

BebopDroneDecodeStream

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Chapter 1

Purpose of BebopDroneDecodeStream

This sample shows how to receive video stream from a Bebop Drone, decode it, display the decoded stream with mplayer and get inputs from users to control the Bebop drone.

To compile SDK Example BebopDroneDecodeStream

On Linux and MacOS X platform : make

Dependencies of BebopDroneDecodeStream

You will need **mplayer** to show the video stream, **ffmpeg** to get the video decoded and **ncurses** to get inputs from console

On Linux you can get ncurses-dev apt-get: apt-get install ncurses-dev

To run SDK Example BebopDroneDecodeStream

On Linux and MacOS X platform : make run

To clean the compilation of BebopDroneDecodeStream

On Linux and MacOS X platform : make clean

Discussion about BebopDroneDecodeStream

This project is separated into 3 classes :

- **BebopDroneDecodeStream** : This is the main class. It will operate the connexion to the drone, the setup of the network and video part. It will also register for commands callback and send commands. If you need to add callbacks, add it in registerARCommandsCallbacks.

In this class, the callback for a new frame received will be called. When it does, it will take a free empty frame from a pool (to avoid an allocation each time a frame is received), put the received data in this free frame and add the free frame to a frame buffer. An other thread will loop, and try to take a frame and pass it to the decoder. Once the

frame has been decoded, it will write the decoded frame in a pipe file. MPlayer will read this pipe file and display the frames.

- `DecoderManager` This is an util class that will perform h264 frame decoding thanks to ffmpeg.
- `ihm` This is an util class that will catch inputs from console and send these events to `BebopDroneDecodeStream`. It will also display some pieces of information about the drone, like its battery level and its flying state.

When you run this sample, be sure to be in the console to catch your keyboard event. As MPlayer will open a new window, you could have to click again in the console. The ihm inputs are implemented on an azerty keyboard. Feel free to adapt it just by changing the key comparison in the function `IHM_InputProcessing`.

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

_ARCODECS_Manager_Component_t	
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_ARCODECS_Manager_Frame_t	
Video and audio codecs manager allow to decode video and audio	8
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IHM_t	11
RawFrame_t	
Component of a frame	11
READER_THREAD_DATA_t	12

Chapter 3

File Index

3.1 File List

Here is a list of all documented files with brief descriptions:

[BebopDroneDecodeStream.c](#)

This file contains sources about basic arsdk example decoding video stream from a BebopDrone
with ffmpeg

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BebopDroneDecodeStream.h

??

DecoderManager.h

??

[ihm.c](#)

This file contains sources about ncurses IHM used by arsdk example "BebopDroneDecode↔
Stream"

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ihm.h

??

Chapter 4

Class Documentation

4.1 `_ARCODECS_Manager_Component_t` Struct Reference

Component of a frame.

```
#include <DecoderManager.h>
```

Public Attributes

- `uint8_t * data`
- `uint32_t lineSize`
- `uint32_t size`

4.1.1 Detailed Description

Component of a frame.

4.1.2 Member Data Documentation

4.1.2.1 `uint8_t* _ARCODECS_Manager_Component_t::data`

data buffer

4.1.2.2 `uint32_t _ARCODECS_Manager_Component_t::lineSize`

size of each line of the component

4.1.2.3 `uint32_t _ARCODECS_Manager_Component_t::size`

size of the buffer

The documentation for this struct was generated from the following file:

- `DecoderManager.h`

4.2 `_ARCODECS_Manager_FFMPEGDecoder_t` Struct Reference

Public Attributes

- AVCodec * **codec**
- AVCodecContext * **codecCtx**
- AVFrame * **decodedFrame**
- AVPacket **avpkt**
- uint8_t * **outputData**
- int **outputDataSize**

The documentation for this struct was generated from the following file:

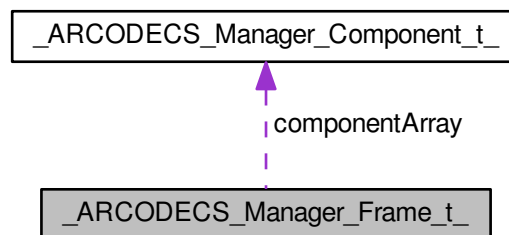
- DecoderManager.c

4.3 _ARCODECS_Manager_Frame_t_ Struct Reference

Video and audio codecs manager allow to decode video and audio.

```
#include <DecoderManager.h>
```

