

Installation Guide for Rc robot

Table of Contents

- Installation Guide for Rc robot
 - Table of Contents
 - Introduction
 - Safety Precautions
 - Components List
 - Tools Required
 - Assembly Instructions
 - Step 1: Base Assembly
 - Step 2: Attach Motor Driver
 - Step 3: Attach ESP32-WROOM-32 module to the motor driver
 - Step 4: Cut the support beams
 - Step 5: Screw in the supports on the bottom of the bottom plate
 - Step 6: Mount all the supports on the bottom plate
 - Step 7: Attach the top plate (you will need to drill holes so that the supports can fit through the top plate)
 - Step 8: Attach the ultrasonic sensor to the top plate
 - Step 9: Attach the battery pack to the RPI 5
 - Step 9.5: Place RPI 5 on top of the top plate
 - Step 10: Connect the hc-sr04 sensor to the RPI 5 and try to fit them on the top plate, together with the battery holder for the ESP32 and the mini oled screen(s)
 - Wiring Guide
 - RPI5 Wiring
 - ESP32 Wiring
 - esp32 Motor pins
 - Software Configuration

Introduction

Provide a brief introduction to the device, its purpose, and any background information necessary for the user.

Safety Precautions

- Always disconnect the device from the power source before assembling or disassembling.
- Be cautious of sharp edges on the metal or plastic parts.
- ...

Components List

- Raspberry Pi 5 8gb ram - Available at [KiwiElectronics](#)
- ESP32-WROOM-32 module (Refer to the datasheet at [Espressif](#))

- 3D printed parts from Thingiverse ([hc-sr04, top plate + alternative for the robot kit](#))
- Motor Driver - available at [DFRobot](#)
- 2WD robot kit - available at [DFRobot](#)
- Mini OLED screen - available at [Amazon](#)
- Sensors - available at [Amazon](#)
- Battery For RPI 5 - available at [Amazon](#)
- Battery Holder For ESP 32 - available at [Amazon](#)
- Other miscellaneous components (screws, wires, etc.)

Tools Required

- Screwdriver
- Wire cutter/stripper
- ...

Assembly Instructions

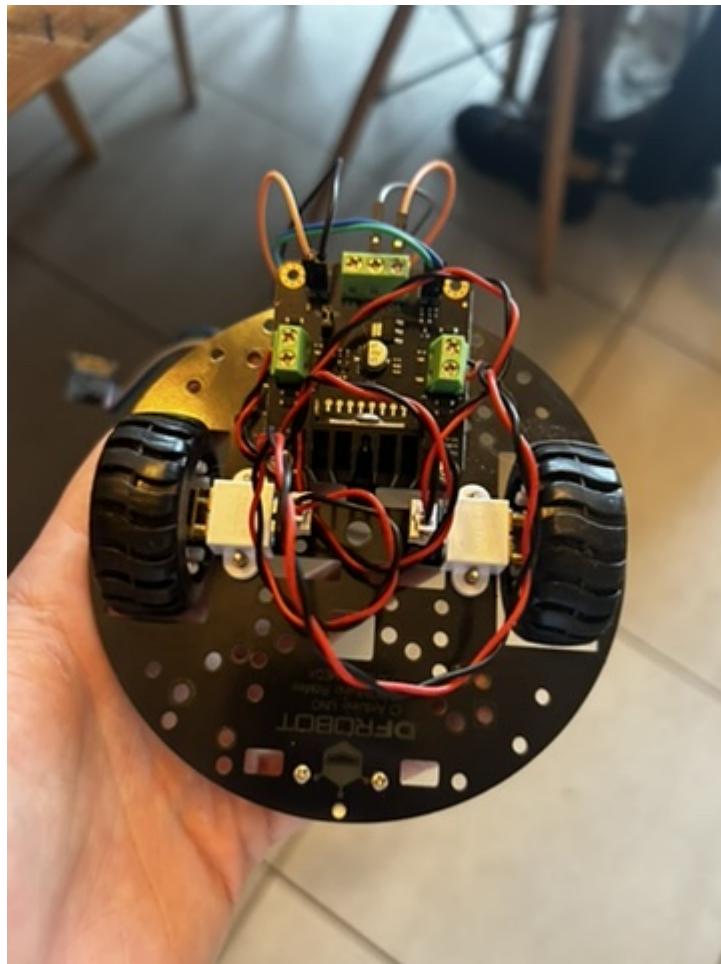
Step 1: Base Assembly

To assemble the base, you can follow this youtube video from the makers themselves:



Step 2: Attach Motor Driver

Attach the motor driver to the base using 2 screws that came with the kit. Just so that it barely fits on the base.



