### CH08-320201

# Algorithms and Data Structures ADS

#### Lecture 15

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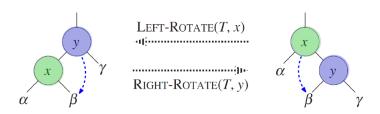
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## **Operations**

- Querying
  - Search/Minimum & Maximum/Successor & Predecessor
  - Just as in normal BST
    - ▶ O(lg n)
- Modifying
  - ▶ Tree-Insert/Tree-Delete  $\rightarrow O(\lg n)$
  - But, need to guarantee red-black tree properties:
    - must change color of some nodes
    - change pointer structure through rotation

# Rotations (1)

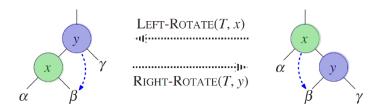
- ▶ Right-Rotate(T, y):
  - node y becomes right child of its left child x.
  - new left child of y is former right child of x.
- ► Left-Rotate(T,x):
  - node x becomes left child of its right child y.
  - new right child of x is former left child of y.



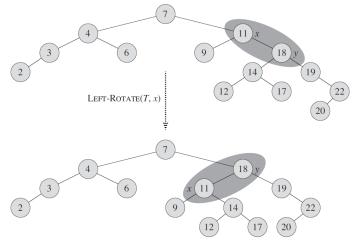
# Rotations (2)

#### BST property is preserved:

- (left):  $key(\alpha) \le x.key \le key(\beta) \le y.key \le key(\gamma)$
- (right):  $key(\alpha) \le x.key \le key(\beta) \le y.key \le key(\gamma)$



## Rotation: Example



## Rotation Pseudocode

Time complexity: O(1)

```
LEFT-ROTATE (T, x)
   y = x.right
                               /\!\!/ set y
 2 x.right = y.left
                               # turn y's left subtree into x's right subtree
 3 if y.left \neq T.nil
        y.left.p = x
 5 v.p = x.p
                               // link x's parent to y
 6 if x.p == T.nil
         T.root = y
    elseif x == x.p.left
        x.p.left = v
10 else x.p.right = y
11 y.left = x
                               /\!\!/ put x on y's left
12 x.p = y
```

#### Insertion

```
TREE-INSERT(T, z)
    v = NIL
    x = T.root
    while x \neq NIL
       v = x
       if z. key < x. key
            x = x.left
        else x = x.right
    z.p = y
    if y == NIL
10
        T.root = z
11
    elseif z. key < y. key
12
        y.left = z
13
    else y.right = z
```

```
RB-INSERT(T, z)
    v = T.nil
    x = T.root
    while x \neq T.nil
       v = x
     if z. key < x. key
            x = x.left
        else x = x.right
    z.p = y
    if v == T.nil
10
        T.root = z
11
    elseif z. key < y. key
12
   v.left = z
    else y.right = z
14 z.left = T.nil
15 z.right = T.nil
16 \quad z.color = RED
17
    RB-INSERT-FIXUP(T, z)
```

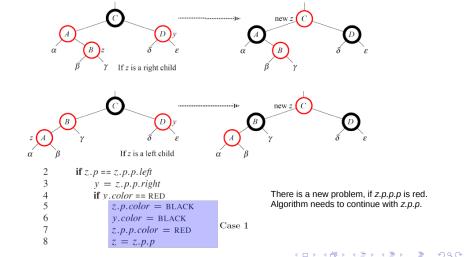
# Fixing Red-Black Tree Properties

- ▶ We are inserting a **red** node to a valid red-black tree.
- Which properties may be violated?
  - 1. Duh: Cannot be violated. ✓
  - 2. RooB: Violated if inserted node is root. X
  - 3. LeaB: Inserted node is not a leaf, i.e., no violation. ✓
  - 4. BredB: Violated if parent of inserted node is red. X
  - 5. BH: Not affected by red nodes, i.e., no violation. ✓

