

CDL Presents Basic Electronics

Week3

1

Analog Integrated Circuits

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Questions from Last Week

2

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Some Common Analog Integrated Circuits

- Operational Amplifier (OP-AMP)
- Voltage Regulators
- NE555 timer
- Audio Amplifier: LM386
- RF Amplifiers
- Motor Controllers
- Direct Digital Synthesis

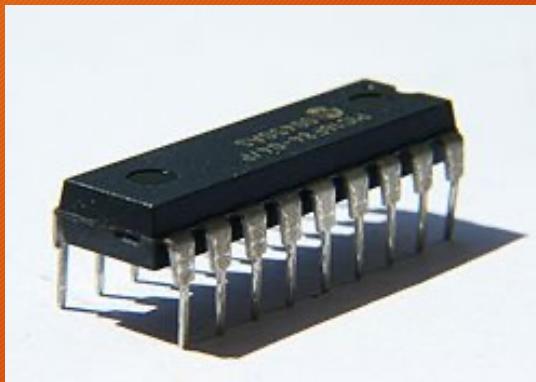
Analog Integrated Circuits (ICs)

- When a circuit design become very popular, they are often designed into a integrated circuit (IC)
 - By providing an IC with:
 - a data sheet, and
 - a reference design
 - The design time for circuits is shortened significantly
- Today, these chips can be found in a variety of packages
- Old school: Dual Inline Chip, with pins to go into holes
 - Surface mount to go on boards with no holes
- Most of the ICs in this talk can be purchased in multiple packages
 - Some can now only be found in surface mount
 - To get some with pins requires old stock or flea markets

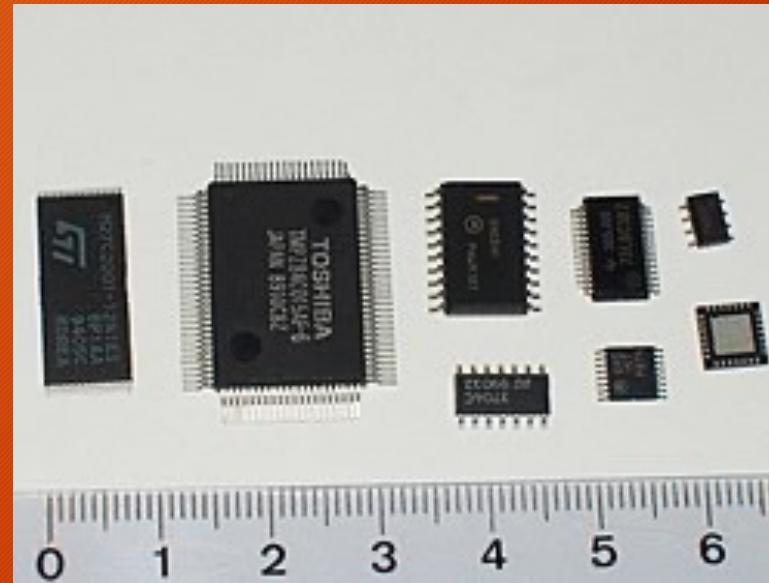
Types of packages

Dual in line

4
8
10
16
18
24
28 pins



Surface Mount, multiple sizes



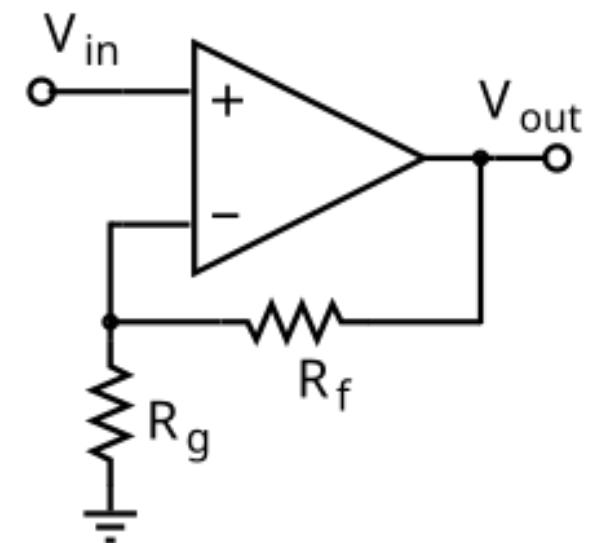
Some IC with only 3 leads,
(typically voltage regulators)
can be found in transistor
size packages

Operational Amplifier (Op Amps)

- While vacuum tube op amps have been around a long time, they were large sub-assemblies and often each designer had their own custom design
- Solid-state op-amps, including the μ A702 from Fairchild in 1963 and the μ A741 in 1968, provided an op amp in one package
- An operational amplifier (often op amp or opamp) is a
 - DC-coupled electronic voltage amplifier with a differential input,
 - A (usually) single-ended output, and
 - Extremely high gain.
- By using negative feedback, an op amp circuit's characteristics
 - (e.g. its gain, input and output impedance, bandwidth, and functionality)
- Can be determined by external components and have little dependence on temperature coefficients or engineering tolerance in the op amp itself.
- This flexibility has made the op amp a popular building block in analog circuits.

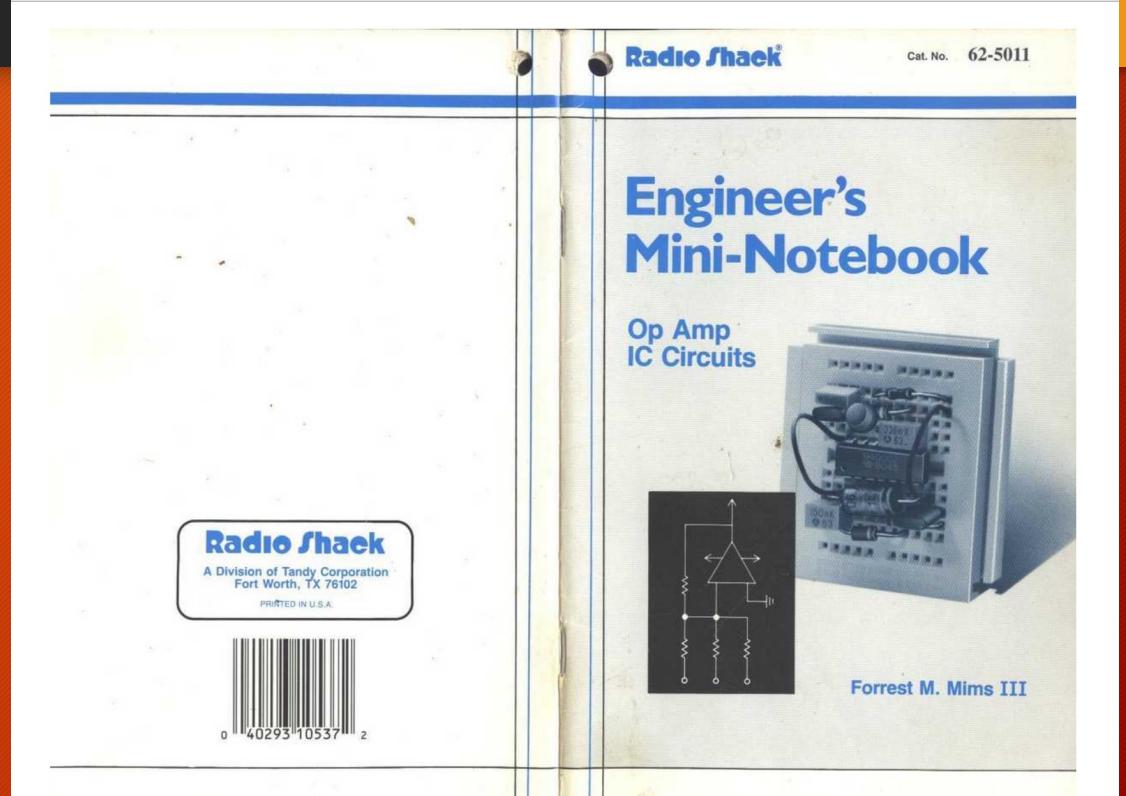
Simple OP AMP circuit

- Early OP Amps needed a set of equal positive and negative supply voltages
- Some OP Amps can operate on a single power supply
- The gain of the circuit is R_f/R_g
- Op Amps are used for audio and have a maximum frequency in the low MHz Range



