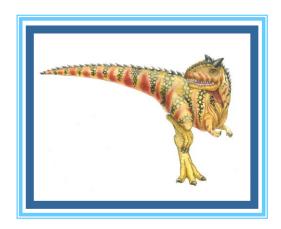
Chapter 5: Process Synchronization





p1: __def f1()

alle 1:

print (A)
print (B)

ABLOLD

ACDBABCD

ABCACD BDAB V

e2: def f2()

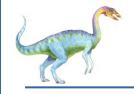
while 1:

print (c)
print (D

AA Bis

D C A B X





Producer

```
while (true) {
      /* produce an item in next produced
*/
      while (counter == BUFFER SIZE) ;
            /* do nothing */
      buffer[in] = next_produced;
      in = (in + 1) % BUFFER SIZE;
      counter++;
```





Consumer

```
while (true) {
    while (counter == 0)
        ; /* do nothing */
    next_consumed = buffer[out];
    out = (out + 1) % BUFFER_SIZE;
        counter--;
    /* consume the item in next consumed
*/
}
```





Race Condition

☐ counter++ could be implemented as

```
register1 = counter
register1 = register1 + 1
counter = register1
```

counter-- could be implemented as

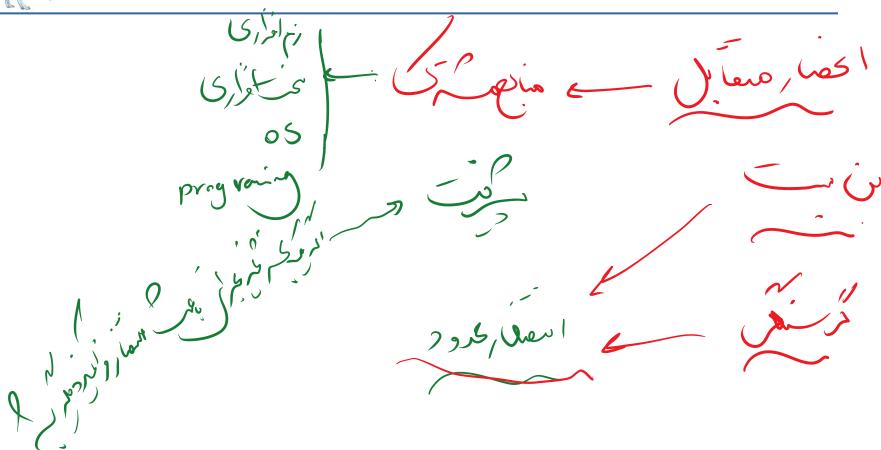
```
register2 = counter
register2 = register2 - 1
counter = register2
```

Consider this execution interleaving with "count = 5" initially:

```
S0: producer execute register1 = counter {register1 = 5}
S1: producer execute register1 = register1 + 1 {register1 = 6}
S2: consumer execute register2 = counter {register2 = 5}
S3: consumer execute register2 = register2 - 1 {register2 = 4}
S4: producer execute counter = register1 {counter = 6}
S5: consumer execute counter = register2 {counter = 4}
```











```
P0(void)
```

```
while(TRUE)
  while( turn != 0) ; /*wait*/
  critical-section();
  turn = 1;
  non-critical- section();
```

```
P1(void)
 while(TRUE)
    while( turn != 1); /*wait*/
    critical-section();
    turn = 0;
    non-critical- section();
```





boolean

```
المقال فرود لا
```

True True X lorses!

```
Hagi

f
```

```
P0(void) {
  while(TRUE) {
    while(flag[1]); ↓
    flag[0] = TRUE; •
    critical-section(); ↓
    flag[0] = FALSE; ↓
    non-critical-section();
}
```

 $flag[2] = {FALSE, FALSE};$

```
P1(void){
while(TRUE) {
while(flag[0]);
flag[1] = TRUE; 
critical-section();
flag[1] = FALSE;
non-critical- section ();
}
```



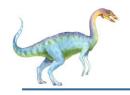


```
boolean flag[2] = {FALSE,FALSE};
```

```
P0(void){
  while(TRUE) {
    flag[0] = TRUE;
    while(flag[1]);
    critical-section();
    flag[0]= FALSE;
    non-critical-section();
  }
}
```

```
P1(void){
  while(TRUE) {
    flag[1] = TRUE;
    while( flag[0] );
    critical-section();
    flag[1] = FALSE;
    non-critical- section();
  }
}
```



