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Combinatorics and Graph Theory Day 31st January, 2019





Outline

- Introduction
 - Spectrum and Seidel Switching
 - Defining Two-Graphs
- Regular Two-Graphs
 - The Involution M
 - Descendant Form of a Regular Two-Graph
 - Results about Descendants of Regular Two-Graphs
- Strongly Regular Graphs
 - Definition
 - Structure of Descendants of Regular Two-Graphs
- Conference Graphs



Definition (Graph)

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Definition (Adjacency matrix)

The adjacency matrix of a graph G = (V, E) is the $n \times n$ matrix (a_{ij}) where

$$a_{ij} = \begin{cases} 1 & \text{if vertex } i \text{ is adjacent to vertex } j, \text{ i.e. } \{v_i, v_j\} \in E \\ 0 & \text{otherwise.} \end{cases}$$

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Strongly Regular Graphs

4/25

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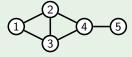
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Eventually we will work with a variant of the Seidel matrix, which we will introduce later.

Example (A simple Seidel matrix)

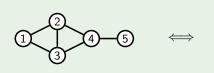
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Strongly Regular Graphs

Introduction

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Note that if **A** and **S** are the adjacency and Seidel matrices of G respectively,

$$S = J - I - 2A$$

where **J** is the matrix consisting entirely of 1's and **I** is the identity matrix.

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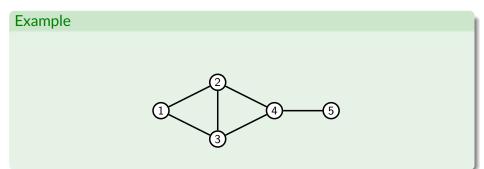
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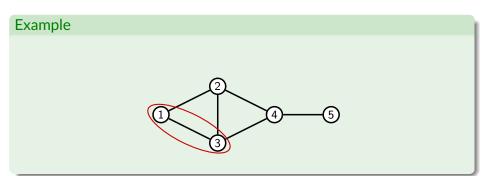
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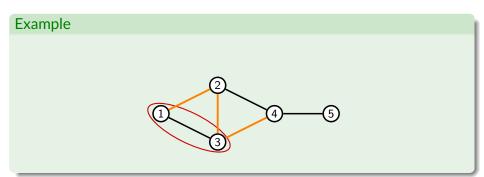
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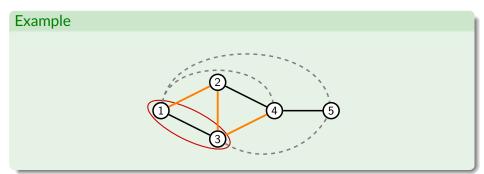
Given a graph G=(V,E) and a subset of the vertices $U\subseteq V$, the operation of *Seidel switching* with respect to U exchanges all edges and non-edges between U and $V\setminus U$ to obtain the graph $\mathrm{SS}_U(G)$.

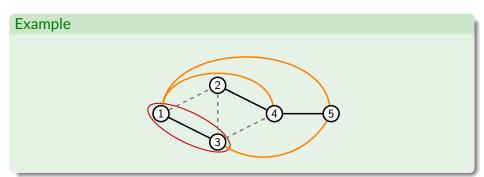


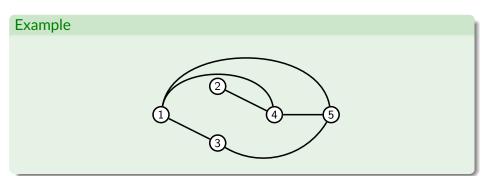
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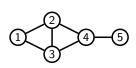


Regular Two-Graphs

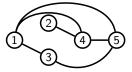
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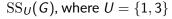


 $SS_U(G)$, where $U = \{1, 3\}$

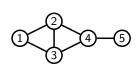


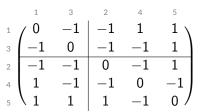
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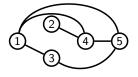
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Strongly Regular Graphs



