

# Chapter 7: Deadlocks



# Chapter 7: Deadlocks

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- System Model
- Deadlock Characterization
- Methods for Handling Deadlocks
- Deadlock Prevention
- Deadlock Avoidance
- Deadlock Detection
- Recovery from Deadlock


# Chapter Objectives

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- To understand **when deadlock occurs** and **how to handle deadlocks** occurred and/or will occur on tasks
- To present a number of different methods for **preventing** or **avoiding** deadlocks in a computer system

# System Model

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- System consists of resources
- Resource types  $R_1, R_2, \dots, R_m$ 
  - *CPU cycles, memory space, I/O devices* 
- Each resource type  $R_i$  has  $W_i$  instances.
- Example: a dual core computer system has a CPU resource  $R_i$  with two instances ( $W_1, W_2$ )
- Each process utilizes a resource as follows:
  - **request**
  - **use**
  - **release**

# Deadlock Characterization

- Deadlock, which is a state that each member of a group is waiting for the others to take actions for progress. **No further progress can be made.**
- Deadlock can arise **if four conditions hold simultaneously.**



- **Mutual exclusion:** only one process at a time can use a resource
- **Hold and wait:** a process holding at least one resource is waiting to acquire additional resources held by other processes
- **No preemption:** a resource can be released only voluntarily by the process holding it, after that process has completed its task
- **Circular wait:** there exists a set  $\{P_0, P_1, \dots, P_n\}$  of waiting processes such that  $P_0$  is waiting for a resource that is held by  $P_1$ ,  $P_1$  is waiting for a resource that is held by  $P_2$ , ...,  $P_{n-1}$  is waiting for a resource that is held by  $P_n$ , and  $P_n$  is waiting for a resource that is held by  $P_0$ .

# Resource-Allocation Graph

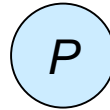
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A set of vertices  $V$  and a set of edges  $E$ .

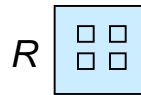
- $V$  is partitioned into two types:
  - $P = \{P_1, P_2, \dots, P_n\}$ , the set consisting of all the processes in the system
  - $R = \{R_1, R_2, \dots, R_m\}$ , the set consisting of all resource types in the system
- **request edge** – directed edge  $P_i \rightarrow R_j$
- **assignment edge** – directed edge  $R_j \rightarrow P_i$

