

Program Structure and Data Types

Parts marked with *) are not available for CANalyzer.

Including other Files textually (CAPL Include)

```
Includes
{
    #include "MySource.cin"
}
```

Global Variables, <type> = data type

```
variables
{
    <type>      myVar[=val]; // elementary
    <type>      myArray[10]; // array
    char        myString[20] [= "val"];
}

<type>
► signed      int(16), long(32), int64(64)
► unsigned    byte(8), word(16), dword(32), qword(64)
► Floating point float(64), double(64)
► character   char(8)
► Messages    message <CAN-id> name
                message <DBC-Name> name
► Other types Associative Fields → Help
                Domain specific types → Help
```

Values in round brackets: Number of bits (not in the source code!).

All types are usable as local variables.

`elcount(myString)` returns the array size.

Please note:

- Local variables are implicitly static.
- No program statements prior to variable declarations

Comments

```
... // rest of line is comment
/* all inside is comment */
```

Ctrl-k-c: comment the selected area

Ctrl-k-u: uncomment

Own Types – Enums

Type definition in the variables section:

```
enum eMyEnumType {eMyEnum1 [=1], eMyEnum2 [=2]},
```

Declaration of an enum variable & initialization:

```
enum eMyEnumType gMyEnum = eMyEnum1;
```

Usage:

```
if (gMyEnum == eMyEnum2)
```

Own Types – Structs

Type definition in the variables section:

```
struct MyStructType
{
    int      anInt;
    long     aLong;
};
```

Declaration of a struct variable and initialization:

```
struct MyStructType gMyStruct [= {20, -1}];
```

Program Structure and Data Types - continued

Access to struct members:

```
gMyStruct.aLong = 22;
```

Constants

```
const <type> = <val>;
```

Events

CAPL is 100% event driven, event handler syntax:

```
on <event type> [additional parameter]
{
    // variable declaration
    // program code
}
```

<event type>

a) System Events

- key 'character' or * keyboard events
- timer <tmr> Timer expired
- preStart pre measurement start
- start after measurement start
- stopMeasurement before measurement stop

b) Value Objects

- signal <sig> Signal value changed *)
- signal_update <sig> Signal write access *)
- sysvar <sys> System variable value changed
- sysvar_update <sys> System variable write access
- envvar Value change environment variable

c) Messages

- message <msg> CAN1.frmStatus
- message <id>-<id> 0x100-999
- message * any message
- message [*] All messages, also those that are processed by another event handler in this CAPL source code.

This

Event data can be accessed via `this`.

- | | |
|---|--------------------------------------|
| on key * | this = character |
| on signal | this[.raw] = physical [raw] value *) |
| on message | this.<selector> |
| ► TIME | measurement time |
| ► ID | CAN-ID |
| ► DLC | message length (data) |
| ► DIR | RX, TX |
| ► CAN | channel number |
| ► BYTE(0..7),
WORD(0..6),
DWORD(0..4),
QWORD(0) raw data | |
| ► Signals | |
| on message <msg> | |
| | { |
| | this.sigTemp |

Raw data of the temperature signal is returned (compare to "on signal this"). Physical values are accessed with `.phys`.

C-Syntax

Operators

<code>a = 23 + b;</code>	add and assign
<code>* / -</code>	multiplication, division, subtraction
<code>r = 37 % 7;</code>	modulo division for integer, here: 2
<code>a++;</code>	increment or decrement an integer type
<code>c+=22.0;</code>	increment and assignment
<code>-= *= /=</code>	decrement, multiplication, division and assignment
<code>a==b</code>	comparison operator „equal“
<code><==> >= !=</code>	other comparison operators
<code>! (a<7) && (b>20)</code>	logical not(!), and (&&)
<code> </code>	logical or
<code>& ~</code>	bitwise and, or, complement
<code>^</code>	bitwise exclusive or (XOR)
<code>a = 2<<3;</code>	bit-shift left (afterwards a is 16)
<code>>></code>	bit-shift right

Please note: Don't mix up comparison (==) and assignment (=) operator!

If Decision

```
if (c <= 50)
{
    // if c less or equal to 50
}
```

Optional branches:

```
else if ((c > 50) && (c <= 70))
{
    // if c in ]50,70]
}
```

...

```
else
{ ... } // in all other cases
```

Switch Selection

```
switch (c) // integer
{
    case 50: // if c==50: ...
    ...
    break; // leave this branch
    case 100:
    case 101: // cntr==100 or cntr==101
    break;
    ...
    default: // in all other cases
    break;
}
```

For Loop

for (initialization; condition; modification):

```
int i;
for (i=0; i<10; i=i+1)
{
    // statements
}
```

While Loop

```
while(c<50)
{
    // statements
}
```

C-Syntax - continued

```
do while - loop
Loop is executed at least once
do
{     // statements
} while (c<50);
```

Please note:
Do not implement infinite loops. CANoe must be terminated via task manager.

