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L3 [M 4.3, 4.4] LINEAR INDEPENDENCE, BASIS + DIMENSION

DEF 1 A V.S. V is finite dimensional if it has a finite spanning set, i.e. $\exists \vec{v}_1, \dots, \vec{v}_n :$

$$V = \text{Span} \{ \vec{v}_1, \dots, \vec{v}_n \}.$$

EX 2 \mathbb{R}^n is F.D. with $\mathbb{R}^n = \text{SPAN} \{ \vec{e}_1, \dots, \vec{e}_n \}$

as if $\vec{v} = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix} \in \mathbb{R}^n$ then $\vec{v} = \sum_{j=1}^n v_j \vec{e}_j$

EX 3 Let $V = \text{SPAN} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 3 \\ 0 \end{pmatrix} \right\} \subset \mathbb{R}^3$

$$\vec{v}_1, \vec{v}_2, \vec{v}_3$$

Although $\mathcal{S} = \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ spans V it contains redundancy as

$$\vec{v}_3 = 2\vec{v}_1 + 3\vec{v}_2 \quad \oplus$$

CLAIM $\text{Span} \{ \vec{v}_1, \vec{v}_2, \vec{v}_3 \} = \text{Span} \{ \vec{v}_1, \vec{v}_2 \} = \text{PMTZ} = 0.$

PF  EASY



EASY

Let $\vec{w} \in \text{Span} \{ \vec{v}_1, \vec{v}_2, \vec{v}_3 \}$

So

$$\begin{aligned} \vec{w} &= \alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \alpha_3 \vec{v}_3 \\ &= \alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \alpha_3 (2\vec{v}_1 + 3\vec{v}_2) \quad \oplus \\ &= (\alpha_1 + 2\alpha_3) \vec{v}_1 + (\alpha_2 + 3\alpha_3) \vec{v}_2 \in \text{Span} \{ \vec{v}_1, \vec{v}_2 \} \quad D \end{aligned}$$

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GOAL Given a finite spanning set \mathcal{S} for a FDS V
 eliminate any redundancies to
 obtain a MINIMUM SPANNING SET.

DEF 4 A finite subset \mathcal{S} of V is a
MINIMUM SPANNING SET for V if

(a) $V = \text{Span}(\mathcal{S})$

(b) If $\tilde{\mathcal{S}} \subset V$ with $\#(\tilde{\mathcal{S}}) < \#(\mathcal{S})$
 Then $\tilde{\mathcal{S}}$ does not span V .

① \exists MSS for V

NOTES ③ $\exists \infty$ MSS for V .

EX $\mathcal{S}_1 = \{\vec{e}_1, \vec{e}_2\}$ $\mathcal{S}_2 = \{\vec{e}_1 + \vec{e}_2, \vec{e}_2\}$
 are 2 MSS for \mathbb{R}^2 .

PROP 5 Any 2 MSS for V contain same # EIS

PF Let $\mathcal{S}_1, \mathcal{S}_2$ be 2 MSS for V
 Suppose $\#(\mathcal{S}_1) < \#(\mathcal{S}_2)$.

Since \mathcal{S}_2 is a MSS, \mathcal{S}_1 cannot span V by ①

So \mathcal{S}_1 cannot be a MSS for V $\neg X$.
 by ② \square

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PF6 @ The dimension of a FD vs V is
 # elts in a MSS for V

⑥ A set $f = \{\vec{v}_1, \dots, \vec{v}_n\}$ contains a redundancy if \vec{v}_j :

$$\vec{v}_j = \text{L.C. of } \vec{v}_1, \dots, \vec{v}_{j-1}, \vec{v}_{j+1}, \dots, \vec{v}_n.$$

REDUNDANCY THM \exists

Let f be a finite spanning set for V .
 Then

f contains a redundancy $\Leftrightarrow f$ is not a MSS

PF OF ~~/~~

Suppose f contains a redundancy w/ $j=n$:

$$\vec{v}_n = \sum_{k=1}^{n-1} b_k \vec{v}_k$$

$$\text{Let } \tilde{f} = \{\vec{v}_1, \dots, \vec{v}_{n-1}\}$$

Then \tilde{f} spans V too (as in Ex 3)

Since $\#(\tilde{f}) < \#(f)$, f is not a MSS

~~See Later~~

□

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The defⁿ of a redundancy is a bit messy,
as not "symmetric" in the \vec{v}_i 's.

