

CSSE 230 Day 22

Graphs and their representations

After this lesson, you should be able to ...
... define the major terminology relating to graphs
... implement a graph in code, using various conventions

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Graphs

Terminology
Representations
Algorithms

Graph Definitions

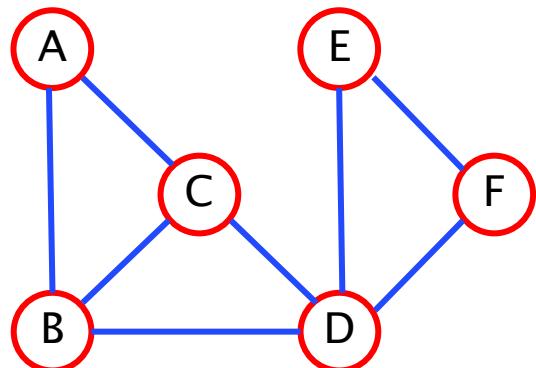
A graph $G = (V, E)$ is composed of:

V : set of *vertices* (singular: vertex)
 E : set of *edges*

An *edge* is a pair of *vertices*. Can be

unordered: $e = \{u, v\}$ (*undirected graph*)

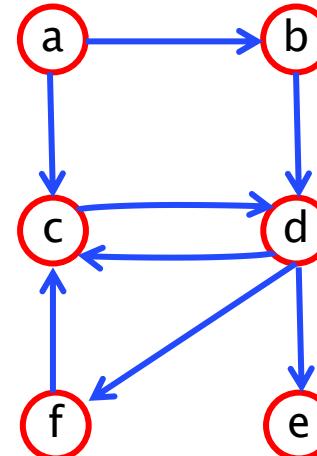
ordered: $e = (u, v)$ (*directed graph / digraph*)



Undirected graph G1 (above)

$$G1.V = \{A, B, C, D, E, F\}$$

$$G1.E = \{\{A, B\}, \{A, C\}, \{B, C\}, \\ \{B, D\}, \{C, D\}, \{D, E\}, \\ \{D, F\}, \{E, F\}\}$$



Directed graph G2 (above)

$$G2.V = \{a, b, c, d, e, f\}$$

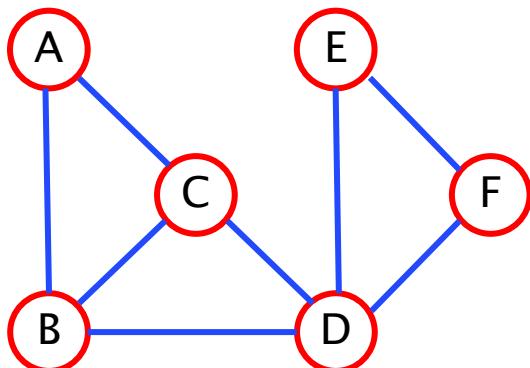
$$G2.E = \{(a, b), (a, c), (b, d), \\ (c, d), (d, c), (d, e), (d, f), \\ (f, c)\}$$

Graph Terminology

- ▶ Size? Edges or vertices?
- ▶ Usually take size to be $n = |\text{V}|$ (# of vertices)
- ▶ But the runtime of graph algorithms often depend on the number of edges, $|\text{E}|$
- ▶ Relationships between $|\text{V}|$ and $|\text{E}|$?

Undirected Graphs: adjacency, degree

- If $\{u,v\}$ is an edge, then u and v are *neighbors* (also: u is *adjacent* to v)
- *degree* of v = number of neighbors of v



$$G1.V = \{A, B, C, D, E, F\}$$

Fact:

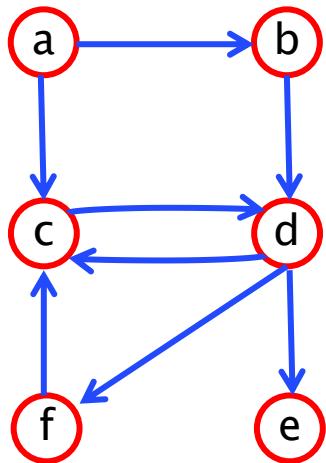
$$\sum_{v \in V} \deg(v) = 2|E|$$

(Why?)

$$\sum_{v \in G1.V} \deg(v) = \deg(A) + \deg(B) + \deg(C) + \deg(D) + \deg(E) + \deg(F)$$

Directed Graphs: adjacency, degree

- If (u,v) is an edge, then v is a *successor* of u and u is a *predecessor* of v
- $\text{Out-degree}(v) = \text{number of successors of } v$
- $\text{In-degree}(v) = \text{number of predecessors of } v$



