

# Ordinary Differential Equations

Pure Mathematics A-Level

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We cover the following first/second order linear ordinary differential equations (ODEs). The *order* of an ODE is determined by the highest derivative. By *linear* we mean that all the derivatives have power 1, and by *ordinary*, we mean that the derivatives are of a function ( $y$ ) of only one independent variable ( $x$ ).

## First Order ODEs

### 1. Separable

These are equations which can be brought to the form

$$f(y) \frac{dy}{dx} = g(x)$$

Integrating both sides gives a solution.

### 2. Product-Rule Equations

These are equations which are the direct result of applying the product rule. They generally have the form

$$f(y)g'(x) + f'(y)g(x) = h(x)$$

which can be transformed to

$$\frac{d}{dx}(fg) = h(x)$$

Again, integrating both sides gives a solution.

### 3. Solvable by Integrating Factors

Equations of the form

$$\frac{dy}{dx} + f(x)y = g(x)$$

can be reduced to exact equations by multiplying throughout by

$$I(x) = \exp \int f(x) dx$$

known as the *integrating factor* (Note that  $\exp x \equiv e^x$ ).

## Second Order ODEs

### 1. Homogeneous with Constant Coefficients

A differential equation is *homogeneous* when it equals zero. Here we consider the equation

$$a \frac{d^2 y}{dx^2} + b \frac{dy}{dx} + cy = 0$$

where  $a, b, c \in \mathbb{R}$  are constants. First, we solve the **auxiliary equation**

$$ak^2 + bk + c = 0$$

whose solutions are  $k = k_1$  and  $k = k_2$ . The general solution is then given by

$$y = \begin{cases} c_1 e^{k_1 x} + c_2 e^{k_2 x} & \text{if } k_1 \neq k_2 \\ e^{kx}(c_1 + c_2 x) & \text{if } k = k_1 = k_2 \\ e^{\alpha x}(c_1 \sin \beta x + c_2 \cos \beta x) & \text{if } k = \alpha \pm \beta i \in \mathbb{C} \end{cases}$$

where  $c_1, c_2$  are arbitrary constants.

### 2. Inhomogeneous with Constant Coefficients

A differential equation is *inhomogeneous* if it is not homogeneous. Here we consider the equation

$$a \frac{d^2 y}{dx^2} + b \frac{dy}{dx} + cy = f(x) \neq 0$$

where  $a, b, c \in \mathbb{R}$  are constants.

We solve by following these steps:

- (i) Solve the **homogeneous equation**

$$a \frac{d^2 y}{dx^2} + b \frac{dy}{dx} + cy = 0$$

to obtain the **complementary function**  $cf(x)$ .

- (ii) Obtain a **trial solution** in the form of  $f(x)$  which caters for second order differentiation. These can be shown in the table below.

	$f(x)$	Trial Solution, $ts(x)$	
Polynomials	$a$	$\lambda$	
	$ax + b$	$\lambda x + \mu$	
	$ax^2 + bx + c$	$\lambda x^2 + \mu x + \eta$	
	$\vdots$	$\vdots$	
Exponentials*	$ae^{\alpha x}$	$\lambda e^{\alpha x}$	if $k_1 \neq \alpha \neq k_2$
		$\lambda x e^{\alpha x}$	if $k_1 = \alpha \neq k_2$
		$\lambda x^2 e^{\alpha x}$	if $k_1 = \alpha = k_2$
Trigonometric	$a \cos \alpha x + b \sin \alpha x$	$\lambda \cos \alpha x + \mu \sin \alpha x$	

\*Note that  $k_1, k_2$  are the solutions to the auxiliary equation solved in part (i).

Observe that any of the constants in  $f(x)$  can be zero, but the trial solution can still have nonzero constants. E.g. if  $f(x) = x^2$ , then we still take the trial solution to be  $\lambda x^2 + \mu x + \eta$ . Similarly, the function  $f(x) = x^2 + \sin 2x$  has trial solution  $\lambda x^2 + \mu x + \eta + \phi \cos 2x + \psi \sin 2x$ .

- (iii) Determine the trial solution derivatives  $ts'(x)$  and  $ts''(x)$ , and substitute them in the original ODE. Compare coefficients to determine correct values for the constants so that the result will equal  $f(x)$ .

The trial solution with the constant(s) found is called the **particular integral**,  $pi(x)$ .

- (iv) The general solution is given by  $y = cf(x) + pi(x)$ .

### Remark

A remark about this method for second order ODEs. The reason such a method works is due to the fact that differentiation is a *linear operator*, i.e. we have

$$\frac{d}{dx}(\alpha f(x) + \beta g(x)) = \alpha \frac{d}{dx}f(x) + \beta \frac{d}{dx}g(x)$$

So upon substitution of the solution  $y = cf(x) + pi(x)$  into our ODE, we have the following:

$$\begin{aligned} \mathcal{LHS} &= a \frac{d^2}{dx^2}(cf(x) + pi(x)) + b \frac{d}{dx}(cf(x) + pi(x)) + c(cf(x) + pi(x)) \\ &= \underbrace{a cf''(x) + b cf'(x) + c cf(x)}_{=0} + \underbrace{a pi''(x) + b pi'(x) + c pi(x)}_{=f(x)} \\ &= 0 + f(x) \\ &= f(x) = \mathcal{RHS} \end{aligned}$$

It is very often the case that students naïvely ask:

*Why do we need the complementary function? Isn't the particular integral alone enough to make the  $\mathcal{LHS} = \mathcal{RHS}$ , and therefore sufficient as a solution?*

The reason we need the complementary function is that it makes our solution more general (much like adding  $+c$  when integrating). We have a function which annihilates the  $\mathcal{LHS}$ , thus incorporating it into our general solution will give us all possible solutions to the ODE. Without it, we are assuming that only the substitution  $y = 0$  can make the  $\mathcal{LHS} = 0$ , which is not the case. In fact, if initial conditions are given (so we would wish to determine a particular solution) then we would definitely need the complementary function.