

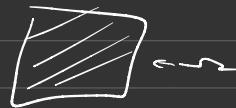
Poisson Problem 1-W

$u''(x) = f(x)$ on Ω and $u(x) = 0$ on $\partial\Omega$

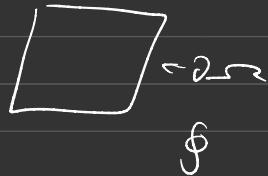
$$\Omega = [0, 1]$$

$$u''(x) \varphi(x) = f(x) \varphi(x)$$

$$u'' \varphi = f \varphi$$



$$\int_{\Omega} u'' \varphi dx = \int_{\Omega} f \varphi dx$$



$$\int_0^1 u' \varphi dx - \int_0^1 u' \varphi' dx = \int_0^1 f \varphi dx$$

$$\partial u = 0 = \varphi(1)$$

$$u = \sum_i u_i \varphi_i, \quad \varphi = \varphi_j$$

$$\begin{aligned} \frac{\partial}{\partial x} u &= \frac{\partial}{\partial x} \left(\sum_i u_i \varphi_i(x) \right) \\ &= \sum_i u_i \varphi'_i(x) \end{aligned}$$

$$\Rightarrow - \int_{\Omega} u' \varphi' dx = \int_{\Omega} f \varphi dx \quad \forall j$$

$$- \sum_i (u_i \int_{\Omega} \varphi'_i \varphi'_j dx) = \int_{\Omega} f \varphi_j dx \quad \forall j$$

$$\Rightarrow \begin{pmatrix} \varphi_0 & \varphi_1 & \dots & \varphi_n \end{pmatrix} \begin{pmatrix} u_0 \\ u_1 \\ \vdots \\ u_n \end{pmatrix} = \begin{pmatrix} f(\varphi_0) \\ f(\varphi_1) \\ \vdots \\ f(\varphi_n) \end{pmatrix}$$

N Dim Case

$$\underbrace{\left(- \int_{\Omega} \nabla u \cdot \nabla \varphi_i \, ds \right)}_{= \sum_i u_i \int_{\Omega} \nabla \varphi_i \cdot \nabla \varphi_j \, ds} = \int_{\Omega} f \varphi_i \, ds$$

$$\Rightarrow \sum_i u_i (\nabla \varphi_i, \nabla \varphi_j) = (f, \varphi_i)$$

$$\nabla u = \sum_i u_i \nabla \varphi_i$$

$$\nabla u = \nabla \sum_i u_i \varphi_i(x, y)$$

$$= \left(\frac{\partial}{\partial x} \sum_i u_i \varphi_i(x, y), \frac{\partial}{\partial y} \sum_i u_i \varphi_i(x, y) \right)$$

$$= \left(\sum_i u_i \partial_x \varphi_i(x, y), \sum_i u_i \partial_y \varphi_i(x, y) \right) \cdot (a, b)$$

$$= \sum u_i \left(\quad \right)$$

$$\nabla^2 u(x, y) =$$

$$u(x, y) = \sin(\pi x) \sin(\pi y)$$

$$\partial_x^2 u + \partial_y^2 u = -\pi^2 \sin(\pi x) \sin(\pi y)$$

$$-\pi^2 \sin(\pi x) \sin(\pi y)$$

$$= -2\pi^2 \sin(\pi x) \sin(\pi y)$$

$$u\left(\frac{1}{2}, \frac{1}{2}\right) = \sin\frac{\pi}{2} \sin\frac{\pi}{2}$$

$$= \sin^2\left(\frac{\pi}{2}\right)$$

$$= 1$$



$$\frac{\partial}{\partial x} \sin(\pi x) = \frac{\partial \sin(\pi x)}{\partial \pi x} \frac{\partial \pi x}{\partial x}$$

$$= \pi \cos \pi x$$

$$\frac{\partial}{\partial x} \pi \cos \pi x = \pi \frac{\partial \cos(\pi x)}{\partial \pi x} \frac{\partial \pi x}{\partial x} = \pi^2$$

$$A_{ij} = (\varphi_i, \varphi_j)$$

$$\varphi_i(x) = \begin{cases} 1 & i \\ 0 & \text{else} \end{cases}$$

$$\varphi_0(x) = \varphi_N(x)$$

$$u(0) = u(1) \Rightarrow \text{rho right so}$$

$$u(x) = \sum_{i=0}^N u_i \varphi_i(x)$$

$$u(0) = \sum_{i=0}^N u_i \varphi_i(0)$$

$$= u(1) = \sum_{i=0}^N u_i \varphi_i(1)$$

$$\Rightarrow \boxed{\varphi_i(0) = \varphi_i(1)}$$

$$\sum u_i \int \varphi_i' \varphi_j' dx = \int f \varphi_j dx$$

Numann BC's

$$-\nabla^2 u = f \quad \text{on } \Omega$$

$$u = u_D \quad \text{on } \partial\Omega_D$$

$$-\frac{\partial u}{\partial n} = -\nabla u \cdot \hat{n} = h \quad \text{on } \partial\Omega_N$$

So the term that is added for Numann BC's is

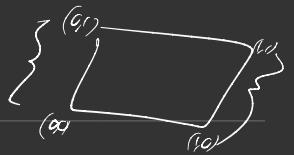
$$\int_{\Omega} h \varrho$$

In 1-dim

$$\int_{\Omega} h \varrho = h \Big|_0^1 \quad \text{for } \Omega = [0, 1]$$

In 2-dim

$$\int_{\Omega} h \varrho = \oint_{\Omega} h \varrho \quad \text{where } \Omega = [0, 1]^2$$



Then if we

$$\int_{\Omega} h \varphi_i = \int_0^1 h(0, y) \varphi_i(0, y) + \int_0^1 h(1, y) \varphi_i(1, y)$$

