

KommunikasjonsProtokoll

Generated by Doxygen 1.8.14

Contents

1	My Personal Index Page	1
1.1	Introduction	1
1.2	Installation	1
1.2.1	Step 1: Opening the box	1
2	Class Index	3
2.1	Class List	3
3	File Index	5
3.1	File List	5
4	Class Documentation	7
4.1	circular_buf_t Struct Reference	7
4.2	packet_data Struct Reference	7
5	File Documentation	9
5.1	comm.c File Reference	9
5.1.1	Detailed Description	10
5.2	comm.h File Reference	10
5.2.1	Detailed Description	11
5.3	main.c File Reference	11
5.3.1	Detailed Description	12
5.3.2	Function Documentation	12
5.3.2.1	circular_buf_put()	12
5.3.2.2	Port_Init()	13
	Index	15

Chapter 1

My Personal Index Page

1.1 Introduction

This is the introduction.

1.2 Installation

1.2.1 Step 1: Opening the box

etc...

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

circular_buf_t	7
packet_data	7

Chapter 3

File Index

3.1 File List

Here is a list of all documented files with brief descriptions:

comm.c	All the configurations for SPI and I2C Author: Christoffer Boothby. Version: 0.0.1.2. Comments:	9
comm.h	All the defines for the COMM.c usage. Author: Christoffer Boothby. Version: 0.0.1.↔ 2. Comments:	10
Error.h	??
main.c	Main program for the G-Chaser Project using Atmega328PB. Author: Christoffer Boothby Version: 0.0.1.2 Comments:	11

Chapter 4

Class Documentation

4.1 circular_buf_t Struct Reference

Public Attributes

- uint8_t * **buffer**
- uint8_t volatile **head**
- uint8_t volatile **tail**
- uint8_t **size**

The documentation for this struct was generated from the following file:

- [main.c](#)

4.2 packet_data Struct Reference

Public Attributes

- uint8_t volatile **mainComm_Counter**
- uint8_t volatile **subComm_Counter**
- uint8_t volatile **maxMainComms**
- uint16_t **crc16**

The documentation for this struct was generated from the following file:

- [main.c](#)

Chapter 5

File Documentation

5.1 comm.c File Reference

All the configurations for SPI and I2C Author: Christoffer Boothby. Version: 0.0.1.2. Comments:.

```
#include <stdint.h>
#include "comm.h"
#include <avr/io.h>
#include <util/twi.h>
#include <avr/interrupt.h>
#include <util/delay.h>
#include <util/atomic.h>
```

Macros

- #define **PORT_SPI** PORTB
- #define **DDR_SPI** DDRB
- #define **DD_MISO** DDRB4
- #define **DD_MOSI** DDRB3
- #define **DD_SCK** DDRB5
- #define **TWI_FREQ** 2000
- #define **Prescaler** 64

Functions

- void **spi_init_adc** ()
- void **spiTransmitADC_1** (uint8_t *dataout, uint8_t datain)
- void **spiTransmitADC_2** (uint8_t *dataout, uint8_t datain)
- void **spi_init_dac** ()
- void **spiTransmitDAC_1** (uint8_t dacAdress, uint8_t dacData)
- void **spiTransmitDAC_2** (uint8_t dacAdress, uint8_t dacData)
- void **i2c_init** (void)
- uint8_t **i2c_start** (uint8_t address)
- uint8_t **i2c_write** (uint8_t data)
- uint8_t **i2c_read_ack** (void)
- uint8_t **i2c_read_nack** (void)
- uint8_t **i2c_transmit** (uint8_t address, uint8_t *data, uint16_t length)
- uint8_t **i2c_receive** (uint8_t address, uint8_t *data, uint16_t length)
- uint8_t **i2c_writeReg** (uint8_t devaddr, uint8_t regaddr, uint8_t *data, uint16_t length)
- uint8_t **i2c_readReg** (uint8_t devaddr, uint8_t regaddr, uint8_t *data, uint16_t length)
- void **i2c_stop** (void)

5.1.1 Detailed Description

All the configurations for SPI and I2C Author: Christoffer Boothby. Version: 0.0.1.2. Comments:.

5.2 comm.h File Reference

All the defines for the [COMM.c](#) usage. Author: Christoffer Boothby. Version: 0.0.1.2. Comments:.

```
#include <stdint.h>
```