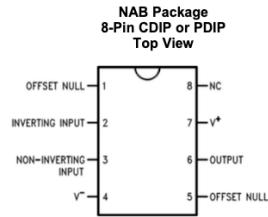
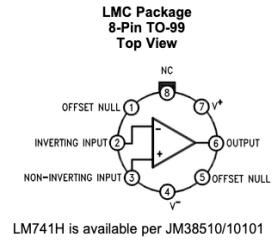
OP Amp Cookbook by Forrest Mims

- Out of print but can be found on web in pdf format
- Nuts and Volts Magazine also has a series on the op amp
- <https://www.nutsvolts.com/magazine/article/op-amp-cookbook>



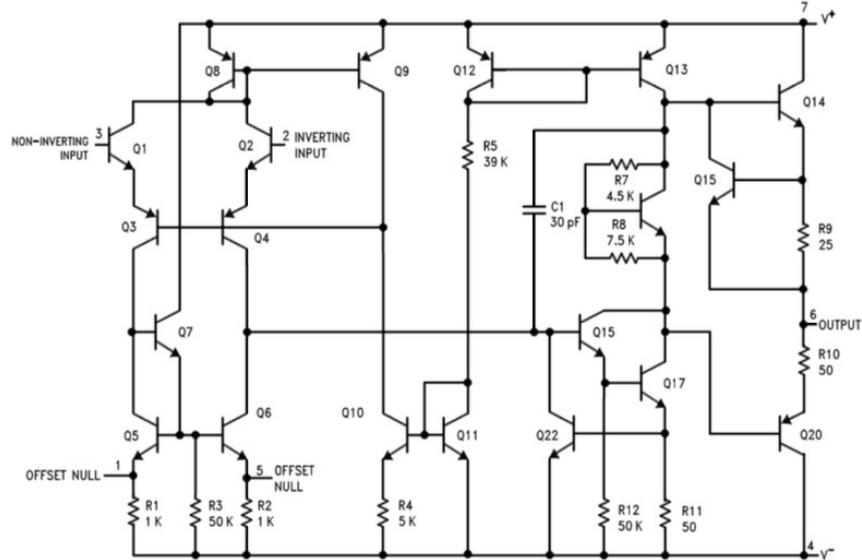
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LM741 Op AMP



PIN	NO.	I/O	DESCRIPTION
NAME	NO.	I/O	DESCRIPTION
INVERTING INPUT	2	I	Inverting signal input
NC	8	N/A	No Connect, should be left floating
NONINVERTING INPUT	3	I	Noninverting signal input
OFFSET NULL	1, 5	I	Offset null pin used to eliminate the offset voltage and balance the input voltages.
OUTPUT	6	O	Amplified signal output
V+	7	I	Positive supply voltage
V-	4	I	Negative supply voltage

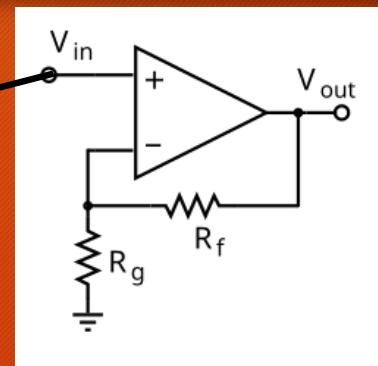
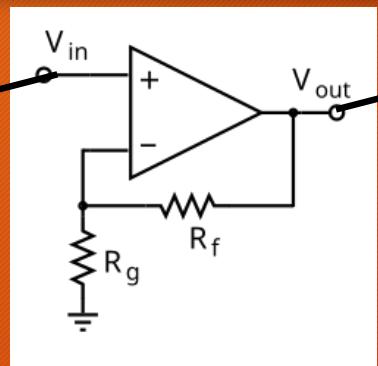
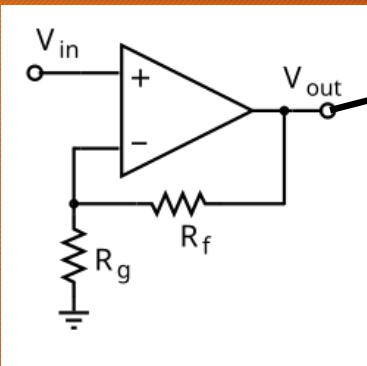
7.2 Functional Block Diagram



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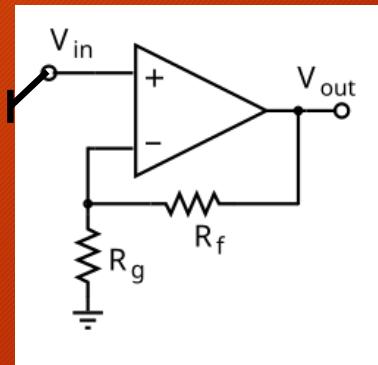
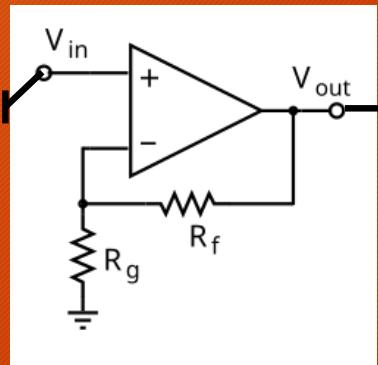
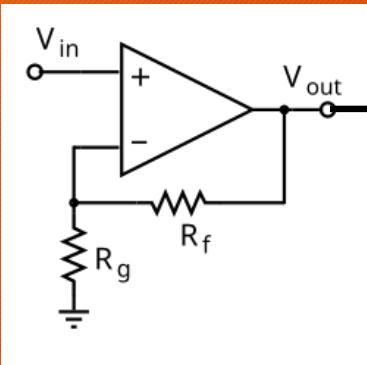
Multi-stage Design

10



DC coupled

For Illustration Not for Design



AC coupled

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Input Offset Adjustment

11

- We use two identical power supply voltages (e.g., +12 v, -12 v)
- When the two inputs have identical voltages on them
 - The output voltage should be 0 volts
- If it is not 0 volts, the voltage offset is amplified by the next stage, and grows through a multi-stage amplifier design
- We use the offset inputs to adjust the output to be 0 volts when the two inputs are identical
- If we capacitive couple stages, the offset may not affect the design

