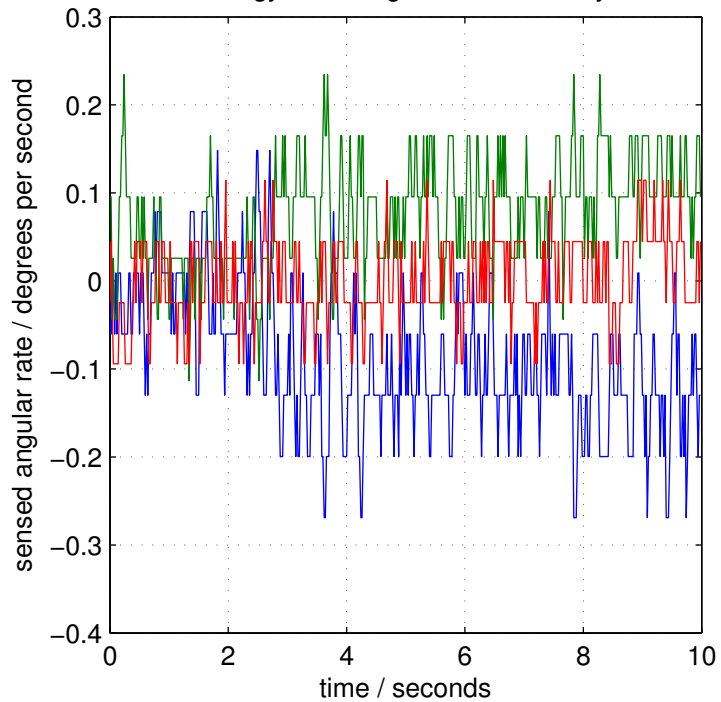


raw gyro readings when stationary



smoothed gyro readings when stationary

