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MATH 430 (Fall 2006) Exam 1, October 4th

Show all work and give **complete explanations** for all your answers.

This is a 75 minute exam. It is worth a total of 100 points.

(1) [30 pts]

(a) Define the term *maximal linearly independent set*.

A subset $B = \{\vec{b}_1, \dots, \vec{b}_n\}$ of a F.D.V.S V is a MLI set if

- ① B is a LI set
- ② If $B' = \{\vec{a}_1, \dots, \vec{a}_m\}$ is ANY other LI set of V then $m \leq n$.

(b) State the Basis Characterization Theorem.

Let V be a F.D.V.S, and let $B = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_n\} \subseteq V$

TRUE

- ① B is a basis for V
- ② B is a maximal LI set for V
- ③ B is a minimal spanning set for V

(c) State the definition of a least squares solution of a linear system $Ax = b$.

A vector \vec{x} is a least squares solution of $A\vec{x} = \vec{b}$ if it minimizes the function

$$E(\vec{x}) = \sum_{i=1}^n \epsilon_i^2 = \sum_{i=1}^n (A\vec{x} - \vec{b})_i^2 = (A\vec{x} - \vec{b})^T (A\vec{x} - \vec{b})$$

(d) Suppose that $B_{r \times r}$ is an invertible $r \times r$ matrix and that $0_{p \times q}$ is the $p \times q$ zero matrix. Let A be the square matrix

$$A = \begin{pmatrix} B_{r \times r} & 0_{r \times s} \\ 0_{s \times r} & 0_{s \times s} \end{pmatrix}.$$

Find bases for the nullspace, $N(A)$, and the range, $R(A)$, of A and verify that the Rank and Nullity Theorem holds for A .

$$\vec{x} \in \mathbb{R}^r \quad \vec{y} \in \mathbb{R}^s$$

$$\begin{pmatrix} B & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \vec{x} \\ \vec{y} \end{pmatrix} = \begin{pmatrix} B\vec{x} \\ \vec{0} \end{pmatrix} = \begin{pmatrix} \vec{0} \\ \vec{0} \end{pmatrix} \quad \text{iff} \quad \vec{x} \in N(B) = \{\vec{0}\} \quad \text{as } B \text{ is invertible}$$

$$\text{So } \begin{pmatrix} \vec{x} \\ \vec{y} \end{pmatrix} \in N(A) \quad \text{iff} \quad \vec{x} = \vec{0}.$$

$$\text{So basis for } N(A) \text{ is } \{\vec{e}_{r+1}, \dots, \vec{e}_{r+s}\}$$

$$\begin{pmatrix} \vec{u} \\ \vec{v} \end{pmatrix} \in R(A) \text{ means } \begin{pmatrix} \vec{u} \\ \vec{v} \end{pmatrix} = \begin{pmatrix} B & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \vec{x} \\ \vec{y} \end{pmatrix} = \begin{pmatrix} B\vec{x} \\ \vec{0} \end{pmatrix}$$

$$\text{So } \vec{v} = \vec{0} \text{ and } \vec{u} = B\vec{x} \text{ must hold, i.e. } \vec{u} \in R(B)$$

So if $B = [B_{*1} \dots B_{*r}]$ decomposes B into columns. Then the vectors $B_{*1} \dots B_{*r}$ are LI as B is invertible. So

$$\left\{ \begin{pmatrix} B_{*1} \\ 0_{s \times 1} \end{pmatrix}, \dots, \begin{pmatrix} B_{*r} \\ 0_{s \times 1} \end{pmatrix} \right\} \text{ are a basis for } R(A)$$

<p>RTN THM</p> <p>$\dim N(A) = s$</p> <p>$\dim R(A) = r$</p> <p>$n = s + r$</p>
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(1e) If $N(A) = N(B)$ for two matrices
does $\text{Rank}(A) = \text{Rank}(B)$?

Yes Let A be $m \times n$, B $k \times l$.

Then $N(A) \subseteq \mathbb{R}^n$ $N(B) \subseteq \mathbb{R}^l$

Since $N(A) = N(B)$ they must
both contain vectors with same # of components

So $n = l$ must hold.

So Rtnv Thm gives

$$\dim N(A) + \text{Rank}(A) = n$$

$$\dim N(B) + \text{Rank}(B) = n$$

$$\text{So } \text{Rank}(A) = \text{Rank}(B)$$

(If). We did This in class.

