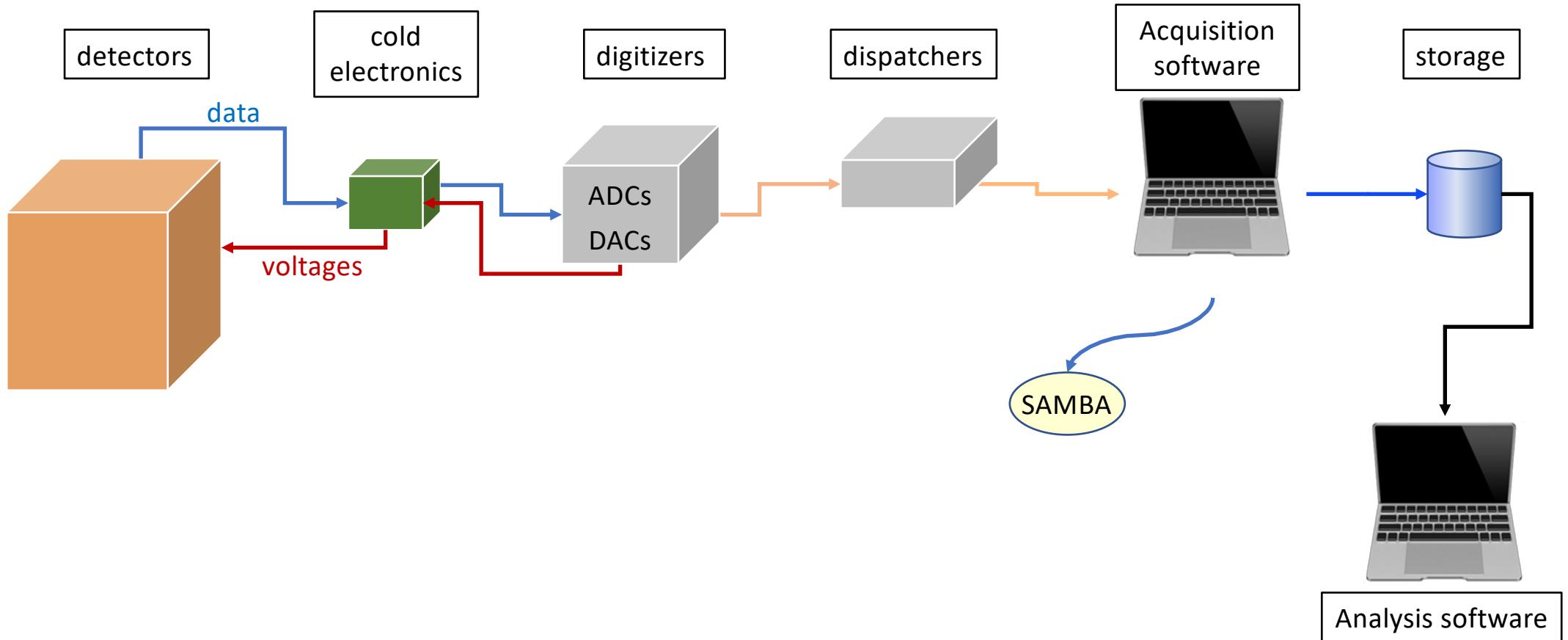


entering inside

SAMBA

The Acquisition chain



User-defined Data Acquisition Software:

- A nice goal to reach!
- Are we so far?
- Is there some experience which can we benefit from?

SAMBA:
Système d'Acquisition Multi-Bolomètres (sur Apple)

- ✓ acquire and store data;
- ✓ select events and analyse;
- ✓ DAQ management, runs management.

TANGO:
Traitement et Analyse Nouvelle Génération Online

extensive use of the software

- more flexibility for
 - all parameters like number of channels, actual setup, ...;
 - data processing;
 - trigger methods.
- more scalability for the electronics part:
 - adapted and controlled structure;
 - simpler and smaller boxes;
 - cheaper setup.

=> more potential for **developments**

=> more potential for **distribution** (test-benches)

- ✓ event reconstruction (ntuple amplitude, rise time, ...);
- ✓ interactive cuts;
- ✓ various interactive plots (histos, fits, biplots,...);

- Cumulated knowledge: since 2005;
- Large number of integrated functionnalities,
- Meets the following wide requirements:

Hardware :

- ✓ Multiples detectors (user-defined), of multiples types (user-defined);
- ✓ Multiples channels per detector (user-defined), of multiples types (user-defined);
- ✓ Multiples cabling sketches (user-defined);
- ✓ Multiples ADC + DAC boxes, of multiple type (user-defined);
- ✓ All this setup is defined through external text files, and experiment-independant;
- ✓ Management of the setup through GUI or by editing these text files;
- ✓ 5 dispatching systems type supported; IP systems to be « generic »;
- ✓ synchronisation of the computers, if several are needed.

Detector Preparation :

- Individual or for a selection;
- Definitions through GUI or by editing user-defined text files:
 - processings,
 - triggering,
 - disk writing;
- Automatic sequences from user-defined scripts.

Adjusting :

- Power spectrum for the electronic noise (for origin identification);
- Mode « oscilloscope »;
- Individual operation and control, for each élément (detector, digitizer, data dispatching).

Data taking :

- The whole data are available (stream mode);
- Library of various ready-to-use algorithms :
 - processings :
 - filtering (butterworth, chebyshev, elliptic),
 - smoothing,
 - event template convolution (analytic or tabulated),
 - demodulation,
 - mean value,
 - maximum by intervals;
 - triggering:
 - threshold,
 - amplitude+rise time,
 - derivative,
 - duration,
 - Random;
- Data storage: stream and/or by event
- *Processing, events and storage are user-defined per channel*

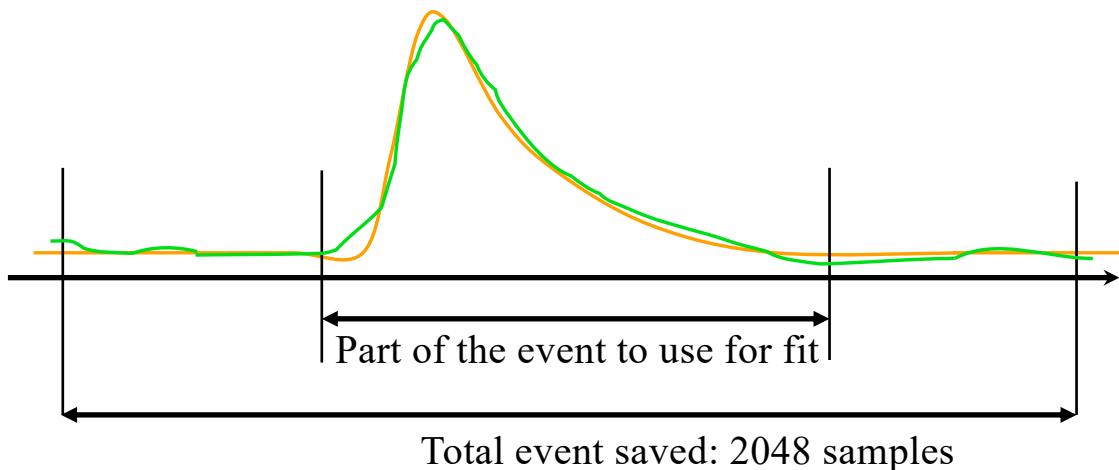
- Example of a supplementary functionality: the *pseudo channels*
 - additional software channels may be defined after the hardware ones;
 - a ‘pseudo channel’ may be any linear combination of the previously defined channels (from the same detector);
 - this pseudo channel may receive any parameter just like the hardware ones: processing, event definition, trigger logic,...
 - application #1: a copy of a channel allows to process/save the signal in 2 formats:
pseudo fastA = ionisA
 - application #2: the trigger logic is applied to a combination of the 2 similar channels:
pseudo sHeat = “0.7 x heatA + 0.3 x heatB”
 - *user interface to be defined.*
- Example of a supplementary feature: the *random trigger*
 - Free parameters:
 - Event rate;
 - Delay fluctuation.
 - Defined on a channel basis;
 - Replaces any other trigger logic for this channel.
- User scripts
 - User-defined functions called at various times of the experiment life.

- Example of a supplementary algorithm: the trigger logic

Improvement 1: automatically compute the appropriate threshold after the current noise (“**adaptative trigger**”).

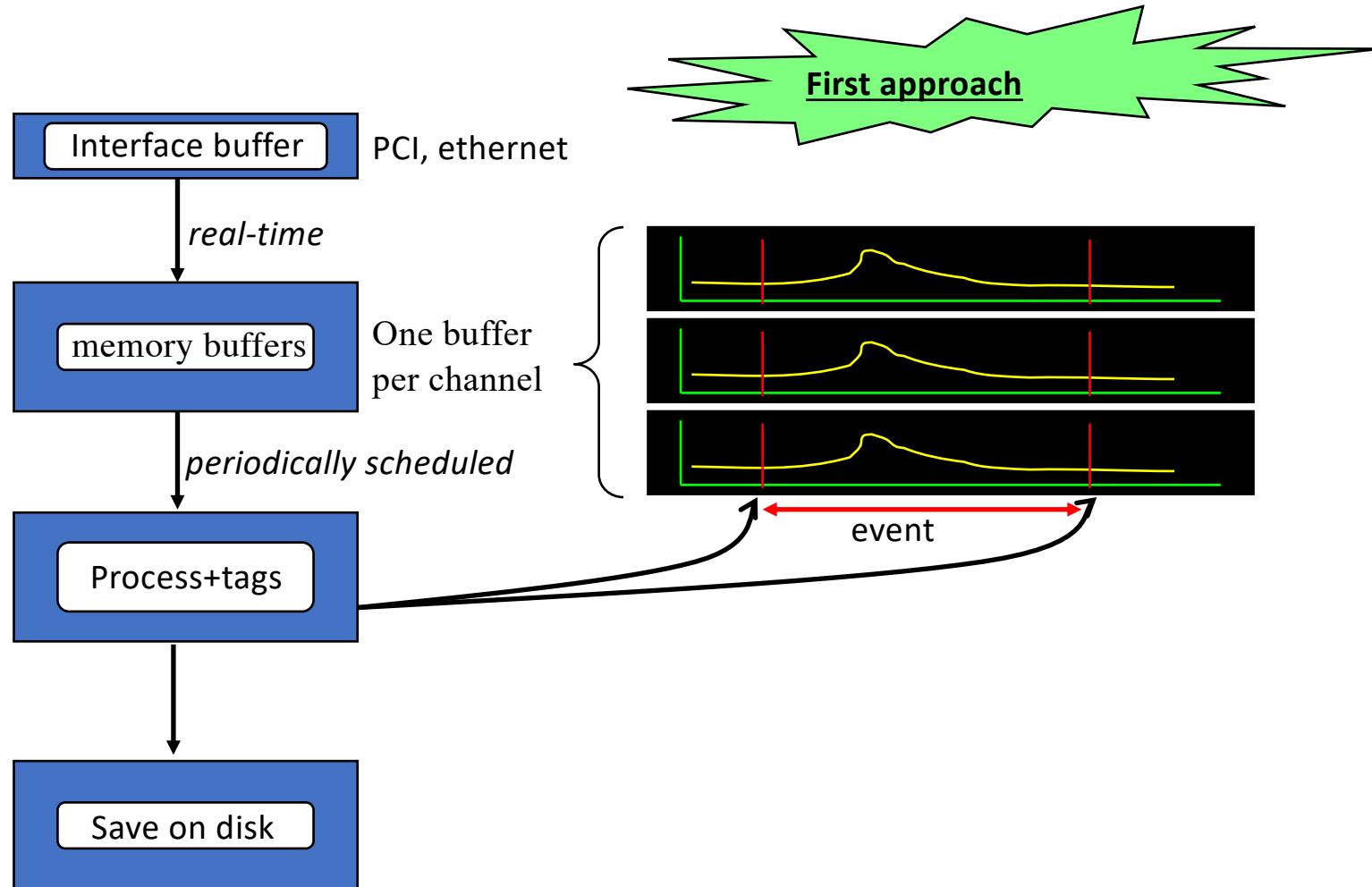
Problem: at low level, threshold oscillate (data are integer), and final analysis threshold are higher than could be expected from acquisition noise.

Improvement 2: direct fit with a pulse shape (analytic or tabulated) = sliding **template convolution**.