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Typical Data Sheet

Note:
The 741 requires
two power supplies

12

6.5 Electrical Characteristics, LM741⁽¹⁾

PARAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNIT
Input offset voltage	$R_S \leq 10 \text{ k}\Omega$	$T_A = 25^\circ\text{C}$ $T_{A\text{MIN}} \leq T_A \leq T_{A\text{MAX}}$		1	5	mV
					6	mV
Input offset voltage adjustment range	$T_A = 25^\circ\text{C}, V_S = \pm 20 \text{ V}$			± 15		mV
Input offset current	$T_A = 25^\circ\text{C}$ $T_{A\text{MIN}} \leq T_A \leq T_{A\text{MAX}}$			20	200	nA
				85	500	
Input bias current	$T_A = 25^\circ\text{C}$ $T_{A\text{MIN}} \leq T_A \leq T_{A\text{MAX}}$			80	500	nA
					1.5	μA
Input resistance	$T_A = 25^\circ\text{C}, V_S = \pm 20 \text{ V}$		0.3	2		$\text{M}\Omega$
Input voltage range	$T_{A\text{MIN}} \leq T_A \leq T_{A\text{MAX}}$		± 12	± 13		V
Large signal voltage gain	$V_S = \pm 15 \text{ V}, V_O = \pm 10 \text{ V}, R_L \geq 2 \text{ k}\Omega$	$T_A = 25^\circ\text{C}$ $T_{A\text{MIN}} \leq T_A \leq T_{A\text{MAX}}$	50	200		V/mV
			25			
Output voltage swing	$V_S = \pm 15 \text{ V}$	$R_L \geq 10 \text{ k}\Omega$ $R_L \geq 2 \text{ k}\Omega$	± 12	± 14		V
			± 10	± 13		
Output short circuit current	$T_A = 25^\circ\text{C}$			25		mA
Common-mode rejection ratio	$R_S \leq 10 \Omega, V_{CM} = \pm 12 \text{ V}, T_{A\text{MIN}} \leq T_A \leq T_{A\text{MAX}}$		80	95		dB
Supply voltage rejection ratio	$V_S = \pm 20 \text{ V} \text{ to } V_S = \pm 5 \text{ V}, R_S \leq 10 \Omega, T_{A\text{MIN}} \leq T_A \leq T_{A\text{MAX}}$		86	96		dB
Transient response	Rise time Overshoot	$T_A = 25^\circ\text{C}, \text{unity gain}$		0.3		μs
				5%		
Slew rate	$T_A = 25^\circ\text{C}, \text{unity gain}$			0.5		$\text{V}/\mu\text{s}$
Supply current	$T_A = 25^\circ\text{C}$			1.7	2.8	mA
Power consumption	$V_S = \pm 15 \text{ V}$	$T_A = 25^\circ\text{C}$ $T_A = T_{A\text{MIN}}$ $T_A = T_{A\text{MAX}}$	50	85		
			60	100		mW
			45	75		

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https://en.wikipedia.org/wiki/Operational_amplifier

Some Typical Op Amps

13

- LM741: A popular and widely used general-purpose op-amp, known for its low cost and availability. It's a good choice for beginner projects, but its performance specs are lower than newer models.
- LM324: A quad (four) op-amp with a low-power design and a wide gain-bandwidth product, making it suitable for various applications.
- TL072: A dual op-amp with JFET inputs, offering low noise and good performance in general-purpose applications.
- OP07: An ultra-low offset voltage op-amp, making it suitable for applications requiring high precision, such as instrumentation.
- LMH6629: A high-speed, ultra-low-noise voltage feedback operational amplifier, often used in audio applications.
- RC4558: A dual general-purpose op-amp with a relatively wide gain-bandwidth product.
- NE5532: A low-noise, high-speed audio op-amp suitable for applications requiring high audio fidelity.

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Voltage Regulators

14

- These are three terminal devices that when inputting a DC voltage will lower it to a known fixed value
- The input voltage must be several volts higher than the desired output
- They are available in different voltages and for positive and negative voltages
- They can handle up to several amps of power
- Typical parts are:
 - Positive voltages: 7805, 7809, 7810, 7815, 7824
 - Negative voltages: 7905, 7809, 7912, 7915, 7924
- There are some models that can adjusted in voltage
- These regulators come in typical transistor packages



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Partial Data Sheet

15

Line
Regulation
is often
called
dropout
voltage

Electrical Characteristics LM78XXC (Note 2)

$0^{\circ}\text{C} \leq T_j \leq 125^{\circ}\text{C}$ unless otherwise noted.

Output Voltage			5V			12V			15V			Units	
Input Voltage (unless otherwise noted)			10V			19V			23V				
Symbol	Parameter	Conditions	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max		
V_O	Output Voltage	$T_j = 25^{\circ}\text{C}, 5 \text{ mA} \leq I_O \leq 1\text{A}$	4.8	5	5.2	11.5	12	12.5	14.4	15	15.6	V	
		$P_D \leq 15\text{W}, 5 \text{ mA} \leq I_O \leq 1\text{A}$	4.75	5.25		11.4		12.6	14.25		15.75	V	
		$V_{MIN} \leq V_{IN} \leq V_{MAX}$		(7.5 $\leq V_{IN} \leq 20$)			(14.5 $\leq V_{IN} \leq 27$)			(17.5 $\leq V_{IN} \leq 30$)		V	
ΔV_O	Line Regulation	$I_O = 500 \text{ mA}$	$T_j = 25^{\circ}\text{C}$	3	50		4	120		4	150	mV	
			ΔV_{IN}			(7 $\leq V_{IN} \leq 25$)		(14.5 $\leq V_{IN} \leq 30$)		(17.5 $\leq V_{IN} \leq 30$)		V	
			$0^{\circ}\text{C} \leq T_j \leq +125^{\circ}\text{C}$	50			120		150			mV	
ΔV_O	Load Regulation	$I_O \leq 1\text{A}$	$T_j = 25^{\circ}\text{C}$		50		120		150			mV	
			ΔV_{IN}		(7.5 $\leq V_{IN} \leq 20$)		(14.6 $\leq V_{IN} \leq 27$)		(17.7 $\leq V_{IN} \leq 30$)			V	
			$0^{\circ}\text{C} \leq T_j \leq +125^{\circ}\text{C}$	25			60		75			mV	
ΔV_O	Load Regulation		ΔV_{IN}		(8 $\leq V_{IN} \leq 12$)		(16 $\leq V_{IN} \leq 22$)		(20 $\leq V_{IN} \leq 26$)			V	
			$T_j = 25^{\circ}\text{C}$	5 mA $\leq I_O \leq 1.5\text{A}$	10	50	12	120	12	150		mV	
				250 mA $\leq I_O \leq 750 \text{ mA}$		25		60		75		mV	
ΔV_O	Load Regulation			$5 \text{ mA} \leq I_O \leq 1\text{A}, 0^{\circ}\text{C} \leq T_j \leq +125^{\circ}\text{C}$	50		120		150			mV	