2D problem with neumann bdry

$$-\nabla^2 u = f$$

$$u = 1 + x^2 + 2y^2$$

$$\frac{\partial u}{\partial x} = 2x, \quad \frac{\partial^2 u}{\partial x^2} = 2$$

$$\frac{\partial u}{\partial y} = 4y, \quad \frac{\partial^2 u}{\partial y^2} = 4$$

$$\Rightarrow 2 + 4 = -f \Rightarrow f(x, y) = -6$$

Let the ~~the~~ neumann bdry only apply to
the sides $y=0, y=1$



so then

$$-\frac{\partial u}{\partial x} - \frac{\partial u}{\partial y} = -2x - 4y = n(x, y)$$

Then let $n(x, y) = -4y$

Nope!

let $u = y^2 \sin(\pi x)$

$$\frac{\partial u}{\partial x} = \pi y^2 \cos(\pi x), \quad \frac{\partial^2 u}{\partial x^2} = -\pi^2 y^2 \sin(\pi x)$$

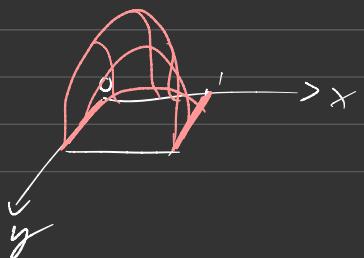
$$\frac{\partial u}{\partial y} = 2y \sin(\pi x), \quad \frac{\partial^2 u}{\partial y^2} = 2 \sin(\pi x)$$

$$-\nabla^2 u = \pi^2 y^2 \sin(\pi x) - 2 \sin(\pi x)$$

$$= \boxed{(\pi^2 y^2 - 2) \sin(\pi x)} = f(x, y)$$

$$-\frac{\partial u}{\partial n} = \pi y \cos(\pi x) - 2y \sin(\pi x)$$

$$= \boxed{u(x, y) = y(\pi \cos(\pi x) - 2 \sin(\pi x))}$$



\mathcal{D}

$$u = y \sin(\pi x)$$

$$\partial_x u = \pi y \cos(\pi x) \quad \partial_y u = \sin(\pi x)$$

$$\partial_x^2 u = -\pi^2 y \sin(\pi x) \quad \partial_y^2 u = 0$$

$$-\frac{\partial u}{\partial n} = -(\pi y \cos(\pi x) + \sin(\pi x)) = u(x, y)$$

$$-\nabla^2 u = -\pi^2 y \sin(\pi x) = f(x, y)$$

Let's not use ~~the~~ ~~another~~ ~~another~~ cuz it looks like a precision problem

$$u = y(x-1)$$

$$\partial_x u = y(x-1 + x) \quad \partial_y u = x(x-1)$$

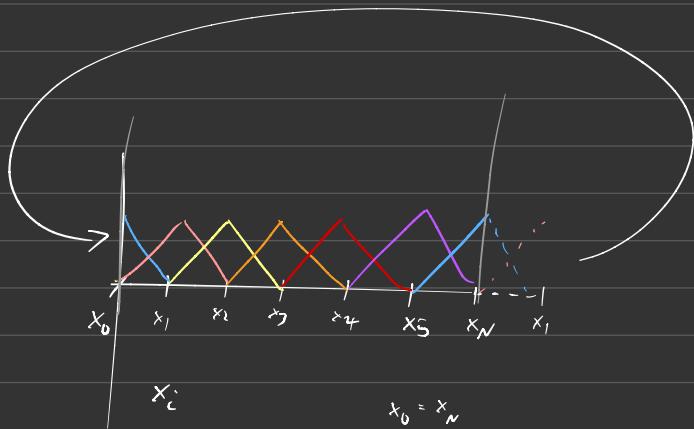
$$= y(2x-1) \quad \partial_y^2 u = 0$$

$$\partial_x^2 u = 2y$$

$$-\nabla^2 u = \boxed{\partial_y u = f(x, y)}$$

$$-\frac{\partial u}{\partial n} = \boxed{u(x, y) = y(2x-1) + x(x-1)}$$

Periodic BCS



$$\sum_{\substack{i,j \\ \text{in} \\ \tilde{u}_i}} \underbrace{\int \varphi_i \varphi_j dx}_{A_{ij}} = \underbrace{\int f \varphi_j dx}_{\equiv_j}$$

And do mod
modulo N
when adding
nodes in $A[i,j]$

A_{ij} doesn't change when $|i-j| \leq 5$

$$A_{ij} =$$

$$A = \begin{bmatrix} \int \varphi_0' \varphi_0' & \int \varphi_0' \varphi_1' & \dots & \int \varphi_0' \varphi_N' \\ \int \varphi_1' \varphi_0' & \int \varphi_1' \varphi_1' & \dots & \int \varphi_1' \varphi_N' \\ \vdots & \vdots & \ddots & \vdots \\ \int \varphi_N' \varphi_0' & \int \varphi_N' \varphi_1' & \dots & \int \varphi_N' \varphi_N' \end{bmatrix}$$