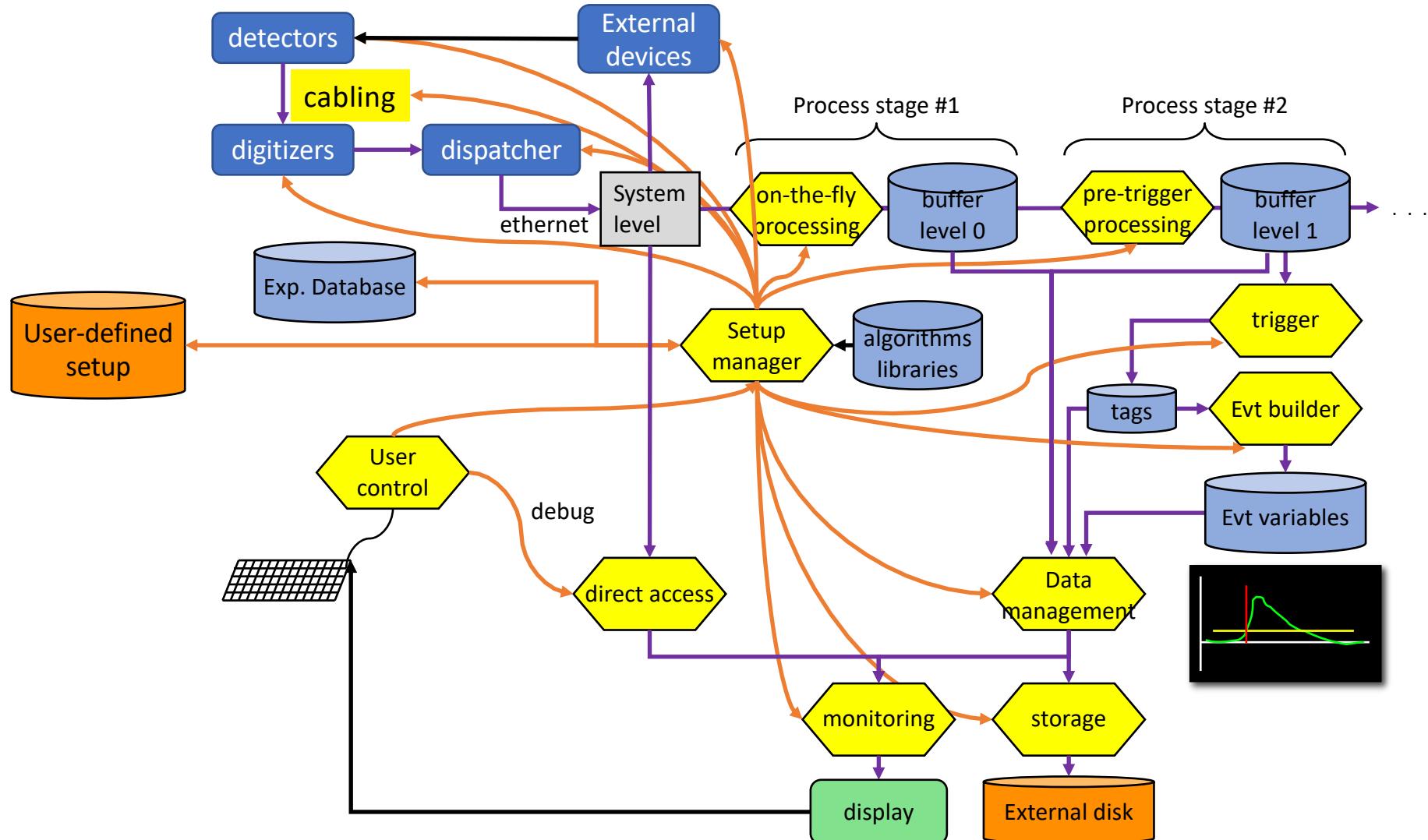


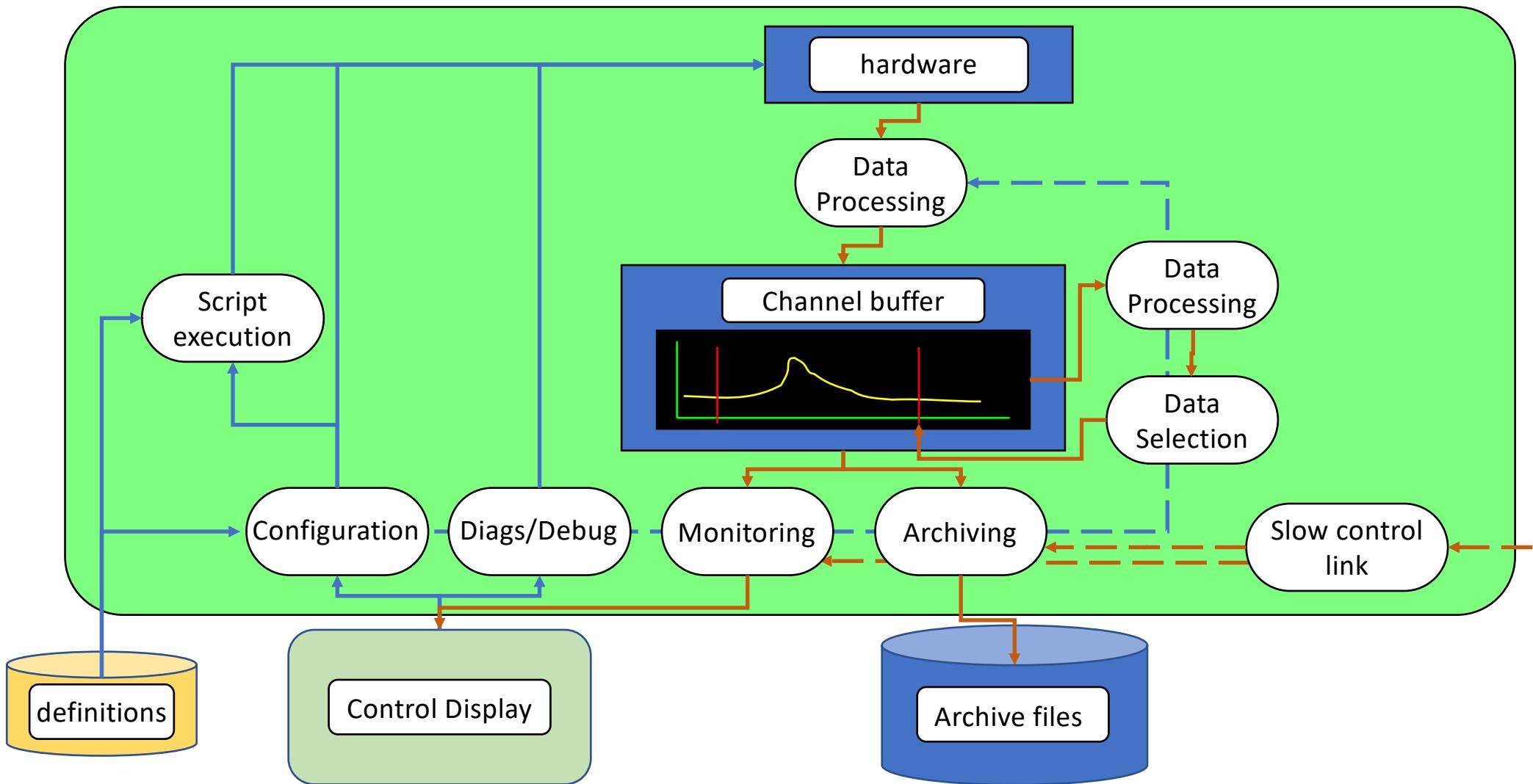
- User definition with either *text files* or *graphic user interface* for
 - all the **hardware** (detectors, digitizers, dispatchers, cabling),
 - all processing parameters (**event** definition, data **processes**, triggering, data **storage**),
 - live **plots**;
- Wide-range complex built-in **procedures**;
 - Activating the electronics,
 - Noise power **Spectra**;
- **User scripts** (in text files) to set up the electronics, or for periodic procedures (loops, waits, ...);
- **Dashboards** for electronics surveillance;
- **Low-level connexions** for hardware diagnostics and debugging;
- Algorithms **library** (processings, trigger);
- **Ntuple** storage on a text file (with the first line as a header);
- Mode “**oscilloscope**” with threshold trigger and amplitude histogram;
- **Calendar** for data taking;
- **Plots saving** with improved quality, in JPEG format.

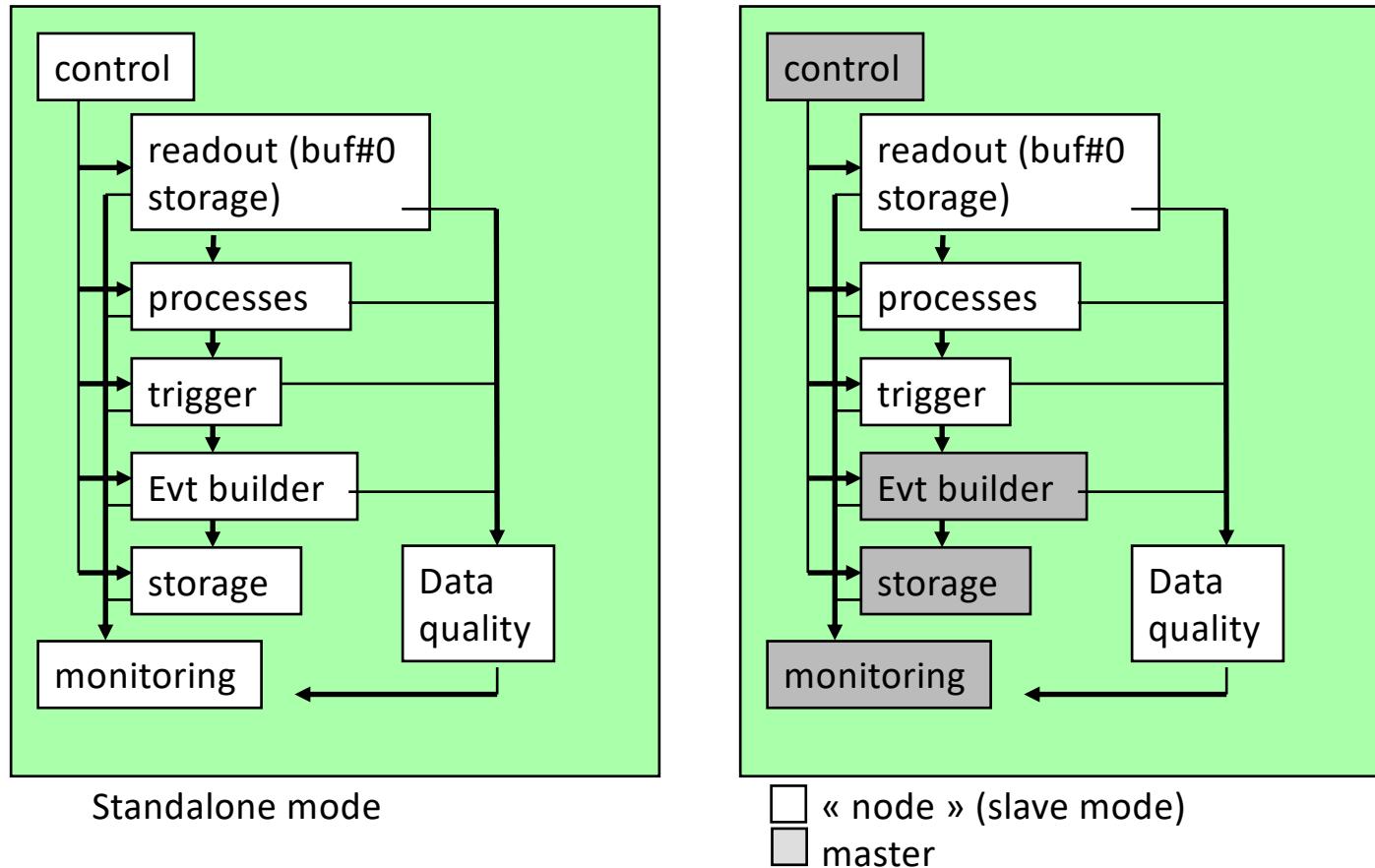
➤ Samba is spread to experiments as different as EDELWEISS, CUPID-MO, NEWS-G, R2D2.

