

1. Pe  $\mathbb{Z}$

Relația  $x R y \Leftrightarrow x = y^2$

Verificăți proprietățile acestei relații

Reflexivitate

Fie  $x \in \mathbb{Z}$   $x \neq x^2 \Rightarrow R$  nu e reflexivă

Dacă vom să arătăm că o proprietate  
nu are loc, trebuie să o arătăm pentru toate  
elementele

Dacă vom să arătăm că o proprietate  
nu are loc, e suficient să găsim  
un contrăstemplu

Simetria

Fie  $x, y \in \mathbb{Z}$  a.i.  $x R y \Rightarrow x = y^2$

$$\underline{x \geq 0}$$

$$y = \pm \sqrt{x} \quad (\bullet)$$

Pf că să aibă loc  $yRx$  ar trebui ca  
 $y = x^2$  să fie și contradicție)

Care 2 nu îl negă și  $x = y^2$  dar  
 $y \neq x^2$

$$x = 4, y = 2 \quad 4R2 \text{ dar } 2R4$$

$\Rightarrow R$  nu este simetrică

Antisimetrică

$$\text{Fie } x, y \in \mathbb{Z} \text{ a.i. } \begin{array}{l} \cancel{xRy} \Rightarrow x = y^2 \\ \cancel{yRx} \Rightarrow y = x^2 \end{array}$$

$$x = (x^2)^2 \Leftrightarrow$$

$$x = x^4 \Rightarrow$$

$$x^4 - x = 0$$

$$x(x^3 - 1) = 0 \rightarrow x = 0 \rightarrow y = 0$$
$$x = 1 \rightarrow y = 1$$

$$x > y$$

$\rightarrow R$  antisimetrică

Transitivitatea

Fie  $x, y, z \in \mathbb{Z}$

$$x R y \rightarrow x = y^2 \quad x = (z^2)^2$$

$$y R z \rightarrow y = z^2 \quad \underline{x = z^4} \leftarrow \text{Stiu}$$

$\longrightarrow$

$$x R z ? \Leftrightarrow \underline{x = z^2} \leftarrow \text{Vreau}$$

$$\begin{array}{lll}
 x = 16 & 16 = 4^2 \rightarrow 16 R 4 \\
 y = 4 & 4 = 2^2 \rightarrow 4 R 2 \\
 z = 2 & \\
 & 16 \not R 2
 \end{array}$$

$\rightarrow R$  nu e transitiivă

→

Pentru ca nu este

$$x \neq y$$

Fie  $x, y \in \mathbb{R}$  a.s.

$$\begin{array}{c}
 x \neq y \\
 \hline
 \text{d} \vdash y \neq x
 \end{array}$$

$x \neq y \Rightarrow y \neq x$  deci nu este  
simetrică

Pe  $\mathbb{Z}$

$$a << b \Leftrightarrow \exists c \in \mathbb{N} \text{ a.s.t. } \underline{b - a = c}$$

Dacă  $<<$  este relație de ordine totală pe

$$\mathbb{Z}, \quad \rightarrow 12:30$$

Reflexivitate: Fie  $a \in \mathbb{Z}$   $\exists 0 \in \mathbb{N}$  a.s.t.

$$a - a = 0 \Rightarrow a << a \quad \forall a \in \mathbb{Z} \Rightarrow << \text{reflexivă}$$

Antisimetrie Fie  $a, b \in \mathbb{Z}$

$$a << b \Rightarrow \exists c_1 \in \mathbb{N} \text{ a.s.t. } b - a = c_1$$

$$b << a \Rightarrow \exists c_2 \in \mathbb{N} \text{ a.s.t. } a - b = c_2$$

(+)

$$b - a + a - b = c_1 + c_2$$

$$0 = c_1 + c_2$$

$$c_1, c_2 \in \mathbb{N}$$

$$c_1 = c_2 = 0 \Rightarrow b - a = 0 \Rightarrow b = a$$

$\Rightarrow <<$  antisimetrică

Transitivitatea Fie  $a, b, d \in \mathbb{Z}$

$$a < b \rightarrow \exists c_1 \in \mathbb{N} \text{ a.s.t } b - a = c_1 \quad (1)$$

$$b < d \rightarrow \exists c_2 \in \mathbb{N} \text{ a.s.t } d - b = c_2$$

$$\underline{d - a + b - a = c_2 + c_1}$$

$$\rightarrow d - a = c_2 + c_1$$

$$\rightarrow \exists (c_1 + c_2) \in \mathbb{N} \text{ a.s.t } d - a = c_1 + c_2$$

