

Delaunay Triangulations on the GPU

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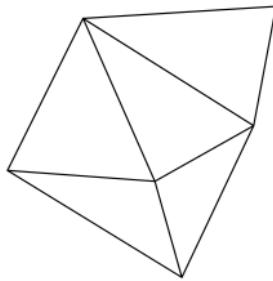


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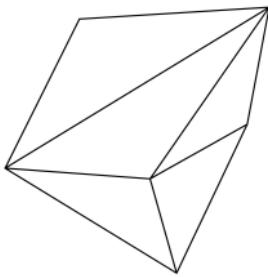
What is a Triangulation

Definition 1.

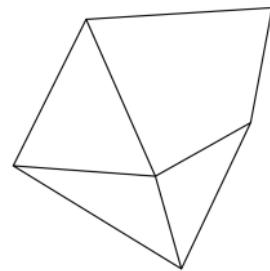
A *triangulation* of a planar point set P is a subdivision of the plane determined by a maximal set of non-crossing edges whose vertex set is P .



(a)



(b)



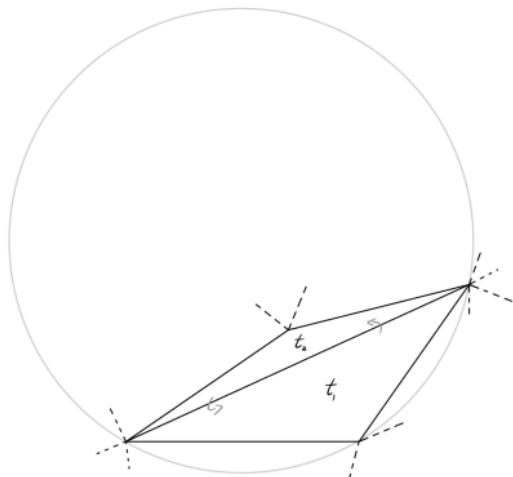
(c)

Figure 1: Examples of two triangulations (a) (b) on the same set of points. In (c) an illustration of a non maximal set of edges.

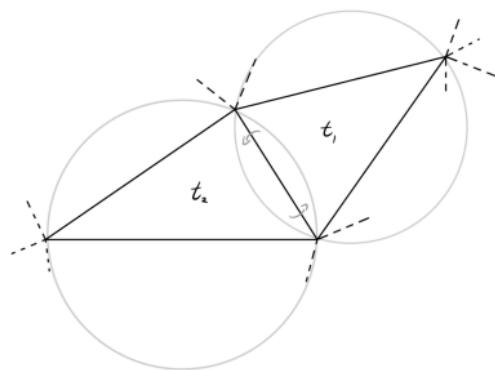
What is a Delaunay Triangulation

Definition 2.

A *Delaunay triangulation* of a point set P is a triangulation such that the circumsphere of any triangle in the triangulation does not contain any other point in P .

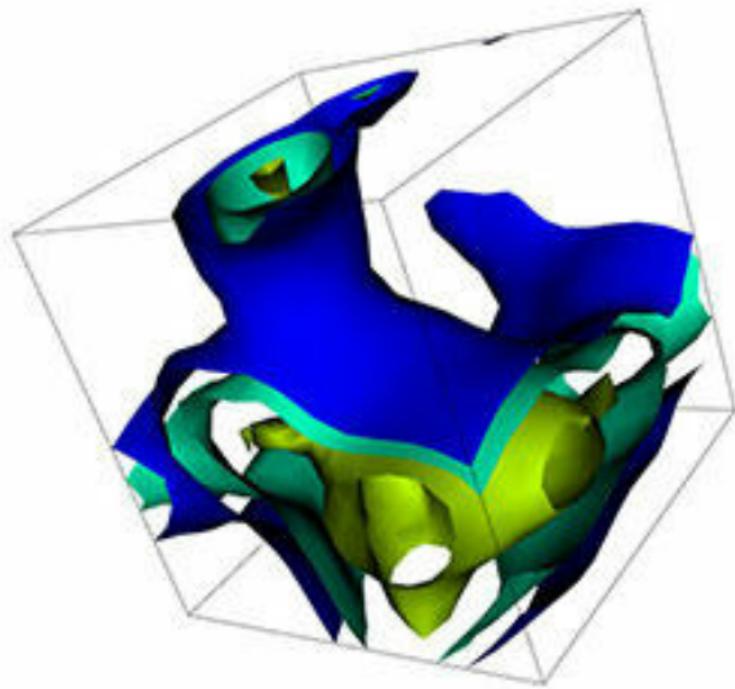


(a)