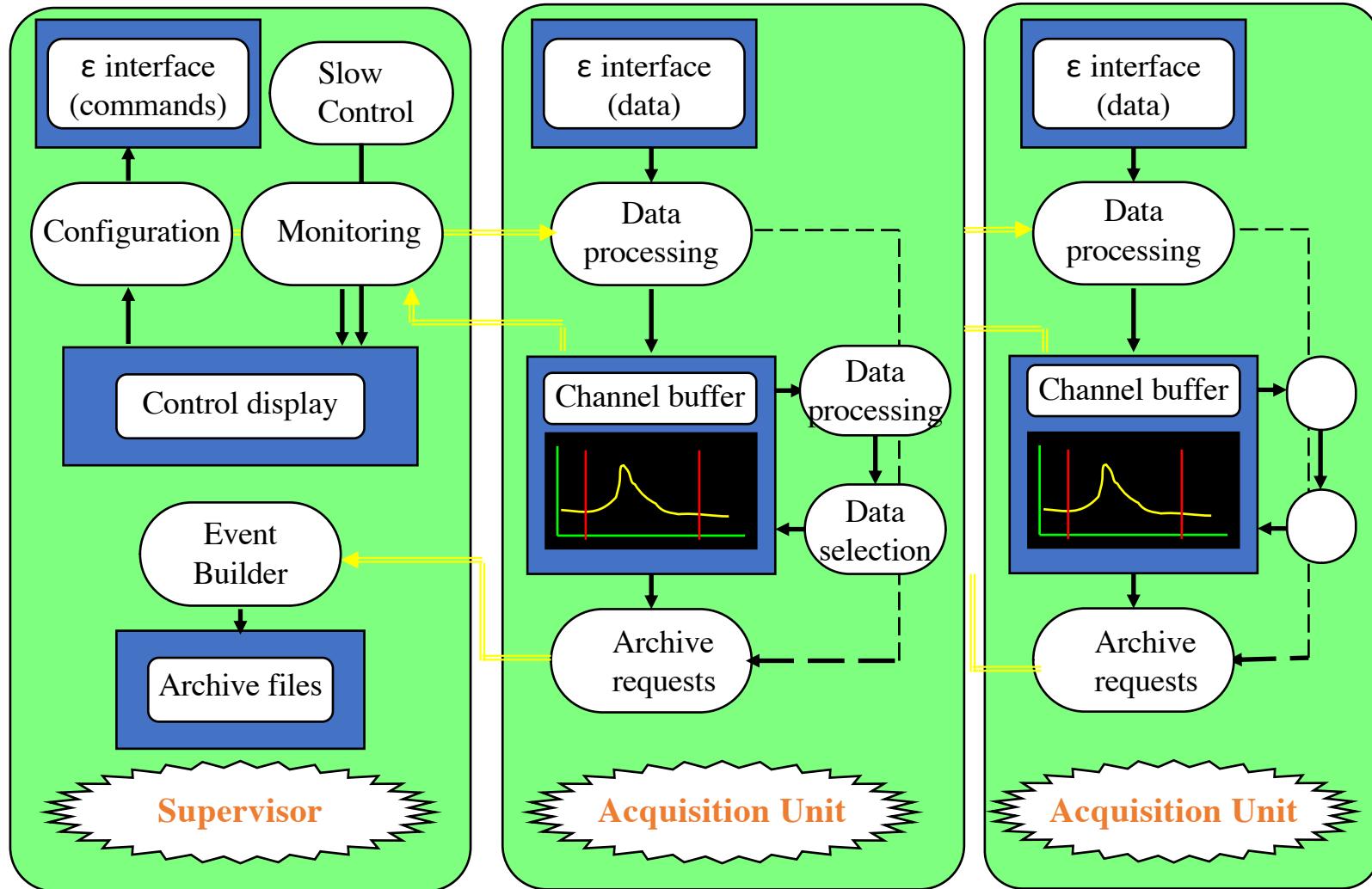


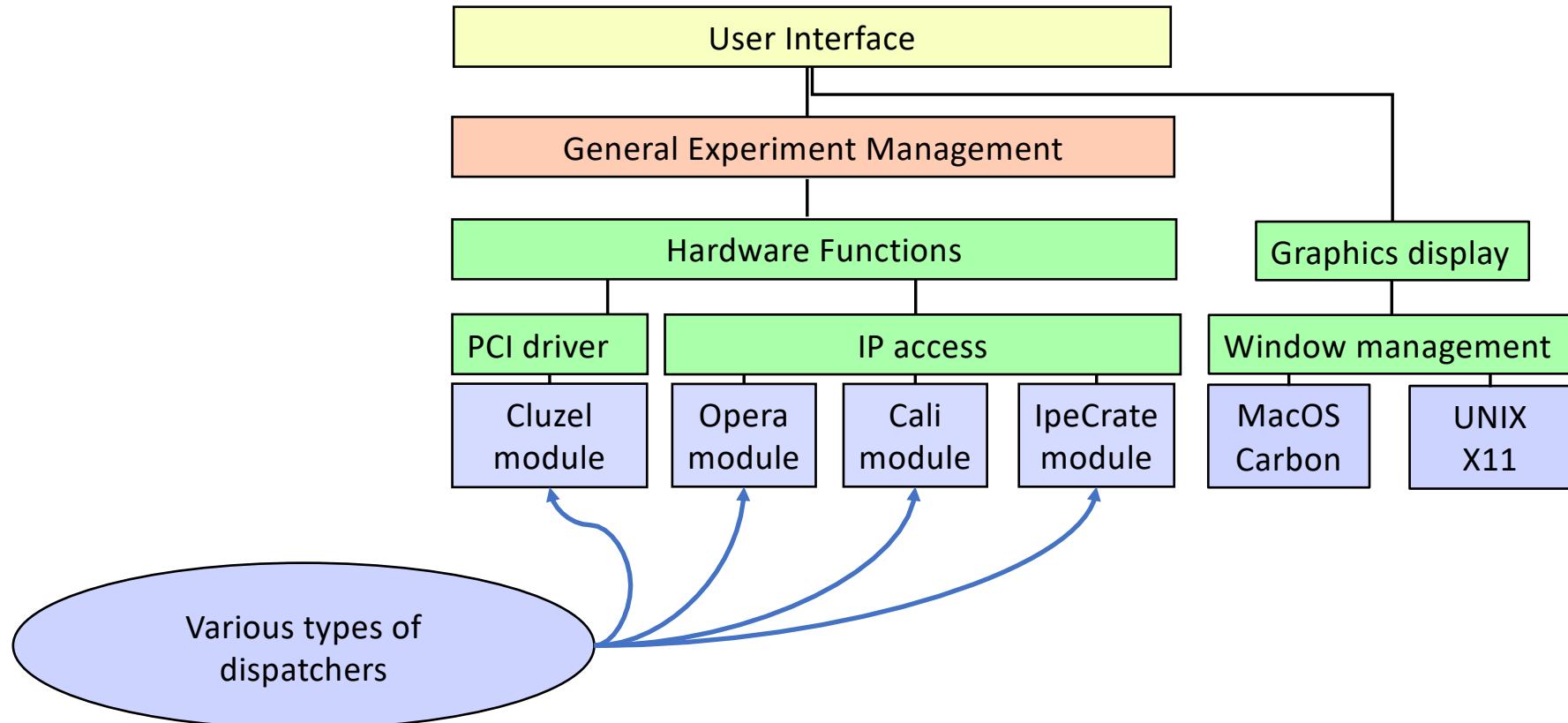
The Data travel, from detector to disk

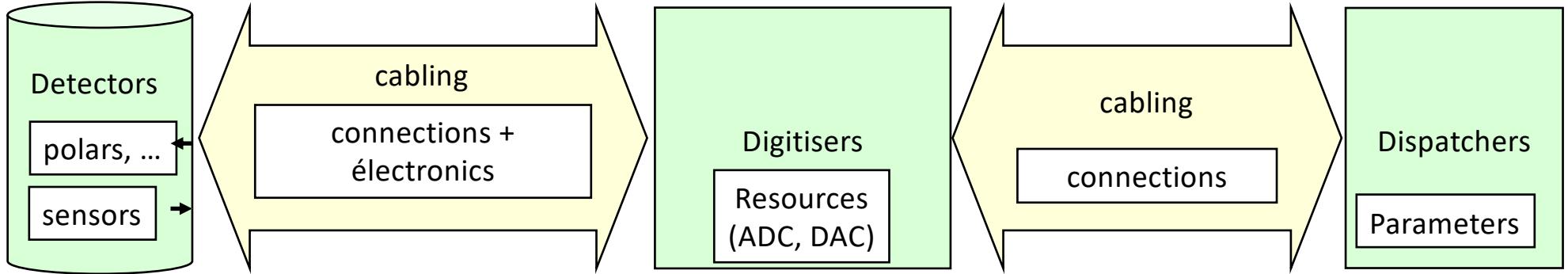




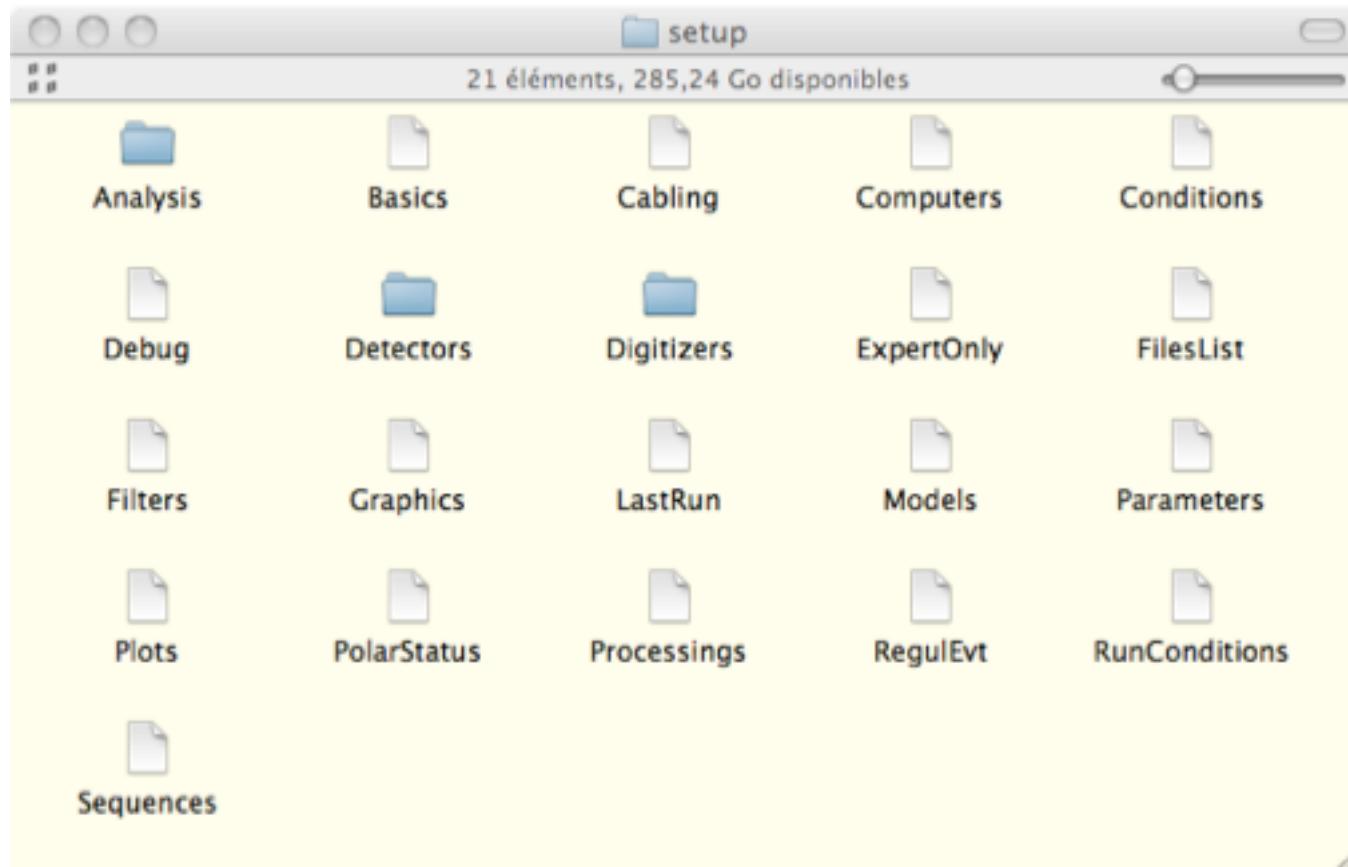








- hardware which are defined by a **same list of parameters** and channels are said to be of **same type**
 - all LMO detectors have the same list; all BBv2 as well*
- establishing a list of variables for a given type turns to define a **model**
 - models of detectors: *ID, FID, LMO*; digitizers: *BBv1, BBv3*; cabling: *LMO-BB1BB3*; dispatchers
- managing external information is part of the User Interface.**
 - the User Interface Library has been improved to handle complex structured data*
- all models of **detectors**, of **digitisers**, and ways of **cabling** them, are **user defined**
 - !! every family of dispatcher need a specific support (pre-defined library)*



```

Detector FullSphere = {
    sensors = ( ball, umbrella, light )
    settings = (
        { HVb := sensor = ball, category = polar },
        { HVu := sensor = umbrella, category = polar }
    )
}

Digitizer CaliADC = {
    resources = (
        { DAC1 := category = polar, address = 0x04, masque = 0xFFFF,
            unit = Volts, encode = float,
            float.min = 0.0, float.max = 8000.0 },
        { DAC2 := category = polar, address = 0x08, masque = 0xFFFF,
            unit = Volts, encode = float,
            float.min = 0.0, float.max = 8000.0 }
    )
}

Cabling = (
    { full_std := detector = FullSphere, digitizers = ( CaliADC ),
        sensors = ( { ball := 1.1 }, { umbrella := 1.2 } ),
        settings = ( { HVb := DAC1 }, { HVu := DAC2 } )
}

```

<u>blue</u> :	your own
<u>green</u> :	user value
	<i>! from your previous defs</i>
<u>black</u> :	Samba lexics
<u>orange</u> :	user values
	<i>! from Samba keywords</i>

```

{ CupidHV := sensors = ( chaleur, lumiere ), settings = (
    { ampl-chaleur := categorie = modulation, sensor = chaleur },
    { comp-chaleur := categorie = compensation, sensor = chaleur },
    { corr-chaleur := categorie = correction, sensor = chaleur },
    { gain-chaleur := categorie = gain, sensor = chaleur },
    { polP := categorie = polar, sensor = chaleur },
    { d2C := categorie = d2, sensor = chaleur },
    { d3C := categorie = d3, sensor = chaleur },
    { raz-chaleur := categorie = razfet, sensor = chaleur },
    { polM := categorie = polar, sensor = chaleur },
    { ampl-lumiere := categorie = modulation, sensor = lumiere },
    { comp-lumiere := categorie = compensation, sensor = lumiere },
    { corr-lumiere := categorie = correction, sensor = lumiere },
    { gain-lumiere := categorie = gain, sensor = lumiere },
    { d2L := categorie = d2, sensor = lumiere },
    { d3L := categorie = d3, sensor = lumiere },
    { raz-lumiere := categorie = razfet, sensor = lumiere },
    { rPol := categorie = relais, sensor = lumiere },
    { rFB := categorie = relais, sensor = lumiere }
), regeneration = non },

{ lvoie := sensors = ( signal ), settings = () },
{ veto := sensors = ( hits, stampHi, stampMi, stampLo ), settings = () }