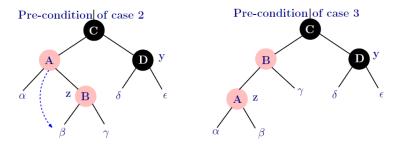
## Fixing BredB

- ▶ BredB for node z is violated, if z.p is red.
- ▶ Then, z.p.p is black. (BredB property)
- ▶ We need to consider different cases depending on the uncle y of z, i.e., the child of z.p.p that is not z.p.
- ► There are 6 cases:
  - z.p is left child of z.p.p
    - ▶ y is red (Case 1)
    - ▶ y is black
      - z is right child of z.p (Case 2)
      - z is left child of z.p (Case 3)
  - ► z.p is right child of z.p.p
    - ▶ y is red (symmetric to Case 1)
    - ▶ y is black
      - z is right child of z.p (symmetric to Case 2)
      - z is left child of z.p (symmetric to Case 3)

## Case 1 (Red Uncle)

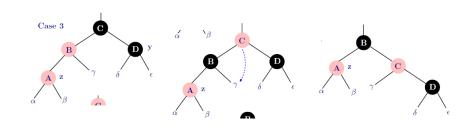


# Case 2 (Black Uncle, z Right Child)



9 **else if** z = z.p.right10 z = z.p11 Case 2

# Case 3 (Black Uncle, z Left Child)



12

13 14 z.p.color = BLACK z.p.p.color = REDRIGHT-ROTATE(T, z.p.p)

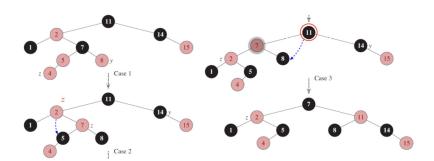
Case 3

## Putting It All Together

- We need to put the 3 cases (and the 3 symmetric cases) together.
- Moreover, we need to propagate the considerations upwards (see Case 1).
- ► Finally, we have to fix RooB.

```
RB-INSERT-FIXUP(T, z)
    while z.p.color == RED
        if z.p == z.p.p.left
             y = z.p.p.right
            if v.color == RED
                 z.p.color = BLACK
                 v.color = BLACK
                                          Case 1
                 z..p.p.color = RED
                 z = z..p.p
            else if z == z.p.right
10
                     z = z.p
                                          Case 2
11
                     LEFT-ROTATE(T, z)
12
                 z..p.color = BLACK
13
                 z.p.p.color = RED
                                          Case 3
14
                 RIGHT-ROTATE(T, z, p, p)
15
        else (same as then clause
                 with "right" and "left" exchanged)
16
    T.root.color = BLACK
```

# Insert Example



## Time Complexity

- ▶ In worst case, we have to go all the way from the leaf to the root along the longest path within the tree.
- ▶ Hence, running time is  $O(h) = O(\lg n)$  for the fixing of the red-black tree properties.
- ▶ Overall, running time for insertion is  $O(h) = O(\lg n)$ .
- Example for building up a red-black tree by iterated node insertion:

http://www.youtube.com/watch?v=vDHFF4wjWYU

## Deletion (Remember BST)

```
(a)
TREE-DELETE (T, z)
    if z. left == NIL
         TRANSPLANT(T, z, z.right)
                                               (b)
    elseif z.right == NIL
         TRANSPLANT(T, z, z. left)
    else y = \text{Tree-Minimum}(z.right)
6
         if y.p \neq z
                                               (c)
             TRANSPLANT(T, y, y.right)
8
             y.right = z.right
9
             y.right.p = y
10
         TRANSPLANT(T, z, y)
11
         y.left = z.left
                                               (d)
12
         y.left.p = y
                                                                               NIL
```

# Deletion (RB) (1)

```
TREE-DELETE (T, z)
    if z. left == NIL
        TRANSPLANT(T, z, z, right)
    elseif z.right == NIL
        TRANSPLANT(T, z, z. left)
    else y = \text{TREE-MINIMUM}(z.right)
        if y.p \neq z
             TRANSPLANT(T, v, v.right)
             v.right = z.right
 9
             v.right.p = v
10
        TRANSPLANT(T, z, y)
        y.left = z.left
11
12
        y.left.p = y
```

```
RB-DELETE(T,z)
    v = z
   v-original-color = v.color
    if z, left == T, nil
        x = z.right
         RB-TRANSPLANT(T, z, z, right)
    elseif z.right == T.nil
        x = z.left
         RB-TRANSPLANT(T, z, z, left)
    else y = \text{TREE-MINIMUM}(z.right)
10
         v-original-color = v.color
        x = v.right
12
        if v, p == z
13
            x.p = y
         else RB-TRANSPLANT(T, v, v.right)
14
15
             v.right = z.right
16
             y.right.p = y
17
         RB-TRANSPLANT(T, z, y)
18
        y.left = z.left
19
        v.left.p = v
20
         v.color = z.color
    if y-original-color == BLACK
         RB-DELETE-FIXUP(T, x)
```