$\rightarrow a < d \rightarrow <$  transitivă

O relație este totală dacă oricare două elemente, ele pot fi pusă în relație

$\forall a, b \in \mathbb{Z}$  are loc  $(a < b) \vee (b < a)$

Fie  $a, b \in \mathbb{Z} \Rightarrow b - a \in \mathbb{Z}$

Dacă  $b - a \in \mathbb{N} \Rightarrow \underline{a < b}$

$b - a \notin \mathbb{N} \Rightarrow b - a \in \mathbb{Z}_- \Rightarrow$

$$a - b \in \mathbb{N}$$

$$\rightarrow b < c$$

$\rightarrow c \in$  este relație totală

Dacă  $a \leq b \rightarrow 0 \leq b - a \rightarrow b - a \in \mathbb{N} \Rightarrow a < c < b$

2.

8. Fie endomorfismul  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  definit prin

$T(\bar{x}) = (2x_1 - x_2 - x_3, x_1 - 2x_2 + x_3, x_1 + x_2 - 2x_3)$ , pentru  
 $\forall \bar{x} = (x_1, x_2, x_3) \in \mathbb{R}^3$ .

- a) Să se afle matricea lui  $T$  în baza canonică  $B$  din  $\mathbb{R}^3$ .
- b) Să se afle matricea lui  $T$  în baza  $B_1 = \{(2, 3, -1), \underbrace{(0, -2, 1)}_{v_1}, \underbrace{(-1, -1, -1)}_{v_3}\}$ .
- c) Să se afle  $\text{rg } T$  și o bază pentru  $\text{Im } T$ .
- d) Să se afle def  $T$  și o bază pentru  $\text{Ker } T$ .

a)

$$T \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 2x_1 - x_2 - x_3 \\ x_1 - 2x_2 + x_3 \\ x_1 + x_2 - 2x_3 \end{pmatrix} = \begin{pmatrix} 2 & -1 & -1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$A_C = \begin{pmatrix} 2 & -1 & -1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} \quad A_{B_1} = ?$$

$$C = \left\{ \bar{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \bar{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \bar{e}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$B_1 = \left\{ \bar{v}_1 = \begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix}, \bar{v}_2 = \begin{pmatrix} 0 \\ -2 \\ 1 \end{pmatrix}, \bar{v}_3 = \begin{pmatrix} -1 \\ -1 \\ -1 \end{pmatrix} \right\}$$

$$S_{CB_1} = \begin{pmatrix} 2 & 0 & -1 \\ 3 & -2 & -1 \\ -1 & 1 & -1 \end{pmatrix}$$

$$\underbrace{(\bar{v}_1 \quad \bar{v}_2 \quad \bar{v}_3)}_{\text{vector de vectori}} = S_{CB_1} \cdot \underbrace{(\bar{e}_1 \quad \bar{e}_2 \quad \bar{e}_3)}_{I_3}$$

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

$$T(\bar{x}) = y$$

$\bar{x}$  pot să îl exprimă în baza canonică

$$\tilde{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = (\tilde{e}_1 \tilde{e}_2 \tilde{e}_3) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} =$$

$$x_1 \tilde{e}_1 + x_2 \tilde{e}_2 + x_3 \tilde{e}_3 =$$

$$x_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} =$$

$$\begin{pmatrix} x_1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ x_2 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ x_3 \end{pmatrix} =$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$\tilde{x}$  pot să îl exprimă în  $B_0$

$$\tilde{x} = (\tilde{v}_1 \tilde{v}_2 \tilde{v}_3) \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \leftarrow \text{coord leii în } \tilde{x} \text{ în } B_0$$

$$\bar{y} = (\bar{e}_1 \ \bar{e}_2 \ \bar{e}_3) \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$$

$$\bar{y} = (\bar{v}_1 \ \bar{v}_2 \ \bar{v}_3) \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

$$A_c \begin{pmatrix} \overset{x}{\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}} \end{pmatrix} = \begin{pmatrix} \overset{y}{\begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}} \end{pmatrix}$$