Step 3: Attach ESP32-WROOM-32 module to the motor driver

Connect the Wires of the motor driver to the ESP32-WROOM-32 as shown in the electrical schematic below.

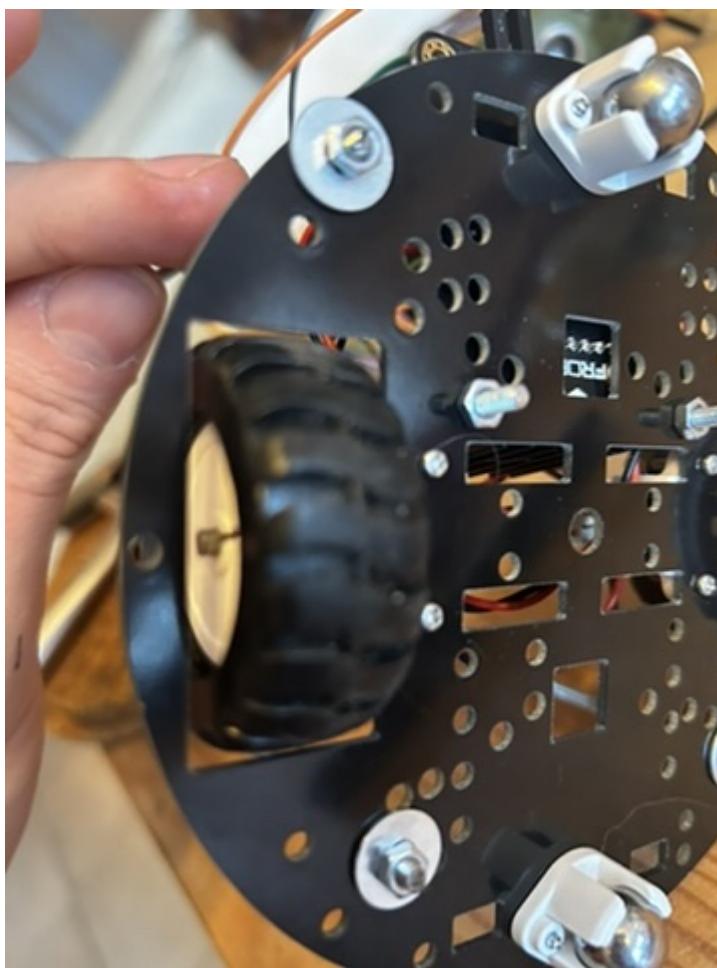