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# Deletion (RB) (2)

#### node y

- either removed (a/b)
- or moved in the tree (c/d)
- v-original-color

#### node x

- the node that moves into y's original position
- x.p points to y's original parent (since it moves into y's position, note special case in 12/13)

```
RB-DELETE(T, z)
    y-original-color = y.color
    if z. left == T.nil
        x = z.right
         RB-TRANSPLANT(T, z, z, right)
 5
    elseif z.right == T.nil
         x = z.left
         RB-TRANSPLANT(T, z, z, left)
    else y = \text{TREE-MINIMUM}(z.right)
10
         v-original-color = v.color
11
        x = y.right
12
         if v, p == z
13
             x.p = y
14
         else RB-TRANSPLANT(T, v, v.right)
15
             v.right = z..right
16
             y.right.p = y
         RB-TRANSPLANT(T, z, y)
17
18
         y.left = z.left
19
         v.left.p = v
20
         v.color = z..color
21
    if y-original-color == BLACK
22
         RB-DELETE-FIXUP(T, x)
```

## Deletion (RB) (3)

```
    y-original-color == red

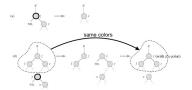
                         (with z's color
                                                 v (with z's color)
```

```
RB-DELETE(T, z)
    v = z
    v-original-color = v.color
    if z. left == T. nil
        x = z.right
         RB-TRANSPLANT(T, z, z, right)
    elseif z.right == T.nil
        x = z.left
         RB-TRANSPLANT(T, z, z, left)
    else y = \text{TREE-MINIMUM}(z.right)
        y-original-color = y.color
        x = y.right
        if y.p == z
             x.p = v
         else RB-TRANSPLANT(T, y, y.right)
15
             y.right = z.right
16
             v.right.p = v
17
         RB-TRANSPLANT(T, z, y)
18
         y.left = z.left
19
         y.left.p = y
20
         y.color = z.color
    if y-original-color == BLACK
         RB-DELETE-FIXUP(T, x)
```

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# Deletion (RB) (4)

- y-original-color == red
  - no problem
- y-original-color == black
  - violations might occur (2,4,5)
  - main idea to fix
    - x gets an "extra black" & needs to get rid of it
  - 4 cases



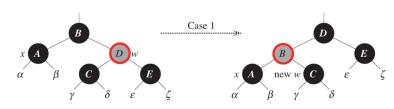
```
RB-DELETE(T, z)
    v = z
    y-original-color = y.color
    if z. left == T. nil
         x = z.right
         RB-TRANSPLANT(T, z, z. right)
    elseif z. right == T.nil
         x = z..left
         RB-TRANSPLANT(T, z, z, left)
    else v = \text{TREE-MINIMUM}(z, right)
10
         y-original-color = y.color
11
         x = y.right
         if y.p == z.
13
             x.p = v
         else RB-TRANSPLANT(T, y, y.right)
14
15
             v.right = z.right
16
             y.right.p = y
         RB-TRANSPLANT(T, z, y)
18
         v.left = z..left
19
         v.left.p = v
20
         v.color = z.color
21
    if y-original-color == BLACK
22
         RB-DELETE-FIXUP(T, x)
```

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# Fixing Red-Black Tree Properties (1)

Case 1: x's sibling w is red.

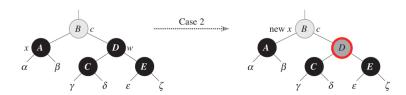
Transform to Case 2, 3, or 4 by left rotation and changing colors of nodes B and D.



x = node with extra black w = x's sibling if w.color == RED w.color == BLACK x.p.color == RED LEFT-ROTATE(T, x.p)w = x.p.right

# Fixing Red-Black Tree Properties (2)

Case 2: x's sibling w is black and the children of w are black. Set color of w to red and propagate upwards.