Directed graph G2

$G2.V = \{a, b, c, d, e, f\}$

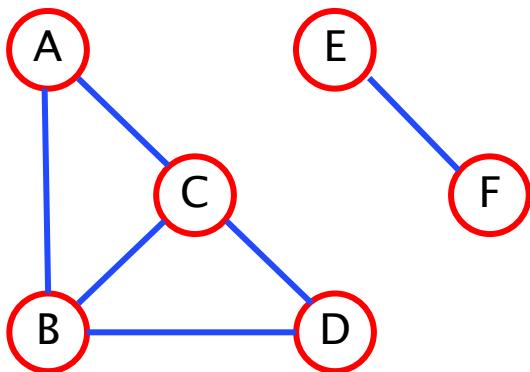
$G2.E = \{ (a, b), (a, c), (b, d), (c, d), (d, c), (d, e), (d, f), (f, c) \}$

Example – Vertex c :

- Is a *predecessor* of d
 $\text{Out-degree}(c) = 1$
- Is a *successor* of: a , d , and f
 $\text{In-degree}(c) = 3$

Undirected Graphs: paths, connectivity

- A *path* is a list of unique vertices joined by edges.
 - For example, [a, c, d] is a path from a to d.
- A subgraph is *connected* if every pair of vertices in the subgraph has a path between them.



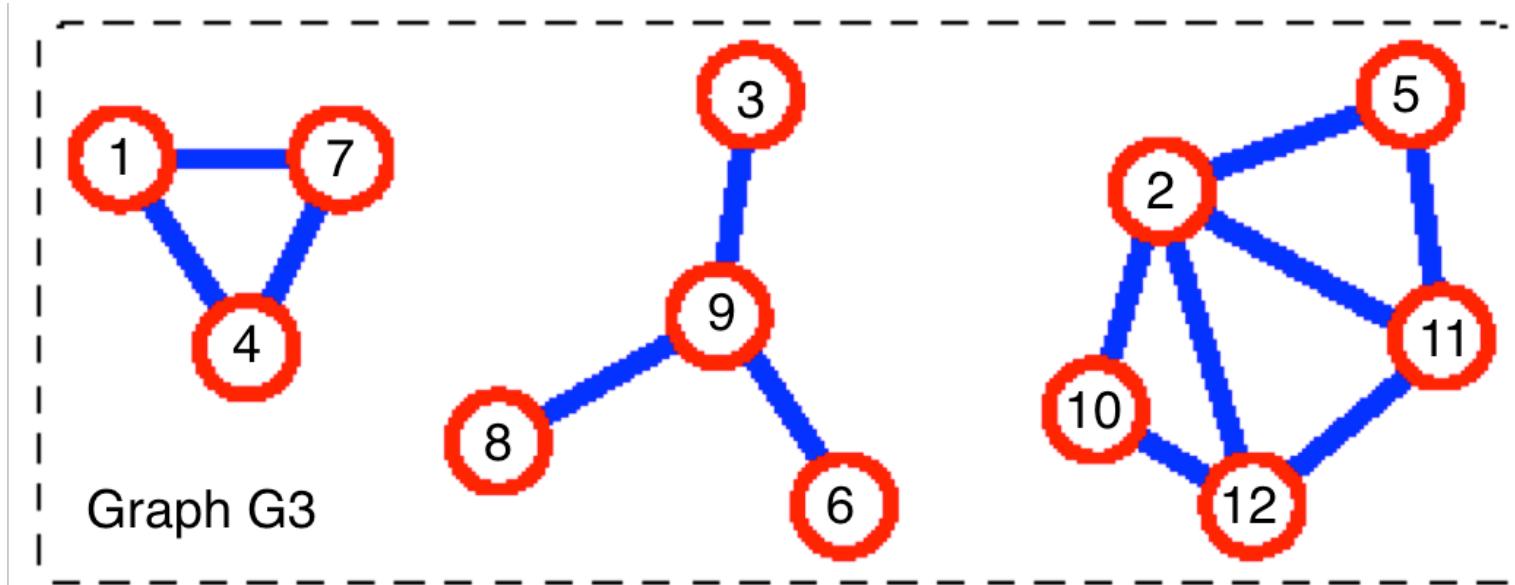
Not a connected graph.

Subgraph	Connected?
{A,B,C,D}	Yes
{E,F}	Yes
{C,D,E}	No
{A,B,C,D,E,F}	No

Undirected Graphs: components

(Connected) *component*: a maximal connected subgraph.