```

<u>blue</u> :	your own
<u>green</u> :	user value
	<i>! from your previous defs</i>
<u>black</u> :	Samba lexics
<u>orange</u> :	user values
	<i>! from Samba keywords</i>

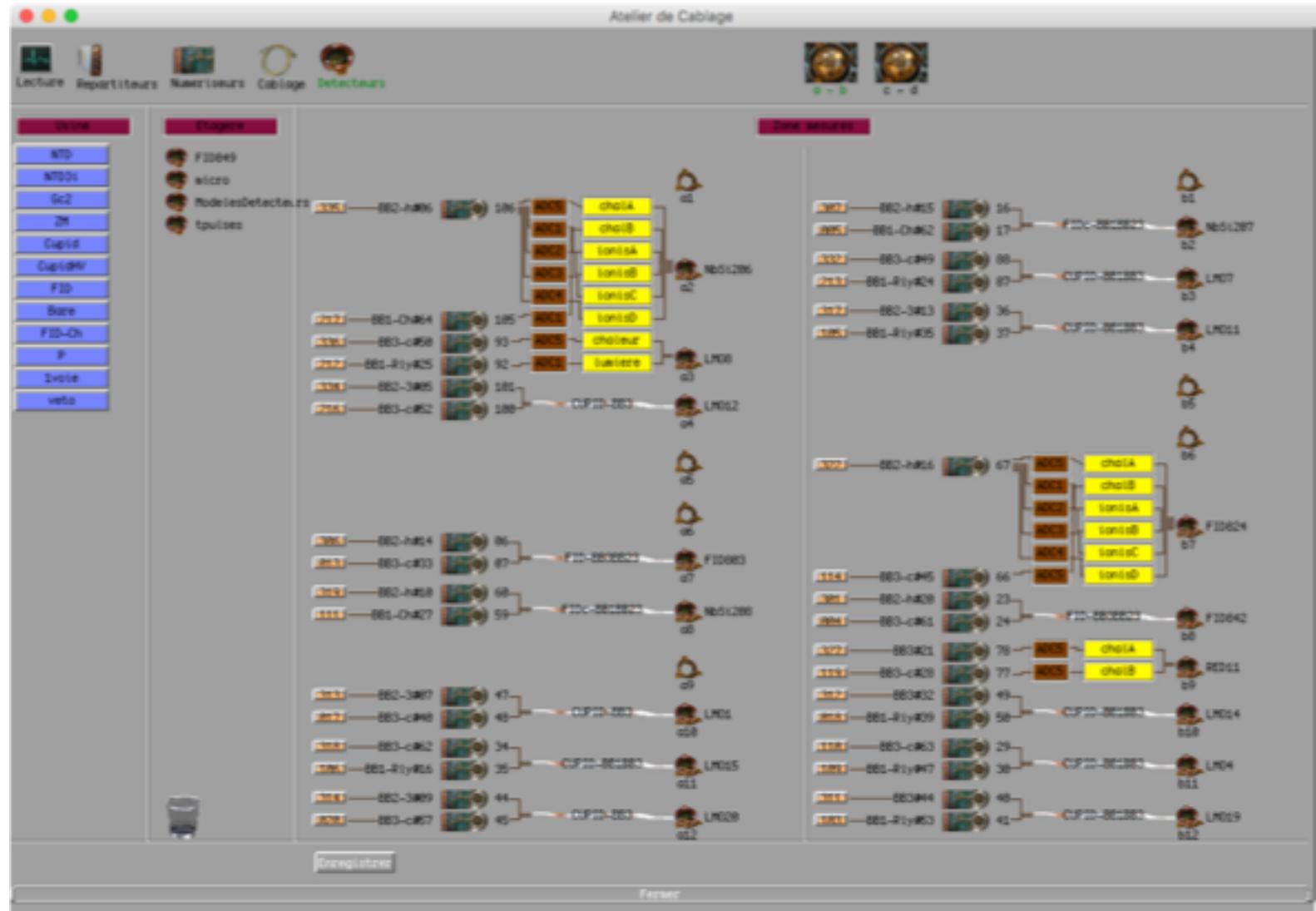
```

LMO1 := modele = CupidHV, status = ok # (HS/ok)
reglages chaleur = {
    ampl-chaleur = 2.000
    comp-chaleur = 0.000
    corr-chaleur = 99.804
    gain-chaleur = 2
    d2C = 200
    d3C = 500
    raz-chaleur = libre
}
evenement chaleur = {
    duree = 2048           # Duree evenement (millisec.)
    delai = 0              # Decalage evenement (millisec.)
    interv = 10             # Fenetre de recherche (millisec.)
    pre-trigger = 50        # Pre-trigger (%)
    temps-mort = -1         # Temps mort avant nouvelle recherche (millisec.)
}
trigger chaleur = {
    type = seuil           # Type de recherche d'evenement (neant/seuil/front/porte/bruit)
    signe = positif          # Sens de la variation attendue (negatif/indifferent/positif)
    regulation = non          # Autorisation de reguler automatiquement
    amplitude.min = 100        # Amplitude minimum pour impulsions positives (ADU)
    amplitude.max = -10        # Amplitude maximum pour impulsions negatives (ADU)
}

```

<u>blue</u> :	your own
<u>green</u> :	user value
	<i>! from your previous defs</i>
<u>black</u> :	Samba lexics
<u>orange</u> :	user values
	<i>! from Samba keywords</i>

Graphic interface for the setup definition



Graphic interface for the setup definition



Fully configurable setup: the plots to display (or not)

```
+ high amplitude sensor signal /form=signal /duration=20/limits=500 1000  
    /dimensions=334 240/position=783 607/display=yes/grid=no /data=  
    sensor s50b raw          (0000 FFFF 0000)  
    laser  s50b raw          (7FFD 7FFD 0000)  
  
+ low amplitude sensor /form=signal /duration=20/limits=-3000 -2000  
    /dimensions=364 244/position=403 609/display=yes/grid=no /data=  
    sensor s50b raw          (0000 FFFF 0000)  
  
+ baseline RMS /form=histo /bins=200/evts=0/limits=0 100  
    /dimensions=318 296/position=890 45/display=yes/grid=no /data=  
    noise   sensor s50b      (0000 FFFF 0000)  
+ high amplitudes /form=histo /bins=200/evts=0/limits=0 40000  
    /dimensions=200 200/position=599 360/display=yes/grid=no /data=  
    amplitude sensor s50b    (0000 FFFF 0000)  
  
+ Laser trigger /form=signal /duration=2/limits=45 85  
    /dimensions=368 205/position=1028 365/display=yes/grid=no /data=  
    laser  s50b raw          (0000 FFFF 0000)  
  
+ frequency spectrum /form=fft /freq-min=0.1/freq-max=100/echantillons=1024/axeX=log  
    /limits=0.1 100/dimensions=299 292/position=882 44/grid=yes /data=  
    sensor s50b raw          (0000 0000 BFFE)
```

```
Variables = (
    { Type := mot-cle, liste = labo/calibration/fond/debug, description = "Type du run" },
    { HV1 := int, description = "Tension capteur HV1 (V)" },
    { HV2 := int, description = "Tension correcteur de champ HV2 (V)" },
    { Pression_mb := float, description = "Pression totale (mb) " },
    { Gaz := mot-cle, liste = He/Ne/Ar/Xe/N2, description = "Gaz principal " },
    { Quencher := mot-cle, liste = CH4, description = "Moderateur " },
    { Taux := float, description = "Quantite relative de moderateur (%)" },
    { Source := mot-cle, liste = neant/ar37/fe55, description = "Source de calibration en place" },
    { Blindage := mot-cle, liste = "absent/ouvert/ferme", description = "Configuration du blindage" }
)
```



```
Type = labo          # Type du run
HV1 = 0             # Tension capteur HV1 (V)
HV2 = 0             # Tension correcteur de champ HV2 (V)
Pression_mb = 0     # Pression totale (mb)
Gaz = He            # Gaz principal
Quencher = CH4      # Moderateur
Taux = 0.7          # Quantite relative de moderateur (%)
Source = neant       # Source de calibration en place
Blidage = absent     # Configuration du blindage
```

```
utilise = (
    { Hc1 := "hauteur suspension 1", unite = , archive = no, display = no, format = float, min = 0.0, max = 0.0 },
    { Hc2 := "hauteur suspension 2", unite = , archive = no, display = no, format = float, min = 0.0, max = 0.0 },
    { Hc3 := "hauteur suspension 3", unite = , archive = no, display = no, format = float, min = 0.0, max = 0.0 },
    { Hc4 := "hauteur suspension 4", unite = , archive = no, display = no, format = float, min = 0.0, max = 0.0 },
    { S_i := S_i, unite = , archive = no, display = float, min = 0, max = 0 },
    { T_Bolo := "T bolo", unite = , archive = no, display = cadrant, format = float, min = 0.0, max = 0.05 },
    { T_Speer := "T speer", unite = , archive = no, display = cadrant, format = float, min = 0.0, max = 0.05 },
    { P_regul := "P regul", unite = , archive = no, display = cadrant, format = float, min = 0.0, max = 10.0 },
    { Ba_grotte := "Calibration grotte", unite = , archive = no, display = voyant, format = bool, },
    { Ba_nemo := "Calibration Nemo", unite = , archive = no, display = voyant, format = bool, },
    { Co_France := "Regeneration France", unite = , archive = no, display = voyant, format = bool, },
    { Co_Italie := "Regeneration Italie", unite = , archive = no, display = voyant, format = bool, }
)
sources = (
    { Ba_grotte := calib-grotte, role = calib },
    { Ba_nemo := calib-nemo, role = calib },
    { Co_France := regen-france, role = regen },
    { Co_Italie := regen-italie, role = regen }
)
autorisees = no      # Autorisation de deplacer les sources
```

red: user value from
the slow-control

```
Exports = (
{
    support = fichier          # Support d'envoi (fichier/memoire/udp)
    nom = DernierExport        # Nom du support
    periode_ms = 250           # Intervalle entre exportations (ms)
    #
    # Mesures implementees: impedance/taux_voie/taux_global
    #
    exportable = { taux := taux_voie }
    exporte = ()
}
)
```

taux[bille-sphere] = 6.33849
Date = 19.02.28/16:27:50.841857

1. User definitions:

- rather JSON than XML;
- JSON readability has been improved: declarations “a la C” ('{}','()', ...);
- Object-oriented files (one per detector, one per ADC, etc...);
- Uniform syntax over all files -> [solid universal UI to/from setup files for any info.](#)

2. User-defined algorithms:

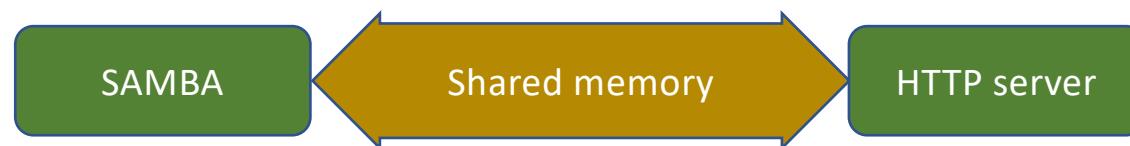
- Moves the difficulty from the developers to the users;
- At the same time, the users have not a compiler to prevent interactively errors;
- Good to keep a library of algorithms and ask only for parameters;
- [*In general, think to let to the user the less work as possible, and the most ways of dialog as possible;*](#)
- **Big work** to achieve a user-friendly error and recovery reporting [colouring code];
- High speed sampling not so compatible with interpreted languages.