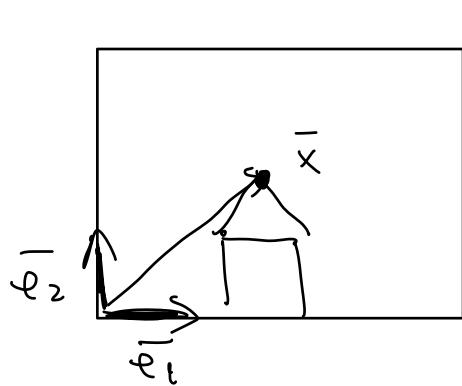
$$\textcircled{?} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

$$x = (\bar{e}_1 \ \bar{e}_2 \ \bar{e}_3) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = (\bar{v}_1 \ \bar{v}_2 \ \bar{v}_3) \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$$

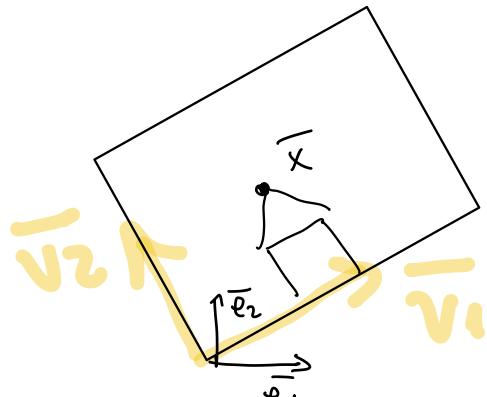
$$(\bar{v}_1 \bar{v}_2 \bar{v}_3) = (\bar{e}_1 \bar{e}_2 \bar{e}_3) S_{CB_1}$$

$$(\bar{v}_1 \bar{v}_2 \bar{v}_3) S_{CB_1}^{-1} = (\bar{e}_1 \bar{e}_2 \bar{e}_3)$$

$$(\bar{e}_1 \bar{e}_2 \bar{e}_3) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = (\bar{e}_1 \bar{e}_2 \bar{e}_3) S_{CB_1} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$$



$$\bar{x} = 2\bar{e}_1 + 1\bar{e}_2$$



$$\bar{x} = \bar{v}_1 + \bar{v}_2$$

$$(\bar{v}_1 \bar{v}_2) = (\bar{e}_1 \bar{e}_2) \cdot S_{CB}$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = S_{CB_1} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$$

coord vecchi = matrice schimbul baza  
coord noi

$$\begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = S_{CB_1} \cdot \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

$$\begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = A_C \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$S_{CB_1} \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = A_C \cdot S_{CB_1} \cdot \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$$

$$\begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = \underbrace{\left( S_{CB_1} \right)^{-1} A_C S_{CB_1}}_{A_{B_1}} \begin{pmatrix} G_1 \\ G_2 \\ G_3 \end{pmatrix}$$

Dacă schimb baza

$$A_{B_1} = \left( S_{CB_1} \right)^{-1} \cdot A_C \cdot S_{CB_1}$$

$$S_{CB_1} = \begin{pmatrix} 2 & 0 & -1 \\ 3 & -2 & -1 \\ -1 & 1 & -1 \end{pmatrix}$$

$$A_C = \begin{pmatrix} 2 & -1 & -1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} \quad \rightarrow 13:20$$

$\overbrace{1}^T(\bar{e}_1) \quad \overbrace{1}^T(\bar{e}_2) \quad \overbrace{1}^T(\bar{e}_3)$

$$\left( \begin{array}{ccc|ccc} ① & 0 & -1 & 1 & 0 & 0 \\ 3 & -2 & -1 & 0 & 1 & 0 \\ -1 & 1 & -1 & 0 & 0 & 1 \end{array} \right) \quad l_1 = \frac{l_1}{2}$$

$$\left( \begin{array}{ccc|ccc} 1 & 0 & -\frac{1}{2} & \frac{1}{2} & 0 & 0 \\ ③ & -2 & -1 & 0 & 1 & 0 \\ -1 & 1 & -1 & 0 & 0 & 1 \end{array} \right) \quad l_2 = l_2 - 3l_1$$

$$l_3 = l_3 + l_1$$

$$\left( \begin{array}{ccc|ccc} 1 & 0 & -\frac{1}{2} & \frac{1}{2} & 0 & 0 \\ 0 & -2 & \frac{1}{2} & -\frac{3}{2} & 1 & 0 \\ 0 & 1 & -\frac{3}{2} & \frac{1}{2} & 0 & 1 \end{array} \right) \quad l_2 = \frac{l_2}{-2}$$