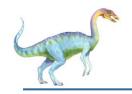


boolean flag[2] = {FALSE,FALSE};

```
Live lock
```

```
P0(void)
  while(TRUE)
   flag[0] = TRUE; \bullet
   while( flag[1]) •
      flag[0] = FALSE;
      delay for a short time();
      critical-section();
  flag[0] = FALSE;
  non-critical- section();
```

```
P1(void)
 while(TRUE)
   flag[1] = TRUE; \bullet
   while( flag [0]) •
      flag[1] = FALSE;
      delay for a short time();
      flag[1] = TRUE;
   critical-section();
   flag[1] = FALSE;
   non-critical- section();
```



Dekker

boolean flag[2] = {FALSE,FALSE};
turn=0;

```
P0(void){
 while(TRUE){
    flag[0] = TRUE;
    while( flag[1] )
     if (turn == 1)
        flag[0] = FALSE;
        while(turn==1) do;
        flag[0] = TRUE;
    critical-section();
    turn = 1;
    flag[0] = FALSE;
    non-critical-section ();
```

```
P1(void){
 while(TRUE){
   flag[1] = TRUE;
   while(flag[0])
     if (turn == 0)
        flag[1] = FALSE;
        while(turn==0) do;
        flag[1] = TRUE;
   critical-section();
    turn = 0;
    flag[1] = FALSE;
    non-critical-section();
```



انتظار محدود	پیشرفت	انحصار متقابل	تلاش های Decker
✓	والارس	✓	تلاش اول
	✓	_	تلاش دوم
	✓	√	تلاش سوم
-	✓	✓	تلاش چهارم
✓	√	✓	تلاش پنجم





Petwson

boolean flag[2] = {FALSE,FALSE}; turn=0;



```
P0(void){
  while (TRUE){
   flag[0] = TRUE;
   turn = 0;
   while (turn==0 && flag[1]
);
   critical-section();
   flag[0] = FALSE;
   non-critical-section();
```

```
P1(void){
  while (TRUE){
   flag[1] = TRUE;
   turn = 1;
   while(turn==1 && flag[0]
);
   critical-section();
   flag[1] = FALSE;
   non-critical-section();
```





disable interripts()

critical Section()

enable interripts()

اهره کوری: کے نوب کری وقعے لکھاری کی





tsl - ver bock tesx & sex bock Sizuel Chet on b

N.J. J.

```
enter_region:
  tsl reg , lock
  cmp reg , #0
  jne enter_region
  ret
```

move reg, #1
swap reg, lock
cmp reg, #0
jne enter_region
ret





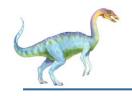
tsl sizis

Swar

Viso Semaphore Cisticii

Wait() Signal()

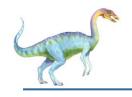




Implementation with no Busy waiting (Cont.)

```
wait(semaphore *S) {
   S->value--;
   if (S->value < 0) {
      add this process to S->list;
      block();
signal(semaphore *S) {
   S->value++;
   if (S->value <= 0) {
      remove a process P from S->list;
      wakeup(P);
```



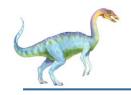


Bounded Buffer Problem (Cont.)

The structure of the consumer process

```
Do {
   wait(full);
   wait(mutex);
    /* remove an item from buffer to next consumed */
    signal(mutex);
    signal(empty);
    /* consume the item in next consumed */
} while (true);
```





Readers-Writers Problem (Cont.)

The structure of a reader process

```
do {
       wait(mutex);
       read count++;
       if (read count == 1)
       wait(rw mutex);
    signal (mutex);
       /* reading is performed */
    wait(mutex);
       read count --;
       if (read count == 0)
    signal(rw mutex);
    signal (mutex);
} while (true);
```





Producer-Consumer

۱ – سمافور mutex :

```
سمافوری برای رعایت شرط انحصار متقابل است، تا تولید کننده و مصرف کننده به طور همزمان به بافر
دسترسی نداشته باشند. (با مقدار اولیه 1)
```

۲- سمافور full :

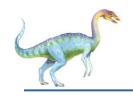
```
سمافوری برای شمارش تعداد خانه های پر بافر (با مقدار اولیه 0)
```

۳- سمافور empty:

سمافوری برای شمارش تعداد خانه های خالی بافر (با مقدار اولیه n

```
void producer (void){
                                    void consumer(void){
 int item;
                                       int item;
 while(TRUE)
                                       while(TRUE)
     item= produce()
                                         wait(full);
     wait(empty);
                                         wait(mutex);
    wait(mutex);
                                         item=remove();
     insert(item);
                                         signal(mutex);
     signal(mutex);
                                         signal(empty);
     signal(full); }
                                         consume();
```