(b)

Why Delaunay Triangulations



The Algorithm

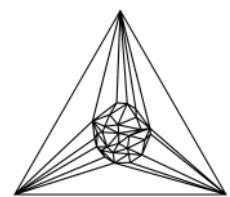
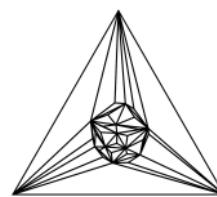
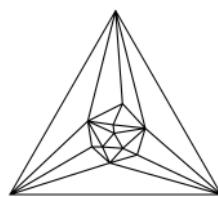
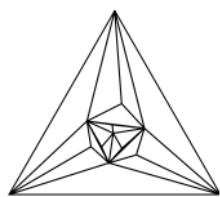
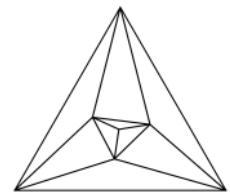
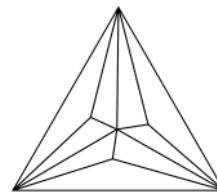
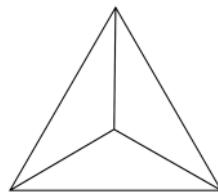
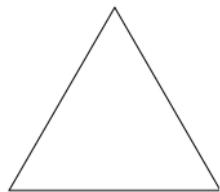
Parallel Algorithm

Algorithm 1: Parallel point insertion and flipping

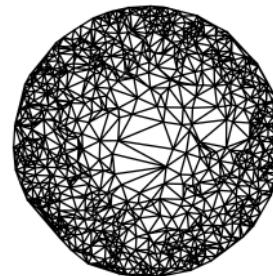
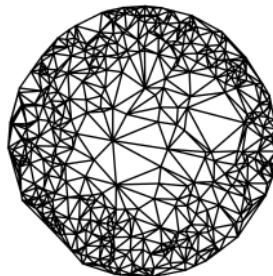
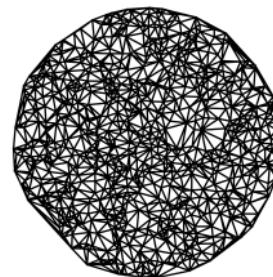
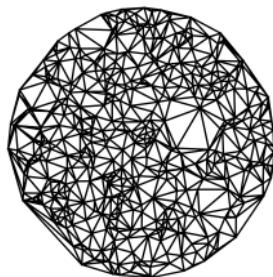
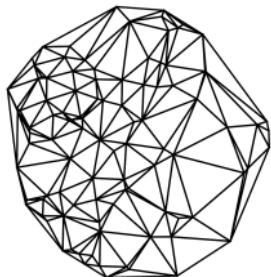
Data: A point set P
Out: Delaunay Triangulation T

- 1 Initialize T with a triangle t enclosing all points in P
- 2 Initialize locations of $p \in P$ to all lie in t
- 3 **while** there are $p \in P$ to insert
- 4 **for each** $p \in P$ **do in parallel**
 - | choose $p_t \in P$ to insert if any
- 5 **for each** $t \in T$ with p_t to insert **do in parallel**
 - | split t
- 6 **while** there are illegal edges
 - | **for each** triangle $t \in T$ **do in parallel**
 - | mark whether it should be flipped
 - | **for each** triangle $t \in T$ in a configuration marked to flip **do in parallel**
 - | flip t
- 7 update locations of $p \in P$
- 8 return T