$$\left( \begin{array}{ccc|ccc} 1 & 0 & -\frac{1}{2} & \frac{1}{2} & 0 & 0 \\ 0 & 1 & -\frac{1}{4} & \frac{3}{4} & -\frac{1}{2} & 0 \\ 0 & 1 & -\frac{3}{2} & \frac{1}{2} & 0 & 1 \end{array} \right) \quad l_3 = l_3 - l_2$$

$$\left( \begin{array}{ccc|ccc} 1 & 0 & -\frac{1}{2} & \frac{1}{2} & 0 & 0 \\ 0 & 1 & -\frac{1}{4} & \frac{3}{4} & -\frac{1}{2} & 0 \\ 0 & 0 & -\frac{5}{4} & -\frac{1}{4} & \frac{1}{2} & 1 \end{array} \right)$$

$$L_3 = L_3 \cdot \left(-\frac{5}{5}\right)$$

$$\left( \begin{array}{ccc|ccc} 1 & 0 & -\frac{1}{2} & \frac{1}{2} & 0 & 0 \\ 0 & 1 & -\frac{1}{4} & \frac{3}{4} & -\frac{1}{2} & 0 \\ 0 & 0 & 1 & \frac{1}{5} & -\frac{2}{5} & -\frac{4}{5} \end{array} \right)$$

$$L_1 = L_1 + \frac{1}{2} L_3$$

$$L_2 = L_2 + \frac{1}{4} L_3$$

$$\left( \begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{3}{5} & -\frac{1}{5} & -\frac{2}{5} \\ 0 & 1 & 0 & \frac{9}{5} & -\frac{3}{5} & -\frac{1}{5} \\ 0 & 0 & 1 & \frac{1}{5} & -\frac{2}{5} & -\frac{4}{5} \end{array} \right)$$

$$S_{C(B_1)}^{-1} = \frac{1}{5} \begin{pmatrix} 3 & -1 & -2 \\ 4 & -3 & -1 \\ 1 & -2 & -4 \end{pmatrix}$$

$$A_{B_1}^{-1} = \frac{1}{5} \begin{pmatrix} 3 & -1 & -2 \\ 4 & -3 & -1 \\ 1 & -2 & -4 \end{pmatrix} \begin{pmatrix} 2 & 0 & -1 \\ 3 & -2 & -1 \\ -1 & 1 & -1 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 3 & -3 & 0 \\ 4 & 1 & -5 \\ -4 & -1 & 5 \end{pmatrix} \begin{pmatrix} 2 & 0 & -1 \\ 3 & -2 & -1 \\ -1 & 1 & -1 \end{pmatrix} =$$

$$\frac{1}{5} \begin{pmatrix} -3 & 6 & 0 \\ 16 & -7 & 0 \\ -16 & 7 & 0 \end{pmatrix}$$

$\text{rg } T = \text{rg } A = \text{dimensiunea celui}$   
 $\text{mai mare din mul}$

$$A_{B_1} = S_{CB_1}^{-1} \cdot A \cdot S_{CB_1}$$

$$\det(A_{B_1}) = \underbrace{\det S_{CB_1}^{-1}}_0 \cdot \det A \cdot \det S_{CB_1}$$

linia 2 = linia 3

$$\Rightarrow \det A_C = 0$$

$$\text{Fie } D = \begin{pmatrix} 2 & -1 \\ 1 & -2 \end{pmatrix} = -4 + 1 = -3 \neq 0$$

$\Rightarrow \text{rang } A_c = 2$  și

$\text{rang } T = 2$

$= \dim \text{Im } T \Rightarrow$

$\dim \text{Im } T = 2$

Pt că numărul  $D$  conține

coloanele care reprezintă

$T(\bar{e}_1), T(\bar{e}_2) \Rightarrow 0$  baza în

$\text{Im } T$  este  $T(\bar{e}_1), T(\bar{e}_2) =$

$$\begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ -2 \\ 1 \end{pmatrix}$$

$$\text{Im } T = \left\{ \alpha \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} + \beta \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix} \mid \alpha, \beta \in \mathbb{R} \right\}$$

$$T: \mathbb{R}^3 \longrightarrow \mathbb{R}^3$$

$$\text{Im } (T) \subset \mathbb{R}^3$$

Găseind rangul lui  $T = 2 \Rightarrow$

Dimensiunea unei baze în  $\text{Im } T$

este 2,  $\Rightarrow$  Am nevoie de 2

vectori în  $\text{Im } T$  care să fie lin

indep.

