

BebopPilotingNewAPI

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Chapter 1

README

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Purpose of BebopPilotingNewAPI

This sample shows how to send and receive commands to communicate with a Parrot drone. The example is based on the Bebop Drone, using the new ARController API.

Dependencies of BebopPilotingNewAPI

You will need ncurses-dev

On Linux you can get ncurses-dev apt-get: `&apt-get install ncurses-dev`

You will need mplayer to use the DISPLAY_WITH_MPLAYER.

To compile SDK Example BebopPilotingNewAPI

On Linux and MacOS X platform : `&make`

To run SDK Example BebopPilotingNewAPI

On Linux and MacOS X platform : `&make run`

After having run the sample, you might have a weird terminal, because we use ncurses. To fix it, you can simply run the command *reset*.

To clean the compilation of BebopPilotingNewAPI

On Linux and MacOS X platform : `&make clean`

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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Chapter 3

File Index

3.1 File List

Here is a list of all documented files with brief descriptions:

[BebopPiloting.c](#)

This file contains sources about basic arsdk example sending commands to a bebop drone for piloting it and make it jump it and receiving its battery level [9](#)

BebopPiloting.h **??**

[ihm.c](#)

This file contains sources about ncurses IHM used by arsdk example "JumpingSumoPiloting" . [10](#)

ihm.h **??**

Chapter 4

Class Documentation

4.1 IHM_t Struct Reference

Public Attributes

- WINDOW * **mainWindow**
- ARSAL_Thread_t **inputThread**
- int **run**
- IHM_onInputEvent_t **onInputEventCallback**
- void * **customData**

The documentation for this struct was generated from the following file:

- ihm.h

Chapter 5

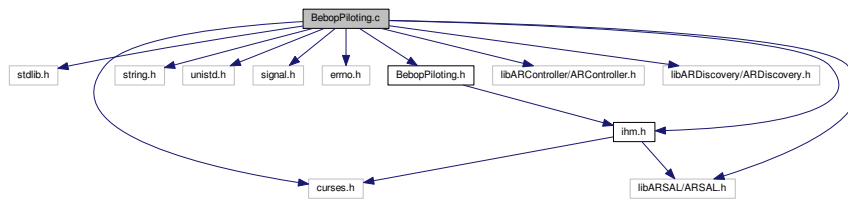
File Documentation

5.1 BebopPiloting.c File Reference

This file contains sources about basic arsdk example sending commands to a bebop drone for piloting it and make it jump it and receiving its battery level.

```
#include <stdlib.h>
#include <curses.h>
#include <string.h>
#include <unistd.h>
#include <signal.h>
#include <errno.h>
#include <libARSAL/ARSAL.h>
#include <libARController/ARController.h>
#include <libARDiscovery/ARDiscovery.h>
#include "BebopPiloting.h"
#include "ihm.h"
```

Include dependency graph for BebopPiloting.c:



Macros

- `#define TAG "SDKExample"`
- `#define ERROR_STR_LENGTH 2048`
- `#define BEBOP_IP_ADDRESS "192.168.42.1"`
- `#define BEBOP_DISCOVERY_PORT 44444`
- `#define DISPLAY_WITH_MPLAYER 1`
- `#define FIFO_DIR_PATTERN "/tmp/arsdk_XXXXXX"`
- `#define FIFO_NAME "arsdk_fifo"`
- `#define IHM`

Functions

- int **main** (int argc, char *argv[])
- void **stateChanged** (eARCONTROLLER_DEVICE_STATE newState, eARCONTROLLER_ERROR error, void *customData)
- void **commandReceived** (eARCONTROLLER_DICTIONARY_KEY commandKey, ARCONTROLLER_DICTIONARY_ELEMENT_t *elementDictionary, void *customData)
- void **batteryStateChanged** (uint8_t percent)
- eARCONTROLLER_ERROR **decoderConfigCallback** (ARCONTROLLER_Stream_Codec_t codec, void *customData)
- eARCONTROLLER_ERROR **didReceiveFrameCallback** (ARCONTROLLER_Frame_t *frame, void *customData)
- void **onInputEvent** (eIHM_INPUT_EVENT event, void *customData)
- int **customPrintCallback** (eARSAL_PRINT_LEVEL level, const char *tag, const char *format, va_list va)

Variables

- int **gIHMRUN** = 1
- char **gErrorStr** [ERROR_STR_LENGTH]
- **IHM_t** * **ihm** = NULL
- FILE * **videoOut** = NULL
- int **frameNb** = 0
- ARSAL_Sem_t **stateSem**
- int **isBebop2** = 0

5.1.1 Detailed Description

This file contains sources about basic arsdk example sending commands to a bebop drone for piloting it and make it jump it and receiving its battery level.

Date

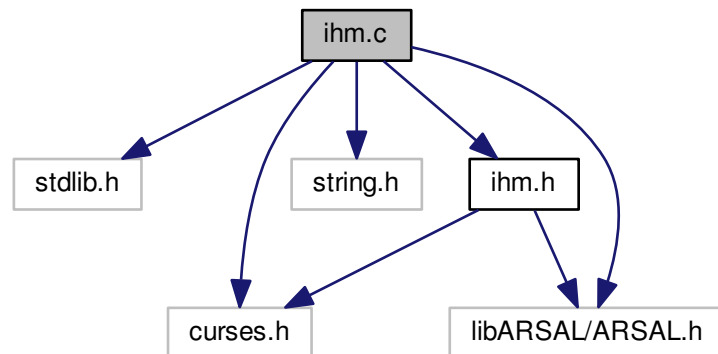
15/01/2015

5.2 ihm.c File Reference

This file contains sources about ncurses IHM used by arsdk example "JumpingSumoPiloting".

```
#include <stdlib.h>
#include <ncurses.h>
#include <string.h>
#include <libARSAL/ARSAL.h>
#include "ihm.h"
```

Include dependency graph for ihm.c:



Macros

- `#define HEADER_X 0`
- `#define HEADER_Y 0`
- `#define INFO_X 0`
- `#define INFO_Y 2`
- `#define BATTERY_X 0`
- `#define BATTERY_Y 4`

Functions

- `void * IHM_InputProcessing (void *data)`
- `IHM_t * IHM_New (IHM_onInputEvent_t onInputEventCallback)`
- `void IHM_Delete (IHM_t **ihm)`
- `void IHM_setCustomData (IHM_t *ihm, void *customData)`
- `void IHM_PrintHeader (IHM_t *ihm, char *headerStr)`
- `void IHM_PrintInfo (IHM_t *ihm, char *infoStr)`
- `void IHM_PrintBattery (IHM_t *ihm, uint8_t percent)`

5.2.1 Detailed Description

This file contains sources about ncurses IHM used by arsdk example "JumpingSumoPiloting".

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