3. Users needs:

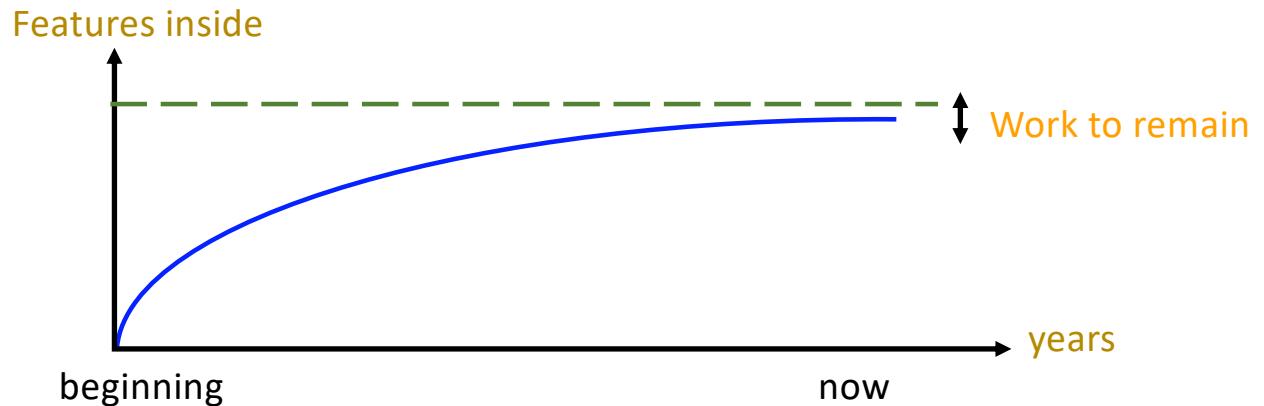
- The flow tends to vanish;
- A number of requests not used at the end (even not tested in the run's life);
- Priority to the well-known functionalities (before the exotic requests).

4. Remote control: see next slide

Direct Desktop Access	Window transfers	HTTP protocol
⊕ <ul style="list-style-type: none"> User interface exists Easy to share operation (control mode, remotely working together) 	⊕	⊕ <ul style="list-style-type: none"> no specific applications (Safari, Chrome, Firefox,...) Allow to avoid shared operation (display mode)
⊖ <ul style="list-style-type: none"> Need to share operation (display mode) <i>Efficient</i> solution needed <ul style="list-style-type: none"> Timbuktu excellent, but limited to MacOS 10.12 	⊖ <ul style="list-style-type: none"> Limited to X11 Impossible to share operation 	⊖ <ul style="list-style-type: none"> Needs to write an adapted HTTP server Unable to work together remotely
<ul style="list-style-type: none"> Vpn + vncviewer Both are ssh-based (<i>not</i> specific) 		<p>Added a layer in the Samba's User Interface: a side server exists, as a first way to distribute acquisition status and allow some control</p>



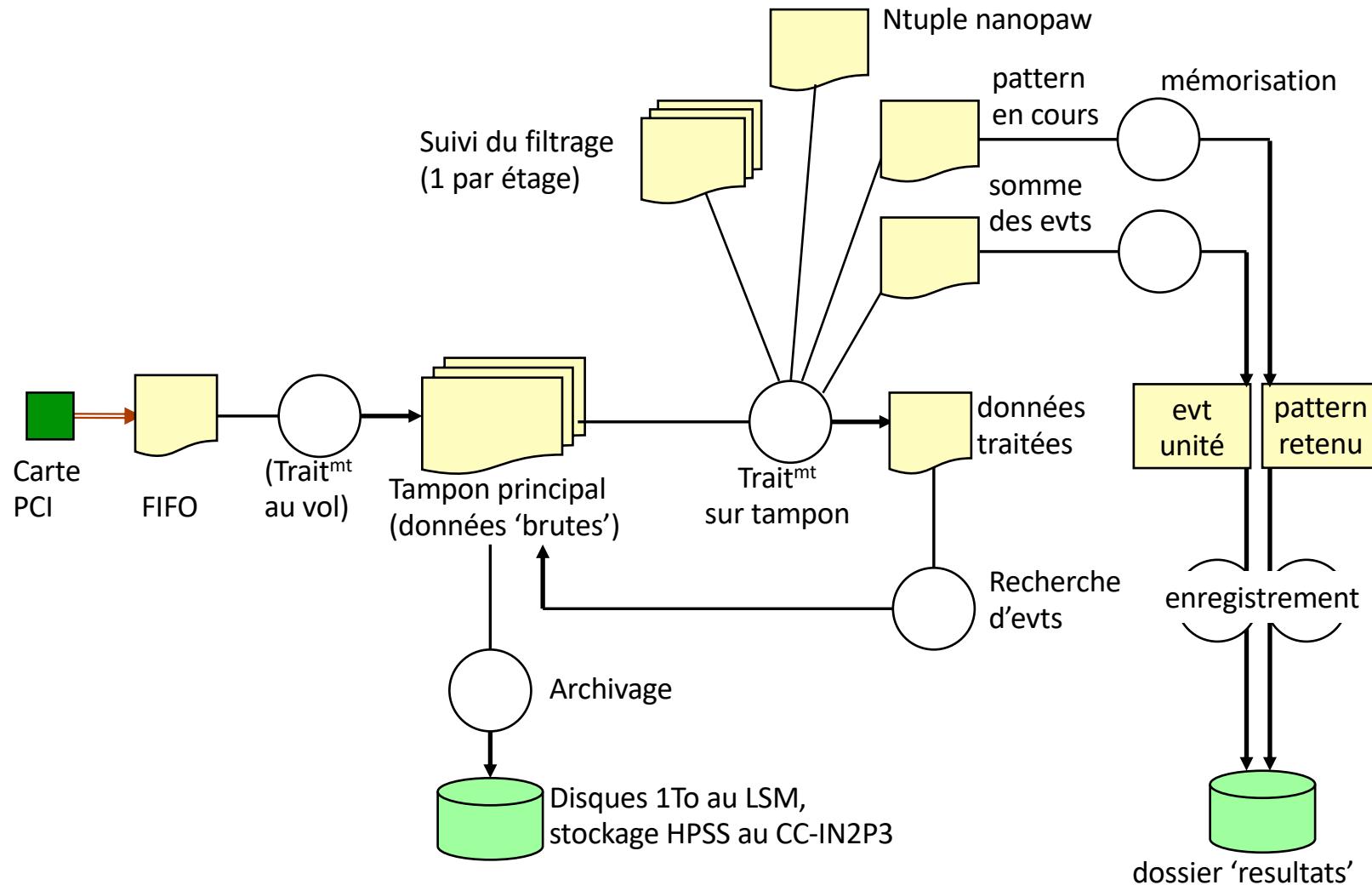
- 12 years of upgrades in Samba
- The flux of the requests seems to reach an asymptote
 - probably no important improvement after the first months of physics run

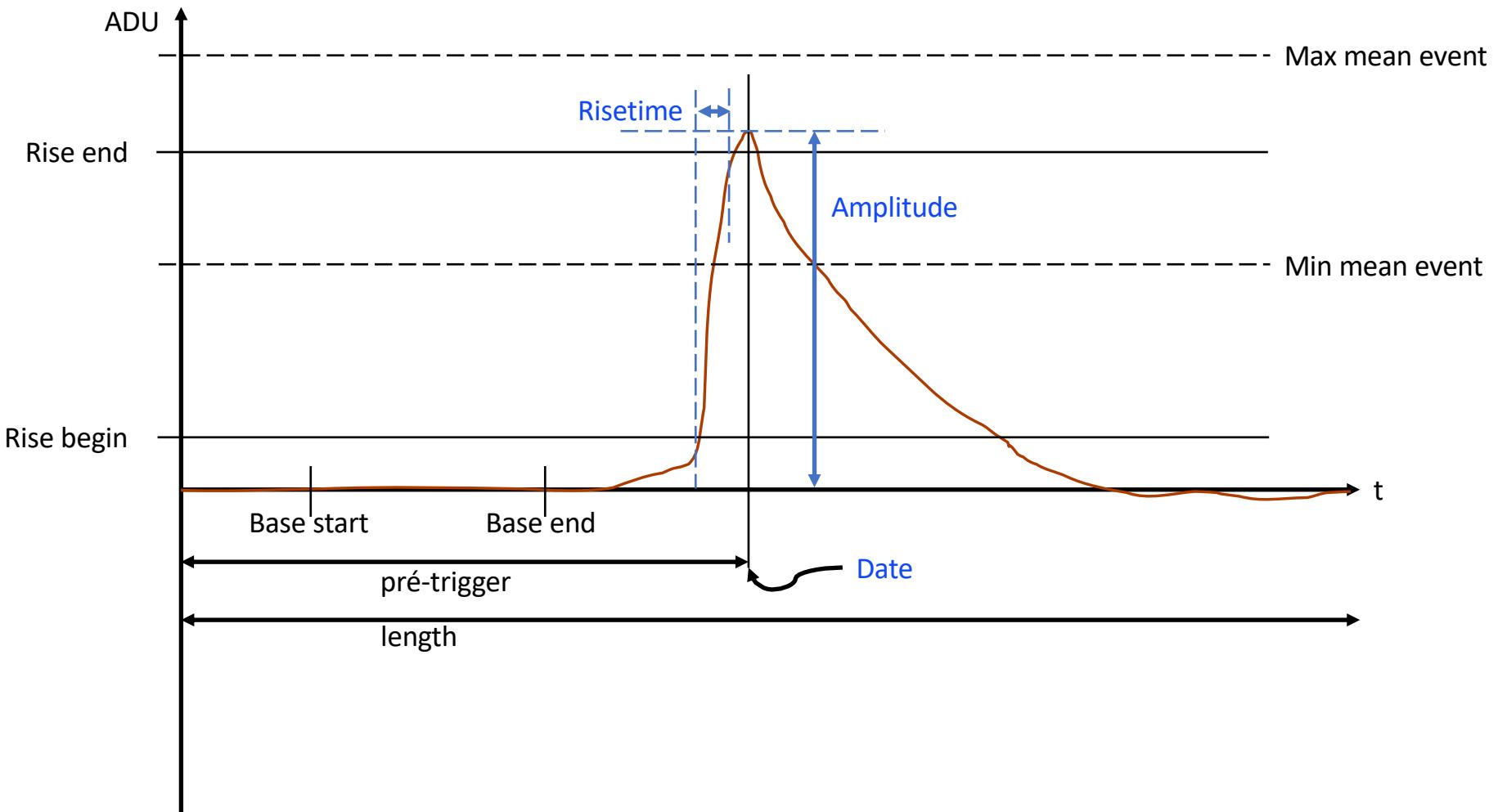


- Few features to achieve, for full completeness:
 - ✓ Slow control: externally defined JSON packets,
 - ✓ ADC boards: generic IP control,
 - ✓ Communication via HTTP,
 - ✓ Distribution packages (the pack for SPC is already available on Twiki),
 - ✓ Exhaustive User's Guide.
- Ability to work on future OS/computers?
 - Quickdraw (window manager) still supported in the latest MacOS 10.14 (tbc);
 - ❖ Acquisition computers should stay as unmodified as possible
 - eventually avoiding these OS version changes.

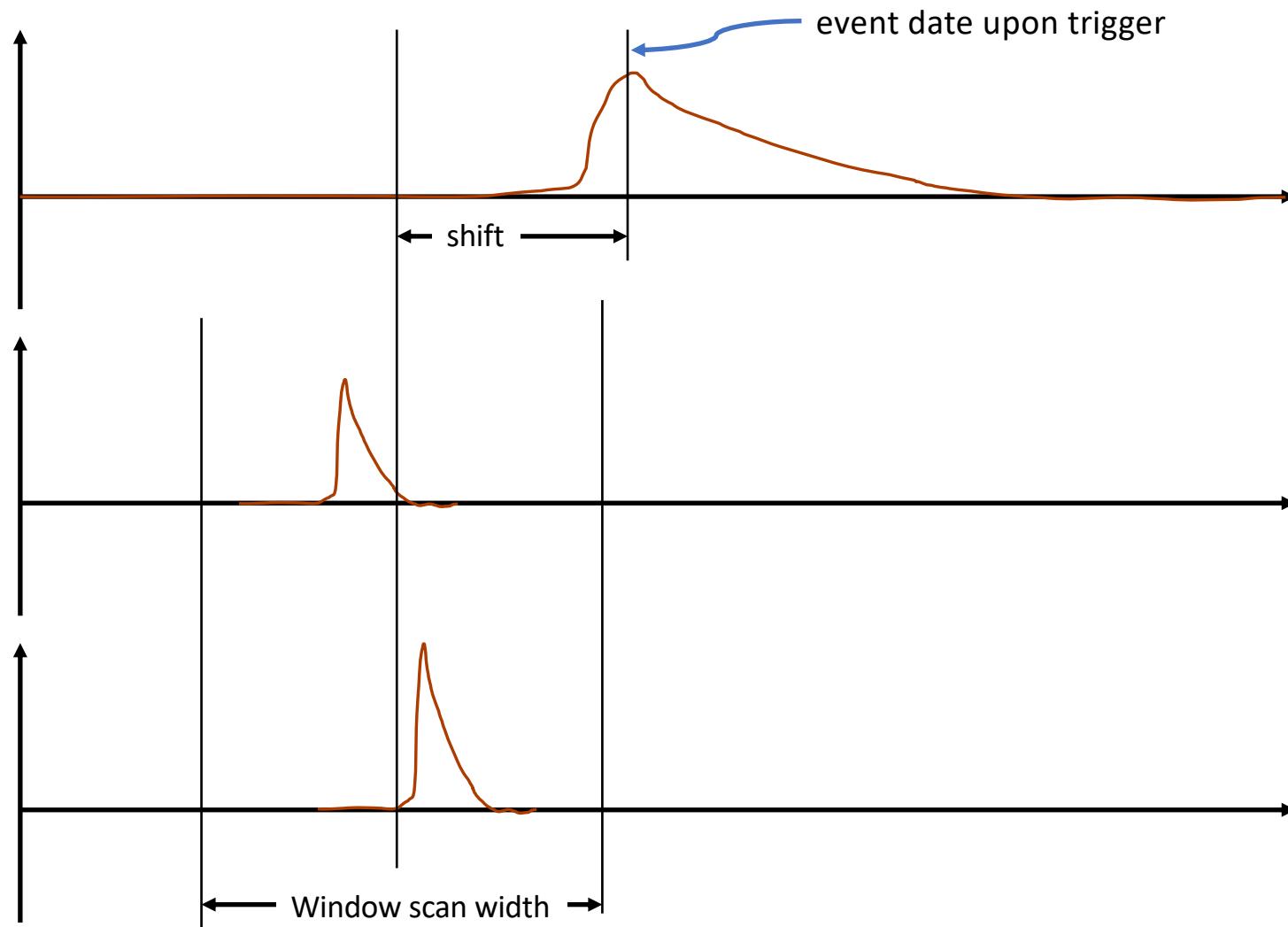
- **Full acquisition system:**
 - Hardware initialisation;
 - Readout and user-defined data processing without deadtime;
 - Software user-defined online trigger;
 - Data storage of stream or events, with all information in the headers;
 - Whole system control (data display, histograms, parameter management, ...);
- **Version management :**
 - All previous options remain in place;
 - Evolution of the parameter set is generally transparent to the users.
- **Software distribution:**
 - A tarfile containing a single full-installation script;
 - Version chooser;
 - User-friendly graphic interface to help building the setup.