Visualization



Visualization



Challenges

GPU programming

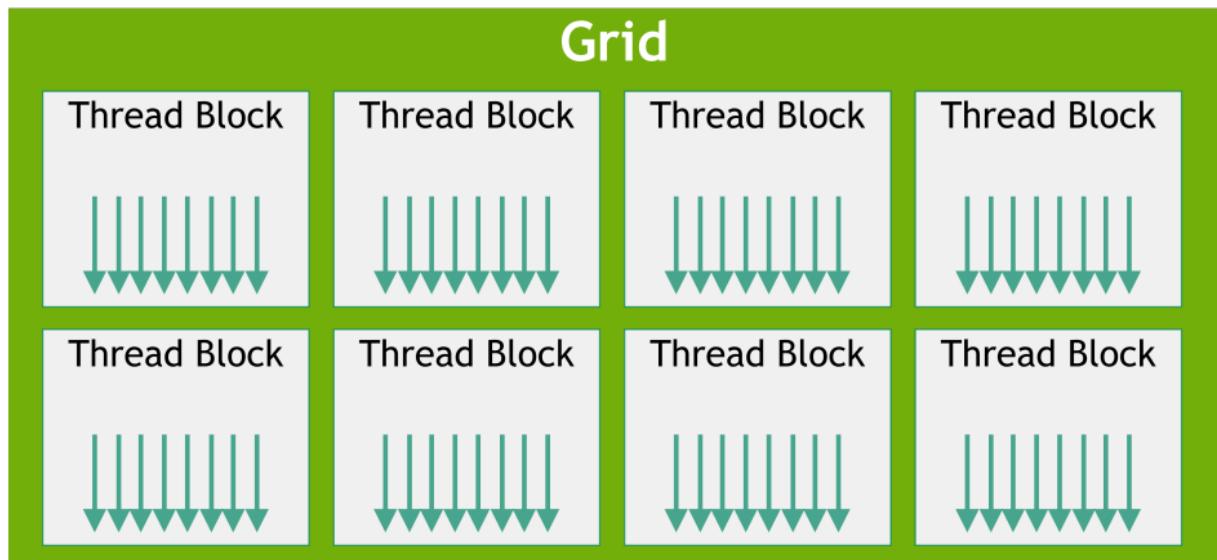
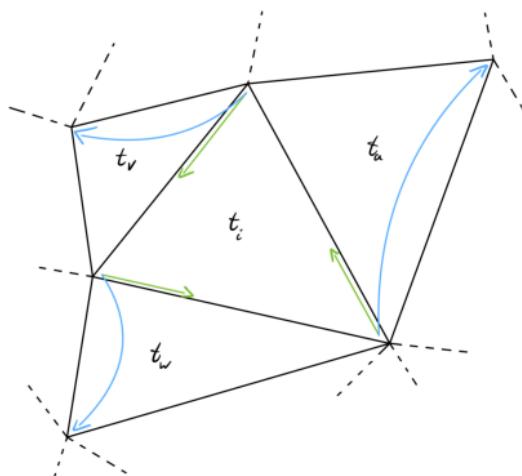
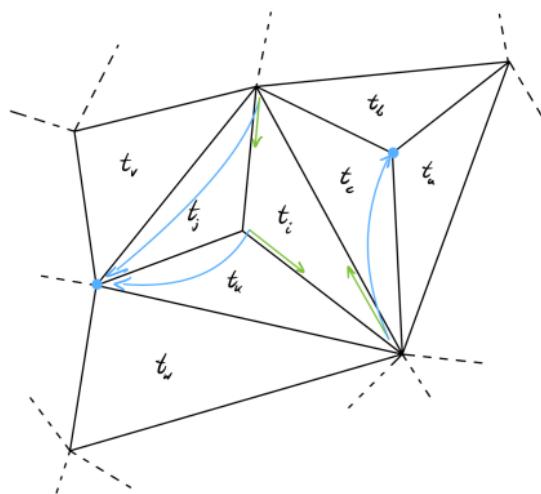


Figure 6: An illustration of the structure of the GPU programming model.