Functions

```
[<return type>] MyFunction (<type> arg1, ...)
{
    [return [constant | Variable];]
```

return type: int, long, int64, byte, word, dword, float, double
void: no return value

Calling a function

```
[var=]MyFunction([val][,val]...);
```

Signals and system variables as function parameters

```
void MyFunction(signal *sig, sysvar *sys, message *msg)
{
    $sig = 20.0;
    @sys = 20.0;
    $sig = DBLookup(sig).maximum; // see attributes
    output(msg);
}
```

DBLookup([msg|sig]) allows to access database attributes.

CAPL & CANoe

Signals and system variables should be accessed via symbol explorer or per auto-completion.

Signals

```
$<sig> = 1;           phys. signal value is set and with next message
                      it will be sent by the interaction layer.
$<sig>.raw = 1;       assign signal raw data
v = $<sig>[.raw];    access last received Signal[raw] value.
$<sig> =<msg>.<sig>::<text> Access to text table definitions
```

System Variables

Assigning values:
@<sys> = 1;
@sysvar::<sys> is also possible

Reading values:
if (@<sys>==2.0)

Special system variables, arrays:
SysSetVariable<type>(<sys>,buffer[]);
SysGetVariable<type>(<sys>,buffer[],size);
<type>: String, IntArray, LongArray, FloatArray, Data
SysVar with conversion formula also as .raw for raw values.

CAPL & CANoe - continued

Timer

Declaration in the variables section:
msTimer myTmr;

Simple Timer:
setTimer(myTmr, <time>);

Start periodic timer, times in milliseconds:
setTimerCyclic(myTmr,<period>[,first period]);

Stopping
cancelTimer(myTmr);

Check if active:
isTimerActive(myTmr)

Event Handler
on timer myTmr
{ ... }

Messages

Declaration of message variables:
message <*>|id|msg> myMsg;

Modification:
myMsg.<selector> = <val>;

<selector> see section **this**.

Copy messages:
myMsg2 = myMsg1;

or in an event handler (e.g. a gateway)
on message CAN1.*

```
{
    message * myMsg2;
    myMsg2 = this;
    myMsg2.sigA = this.sigA * 2.0;
    myMsg2.CAN = 2;
    output(myMsg); // send
}
```

Attributes

Attribute names with (*) are OEM specific. Vector IL:

```
<msg>.<attribute>
► GenMsgSendType*
► GenMsgCycleTime*
► GenMsgILSupport*
<sig>.<attribute>
► GenSigStartTime*
► GenSigInactiveValue*
► GenSigSendType*
► factor      // for conversion
► offset      // for conversion
► unit        // string
► maximum     // physical
► minimum     // physical
```

Useful CAPL Functions

Write Window

```
► Write window output void write(char format[], ...);
write("Sig phys=%f, Raw=%d", $sig, $sig.raw);
%... = Format expression
%d      decimal          %4d    4 digits
%f      float             %6.2f   6 digits in total, including 2 dec. places
%x      hex               %08X   8 digits, leading zeroes, capital letters
%s      string            for character arrays
```

- writeCreate create a new write window tab → Help
- writeClear clear a write tab → Help
- writeEx extended write → Help
- snprintf output to a string buffer → Help

Interaction Layer (control from within the node)

- Stop message sending
ILDisableMsg(<msg>)
- Activate message sending
ILEnableMsg(<msg>)
- Other:
IL...() → Help

CAPL Tips

- Watch for compiler warnings, enable them all in CANoe options
- Use comments
- Use name prefixes, e.g.
c<Name> constants
g<Name> global variables
ut<Name> utility functions
p<Name> Function parameters
- Avoid complex calculations in conditions (readability, debugging)
Instead: assign intermediate results to local variables
- Even if not needed for single statements after if: use curly brackets
- Event handler should not be a long runner
- Allow reuse with CAPL include files
- Return values should be assigned to local variables.
Their values are visible when debugging

Notation on this Sheet

<>	mandatory
[]	optional or array index
val	value or string
sig	a signal name
sys	a system variable name
var	a CAPL variable
my...	user identifier
msg	message name
→ Help	see online help (F1)

Test Modules ***Structure**

MainTest is called upon test module start and determines the sequence of test cases. Test groups organize the test module structure and reporting.

```
void MainTest()
{
    ... variables declaration
    MyTestcase1(...);
    testGroupBegin (<title>, <description>);
        MyTestcase1(...);

        ...
        MyTestcaseN(...);
    testGroupEnd();
}
```

Functions marked with `testcase` are test cases. They do not have return values.

```
testcase MyTestcase1()
{ ... }
```

Accordance with Simulation Nodes:

- ▶ All event handler
- ▶ C-syntax
- ▶ Data types
- ▶ System variables und signal access

Test verdict

Every test step, test case, test group and the test module has a test result Fail or Pass.

