

# Physics 1 & 2 for Engineers (PS 161) – Exam Formulas

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# 1 Exam 1 Formulas – Ch. 1-3

$$v = v_0 + at \quad (1)$$

$$x = \frac{v_0 + v}{t} \quad (2)$$

$$x = v_0 t + \frac{a}{2} t^2 \quad (3)$$

$$v^2 = v_0^2 + 2ax \quad (4)$$

$$\text{vector stuff: dot, cross, angle, magnitude} \quad (5)$$

## 2 Exam 2 Formulas – Ch. 4-5

$$a_c = \frac{v^2}{r} \quad (6)$$

$$f_s = \mu_s N \quad (7)$$

$$f_k = \mu_k N \quad (8)$$

$$a_{\parallel} = g(\sin \theta - \mu_k \cos \theta) \quad \text{box sliding down slope} \quad (9)$$

$$F = ma \quad (10)$$

### 3 Exam 3 Formulas – Ch. 6-8

$$W = \int_{x_1}^{x_2} \vec{F} \cdot d\vec{s} = W_{\text{cons}} + W_{\text{nc}} = \Delta K = \left( \frac{1}{2}mv^2 \text{ or } \frac{p^2}{2m} \right) \Big|_{x_1}^{x_2} \quad (11)$$

$$W_F^{\text{cons}} = -\Delta U_F \quad (12)$$

$$U_{\text{grav}} = mgy \quad U_{\text{el}} = \frac{1}{2}kx^2 \quad (13)$$

$$J = \int_{t_1}^{t_2} F(t) dt = \Delta p = mv \Big|_{t_1}^{t_2} = F_{\text{av}} \Delta t \quad (14)$$

$$F = -\vec{\nabla}U = \dot{m}\vec{v} \quad (15)$$

$$P_{\text{av}} = \frac{W}{\Delta t} \quad P = \dot{W} = \vec{F} \cdot \vec{v} \quad (16)$$

$$\vec{p} = m\vec{v} \quad (17)$$

$$x_{\text{cm}} = \frac{\sum mx}{\sum m} \quad \vec{v}_{\text{cm}} = \frac{\sum \vec{p}}{\sum m} \quad (18)$$

$$\Delta W = -\Delta U \quad (19)$$

$$v_{Af}, v_{Bf} = \frac{p_{Ai} + 2p_{Bi} - m_B v_{Ai}}{m_A + m_B}, \frac{p_{Bi} + 2p_{Ai} - m_A v_{Bi}}{m_A + m_B} \quad (\text{elastic}) \quad (20)$$