Parallel point insertion

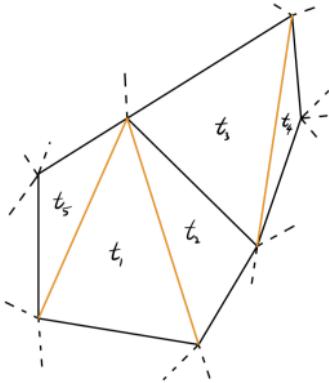


(a) Before insertion.

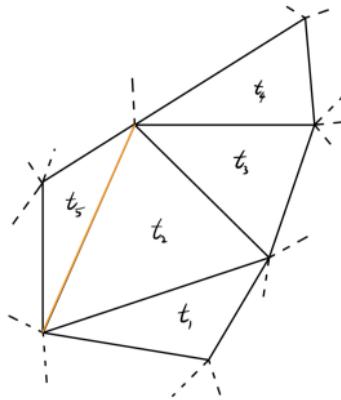


(b) After insertion.

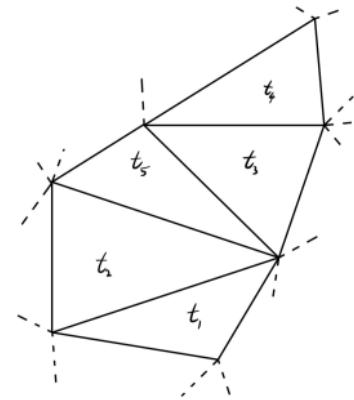