(2) [15 pts] Let A be the matrix

$$A = \begin{pmatrix} 1 & 2 & 2 & 3 \\ 2 & 4 & 1 & 3 \\ 3 & 6 & 1 & 4 \end{pmatrix}$$

Find bases for the nullspace and range of the A and for the range of A^T .

$$\begin{pmatrix} 1 & 2 & 2 & 3 \\ 2 & 4 & 1 & 3 \\ 3 & 6 & 1 & 4 \end{pmatrix} \begin{array}{l} R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 - 3R_1 \end{array}$$

$$\sim \begin{pmatrix} 1 & 2 & 2 & 3 \\ 0 & 0 & -3 & -3 \\ 0 & 0 & -5 & -5 \end{pmatrix} \begin{array}{l} R_2 \rightarrow -\frac{1}{3}R_2 \\ R_3 \rightarrow \frac{1}{5}R_3 + 5R_2 \end{array}$$

$$\sim \begin{pmatrix} \boxed{1} & 2 & 2 & 3 \\ 0 & 0 & \boxed{1} & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} \boxed{1} & 2 & 0 & 3 \\ 0 & 0 & \boxed{1} & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} = U \quad R_1 \rightarrow R_1 - 2R_2$$

$R(A)$ has basis given by pivot columns in A : $\left\{ \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \right\}$

x_1, x_3 basic variables, x_2, x_4 free variables.

Solution to $A\vec{x} = \vec{0}$ is

$$x_3 = -x_4$$

$$x_1 = -2x_2 - 3x_4$$

$$\text{So } \vec{x} = \begin{pmatrix} -2x_2 - 3x_4 \\ x_2 \\ -x_4 \\ x_4 \end{pmatrix} = x_2 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -3 \\ 0 \\ -1 \\ 1 \end{pmatrix}$$

Basis for $N(A) = \left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ -1 \\ 1 \end{pmatrix} \right\}$

Basis for $R(A^T) =$ Non zero rows of U

$$= \left\{ (1, 2, 0, 3) \text{ and } (0, 0, 1, 1) \right\}$$

(3) [15 pts] Find the least squares solutions to the linear system

$$2x + 3y = 2$$

$$4x - 2y = -1$$

$$x + 5y = 1$$

$$2x + 0y = 3$$

$$\begin{pmatrix} 2 & 3 \\ 4 & -2 \\ 1 & 5 \\ 2 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \\ 1 \\ 3 \end{pmatrix} \quad \underline{\text{or}} \quad A\vec{x} = \vec{b}.$$

Least squares solutions of $A\vec{x} = \vec{b}$ are precisely solutions of Normal equations $A^T A \vec{x} = A^T \vec{b}$:

$$A^T A = \begin{pmatrix} 2 & 4 & 1 & 2 \\ 3 & -2 & 5 & 0 \end{pmatrix} \begin{pmatrix} 2 & 3 \\ 4 & -2 \\ 1 & 5 \\ 2 & 0 \end{pmatrix} = \begin{pmatrix} 25 & 3 \\ 3 & 38 \end{pmatrix}$$

$$A^T \vec{b} = \begin{pmatrix} 2 & 4 & 1 & 2 \\ 3 & -2 & 5 & 0 \end{pmatrix} \begin{pmatrix} 2 \\ -1 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 7 \\ 13 \end{pmatrix}$$

$$\left(\begin{array}{cc|c} 25 & 3 & 7 \\ 3 & 38 & 13 \end{array} \right) \quad R2 \rightarrow R2 - \frac{3}{25} R1$$

$$\sim \left(\begin{array}{cc|c} 25 & 3 & 7 \\ 0 & 37\frac{16}{25} & 12\frac{4}{25} \end{array} \right)$$

$$\sim \left(\begin{array}{cc|c} \text{---} & \text{---} & \text{---} \end{array} \right)$$

$$38 - \frac{9}{25}$$

$$= 37\frac{16}{25}$$

$$13 - \frac{21}{25}$$

$$= 12\frac{4}{25}$$

$$37\frac{16}{25} y = 12\frac{4}{25}$$

$$y = \frac{12 \times 25 + 4}{25} \cdot \frac{25}{37 \cdot 25 + 16}$$

$$y = \frac{12 \times 25 + 4}{37 \times 25 + 16}$$

$$25x = 7 - 3y$$

$$x = \frac{7 - 3 \left(\frac{12 \times 25 + 4}{37 \times 25 + 16} \right)}{25}$$

(4) [10 pts] Let A and B be two matrices with the same number of columns and let $C = \begin{pmatrix} A \\ B \end{pmatrix}$. Prove that $N(C) \subseteq N(A)$. Is $N(C) = N(A)$? Why?