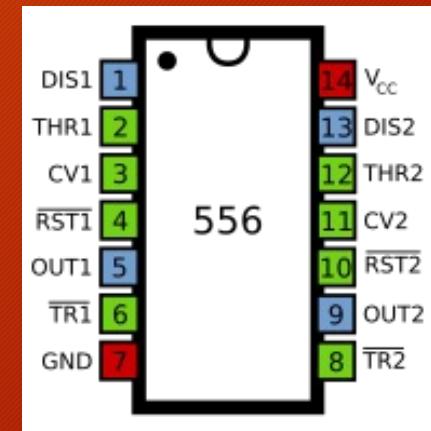
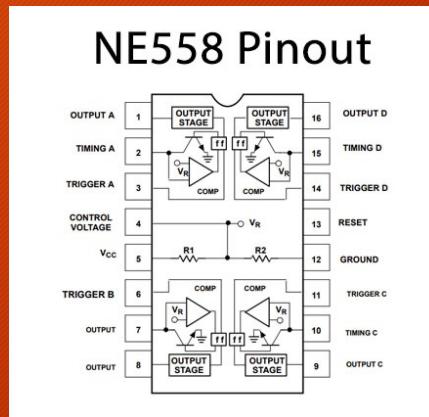
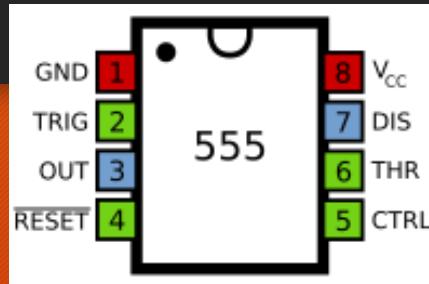
The input voltage
needs to be about
2-3 volts higher
than the
output voltage

There are some
"low dropout voltage"
devices

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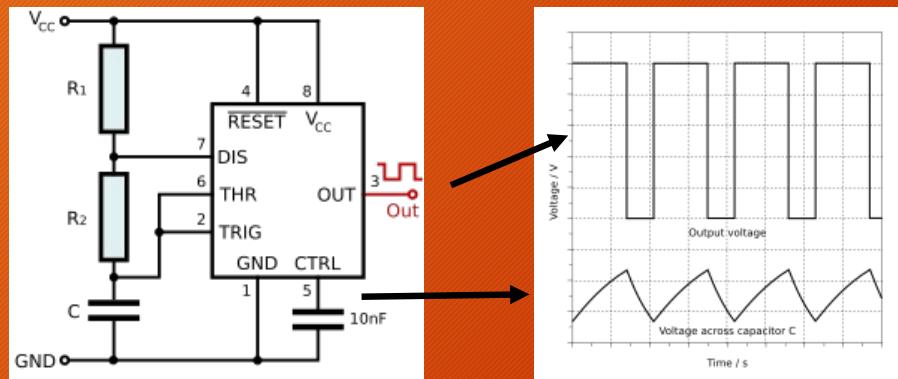
NE555 Timer

- The NE555 Timer is probably the most used analog IC in the world
- Articles have been written for years about it and people are always inventing new ways to use it.
- It is cheap and versatile
- It is available in 1, 2 and 4 chips in the same package



NE555 in Astable Mode

- By selecting which pin to provide the output, the astable mode provides
- A continuous pulse train, or
- A saw tooth waveform

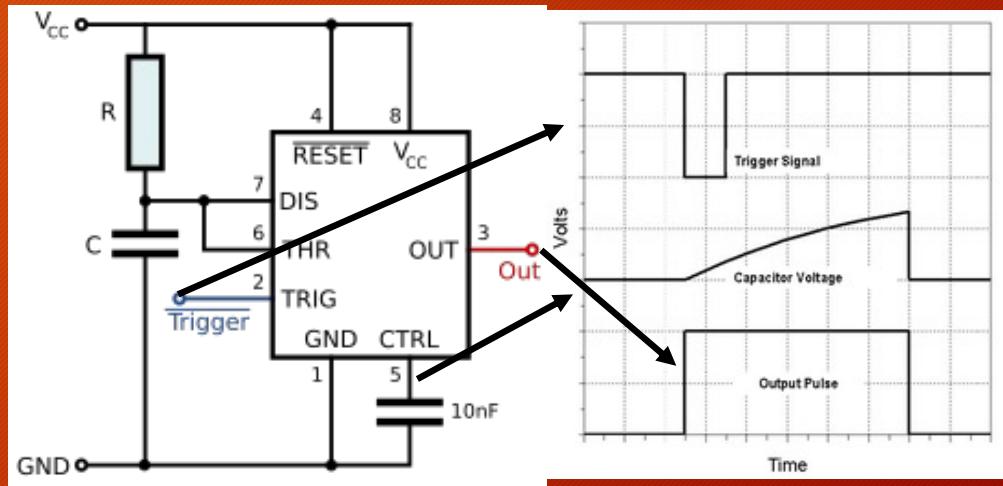


Astable mode examples with common values

Frequency	C	R ₁	R ₂	Duty cycle
0.1 Hz (+0.048%)	100 μ F	8.2 k Ω	68 k Ω	52.8%
1 Hz (+0.048%)	10 μ F	8.2 k Ω	68 k Ω	52.8%
10 Hz (+0.048%)	1 μ F	8.2 k Ω	68 k Ω	52.8%
100 Hz (+0.048%)	100 nF	8.2 k Ω	68 k Ω	52.8%
1 kHz (+0.048%)	10 nF	8.2 k Ω	68 k Ω	52.8%
10 kHz (+0.048%)	1 nF	8.2 k Ω	68 k Ω	52.8%
100 kHz (+0.048%)	100 pF	8.2 k Ω	68 k Ω	52.8%

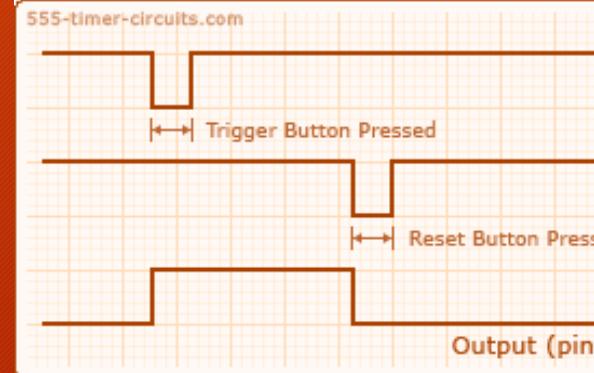
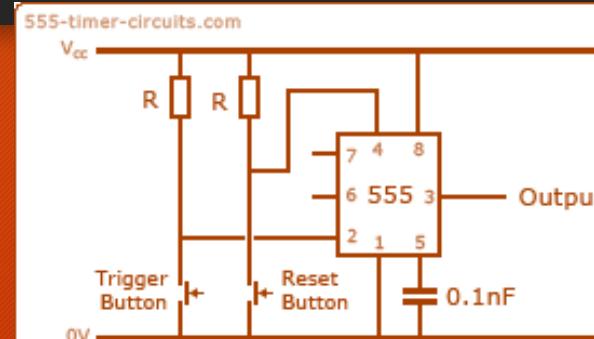
NE555 in Mono Stable Mode

