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7.3, 7.4 MATRIX EXPONENTIATION + ODE SYSTEMS

Recall

$$e^z = \sum_{k=0}^{\infty} \frac{1}{k!} z^k \quad z \in \mathbb{C}$$

If A is $n \times n$ we could formally define

$$e^A = \sum_{k=0}^{\infty} \frac{1}{k!} A^k \quad \text{An } n \times n \text{ MATRIX} \quad \textcircled{1}$$

assuming ∞ -series converged. (It does).

How can we calculate e^A in practice?

If A is diagonalizable $A = P D P^{-1}$

with $D = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$ then

$$A^k = P D^k P^{-1} \quad \text{with} \quad D^k = \begin{bmatrix} \lambda_1^k & & \\ & \ddots & \\ & & \lambda_n^k \end{bmatrix}$$

So

$$\begin{aligned} e^A &= \sum_{k=0}^{\infty} \frac{1}{k!} P D^k P^{-1} = P \left(\sum_{k=0}^{\infty} \frac{1}{k!} D^k \right) P^{-1} \\ &= P \begin{bmatrix} \sum_{k=0}^{\infty} \frac{1}{k!} \lambda_1^k & & \\ & \ddots & \\ & & \sum_{k=0}^{\infty} \frac{1}{k!} \lambda_n^k \end{bmatrix} P^{-1} \end{aligned}$$

$$= P \begin{bmatrix} e^{\lambda_1} & & \\ & \ddots & \\ & & e^{\lambda_n} \end{bmatrix} P^{-1}$$

(2)

SUMMARY Suppose $A = PDP^{-1}$. Define

$$e^D = \begin{bmatrix} e^{\lambda_1} & & \\ & \ddots & \\ & & e^{\lambda_n} \end{bmatrix} \quad \text{Then } \boxed{e^A = P e^D P^{-1}} \quad (3)$$

EX A Calculate e^A for your favorite 3×3 matrix A that is diagonalizable but for which one eigenvalue has multiplicity 2

ISSUE P may not be unique. So how do we know e^A given by (3) is uniquely defined?

SOLUTION [CASE A IS NORMAL] Use Spectral Decomposⁿ.

$$e^A = P e^D P^{-1} = [x_1 | \dots | x_k] \begin{bmatrix} e^{\lambda_1} I & & \\ & \ddots & \\ & & e^{\lambda_k} I \end{bmatrix} \begin{bmatrix} x_1^* \\ \vdots \\ x_k^* \end{bmatrix}$$

$$= e^{\lambda_1} x_1 x_1^* + \dots + e^{\lambda_k} x_k x_k^*$$

$$\boxed{e^A = e^{\lambda_1} G_1 + \dots + e^{\lambda_k} G_k}$$

MORE GENERALLY

Suppose $f: \mathbb{C} \rightarrow \mathbb{C}$ is any function
and $A = PDP^{-1}$.

We define

$$f(A) = P f(D) P^{-1}$$

$$f(A) = f(\lambda_1) E_1 + \dots + f(\lambda_k) E_k$$

EX $f(z) = \sin z$
 $f(z) = \cos z$

RECALL $E_i = \frac{\prod_{\substack{j=1 \\ j \neq i}}^k (A - \lambda_j I)}{\prod_{\substack{j=1 \\ j \neq i}}^k (\lambda_i - \lambda_j)}$

is a polynomial of degree $\leq k-1$ in A .

So $f(A)$ is too (even though $f(z) = e^z$
or $f(z) = \sin z$ has a power series in z)

CAUTION $\lambda_j = \lambda_j(A)$ depends on A too.

(3)

APPLICATION

Solve IVP

$$\begin{cases} \frac{d\vec{u}}{dt} = A\vec{u} \\ \vec{u}(0) = \vec{u}_0 \end{cases}$$

 A diagonalizableCLAIM.

$$\vec{u}(t) = e^{\lambda_1 t} \vec{v}_1 + \dots + e^{\lambda_k t} \vec{v}_k$$

where $\vec{v}_j := f_j \vec{u}_0$ is an evector of A with evalue λ_j

(Recall f_j projects onto $N(A - \lambda_j I)$)

PF

① Since we have

$$e^{At} = e^{\lambda_1 t} f_1 + \dots + e^{\lambda_k t} f_k$$

$$\begin{aligned} \frac{d}{dt} (e^{At}) &= \lambda_1 e^{\lambda_1 t} f_1 + \dots + \lambda_k e^{\lambda_k t} f_k \\ &= (\lambda_1 f_1 + \dots + \lambda_k f_k) (e^{\lambda_1 t} f_1 + \dots + e^{\lambda_k t} f_k) \end{aligned}$$

$$\text{as } f_i \cdot f_j = \delta_{ij} f_i$$

$$\begin{aligned} &= A e^{At} \\ &= e^{At} A \end{aligned}$$

(4)

And by similar arguments

$$e^{-At} e^{At} = I = e^0$$

(2) Let $\vec{u}(t) = e^{At} \vec{u}_0$.

Then $\frac{d\vec{u}}{dt} = A e^{At} \vec{u}_0$ by (1)
 $= A \vec{u}$

and $\vec{u}(0) = e^0 \vec{u}_0 = \vec{u}_0$. D.

EXERCISE 8 For matrix A you picked in EX A

solve $\begin{cases} \frac{d\vec{u}}{dt} = A\vec{u} \\ \vec{u}(0) = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \end{cases}$