~~Let $\vec{x} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \in N(C)$~~

Let $\vec{x} \in N(C)$.

$$\text{So } \vec{0} = \begin{pmatrix} \vec{0} \\ \vec{0} \end{pmatrix} = C\vec{x} = \begin{pmatrix} A \\ B \end{pmatrix} \vec{x} = \begin{pmatrix} A\vec{x} \\ B\vec{x} \end{pmatrix}$$

So $A\vec{x} = \vec{0}$ must hold

Therefore $\vec{x} \in N(A)$

So $N(C) \subseteq N(A)$.

$N(C) \neq N(A)$: as can be seen by the following example

$$A = [0] \quad (1 \times 1), \quad B = [1] \quad (1 \times 1), \quad C = \begin{pmatrix} A \\ B \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad 2 \times 1$$

~~$N(A) = \mathbb{R}$~~ $N(A) = \mathbb{R}$

$$N(C) = \left\{ x \in \mathbb{R} \mid \begin{pmatrix} 0 \\ 1 \end{pmatrix} x = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right\} = \left\{ x \in \mathbb{R} \mid \begin{pmatrix} 0 \\ x \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right\}$$

$$= \left\{ \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right\} = \{0\}. \quad \boxed{\{0\} \neq \mathbb{R}}$$

(5) [10 pts] Suppose that A is a 2×2 matrix with

$$A \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \end{pmatrix} \quad A \begin{pmatrix} 2 \\ 5 \end{pmatrix} = \begin{pmatrix} 6 \\ 7 \end{pmatrix}.$$

Without working out the entries of A , find $A \begin{pmatrix} 6 \\ 10 \end{pmatrix}$.

$\left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ 5 \end{pmatrix} \right\}$ is a basis for \mathbb{R}^2 .

Let's write $\begin{pmatrix} 6 \\ 10 \end{pmatrix} = x \begin{pmatrix} 1 \\ 2 \end{pmatrix} + y \begin{pmatrix} 2 \\ 5 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$

Solving for $\begin{pmatrix} x \\ y \end{pmatrix}$:

$$\left(\begin{array}{cc|c} 1 & 2 & 6 \\ 2 & 5 & 10 \end{array} \right) \quad R_2 \rightarrow R_2 - 2R_1$$

$$\sim \left(\begin{array}{cc|c} 1 & 2 & 6 \\ 0 & 1 & -2 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & 0 & 10 \\ 0 & 1 & -2 \end{array} \right) \quad R_1 \rightarrow R_1 - 2R_2$$

gives $y = -2$, $x = 10$

So

$$\begin{pmatrix} 6 \\ 10 \end{pmatrix} = 10 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + -2 \begin{pmatrix} 2 \\ 5 \end{pmatrix}$$

So by linearity of matrix multiplication.

$$A \begin{pmatrix} 6 \\ 10 \end{pmatrix} = 10 A \begin{pmatrix} 1 \\ 2 \end{pmatrix} + -2 A \begin{pmatrix} 2 \\ 5 \end{pmatrix}$$

$$= 10 \begin{pmatrix} 2 \\ 3 \end{pmatrix} - 2 \begin{pmatrix} 6 \\ 7 \end{pmatrix}$$

$$= \begin{pmatrix} 8 \\ 16 \end{pmatrix}$$

(6) [10 pts] Let A be an $n \times n$ matrix. Suppose that $\{v_1, \dots, v_n\}$ is a basis for \mathbb{R}^n such that $\{v_{r+1}, \dots, v_n\}$ is a basis for $N(A)$. Prove that $\{Av_1, \dots, Av_r\}$ is a basis for $R(A)$.

SPANNING

Let $\vec{w} \in R(A)$.

So $\vec{w} = A\vec{u}$ for some $\vec{u} \in \mathbb{R}^n$.

Since $\{\vec{v}_1, \dots, \vec{v}_n\}$ is a basis for $\mathbb{R}^n \exists \alpha_1, \dots, \alpha_n \in \mathbb{R}$:

$$\vec{u} = \alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n$$

$$\text{Then } A\vec{u} = \alpha_1 A\vec{v}_1 + \dots + \alpha_r A\vec{v}_r$$

$$+ \alpha_{r+1} A\vec{v}_{r+1} + \dots + \alpha_n A\vec{v}_n$$

$$= \alpha_1 A\vec{v}_1 + \dots + \alpha_r A\vec{v}_r + \vec{0} + \dots + \vec{0}$$

$$\approx A\vec{v}_j = \vec{0} \text{ as } \vec{v}_j \in N(A) \text{ for } j > r.$$

$$\text{So } \vec{w} = A\vec{u} \in \text{Span}\{A\vec{v}_1, \dots, A\vec{v}_r\}$$