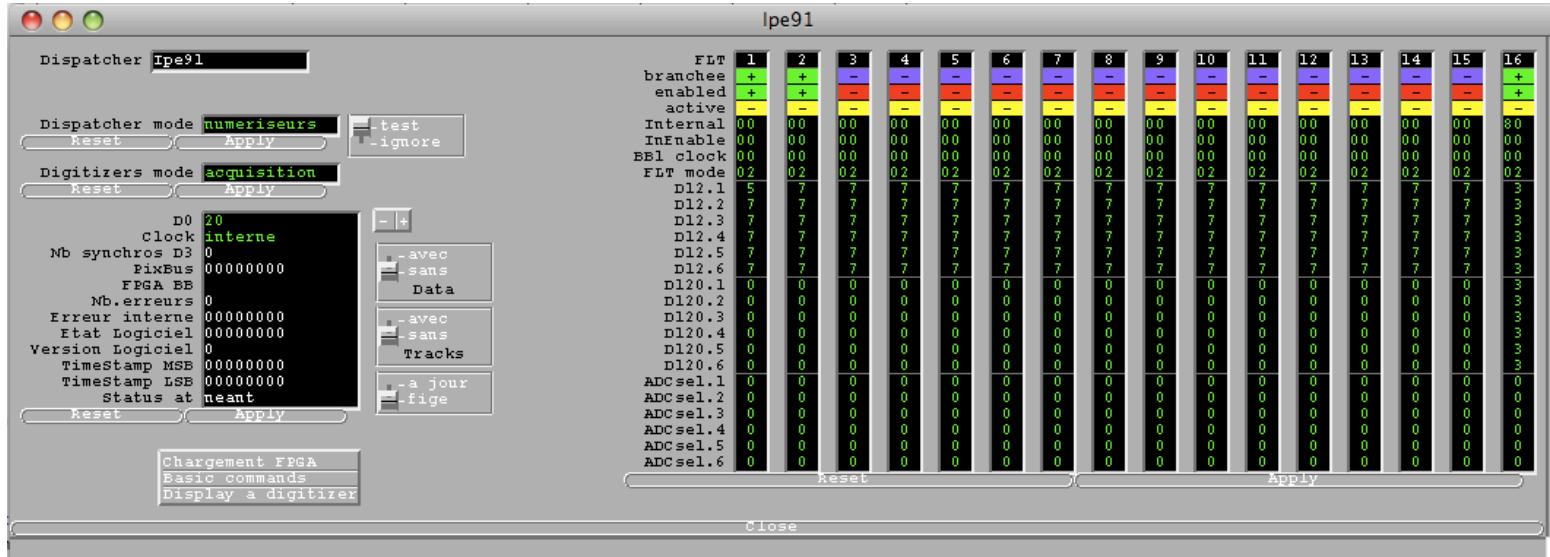
Simplified view of the internal buffers





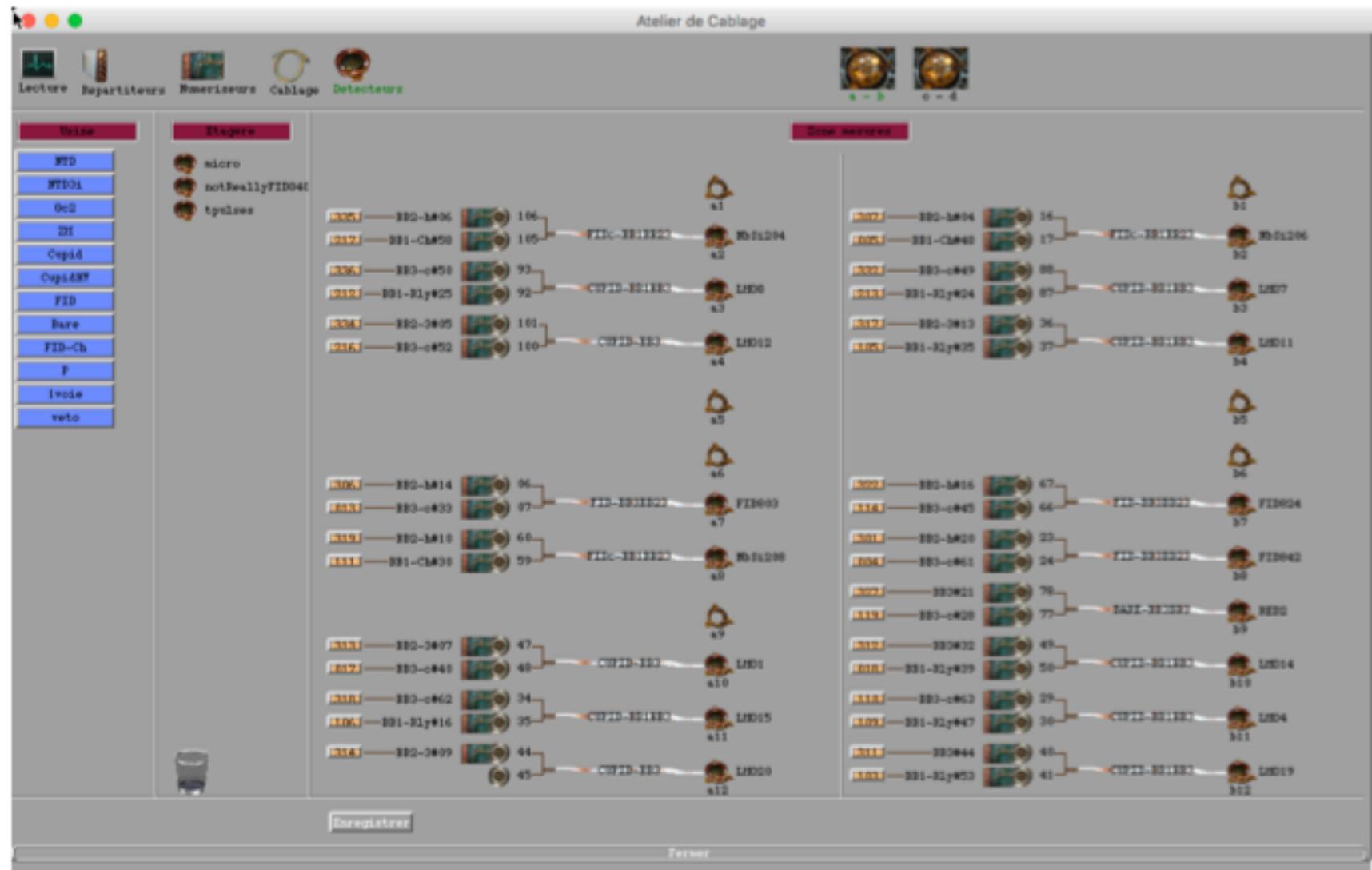
Event localization

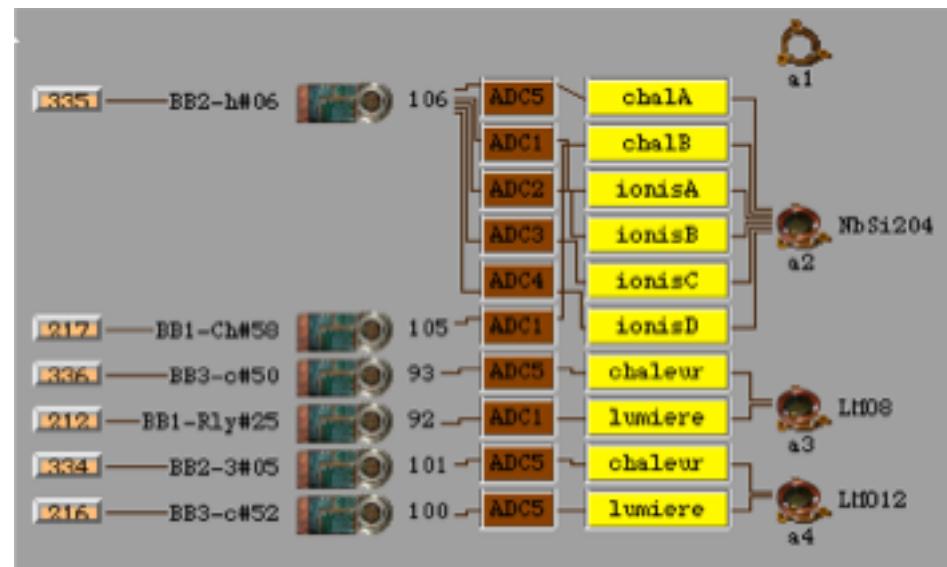




- Tool intended to the “shifter”:
 - quick verification (all is supposed working);
 - diagnostics for simple anomalies;
 - concerns mainly the parameters to be used by Samba.
- No interference with a low-level, full diagnostic, independent tool (like the one currently build with Orca).