# Resource-Allocation Graph (Cont.)

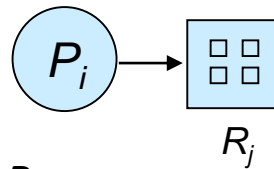
- Process  $P$



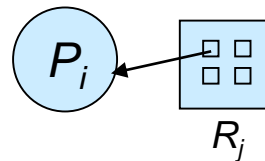
- Resource Type  $R$  with 4 instances



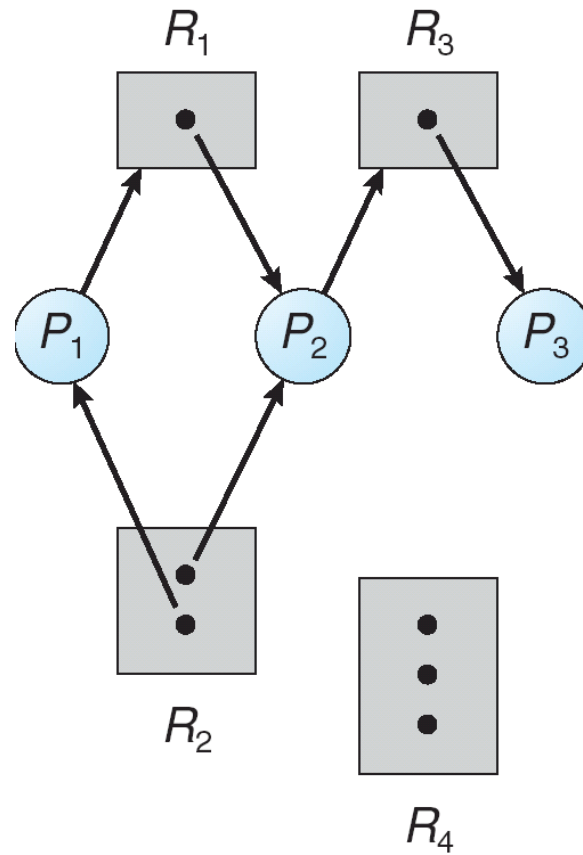
- $P_i$  requests instance of  $R_j$



- $P_i$  is holding an instance of  $R_j$

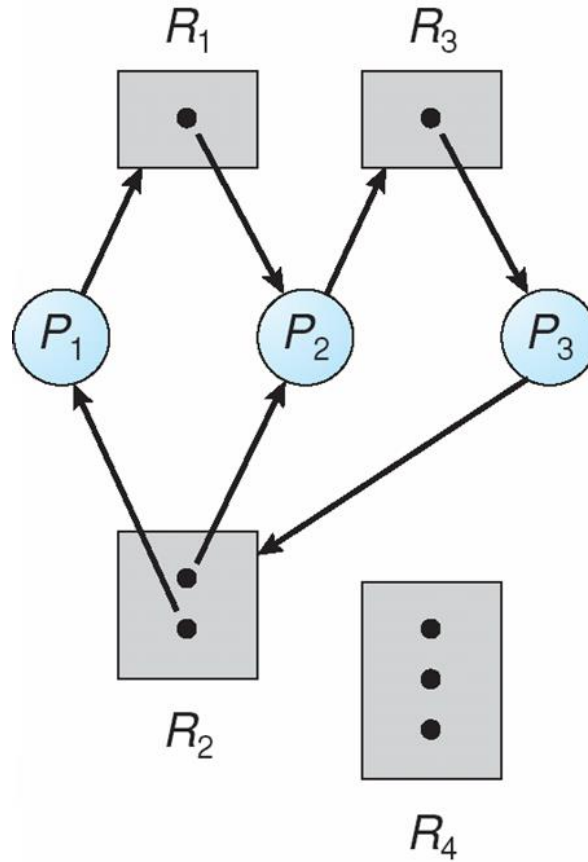


# Example of a Resource Allocation Graph

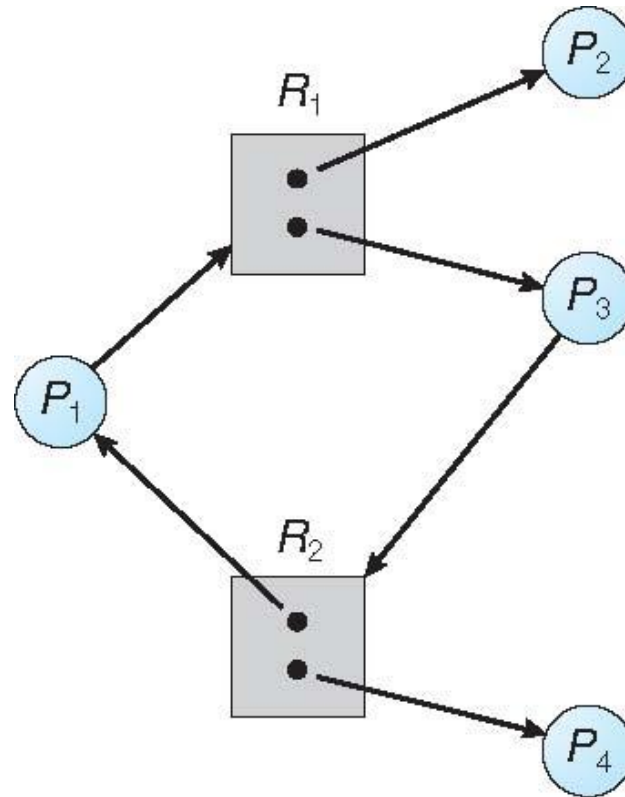




# Resource Allocation Graph With A Deadlock



# Graph With A Cycle But No Deadlock




# Basic Facts

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- If graph contains no cycles  $\Rightarrow$  no deadlock
- If graph contains a cycle  $\Rightarrow$ 
  - if only one instance exists per resource type, then deadlock must occur
  - if several instances exist per resource type, deadlock can possibly occur

# Methods for Handling Deadlocks



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- Approach 1: Ensure that the system will *never* enter a deadlock state:
  - Deadlock prevention
  - Deadlock avoidance
- Approach 2: Allow the system to enter a deadlock state and then recover from the deadlock
- Approach 3: Ignore the problem and pretend that deadlocks never occur in the system; used by most operating systems, including Linux and Windows.
  - It is up to the application developer to write programs that handle deadlocks