- Monostable mode produces an output pulse when the trigger signal drops below $1/3$ VCC.
- An RC circuit sets the output pulse's duration as the time t in seconds it takes to charge C to $2/3$ VCC
- $t = \ln(3) \cdot R \cdot C$, Where
 - R is the resistance in ohms,
 - C is the capacitance in farads,
 - $\ln(3)$ is the natural log of 3, i.e., log to base e, not base 10
- The output pulse duration can be lengthened or shortened as desired by adjusting the values of R and C.
- Subsequent triggering before the end of this timing interval won't affect the output pulse



Bistable Mode (or Schmitt Trigger)

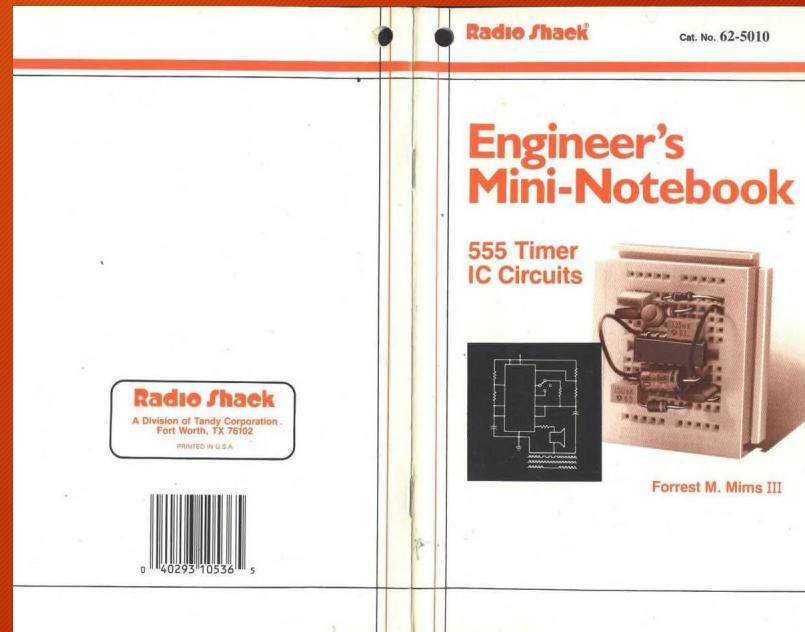
- A Bistable Mode or what is sometimes called a Schmitt Trigger, has two stable states, high and low.
- Taking the Trigger input low makes the output of the circuit go into the high state.
- Taking the Reset input low makes the output of the circuit go into the low state.



Other Uses for NE555

20

- There are many other circuits that have been adapted using the NE555
- The most popular is in a book by Forrest Mims
- It is out of print but can be found on the Internet in pdf form
- Another source is
<https://www.555-timer-circuits.com/>



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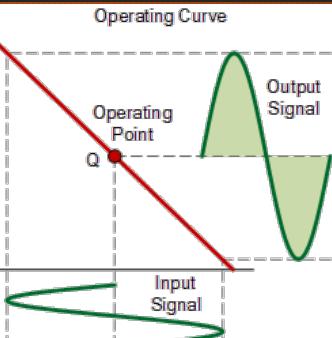
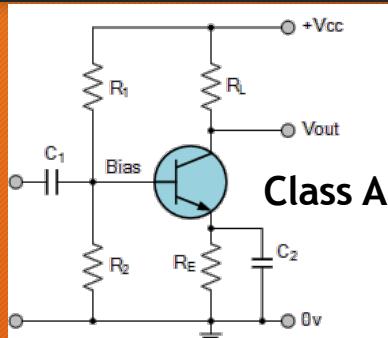
Audio Amplifiers

21

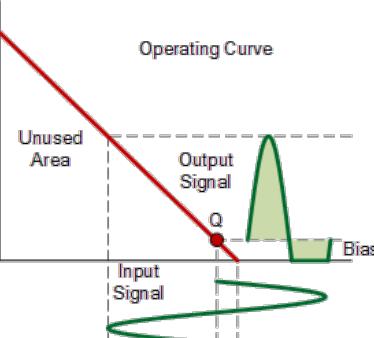
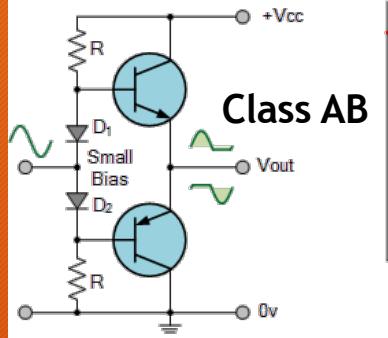
- Audio Amplifiers are characterized by the class of the amplifier.
- Amplifier Classes relate back to vacuum tubes but are appropriate for transistor amplifiers also
- Class A is the most common and has the best fidelity but the lowest efficiency
- Class B has higher efficiency but needs to have two transistors in a push-pull configuration to achieve good fidelity
- Class AB tries to give better fidelity and better efficiency at the same time
- Class C is used for RF Amplifiers and has the best efficiency but high distortion
 - Not acceptable for audio applications
 - In RF applications, filters are necessary to remove distortion products that can interfere with other radio systems

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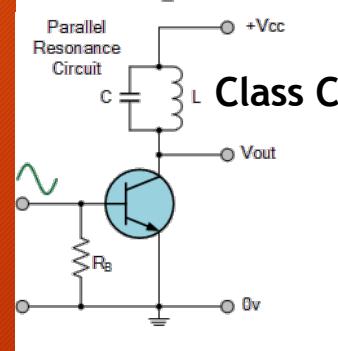
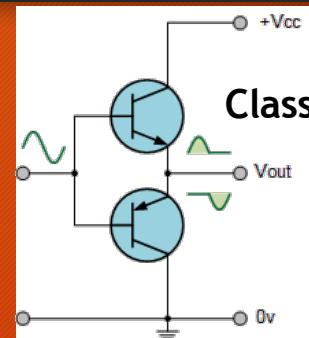
Basic Diagram of Amplifier Classes



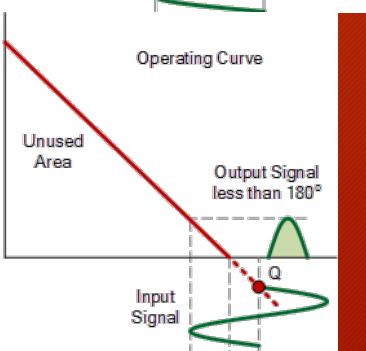
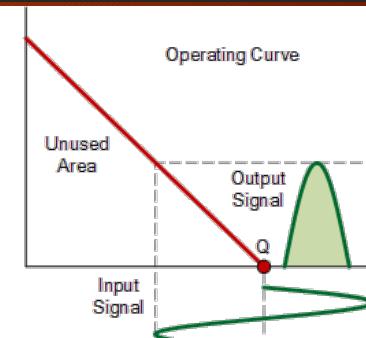
Class A