Step 4: Cut the support beams

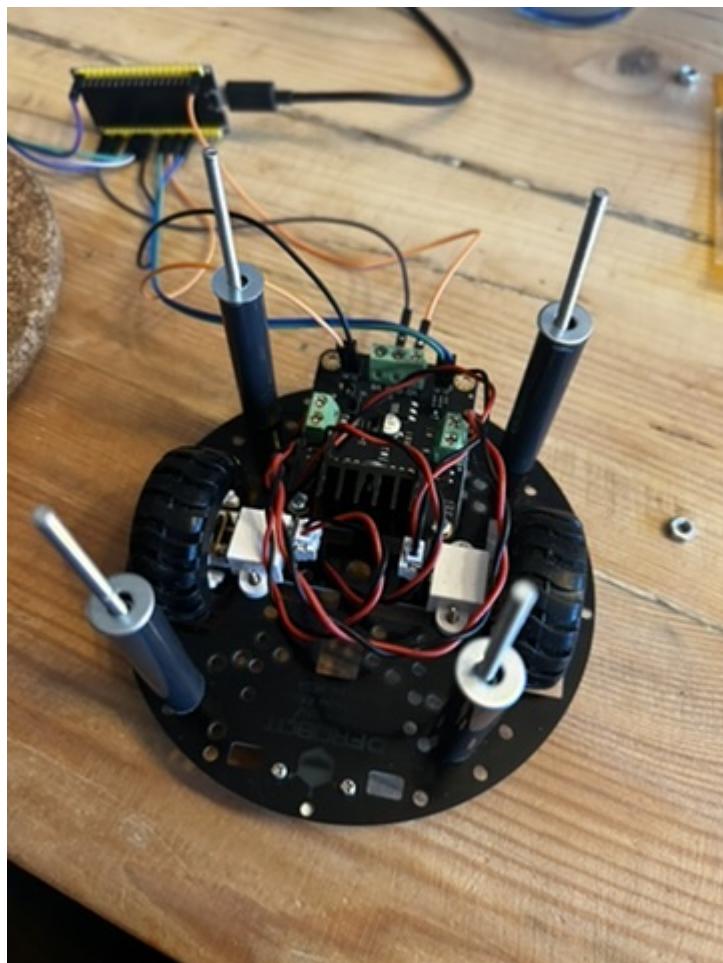
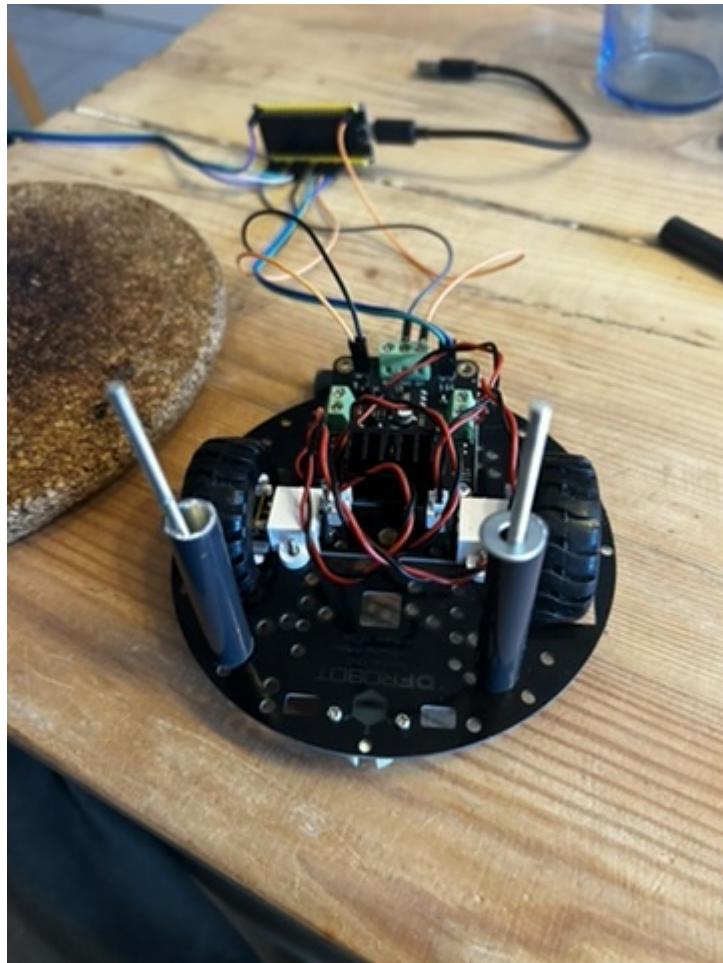
Cut the support beams so that we can securely attach the top plate to the base. I cut them to ~7cm.