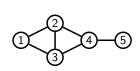


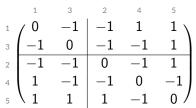


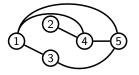
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In general, if **S** and $S_{SS_U(G)}$ are the Seidel matrices of G and $SS_U(G)$, then

$$\mathbf{S} = \left(\begin{array}{c|c} \mathbf{S}_U & \mathbf{R} \\ \hline \mathbf{R}^\top & \mathbf{S}_{V \setminus U} \end{array} \right) \iff$$

9/25

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In other words, $\mathbf{S}_{SS_U(G)} = \mathbf{D}^{-1}\mathbf{S}\mathbf{D}$, where $\mathbf{D}^{-1} = \mathbf{D}$ is the diagonal matrix with $d_{ii} = +1$ if $i \in U$ and $d_{ii} = -1$ otherwise.

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It follows that **S** and $\mathbf{S}_{SS_U(G)}$ are similar, and therefore G and $SS_U(G)$ have the same Seidel spectrum.

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A **two-graph** or **switching class** is an equivalence class of the Seidel switching equivalence relation.

- A two-graph on *n* vertices consists of all the *n*-vertex graphs with the same Seidel spectrum.
- The term 'two-graph' originally arose in a combinatorial context, and actually refers to a couple (V, Δ) where $\Delta \subseteq \binom{V}{3}$ is a collection of triples $\{v_1, v_2, v_3\}$ with the property that any 4-subset of V contains an even number of triples of Δ . This is known to be equivalent to our definition.

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- Reverting to the combinatorial definition of 'two-graph', (V, Δ) is said to be regular if every pair of vertices lies in the same number of triples of Δ . This is known to be equivalent to our definition.

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then $\mathbf{B}v = \lambda v$ and $|\lambda| < 1$.

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Furthermore, if the spectrum of **M** is $1^{(n-k)}(-1)^{(k)}$, then it follows by Cauchy's interlacing inequalities that the spectrum of **B** is

$$1^{(n-k-1)}(-1)^{(k-1)}\lambda^{(1)}$$
.

$$\mathbf{M} = \alpha \mathbf{S} - \lambda \mathbf{I}$$

If **S** is the Seidel matrix of a regular two-graph on n vertices with eigenvalues μ_1, μ_2 , then

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Strongly Regular Graphs

where

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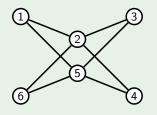
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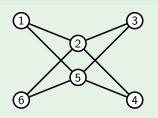
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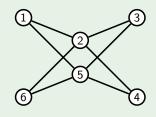
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Strongly Regular Graphs

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- Pick any vertex $v \in V$.
- 2 Let U be the set of all neighbours of v.
- **3** Then the vertex v is isolated in $SS_U(G)$.



Example (The Petersen Graph)

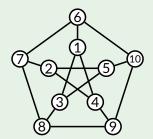
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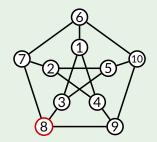
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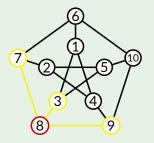
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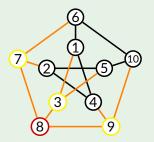
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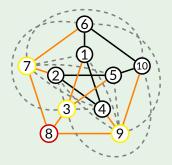
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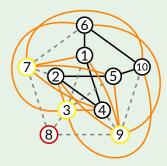
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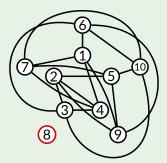
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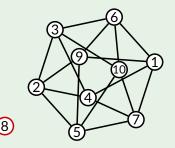
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Strongly Regular Graphs

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② Substituting for α and λ , we also get that n and $\mu_1 + \mu_2$ have the same parity (even/odd).



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Proof.