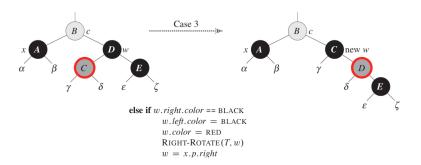
x = node with extra black
w = x's sibling
c = color of the node

if w.left.color == BLACK and w.right.color == BLACK w.color = REDx = x.p

# Fixing Red-Black Tree Properties (3)

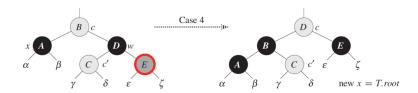
Case 3: x's sibling w is black and the left child of w is red, while the right child of w is black.

Transform to Case 4 by right rotation and changing colors of nodes C and D.



# Fixing Red-Black Tree Properties (4)

Case 4: x's sibling w is black and the right child of w is red. Perform a left-rotate and change colors of B, D, and E. Then, the loop terminates.



w.color = x.p.color x.p.color = BLACK w.right.color = BLACKLEFT-ROTATE(T, x.p)

# Fixing Red-Black Tree Properties (5)

```
RB-DELETE-FIXUP(T, x)
    while x \neq T.root and x.color == BLACK
        if x == x.p.left
             w = x.p.right
            if w.color == RED
                 w.color = BLACK
                                                                    // case 1
                 x.p.color = RED
                                                                    // case 1
                 LEFT-ROTATE(T, x, p)
                                                                    // case 1
                 w = x.p.right
                                                                   // case 1
            if w.left.color == BLACK and w.right.color == BLACK
10
                 w.color = RED
                                                                   // case 2
                                                                    // case 2
                 x = x.p
12
            else if w.right.color == BLACK
13
                     w.left.color = BLACK
                                                                   // case 3
14
                     w \ color = RED
                                                                    // case 3
15
                     RIGHT-ROTATE (T, w)
                                                                   // case 3
                     w = x.p.right
                                                                   // case 3
16
17
                 w.color = x.p.color
                                                                    // case 4
18
                 x.p.color = BLACK
                                                                    // case 4
19
                 w.right.color = BLACK
                                                                   // case 4
20
                 LEFT-ROTATE(T, x, p)
                                                                   // case 4
21
                 x = T.root
                                                                   // case 4
22
        else (same as then clause with "right" and "left" exchanged)
    x.color = BLACK
```

Time complexity:  $O(h) = O(\lg n)$ 

## Conclusion

Modifying operations on red-black trees can be executed in  $O(\lg n)$  time.

#### Direct Access Table

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- ► The idea of a direct access table is that objects are directly accessed via their key.
- ▶ Assuming that keys are out of  $U = \{0, 1, ..., m-1\}$ .
- ▶ Moreover, assume that keys are distinct.
- ▶ Then, we can set up an array T[0..m-1] with

$$T[k] = \begin{cases} x & \text{if } x \in K \text{ and } key[x] = k \\ \text{NIL} & \text{otherwise.} \end{cases}$$

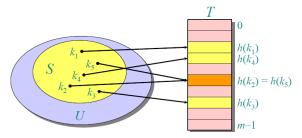
- Time complexity: With this set-up, we can have the dynamic-set operations (Search, Insert, Delete, ...) in Θ(1).
- ▶ Problem: *m* is often large. For example, for 64-bit numbers we have 18, 446, 744, 073, 709, 551, 616 different keys.

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#### Hash Function

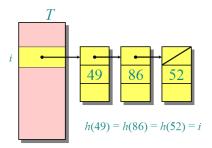
▶ Use a function h that maps U to a smaller set  $\{0, 1, ..., m-1\}$ .



- Such a function is called a hash function.
- ▶ The table *T* is called a hash table.
- If two keys are mapped to the same location, we have a collision.

## Resolving Collisions

► Collisions can be resolved by storing the colliding mappings in a (singly-)linked list.



▶ Worst case: All keys are mapped to the same location. Then, access time is  $\Theta(n)$ .

# Average Case Analysis (1)

- ► Assumption (simple uniform hashing): Each key is equally likely to be hashed to any slot of the table, independent of where other keys are hashed.
- ▶ Let *n* be the number of keys.
- ▶ Let *m* be the number of slots.
- ▶ The load factor  $\alpha = n/m$  represents the average number of keys per slot.

