

- Rate1
 - HOME
 - latitude
 - longitude
 - alt
 - BATTERY_STATUS
 - voltage
 - current
-
- Rate2
 - GLOBAL_POSITION_INT
 - latitude
 - longitude
 - relative_alt
 - LOCAL_POSITION_NED
 - vx
 - vy
 - GPS_RAW_INT
 - fix_type
 - satellites_visible
 - ATTITUDE
 - roll
 - pitch
 - VFR_HUD
 - airspeed
 - heading
 - gndspeed
 - vspeed
 - throttle %
-
- Rate3
 - RC_CHANNELS
 - chancount
 - chan1_raw, chan2_raw... chan18_raw, rssi
 - SERVO_OUTPUT_RAW
 - port
 - servo1_raw, servo2_raw... servo16_raw
- Rate4
 - MAV
 - armed
 - base_mode
 - flight_mode
 - mav_type
 - HEARTBEAT
 - system_status
 - autopilot
 - base_mode
 - custom_mode