Class AB



Class B



Operating Curve

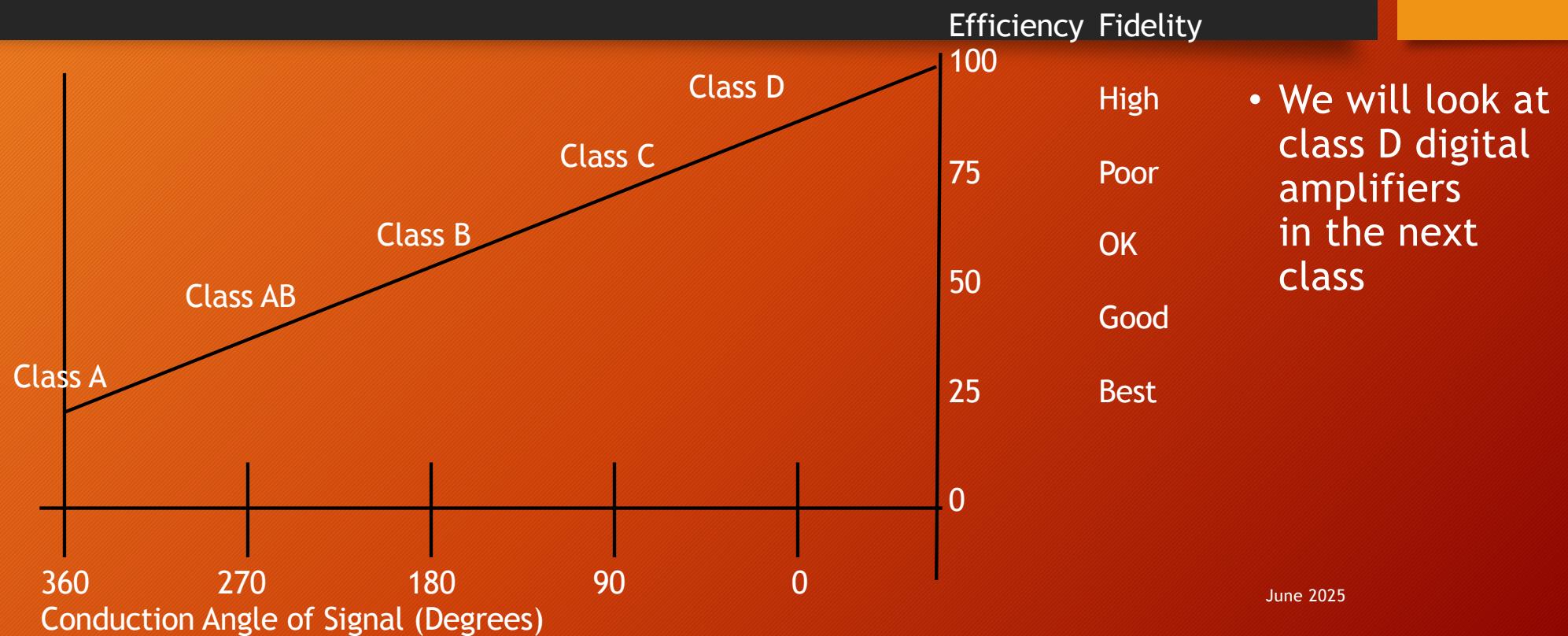
As the configuration evolves from Class A to Class C, the output signal gets more distorted

But the efficiency gets better

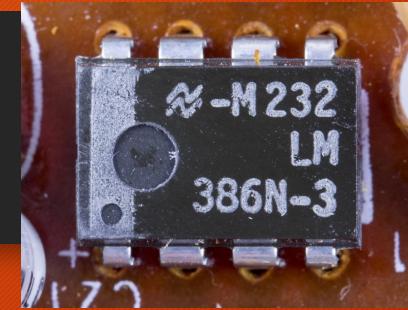
https://en.wikipedia.org/wiki/Power_amplifier_classes

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Efficiency of Amplifier Classes

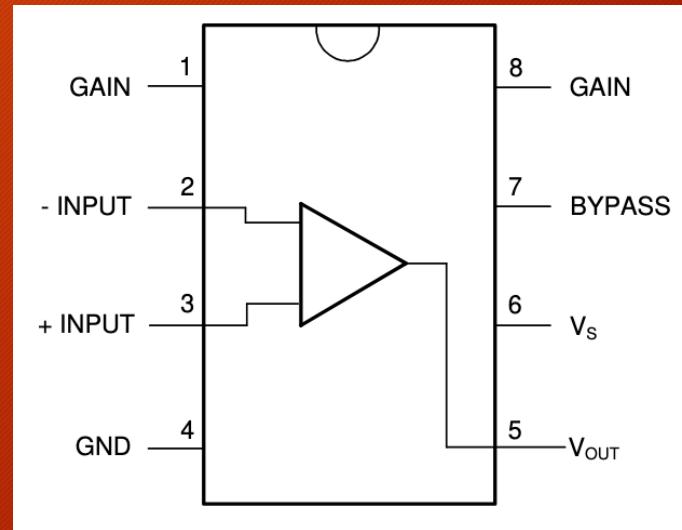


Audio Amplifier: LM386



24

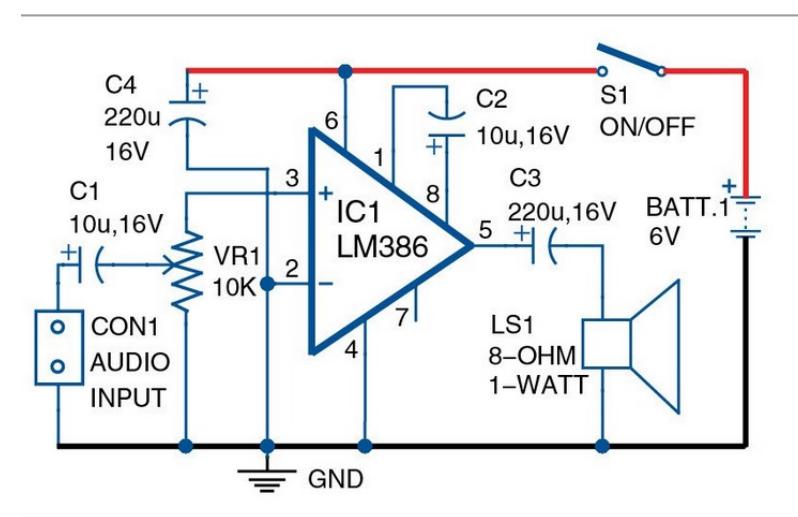
- A common class A audio amplifier is the LM386
- Its output power is about 0.25-0.7 watts of audio
- The LM386 is popular, cheap and readily available
- It is used in many projects
- In the next class, we will learn about class D amplifiers that deliver more power and are also cheap and readily available



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Typical LM386 Circuit Diagram

Part number	Supply voltage, V		Min Speaker impedance, Ω	Output power, mW	
	Min.	Max.		Min.	Typical
LM386N-1	4	12	4	250	325 @ Vs=6V, R _L =8Ω
LM386N-3	4	12	4	500	700 @ Vs=9V, R _L =8Ω
LM386N-4	5	18	4	700	1000 @ Vs=16V, R _L =32Ω



RF Amplifiers

26

- Any circuits that are designed for radio frequencies (RF) are difficult to design, build and debug.
- RF circuit design is often called a "Black Art" since it needs special skills
- Several companies make special amplifiers that are designed for RF but they need inductor and capacitors to make them work
- They also may need special Printed Circuit Board designs
- <https://www.kitsandparts.com/index.php> provides circuit boards, kits and parts for various hobbyist RF projects
- There are alternatives