Parallel flipping



(a) Pass 0



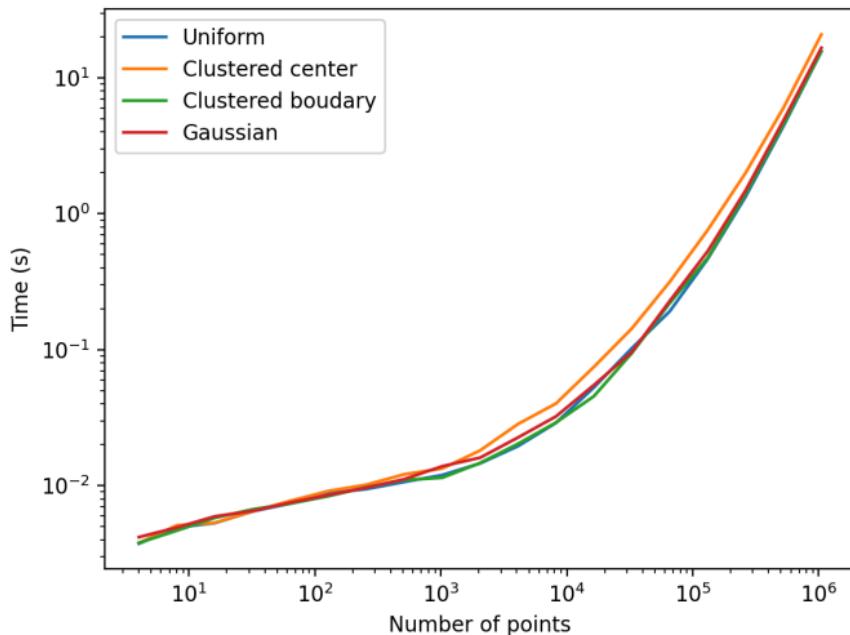
(b) Pass 1



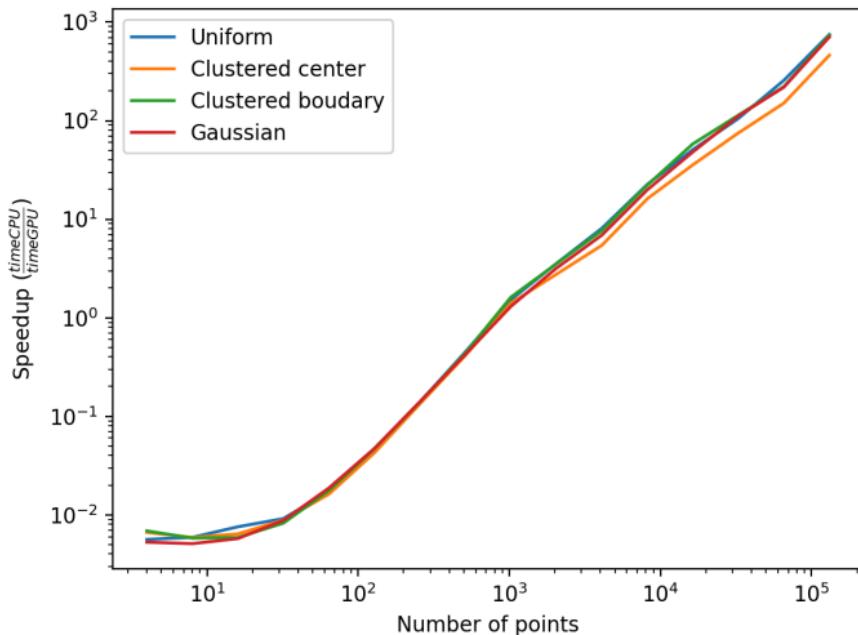
(c) Pass 2

Analysis