# Deadlock Prevention



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Restrain the ways request can be made

- **Mutual Exclusion** – not required for sharable resources (e.g., read-only files); however some resources are intrinsically nonsharable (e.g., a mutex lock), so cannot prevent deadlock by denying mutual-exclusion condition. 
- **Hold and Wait** – must guarantee that whenever a process requests a resource, it does not hold any other resources 
  - Require process to request and be allocated all its resources before it begins execution, or allow process to request resources only when the process has none allocated to it.
  - Low resource utilization; starvation possible

# Deadlock Prevention (Cont.)

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- **No Preemption** – 
  - If a process that is holding some resources requests another resource that cannot be immediately allocated to it, if the other process holding the another resource
    - is waiting, then release the other process and assign its resource to the process
    - is not waiting, then the process waits
  - Preempted resources are added to the list of resources for which the process is waiting
  - Process will be restarted only when it can regain its *old* resources, as well as the *new* ones that it is requesting
- **Circular Wait** – impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration 

# Deadlock Example

```
/* thread one runs in this function */
void *do_work_one(void *param)
{
    pthread_mutex_lock(&first_mutex);
    pthread_mutex_lock(&second_mutex);
    /** * Do some work */
    pthread_mutex_unlock(&second_mutex);
    pthread_mutex_unlock(&first_mutex);
    pthread_exit(0);
}

/* thread two runs in this function */
void *do_work_two(void *param)
{
    pthread_mutex_lock(&second_mutex);
    pthread_mutex_lock(&first_mutex);
    /** * Do some work */
    pthread_mutex_unlock(&first_mutex);
    pthread_mutex_unlock(&second_mutex);
    pthread_exit(0);
}
```

In this example, deadlock is possible if thread\_one acquires first\_mutex while thread\_two acquires second\_mutex

A lock-order verifier, **witness**, records the relationship that first\_mutex must be acquired before second\_mutex. If thread two later acquires the locks out of order, witness generates a warning message on the system console. 