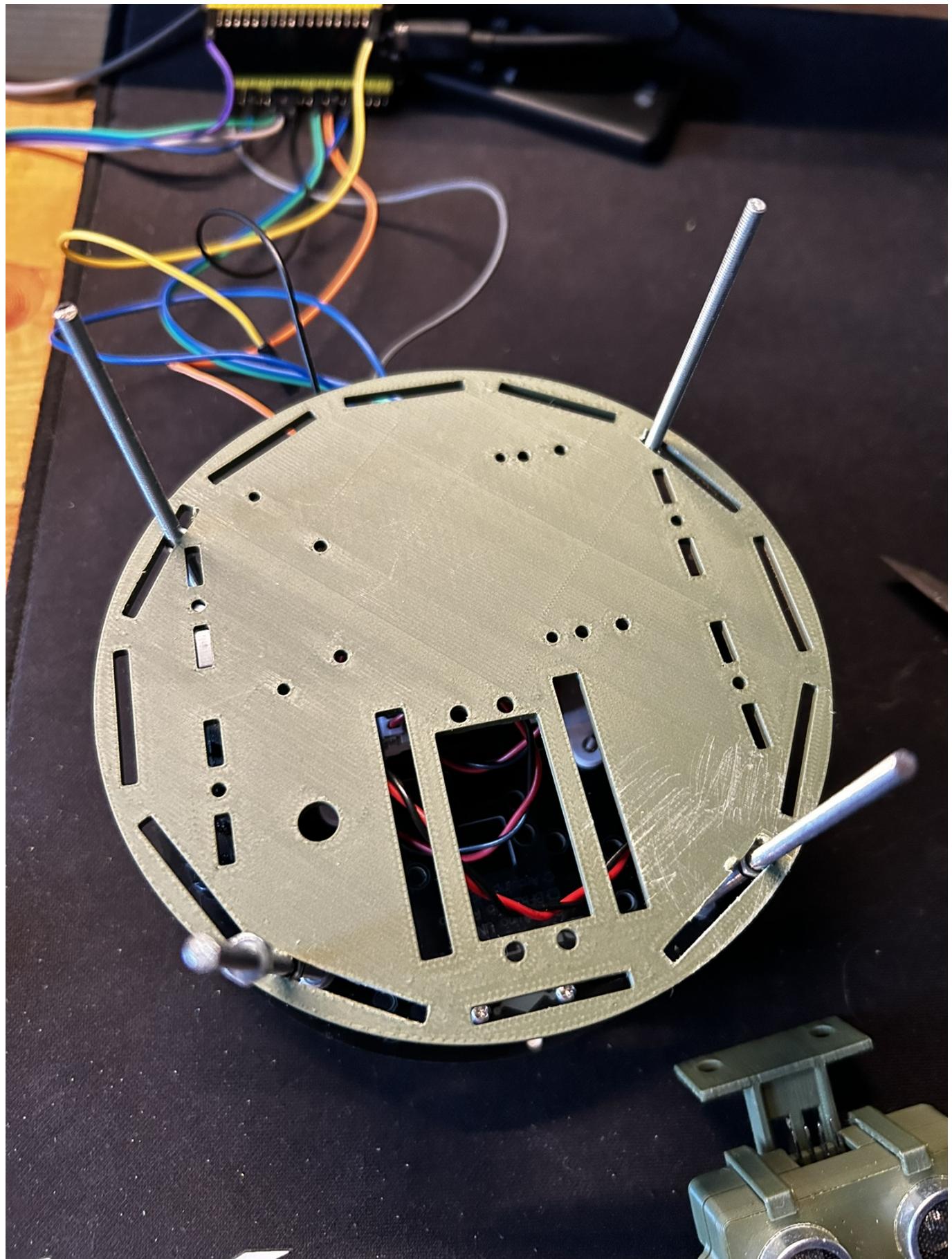
Step 5: Screw in the supports on the bottom of the bottom plate



Step 6: Mount all the supports on the bottom plate



Step 7: Attach the top plate (you will need to drill holes so that the supports can fit through the top plate)



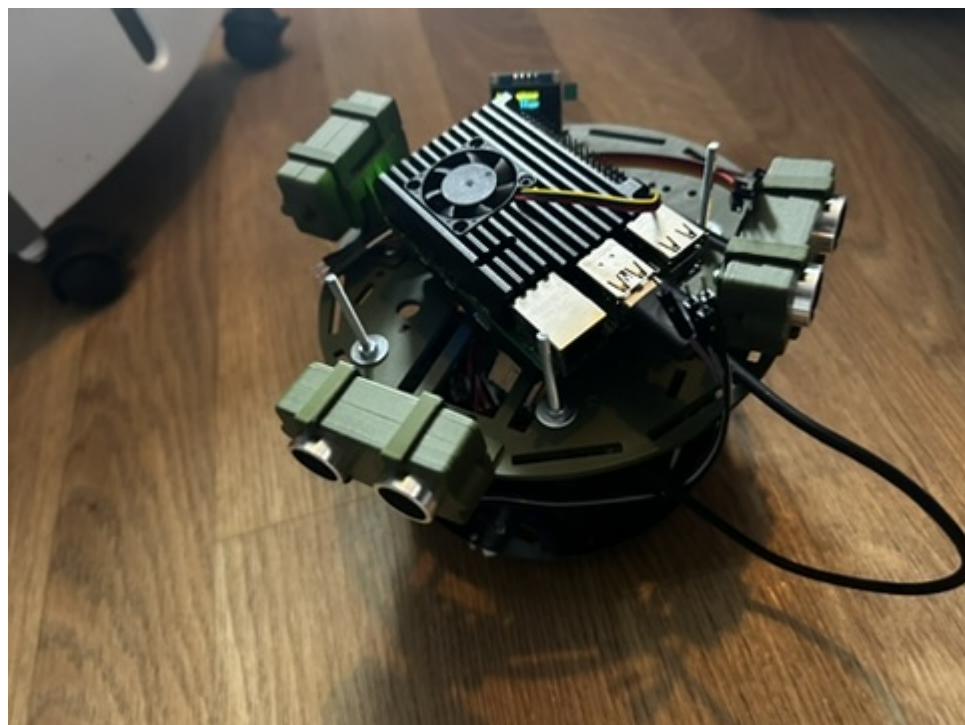
Step 8: Attach the ultrasonic sensor to the top plate