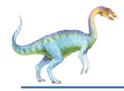


Dining-Philosophers Problem



- Philosophers spend their lives alternating thinking and eating
- Don't interact with their neighbors, occasionally try to pick up 2 chopsticks (one at a time) to eat from bowl
 - Need both to eat, then release both when done
- ☐ In the case of 5 philosophers
 - Shared data
 - Bowl of rice (data set)
 - Semaphore chopstick [5] initialized to 1





Dining-Philosophers Problem Algorithm

```
The structure of Philosopher i:
       do {
            wait (chopstick[i] );
            wait (chopStick[ (i + 1) % 5] );
                         // eat
             signal (chopstick[i] );
             signal (chopstick[ (i + 1) % 5] );
                              think
        } while (TRUE);
    What is the problem with this algorithm?
П
```





The Deadlock Problem

- A set of blocked processes each holding a resource and waiting to acquire a resource held by another process in the set
- Example
 - System has 2 disk drives
 - \square P_1 and P_2 each hold one disk drive and each needs another one
- Example
 - semaphores A and B, initialized to 1

P_0	P_1
wait (A);	wait(B)
wait (B);	wait(A)





Dining-Philosophers Problem Algorithm

```
semaphore room=4;
semaphore fork[5]=\{1\};
void philosopher (int i){
  while(TRUE){
    think();
    wait( room );
    wait( fork[i] );
    wait( fork[(i+1) \% 5]);
    eat(); ناحیه بحرانی
    signal ( fork[(i+1) % 5] );
     signal (fork[i]);
     signal (room);
void main(){
 parbegin (p(0),p(1),p(2),p(3),p(4)));
```





Resource-Allocation Graph (Cont.)

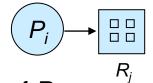
Process



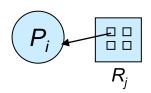
Resource Type with 4 instances



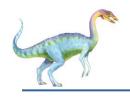
 \square P_i requests instance of R_i



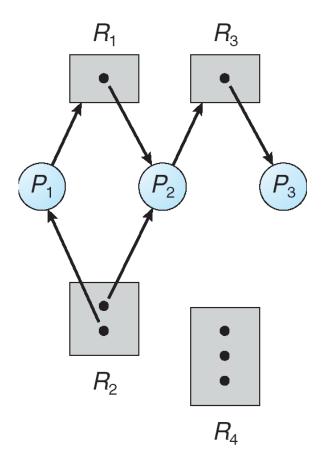
 \square P_i is holding an instance of R_j







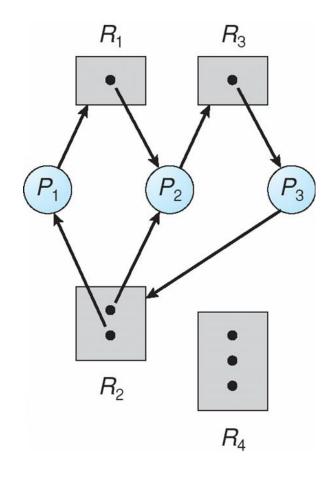
Example of a Resource Allocation Graph



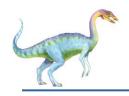




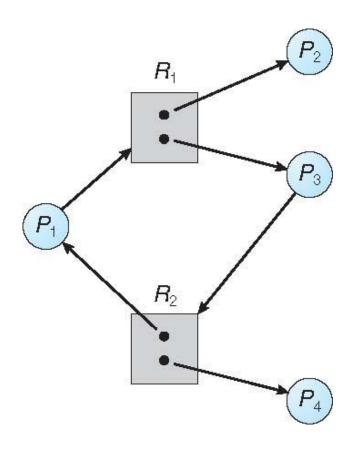
Resource Allocation Graph With A Deadlock







Graph With A Cycle But No Deadlock







Basic Facts

- □ If graph contains no cycles ⇒ no deadlock
- ☐ If graph contains a cycle ⇒
 - □ if only one instance per resource type, then deadlock
 - if several instances per resource type, possibility of deadlock





Methods for Handling Deadlocks

- Ensure that the system will *never* enter a deadlock state:
 - Deadlock prevention
 - Deadlock avoidence
- Allow the system to enter a deadlock state and then recover
- Ignore the problem and pretend that deadlocks never occur in the system; used by most operating systems, including UNIX



End of Chapter 5