# Deadlock Example with Lock Ordering

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```
void transaction(Account from, Account to, double amount)
{
    mutex lock1, lock2;
    lock1 = get_lock(from);
    lock2 = get_lock(to);
    acquire(lock1);
    acquire(lock2);
    withdraw(from, amount);
    deposit(to, amount);
    release(lock2);
    release(lock1);
}
```



Transactions 1 and 2 execute concurrently.

Transaction 1: transaction(A, B, \$25);

Transaction 2: transaction(B, A, \$50);

Depending on values of parameters (from and to), deadlock is possible



# Deadlock Avoidance



Requires that the system has some additional ***a priori*** information available



- Simplest and most useful model requires that each process declare the ***maximum number*** of resources of each type that it may need
- The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition
- Resource-allocation *state* is defined by the number of available and allocated resources, and the maximum demands of the processes

# Safe State


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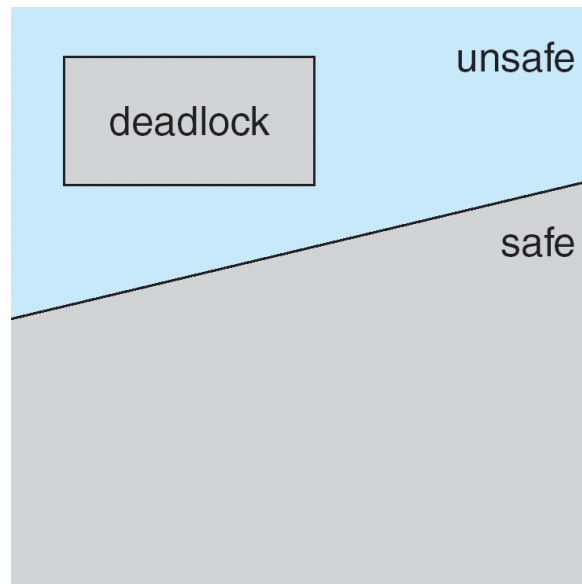
- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state
- System is in **safe state** if there exists a sequence  $\langle P_1, P_2, \dots, P_n \rangle$  of ALL the processes in the systems such that for each  $P_i$ , the resources that  $P_i$  can still request can be satisfied by currently available resources + resources held by all the  $P_j$ , with  $j < i$
- That is:
  - If  $P_i$  resource needs are not immediately available, then  $P_i$  can wait until all  $P_j$  have finished
  - When  $P_j$  is finished,  $P_i$  can obtain needed resources, execute, return allocated resources, and terminate
  - When  $P_i$  terminates,  $P_{i+1}$  can obtain its needed resources, and so on



# Basic Facts

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- If a system is in safe state  $\Rightarrow$  no deadlocks
- If a system is in unsafe state  $\Rightarrow$  deadlock may occur 
- Avoidance  $\Rightarrow$  ensure that a system will never enter an unsafe state.





# Avoidance Algorithms

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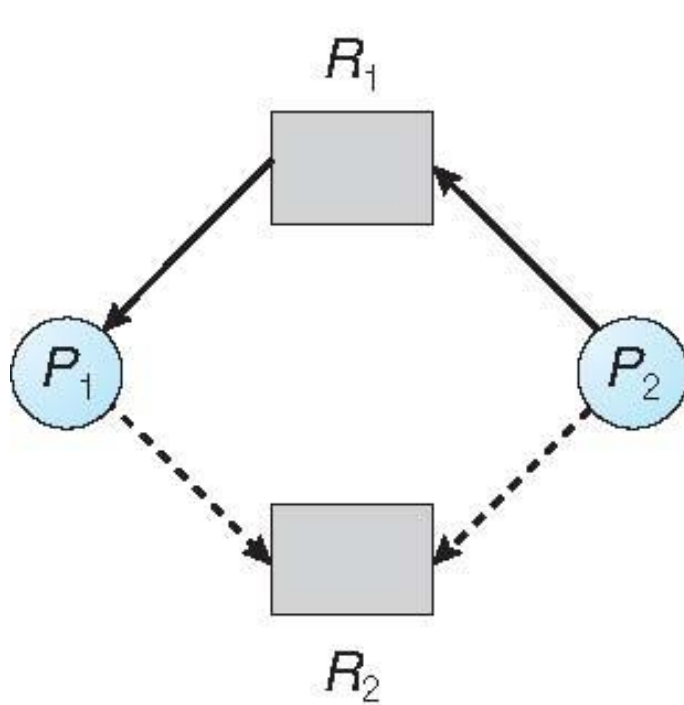
- Single instance of a resource type
  - Use a resource-allocation graph
- Multiple instances of a resource type
  - Use the banker's algorithm

# Resource-Allocation Graph Scheme

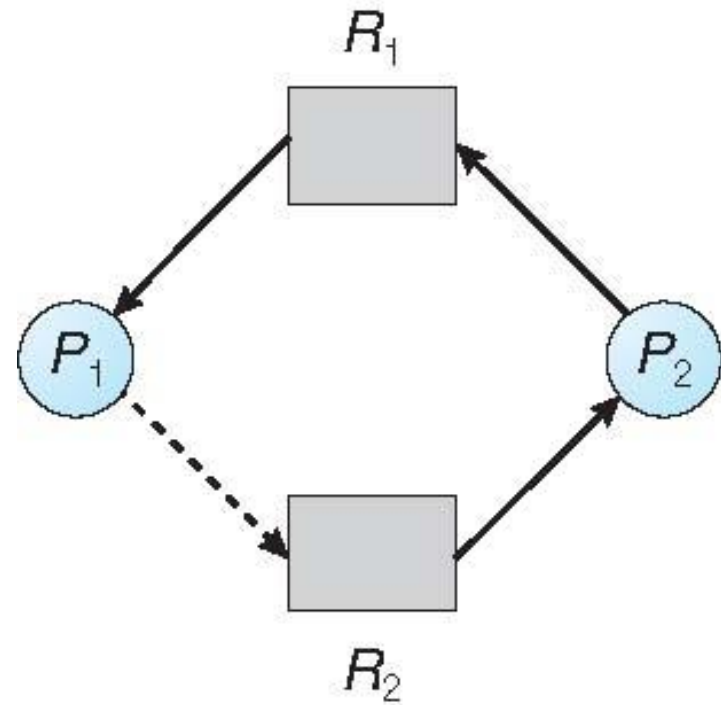
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- **Claim edge**  $P_i \rightarrow R_j$  indicated that process  $P_j$  may request resource  $R_j$ ; represented by a dashed line 
- Claim edge converts to request edge when a process requests a resource
- Request edge converted to an assignment edge when the resource is allocated to the process
- When a resource is released by a process, assignment edge reconverts to a claim edge
- Resources must be claimed *a priori* in the system 

# Resource-Allocation Graph



Resource-allocation graph  