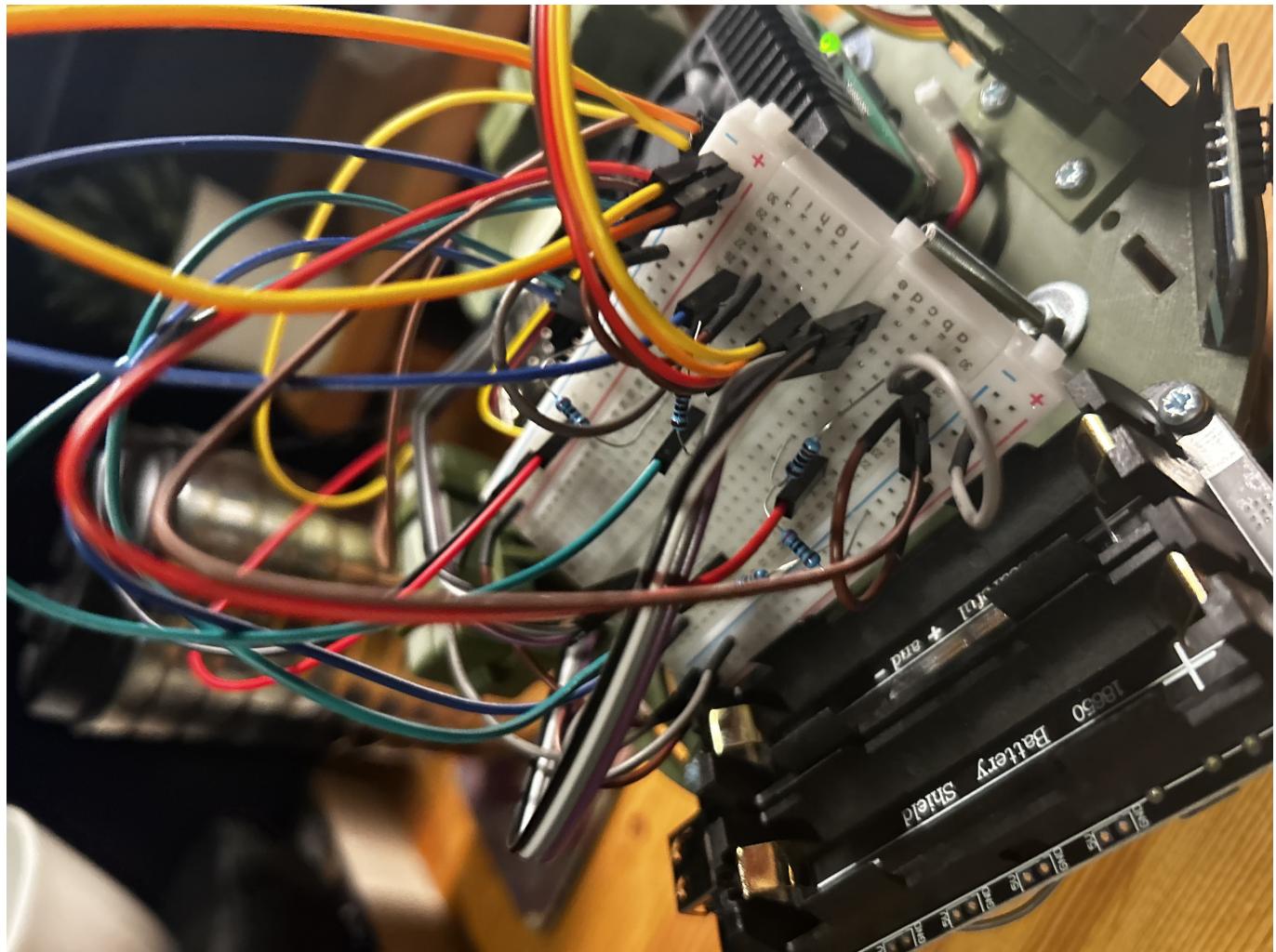
Step 9: Attach the battery pack to the RPI 5