Test cases

Most test cases can be structured logically into three phases:

1. Stimulation: signals, IOs, messages ...
2. Wait for a reaction
3. Evaluation

The phases are made of test steps that set the test verdict:

```
testcase myTestcase()
{
    ...
    testStep<Pass|Fail>("id", "description");
    ...
    testStep ("id", "description"); // w/o verdict
}
```

`id` is a user definable text for identification.

Functions / Test Functions

Frequently used tests should be implemented as test functions or functions (for re-use). Both produce different reporting data.

Stimulation

```
@<sys> = <val>; // system variable
$<sig> = <val>; // with interaction layer
output(<msg>); // local message object
```

Test Modules - continued**Waiting for Events → Help:**

```
long testWaitFor<what>(..., <max time in millisec.>);
<what>
    ▶ Timeout          fixed time span
    ▶ SignalIn/OutSideRange sys / sig value within / outside range
    ▶ SignalMatch      sys / sig value
    ▶ ValueInput       user input
    ▶ Message          message reception
    ▶ TesterConfirmation user confirmation → Help
    ▶ MeasurementEnd   wait for measurement end
```

Return value: 0 = timeout; 1 = event

Evaluation

Using C statements:

```
if ... else ...
```

Better for signals and system variables:

```
testValidateSignalMatch("id", <Sys/Sig>, <val>);
testValidateSignalIn/OutRange -> Help
```

Reporting

```
testCaseTitle
testModuleTitle
teststep[Pass|Fail]("id", "text ...%d text", <var>);
testReportAdd<what>(...)
```

<what>

- ▶ EngineerInfo
- ▶ ExternalRef
- ▶ Image
- ▶ WindowCapture
- ▶ ... → Help

Fault Insertion

From the test module for all simulation nodes

- ▶ TestDisableMessage<(msg)>
- ▶ TestEnableMessage<(msg)>
- ▶ TestEnableCRCCalculation<(msg)>
- ▶ TestResetAllFaultInjections()
- ▶ ... → Help

Background Checks

Configuration: (identification is done with a dword handle)

```
<dword> = ChkCreate_<checktype> (<parameter>)
<Check type>
    ▶ MsgAbsCycleTimeViolation
    ▶ ErrorFramesOccured
    ▶ ... → Help
```

Control:

```
chkControl_<Start|Stop|Reset|Destroy>(<dword>)
```

Evaluation:

```
chkQuery_<what>(<dword>)
```

<what>

- ▶ NumEvents
- ▶ EventStatus
- ▶ ... → Help

Test Modules - continued

Check as constraint (=observation of the test environment) or as condition (=observation of the ECU behavior). Both write events to the report and impact the verdict:

```
testAdd<Condition|Constraint>(<dword[,1]>)
```

With the optional second parameter being 1 the verdict is not influenced.

Stimulations

Create signal value sequences. Creation with

```
<dword> = stmCreate_<what>(<signal>, <parameter>)
```

<what>

- ▶ CSV comma separated values
- ▶ Ramp
- ▶ Toggle
- ▶ ... → Help

Control:

```
stmControl_Start|Stop(<dword>)
```

Diagnostics

Diagnostic objects must be declared. The service qualifier should be inserted via Drag & Drop from the Symbol Explorer:

```
DiagRequest <service qualifier> myReq;
DiagResponse <service qualifier> myResp;
```

Selecting the diagnostic target:

```
DiagSetTarget("<ECU qualifier>");
```

Set a request parameter, the parameter qualifier taken from the Symbol Explorer:

```
diagSetParameter(myReq, "<Parameter>", val);
```

Send:

```
DiagSendRequest(myReq);
```

Wait for a response:

```
int = testWaitForDiagResponse(myName, 10000);
```

Evaluation, the response can be addressed with the request (request and response belong together):

```
double = DiagGetRespParameter(myReq, "Para");
```

Alternative:

```
DiagGetLastResponse(myReq, myResp);
```

Other functions:

- ▶ DiagGetLastResponseCode(myReq) -1 upon positive response, else negative response code
- ▶ DiagGetComplexParameter(...) dynamic data → Help
- ▶ Diag... → Help

Test Module Tips

- ▶ Implement functions for re-use in test cases (readability, maintenance, effort).
- ▶ Check return values and document problems with `TestStepFail()`.