for deadlock avoidance



An unsafe state in a  
resource-allocation graph



# Resource-Allocation Graph Algorithm

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- Suppose that process  $P_i$  requests a resource  $R_j$
- The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph

# Banker's Algorithm

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- Multiple instances in a resource type
- Each process must declare a priori claim of the maximum use to resources 
- When a process requests a set of resources, the system must determine whether the allocation of these resources will keep the system be in a safe state.
  - If it will, the resources are allocated; otherwise, the process must wait until some other process releases enough resources
- If a process gets all its resources, it must return them in a finite amount of time 



# Data Structures for the Banker's Algorithm

Let  $n$  = the number of processes, and  $m$  = the number of resource types.



- **Available:** Vector of length  $m$ . If  $available[j] = k$ , there are  $k$  instances of resource type  $R_j$  available
- **Max:**  $n \times m$  matrix. If  $Max[i,j] = k$ , then process  $P_i$  may request at most  $k$  instances of resource type  $R_j$
- **Allocation:**  $n \times m$  matrix. If  $Allocation[i,j] = k$  then  $P_i$  is currently allocated  $k$  instances of  $R_j$
- **Need:**  $n \times m$  matrix. If  $Need[i,j] = k$ , then  $P_i$  may need  $k$  more instances of  $R_j$  to complete its task

$$Need[i,j] = Max[i,j] - Allocation[i,j]$$



# Safety Algorithm

1. Let **Work** and **Finish** be vectors of length  $m$  and  $n$ , respectively. Initialize:

**Work** = **Available** [1: $m$ ]

**Finish** [ $i$ ] = **false** for  $i = 0, 1, \dots, n-1$  

2. Find an  $i$  such that both:

(a) **Finish** [ $i$ ] = **false**

(b) **Need** <sub>$i$</sub>  ≤ **Work** 

If no such  $i$  exists, go to step 4 

3. **Work** = **Work** + **Allocation** <sub>$i$</sub>




**Finish** [ $i$ ] = **true** 

go to step 2

4. If **Finish** [ $i$ ] == **true** for all  $i$ , then the system is in a safe state

# Resource-Request Algorithm for Process $P_i$

**$Request_i$**  = request vector for process  $P_i$ . If  **$Request_i[j] = k$**  then process  $P_i$  wants  $k$  instances of resource type  $R_j$

1. If  **$Request_i \leq Need_i$** , go to step 2. Otherwise, raise error condition, since the process  $i$  claimed the wrong maximum use of resources 
2. If  **$Request_i \leq Available$** , go to step 3. Otherwise  $P_i$  must wait, since resources are not available  
3. Pretend to allocate requested resources to  $P_i$  by modifying the state as follows:

$$Available = Available - Request_i;$$

$$Allocation_i = Allocation_i + Request_i;$$

$$Need_i = Need_i - Request_i;$$



- If safe  $\Rightarrow$  the resources are allocated to  $P_i$
- If unsafe  $\Rightarrow P_i$  must wait, and the old resource-allocation state is restored