$$\nabla^2 u = \underbrace{u''}_{= -1}$$

$$u(0) = -u(1)$$

$$u'' = -1$$

$$u' = -x + c$$

$$u = -\frac{x^2}{2} + xc + d$$

$$u(0) = d = u(1) = -\frac{1}{2} + c + d$$

$$\Rightarrow d = -\frac{1}{2} + c + d$$

$$\Rightarrow c = \frac{1}{2}$$

$$\text{So } u = -\frac{x^2}{2} + \frac{x}{2} + d$$

Neumann

$$\text{Let } u' = -x + \frac{1}{2}$$

$$-u' = x - \frac{1}{2}$$

$$(\psi_i, \psi_j) = (\varphi_i + \varphi_{np}, \varphi_j)$$

$$= \int \varphi_i \varphi_j + \int \varphi_{np} \varphi_j$$

$$= (\varphi_i, \varphi_j) + (\varphi_{np}, \varphi_j)$$

$$= A_{ij} + A_{npi}$$



$$\nabla^2 u = -f = -1$$

$$u(0, y) = u(1, y)$$

$$n(x, y) = x = \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y}$$

$$\Rightarrow u = -\frac{x^2}{2} + xc + d$$

$$u(0) = d = u(1) = -\frac{1}{2} + c + d$$

$$\boxed{c = \frac{1}{2}}$$

$$u = -\frac{x^2}{2} + xc + d$$

Heat Equation

$$\frac{\partial u}{\partial t} = \alpha \nabla^2 u + f$$

$$u = u(x, y, t)$$
$$f = f(x, y, t)$$

Use finite difference on time step

So we write

$$\left(\frac{\partial u}{\partial t} \right)^{n+1} = \nabla^2 u^{n+1} + f^{n+1}$$

$$\left(\frac{\partial u}{\partial t} \right)^{n+1} \approx \frac{u^{n+1} - u^n}{\Delta t}$$

$$\Rightarrow \frac{u^{n+1} - u^n}{\Delta t} = \nabla^2 u^{n+1} + f^{n+1}$$

Reorder to get

$$u^{n+1} - \Delta t \nabla^2 u^{n+1} = u^n + \Delta t f^{n+1}$$

Now use finite element method on the above

$$u^{n+1} \varphi - \Delta t \nabla^2 u^{n+1} \varphi = u^n \varphi + \Delta t f^{n+1} \varphi$$

$$\int_{\Omega} (u^{n+1} \varphi - \Delta t \nabla^2 u^{n+1} \varphi) dx = \int_{\Omega} (u^n \varphi + \Delta t f^{n+1} \varphi) dx$$

$$\boxed{\int_{\Omega} (u^{n+1} \varphi + \Delta t \nabla u^{n+1} \cdot \nabla \varphi) dx = \int_{\Omega} (u^n + \Delta t f^{n+1}) \varphi dx}$$

$$u^{n+1} = \sum_i u_i^{n+1} \varphi_i, \quad \varphi = \varphi_j$$

$$= \int_{\Omega} \left(\sum_i u_i^{n+1} \varphi_i \varphi_j + \Delta t \sum_i u_i^{n+1} \nabla \varphi_i \cdot \nabla \varphi_j \right) dx$$

$$= \underbrace{\sum_i u_i^{n+1}}_{\varphi_i} \int_{\Omega} (\varphi_i \varphi_j + \Delta t \nabla \varphi_i \cdot \nabla \varphi_j) dx$$

$$= \int_{\Omega} \left(\sum_i u_i^n \varphi_i + \Delta t f(x, y, t) \varphi_j \right) dx$$

$$u_0(x, y) = e^{-(x^2+y^2)}$$

Then at $t=0 = \Delta t$ we get

$$\int_{\Omega} u Q dx = \int_{\Omega} u^0 Q dx \quad u^0 = u_0$$

Or just put a nice function like

$$u_0(x, y) = e^{-(x^2+y^2)}$$

$$u_0(x, y) = \sin(\pi y) \sin(\pi y)$$

A selected non-linear PDE problem

$$-\nabla \cdot ((u+1)\nabla u) = g \quad \text{on } \Omega$$

$$u = b \quad \text{on } \Gamma$$

Ω, Γ are the domain and boundary respectively

We get a weak form solution of

$$f(u; \varrho) = \int_{\Omega} ((u+1) \nabla u \cdot \nabla \varrho - g \varrho) dx \quad \forall \varrho$$

Then

$$f(u; \varrho_j) = \int_{\Omega} ((u+1) \nabla u \cdot \nabla \varrho_j - g \varrho_j) dx \quad \forall \varrho_j$$

So solve for this u we use a sort of Taylor series expansion for what's called the Gateaux derivatives of f

$$\text{Note } f(u+\hat{u}; \varrho) \approx f(u; \varrho) + J(u; \varrho, \hat{u})$$

$$\text{and } u^{n+1} = u^n + \hat{u}$$

And note that \mathcal{T} acts like a derivative
for f

$$\mathcal{T}(u; \vartheta, \hat{u}) = \lim_{\varepsilon \rightarrow 0} \frac{f(u + \varepsilon \hat{u}; \vartheta) - f(u; \vartheta)}{\varepsilon}$$

$$= \lim_{\varepsilon \rightarrow 0} \frac{\int_{\Omega} [(u + \varepsilon \hat{u} + 1) \nabla (u + \varepsilon \hat{u}) \cdot \nabla \vartheta - g \vartheta] dx - \int_{\Omega} [u + 1) \nabla u \cdot \nabla \vartheta - g \vartheta] dx}{\varepsilon}$$

$$= \lim_{\varepsilon \rightarrow 0}$$

,

,

,

$$= \int_{\Omega} \nabla \vartheta \cdot (\hat{u} \nabla u + (u + 1) \nabla \hat{u}) dx$$

And \mathcal{T} is linear in \hat{u} so we can solve
for \hat{u} using the finite element method
with some initial guess u and some
arbitrary ϑ

$$\mathcal{T}_{ij} = \mathcal{T}(u^n; \vartheta_i, \vartheta_j) = \int_{\Omega} (\nabla \vartheta_i \cdot (\vartheta_j \nabla u^n + (u^n + 1) \nabla \vartheta_j)) dx$$