For example, this graph has 3 connected components:



$G3 = (V, E)$

$G3.V = \{1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12\}$

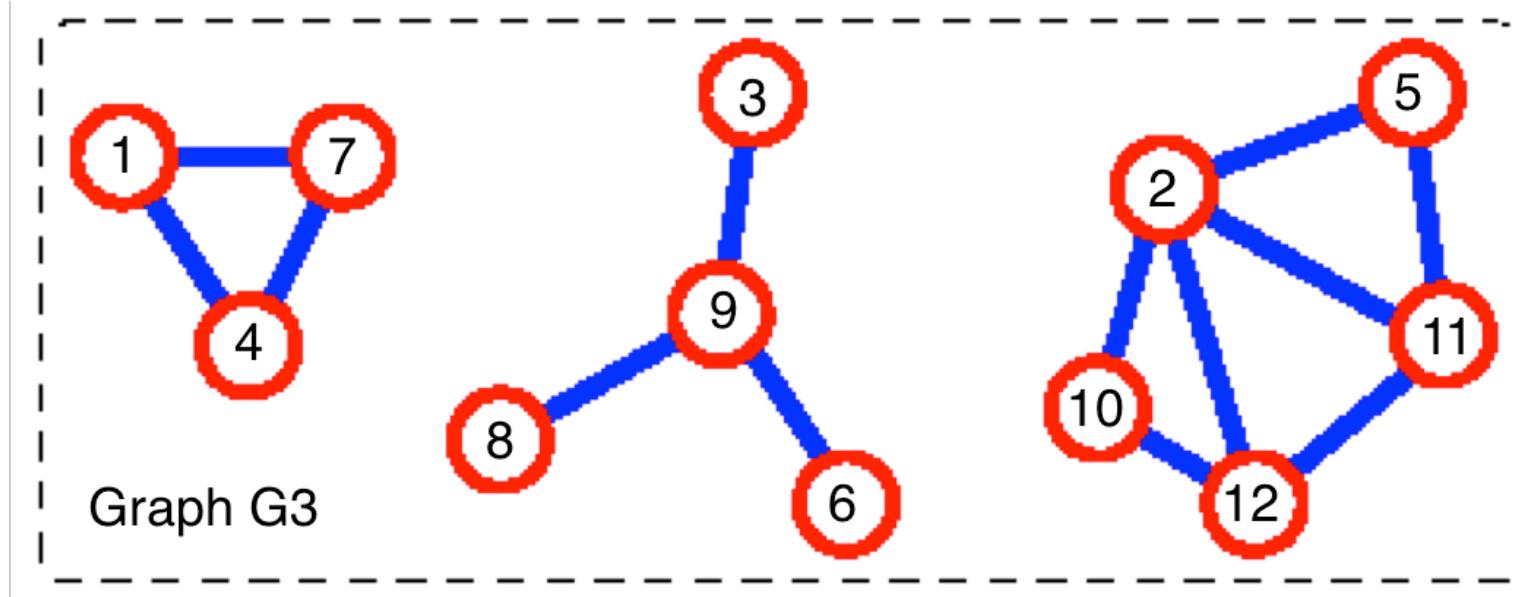
$G3.E = \{$

```
{1, 7}, {1, 4}, {4, 7},  
{3, 9}, {6, 9}, {8, 9},  
{2, 5}, {2, 10}, {2, 11}, {2, 12}, {5, 11}, {10, 12}, {11, 12}\}
```

Undirected Graphs: (mathematical) tree

Tree: connected acyclic graph (no cycles)

Example. Which component is a tree?

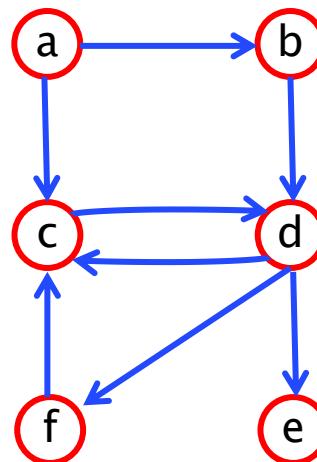


Question: for a tree, what is the relationship between
 $m = \# \text{edges}$ and $n = \# \text{vertices}$?

