## **Programming HW2 for Numerical Optimizations**

## **Minimization of quadratic function:**

Iteration	Objective	Х	у	Z	nu
0	2.94	0.1	0.2	0.7	0
1	1.8134	0.38379	0.38379	0.2324081	1.8379594
2	1.5775	0.46492	0.46492	0.0701490	-7.1476268
3	1.5096	0.49523	0.49523	0.0095347	-97.0272734
4	1.5009	0.49950	0.49950	0.0009950	-997.002970
5	1.50009	0.49995	0.49995	0.0000999	-9997.00030
6	1.500009	0.49999	0.49999	9.99949e-06	-999970.0

Optimization reached the target of objective function.

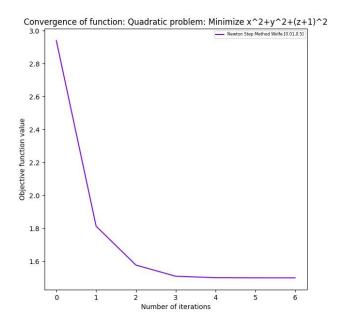
Objective: 1.5000099996498275

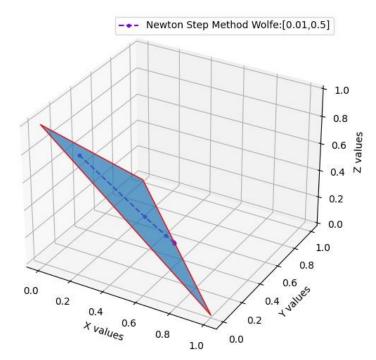
Location: [4.99995000e-01, 4.99995000e-01, 9.99949984e-06]

Final nu: -99997.00003002

Equality constraints values: [0.0]

Inequality constraints values: [-0.499995, -0.499995, -9.9994998e-06]





## **Maximization of linear function:**

Iter	Objective	х	у
0	1.25	0.5	0.75
1	2.1597557552	1.46301532	0.69674044
2	2.8193261240	1.90521016	0.91411596
3	2.9801994802	1.99005025	0.99014923
4	2.9980019994	1.9990005	0.9990015
5	2.9998000200	1.99990001	0.99990002
6	2.9999800002	1.99999	0.99999
7	2.9999980000	1.999999	0.999999
8	2.9999998000	1.9999999	0.999999
9	2.999999820	1.99999999	0.9999999
10	2.99999999	2.	1.

Optimization reached the target of objective function.

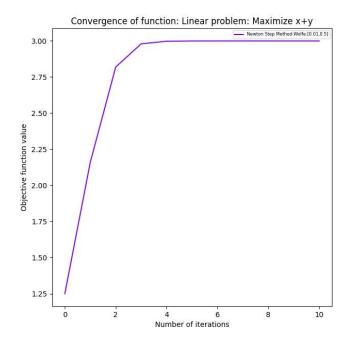
objective: 2.999999999999005

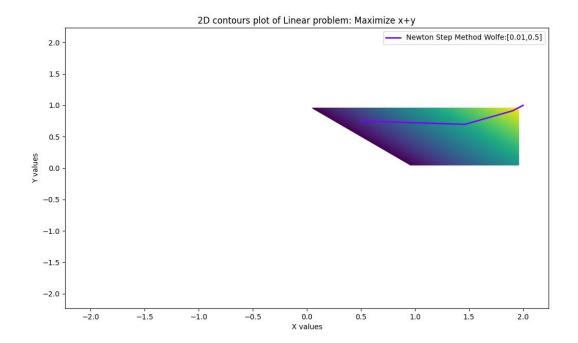
location: [2., 1.]

Equality constraints values: []

Inequality constraints values: [-1.9999999999999005, -5.051070672834612e-12, -5.048184092970587e-12,

-0.999999999949489]





## 3D plot of Linear problem: Maximize x+y