# Example of Banker's Algorithm

- 5 processes  $P_0$  through  $P_4$ ;

3 resource types:

$A$  (10 instances),  $B$  (5 instances), and  $C$  (7 instances)

- Snapshot at time  $T_0$ :



	<u>Allocation</u>	<u>Max</u>	<u>Available</u>
	$A \ B \ C$	$A \ B \ C$	$A \ B \ C$
$P_0$	0 1 0	7 5 3	3 3 2
$P_1$	2 0 0	3 2 2	
$P_2$	3 0 2	9 0 2	
$P_3$	2 1 1	2 2 2	
$P_4$	0 0 2	4 3 3	

# Example (Cont.)

- The content of the matrix **Need** is defined to be **Max – Allocation**

	<u>Allocation</u>	<u>Max</u>	<u>Available</u>	<u>Need</u>
	A B C	A B C	A B C	A B C
$P_0$	0 1 0	7 5 3	3 3 2	7 4 3
$P_1$	2 0 0	3 2 2		1 2 2
$P_2$	3 0 2	9 0 2		6 0 0
$P_3$	2 1 1	2 2 2		0 1 1
$P_4$	0 0 2	4 3 3		4 3 1

- The system is in a safe state since the sequence  $\langle P_1, P_3, P_4, P_2, P_0 \rangle$  satisfies safety criteria



- Available** becomes

- $P_1$ : 2 1 0 ->  $P_1$  finishes -> 5 3 2
- $P_3$ : 5 2 1 ->  $P_3$  finishes -> 7 4 3
- $P_4$ : 3 1 2 ->  $P_4$  finishes -> 7 4 5
- $P_2$ : 1 4 5 ->  $P_2$  finishes -> 10 4 7
- $P_0$ : 3 0 4 ->  $P_0$  finishes -> 10 5 7

# Example: $P_1$ Request (1,0,2)

- Check that Request  $\leq$  Available (that is,  $P_1$ 's (1,0,2)  $\leq$  (3,3,2)  $\Rightarrow$  true)

	<u>Allocation</u>	<u>Need</u>	<u>Available</u>
	A B C	A B C	A B C
$P_0$	0 1 0	7 4 3	2 3 0
$P_1$	3 0 2	0 2 0	
$P_2$	3 0 2	6 0 0	
$P_3$	2 1 1	0 1 1	
$P_4$	0 0 2	4 3 1	

- Executing safety algorithm shows that sequence  $\langle P_1, P_3, P_4, P_0, P_2 \rangle$  satisfies safety requirement
- Can request for (3,3,0) by  $P_4$  be granted? 
- Can request for (0,2,0) by  $P_0$  be granted? 


# Deadlock Detection



- Allow system to enter deadlock state
- Detection algorithm
- Recovery scheme

# Single Instance of Each Resource Type

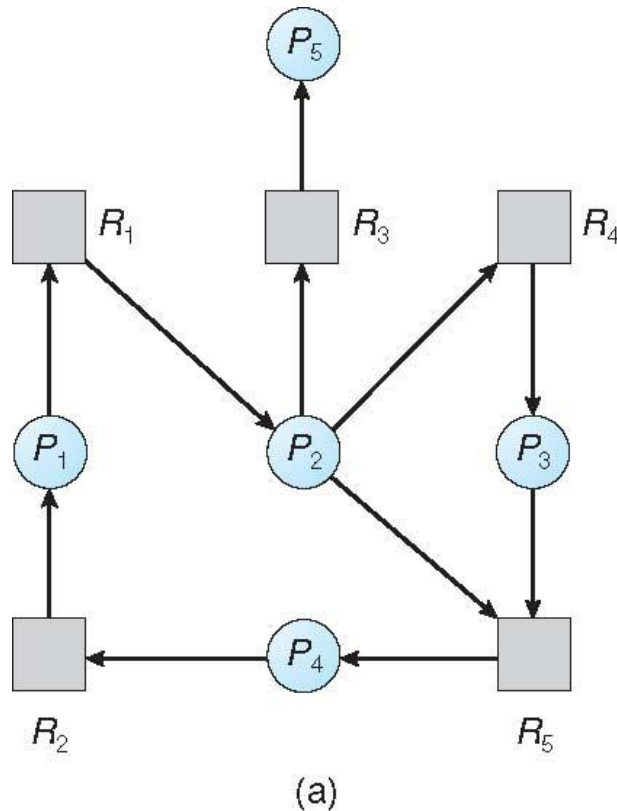
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- Maintain **wait-for** graph 
  - Nodes are processes
  - $P_i \rightarrow P_j$  if  $P_i$  is waiting for  $P_j$
- Periodically invoke an algorithm that searches for a cycle in the graph. If there is a cycle, there exists a deadlock
- An algorithm to detect a cycle in a graph requires an order of  $n^2$  operations, where  $n$  is the number of vertices in the graph

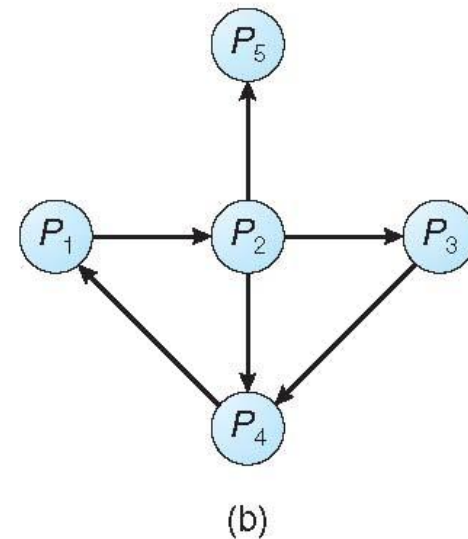




# Resource-Allocation Graph and Wait-for Graph



Resource-Allocation Graph



Corresponding wait-for graph




# Several Instances of a Resource Type

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- **Available:** A vector of length  $m$  indicates the number of available resources of each type
- **Allocation:** An  $n \times m$  matrix defines the number of resources of each type currently allocated to each process
- **Request:** An  $n \times m$  matrix indicates the current request of each process. If **Request**  $[i][j] = k$ , then process  $P_i$  is requesting  $k$  more instances of resource type  $R_j$ .



# Detection Algorithm

1. Let **Work** and **Finish** be vectors of length  $m$  and  $n$ , respectively. Initialize:
  - (a) **Work = Available**
  - (b) For  $i = 1, 2, \dots, n$ , if  $Allocation_i \neq 0$ , then  
**Finish[i] = false**; otherwise, **Finish[i] = true** 
2. Find an index  $i$  such that both:
  - (a) **Finish[i] == false**
  - (b) **Request<sub>i</sub> ≤ Work**If no such  $i$  exists, go to step 4
3. **Work = Work + Allocation<sub>i</sub>**  
**Finish[i] = true**  
go to step 2
4. If **Finish[i] == false**, for some  $i$ ,  $1 \leq i \leq n$ , then the system is in deadlock state.  
Moreover, if **Finish[i] == false**, then  $P_i$  is deadlocked

**Algorithm requires an order of  $O(m \times n^2)$  operations to detect whether the system is in deadlocked state**

# Example of Detection Algorithm



- Five processes  $P_0$  through  $P_4$ ; three resource types A (7 instances), B (2 instances), and C (6 instances)



- Snapshot at time  $T_0$ :

	<u>Allocation</u>	<u>Request</u>	<u>Available</u>
	A B C	A B C	A B C
$P_0$	0 1 0	0 0 0	0 0 0
$P_1$	2 0 0	2 0 2	
$P_2$	3 0 3	0 0 0	
$P_3$	2 1 1	1 0 0	
$P_4$	0 0 2	0 0 2	

- Sequence  $\langle P_0, P_2, P_3, P_1, P_4 \rangle$  will result in ***Finish[i] = true*** for all  $i$

# Example (Cont.)

- $P_2$  requests an additional instance of type **C**



	<u>Request</u>		
	A	B	C
$P_0$	0	0	0
$P_1$	2	0	2
$P_2$	0	0	1
$P_3$	1	0	0
$P_4$	0	0	2

- State of system?
  - Can reclaim resources held by process  $P_0$ , but insufficient resources to fulfill other processes; requests
  - Deadlock exists, consisting of processes  $P_1$ ,  $P_2$ ,  $P_3$ , and  $P_4$



# Detection-Algorithm Usage



- When, and how often, to invoke depends on:
  - How often a deadlock is likely to occur?
  - How many processes will need to be rolled back?
    - one for each disjoint cycle
- In the extreme, we can invoke the deadlock detection algorithm every time a request for allocation cannot be granted immediately.  
Considerable overhead is incurred
- If detection algorithm is invoked arbitrarily, there may be many cycles in the resource graph and so we would not be able to tell which of the many deadlocked processes “caused” the deadlock.

# Recovery from Deadlock: Process Termination


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- Abort all deadlocked processes
- Abort one process at a time until the deadlock cycle is eliminated
- In which order should we choose to abort?
  1. Priority of the process 
  2. How long process has computed, and how much longer to completion
  3. Resources the process has used 
  4. Resources process needs to complete
  5. How many processes will need to be terminated
  6. Is process interactive or batch?



# Recovery from Deadlock: Resource Preemption

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- **Selecting a victim** – minimize cost 
- **Rollback** – return to some safe state, restart process for that state
- **Starvation** – same process may always be picked as victim, include number of rollback in cost factor



# End of Chapter 7