So

DEF 8 @ A set $S = \{\vec{v}_1, \dots, \vec{v}_n\}$ is LINEARLY DEPT

if \exists scalars $\alpha_1, \dots, \alpha_n$ NOT ALL ZERO :

$$\alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n = \vec{0}.$$

(b) $\forall \vec{v} \in S \sim LD \Leftrightarrow S$ contains a redundancy.

(c) S is LINEARLY INDEPT if $S \sim \text{NOT LD}$.

(d) $\forall \vec{v} \in S = \{\vec{v}_1, \dots, \vec{v}_n\} \sim LI$ if

only solⁿ of $\alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n = \vec{0}$

\sim The trivial solⁿ $\alpha_1 = \alpha_2 = \dots = \alpha_n = 0$.

(e) A BASIS for a FDVS V is a LI, SPANNING SET for V .

PROP 9 (USING MATRICES TO TEST FOR LI)

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Let $A = [\vec{v}_1 \dots \vec{v}_n]$ be $m \times n$ So $\vec{v}_j \in \mathbb{R}^m$

TFAE

① $\{\vec{v}_1 \dots \vec{v}_n\}$ is a LI set

② $N(A) = \{0\}$

③ $Rk(A) = n \leftarrow$ Use GE on A to check
pivot.

PF

① \Leftrightarrow ②

$$A \vec{x} \stackrel{(A)}{=} \vec{0} \Leftrightarrow \alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n \stackrel{(B)}{=} \vec{0} \quad \vec{x} = \begin{pmatrix} x_1 \\ 1 \\ \vdots \\ x_n \end{pmatrix}$$

So

$\{\vec{v}_1 \dots \vec{v}_n\}$ LI

\Leftrightarrow Only soln of ③ is $\alpha_1 = \dots = \alpha_n = 0$

\Leftrightarrow Only Sol^n of ④ is $\vec{x} = \vec{0}$

$\Leftrightarrow N(A) = \{0\}$

② \Leftrightarrow ③

See L2 Cor 9.

□

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BASIS CHARACTERIZATION THM 10

Let V be a FDVS, $B = \{\vec{b}_1, \dots, \vec{b}_n\} \subseteq V$.
 TFAE

- ① B is a basis for V
- ② B is a MSS for V
- ③ B is a maximal LI set for V .

IN PARTICULAR since V has a MSS, V has a basis!

PF

② \Rightarrow ① : See PF of Red^y Thm 7

① \Rightarrow ② : Let B be a basis for V .
 Suppose B is not a MSS.

Let $S = V = \text{Span}\{\vec{x}_1, \dots, \vec{x}_k\}$ for some $k < n$.

$$\text{So } \exists A_j : \vec{b}_j = \sum_{i=1}^k A_{ij} \vec{x}_i \quad j = 1, \dots, n \quad (*)$$

$k \times n$

$$\text{So } \text{Rk}(A) \leq \min(k, n) = k < n$$

So by L2 Cor 9 $N(A) \neq \{\vec{0}\}$

$$\text{So } \exists \vec{z} \in \mathbb{R}^n : A \vec{z} = \vec{0}.$$

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So \vec{v}_i

$$0 = (\vec{A}\vec{z})_i = \sum_{j=1}^n A_{ij} z_j$$

**

Then

$$\begin{aligned} \sum_{j=1}^n z_j \vec{v}_j &= \sum_{j=1}^n z_j \left(\sum_{i=1}^k A_{ij} \vec{x}_i \right) \quad \text{by } \textcircled{P} \\ &= \sum_{i=1}^k \left(\sum_{j=1}^n z_j A_{ij} \right) \vec{x}_i \\ &= \sum_{i=1}^k (\vec{A}\vec{z})_i \underset{\parallel}{\vec{x}_i} = \vec{0} \quad \text{by } \textcircled{P} \end{aligned}$$

Since z_j not all 0 ($\vec{z} \neq \vec{0}$) $B = \{\vec{v}_1, \dots, \vec{v}_n\}$ is not LI (not a basis)

~~x~~
 " D

$\textcircled{3} \Rightarrow \textcircled{1}$

Suppose B is a max LI set but B is not a basis.