$$m = n - 1$$

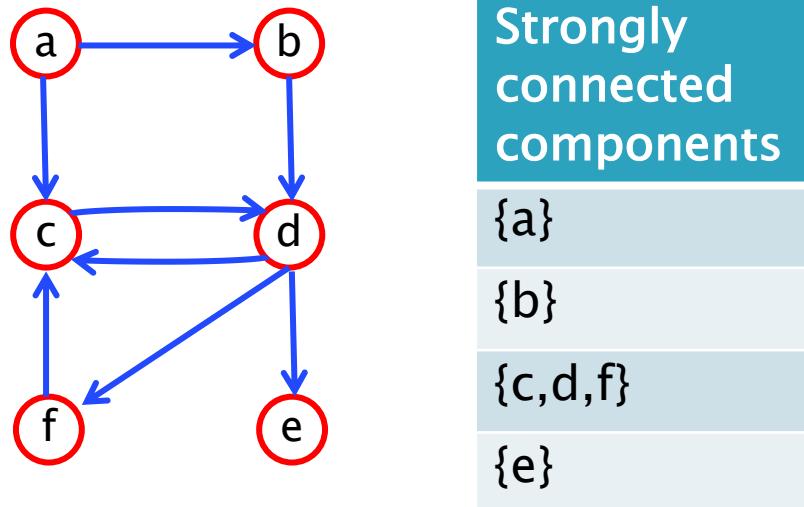
Directed Graphs: paths, connectivity

- A *directed path* is a list of unique vertices joined by directed edges.
 - For example, [a, c, d, f] is a directed path from a to f. We say f is *reachable* from a.
- A subgraph is *strongly connected* if for every pair (u,v) of its vertices, v is reachable from u and u is reachable from v.



Directed graphs: components

- *Strongly-connected component*: aka maximal strongly connected subgraph



Note, implicit edges exist

$\forall v \in G.V \text{ there exists edge } (v, v)$

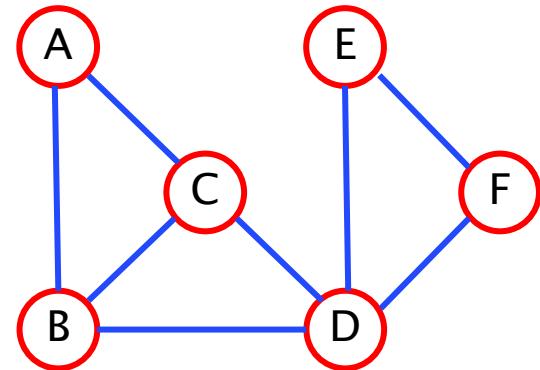
Viewing a graph as a data structure

- ▶ Each vertex associated with a name (key)
- ▶ Examples:
 - City name
 - IP address
 - People in a social network
- ▶ An edge (undirected/directed) represents a link between keys
- ▶ Graphs are flexible: edges/nodes can have *weights*, *capacities*, or other attributes

There are several alternatives for representing edges of a graph

1. Edge list

- A collection of vertices and a collection of edges



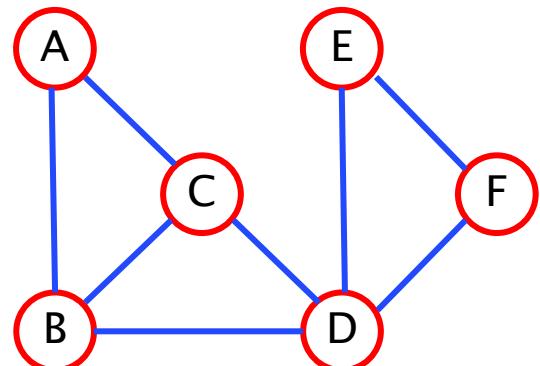
2. Adjacency matrix

- Each *key* is associated with an index from 0, ..., (n-1)
 - Map from keys to ints?
- Edges denoted by 2D array ($|V| \times |V|$) of 0's and 1's
 - 0 stored at $A[2,7]$ means no edge between vertex 2 and 7
 - 1 stored at $A[2,7]$ means an edge exists between 2 and 7

3. Adjacency list

- Collection of vertices
 - Map from *keys* to Vertex objects?
- Each Vertex stores a List of adjacent vertices

