

Program Structure and Data Types

Parts marked with *) are not available for CANalyzer.

Including other Files textually (CAPL Include)

```
Includes
{
    #include "MySource.cin"
}
```

Global Variables, <type> = data type

```
variables
{
    <type>      myVar[=val]; // elementary
    <type>      myArray[10]; // array
    char        myString[20] [= "val"];
}
```

<type>

- ▶ signed int(16), long(32), int64(64)
- ▶ unsigned byte(8), word(16), dword(32), qword(64)
- ▶ Floating point float(64), double(64)
- ▶ character char(8)
- ▶ Messages message <CAN-id> name
 message <DBC-Name> name
- ▶ Other types Associative Fields → Help
 Domain specific types → Help

Values in round brackets: Number of bits (not in the source code!).

All types are usable as local variables.

elcount(myString) returns the array size.

Please note:

- ▶ Local variables are implicitly static.
- ▶ No program statements prior to variable declarations

Comments

```
... // rest of line is comment
/* all inside is comment */
```

Ctrl-k-c: comment the selected area

Ctrl-k-u: uncomment

Own Types – Enums

Type definition in the variables section:

```
enum eMyEnumType {eMyEnum1 [=1], eMyEnum2 [=2]};
```

Declaration of an enum variable & initialization:

```
enum eMyEnumType gMyEnum = eMyEnum1;
```

Usage:

```
if (gMyEnum == eMyEnum2)
```

Own Types – Structs

Type definition in the variables section:

```
struct MyStructType
{
    int    aInt;
    long   aLong;
};
```

Declaration of a struct variable and initialization:

```
struct MyStructType gMyStruct [= {20, -1}];
```

Program Structure and Data Types - continued

Access to struct members:

```
gMyStruct.aLong = 22;
```

Constants

```
const <type> = <val>;
```

Events

CAPL is 100% event driven, event handler syntax:

```
on <event type> [additional parameter]
{
    // variable declaration
    // program code
}
```

<event type>

a) System Events

- ▶ key 'character' or * keyboard events
- ▶ timer <tmr> Timer expired
- ▶ preStart pre measurement start
- ▶ start after measurement start
- ▶ stopMeasurement before measurement stop

b) Value Objects

- ▶ signal <sig> Signal value changed *)
- ▶ signal_update <sig> Signal write access *)
- ▶ sysvar <sys> System variable value changed
- ▶ sysvar_update <sys> System variable write access
- ▶ envvar Value change environment variable

c) Messages

- ▶ message <msg> CAN1.frmStatus
- ▶ message <id>--<id> 0x100-999
- ▶ message * any message

message [*] All messages, also those that are processed by another event handler in this CAPL source code.

This

Event data can be accessed via this.

- on key * this = character
- on signal this[.raw] = physical [raw] value *)
- on message this.<selector>
- ▶ TIME measurement time
- ▶ ID CAN-ID
- ▶ DLC message length (data)
- ▶ DIR RX, TX
- ▶ CAN channel number
- ▶ BYTE(0...7),
WORD(0...6),
DWORD(0...4),
QWORD(0) raw data
- ▶ Signals
 on message <msg>
 {
 this.sigTemp

Raw data of the temperature signal is returned (compare to "on signal this"). Physical values are accessed with .phys.

C-Syntax

Operators

a = 23 + b;	add and assign
* / -	multiplication, division, subtraction
r = 37 % 7;	modulo division for integer, here: 2
a++; b--;	increment or decrement an integer type
c+=22.0;	increment and assignment
-= *= /=	decrement, multiplication, division and assignment
a==b	comparison operator „equal“
< <= > >= !=	other comparison operators
!(a<7) && (b>20)	logical not(!), and (&&)
	logical or
& ~	bitwise and, or, complement
^	bitwise exclusive or (XOR)
a = 2<<3;	bit-shift left (afterwards a is 16)
>>	bit-shift right

Please note: Don't mix up comparison (==) and assignment (=) operator!

If Decision

```
if (c <= 50)
{
    // if c less or equal to 50
}
```

Optional branches:

```
else if ((c > 50) && (c <= 70))
{
    // if c in ]50,70]
}
...
else
{ ... } // in all other cases
```

Switch Selection

```
switch (c)                   // integer
{
    case 50:                 // if c==50: ...
    ...
    break;                  // leave this branch
    case 100:
    case 101:                // cntnr==100 or cntnr==101
    break;
    ...
    default:                 // in all other cases
    break;
}
```

For Loop

for (initialization; condition; modification):

```
int i;
for (i=0; i<10; i=i+1)
{
    // statements
}
```

While Loop

```
while(c<50)
{
    // statements
}
```

C-Syntax - continued

do while – loop

Loop is executed at least once

```
do
{
    // statements
} while (c<50);
```

Please note:

Do not implement infinite loops. CANoe must be terminated via task manager.

