	0	The initial v-values
	(S,B):val and default:val		(see Section 5.5.2)
	where Sestimulus_elements, Bebehaviors and val is a		
	number		
alpha_v	See start_v	1	
alpha_w	A number, or a list of S:val	1	$\alpha_v$
arpna_w	and default:val where	1	$\alpha_w$
	Sestimulus_elements and		
	val is a number		
beta	A number	1	β
behavior_cost	A number, or a list of B:val	0	The cost for each
50001101_0020	and default: val where		behavior
	Sebehaviors and val is a		Solidavioi
	number		
u	See alpha_w	0	The u-values
	A list of $B:S_1,S_2,\ldots$ where	No re-	The available
response_requirements	B∈behaviors and	strictions	stimulus elements for
	$\mathtt{S}_i \in \mathtt{stimulus\_elements}$		each behavior (see
			Section 5.5.3)
bind_trials	on or off	off	Whether ot not to
			bind learning between
			trials (see
			Section 5.5.4)

Table 4: The parameters.

Case	Description	
countrow()=N	If this line has been visited N	
	times consecutively.	
countrow(e)=N	If event e has occured on this	
	line N times (since this line was	
	entered). The event <b>e</b> is either a	
	stimulus element or a response.	
count(e)=N	If event e has occured on this	
	line N times (since the start of	
	the phase or since it was last	
	reset with count_reset(e)).	
	The event <b>e</b> is either a line	
	label, a stimulus element or a	
	response.	
var=N	If the variable var has the value	
	N.	
R	If the response to the stimulus	
	on this line was R.	

Table 5: The format of condition in a logic case in a phase line.

Case	Description	
lbl	Go to the line with label 1b1.	
1b1(p)	Go to the line with label 1b1	
	with probability $p$ .	
$ exttt{lbl1}(p_1),  exttt{lbl2}(p_2), \dots,  exttt{lblN}(p_N)$	Go to 1b11 with probability $p_1$ ,	
	to 1b12 w.p. $p_2$ , etc.	

Table 6: The format of goto in a logic case in a phase line.

Command name	Purpose		
@vplot	Plots a <i>v</i> -variable against time-steps as a		
	line plot		
@wplot	Plots a w-variable against time-steps as a		
	line plot		
@pplot	Plots a probability (of a specific response		
	to a specific stimulus) against time-steps		
	as a line plot		
@nplot	Plots the number of occurences of a		
	specific stimulus, stimulus element,		
	behavior or a sequence of them		
@figure	Creates a figure window to hold axes		
	objects		
@subplot	Creates an axes object to hold the plots		
@legend	Creates a legend for line labels		

Table 7: The visualization commands

Parameter	Value	Default	Description
runlabel	A string	The label	The @run label
		of the last	
		@run	
subject	An integer (zero-based	'average'	Which subjects
	index) or 'average' or		to include
	'all'		
xscale	'all' or a string or a	'all'	The steps at
	tuple or a list		which to plot
	'exact' or 'subset'	'subset'	Use exact or
xscale_match			subset matching
			for steps
phase	A string or a tuple of	All phases	Which phase(s)
	strings		to include

Table 8: The value-options to  ${\tt @vplot}, {\tt @wplot}, {\tt @pplot}$  and  ${\tt @nplot}.$ 

Parameter	Value	Default	Description
cumulative	'on' or 'off'	'on'	Cumulative
			counting
match	exact or subset	subset	Use exact
			matching for
			expr

Table 9: The additional value-options to  ${\tt Qnplot}.$ 

Command name	Purpose		
@vexport	Exports data for a <i>v</i> -variable against		
	time-steps		
@wexport	Exports data for a w-variable against		
	time-steps		
@pexport	Exports probabilites (of a specific		
	response to a specific stimulus) against		
	time-steps		
@nexport	Exports data for the number of		
	occurences of a specific stimulus, stimulus		
	element, behavior or a sequence of them		
@hexport	Exports the stimulus-response pair for		
	each step, together with the step		
	numbers.		

Table 10: The export commands.

Parameter	Value	Default	Description
filename	String		CSV-file name

Table 11: The additional value-options to the export commands.