Implementation tradeoffs



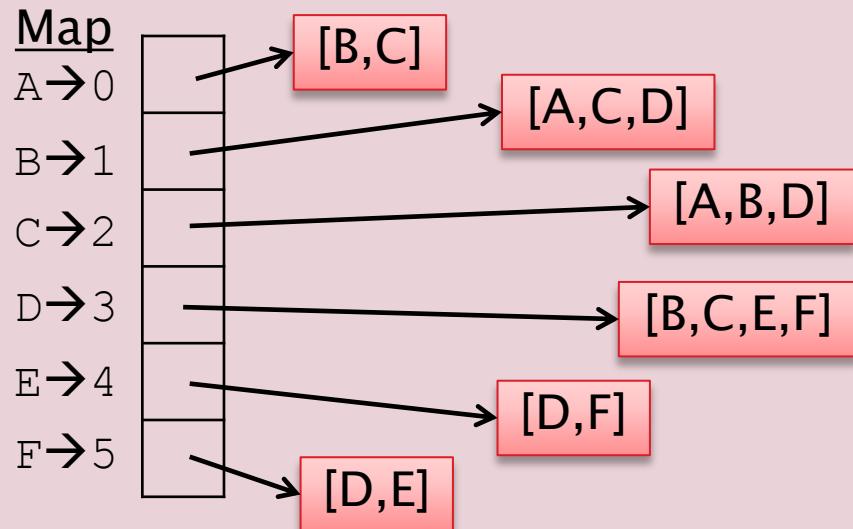
$G1.V = \{A, B, C, D, E, F\}$

$G1.E = \{\{A, B\}, \{A, C\}, \{B, C\}, \{B, D\}, \{C, D\}, \{D, E\}, \{D, F\}, \{E, F\}\}$

Adjacency Matrix

Map	0	1	2	3	4	5
A → 0	0	1	1	0	0	0
B → 1	1	0	1	1	0	0
C → 2	2	1	1	0	1	0
D → 3	3	0	1	1	0	1
E → 4	4	0	0	0	1	0
F → 5	5	0	0	0	1	1

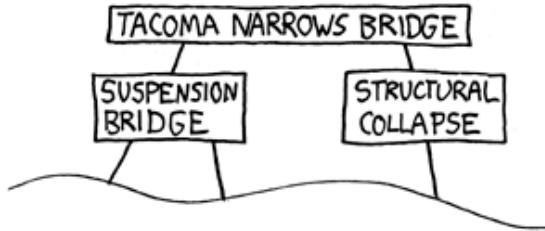
Adjacency List



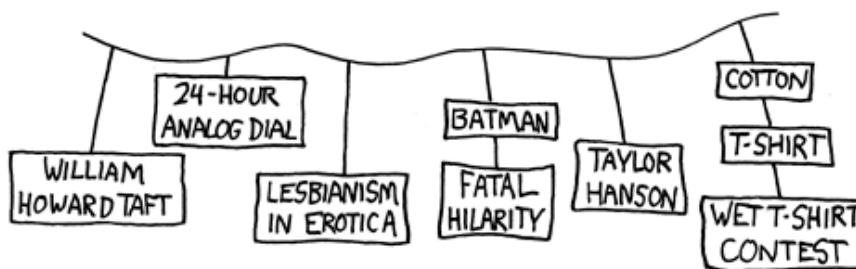
- ▶ Running time of $\deg(v)$?
- ▶ Running time of $\text{deleteEdge}(u,v)$?
- ▶ What are the space requirements?

GraphSurfing Project

THE PROBLEM WITH WIKIPEDIA:



[THREE HOURS OF
FASCINATED CLICKING]



GraphSurfing assignment

- ▶ M1: Implement `AdjacencyListGraph<T>` and `AdjacencyMatrixGraph<T>`
 - both extend the given ADT, `Graph<T>`.
- ▶ M2: Write methods
 - `stronglyConnectedComponent(v)`
 - `shortestPath(from, to)`