So we essentially just solve

$$\mathcal{T}(u^n; \varrho_i, \varrho_j) = -f(u^n, \varrho_j)$$

where

$$\mathcal{T}_{ij} = \mathcal{T}(u^n; \varrho_i, \varrho_j) = \int_{\Omega} (\nabla \varrho_i \cdot (\varrho_j \nabla u^n + (u^n + 1) \nabla \varrho_j)) dx$$

and

$$f_j = f(u^n, \varrho_j) = \int_{\Omega} ((u^n + 1) \nabla u^n \cdot \nabla \varrho_j - g \varrho_j) dx$$

For a manufactured solution let

$$u(x, y) = \sin(\pi x) \sin(\pi y) \quad \text{maybe try } u = x(x-1)y(y-1)$$

$$\begin{aligned} \nabla \cdot (u + 1) \nabla u &= \nabla \cdot ((u + 1) \left[\begin{array}{c} \pi \cos(\pi x) \sin(\pi y) \\ \pi \sin(\pi x) \cos(\pi y) \end{array} \right]) \\ &= \pi \nabla \cdot (\sin(\pi x) \sin(\pi y) + 1) \left[\begin{array}{c} \cos(\pi x) \sin(\pi y) \\ \sin(\pi x) \cos(\pi y) \end{array} \right] \end{aligned}$$

$$\begin{aligned} &= \pi \left(\frac{\partial}{\partial x} (\sin(\pi x) \sin(\pi y) + 1) \cos(\pi x) \sin(\pi y) \right. \\ &\quad \left. + \frac{\partial}{\partial y} (\sin(\pi x) \sin(\pi y) + 1) \sin(\pi x) \cos(\pi y) \right) \end{aligned}$$

$$\begin{aligned}
&= \bar{n} \left[\frac{\partial}{\partial x} \left(\sin(\bar{n}x) \cos(\bar{n}y) \sin^2(\bar{n}y) + \cos(\bar{n}x) \sin(\bar{n}y) \right) \right. \\
&\quad \left. + \frac{\partial}{\partial y} \left(\sin(\bar{n}x) \sin(\bar{n}y) \cos(\bar{n}y) + \sin(\bar{n}x) \cos(\bar{n}y) \right) \right] \\
&= \bar{n} \left[\sin^2(\bar{n}y) \left[\bar{n} \cos^2(\bar{n}x) - \bar{n} \sin^2(\bar{n}x) \right] - \bar{n} \sin(\bar{n}x) \sin(\bar{n}y) \right. \\
&\quad \left. + \sin^2(\bar{n}x) \left[\bar{n} \cos^2(\bar{n}y) - \bar{n} \sin^2(\bar{n}y) \right] - \bar{n} \sin(\bar{n}x) \sin(\bar{n}y) \right] \\
&= \bar{n}^2 \left[\sin^2(\bar{n}y) \cos^2(\bar{n}x) - \sin^2(\bar{n}y) \sin^2(\bar{n}x) - \sin(\bar{n}x) \sin(\bar{n}y) \right. \\
&\quad \left. + \sin^2(\bar{n}x) \cos^2(\bar{n}y) - \sin(\bar{n}x) \sin^2(\bar{n}y) - \sin(\bar{n}x) \sin(\bar{n}y) \right] \\
&= \bar{n}^2 \left[-2 \sin(\bar{n}x) \sin(\bar{n}y) - 2 \sin^2(\bar{n}y) \sin^2(\bar{n}x) \right. \\
&\quad \left. + \sin^2(\bar{n}y) \cos^2(\bar{n}x) + \sin^2(\bar{n}x) \cos^2(\bar{n}y) \right]
\end{aligned}$$

$$u(x, y) = \sin(\pi x) \sin(\pi y)$$

$$\nabla \cdot (u + l) \nabla u$$

$$= \nabla \cdot (u + l) \left[\begin{array}{c} \partial_x \sin(\pi x) \sin(\pi y) \\ \partial_y \sin(\pi x) \sin(\pi y) \end{array} \right]$$

$$= \nabla \cdot (u + l) \left[\begin{array}{c} \pi \cos(\pi x) \sin(\pi y) \\ \pi \sin(\pi x) \cos(\pi y) \end{array} \right]$$

$$= \bar{n} \partial_x \left((\sin(\pi x) \sin(\pi y) + 1) \cos(\pi x) \sin(\pi y) \right)$$

$$+ \bar{n} \partial_y \left((\sin(\pi x) \sin(\pi y) + 1) \sin(\pi x) \cos(\pi y) \right)$$

$$= \bar{n} \left[\partial_x \left(\sin(\pi x) \cos(\pi x) \sin(\pi y) + \cos(\pi x) \sin(\pi y) \right) \right.$$

$$\left. + \partial_y \left(\sin^2(\pi x) \sin(\pi y) \cos(\pi y) + \sin(\pi x) \cos(\pi y) \right) \right]$$

$$= \bar{n} \left[\sin^2(\pi y) \left[\bar{n} \cos^2(\pi x) - \bar{n} \sin^2(\pi y) \right] \right]$$

Then to see what the below thing looks like

$$\bar{J}_{ij} = \bar{J}(u^n; \varphi_i \varphi_j) = \int \left(\nabla \varphi_i \cdot (\varphi_j \nabla u^n + (u^{n+1}) \nabla \varphi_j) dx \right)$$

$$\nabla \varphi_i \cdot (\varphi_j \nabla u^n + (u^{n+1}) \nabla \varphi_j)$$

$$= \begin{bmatrix} \partial_x \varphi_i \\ \partial_y \varphi_i \end{bmatrix} \cdot \begin{bmatrix} (\varphi_j \partial_x u^n) & + & (u^{n+1}) \partial_x \varphi_j \\ (\varphi_j \partial_y u^n) & + & (u^{n+1}) \partial_y \varphi_j \end{bmatrix}$$

$$\nabla \cdot (u+1) \nabla u = \nabla \cdot \begin{bmatrix} (u+1) \partial_x u \\ (u+1) \partial_y u \\ (u+1) \partial_z u \end{bmatrix}$$

$$= \partial_x((u+1) \partial_x u) + \partial_y((u+1) \partial_y u) \\ + \partial_z((u+1) \partial_z u)$$