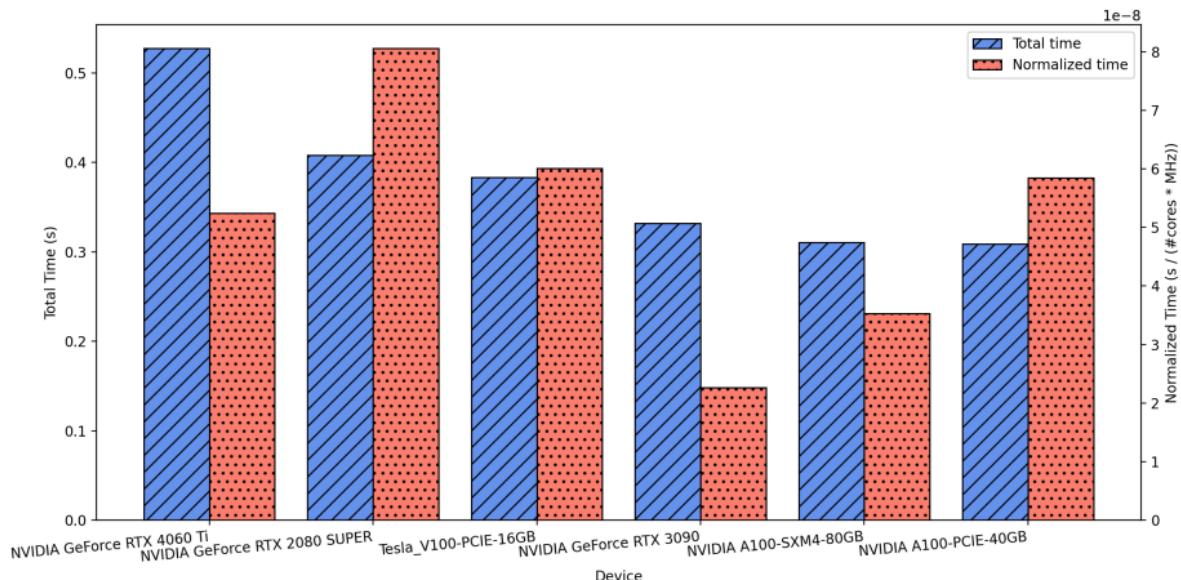
Timing



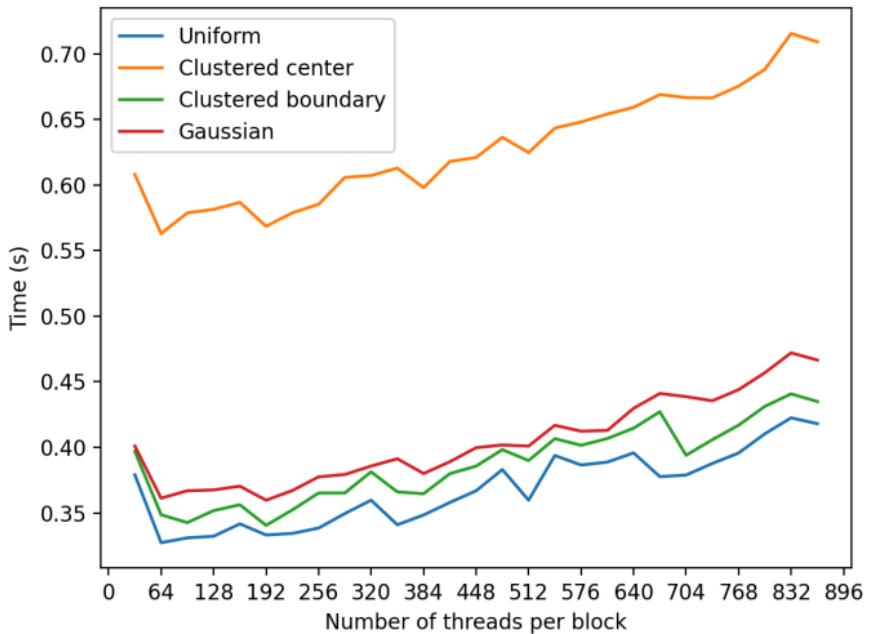
Speedup



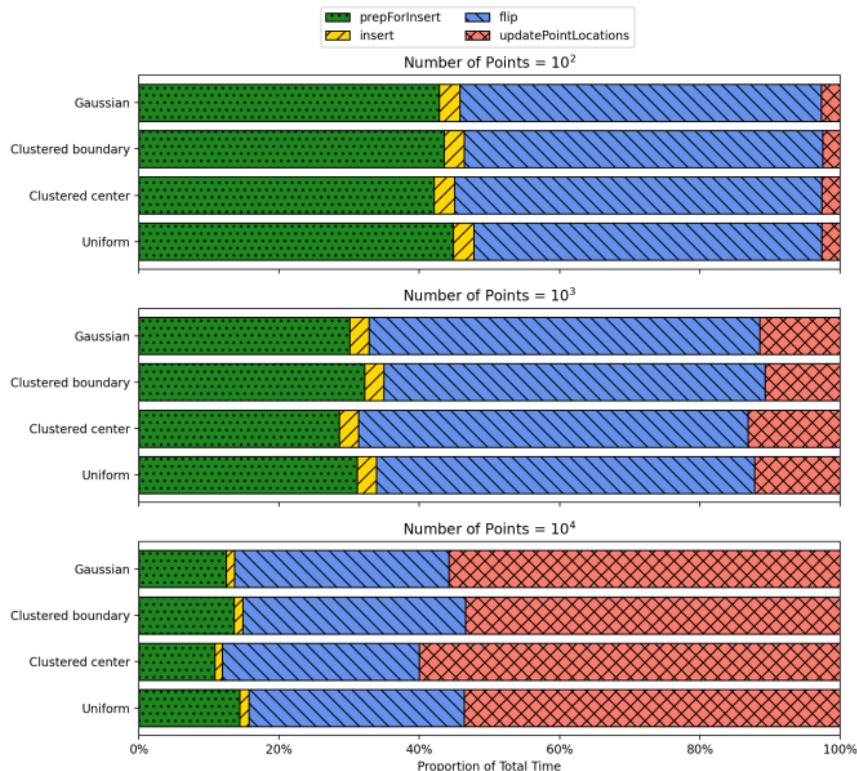
Scaling



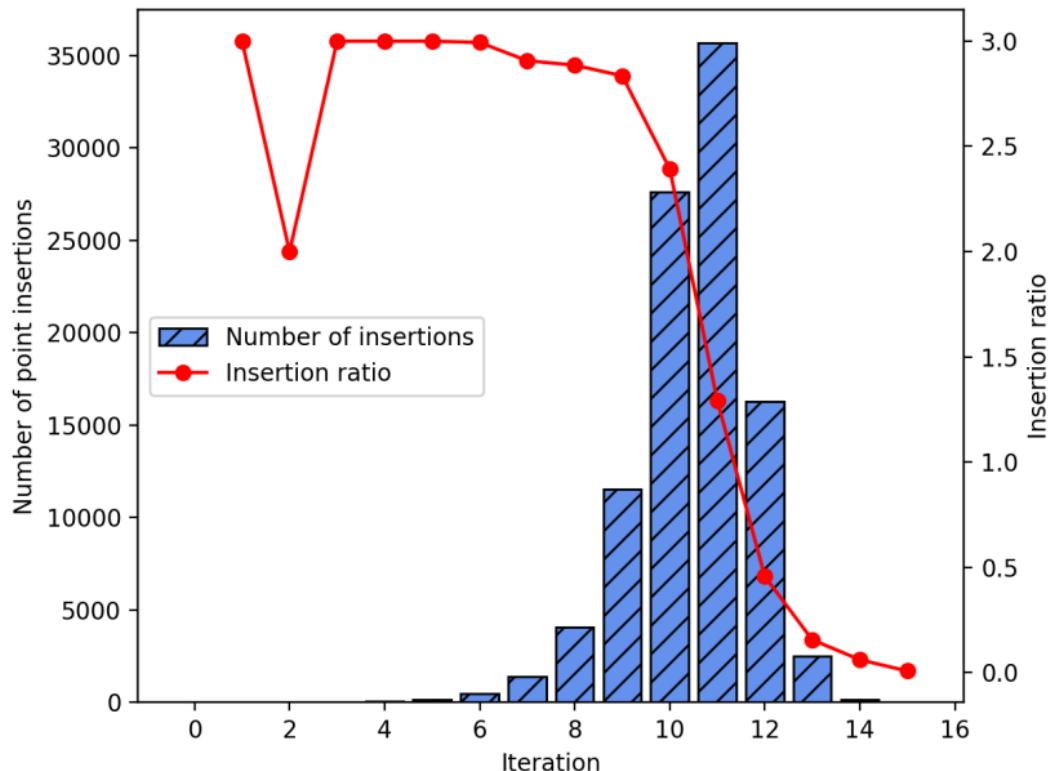