Then $\exists \vec{v} \in V : \vec{v} \notin \text{Span}(B)$ as B does not span V .

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So by Lemma below

$$\{\vec{v}, \vec{b}_1, \dots, \vec{b}_n\} \text{ is LI set}$$

So \mathcal{B} is not a MAXIMAL LI set.

$\boxed{1 \Rightarrow 3}$ SIMILAR IDEAS See [M, p 196]

LEMMA 11

If \mathcal{B} is LI and $\vec{v} \in V$ Then

$$\mathcal{B} \cup \{\vec{v}\} \text{ is LI} \Leftrightarrow \vec{v} \notin \text{Span}(\mathcal{B})$$

$\frac{\text{PF}}{\Leftarrow}$

Suppose $\vec{v} \notin \text{Span}(\mathcal{B})$ and

$$\alpha_1 \vec{b}_1 + \dots + \alpha_n \vec{b}_n + \gamma \vec{v} = \vec{0} \quad \text{④}$$

SHOW $\alpha_1 = \dots = \alpha_n = \gamma = 0$

If $\gamma \neq 0$ Then

$$\vec{v} = -\frac{1}{\gamma} (\alpha_1 \vec{b}_1 + \dots + \alpha_n \vec{b}_n) \in \text{Span}(\mathcal{B})$$

So $\gamma = 0$

Then as $\{\vec{b}_1, \dots, \vec{b}_n\}$ are LI $\text{④} \Rightarrow \alpha_j = 0 \forall j$

\Rightarrow

You do it!

□

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Use contrapositive.

Show $\vec{v} \in \text{Span}(\beta) \Rightarrow B \cup \{\vec{v}\}$ is LD.

Well
By assumption

$$\vec{v} = \sum_{j=1}^n \alpha_j \vec{b}_j$$

So

$$\sum_{j=1}^n \alpha_j \vec{b}_j - 1\vec{v} = \vec{0}$$

is a nontrivial L.C. of n vectors in $B \cup \{\vec{v}\}$. That gives D.

So $B \cup \{\vec{v}\}$ is LD

D

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PROP 12

Suppose $\dim W < \infty$ and $V \subseteq W$ is a VSS

Then $\dim V < \infty$.

PF Suppose $\dim V = \infty$.
CLAIM $\nexists k \in \mathbb{Z} \ni \mathcal{F}_k = \{\vec{v}_1, \dots, \vec{v}_k\} \subseteq V$ LI.

PF BY INDUCTION

$\boxed{k=1}$ $V \neq \{\}$ $\Rightarrow \exists 0 \neq \vec{v}_1 \in V$.

INDUCTION STEP

Let $\mathcal{F}_k = \{\vec{v}_1, \dots, \vec{v}_k\} \subseteq V$ fe LI

Since $\dim V = \infty$, \mathcal{F}_k cannot span V

So $\exists \vec{v}_{k+1} \notin \text{Span}(\mathcal{F}_k)$, $\vec{v}_{k+1} \in V$.

So by LEMMA 11 \mathcal{F}_{k+1} is LI. \square

By claim with $k = \dim W + 1$

\exists LI subset of V (and hence of W) with $\dim W + 1$ elts.

So any basis for W is NOT a MAXIMALLY LI subset for W . \square

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SUBSPACE DIM THM IS

Let V, W be \mathbb{F} VSs with $V \subseteq W$
 Then

$$\textcircled{1} \quad \dim V \leq \dim W$$

$$\textcircled{2} \quad \text{If } \dim V = \dim W \text{ Then } V = W.$$

PF Let $n = \dim V$

\textcircled{1} If $\{\vec{v}_1, \dots, \vec{v}_n\}$ is a basis for V

Then $\{\vec{v}_1, \dots, \vec{v}_n\}$ is a LI subset of V
 and hence of W .

$$\begin{aligned} \text{So } \dim V = n &\leq \# \text{ LIs in MAX LI set for } W \\ &= \dim W \end{aligned}$$

