Master of Science on Computational Science

Institute of Computational Science

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31 Oct 2016, LAB5

Slow FE Assembly using MATLAB

```
function [M,K,b] = assembleDiscreteOperators(mesh)
 N
     = mesh.N;
 Ne = mesh.N_e;
 M = zeros(N,N); K = zeros(N,N);
 b = zeros(N,1);
 for e=1:N e
   Me = makeMe(e, mesh);
   Ke = makeKe(e, mesh);
   fp = makebe(e, mesh);
   I = mesh.Elements(e, :);
   M(I, I) = M(I, I) + Me;
   K(I, I) = K(I, I) + Ke;
   b(I) = b(I) + Me*fp;
 end % e loop
end
```

FE Assembly using MATLAB

```
function [A] = assembleFast(mesh)
  ele_nodes = mesh.N_e * mesh.N_v^2;
  K = zeros(1. ele nodes): iK = zeros(1. ele nodes):
  jK = zeros(1, ele_nodes); i = 1:mesh.N_v; j = ones(1, mesh.N_v);
  % ig = [1..nv, 1..nv, ... 1..nv] nv times
          = repmat(i,1,mesh.N_v);
  ig
 \% jg = [1 1 ... 1, 2 2 ... 2, ... , nv nv ... nv]
          = repmat(1:mesh.N_v, mesh.N_v,1);
  jg
  jg = jg(:)'; b = zeros(mesh.nodes,1);
  k
     = 1:mesh.N v^2:
 for e = 1:mesh.N e
   Me = makeMe(mesh.dx, mesh.dy); me = Me(:);
   Ke = makeKe(mesh.dx, mesh.dy); ke = Ke(:);
   I = mesh.Elements(e,:); iK(k) = I(ig); jK(k) = I(jg);
   x_e = mesh.Points(I,:); f_e = makeSource(x_e);
   b(I) = b(I) + Me*f e:
   Kg(k) = ke + me; k = k + mesh.N_v^2;
 end
 A = sparse(iK, jK, K);
end
```

Fast FE Assembly using MATLAB

```
function [As,b] = assembleFast(mesh)
 Мe
    = makeMe(mesh):
 Ke = makeKe(mesh):
 me = Me(:):
 ke = Ke(:):
 M = repmat(me, mesh.N_e, 1);
 K = repmat(ke, mesh.N_e, 1);
 i=1:mesh.N_v; j=ones(1, mesh.N_v);
 \% ig = [1..N_v, 1..N_v, ... 1..N_v] N_v times
 ig=repmat(i, 1, mesh.N_v);
 \% jg = [1 1 ... 1, 2 2 ... 2, ... , N_v N_v N_v ... N_v]
 jg=repmat(1:mesh.N_v, mesh.N_v, 1); jg=jg(:)';
 iΑ
      = mesh.Elements(:,ig)';
 jA = mesh.Elements(:,jg)';
      = K + M:
       = sparse(iA(:), jA(:), A, mesh.N, mesh.N);
 Аs
```

Fast FE Assembly of rhs using MATLAB

```
% this is just a vector form of the source function
  f = makeSource(mesh.Points);
  I = mesh.Elements';
  F = f(I):
  b = Me*F;
 I = I(:);
  J = ones(mesh.N_v*mesh.N_e, 1);
  B = sparse(I, J, b(:), mesh.N, 1);
  [I, J, b] = find(B);
end
```