$$\text{Im } T = \{ T(\bar{x}) \mid \bar{x} \in \mathbb{R}^3 \}$$

$$A_C = \begin{pmatrix} 2 & -1 & -1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$$

$$\bar{x} = x_1 \bar{e}_1 + x_2 \bar{e}_2 + x_3 \bar{e}_3$$

$$\underbrace{T(\bar{x})}_{\downarrow} = T(x_1 \bar{e}_1 + x_2 \bar{e}_2 + x_3 \bar{e}_3) = T^{\text{lineare}}$$

$$x_1 T(\bar{e}_1) + x_2 T(\bar{e}_2) + x_3 T(\bar{e}_3)$$

element sammale dim Mu T

$$\begin{pmatrix} 2 & -1 \\ 1 & -2 \end{pmatrix} \neq 0$$

$$2 \cdot (-2) - 1 \cdot (-1) \neq 0$$

$$(2, 1) \neq \alpha(-1, -2)$$

$$(2, 1, 1) \neq \alpha(-1, -2, 1)$$

$T(\bar{e}_1), T(\bar{e}_2)$  l.videp

$T(\bar{e}_1), T(\bar{e}_2), T(\bar{e}_3)$  generatori p) la T

$$\text{rang } T = 2$$

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Dacă  $\det A \neq 0 \rightarrow \text{rang matricei}$

$\det A = 0 \rightarrow \text{rang} < \text{matricei}$

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$$\text{def } T = \underbrace{\dim \text{sp}} - \text{rang } T = \\ 3 - 2 = 1$$

$$\text{Ker } T = \{ \bar{x} \mid T(\bar{x}) = 0 \}$$

$$\begin{pmatrix} 2 & -1 & -1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\det A = 0$$

Matrrix contine liniele l și z  $\Rightarrow$

$x_1$  și  $x_2$  nec pp și  $x_3$  nec slc.

$$x_3 = \alpha$$

$$\begin{pmatrix} 2 & -1 & -1 \\ 1 & -2 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\left\{ \begin{array}{l} 2x_1 - x_2 - x_3 = 0 \end{array} \right.$$

$$\left. \begin{array}{l} x_1 - 2x_2 + x_3 = 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} 2x_1 - x_2 = \alpha \quad | \cdot 2 \\ x_1 - 2x_2 = -\alpha \end{array} \right.$$

$$\left. \begin{array}{l} 4x_1 - 2x_2 = 2\alpha \\ x_1 - 2x_2 = -\alpha \end{array} \right.$$

$$\left. \begin{array}{l} 3x_1 = 3\alpha \Rightarrow x_1 = \alpha \\ x_2 = -\alpha \end{array} \right.$$

$$\begin{pmatrix} 2 & -1 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \alpha \\ -\alpha \end{pmatrix}$$

$2x_1 - x_2 = \alpha$   
 $x_1 - 2x_2 = -\alpha$

→ Cramer

→ Rezolvare reducere

→ Înmulțind cu inversa

→ Substituție

e

$$\text{Ker } T = \{(\alpha, \alpha, \alpha) \mid \alpha \in \mathbb{R}\}$$

$$0 \text{ bază în } \text{Ker } T = \{(1, 1, 1)\}$$

$$\begin{pmatrix} 2 & -1 & -1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix}$$

$$\left| \begin{array}{ccc} 2 \rightarrow & -1 & -1 \\ 1 & -2 \rightarrow & 1 \\ 1 & 1 & -2 \rightarrow \end{array} \right| \quad \left. \begin{array}{l} L_1 = L_1 + L_2 + L_3 \\ \hline \end{array} \right.$$

$$\left| \begin{array}{ccc} 3 \rightarrow & -2 \rightarrow & -2 \rightarrow \\ 1 & -2 \rightarrow & 1 \\ 1 & 1 & -2 \rightarrow \end{array} \right| \quad \left. \begin{array}{l} C_1 = C_1 + C_2 + C_3 \\ \hline \end{array} \right.$$

$$\left| \begin{array}{ccc} -3 \rightarrow & -2 \rightarrow & -2 \rightarrow \\ -\rightarrow & -2 \rightarrow & 1 \\ -\rightarrow & 1 & -2 \rightarrow \end{array} \right| =$$

