MINGXUAN LI

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EDUCATION

Brown University

Sept 2019 - June 2021(Expected)

ScM in Computer Science, GPA: 4.0/4.0

Selected Courses: Learning and Sequential Decision Making (A), Introduction to Robotics (A),

Reintegrating AI (A)

Hong Kong University of Science and Technology(HKUST)

Feb 2018 - June 2018

Exchange Student in Computer Science; Major GPA: 4.0/4.3

Selected Courses: Intro to Bayesian Networks (A-), Data Visualisation (A+)

Beihang University

Sept 2015 - June 2019

B.S in Computer Science and Technology; Overall GPA: 3.7/4.0

Selected Courses: Compiler Theory (97/100), Image Processing and Pattern Recognition (100/100),

Introduction to Machine Learning (100/100)

RESEARCH INTERESTS

Reinforcement Learning, Efficient Planning, Adversarial Robustness

PUBLICATIONS

- "Towards Sample Efficient Agents through Algorithmic Alignment" AAAI 21 Student Abstract and Poster Program (Accepted) Mingxuan Li, Michael L. Littman
- "Interpretability is a Kind of Safety: An Interpreter-based Ensemble for Adversary Defense" KDD 2020 (Accepted) Jingyuan Wang, Yufan Wu, Mingxuan Li, Xin Lin, Junjie Wu, Chao Li
- "Replication of 'When to Trust Your Model: Model-Based Policy Optimization' " *Preprint* Mingxuan Li*, Xiaoyu Jiang*, Qiuxuan Chen*, Shiyi Han*, Jingyan Dong*, Ruochen Zhang*
- "Are L2 adversarial examples intrinsically different?" *Preprint* **Mingxuan** Li, Jingyuan Wang, Yufan Wu, Shuchang Zhou, Chao Li

SELECTED RESEARCH EXPERIENCE

Learning to Control with the Explainable Latent Dynamics Graph May. 2020 - Current Advisor: Prof. Michael L. Littman RLab, Brown University

- · Lead the effort to build a generalizable StarCraft agent for DARPA XAI project;
- · Designed the Latent Local Planning Network, an explainable world model that explicitly learns the latent dynamics purely from pixel inputs without reconstruction;
- · Proposed soft lambda return actor-critic learning behaviours from pure simulated trajectories;

Planning with Hierarchical State Partitions

Feb. 2020 - Current

Advisor: Prof. Michael L. Littman

RLab, Brown University

- · Took on the challenge of speeding up policy evaluation via divide & conquer;
- · Established a hierarchical planning framework based on state partitions;
- · Proved that the problem of finding planning amenable state partition is in general NP-complete;
- · Proposed a hierarchical state partition algorithm with near-optimal partition quality.

Towards Sample Efficient Agents through Algorithmic Alignment Advisor: Prof. Michael L. Littman Mar. 2020 - May 2020 RLab, Brown University

- · Revealed the potential of GNNs in sample efficient learning by creating the Deep Graph Value Networks (DeepGVs);
- · DeepGVs efficiently solved MDPs and outperformed unstructured baseline by over 50%;
- · Resulted in an abstract paper accepted by AAAI-21 Student Abstract and Poster Program.

Robust Adversaries Detection and Recovery

Mar. 2019 - Nov. 2019

Advisor: Prof. Jingyuan Wang, Dr. Shuchang Zhou

Megvii CV Group, Beihana U

- · Was a key player in designing an input sensitivity based adversarial examples detection and recovery pipeline which achieved an average of 96% detection accuracy and high robust classification accuracy against famous adversaries;
- · Developed a theoretical explanation of L_2 adversarial examples' intrinsic properties that can differentiate them from normal inputs;
- · Formed two research papers as first author and second student author, respectively, one of which is accepted by KDD 2020.

INTERNSHIP EXPERIENCE

Turing Microbe Co.,Ltd

Mar. 2019 - Jul. 2019

Advisor: Prof. Wei Xu(IIIS, Tsinghua U)

 $Computer\ Vision\ Research\ Intern,\ R\&D\ Department$

- · Analysed over 30,000 cases of gynaecological diseases data with T-SNE and deep clustering to give doctors insights on new taxonomy for Bacterial Vaginal(BV) diagnosis;
- · Used StyleGAN to generate realistic and highly diverse BV pictures for training young doctors;
- · Highly recognised by Prof. Qinping Liao, the chairman of Chinese Medical Doctor Association, gynae-cology branch, for insightful data analyse and practical application value of the work.

SELECTED PROJECTS

PiDrone: An autonomous drone using Raspberry Pi

Sept. 2019 - Dec. 2019

Course Project

Brown University

- · Built a drone equipped with Raspberry Pi from scratch under the guidance of online manuals;
- · Implemented core algorithms to enable the drone to fly, including PID controller, speed control with optical flow, state estimation with unscented Kalman Filter and position control with SLAM;
- · Got a solid grasp of foundations of robotics and probabilistic control theory.

JPEG-2000 Standard Image I/O Pipeline

May 2019 - Jun. 2019

Beihang U

Personal Side Project

- · Implemented 2D-FastDCT and 2D-FFT in JAVA;
- · Analysed JPEG-2000 ISO standard and implemented the whole I/O process including image header information extraction without using any external JAVA image processing packages;
- · Provided a visual interface for previewing the processed image along with its grey scale distribution.

AWARDS&HONOURS

10/2018, Scholarship for Academic Achievements, Second Prize (Top 10%)

09/2018, Was selected to appear on the Deans List for the School of Engineering, HKUST

09/2017, The 1st National Student Computer System Capability Challenge, Second Prize (Final 2/70)

 $05/2017,\, {\rm The}\ 27 {\rm th}$ "FengRu Cup" University Students Extra-Curricular Scientific and Technological Invention Competition, Second Prize (Final 4/176)