Collaboration diagram for _ARCODECS_Manager_Frame_t_:



Public Attributes

- eARCODECS_FORMAT **format**
- uint32_t **width**
- uint32_t **height**
- uint32_t **numberOfComponent**
- [ARCODECS_Manager_Component_t](#) * **componentArray**

4.3.1 Detailed Description

Video and audio codecs manager allow to decode video and audio.

The documentation for this struct was generated from the following file:

- DecoderManager.h

4.4 _ARDrone3CameraData_t Struct Reference

Public Attributes

- int **tilt**
- int **pan**

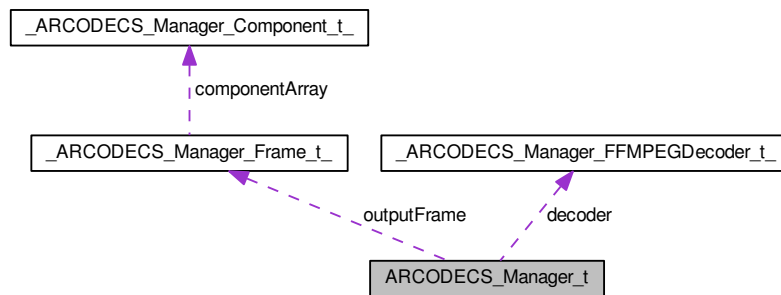
The documentation for this struct was generated from the following file:

- BebopDroneDecodeStream.h

4.5 ARCODECS_Manager_t Struct Reference

Video and audio codecs manager structure allow to decode video and audio.

Collaboration diagram for ARCODECS_Manager_t:



Public Attributes

- ARCODECS_Manager_GetNextDataCallback_t **callback**
- void * **callbackCustomData**
- [ARCODECS_Manager_FFMPEGDecoder_t](#) * **decoder**
- [ARCODECS_Manager_Frame_t](#) **outputFrame**

4.5.1 Detailed Description

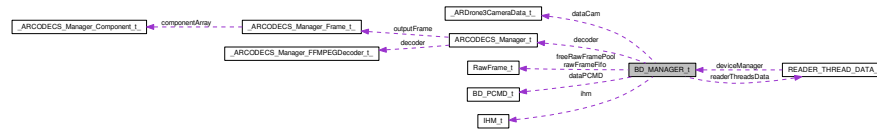
Video and audio codecs manager structure allow to decode video and audio.

The documentation for this struct was generated from the following file:

- DecoderManager.c

4.6 BD_MANAGER_t Struct Reference

Collaboration diagram for BD_MANAGER_t:



Public Attributes

- ARNETWORKAL_Manager_t * **alManager**
- ARNETWORK_Manager_t * **netManager**
- ARSTREAM_Reader_t * **streamReader**
- ARSAL_Thread_t **looperThread**
- ARSAL_Thread_t **rxThread**
- ARSAL_Thread_t **txThread**
- ARSAL_Thread_t **videoTxThread**
- ARSAL_Thread_t **videoRxThread**
- int **d2cPort**
- int **c2dPort**
- int **arstreamFragSize**
- int **arstreamFragNb**
- int **arstreamAckDelay**
- uint8_t * **videoFrame**
- uint32_t **videoFrameSize**
- [BD_PCMD_t](#) **dataPCMD**
- [BD_Cam_t](#) **dataCam**
- [ARCODECS_Manager_t](#) * **decoder**
- int **decodingCanceled**
- ARSAL_Thread_t **decodingThread**
- int **hasReceivedFirstIframe**
- [RawFrame_t](#) ** **freeRawFramePool**
- int **rawFramePoolCapacity**
- int **lastRawFrameFreeIdx**
- [RawFrame_t](#) ** **rawFrameFifo**
- int **fifoReadIdx**
- int **fifoWriteIdx**
- eARCOMMANDS_ARDRONE3_PILOTINGSTATE_FLYINGSTATECHANGED_STATE **flyingState**
- FILE * **video_out**
- ARSAL_Mutex_t **mutex**
- ARSAL_Thread_t * **readerThreads**
- [READER_THREAD_DATA_t](#) * **readerThreadsData**
- int **run**
- [IHM_t](#) * **ihm**