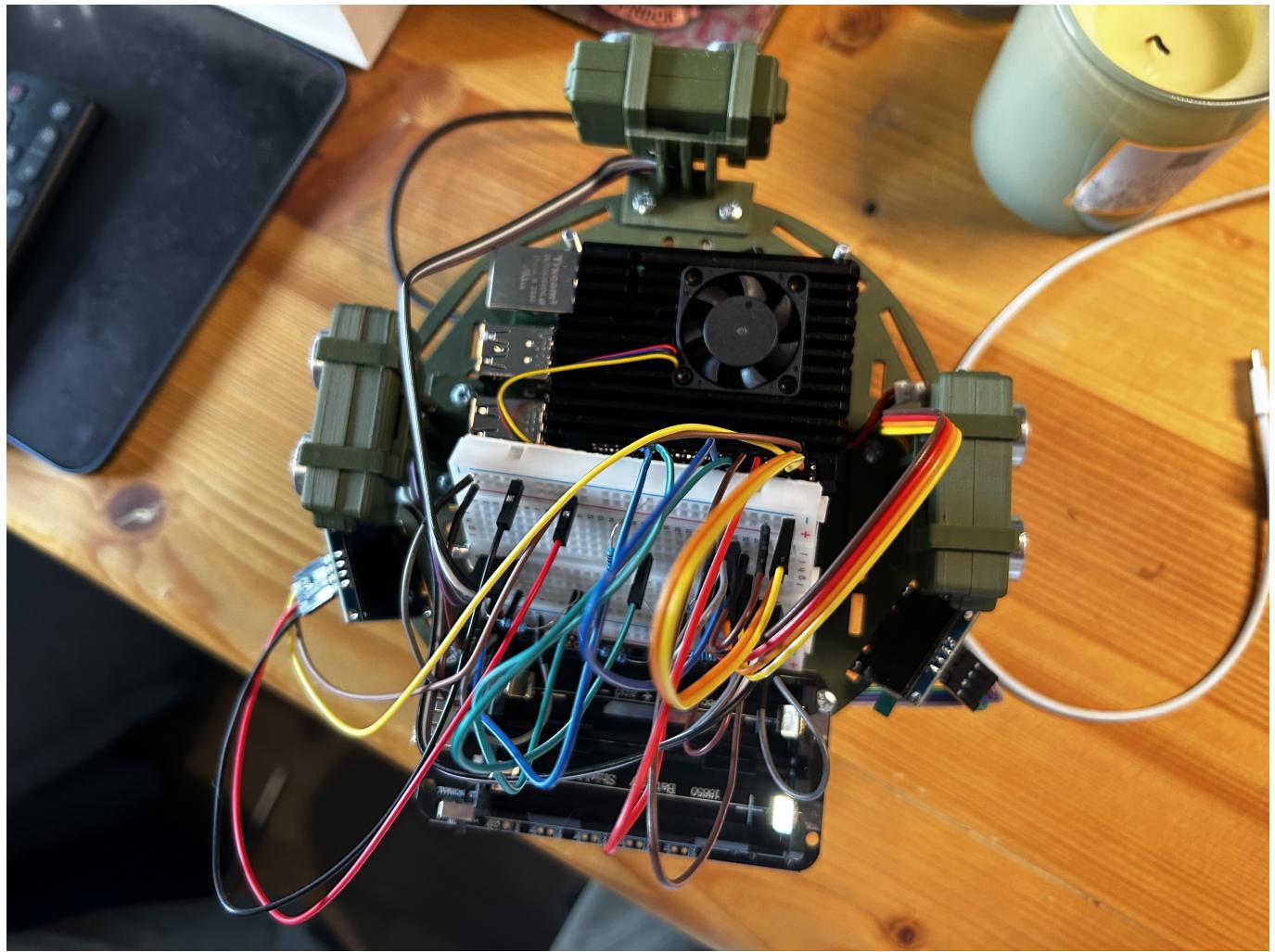


Step 9.5: Place RPI 5 on top of the top plate



Step 10: Connect the hc-sr04 sensor to the RPI 5 and try to fit them on the top plate, togheter with the battery holder for the ESP32 and the mini oled screen(s)