Mini-Circuit Labs RF amplifiers

27

- A Brooklyn, NY company makes a wide range of RF amplifiers that are used in circuit design, prototyping, and test set ups
- They make transistors, amplifiers, lab equipment, etc.
- For a full list of their equipment see:
<https://www.minicircuits.com/>
- Note that some of the parts are expensive but very functional



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Motor Controllers

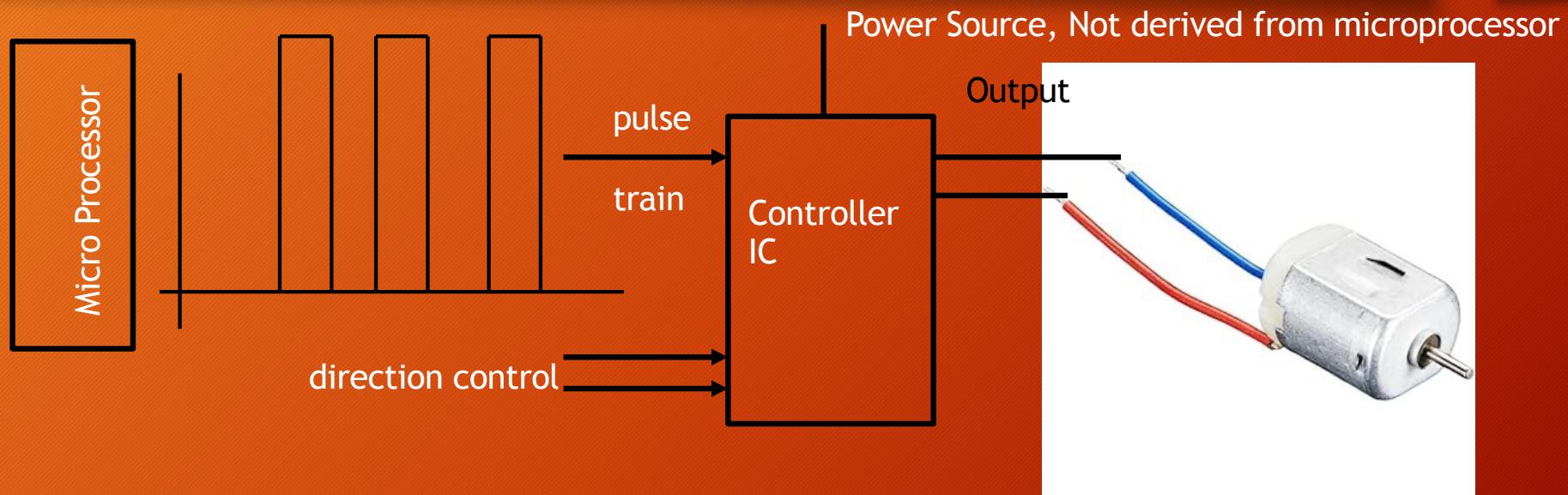
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- Typical microcontrollers, Pi, Arduino, Feather, Pico, etc. can only deliver milliamps from their output ports
- Most motors require power in the range of amps to operate
- A motor controller IC will take the milliamp power from the microcontroller and control amps of power
- It requires a different power source than the one the runs the microcontroller.
- The motor controller IC does the following:
 - Change the speed of DC motors by pulsing the DC power on and off
 - Change direction of the motor by reversing the positive and negative leads to the motor
- Adafruit and others make shields/hats/etc. with motor controller ICs to use with popular microcontrollers

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Interfacing motor controller and motor

29

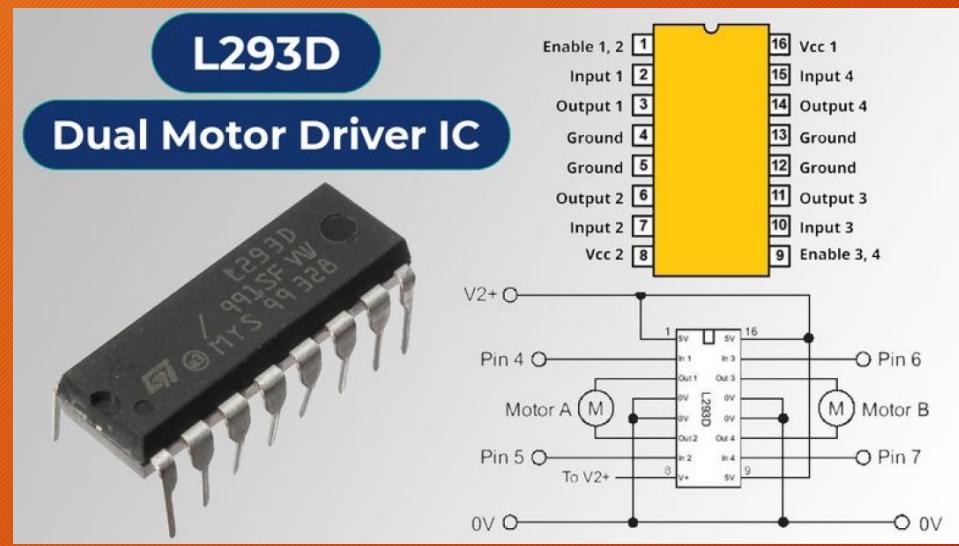


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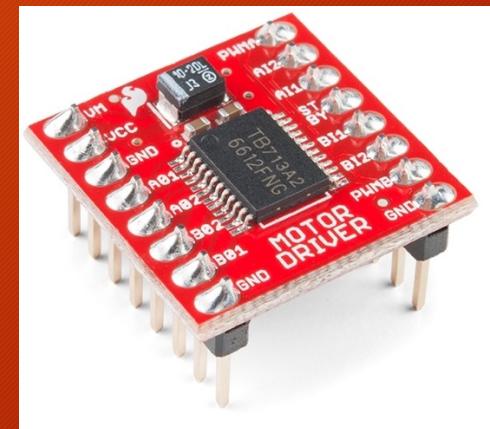
Two common motor controllers

30

- The L293D and the TB6612FNG are two popular motor controller ICs
- The both support two DC motors



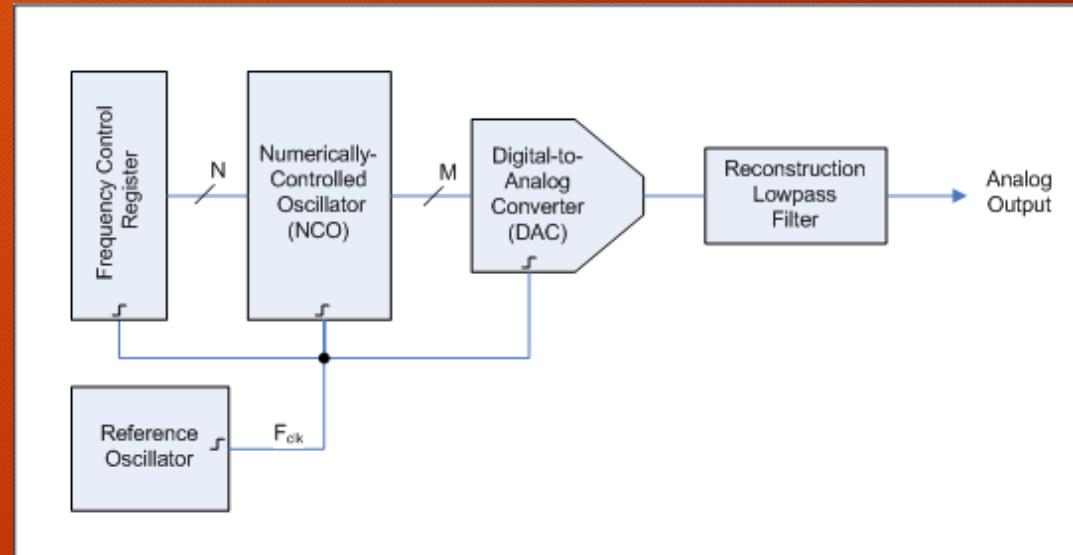
Sparkfun TB6612 motor driver board



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Direct Digital Synthesis

- A quasi analog circuit is a Direct Digital Synthesizer (DDS)
- It is controlled by a microprocessor and delivers a analog sine wave signal at a given frequency
- There are two popular DDS ICs
- Each requires a driver library for the microcontroller