Partitions of unity

$$x(x-1)y(y-1)$$

$$\mathcal{F} u = x(x-1)y(y-1)$$

$$\begin{aligned}\nabla \cdot (u+1) \nabla u &= \left[\frac{\partial_x}{\partial_y} \frac{(x(x-1)y(y-1)+1)}{(x(x-1)y(y-1)+1)} \frac{\partial_x(x-1)y(y-1)}{\partial_y x(x-1)y(y-1)} \right] \\ &= \left[\frac{\partial_x}{\partial_y} \frac{(x(x-1)y(y-1)+1)(2x-1)y(y-1)}{(x(x-1)y(y-1)+1)x(x-1)(2y-1)} \right] \\ &= \left[\begin{array}{l} \frac{(x-1)(2x-1)(y^2(y-1)^2) + (2x-1)y(y-1)}{x^2(x-1)^2(2y-1)y(y-1)} \\ \frac{x(x-1)(2y-1)}{x(x-1)(2y-1)} \end{array} \right] \\ &= \left[\begin{array}{l} \frac{(x-1)(2x-1)(y^2(y-1)^2) + (2x-1)y(y-1)}{x^2(x-1)^2(2y-1)y(y-1)} \\ 1 \end{array} \right]\end{aligned}$$

Non Linear Poisson Problem

The general form of the non linear poisson problem is

$$-\nabla \cdot (g(u) \nabla u) = g$$

with weak formulation of

$$\int_{\Omega} g(u) \nabla u \cdot \nabla Q \, dx = \int_{\Omega} g Q \, dx$$

Consider in 2D

$$-\nabla \cdot (|\nabla u|^2 \nabla u) = g$$

$$= -\nabla \cdot \left(\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 \right) \nabla u = g$$

$$\Rightarrow \int_{\Omega} \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 \right] \nabla u \cdot \nabla Q - g Q \, dx = f(u; Q)$$

Next we calculate J

$$J(u; Q, \hat{u}) = \lim_{\varepsilon \rightarrow 0} \frac{f(u + \varepsilon \hat{u}; Q) - f(u; Q)}{\varepsilon}$$

$$\left[\left(\frac{\partial(u + \varepsilon \tilde{u})}{\partial x} \right)^2 + \left(\frac{\partial(u + \varepsilon \tilde{u})}{\partial y} \right)^2 \right] \nabla(u + \varepsilon \tilde{u}) \cdot \nabla Q - \cancel{gQ}$$

$$- \left(\left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 \right] \nabla u \cdot \nabla Q - \cancel{gQ} \right)$$

$$= (\partial_x u + \varepsilon \partial_x \tilde{u})^2 + (\partial_y u + \varepsilon \partial_y \tilde{u})^2 (\nabla u + \varepsilon \nabla \tilde{u}) \cdot \nabla Q$$

$$- \left[(\partial_x u)^2 + (\partial_y u)^2 \right] \nabla u \cdot \nabla Q$$

$$= \left[\left(\frac{\partial u}{\partial x} \right)^2 + \varepsilon^2 \left(\partial_x u \right)^2 + 2\varepsilon (\partial_x u) (\partial_x \tilde{u}) + \left(\frac{\partial u}{\partial y} \right)^2 + \varepsilon^2 \left(\partial_y u \right)^2 + 2\varepsilon (\partial_y u) (\partial_y \tilde{u}) \right] \nabla u \cdot \nabla Q$$

$$\left[\left(\partial_x u \right)^2 + \varepsilon^2 \left(\partial_x u \right)^2 + 2\varepsilon (\partial_x u) (\partial_x \tilde{u}) + \left(\partial_y u \right)^2 + \varepsilon^2 \left(\partial_y u \right)^2 + 2\varepsilon (\partial_y u) (\partial_y \tilde{u}) \right] \varepsilon \nabla \tilde{u} \cdot \nabla Q$$

$$- \left[(\partial_x u)^2 + (\partial_y u)^2 \right] \nabla u \cdot \nabla Q$$

$$= \left[+ \varepsilon^2 (\partial_x u)^2 + 2\varepsilon (\partial_x u)(\partial_x \tilde{u}) + \varepsilon (\partial_y u)^2 + 2\varepsilon (\partial_y u)(\partial_y \tilde{u}) \right] \nabla u \cdot \nabla Q$$

$$\left[\begin{aligned} & (\partial_x u)^2 + \varepsilon^2 (\partial_x u)^2 + 2\varepsilon (\partial_x u)(\partial_x \tilde{u}) \\ & + (\partial_y u)^2 + \varepsilon^2 (\partial_y u)^2 + 2\varepsilon (\partial_y u)(\partial_y \tilde{u}) \end{aligned} \right] \varepsilon \nabla \tilde{u} \cdot \nabla Q$$

divide by ε gives

$$\Rightarrow \left[+ \varepsilon (\partial_x u)^2 + 2 (\partial_x u)(\partial_x \tilde{u}) + \varepsilon (\partial_y u)^2 + 2 (\partial_y u)(\partial_y \tilde{u}) \right] \nabla u \cdot \nabla Q$$

$$\left[\begin{aligned} & (\partial_x u)^2 + \varepsilon^2 (\partial_x u)^2 + 2\varepsilon (\partial_x u)(\partial_x \tilde{u}) \\ & + (\partial_y u)^2 + \varepsilon^2 (\partial_y u)^2 + 2\varepsilon (\partial_y u)(\partial_y \tilde{u}) \end{aligned} \right] \nabla \tilde{u} \cdot \nabla Q$$