The documentation for this struct was generated from the following file:

- [BebopDroneDecodeStream.h](#)

4.7 BD_PCMD_t Struct Reference

Public Attributes

- int **flag**
- int **roll**
- int **pitch**
- int **yaw**
- int **gaz**

The documentation for this struct was generated from the following file:

- BebopDroneDecodeStream.h

4.8 IHM_t Struct Reference

Public Attributes

- WINDOW * **mainWindow**
- ARSAL_Thread_t **inputThread**
- int **run**
- IHM_onInputEvent_t **onInputEventCallback**
- void * **customData**

The documentation for this struct was generated from the following file:

- ihm.h

4.9 RawFrame_t Struct Reference

Component of a frame.

Public Attributes

- uint8_t * [data](#)
- uint32_t [size](#)
- uint8_t **isIframe**

4.9.1 Detailed Description

Component of a frame.

4.9.2 Member Data Documentation

4.9.2.1 uint8_t* RawFrame_t::data

data buffer

4.9.2.2 uint32_t RawFrame_t::size

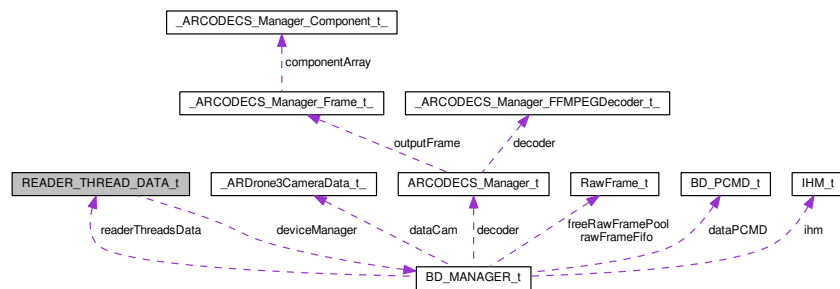
size of the buffer

The documentation for this struct was generated from the following file:

- [BebopDroneDecodeStream.c](#)

4.10 READER_THREAD_DATA_t Struct Reference

Collaboration diagram for READER_THREAD_DATA_t:



Public Attributes

- `BD_MANAGER_t * deviceManager`
- `int readerBufferId`

The documentation for this struct was generated from the following file:

- [BebopDroneDecodeStream.h](#)

Chapter 5

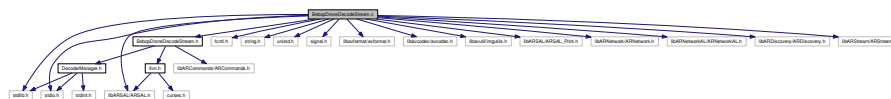
File Documentation

5.1 BebopDroneDecodeStream.c File Reference

This file contains sources about basic arsdk example decoding video stream from a BebopDrone with ffmpeg.

```
#include <stdlib.h>
#include <stdio.h>
#include <fcntl.h>
#include <string.h>
#include <unistd.h>
#include <signal.h>
#include <libavformat/avformat.h>
#include <libavcodec/avcodec.h>
#include <libavutil/imgutils.h>
#include <libARSAL/ARSAL.h>
#include <libARSAL/ARSAL_Print.h>
#include <libARNetwork/ARNetwork.h>
#include <libARNetworkAL/ARNetworkAL.h>
#include <libARDiscovery/ARDiscovery.h>
#include <libARStream/ARStream.h>
#include "BebopDroneDecodeStream.h"
```

Include dependency graph for BebopDroneDecodeStream.c:



Classes

- struct [RawFrame_t](#)
Component of a frame.