$$-\rightarrow \left| \begin{array}{ccc} 3 & -2 \rightarrow & -2 \rightarrow \\ 1 & -2 \rightarrow & 1 \\ 1 & 1 & -2 \rightarrow \end{array} \right|$$

$$\underline{\underline{L_2 = L_2 - L_3}}$$

$$-\lambda \begin{vmatrix} 3 & -2-\lambda & -2-\lambda \\ 0 & -3-\lambda & 3+\lambda \\ 1 & 1 & -2-\lambda \end{vmatrix}$$

$$= -\lambda(3+\lambda) \begin{vmatrix} 3 & -2-\lambda & -2-\lambda \\ 0 & -1 & 1 \\ 1 & 1 & -2-\lambda \end{vmatrix}$$

$$\begin{aligned} C_3 &= C_3 + C_2 \\ -\lambda(3+\lambda) & \quad \begin{vmatrix} 3 & -2-\lambda & -4-2\lambda \\ 0 & -1 & 0 \\ 1 & 1 & -1-\lambda \end{vmatrix} \\ + \lambda(3+\lambda) & \quad \begin{vmatrix} 3 & -4-2\lambda \\ 1 & -1-\lambda \end{vmatrix} = \end{aligned}$$

$$\lambda(3+\lambda)(-3-3\lambda+4+2\lambda) =$$

$$\det(A - \lambda I_3) = \underbrace{\lambda(3+\lambda)(1-\lambda)}_{(\lambda - \lambda_x)^3}$$

$$\lambda_1 = 0$$

$$m_{\lambda_1} = 1$$

D'accè

$$\lambda_2 = -3$$

$$m_{\lambda_2} = 1$$

$$\lambda^2 (\lambda - 2)^3 (\lambda + 1)$$

$$\lambda_3 = 1$$

$$m_{\lambda_3} = 1$$

0 are mult 2  
1 are mult 3

-1 are mult 1

$$m_{\lambda_1} + m_{\lambda_2} + m_{\lambda_3} = 3 = \dim \mathbb{R}^3$$

$$\lambda_1 = 0 \quad V_{\lambda_1} = \text{Ker } T = \{(\alpha, \alpha, \alpha) \mid \alpha \in \mathbb{R}\}$$

$$\dim V_{\lambda_1} = 1$$

$$v_{\lambda_1} = \underbrace{(1, 1, 1)}_{\text{vector proprie}} \quad \text{base in } V_{\lambda_1}$$

$$x_2 = -3$$

$$\begin{pmatrix} 2+3-1 & -1 \\ 1 & -2+3 & 1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 5 & -1 & -1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Delta' = \begin{vmatrix} 5 & -1 \\ 1 & 1 \end{vmatrix} = 5 + 1 = 6 \neq 0$$

$x_1, x_2$  are pp     $x_3 = \alpha$  nec sc

$$\begin{pmatrix} 5 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = -\alpha \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$5x_1 - x_2 = \alpha \quad \textcircled{+}$$

$$x_1 + x_2 = -\alpha$$

$$6x_1 = 0 \rightarrow x_1 = 0$$

$$x_2 = -2$$

$$V_{x_2} = \{(0, -\alpha, \alpha) | \alpha \in \mathbb{R}\}$$

$v_{x_2} = (0, -1, 1)$  vector proprie-

$$\dim V_{x_2} = 1$$

$$\begin{pmatrix} 2 & -1 & -1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -1 & -1 \\ 1 & -3 & 1 \\ 1 & 1 & -3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Delta'' = \begin{pmatrix} 1 & -1 \\ 1 & -3 \end{pmatrix} \neq$$

$x_1, x_2$  nec pp  $x_3 =$  nec nec

$$\begin{pmatrix} 1 & -1 \\ 1 & -3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = -\alpha \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\begin{array}{r} x_1 - x_2 = \alpha \\ x_1 - 3x_2 = -\alpha \end{array}$$

(-)

$$2x_2 = 2\alpha \Rightarrow x_2 = \alpha$$

$$x_1 = 2\alpha$$

$$V_{x_3} = \{(2\alpha, \alpha, \alpha) \mid \alpha \in \mathbb{R}\}$$

$$V_{x_3} = (2, 1, 1)$$

$$\dim V_{x_3} = 1$$

$$m_{x_1} + m_{x_2} + m_{x_3} = 3 = \dim \mathbb{R}^3$$

$$m_{x_i} = \dim V_{x_i} \text{ pt tot i}$$

$\Rightarrow T$  diag.