https://en.wikipedia.org/wiki/Direct_digital_synthesis

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Ad9850 DDS

vs

Si5351 DDS

32

- Single Frequency Output
- Range 0-1/2 crystal frequency
- Practical limit is 0- 30% of crystal frequency
- Max Frequency is around 40 MHz
- Cost about \$22 for module

- 3 independent Output Frequencies
- Range up to several hundred Megahertz
- Two of the outputs can be programmed to be 90 degrees out of phase
- Useful for SDR RX and TX
- Cost about \$8 for module

Other Analog Integrated Circuits

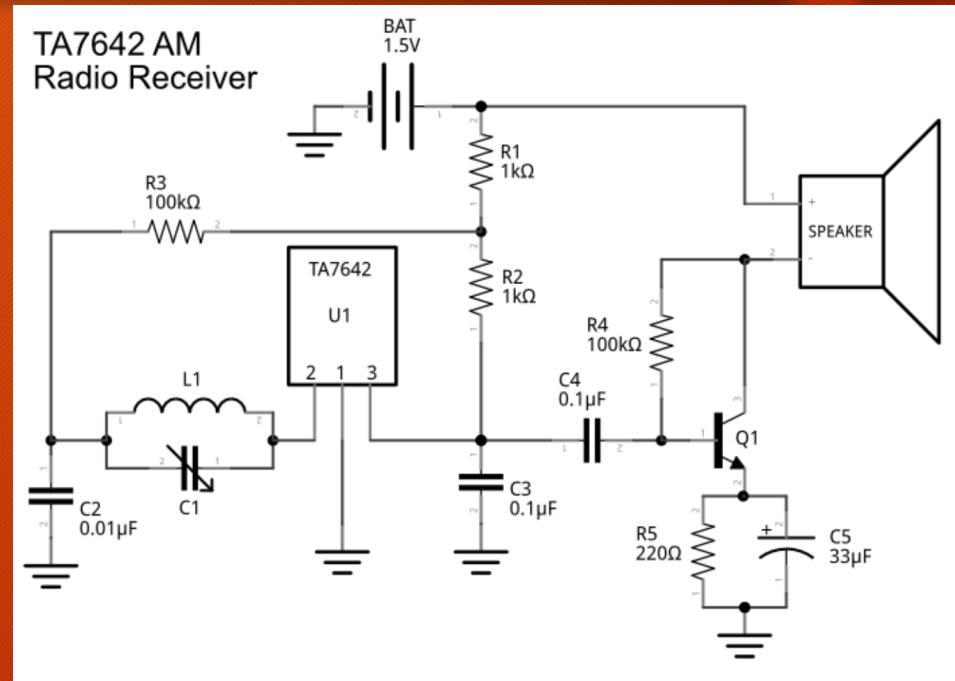
33

- Several Analog integrated circuits were designed for use in radio and TV receivers
- Some of the best ones are no longer in production
- Two notable exceptions are:
 - TA7642 analog AM receiver
 - The Si4734/35 from Skyworks and Si4732, are single-chip solutions that integrate the entire radio receiver function, from antenna input to audio output, on a single chip.
- Most new designs for radio transmitter and receivers moves all of the signal processing to demodulate and modulate radio signals to Digital Signal Processors (DSPs)
- Our very small cell phones would not be possible without DSPs

TA7642

34

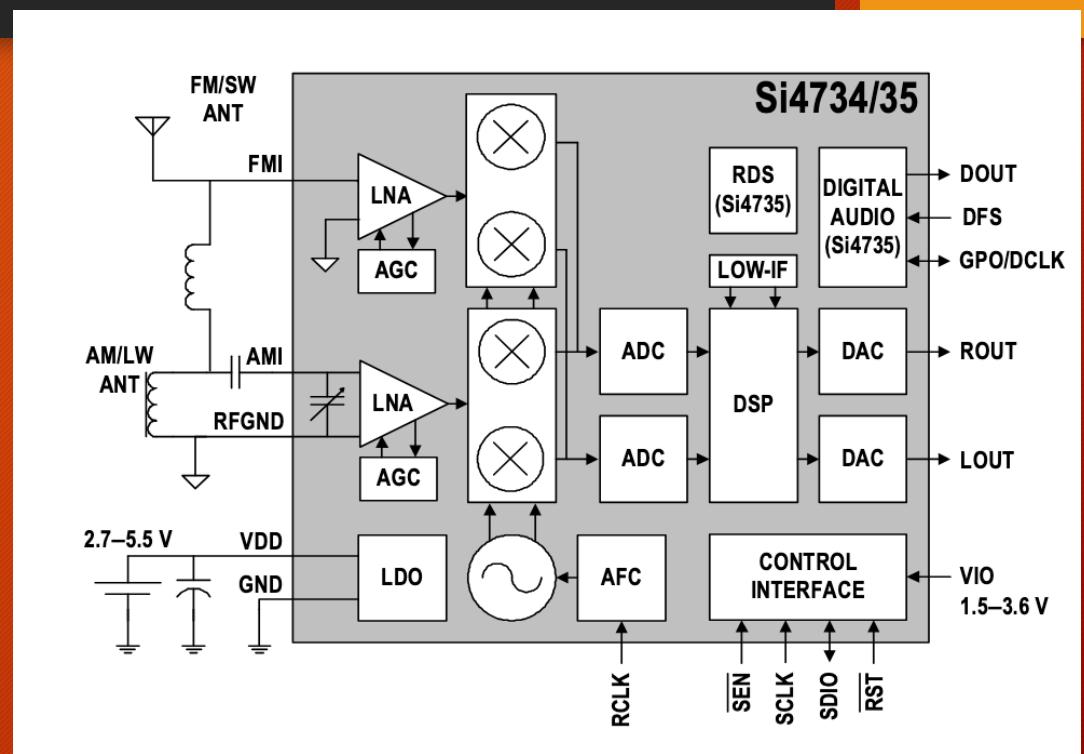
- <https://makerf.com/posts/make-your-own-rocket-radio-with-the-ta7642>
- parts can be purchased from Amazon
 - <https://www.amazon.com/DBParts-TA7642-Chip-Radio-Pack/dp/B07Z396FHD>



The Si4734/35

35

- Needs to be controller by a microprocessor like an Arduino nano



Questions

36

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