Macros

- #define **TAG** "BebopDroneReceiveStream"
- #define **BD_IP_ADDRESS** "192.168.42.1"
- #define **BD_DISCOVERY_PORT** 44444
- #define **BD_C2D_PORT** 54321
- #define **BD_D2C_PORT** 43210

- `#define BD_NET_CD_NONACK_ID 10`
- `#define BD_NET_CD_ACK_ID 11`
- `#define BD_NET_CD_EMERGENCY_ID 12`
- `#define BD_NET_CD_VIDEO_ACK_ID 13`
- `#define BD_NET_DC_NAVDATA_ID 127`
- `#define BD_NET_DC_EVENT_ID 126`
- `#define BD_NET_DC_VIDEO_DATA_ID 125`
- `#define BD_NET_DC_VIDEO_FRAG_SIZE 65000`
- `#define BD_NET_DC_VIDEO_MAX_NUMBER_OF_FRAG 4`
- `#define BD_RAW_FRAME_BUFFER_SIZE 50`
- `#define BD_RAW_FRAME_POOL_SIZE 50`
- `#define ERROR_STR_LENGTH 2048`
- `#define FIFO_DIR_PATTERN "/tmp/arsdk_XXXXXX"`
- `#define FIFO_NAME "arsdk_fifo"`

Functions

- `int getNextDataCallback (uint8_t **data, void *customData)`
- `void * Decode_RunDataThread (void *customData)`
- `RawFrame_t * getFreeRawFrame (BD_MANAGER_t *deviceManager)`
- `void addFreeRawFrameToFifo (BD_MANAGER_t *deviceManager, RawFrame_t *rawFrame)`
- `void flushFifo (BD_MANAGER_t *deviceManager)`
- `void putRawFrameBackToPool (BD_MANAGER_t *deviceManager, int fifoldx)`
- `RawFrame_t * getFrameFromData (BD_MANAGER_t *deviceManager, uint8_t *data)`
- `int main (int argc, char *argv[])`
- `int ardiscoveryConnect (BD_MANAGER_t *deviceManager)`
- `eARDISCOVERY_ERROR ARDISCOVERY_Connection_SendJsonCallback (uint8_t *dataTx, uint32_t *dataTxSize, void *customData)`
- `eARDISCOVERY_ERROR ARDISCOVERY_Connection_ReceiveJsonCallback (uint8_t *dataRx, uint32_t dataRxSize, char *ip, void *customData)`
- `int startNetwork (BD_MANAGER_t *deviceManager)`
- `void stopNetwork (BD_MANAGER_t *deviceManager)`
- `void onDisconnectNetwork (ARNETWORK_Manager_t *manager, ARNETWORKAL_Manager_t *alManager, void *customData)`
- `int startVideo (BD_MANAGER_t *deviceManager)`
- `void stopVideo (BD_MANAGER_t *deviceManager)`
- `uint8_t * frameCompleteCallback (eARSTREAM_READER_CAUSE cause, uint8_t *frame, uint32_t frameSize, int numberOfSkippedFrames, int isFlushFrame, uint32_t *newBufferCapacity, void *custom)`
- `int sendPCMD (BD_MANAGER_t *deviceManager)`
- `int sendCameraOrientation (BD_MANAGER_t *deviceManager)`
- `int sendDate (BD_MANAGER_t *deviceManager)`
- `int sendAllSettings (BD_MANAGER_t *deviceManager)`
- `int sendAllStates (BD_MANAGER_t *deviceManager)`
- `int sendBeginStream (BD_MANAGER_t *deviceManager)`
- `int sendTakeoff (BD_MANAGER_t *deviceManager)`
- `int sendLanding (BD_MANAGER_t *deviceManager)`
- `int sendEmergency (BD_MANAGER_t *deviceManager)`
- `eARNETWORK_MANAGER_CALLBACK_RETURN arnetworkCmdCallback (int buffer_id, uint8_t *data, void *custom, eARNETWORK_MANAGER_CALLBACK_STATUS cause)`
- `void registerARCommandsCallbacks (BD_MANAGER_t *deviceManager)`
- `void unregisterARCommandsCallbacks (void)`
- `void batteryStateChangedCallback (uint8_t percent, void *custom)`
- `void flyingStateChangedCallback (eARCOMMANDS_ARDRONE3_PILOTINGSTATE_FLYINGSTATE_CHANGED_STATE state, void *custom)`
- `int startDecoder (BD_MANAGER_t *deviceManager)`
- `void stopDecoder (BD_MANAGER_t *deviceManager)`
- `void onInputEvent (eIHM_INPUT_EVENT event, void *customData)`
- `int customPrintCallback (eARSAL_PRINT_LEVEL level, const char *tag, const char *format, va_list va)`