Functions

```
[<return type>] MyFunction (<type> arg1, ...)
{
    [return [constant | Variable];]
}
```

return type: int, long, int64, byte, word, dword, float, double
void: no return value

Calling a function

```
[var=]MyFunction([val][,val]...);
```

Signals and system variables as function parameters

```
void MyFunction(signal *sig, sysvar * sys, message * msg)
{
    $sig = 20.0;
    @sys = 20.0;
    $sig = DBLookup(sig).maximum; // see attributes
    output(msg);
}
```

DBlookup([msg|sig]) allows to access database attributes.

CAPL & CANoe

Signals and system variables should be accessed via symbol explorer or per auto-completion.

Signals

\$<sig> = 1; phys. signal value is set and with next message
 it will be sent by the interaction layer.

\$<sig>.raw = 1; assign signal raw data

v = \$<sig>[.raw]; access last received Signal[raw] value.

\$<sig> =<msg>.<sig>::<text> Physical values are of type double.

\$<sig> =<msg>.<sig>::<text> Access to text table definitions

System Variables

Assigning values:

```
@<sys> = 1;
@sysvar::<sys> is also possible
```

Reading values:

```
if (@<sys>==2.0)
```

Special system variables, arrays:

```
SysSetVariable<type>(<sys>,buffer[]);
SysGetVariable<type>(<sys>,buffer[],size);
```

<type>: String, IntArray, LongArray, FloatArray, Data

SysVar with conversion formula also as .raw for raw values.

CAPL & CANoe - continued

Timer

Declaration in the variables section:

```
mTimer myTmr;
```

Simple Timer:

```
setTimer(myTmr, <time>);
```

Start periodic timer, times in milliseconds:

```
setTimerCyclic(myTmr,<period>[,first period]);
```

Stopping

```
cancelTimer(myTmr);
```

Check if active:

```
isTimerActive(myTmr)
```

Event Handler

```
on timer myTmr
{ ... }
```

Messages

Declaration of message variables:

```
message <*<id>msg> myMsg;
```

Modification:

```
myMsg.<selector> = <val>;
```

<selector> see section this.

Copy messages:

```
myMsg2 = myMsg1;
```

or in an event handler (e.g. a gateway)

```
on message CAN1.*
{
    message * myMsg2;
    myMsg2 = this;
    myMsg2.sigA = this.sigA * 2.0;
    myMsg2.CAN = 2;
    output(myMsg); // send
}
```

Attributes

Attribute names with (*) are OEM specific. Vector IL:

```
<msg>.<attribute>
```

- ▶ GenMsgSendType*
- ▶ GenMsgCycleTime*
- ▶ GenMsgILSupport*

```
<sig>.<attribute>
```

- ▶ GenSigStartValue*
- ▶ GenSigInactiveValue*
- ▶ GenSigSendType*
- ▶ factor // for conversion
- ▶ offset // for conversion
- ▶ unit // string
- ▶ maximum // physical
- ▶ minimum // physical

Useful CAPL Functions

Write Window

▶ Write window output void write(char format[], ...);

```
write("Sig phys=%f, Raw=%d", $sig, $sig.raw);
```

%... = Format expression

%d	decimal	%4d	4 digits
%f	float	%6.2f	6 digits in total, including 2 dec. places
%x	hex	%08X	8 digits, leading zeroes, capital letters
%s	string		for character arrays

▶ writeCreate create a new write window tab → Help

▶ writeClear clear a write tab → Help

▶ writeEx extended write → Help

▶ sprintf output to a string buffer → Help

Interaction Layer (control from within the node)

▶ Stop message sending

```
ILDisableMsg(<msg>)
```

▶ Activate message sending

```
ILEnableMsg(<msg>)
```

▶ Other:

```
IL...() → Help
```

CAPL Tips

▶ Watch for compiler warnings, enable them all in CANoe options

▶ Use comments

▶ Use name prefixes, e.g.

c<Name> constants

g<Name> global variables

ut<Name> utility functions

p<Name> Function parameters

▶ Avoid complex calculations in conditions (readability, debugging)

Instead: assign intermediate results to local variables

▶ Even if not needed for single statements after if: use curly brackets

▶ Event handler should not be a long runner

▶ Allow reuse with CAPL include files

▶ Return values should be assigned to local variables.

Their values are visible when debugging.

