PS 161 Exam 4 Formulas

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$$s = r\theta$$
 $v = r\omega$ $a = r\alpha$ (1)

$$\omega = \omega_0 + \alpha t \tag{2}$$

$$\theta = \omega_{\rm av}t = \omega_0 t + \frac{\alpha}{2}t^2 \tag{3}$$

$$\omega^2 = \omega_0^2 + 2\alpha\theta \tag{4}$$

$$a_{\rm rad} = \frac{v^2}{r} = r\omega^2 \tag{5}$$

$$I = \sum_{i=1}^{N} m_i r_i^2 = \int r^2 dm = \int r^2 \lambda(r) dr$$
 (6)

$$I = I_{\rm cm} + md^2 \Longrightarrow I_2 = I_1 + m(d_2^2 - d_1^2)$$
 (7)

$$K_{\rm rot} = \frac{1}{2}I\omega^2 \tag{8}$$

$$W = \Delta K_{\rm lin} + \Delta K_{\rm rot} \tag{9}$$

$$U_{\rm grav} = mgy_{\rm cm} \tag{10}$$

$$\tau = \vec{r} \times \vec{F} = F\ell = F_{\perp}r = rF\sin\theta = I\alpha = \dot{L}$$
 (11)

$$x_{\rm cg} = x_{\rm cm}$$
 (usually) (12)

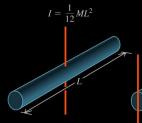
statics
$$\Longrightarrow \sum F = \sum \tau = 0$$
 (13)

rolling without slipping
$$\Longrightarrow v_{\rm cm} = r\omega \wedge a_{\rm cm} = r\alpha$$
 (14)

$$P = \tau \omega \tag{15}$$



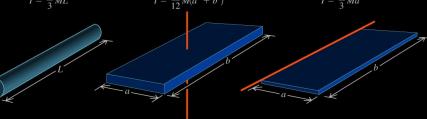
- (b) Slender rod, axis through one end
- (c) Rectangular plate, axis through center
- (d) Thin rectangular plate, axis along edge











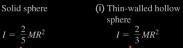
(e) Hollow cylinder



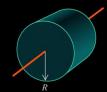


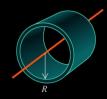


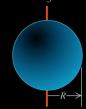


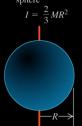












$$L = \vec{r} \times \vec{p} = mvr \sin \theta = mv\ell = I\omega \tag{16}$$

$$L_0 = L_1$$
 (assuming no external torque) (17)