Variables

- int **gIHMRUN** = 0
- char **gErrorStr** [ERROR_STR_LENGTH]

5.1.1 Detailed Description

This file contains sources about basic arsdk example decoding video stream from a BebopDrone with ffmpeg.

Date

08/01/2015

5.1.2 Function Documentation

5.1.2.1 int ardiscoveryConnect (**BD_MANAGER_t** * *deviceManager*)

Connection part

5.1.2.2 eARNETWORK_MANAGER_CALLBACK_RETURN arnetworkCmdCallback (int *buffer_id*, uint8_t * *data*, void * *custom*, eARNETWORK_MANAGER_CALLBACK_STATUS *cause*)

Commands part

5.1.2.3 int getNextDataCallback (uint8_t ** *data*, void * *customData*)

Handle older ffmpeg/libav versions

5.1.2.4 void onInputEvent (eIHM_INPUT_EVENT *event*, void * *customData*)

IHM callbacks

5.1.2.5 void registerARCommandsCallbacks (**BD_MANAGER_t** * *deviceManager*)

Commands callback part

5.1.2.6 int startDecoder (**BD_MANAGER_t** * *deviceManager*)

decoding part

5.1.2.7 int startNetwork (**BD_MANAGER_t** * *deviceManager*)

Network part

5.1.2.8 int startVideo (**BD_MANAGER_t** * *deviceManager*)

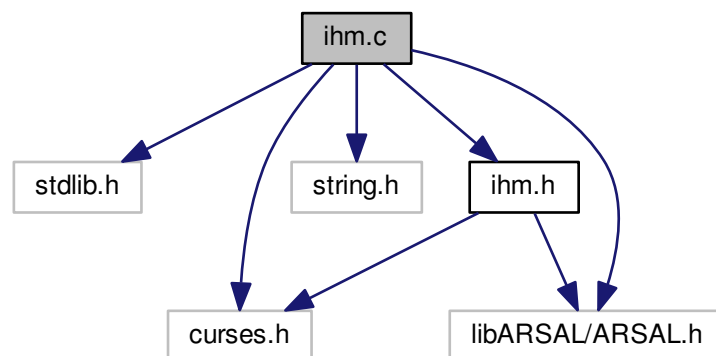
Video part

5.2 ihm.c File Reference

This file contains sources about ncurses IHM used by arsdk example "BebopDroneDecodeStream".

```
#include <stdlib.h>
#include <curses.h>
#include <string.h>
#include <libARSAL/ARSAL.h>
#include "ihm.h"
```

Include dependency graph for ihm.c:



Macros

- #define **HEADER_X** 0
- #define **HEADER_Y** 0
- #define **INSTRUCTION_X** 0
- #define **INSTRUCTION_Y** 2
- #define **BATTERY_X** 0
- #define **BATTERY_Y** 10
- #define **INFO_X** 0
- #define **INFO_Y** 12

Functions

- void * **IHM_InputProcessing** (void *data)
- **IHM_t** * **IHM_New** (IHM_onInputEvent_t onInputEventCallback)
- void **IHM_Delete** (**IHM_t** **ihm)
- void **IHM_setCustomData** (**IHM_t** *ihm, void *customData)
- void **IHM_PrintHeader** (**IHM_t** *ihm, char *headerStr)
- void **IHM_PrintInstruction** (**IHM_t** *ihm, char *instructionStr)
- void **IHM_PrintInfo** (**IHM_t** *ihm, char *infoStr)
- void **IHM_PrintBattery** (**IHM_t** *ihm, uint8_t percent)

5.2.1 Detailed Description

This file contains sources about ncurses IHM used by arsdk example "BebopDroneDecodeStream".

Date

15/01/2015

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