$$AD = \begin{pmatrix} 0 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$D = \{ v x_1, v x_2, v x_3 \}$$

$$W = \{ (x_1, x_2, x_3) \in \mathbb{R}^3 \mid x_1 + x_2 + 2x_3 = 0 \}$$

+

a)  $W \subseteq \mathbb{R}^3$

b) O bază ortonormală a lui  $W$  îl rap

$\leftrightarrow$  canonic

c)  $W^\perp$ , o bază ortonormală îl  $W^\perp$

++)

a)  $\mu_{W^\perp}$

$$x_1 + x_2 + 2x_3 = 0$$

sistem de ec și

3 nec

$x_1$  nec pp,  $x_2, x_3$  nec sc.

$$x_2 = \alpha \quad x_3 = \beta$$

$$x_1 = -\alpha - 2\beta$$

$$W = \{(-\alpha - 2\beta, \alpha, \beta) \mid \alpha, \beta \in \mathbb{R}\}$$

$$\forall x, y \in W \quad x + y \in W$$

$$\forall \mu \in \mathbb{R} \quad \forall x \in W \quad \mu x \in W$$

$$x = (-\alpha_1 - 2\beta_1, \alpha_1, \beta_1)$$

$$y = (-\alpha_2 - 2\beta_2, \alpha_2, \beta_2)$$

---

$$x + y = \left( -\underbrace{(\alpha_1 + \alpha_2)}_{(\alpha_1 + \alpha_2)}, -2\underbrace{(\beta_1 + \beta_2)}_{(\beta_1 + \beta_2)} \right) \in W$$

$$\mu x = (-\mu\alpha_1 - 2\mu\beta_1, \mu\alpha_1, \mu\beta_1) \in W$$

$$\Rightarrow W \subseteq \mathbb{R}^3$$

Met 11

Sei  $x, y \in W$

$$x = (x_1, x_2, x_3), x_1 + x_2 + 2x_3 = 0$$

$$y = (y_1, y_2, y_3) \quad y_1 + y_2 + 2y_3 = 0$$

$$x+y = (x_1+y_1, x_2+y_2, x_3+y_3)$$

$$x+y \in W$$

$$(x_1+y_1) + (x_2+y_2) + 2(x_3+y_3) = 0$$

$$\mu x = (\mu x_1, \mu x_2, \mu x_3)$$

$$\mu x_1 + \mu x_2 + 2\mu x_3 = 0$$

$$\rightarrow \mu x \in W$$

$$\rightarrow W \subseteq \mathbb{R}^3$$

2)

$$W = \{(-\alpha - 2\beta, \alpha, \beta) \mid \alpha, \beta \in \mathbb{R}\}$$

$$\alpha = 1, \beta = 0 \quad \bar{v}_1 = (-1, 1, 0)$$

$$\alpha = 0, \beta = 1 \quad \bar{v}_2 = (-2, 0, 1)$$

$$\bar{f}_1 = \bar{v}_1$$

$$\bar{f}_2 = \bar{v}_2 + \delta \bar{v}_1 = (-2, 0, 1) - (-1, 1, 0)$$

$$\langle \bar{f}_2, \bar{f}_1 \rangle = 0 \Rightarrow \underline{(-1, -1, 1)}$$

$$\langle \bar{v}_2 + \delta \bar{v}_1, \bar{v}_1 \rangle = 0$$

$$\langle \bar{v}_2, \bar{v}_1 \rangle + \delta \langle \bar{v}_1, \bar{v}_1 \rangle = 0$$

$$\delta = - \frac{\langle \bar{v}_2, \bar{v}_1 \rangle}{\langle \bar{v}_1, \bar{v}_1 \rangle} = - \frac{2}{2} = -1$$

$$\bar{b}_1 = \frac{1}{\|\bar{v}_1\|} \cdot \bar{v}_1 = \frac{1}{\|\bar{f}_1\|} \cdot \bar{f}_1 = \frac{1}{\sqrt{2}} (-1, 1, 0)$$

$$\bar{b}_2 = \frac{1}{\|\bar{f}_2\|} \cdot \bar{f}_2 = \frac{1}{\sqrt{3}} (-1, -1, 1)$$