## 4 Exam 4 Formulas – Ch. 9-11

$$s = r\theta \quad v = r\omega \quad a = r\alpha \quad (21)$$

$$\omega = \omega_0 + \alpha t \quad (22)$$

$$\theta = \omega_{\text{av}} t = \omega_0 t + \frac{\alpha}{2} t^2 \quad (23)$$

$$\omega^2 = \omega_0^2 + 2\alpha\theta \quad (24)$$

$$a_{\text{rad}} = \frac{v^2}{r} = r\omega^2 \quad (25)$$

$$I = \sum_{i=1}^N m_i r_i^2 = \int r^2 dm = \int r^2 \lambda(r) dr \quad (26)$$

$$I = I_{\text{cm}} + md^2 \implies I_2 = I_1 + m(d_2^2 - d_1^2) \quad (27)$$

$$K_{\text{rot}} = \frac{1}{2} I \omega^2 \quad (28)$$

$$W = \Delta K_{\text{lin}} + \Delta K_{\text{rot}} \quad (29)$$

$$U_{\text{grav}} = mgy_{\text{cm}} \quad (30)$$

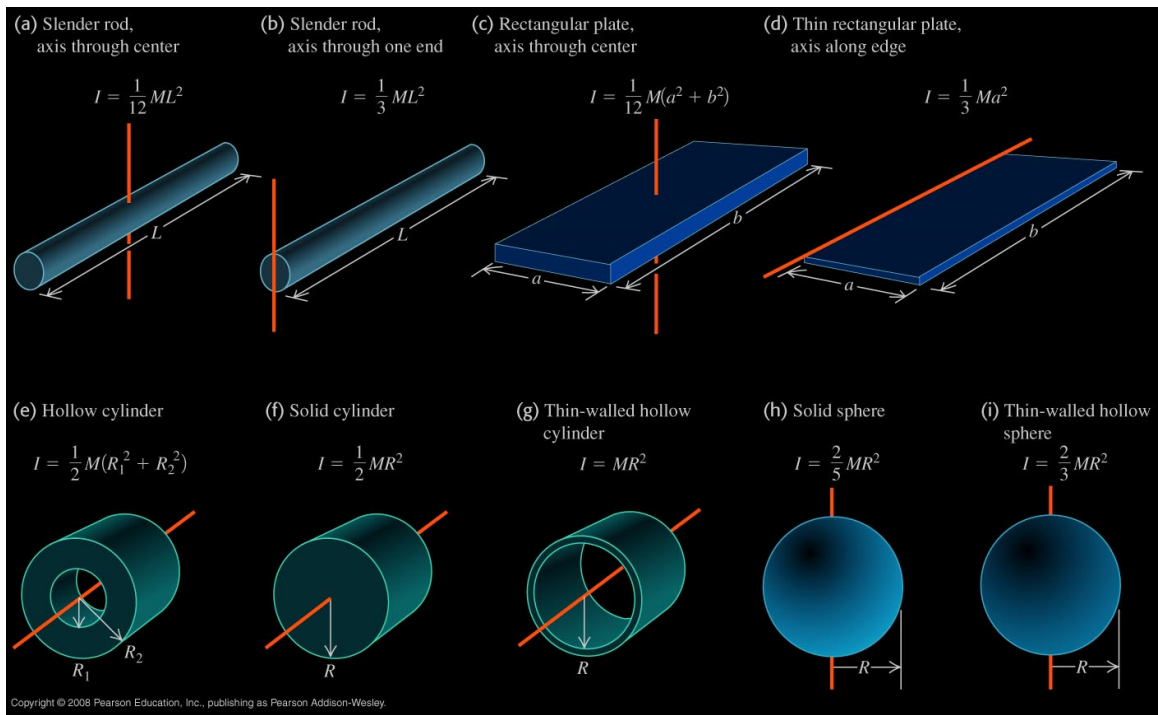
$$\tau = \vec{r} \times \vec{F} = F\ell = F_{\perp} r = rF \sin \theta = I\alpha = \dot{L} \quad (31)$$

$$x_{\text{cg}} = x_{\text{cm}} \quad (\text{usually}) \quad (32)$$

$$\text{statics} \implies \sum F = \sum \tau = 0 \quad (33)$$

$$\text{rolling without slipping} \implies v_{\text{cm}} = r\omega \quad \wedge \quad a_{\text{cm}} = r\alpha \quad (34)$$

$$P = \tau\omega \quad (35)$$



$$L = \vec{r} \times \vec{p} = mvr \sin \theta = mv\ell = I\omega \quad (36)$$

$$L_0 = L_1 \quad (\text{assuming no external torque}) \quad (37)$$

## 5 Final Exam Formulas – Ch. 12-14

$$Y = \frac{\text{stress}}{\text{strain}} = \frac{F/A}{\Delta L/L_0} = \frac{FL_0}{A\Delta L} \quad [\text{Pa}] \quad (38)$$

$$\lambda = \frac{m}{L} \quad \sigma = \frac{m}{A} \quad \rho = \frac{m}{V} \quad (39)$$

$$p = \rho gh = \frac{F_1}{A_1} = \frac{F_2}{A_2} \quad [\text{Pa}] \quad (40)$$

$$F_{\text{pressure}} = pA \quad (41)$$

$$F_{\text{buoyant}} = \rho gV \quad (42)$$

$$R = Av \quad (\text{flow rate}) \quad (43)$$

$$\rho_1 R_1 = \rho_2 R_2 \quad (\text{mass flux}) \quad (44)$$

$$\rho_1 = \rho_2 \quad (\text{incompressible}) \quad (45)$$

$$ME = p + \frac{1}{2}\rho v^2 + \rho gy \quad (46)$$

$$U_g = -\frac{GMm}{r} \quad (47)$$

$$F_g = -\frac{GMm}{r^2} \quad (48)$$

$$v_{\text{orbit}} = \sqrt{\frac{GM}{R}} \quad (49)$$

$$v_{\text{escape}} = v_{\text{orbit}}\sqrt{2} \quad (50)$$

$$T = \frac{2\pi r}{v} = \frac{2\pi r^{1.5}}{\sqrt{GM}} \quad (51)$$

$$R_S = \frac{2GM}{c^2} \quad (52)$$

Simple Harmonic Motion (SHM):

$$x(t) = A \cos(\omega t + \phi) \ni \omega^2 = \frac{k}{m} \quad (53)$$

$$\omega = 2\pi f \quad (54)$$

$$E = \frac{mv^2 + kx^2}{2} \quad (55)$$

$$v = \pm \omega \sqrt{A^2 - x^2} \quad (56)$$

$$\theta(t) = \theta_0 \cos(\omega t + \phi) \quad (57)$$

$$\text{Angular SHM: } \omega^2 = \frac{\kappa}{I} \ni \kappa = \text{torsion constant} \quad (58)$$

$$\text{Small } \theta \text{ Simple Pendulum: } \omega^2 = \frac{g}{L} \quad (59)$$

$$\text{Physical Pendulum: } \omega^2 = \frac{mgd}{I} \quad (60)$$