LI

$$\text{Suppose } \alpha_1 A\vec{v}_1 + \dots + \alpha_r A\vec{v}_r = \vec{0}$$

$$\text{Then } A(\alpha_1 \vec{v}_1 + \dots + \alpha_r \vec{v}_r) = \vec{0}$$

$$\text{So } \alpha_1 \vec{v}_1 + \dots + \alpha_r \vec{v}_r \in N(A)$$

Since $\vec{v}_{r+1}, \dots, \vec{v}_n$ is a basis for $N(A) \exists \beta_{r+1}, \dots, \beta_n$:

$$\alpha_1 \vec{v}_1 + \dots + \alpha_r \vec{v}_r = \beta_{r+1} \vec{v}_{r+1} + \dots + \beta_n \vec{v}_n$$

$$\text{So } \alpha_1 \vec{v}_1 + \dots + \alpha_r \vec{v}_r - \beta_{r+1} \vec{v}_{r+1} - \dots - \beta_n \vec{v}_n = \vec{0}$$

$$\text{So } \alpha_1 = \dots = \alpha_r = \beta_{r+1} = \dots = \beta_n = 0 \text{ as } \vec{v}_1, \dots, \vec{v}_n \text{ B.A.U.}$$

So $\alpha_1 = \dots = \alpha_r = 0$
 So $\{A\vec{v}_1, \dots, A\vec{v}_r\}$
 are LI

(7) [10 pts] Let \mathbf{v}, \mathbf{w} be two column vectors in \mathcal{R}^n and let I denote the $n \times n$ identity matrix. Suppose that $\mathbf{w}^T \mathbf{v} \neq 1$. Show that the matrix $I - \mathbf{v} \mathbf{w}^T$ is invertible and that its inverse is a matrix of the form $I - c \mathbf{v} \mathbf{w}^T$, for some scalar c . Also, find a formula for c in terms of \mathbf{v} and \mathbf{w} .

$I - \mathbf{v} \mathbf{w}^T$ is invertible if $\exists B$:

$$(I - \mathbf{v} \mathbf{w}^T) B = I = B(I - \mathbf{v} \mathbf{w}^T)$$

Let's try $B = I - c \mathbf{v} \mathbf{w}^T$.

Well

$$\begin{aligned} (I - \mathbf{v} \mathbf{w}^T)(I - c \mathbf{v} \mathbf{w}^T) &= I - \mathbf{v} \mathbf{w}^T - c \mathbf{v} \mathbf{w}^T + c \underbrace{\mathbf{v} \mathbf{w}^T \mathbf{v} \mathbf{w}^T}_{1 \times 1} \\ &= I - (1+c) \mathbf{v} \mathbf{w}^T + (c \mathbf{w}^T \mathbf{v}) \mathbf{v} \mathbf{w}^T \\ &= I + (-1-c + c \mathbf{w}^T \mathbf{v}) \mathbf{v} \mathbf{w}^T = I \end{aligned}$$

iff $-1-c + c \mathbf{w}^T \mathbf{v} = 0$

$\Leftrightarrow 1 = -c(1 - \mathbf{w}^T \mathbf{v})$

$\Leftrightarrow c = \frac{1}{\mathbf{w}^T \mathbf{v} - 1}$ provided $\mathbf{w}^T \mathbf{v} \neq 1$ as we assumed.

So $(I - \mathbf{v} \mathbf{w}^T)^{-1} = I - \frac{\mathbf{v} \mathbf{w}^T}{\mathbf{w}^T \mathbf{v} - 1}$ should hold.

Indeed if you redo calculation \oplus with $c = \frac{1}{\mathbf{w}^T \mathbf{v} - 1}$

Pledge: I have neither given nor received aid on this exam

you see that you get I , as required.

Signature: _____

Similarly $\textcircled{\text{PTD}}$

$$(I - c \vec{v} \vec{w}^T) (I - \vec{v} \vec{w}^T)$$

$$= I - c \vec{v} \vec{w}^T - \vec{v} \vec{w}^T + c \underbrace{\vec{v} \vec{w}^T \vec{v} \vec{w}^T}_{1 \times 1}$$

$$= I + (-cI - I + c \vec{w}^T \vec{v}) \vec{v} \vec{w}^T$$

$$= I \quad \text{if} \quad c = \frac{1}{\vec{w}^T \vec{v} - 1} \quad \text{as required.}$$

Together these results
shows that

$$\cancel{I - \vec{v} \vec{w}^T} (I - \vec{v} \vec{w}^T)^{-1} = I - \frac{\vec{v} \vec{w}^T}{\vec{w}^T \vec{v} - 1}$$