Notation on this Sheet

<>	mandatory
[]	optional or array index
val	value or string
sig	a signal name
sys	a system variable name
var	a CAPL variable
my...	user identifier
msg	message name
→ Help	see online help (F1)

Test Modules *)

Structure

MainTest is called upon test module start and determines the sequence of test cases. Test groups organize the test module structure and reporting.

```
void MainTest()
{
    ... variables declaration
    MyTestcase1 (...);
    testGroupBegin (<title>, <description>);
        MyTestcase1 (...);
        ...
        MyTestcaseN (...);
    testGroupEnd();
}
```

Functions marked with `testcase` are test cases. They do not have return values.

```
testcase MyTestcase1()
{ ... }
```

Accordance with Simulation Nodes:

- ▶ All event handler
- ▶ C-syntax
- ▶ Data types
- ▶ System variables und signal access

Test verdict

Every test step, test case, test group and the test module has a test result Fail or Pass.

Test cases

Most test cases can be structured logically into three phases:

1. Stimulation: signals, IOs, messages ...
2. Wait for a reaction
3. Evaluation

The phases are made of test steps that set the test verdict:

```
testcase myTestcase()
{
    ...
    testStep<Pass|Fail>("id", "description");
    ...
    testStep ("id", "description"); // w/o verdict
}
```

id is a user definable text for identification.

Functions / Test Functions

Frequently used tests should be implemented as test functions or functions (for re-use). Both produce different reporting data.

Stimulation

```
@<sys> = <val>; // system variable
$<sig> = <val>; // with interaction layer
output(<msg>); // local message object
```

Test Modules - continued

Waiting for Events → Help:

```
long testWaitFor<what>(..., <max time in millisec.>);
<what>
```

- ▶ Timeout fixed time span
- ▶ SignalIn/OutSideRange sys / sig value within / outside range
- ▶ SignalMatch sys / sig value
- ▶ ValueInput user input
- ▶ Message message reception
- ▶ TesterConfirmation user confirmation → Help
- ▶ MeasurementEnd wait for measurement end

Return value: 0 = timeout; 1 = event

Evaluation

Using C statements:

```
if ... else ...
```

Better for signals and system variables:

```
testValidateSignalMatch("id", <Sys/Sig>, <val>);
testValidateSignalIn/OutRange -> Help
```

Reporting

```
testCaseTitle
testModuleTitle
teststep[Pass|Fail]("id", "text ...%d text", <var>);
testreportAdd<what>(...)
```

<what>

- ▶ EngineerInfo
- ▶ ExternalRef
- ▶ Image
- ▶ WindowCapture
- ▶ ... → Help

Fault Insertion

From the test module for all simulation nodes

- ▶ TestDisableMessage(<msg>)
- ▶ TestEnableMessage(<msg>)
- ▶ TestEnableCRCCalculation(<msg>)
- ▶ TestResetAllFaultInjections()
- ▶ ... → Help

Background Checks

Configuration: (identification is done with a dword handle)

```
<dword> = ChkCreate_<checktype> (<parameter>)
```

<Check type>

- ▶ MsgAbsCycleTimeViolation
- ▶ ErrorFramesOccured
- ▶ ... → Help

Control:

```
chkControl_<Start|Stop|Reset|Destroy>(<dword>)
```

Evaluation:

```
chkQuery_<what>(<dword>)
```

<what>

- ▶ NumEvents
- ▶ EventStatus
- ▶ ... → Help

Test Modules - continued

Check as constraint (=observation of the test environment) or as condition (=observation of the ECU behavior). Both write events to the report and impact the verdict:

```
testAdd<Condition|Constraint>(dword[, 1])
```

With the optional second parameter being 1 the verdict is not influenced.

Stimulations

Create signal value sequences. Creation with

```
<dword> = stmCreate_<what>(<signal>, <parameter>)
```

<what>

- ▶ CSV comma separated values
- ▶ Ramp
- ▶ Toggle
- ▶ ... → Help

Control:

```
stmControl_Start|Stop(<dword>)
```

Diagnostics

Diagnostic objects must be declared. The service qualifier should be inserted via Drag & Drop from the Symbol Explorer:

```
DiagRequest <service qualifier> myReq;
DiagResponse <service qualifier> myResp;
```

Selecting the diagnostic target:

```
DiagSetTarget("<ECU qualifier>");
```

Set a request parameter, the parameter qualifier taken from the Symbol Explorer:

```
diagSetParameter(myReq, "<Parameter>", val);
```

Send:

```
DiagSendRequest(myReq);
```

Wait for a response:

```
int = testWaitForDiagResponse(myName, 10000);
```

Evaluation, the response can be addressed with the request (request and response belong together):

```
double = DiagGetRespParameter(myReq, "Para");
```

Alternative:

```
DiagGetLastResponse(myReq, myResp);
```

Other functions:

- ▶ DiagGetLastResponseCode(myReq) -1 upon positive response, else negative response code
- ▶ DiagGetComplexParameter(...) dynamic data → Help
- ▶ Diag... → Help

Test Module Tips

- ▶ Implement functions for re-use in test cases (readability, maintenance, effort).
- ▶ Check return values and document problems with TestStepFail().