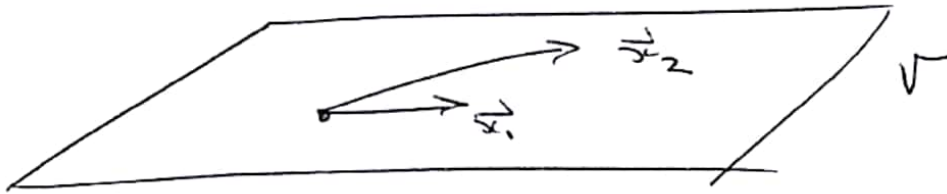


## 5.5 GRAM-SCHMIDT ORTHOGONALIZATION

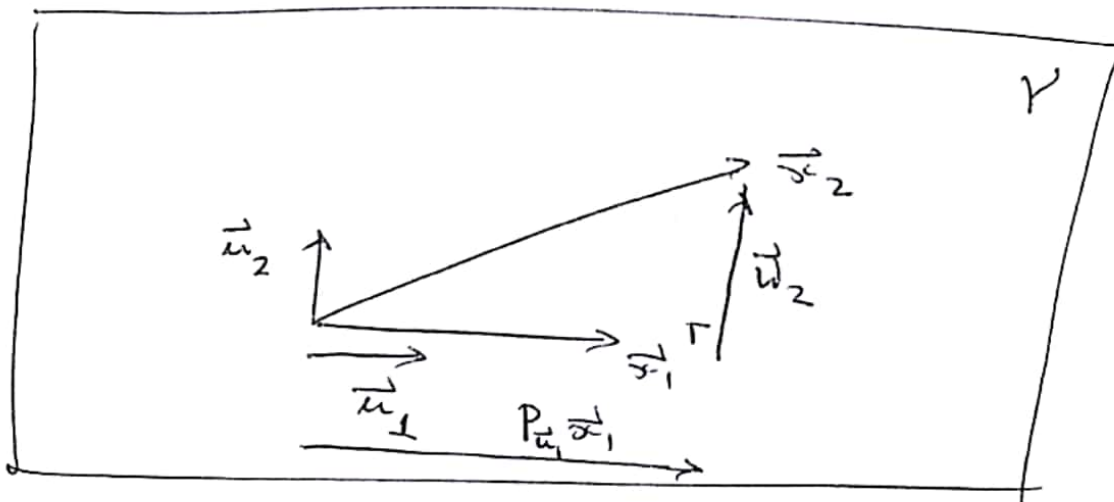
①

### MOTIVATING EX

Let  $V = \text{Span} \{ \vec{x}_1, \vec{x}_2 \} \subseteq \mathbb{R}^3$ .



GOAL Construct ONB  $\mathcal{O} = \{ \vec{u}_1, \vec{u}_2 \}$  for  $V$ .



$$\text{Set } \vec{u}_1 = \frac{\vec{x}_1}{\|\vec{x}_1\|}$$

$$\text{Set } \vec{w}_2 = \vec{x}_2 - P_{\vec{u}_1} \vec{x}_2 = \vec{x}_2 - \langle \vec{x}_2, \vec{u}_1 \rangle \vec{u}_1$$

CHECK

$$\langle \vec{w}_2 | \vec{u}_1 \rangle = \langle \vec{x}_2 | \vec{u}_1 \rangle - \langle \vec{x}_2 | \vec{u}_1 \rangle \underbrace{\langle \vec{u}_1 | \vec{u}_1 \rangle}_{=1} = 0$$

$$\text{Set } \vec{u}_2 = \vec{w}_2 / \|\vec{w}_2\|$$

①

S.5 GRAM-SCHMIDT ORTHOGONALIZATION

Given a basis

$$B = \{\vec{x}_1, \dots, \vec{x}_n\} \quad \text{for IPS } V$$

construct ONB  $\mathcal{O} = \{\vec{u}_1, \dots, \vec{u}_n\}$  for  $V$  using an inductive process:

$$\forall k \quad \mathcal{O}_k = \{\vec{u}_1, \dots, \vec{u}_k\} \text{ is ONB for } V_k = \text{Span}\{\vec{x}_1, \dots, \vec{x}_k\}$$

$$\boxed{k=1} \quad \vec{u}_1 = \frac{\vec{x}_1}{\|\vec{x}_1\|}$$

INDUCTION STEP

Given  $\mathcal{O}_k$  for  $V_k$  find  $\vec{u}_{k+1}$  so that  $\mathcal{O}_{k+1}$  is ONB for  $V_{k+1}$ .

If we had  $\vec{u}_{k+1}$  we could express  $\vec{x}_{k+1}$  as

$$\begin{aligned} \vec{x}_{k+1} &= \sum_{i=1}^{k+1} \langle \vec{u}_i | \vec{x}_{k+1} \rangle \vec{u}_i \\ &= \sum_{i=1}^k \langle \vec{u}_i | \vec{x}_{k+1} \rangle \vec{u}_i + \langle \vec{u}_{k+1} | \vec{x}_{k+1} \rangle \vec{u}_{k+1} \quad \textcircled{1} \end{aligned}$$

2

CLAIM

$$\langle \vec{u}_{k+1} | \vec{x}_{k+1} \rangle \neq 0$$

PF

otherwise by ①  $\vec{x}_{k+1} \in \text{Span}(\mathcal{O}_k) = \text{Span}(V_k)$

contradicting assump<sup>n</sup>  $\mathcal{B}$  is basis for  $V$ .  $\square$

So by ①

$$\vec{u}_{k+1} = \frac{\vec{x}_{k+1} - \sum_{i=1}^k \langle \vec{u}_i | \vec{x}_{k+1} \rangle \vec{u}_i}{\langle \vec{u}_{k+1} | \vec{x}_{k+1} \rangle}$$

$$\langle \vec{u}_{k+1} | \vec{x}_{k+1} \rangle$$

We don't care about <sup>this</sup> denominator as we need  $\|\vec{u}_{k+1}\| = 1$ .