# Average Case Analysis (2)

#### Theorem:

In a hash table in which collisions are resolved by chaining, an unsuccessful search takes average-case time  $\Theta(1+\alpha)$  under the assumption of simple uniform hashing.

#### Proof:

- ▶ Any key *k* not already stored in the table is equally likely to hash to any of the *m* slots.
- ▶ The expected time to search unsuccessfully for a key k is the expected time to search to the end of list T[h(k)].
- Expected length of the list is  $E[n_{h(k)}] = \alpha$ .
- ▶ Time for computing  $h(k) = O(1) \Rightarrow$  overall time  $\Theta(1 + \alpha)$ .

# Average Case Analysis (3)

- ▶ Runtime for unsuccessful search: The expected time for an unsuccessful search is  $\Theta(1+\alpha)$  including applying the hash function and accessing the slot and searching the list.
- What does this mean?
  - $m \sim n$ , i.e., if  $n = O(m) \Rightarrow \alpha = n/m = O(m)/m = O(1)$
  - ▶ Thus, search time is O(1)
- A successful search has the same asymptotic bound.

# Choosing a Hash Function (1)

- ▶ What makes a good hash function?
  - ► The goal for creating a hash function is to distribute the keys as uniformly as possible to the slots.
- Division method
  - ▶ Define hashing function  $h(k) = k \mod m$ .
  - ▶ Deficiency: Do not pick an m that has a small divisor d, as a prevalence of keys with the same modulo d can negatively effect uniformity.
  - **Example:** if m is a power of 2, the hash function only depends on a few bits: If k = 1011000111011010 and  $m = 2^6$ , then h(k) = 011010.

# Choosing a Hash Function (2)

- ► Division method (continue)
  - blueCommon choice: Pick m to be a prime not too close to a power of 2 or 10 and not otherwise prominently used in computing environments.
  - ▶ Example: n = 2000; we are OK with average 3 elements in our collision chain  $\Rightarrow m = 701$  (a prime number close to 2000/3),  $h(k) = k \mod 701$ .

# Choosing a Hash Function (3)

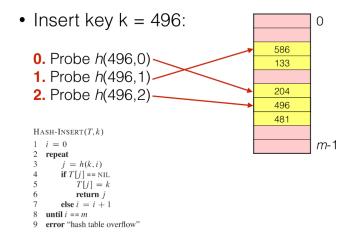
#### ► Multiplication method

- Assume all keys are integers,  $m = 2^r$ , and the computer uses w-bit words.
- ▶ Define hash function  $h(k) = (A \cdot k \mod 2^w) >> (w r)$ , where ">>" is the right bit-shift operator and A is an odd integer with  $2^{w-1} < A < 2^w$ .
- Note that these operations are faster than divisions.
- Example:  $m = 2^3 = 8$  and w = 7.

# Resolving Collisions by Open Addressing

- ▶ No additional storage is used.
- ▶ Only store one element per slot.
- Insertion probes the table systematically until an empty slot is found.
- ▶ The hash function depends on the key and the probe number, i.e.,  $h: U \times \{0, 1, ..., m-1\} \rightarrow \{0, 1, ..., m-1\}$ .
- ► The probe sequence < h(k,0), h(k,1), ..., h(k,m-1) > should be a permutation of  $\{0,1,...,m-1\}$ .

## Insert Example



## Search Example



- ▶ Search key k = 496
  - Search uses the same probe sequence, terminating successfully if it finds the key and unsuccessfully if it encounters an empty slot (or made it all the way through the list)
- What about delete?
  - ▶ Have a special node type: DELETED
  - lacktriangle Note though: search times no longer depend on load factor lpha
  - ► Chaining more commonly used when keys must also be deleted

# Probing Strategies (1)

#### Linear probing:

- ► Given an ordinary hash function h'(k), linear probing uses the hash function  $h(k, i) = (h'(k) + i) \mod m$ .
- ▶ This is a simple computation.
- However, it may suffer from primary clustering, where long runs of occupied slots build up and tend to get longer.
  - empty slot preceded by i full slots gets filled next with probability (i+1)/m