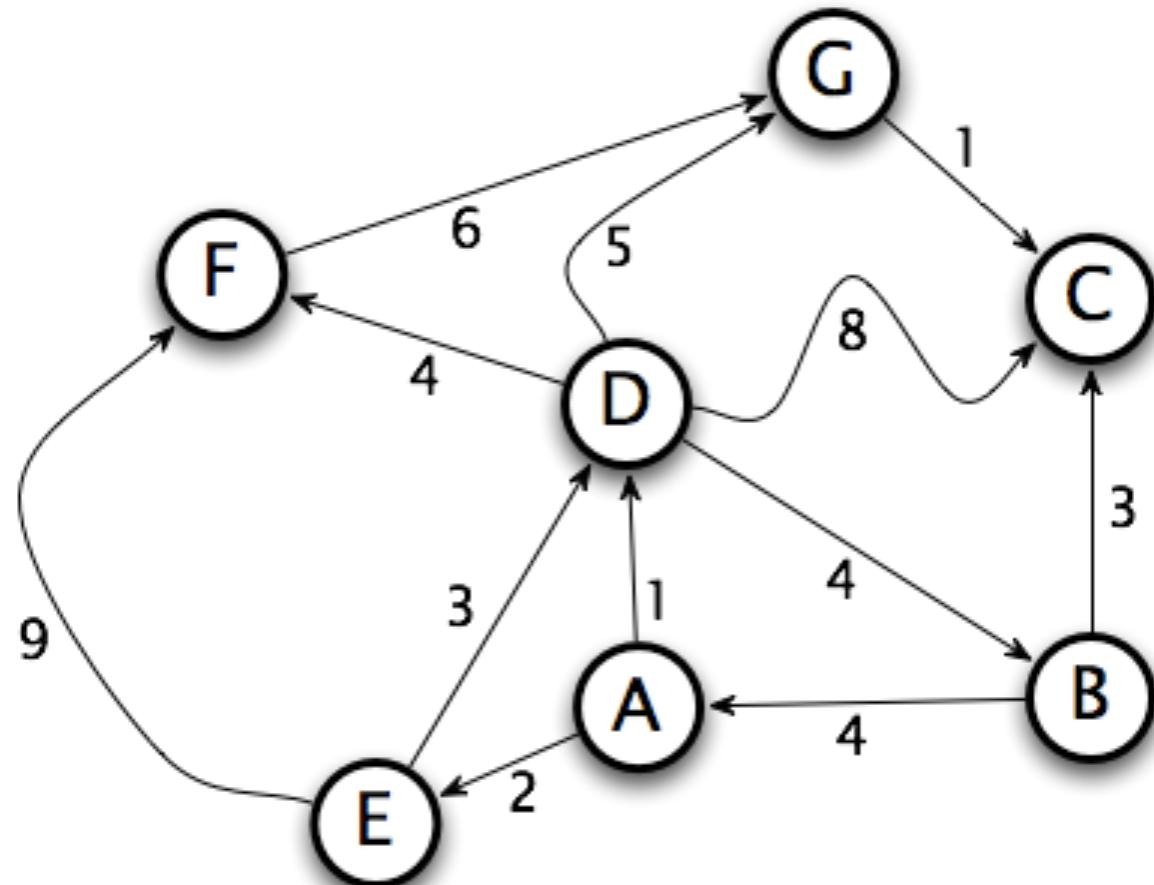
and use them to go [WikiSurfing!](#)

Sample Graph Problems

To discuss algorithms, take
MA/CSSE473 or MA477

Weighted Shortest Path

- What's the cost of the shortest path from A to each of the other nodes in the graph?

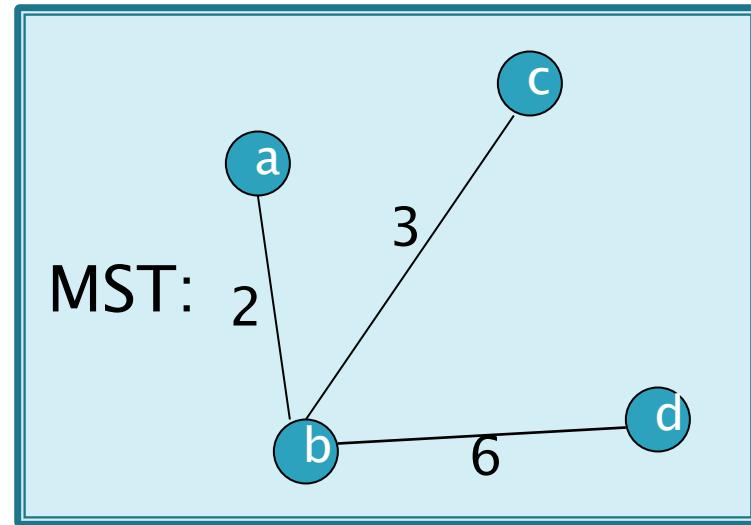
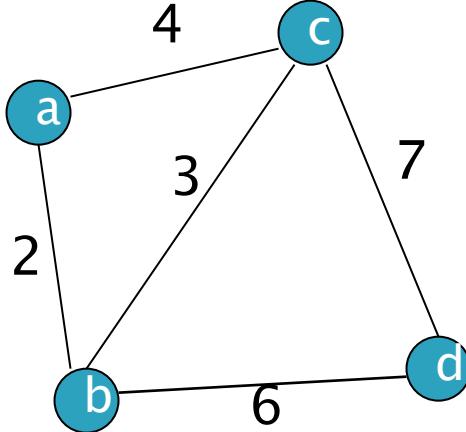