FS ALGORITHM

$$\vec{u}_1 = \frac{\vec{x}_1}{\|\vec{x}_1\|}$$

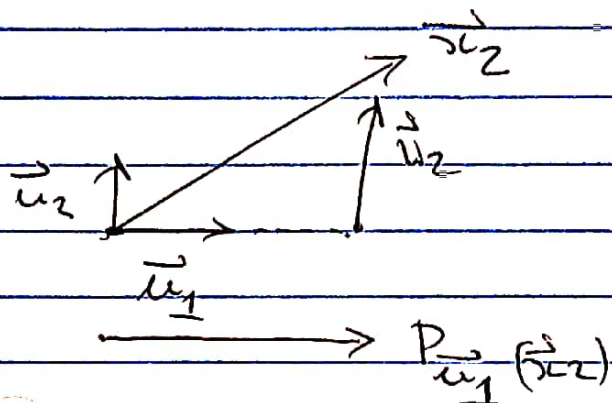
FOR  $k \geq 1$

$$\vec{w}_k = \vec{x}_k - \sum_{i=1}^{k-1} \langle \vec{u}_i | \vec{x}_k \rangle \vec{u}_i$$

$$\vec{u}_k = \frac{\vec{w}_k}{\|\vec{w}_k\|}$$

$$\vec{w}_k = \vec{x}_k - \sum_{i=1}^{k-1} P_{\vec{u}_i}(\vec{x}_k)$$

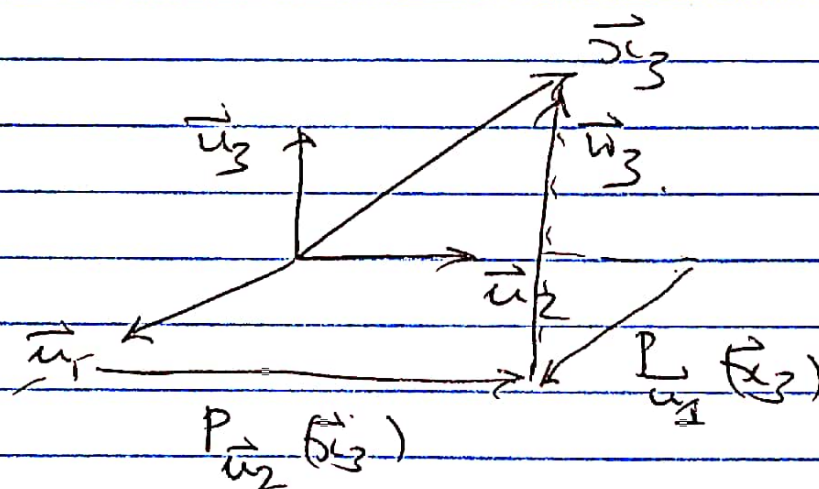


PICTURES $k=2$ 

$$\vec{w}_2 = \vec{x}_2 - P_{\vec{u}_1}(\vec{x}_2)$$

 $k=3$ 

$$\vec{w}_3 = \vec{x}_3 - P_{\vec{u}_1}(\vec{x}_3) - P_{\vec{u}_2}(\vec{x}_3)$$



Ex  $\mathbb{R}^3$

①  $\vec{x}_1 = \begin{pmatrix} 3 \\ 4 \\ 0 \end{pmatrix}$   $\vec{x}_2 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$   $\vec{x}_3 = \begin{pmatrix} 0 \\ 4 \\ 5 \end{pmatrix}$  ④

$$\vec{u}_1 = \frac{\vec{x}_1}{\|\vec{x}_1\|} = \begin{pmatrix} 3/5 \\ 4/5 \\ 0 \end{pmatrix}$$

②  $\vec{w}_2 = \vec{x}_2 - \langle \vec{u}_1 | \vec{x}_2 \rangle \vec{u}_1$

$$= \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} - (3/5 \ 4/5 \ 0) \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \begin{pmatrix} 3/5 \\ 4/5 \\ 0 \end{pmatrix} = \begin{pmatrix} -8/25 \\ 6/25 \\ 3 \end{pmatrix}$$

U ✓  $\langle \vec{w}_2 | \vec{u}_1 \rangle = 0$

$$\|\vec{w}_2\| = \sqrt{5725} / 25$$

$$\vec{u}_2 = \begin{pmatrix} -8 \\ 6 \\ 75 \end{pmatrix} / \sqrt{5725}$$

③  $\vec{w}_3 = \vec{x}_3 - \langle \vec{u}_1 | \vec{x}_3 \rangle \vec{u}_1 - \langle \vec{u}_2 | \vec{x}_3 \rangle \vec{u}_2$

$$= \begin{pmatrix} 0 \\ 4 \\ 5 \end{pmatrix} - \frac{1}{25} \begin{pmatrix} 48 \\ 64 \\ 0 \end{pmatrix} - \frac{423}{5725} \begin{pmatrix} -8 \\ 6 \\ 75 \end{pmatrix} = *$$

$$\vec{u}_3 = \vec{w}_3 / \|\vec{w}_3\| = \text{ETC}$$