Let the Seidel eigenvalues of G be μ_1 and μ_2 , where G is in descendant form. Using the values of α and λ , the first and last rows of the involution \mathbf{M} are of the form

Row 1
$$\begin{pmatrix} -\lambda & \pm \alpha & \pm \alpha & \cdots & \pm \alpha & \alpha \\ & & \vdots & & & \\ \alpha & \alpha & \alpha & \cdots & \alpha & -\lambda \end{pmatrix}$$

where we are assuming that the last row corresponds to the isolated vertex. The number of $-\alpha$'s in row 1 is the degree of vertex 1. Since $\mathbf{M}^2 = \mathbf{I}$, the inner product $\langle \text{Row } \mathbf{1}, \text{Row } n \rangle = 0$.

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Proof. (continued...)

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$$\langle \text{Row 1}, \text{Row } n \rangle = 0 \implies -\alpha \lambda + (n-2)\alpha^2 - 2\rho_1 \alpha^2 - \alpha \lambda = 0$$

where ρ_1 denotes the degree of vertex 1.

Note that ρ_1 is independent of the vertex label 1, since $\langle \text{Row 1}, \text{Row } i \rangle = 0$ for all $1 \leq i \leq n-1$. Thus D is ρ -regular.

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A graph G is said to be a strongly regular graph or an $srg(n, \rho, e, f)$ if:

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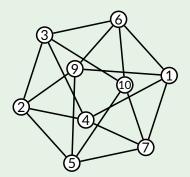
Definition (Strongly regular graph)

- 1 it has *n* vertices,
- 2 each vertex has degree ρ ,
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- every two non-adjacent vertices have f common neighbours.

Example (Descendant of Petersen Graph)

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The descendant from the last example is an srg(9, 4, 1, 2).



Consider a descendant form $D \dot{\cup} K_1$ of a regular two-graph and the following notations for pairs of vertices.

	# of common	# of common
	neighbours	non-neighbours
Adjacent vertices	ẽ	ě
Non-adjacent vertices	$ ilde{f}$	$\widetilde{\widetilde{f}}$

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Strongly Regular Graphs

By considering the rows of **M** we obtain the following formulæ:

$$\tilde{e} + \tilde{e} = \frac{1}{2}(n-2) - \frac{\lambda}{\alpha}$$
 $\tilde{f} + \tilde{f} = \frac{1}{2}(n-2) + \frac{\lambda}{\alpha}$
 $\tilde{e} - \tilde{e} = 2\rho - n$ $\tilde{f} - \tilde{f} = 2\rho - (n-2)$

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From these it follows that \tilde{e} , \tilde{e} , \tilde{f} and \tilde{f} are invariant for any pair of adjacent/non-adjacent vertices.



From the formulæ obtained previously, we get the following results. Given a descendant form $D \dot{\cup} K_1$ of a regular two-graph on n vertices, then

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Strongly Regular Graphs

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- D is an $srg(n-1, \rho, e, f)$ where $e = \tilde{e}$ and $f = \tilde{f} = \frac{\rho}{2}$.
- $\rho = -\frac{1}{2}(1 + \mu_1\mu_2 + (\mu_1 + \mu_2))$ and $e = -\frac{1}{2}(5 + \mu_1\mu_2 + 3(\mu_1 + \mu_2))$.

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- *n* must be even.
- $\frac{\lambda}{\alpha}$ is an integer.

We conclude by mentioning an application of two-graphs. In the paper, we continue to use the theory of NSSD's to study **conference graphs**. These are regular two-graphs which have $\mu_1 = -\mu_2$.

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An Application: Conference Graphs

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Their Seidel matrices are precisely the so-called **conference matrices**, i.e. (0,1,-1)-matrices with zero on the diagonal and which satisfy $\mathbf{SS}^{\top}=k\mathbf{I}$ for some k.

These have applications in telephone networks. A necessary condition for setting up a conference with n telephone ports and ideal signal loss is the existence of an $n \times n$ conference matrix.

An Application: Conference Graphs

Regular Two-Graphs

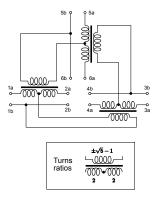


Figure: Implementation of 6-port conference matrix, corresponds to the smallest existing conference graph on n=6 vertices with Seidel eigenvalues $\pm\sqrt{5}$.

Thank you!

Strongly Regular Graphs

DEPARTMENT OF MATHEMATICS

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25/25