For much more on graphs, take MA/CSSE 473 or MA 477

Minimum Spanning Tree

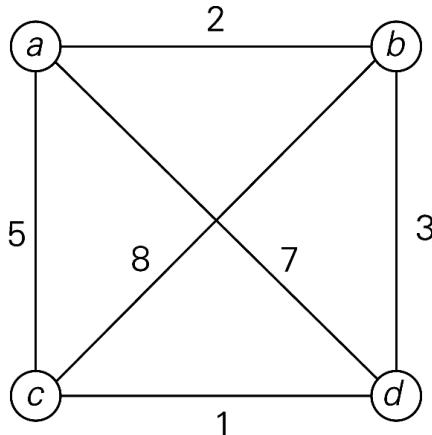
- ▶ *Spanning tree*: a connected acyclic subgraph that includes all of the graph's vertices
- ▶ *Minimum spanning tree* of a weighted, connected graph: a spanning tree of minimum total weight

Example:



Traveling Salesman Problem (TSP)

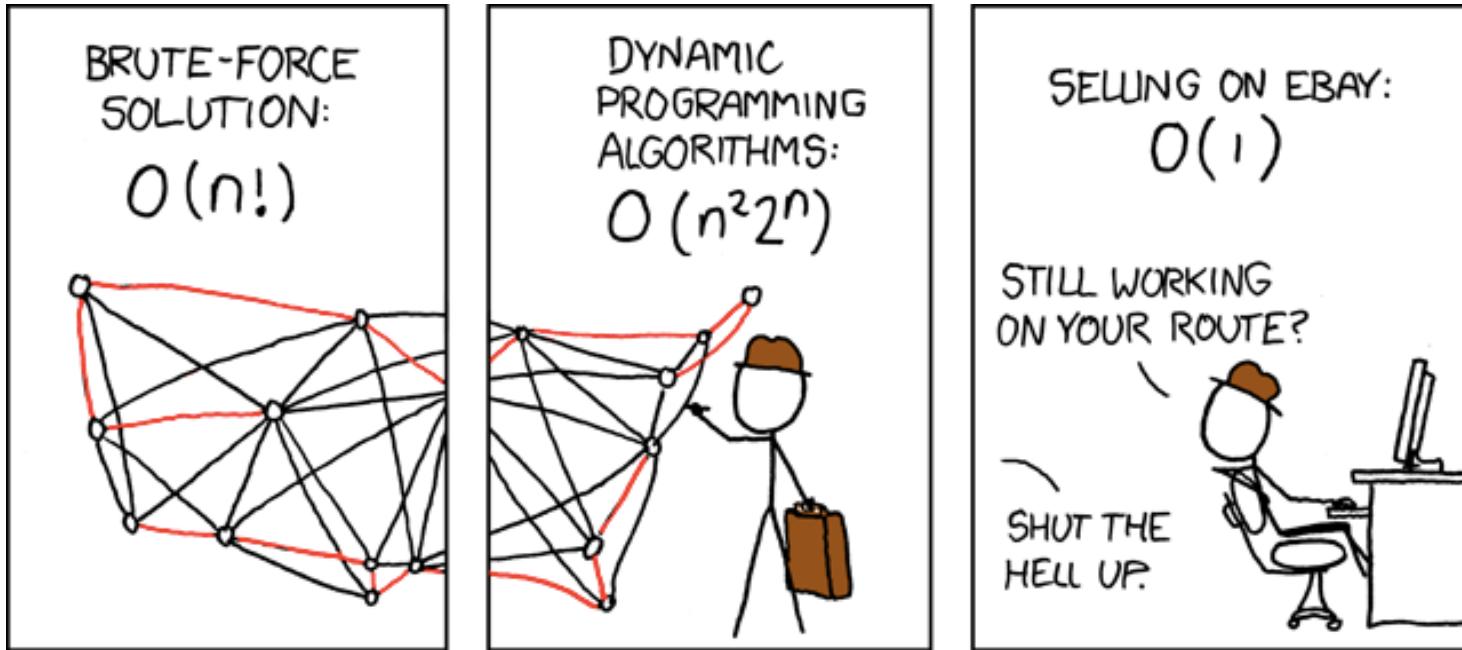
- ▶ n cities, weights are travel distance
- ▶ Must visit all cities (starting & ending at same place) with shortest possible distance