Block Size



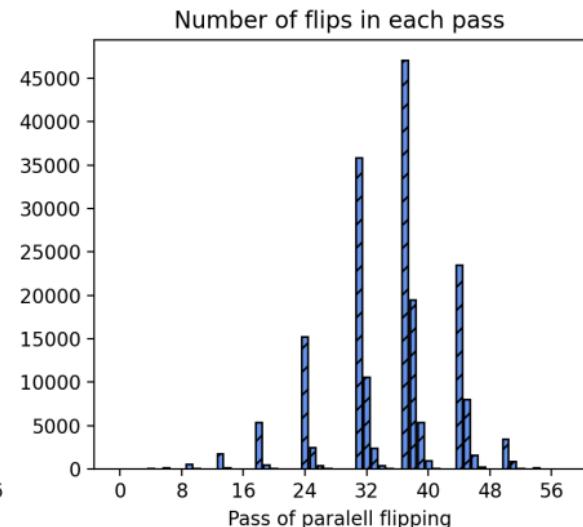
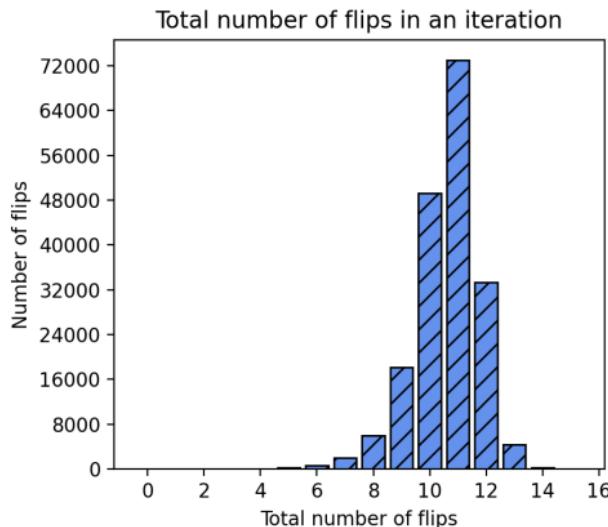
Profiling



Point Insertions



Flipping



Conclusion

Thank You! Any Questions?