# Probing Strategies (2)

#### Quadratic probing:

- ▶ Quadratic probing uses the hash function  $h(k, i) = (h'(k) + c_1 \cdot i + c_2 \cdot i^2) \mod m$ .
- Offset by amount that depends on quadratic manner, works much better than linear probing
- But, it may still suffer from secondary clustering: If two keys have initially the same value, then they also have the same probe sequence
- ▶ In addition  $c_1$ ,  $c_2$ , and m need to be constrained to make full use of the hash table

# Probing Strategies (3)

#### Double hashing:

- ▶ Given two ordinary hash functions  $h_1(k)$  and  $h_2(k)$ , double hashing uses the hash function  $h(k, i) = (h_1(k) + i \cdot h_2(k))$  mod m.
- ▶ The initial probe goes to position  $T[h_1(k)]$ ; successive probe positions are offset by  $h_2(k) \rightarrow$  the initial probe position, the offset, or both, may vary
- ▶ This method generates excellent results, if  $h_2(k)$  is "relatively prime" to the hash-table size m,

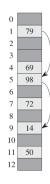
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# Probing Strategies (4)

#### Double hashing (continue):

- ▶ e.g., by making m a power of 2 and design h<sub>2</sub>(k) to only produce odd numbers.
- ▶ or let m be prime and design h₂ such that it always returns a positive integer less than m, e.g. let m' be slightly less than m:

$$h_1(k) = k \mod m$$
  
$$h_2(k) = 1 + (k \mod m')$$



$$h_1(k) = k \mod 13$$
  
 $h_2(k) = 1 + (k \mod 11)$   
 $-> k=14; h_1(k)=1, h_2(k)=4$ 

-> k=27; h<sub>1</sub>(k)=1, h<sub>2</sub>(k)=6

# Analysis of Open Addressing (1)

#### Theorem:

- Assume uniform hashing, i.e., each key is likely to have any one of the *m*! permutations as its probe sequence.
- Given an open-addressed hash table with load factor  $\alpha = n/m < 1$ .
- ▶ The expected number of probes in an unsuccessful search is, at most,  $1/(1-\alpha)$ .

# Analysis of Open Addressing (2)

#### Proof:

- At least, one probe is always necessary.
- ▶ With probability n/m, the first probe hits an occupied slot, i.e., a second probe is necessary.
- ▶ With probability (n-1)/(m-1), the second probe hits an occupied slot, i.e., a third probe is necessary.
- ▶ With probability (n-2)/(m-2), the third probe hits an occupied slot, i.e., a fourth probe is necessary.
- **...**

# Analysis of Open Addressing (3)

Given that 
$$\frac{n-i}{m-i} < \frac{n}{m} = \alpha$$
 for  $i = 1, 2, ..., n$ .

$$1 + \frac{n}{m} \left( 1 + \frac{n-1}{m-1} \left( 1 + \frac{n-2}{m-2} \left( \cdots \left( 1 + \frac{1}{m-n+1} \right) \cdots \right) \right) \right)$$

$$\leq 1 + \alpha \left( 1 + \alpha \left( 1 + \alpha \left( \cdots \left( 1 + \alpha \right) \cdots \right) \right) \right)$$

$$\leq 1 + \alpha + \alpha^2 + \alpha^3 + \cdots$$

$$= \sum_{i=0}^{\infty} \alpha^i$$

$$= \frac{1}{1-\alpha}.$$

# Analysis of Open Addressing (4)

- ► The successful search takes less number of probes pected number is  $1/\alpha \ln(1/(1-\alpha))$ .
- We conclude that if  $\alpha$  is constant, then accessing an open-addressed hash table takes constant time.
- ▶ For example, if the table is half full, the expected number of probes is 1/(1-0.5) = 2.
- ▶ Or, if the table is 90% full, the expected number of probes is 1/(1-0.9) = 10.

## Summary

- ▶ Dynamic sets with queries and modifying operations.
- Array: Random access, search in  $O(\lg n)$ , but modifying operations O(n).
- ▶ Stack: LIFO only. Operations in O(1).
- ▶ Queue: FIFO only. Operations in O(1).
- ▶ Linked list: Modifying operations in O(1), but search O(n).
- ▶ BST: All operations in O(h).
- ▶ Red-black trees: All operations in  $O(\lg n)$ .
- ▶ Heap: All operations in  $O(\lg n)$ .
- ▶ Hash tables: Operations in O(1), but additional storage space.