then take $\varepsilon \rightarrow 0$

$$\Rightarrow \left[\cancel{\varepsilon (\partial_x u)^2} + 2 (\partial_x u)(\partial_x \tilde{u}) + \cancel{\varepsilon (\partial_y u)^2} + 2 (\partial_y u)(\partial_y \tilde{u}) \right] \nabla u \cdot \nabla Q$$

$$+ \left[\begin{aligned} & (\partial_x u)^2 + \cancel{\varepsilon^2 (\partial_x u)^2} + \cancel{2\varepsilon (\partial_x u)(\partial_x \tilde{u})} \\ & + (\partial_y u)^2 + \cancel{\varepsilon^2 (\partial_y u)^2} + \cancel{2\varepsilon (\partial_y u)(\partial_y \tilde{u})} \end{aligned} \right] \nabla \tilde{u} \cdot \nabla Q$$

$$\mathcal{T} = \int_{\Omega} \left[\left[2(\partial_x u)(\partial_x \bar{u}) + 2(\partial_y u)(\partial_y \bar{u}) \right] \nabla u \cdot \nabla \bar{u} + \left[(\partial_x u)^2 + (\partial_y u)^2 \right] \nabla \bar{u} \cdot \nabla \bar{u} \right] dx$$

Since \hat{u} for $\hat{u} = \sum \hat{u}_i \varphi_i$ and $\varphi_i = \varphi_i$

$$\mathcal{T}(u; \hat{u}, \varphi)$$

$$= \sum_i \hat{u}_i \int_{\Omega} \left\{ \left[2 \left[\frac{\partial u}{\partial x} \frac{\partial \varphi_i}{\partial x} + \frac{\partial u}{\partial y} \frac{\partial \varphi_i}{\partial y} \right] \nabla u \cdot \nabla \varphi_i + \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 \right] \nabla \varphi_i \cdot \nabla \varphi_i \right] \right\} dx$$

Let's compute a forcing function g for $u = e^{xy}$

$$-\nabla \cdot (|\nabla u|^2 \nabla u) = g$$

$$= -\nabla \cdot \left(\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 \right) \left[\begin{array}{l} \frac{\partial u}{\partial x} \\ \frac{\partial u}{\partial y} \end{array} \right]$$

$\frac{\partial u}{\partial x} = \frac{\partial}{\partial x} e^{xy} = y e^{xy}$
 $\frac{\partial u}{\partial y} = \frac{\partial}{\partial y} e^{xy} = x e^{xy}$

$$\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = e^{xy}(x + y)$$

$$\begin{aligned}
 &= -\nabla \cdot e^{2xy} (x^2y^2) \begin{bmatrix} ye^{xy} \\ xe^{xy} \end{bmatrix} \\
 &= -\nabla \cdot \left[\frac{(x^2y^2)y}{(x^2y^2)x} e^{3xy} \right] \\
 &= -\frac{\partial}{\partial x} \left(\frac{(x^2y^2)y}{(x^2y^2)x} e^{3xy} \right) \\
 &\quad - \frac{\partial}{\partial y} \left(\frac{(x^2y^2)y}{(x^2y^2)x} e^{3xy} \right)
 \end{aligned}$$

$$\begin{aligned}
 \left(\frac{\partial u}{\partial x} \right)^2 &= y^2 e^{2xy} \\
 \left(\frac{\partial u}{\partial y} \right)^2 &= x^2 e^{2xy}
 \end{aligned}$$

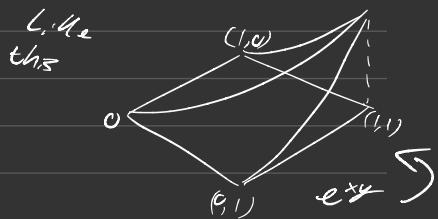
$$\begin{aligned}
 &= -\frac{\partial}{\partial x} x^2 y e^{3xy} - \frac{\partial}{\partial y} y^3 e^{3xy} \\
 &\quad - \frac{\partial}{\partial y} x^3 e^{3xy} - \frac{\partial}{\partial x} y^2 x e^{3xy} \\
 &= -2xye^{3xy} - 3y^2 x^2 e^{3xy} - 3y^4 e^{3xy} \\
 &\quad - 3x^4 e^{3xy} - 2y x e^{3xy} - 3y^2 x^2 e^{3xy} \\
 &= -e^{3xy} (2xy - 3y^2 x^2 - 3y^4 - 3x^4)
 \end{aligned}$$

$$-\nabla \cdot (1-u) \nabla u = g$$

$$\text{Let } u = e^{-((x-1)^2 + (y-1)^2)}$$

To do

Rewrite B-splines to allow any boundary conditions



Vector Partial Differential equations

The Navier Stokes equations

$$\rho \frac{\partial \vec{u}}{\partial t} - \nu \nabla^2 \vec{u} + \rho (\vec{u} \cdot \vec{\nabla}) \vec{u} + \nabla P = \vec{f}$$

$$\frac{\partial P}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} = 0$$

In 2D with $\vec{u} = (u_1, u_2)$

$$\rho \frac{\partial u_1}{\partial t} - \nu \left(\frac{\partial^2 u_1}{\partial x^2} + \frac{\partial^2 u_1}{\partial y^2} \right) + \rho u_1 \frac{\partial u_1}{\partial x} + \rho u_2 \frac{\partial u_1}{\partial y} + \frac{\partial P}{\partial x} = 0$$

$$\rho \frac{\partial u_2}{\partial t} - \nu \left(\frac{\partial^2 u_2}{\partial x^2} + \frac{\partial^2 u_2}{\partial y^2} \right) + \rho u_1 \frac{\partial u_2}{\partial x} + \rho u_2 \frac{\partial u_2}{\partial y} + \frac{\partial P}{\partial y} = 0$$

$$\frac{\partial P}{\partial t} + \frac{\partial \rho u}{\partial x} + \frac{\partial \rho v}{\partial y} = 0$$