Macros

- `#define COMM_H_`
- `#define F_CPU (14745600UL)`
- `#define ADV_CONVERSION_START_1 DDRE2`
- `#define ADC_READ_1 DDRE3`
- `#define ADC_1_BUSY DDRC0`
- `#define ADV_CONVERSION_START_2 DDRB6`
- `#define ADC_READ_2 DDD7`
- `#define ADC_2_BUSY DDRB0`
- `#define CS_DAC_1 DDRC1`
- `#define LD_DAC_1 DDRC2`
- `#define CS_DAC_2 DDRB1`
- `#define LD_DAC_2 DDRB2`
- `#define LTC1859_CH0 0b10000100`
- `#define LTC1859_CH1 0b11010100`
- `#define LTC1859_CH2 0b10010100`
- `#define LTC1859_CH3 0b11010100`
- `#define LTC1859_CH4 0b10100100`
- `#define LTC1859_CH5 0b11100100`
- `#define LTC1859_CH6 0b10110100`
- `#define LTC1859_CH7 0b11110100`
- `#define G1_BIAS_1 (uint16_t)0xFFFF`
- `#define G2_BIAS_1 (uint16_t)0xFFFF`
- `#define G3_BIAS_1 (uint16_t)0xFFFF`
- `#define G1_BIAS_2 (uint16_t)0xFFFF`
- `#define G2_BIAS_2 (uint16_t)0xFFFF`
- `#define G3_BIAS_2 (uint16_t)0xFFFF`
- `#define DAC_B 0x4`
- `#define DAC_C 0x8`
- `#define DAC_D 0xC`
- `#define U7_ADDR 0xD2`
- `#define U8_ADDR 0xCE`
- `#define U9_ADDR 0xDE`
- `#define I2C_READ 0x01`
- `#define I2C_WRITE 0x00`

Functions

- void **spi_init_dac** ()
- void **spi_init_adc** ()
- void **spiTransmitADC_1** (uint8_t *dataout, uint8_t datain)
- void **spiTransmitADC_2** (uint8_t *dataout, uint8_t datain)
- void **spiTransmitDAC_1** (uint8_t dacAddress, uint8_t dacData)
- void **spiTransmitDAC_2** (uint8_t dacAddress, uint8_t dacData)
- void **i2c_init** (void)
- uint8_t **i2c_start** (uint8_t address)
- uint8_t **i2c_write** (uint8_t data)
- uint8_t **i2c_read_ack** (void)
- uint8_t **i2c_read_nack** (void)
- uint8_t **i2c_transmit** (uint8_t address, uint8_t *data, uint16_t length)
- uint8_t **i2c_receive** (uint8_t address, uint8_t *data, uint16_t length)
- uint8_t **i2c_writeReg** (uint8_t devaddr, uint8_t regaddr, uint8_t *data, uint16_t length)
- uint8_t **i2c_readReg** (uint8_t devaddr, uint8_t regaddr, uint8_t *data, uint16_t length)
- void **i2c_stop** (void)

5.2.1 Detailed Description

All the defines for the [COMM.c](#) usage. Author: Christoffer Boothby. Version: 0.0.1.2. Comments:.

5.3 main.c File Reference

Main program for the G-Chaser Project using Atmega328PB. Author: Christoffer Boothby Version: 0.0.1.↵
2 Comments:

```
#include "comm.h"
#include <stdint.h>
#include <avr/io.h>
#include <avr/interrupt.h>
#include <stdbool.h>
#include <stdlib.h>
#include <util/crc16.h>
#include <util/delay.h>
#include <util/twi.h>
#include <util/atomic.h>
#include <util/setbaud.h>
```

Classes

- struct [circular_buf_t](#)
- struct [packet_data](#)

Macros

- #define **BAUD** 1200
- #define **UART_BUFFER_SIZE** 128
- #define **UART_TX0_MAXBUFFER** (UART_BUFFER_SIZE-1)

Functions

- void `circular_buf_put` (`circular_buf_t` *cbuf, `packet_data` *pData, uint8_t data)
Putting 1 byte into the buffer.
- void `Port_Init` ()
Port initialization function.
- void `USART_Init` ()
- `ISR` (USART0_UDRE_vect)
- void `subCommFormat` (`circular_buf_t` *cbuf, `packet_data` *pData)
- void `packetFormat` (`circular_buf_t` *cbuf, `packet_data` *pData)
- int `main` (void)

Variables

- `circular_buf_t` `cbuf`
- `packet_data` `pData`
- uint8_t `array` [UART_BUFFER_SIZE]
- uint8_t `testvalue`

5.3.1 Detailed Description

Main program for the G-Chaser Project using Atmega328PB. Author: Christoffer Boothby Version: 0.0.1.↩
2 Comments:

5.3.2 Function Documentation

5.3.2.1 `circular_buf_put()`

```
void circular_buf_put (
    circular_buf_t * cbuf,
    packet_data * pData,
    uint8_t data )
```

Putting 1 byte into the buffer.

Parameters

in	<code>data</code>	The data that goes into the buffer.
in	<code>cbuf</code>	refrence to the circular buffer.
in	<code>pdata</code>	refrence for pdata.

Returns

None.

5.3.2.2 Port_Init()

```
void Port_Init ( )
```

Port initialization function.

Parameters

<i>None.</i>	
--------------	--

Returns

None.

Index

- circular_buf_put
 - main.c, [12](#)
- circular_buf_t, [7](#)
- comm.c, [9](#)
- comm.h, [10](#)
- main.c, [11](#)
 - circular_buf_put, [12](#)
 - Port_Init, [12](#)
- packet_data, [7](#)
- Port_Init
 - main.c, [12](#)