Graphic interface for the setup definition

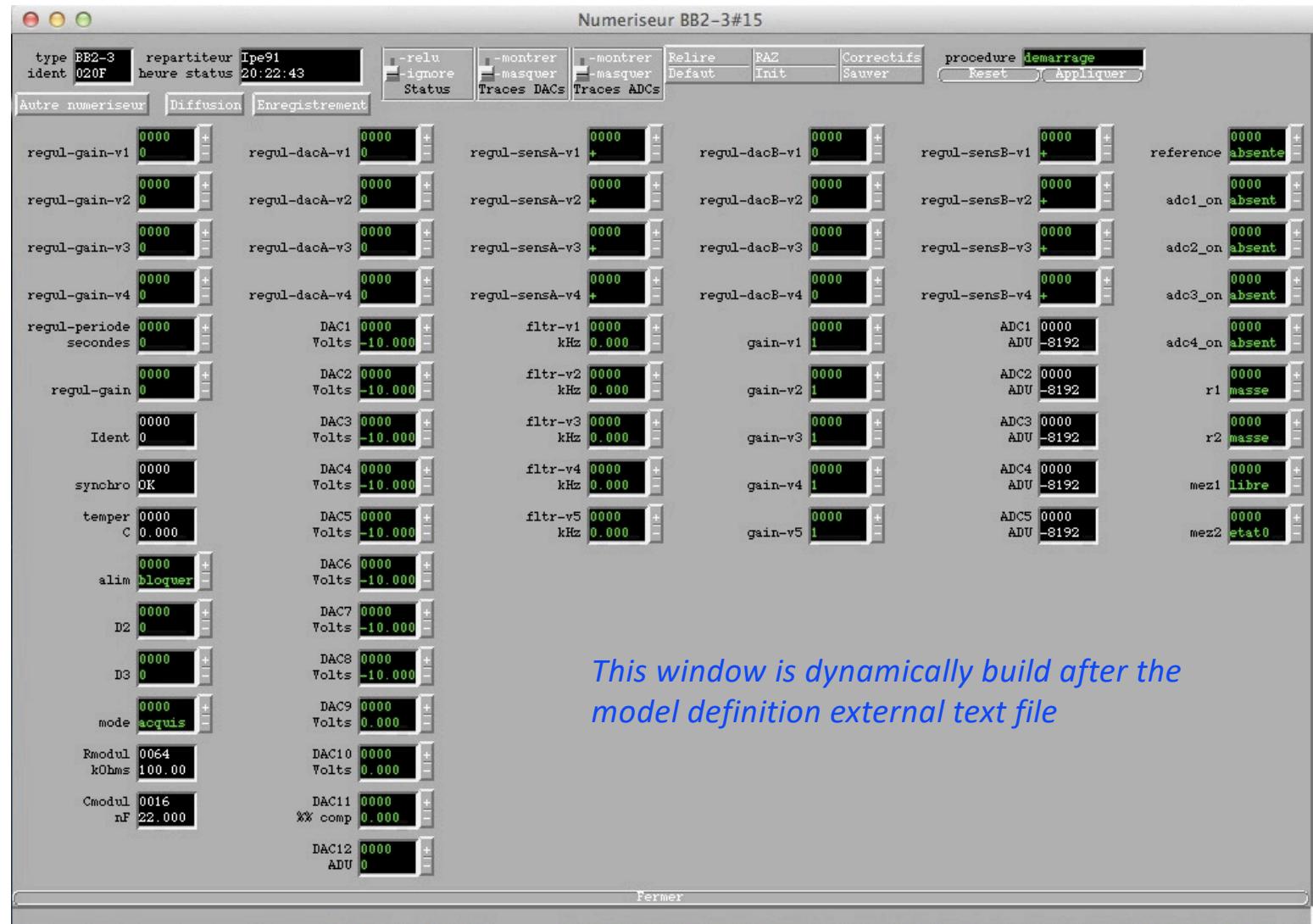




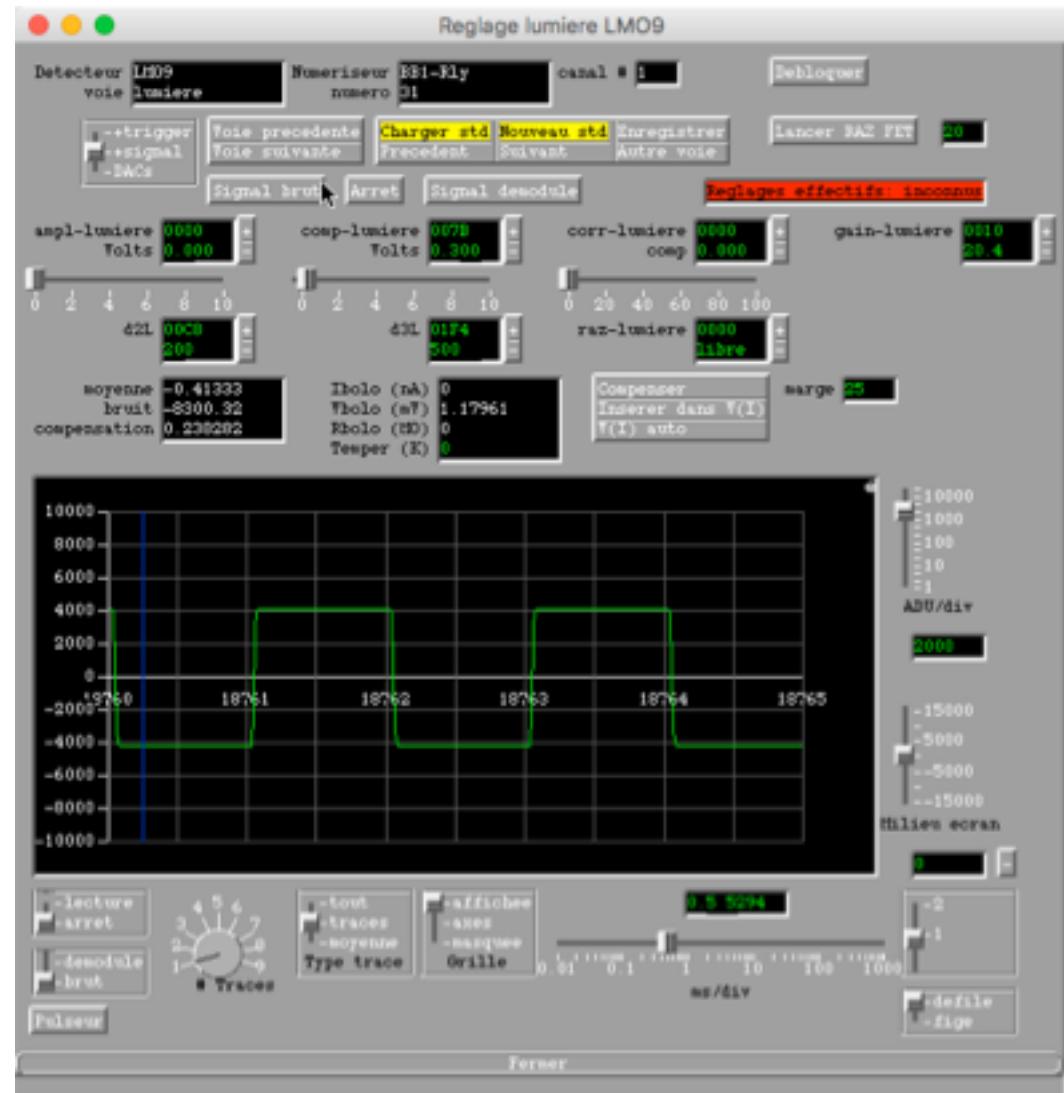
Channels view



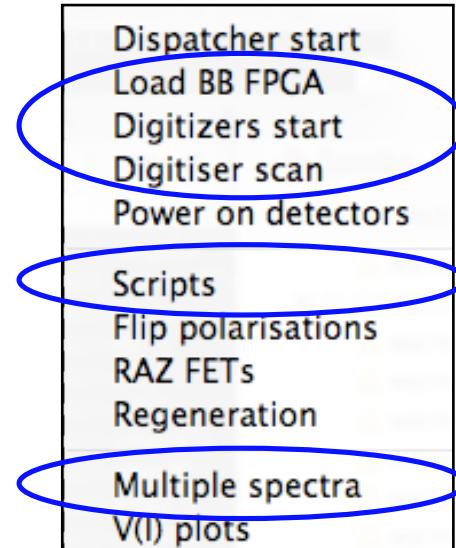
Individual operation of a given BB



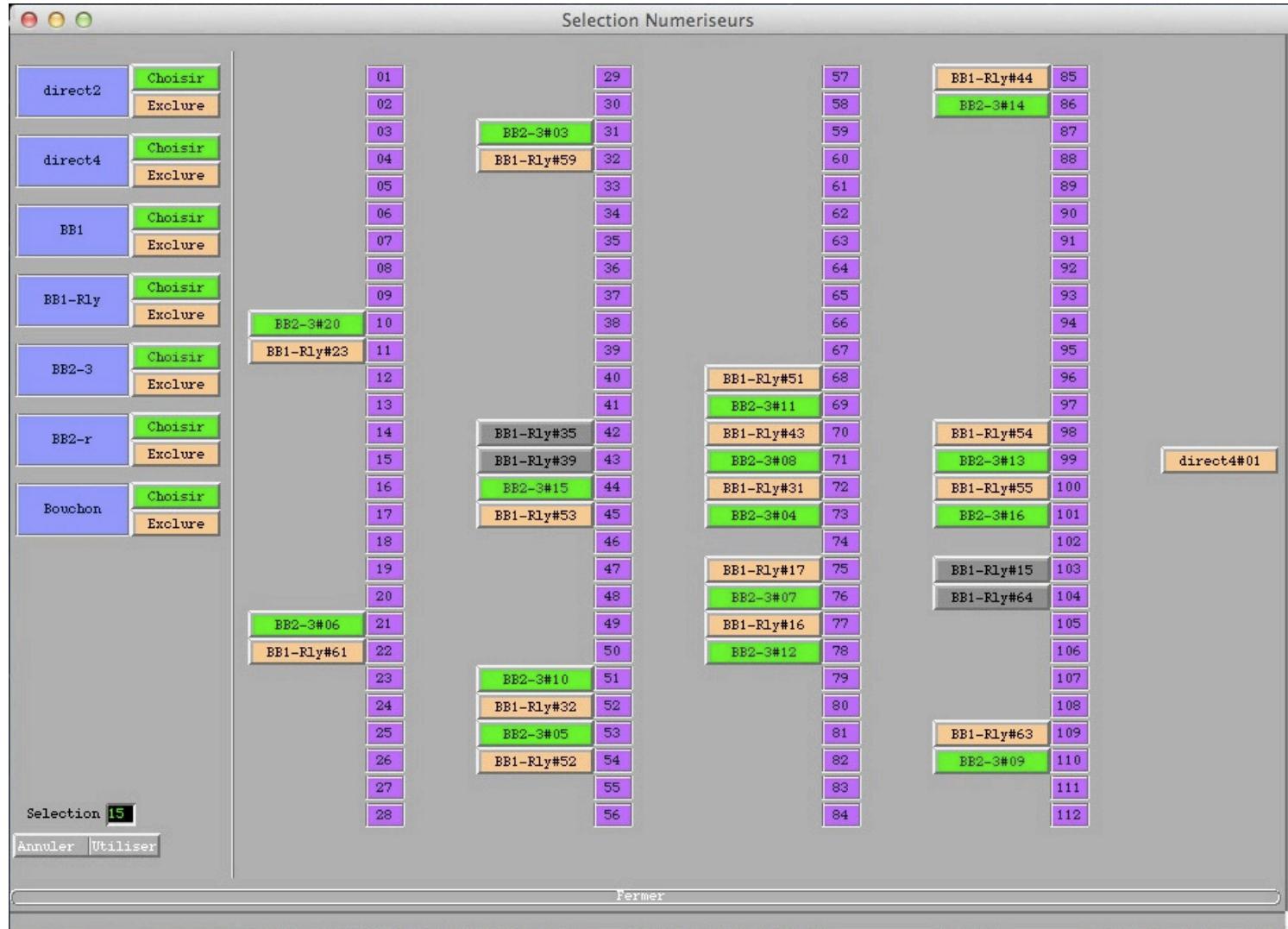
Individual operation of a given channel



This window is dynamically build after the model definition external text file



Defining the perimeter of a procedure: the BB selection



One-sight view of all the BB status

Etat Numeriseurs

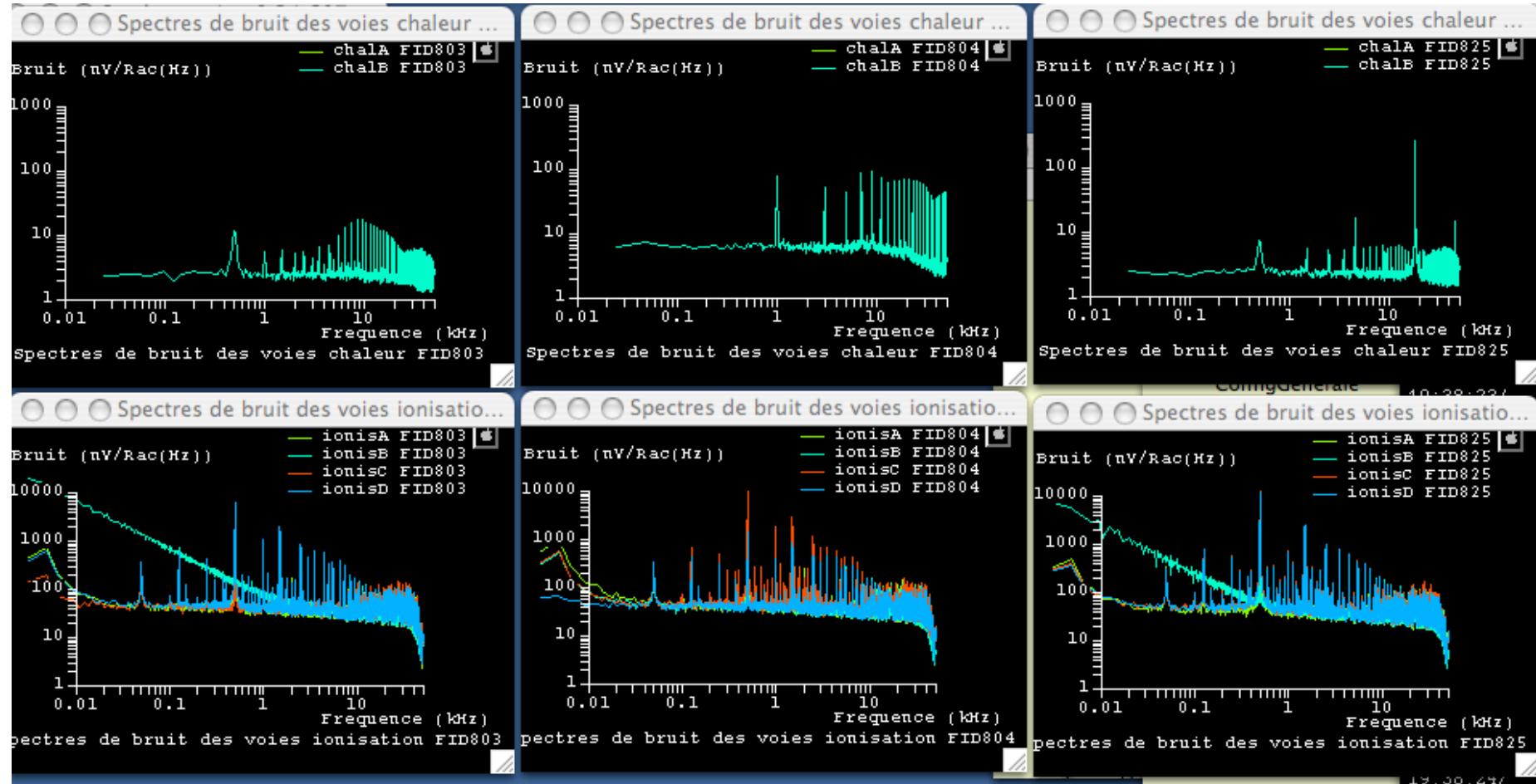
Entree	stamp	BB	[iden]	T(C)	d2/d3	alim	r1234	r1	r2	A	B	C	D	H	Rt+g	rA	PA	rB	PB	rC	PC	rD	PD	eH	cH	tH	-	detecteur
i.3.J6/BB2	106534857:	50	[0332]	32.4	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM08	
i.4.N4/BB2	106534857:	49	[0331]	32.1	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM07
i.4.N6/BB2	106534857:	48	[0330]	33.4	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM06
i.3.J3/BB2	106534857:	51	[0333]	31.2	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM05
i.3.J4/BB2	106534857:	41	[0329]	32.9	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM05
i.3.J1/BB2	106534857:	52	[0334]	31.2	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM012
i.3.J2/BB2	106534857:	05	[0205]	32.3	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM012
i.3.I6/BB2	106534857:	13	[0200]	32.1	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM011
i.3.I4/BB2	106534857:	23	[0317]	32.1	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM010
i.3.I2/BB2	106534857:	59	[0338]	31.9	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM09
i.3.L2/BB2	106534857:	07	[0207]	32.3	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM01
i.3.L1/BB2	106534857:	40	[0000]	0.0	0/0	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM01
i.3.K6/BB2	106534857:	32	[0000]	0.0	0/0	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM014
i.3.K4/BB2	106534857:	39	[0327]	33.3	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM016
i.3.L4/BB2	106534857:	62	[033E]	29.2	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM015
i.3.L6/BB2	106534857:	63	[033F]	30.3	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM04
i.4.N2/BB2	106534857:	43	[032B]	32.2	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM03
i.4.M2/BB2	106534857:	27	[031B]	30.1	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM02
i.4.M1/BB2	106534857:	46	[032E]	30.2	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM02
i.4.M4/BB2	106534857:	09	[0209]	33.8	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM020
i.4.M6/BB2	106534857:	44	[032C]	32.8	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM019
i.4.04/BB2	106534857:	11	[020B]	32.3	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM018
i.4.02/BB2	106534857:	30	[031E]	31.9	200/500	ob	ooooo	w	w	<<	<<	<<	<<	<<	00000	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	<<	LM013