Some simplifications

1

1

1

$$-\nu \left(\frac{\partial^2 u_1}{\partial x^2} + \frac{\partial^2 u_1}{\partial y^2} \right) + \frac{\partial P}{\partial x} = 0$$

$$-\nu \left(\frac{\partial^2 u_2}{\partial x^2} + \frac{\partial^2 u_2}{\partial y^2} \right) + \frac{\partial P}{\partial y} = 0$$

$$\frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial y} = 0$$

Or more compactly

$$\begin{cases} \nu \nabla^2 u_1 = \frac{\partial P}{\partial x} & \nabla \cdot u = 0 \\ \nu \nabla^2 u_2 = \frac{\partial P}{\partial y} \end{cases}$$

Now set

$$u_1 = \sum_i u_{1i} Q_i \quad P = \sum_i P_i Q_i$$

$$u_2 = \sum_i u_{2i} Q_i$$

then if $\mathcal{Q} = (\mathcal{Q}_1, \mathcal{Q}_2, \mathcal{Q}_3)$

$$\nu \nabla^2 u_1 = \frac{\partial P}{\partial x}$$

$$\Rightarrow \int_{\Omega} \nu \nabla^2 u_1 \mathcal{Q}_1 = \int_{\Omega} P \frac{\partial \mathcal{Q}_1}{\partial x}$$

$$\Rightarrow \nu \int_{\Omega} \nabla u_1 \cdot \nabla \mathcal{Q}_1 = \int_{\Omega} P \frac{\partial \mathcal{Q}_1}{\partial x}$$

and similarly

$$\nu \int_{\Omega} \nabla u_2 \cdot \nabla \mathcal{Q}_2 = \int_{\Omega} P \frac{\partial \mathcal{Q}_2}{\partial y}$$

and

$$\nabla \cdot u = 0$$

$$\Rightarrow \int_{\Omega} \nabla \cdot u \mathcal{Q}_3 = 0$$

$$\nu \int_{\Omega} \nabla u_i \cdot \nabla \varphi_j = \int_{\Omega} \rho \frac{\partial \varphi_j}{\partial x}$$

$$\varphi = (\varphi_1, \varphi_2, \varphi_3)$$

$$\varphi_i = (\varphi_{1,i}, \varphi_{2,i}, \varphi_{3,i})$$

$$\varphi_{ijk} = (\varphi_{1,ij}, \varphi_{2,ij}, \varphi_{3,ij})$$

$$(i,j,u) \quad i,j,u \in \{0,-0.1,1\} \times \{0,-0.1,1\}$$

$$10 \cdot 10 \cdot 10 = 10^3 = 1000$$

with $u_i = \sum u_{i,j} \varphi_j$ $\varphi = \varphi_j$

$$\boxed{\sum_i u_{i,i} \left(\nu \int_{\Omega} \nabla \varphi_i \cdot \nabla \varphi_j \right) = \sum_i \rho_i \int_{\Omega} \varphi_{3,i} \frac{\partial \varphi_j}{\partial x}} + \int_{\Omega} f_i \varphi_j$$

Similarly for u_2 we get

$$\boxed{\sum_i u_{2,i} \left(\nu \int_{\Omega} \nabla \varphi_{2,i} \cdot \nabla \varphi_j \right) = \sum_i \rho_i \int_{\Omega} \varphi_{3,i} \frac{\partial \varphi_j}{\partial y}}$$

and $\int_{\Omega} \nabla \cdot u \varphi_3 = \int_{\Omega} \left(\frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial y} \right) \varphi_3 = 0$

$$= \boxed{\sum_i u_{i,i} \int_{\Omega} \frac{\partial \varphi_i}{\partial x} \varphi_3 + \sum_i u_{2,i} \int_{\Omega} \frac{\partial \varphi_{2,i}}{\partial y} \varphi_3 = 0}$$

$$u_1() + u_1() + \dots + u_{1,n}() + u_{2,1}() + \dots + u_{2,n}() + 0 + \dots + 0 = 0$$

$$0 + \dots + 0 + \underbrace{u_2() + \dots + u_{2n}()}_{u_2} - \underbrace{p_1() - \dots - p_n()}_{p} = 0$$

6

$$\left[\begin{array}{c|c|c|c|c|c} u_1 & & & & u_1 & \\ \hline & u_2 & & & u_2 & \\ \hline & & p & & p & \\ \hline & & & u_1 & & \\ & & & u_2 & & \\ & & & \vdots & & \\ & & & u_{2n} & & \\ & & & p_1 & & \\ & & & \vdots & & \\ & & & p_n & & \end{array} \right] = \left[\begin{array}{c|c} \square & \square \end{array} \right] = \square$$

free bits

For the next part

Block
Matrix
Kinda

$$p\hat{n} = \sin(\hat{\alpha}_x) \sin(\hat{\alpha}_y) \hat{n}$$

Manufacturing a solution

$$-\nu \left(\frac{\partial^2 u_1}{\partial x^2} + \frac{\partial^2 u_2}{\partial y^2} \right) + \frac{\partial P}{\partial x} = 0$$

$$-\nu \left(\frac{\partial^2 u_2}{\partial x^2} + \frac{\partial^2 u_1}{\partial y^2} \right) + \frac{\partial P}{\partial y} = 0$$