$$c) W^\perp = \{ y \mid \langle x, y \rangle = 0 \quad \forall x \in W \}$$

$$x = (x_1, x_2, x_3)$$

$$y = (y_1, y_2, y_3)$$

$$x_1 y_1 + x_2 y_2 + x_3 y_3 = 0 \quad \forall x_1, x_2, x_3 \in W$$

$$(x_1, x_2, x_3) = (-\alpha - 2\beta, \alpha, \beta)$$

$$(-\alpha - 2\beta) y_1 + \alpha y_2 + \beta y_3 = 0$$

$$\underbrace{\alpha(-y_1 + y_2)}_{\alpha} + \underbrace{\beta(-2y_1 + y_3)}_{\beta} = 0 \quad \forall \alpha, \beta \in \mathbb{R}$$

$$\left\{ \begin{array}{l} \alpha = 1 \quad \beta = 0 \\ -y_1 + y_2 = 0 \\ \alpha = 0 \quad \beta = 1 \\ -2y_1 + y_3 = 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} -y_1 + y_2 = 0 \Rightarrow y_1 = y_2 \Rightarrow \\ y_2 = \frac{r}{2} \\ -2y_1 + y_3 = 0 \end{array} \right.$$

$$\begin{pmatrix} -1 & 1 & 0 \\ -2 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \quad \begin{array}{l} y_3 \text{ nec nec} \\ y_3 = r \\ y_1, y_2 \text{ nec pp} \end{array}$$

$$-2y_1 + r = 0 \Rightarrow$$

$$y_1 = \frac{r}{2}$$

$$\rightarrow W^\perp = \left\{ \left( \frac{r}{2}, \frac{r}{2}, r \right) \mid r \in \mathbb{R} \right\}$$

0 basis este  $\bar{v} = \left( \frac{1}{2}, \frac{1}{2}, 1 \right)$

$$\|\bar{v}\| = \sqrt{\frac{1}{4} + \frac{1}{4} + 1} = \sqrt{\frac{3}{2}}$$

$$\vec{f} = \sqrt{\frac{2}{3}} \left( \frac{1}{2}, \frac{1}{2}, 1 \right)$$

$$\sum_{n=1}^{\infty} \cos \frac{\pi(\sqrt{n} + \frac{1}{n})}{3}$$

$$\cos \frac{\pi(\sqrt{n} + \frac{1}{n})}{3}$$

$$n = gk^2 \quad k \in \mathbb{N}$$

$$\cos(a+b) = \cos a \cos b - \sin a \sin b$$

$$\cos \frac{\pi(3k + \frac{1}{gk^2})}{3} = \cos \left( \frac{3k\pi}{3} + \frac{\pi}{gk^2} \right)$$

$$\cos \frac{3k\pi}{3} \cos \frac{\pi}{gk^2} - \sin \frac{3k\pi}{3} \sin \frac{\pi}{gk^2}$$

$$\cos k\pi \cos \frac{\pi}{gk^2} - \sin k\pi \sin \frac{\pi}{gk^2} =$$

$$(-1)^k \cos \frac{\pi}{9k^2} \xrightarrow{k \rightarrow \infty}$$

c)  $\sum_{n=20}^{\infty} \frac{\sin \frac{n}{3}}{\ln \ln n} + \frac{\sqrt{n+1} - \sqrt{n}}{n}$

$\sin \frac{n}{3}$   
 $\ln \ln n$   
 $\sqrt{n+1} - \sqrt{n}$   
 $a_n$

$$a_n = \frac{\sqrt{n+1} - \sqrt{n}}{n}$$

$$\frac{(n+1-n)}{n(\sqrt{n+1} + \sqrt{n})} = \frac{1}{n(\sqrt{n+1} + \sqrt{n})}$$

$$\sum a_n \xrightarrow{a_n} \frac{1}{n^{3/2}} = \frac{1}{n^{3/2}}$$

$$\frac{\sqrt{n}}{\sqrt{n+1} + \sqrt{n}} \rightarrow \frac{1}{2} \in (0, \infty)$$

$$\Rightarrow \sum a_n \sim \sum \frac{1}{n^{\frac{3}{2}}} C$$

$$\frac{\sin \frac{n}{3}}{\ln \ln n}$$

$$|\sin \frac{n}{3}| < 1$$

$$\ln \ln n \rightarrow 0$$