\textcircled{2} If $\dim V = \dim W$ but $V \neq W$

Let $\vec{w} \in W$ with $\vec{w} \notin V$

Let $\{\vec{v}_1, \dots, \vec{v}_n\}$ be basis for V

By Lemma 11 $\{\vec{v}_1, \dots, \vec{v}_n, \vec{w}\}$ is LI in W

$$\text{So } n+1 \leq \text{MAX # LI elts of } W = \dim W$$

$$\begin{aligned} \text{So } \dim V = n &\leq \dim W - 1 \\ &< \dim W \end{aligned} \quad \square$$

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THEORY ON BASES FOR 4 FUNDAMENTAL SUBSPACES '14

Let $\text{Rk } A_{m \times n} = r$ with

$E = PA$ in row echelon form

$\mathcal{H} = \{h_1, \dots, h_{n-r}\}$ set of vectors in \mathbb{R}^n
of $A\vec{x} = \vec{0}$.

Then

① BASIS for $R(A) =$ Set of Basic Cols of A

$$\dim R(A) = r$$

② BASIS for $R(AT) =$ Set of Nonzero rows of E

$$\dim R(AT) = r$$

③ BASIS for $N(A) = \mathcal{H}$

$$\dim N(A) = n - r$$

④ BASIS for $N(AT) =$ Last $m - r$ rows of P

$$\dim N(AT) = m - r.$$

RE. Show Spanning Sets we found in L2 are all \mathbb{Z}
• Convince yourself using Exs.

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COR 15 RANK + NULLITY THMIf A is $m \times n$ Then

$$\dim N(A) + \dim R(A) = n$$

SIMPLEST EX

$$A_{m \times n} = N_r = \begin{bmatrix} I_{r \times r} & 0_{r \times (n-r)} \\ 0_{(m-r) \times r} & 0_{(m-r) \times (n-r)} \end{bmatrix}$$

$$\begin{aligned} \mathbb{R}^n &= \text{Span}\{\vec{e}_1 - \vec{e}_n\} \\ \mathbb{R}^m &= \text{Span}\{\vec{f}_1, \dots, \vec{f}_r\} \end{aligned}$$

$$N(A) = \text{Span}\{\vec{e}_m, \dots, \vec{e}_n\} \text{ has dim } n-r$$

$$R(A) = \text{Span}\{\vec{f}_1, \dots, \vec{f}_r\} \text{ has dim } r.$$

PROP 16 Let V be a VSS of \mathbb{R}^n

$$\text{Then } \exists \{\vec{v}_1, \dots, \vec{v}_n\}: V = \text{Span}\{\vec{v}_1, \dots, \vec{v}_n\}$$

PF By PROP 12, $\dim V < \infty$ So by BASIS CHAR n THM 10, V has a basis \square

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PROP 17 Let V be a VSS of \mathbb{R}^m

Then $\exists m \times n A : R(A) = V$

Pf By Prop 16

$V = \text{Span}\{\vec{v}_1, \dots, \vec{v}_n\}$ for some $\vec{v}_j \in \mathbb{R}^m$

$$= \{ \alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n \mid \alpha_j \in \mathbb{R} \}$$

$$= \{ A\vec{x} \mid \vec{x} \in \mathbb{R}^n \} \quad A = [\vec{v}_1 \dots \vec{v}_n]$$

$$= R(A)$$

□

BASIS EXTN THM 18

Let $V \subseteq W \subseteq \mathbb{R}^N$

Let $\{\vec{v}_1, \dots, \vec{v}_k\}$ be a basis for V

Then \exists vectors $\vec{w}_1, \dots, \vec{w}_l$ in W :

$\{\vec{v}_1, \dots, \vec{v}_k, \vec{w}_1, \dots, \vec{w}_l\}$ is basis for W .

Pf Let $\{\vec{u}_1, \dots, \vec{u}_{k+l}\}$ be any basis for W .

Form $A = [\vec{v}_1, \dots, \vec{v}_k \mid \vec{u}_1, \dots, \vec{u}_{k+l}]$ $R(A) = W$ ✓

The basic cols of A give the desired basis. □