Tour	Length	
$a \rightarrow b \rightarrow c \rightarrow d \rightarrow a$	$l = 2 + 8 + 1 + 7 = 18$	
$a \rightarrow b \rightarrow d \rightarrow c \rightarrow a$	$l = 2 + 3 + 1 + 5 = 11$	optimal
$a \rightarrow c \rightarrow b \rightarrow d \rightarrow a$	$l = 5 + 8 + 3 + 7 = 23$	
$a \rightarrow c \rightarrow d \rightarrow b \rightarrow a$	$l = 5 + 1 + 3 + 2 = 11$	optimal
$a \rightarrow d \rightarrow b \rightarrow c \rightarrow a$	$l = 7 + 3 + 8 + 5 = 23$	
$a \rightarrow d \rightarrow c \rightarrow b \rightarrow a$	$l = 7 + 1 + 8 + 2 = 18$	

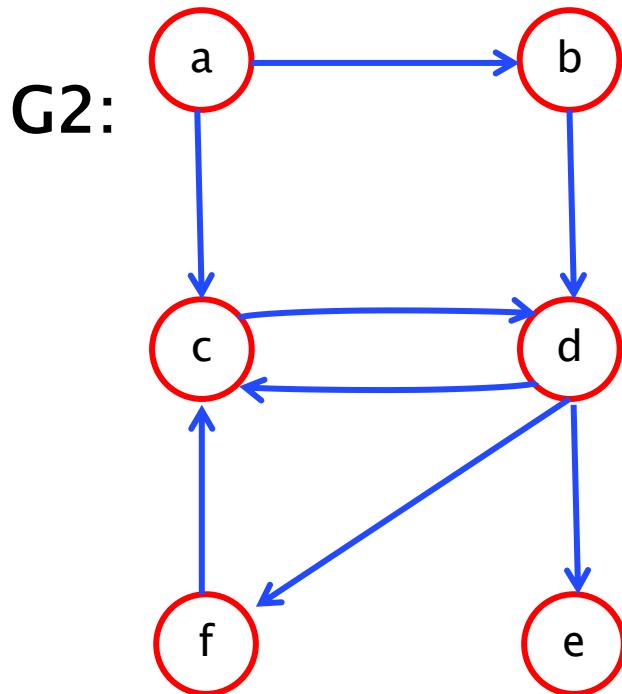
- Exhaustive search: how many routes?
- $(n-1)!/2 \in \Theta((n-1)!)$

Traveling Salesman Problem

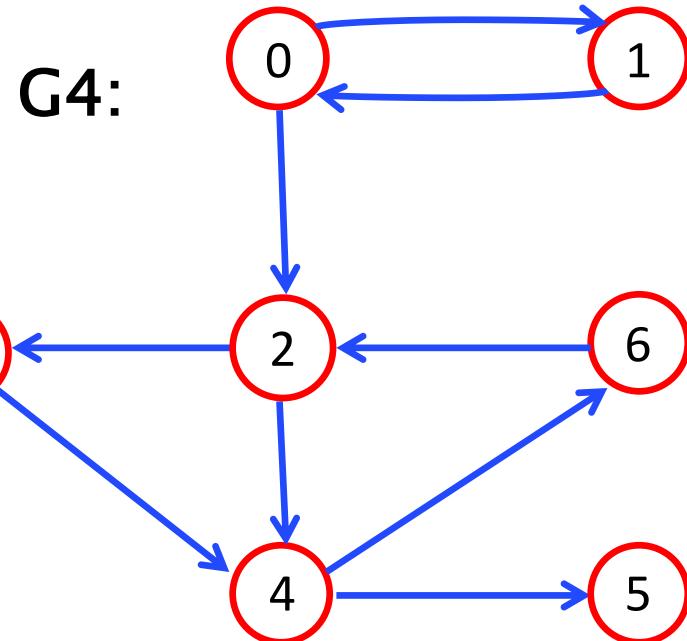


- ▶ Online source for all things TSP:
 - <http://www.math.uwaterloo.ca/tsp/>

Example graphs for project



$G2.V = \{a, b, c, d, e, f\}$
 $G2.E = \{(a, b), (a, c), (b, d), (c, d), (d, c), (d, e), (d, f), (f, c)\}$



$G4.V = \{0, 1, 2, 3, 4, 5, 6\}$
 $G4.E = \{(0, 1), (0, 2), (1, 0), (1, 2), (2, 3), (2, 4), (3, 2), (3, 4), (4, 2), (4, 5), (5, 4)\}$