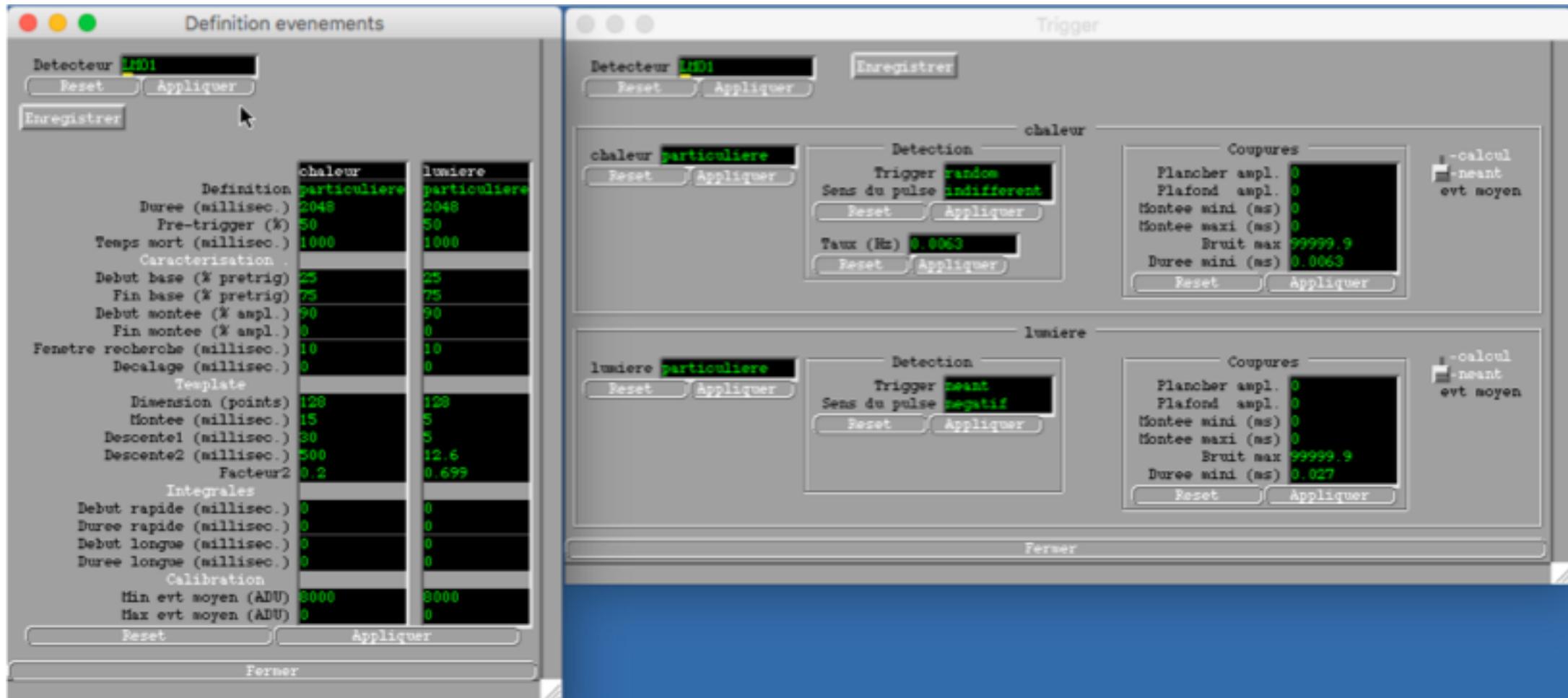
Synchro **106534858** à **13:01:58**

à jour
 figé
 Status

Fermer

One-sight spectra for all channels





Setting at once all the operating conditions for all the detectors

Consignes Detecteurs												
detece	etat	pos	canal	BB	Rep	ampl	comp	corr	gain	d2C	d3C	raz
LMD08:	ok	a3	chaleur	50	J6	1.000	0.000	60.000	1	100	1000	libre
			lumiere	25	J5	1.000	0.000	0.000	20.4	100	1000	libre
LMD07:	ok	b3	chaleur	49	N4	1.000	0.000	50.000	1	100	1000	libre
			lumiere	24	N3	1.000	0.000	0.000	20.4	100	1000	libre
LMD06:	ok	c3	chaleur	48	N6	1.000	0.000	60.000	1	100	1000	libre
			lumiere	23	N5	1.000	0.000	0.000	20.4	100	1000	libre
LMD05:	ok	d3	chaleur	41	J4	1.000	0.000	50.000	1	100	1000	libre
			lumiere	51	J3	1.000	0.000	62.000	2	100	1000	libre
LMD12:	ok	a4	chaleur	5	J2	1.000	0.000	70.000	2	100	1000	libre
			lumiere	52	J1	1.000	0.000	88.002	2	100	1000	libre
LMD11:	ok	b4	chaleur	13	I6	1.000	0.000	60.000	2	100	1000	libre
			lumiere	35	I5	1.000	0.000	0.000	20.4	100	1000	libre
LMD10:	ok	c4	chaleur	23	I4	1.000	0.000	60.000	1	100	1000	libre
			lumiere	34	I3	1.000	0.000	0.000	20.4	100	1000	libre
LMD09:	ok	d4	chaleur	59	I2	1.000	0.000	60.000	1	100	1000	libre
			lumiere	31	I1	1.000	0.000	0.000	20.4	100	1000	libre
LMD01:	ok	a10	chaleur	7	L2	1.000	0.000	50.001	2	100	1000	libre
			lumiere	40	L1	1.000	0.000	82.002	2	100	1000	libre
LMD14:	ok	b10	chaleur	32	K6	1.000	0.000	60.000	1	100	1000	libre
			lumiere	39	K5	1.000	0.000	0.000	20.4	100	1000	libre
LMD16:	ok	c10	chaleur	39	K4	1.000	0.000	60.000	1	100	1000	libre
			lumiere	43	K3	1.000	0.000	0.000	20.4	100	1000	libre
LMD15:	ok	a11	chaleur	62	L4	1.000	0.000	0.000	1	100	1000	libre
			lumiere	16	L3	1.000	0.000	0.000	20.4	100	1000	libre
LMD04:	ok	b11	chaleur	63	L6	1.000	0.000	70.001	1	100	1000	libre
			lumiere	47	L5	1.000	0.000	0.000	20.4	100	1000	libre
LMD03:	ok	c11	chaleur	43	M2	1.000	0.000	70.001	1	100	1000	libre
			lumiere	42	M1	1.000	0.000	0.000	20.4	100	1000	libre
LMD02:	ok	d11	chaleur	27	H2	1.000	0.000	50.000	1	100	1000	libre
			lumiere	46	H1	1.000	0.000	0.000	2	100	1000	libre
LMD20:	ok	a12	chaleur	9	H4	1.000	0.000	0.000	2	100	1000	libre
			lumiere	44	H6	1.000	0.000	0.000	1	100	1000	libre
LMD19:	ok	b12	chaleur	53	H5	1.000	0.000	0.000	20.4	100	1000	libre
			lumiere	52	O3	1.000	0.000	0.000	2	100	1000	libre
LMD18:	ok	c12	chaleur	11	O4	1.000	0.000	0.000	2	100	1000	libre
			lumiere	37	O1	1.000	0.000	0.000	20.4	100	1000	libre
LMD13:	ok	d12	chaleur	30	O2	1.000	0.000	60.000	1	100	1000	libre
			lumiere	37	O1	1.000	0.000	0.000	20.4	100	1000	libre

Setting at once all the acquisition process for all channels

Traitement des voies

detect.	etat	pos	canal	BB	Rep	Au vol	Pretrigger	Trigger	Usage
Standard:			chaleur			neant	0 x1	standard	regale
			lumiere			neant	0 x1	standard	corde
LHD8:	ok	a3	chaleur	50	J6	demodulation	25 x2	neant	fine
			lumiere	25	J5	demodulation	25 x3	neant	tout
LHD7:	ok	b3	chaleur	49	H4	demodulation	25 x2	neant	fine
			lumiere	24	H3	demodulation	25 x2	neant	tout
LHD6:	ok	c3	chaleur	48	H6	demodulation	25 x2	neant	fine
			lumiere	23	H5	demodulation	25 x2	neant	tout
LHD5:	ok	d3	chaleur	41	J4	demodulation	25 x2	neant	fine
			lumiere	51	J3	demodulation	25 x2	neant	tout
LHD12:	ok	a4	chaleur	5	J2	demodulation	25 x2	neant	fine
			lumiere	52	J1	demodulation	25 x2	neant	tout
LHD11:	ok	b4	chaleur	13	I6	demodulation	25 x2	neant	fine
			lumiere	35	I5	demodulation	25 x2	neant	tout
LHD10:	ok	c4	chaleur	23	I4	demodulation	25 x2	neant	fine
			lumiere	34	I3	demodulation	25 x2	neant	tout
LHD9:	ok	d4	chaleur	59	I2	demodulation	25 x2	neant	fine
			lumiere	31	I1	demodulation	25 x2	neant	tout
LHD1:	ok	a10	chaleur	7	L2	demodulation	25 x2	neant	fine
			lumiere	40	L1	demodulation	25 x2	neant	tout
LHD14:	ok	b10	chaleur	32	K6	demodulation	25 x2	neant	fine
			lumiere	39	K5	demodulation	25 x2	neant	tout
LHD16:	ok	c10	chaleur	39	K4	demodulation	25 x2	neant	fine
			lumiere	43	K3	demodulation	25 x2	neant	tout
LHD17:	ES	d10	chaleur	0		demodulation	25 x2	neant	fine
			lumiere	46	K1	demodulation	25 x2	neant	tout
LHD15:	ok	a11	chaleur	62	L4	demodulation	25 x2	neant	fine
			lumiere	16	L3	demodulation	25 x2	neant	tout
LHD4:	ok	b11	chaleur	63	L6	demodulation	25 x2	neant	fine
			lumiere	47	L5	demodulation	25 x2	neant	tout
LHD3:	ok	c11	chaleur	43	M2	demodulation	25 x2	neant	fine
			lumiere	42	M1	demodulation	25 x2	neant	tout
LHD2:	ok	d11	chaleur	27	M2	demodulation	25 x2	neant	fine
			lumiere	46	M1	demodulation	25 x2	neant	tout
LHD20:	ok	a12	chaleur	9	M4	demodulation	25 x2	neant	fine
			lumiere	0		demodulation	25 x2	neant	tout
LHD19:	ok	b12	chaleur	44	M6	demodulation	25 x2	neant	fine
			lumiere	53	M5	demodulation	25 x2	neant	tout
LHD18:	ok	c12	chaleur	11	O4	demodulation	25 x2	neant	fine
			lumiere	52	O3	demodulation	25 x2	neant	tout
LHD13:	ok	d12	chaleur	30	O2	demodulation	25 x2	neant	fine
			lumiere	37	O1	demodulation	25 x2	neant	tout

Reset

Sauver

Annuler

Sauver et fermer



Saving raw data + random “events” for 20 detectors: 20% of the available CPU power