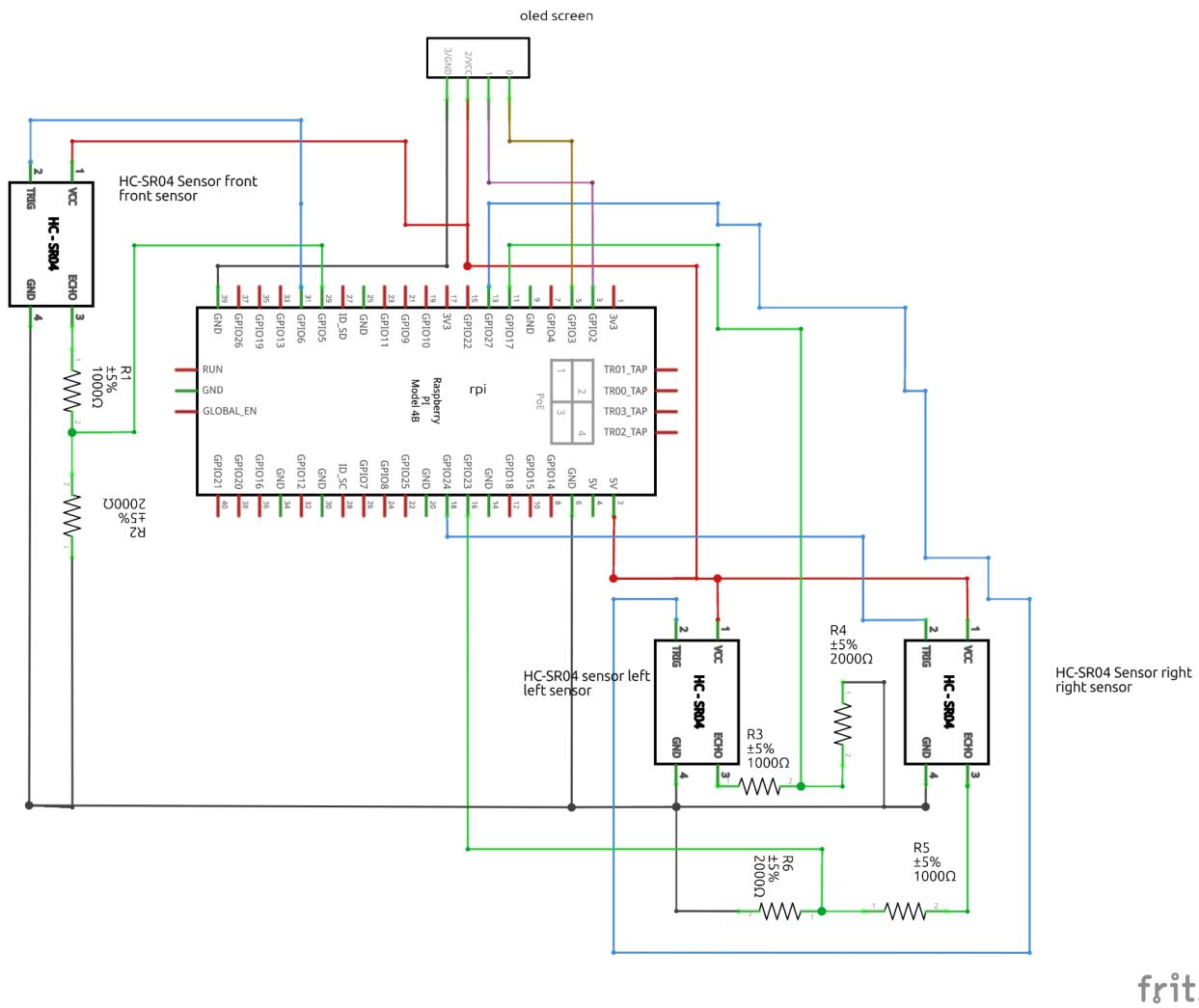




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Wiring Guide

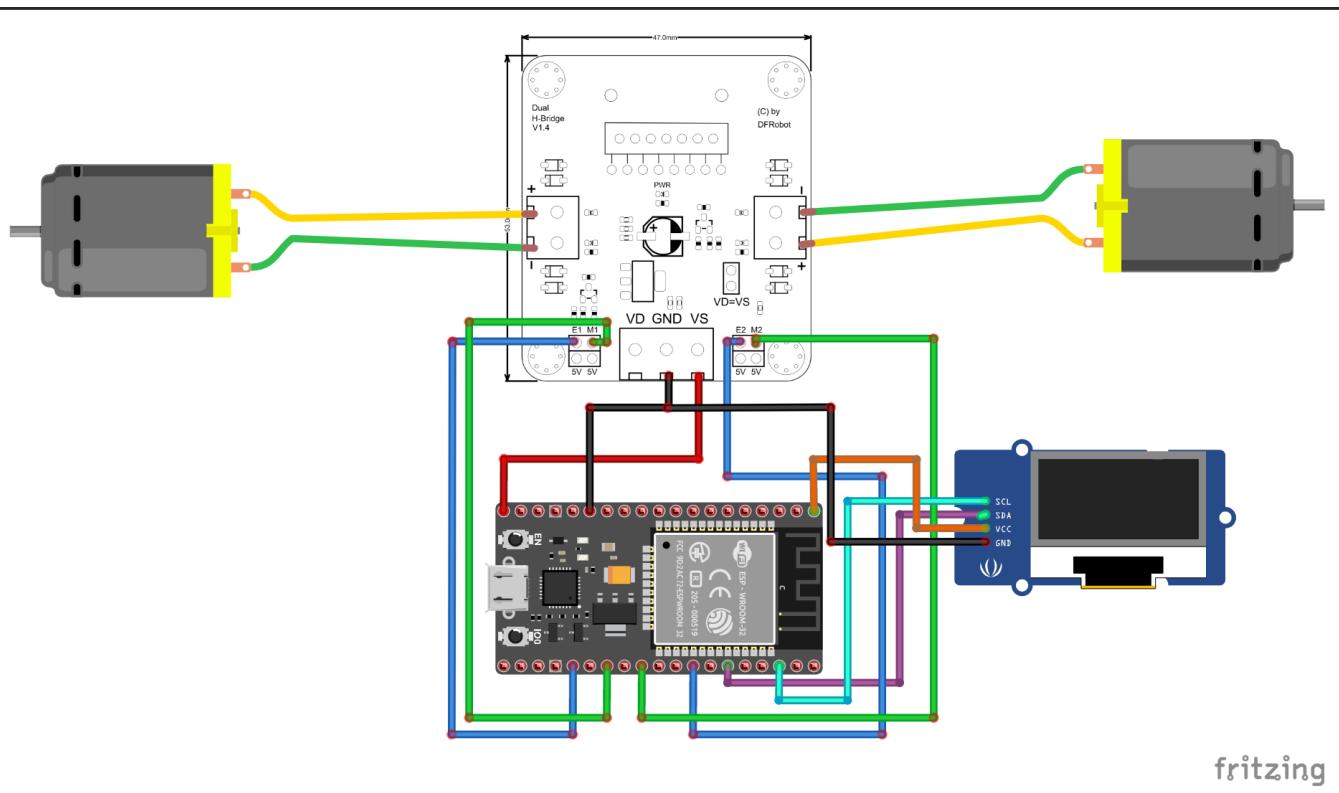
RPI5 Wiring



fritzing

Detail the wiring for the motors, referencing the motor driver documentation.

ESP32 Wiring



fritzing

Explain how to wire the sensors to the main board.

esp32 Motor pins

```
int E1 = 2;  
int M1 = 17;  
int E2 = 19;  
int M2 = 4;
```

...

Software Configuration

.... to be added