$$\frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial y} = 0$$

For zero boundary conditions

$$\text{Let } u = (\sin(\pi x) \sin(\pi y), \sin(\pi x) \sin(\pi y))$$

$$P = \sin(\pi x) \sin(\pi y)$$

$$-\nu \left(\frac{\partial^2 u_1}{\partial x^2} + \frac{\partial^2 u_2}{\partial y^2} \right) + \frac{\partial P}{\partial x} = 0$$

$$2\nu\pi^2 \sin(\pi x) \sin(\pi y) + \pi \cos(\pi x) \sin(\pi y) = f_1$$

$$2\nu\pi^2 \sin(\pi x) \sin(\pi y) + \pi \sin(\pi x) \cos(\pi y) = f_2$$

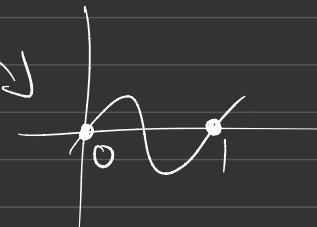
But

$$\frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial x} = 0$$

$$\Rightarrow \boxed{\frac{\partial u_1}{\partial x} = -\frac{\partial u_2}{\partial y}}$$

Complex differentiable function

$$u_1 = \sin(\pi x) \sin(\pi y)$$



$$\frac{\partial u_1}{\partial x} = \pi \cos(\pi x) \sin(\pi y)$$

$$-u_2 = \int \pi \cos(\pi x) \sin(\pi y) dy$$

$$= \pi \cos(\pi x) \int \sin \pi y dy$$

$$= \pi \cos(\pi x) \left(-\frac{1}{\pi} \cos(\pi y) \right)$$

$$\Rightarrow u_2 = \cos(\pi x) \cos(\pi y) + f(x)$$

But we need $u_2(\{0\}, \{0\}) = 0$ so let $f(x) = -1$

$$u_2(0,0) = 0 = 1 + f(0) = \begin{cases} f(0) = -1 \\ f(0) = 0 \end{cases}$$

$$1 + f(1) = 1 + f(0) = f(0) = f(1)$$

$$u_2 = X(x) Y(y)$$

$$\text{If } u_2(a,b) = \begin{cases} 0 & \text{if } a=0 \text{ or } b=0 \\ \text{else} \end{cases}$$

$$u_2($$

May be

$$u_1 = x(x-1)y(y-1)$$

$$\frac{\partial u_1}{\partial x} = y(y-1) \left[(x-1) + x \right]$$

$$= y(y-1)(2x-1)$$

$$-u_2 = (2x-1) \int y(y-1) dy$$

$$= (2x-1) \int y^2 - y dy$$

$$= (2x-1) \left(\frac{y^3}{3} - \frac{y^2}{2} \right) + f(x)$$

$$= (2x-1) \left(y^2 \left(-\frac{1}{3} - \frac{1}{2} \right) + f(x) \right)$$

$$u_2 = -(2x-1)y^2 \left(-\frac{1}{3} - \frac{1}{2} \right) + f(x)$$

$$u_2(0, y) = u_2(1, y) = u_2(x, 0) = u_2(x, 1)$$

$$u_2(0, y) = y^2 \left(-\frac{1}{3} - \frac{1}{2} \right) + f(0) = 0$$

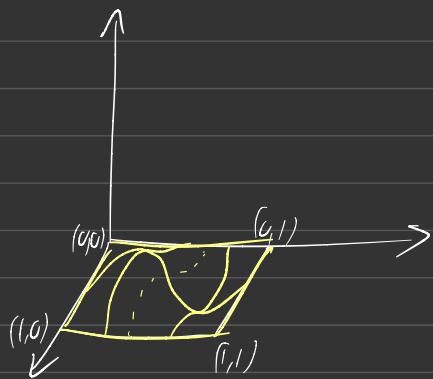
$$u_2(1, y) = -y^2 \left(-\frac{1}{3} - \frac{1}{2} \right) + f(1) = 0$$

$$u_2(x, 0) = 0 + f(x) \quad |$$

$$u_2(x, 1) = \frac{1}{6}(2x-1) + f(x) = 0 \quad |$$

$$= \frac{1}{6}$$

$$\frac{\partial u_1}{\partial x} = - \frac{\partial u_2}{\partial y}$$



$$\left\{ \begin{array}{l} -\nu \left(\frac{\partial^2 u_1}{\partial x^2} + \frac{\partial^2 u_1}{\partial y^2} \right) + \frac{\partial P}{\partial x} = f_1 \\ \\ \end{array} \right.$$

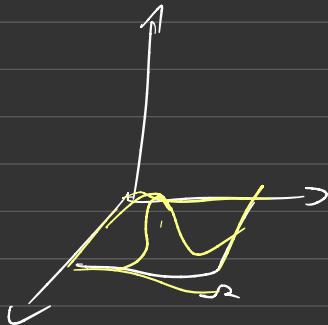
$$\left. \begin{array}{l} -\nu \left(\frac{\partial^2 u_2}{\partial x^2} + \frac{\partial^2 u_2}{\partial y^2} \right) + \frac{\partial P}{\partial y} = f_2 \end{array} \right.$$

$$\left. \begin{array}{l} \frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial y} = 0 = \nabla \cdot u \end{array} \right.$$

$$u(x, y) = (u_1(x, y), u_2(x, y))$$

$$f(x, y) = (f_1(x, y), f_2(x, y))$$

$$\left\{ \begin{array}{l} \frac{\partial u_1}{\partial x} = -\frac{\partial u_2}{\partial y} \quad \text{with} \quad \nabla \cdot u = 0 \end{array} \right.$$



Another solution for Stokes equation

$$\nabla \cdot \nabla f = 0$$

$$f(x,y) = (1 - \cos(2\pi x))(1 - \cos(2\pi y))$$

$$\nabla f = u = \begin{bmatrix} (2\pi \sin(2\pi x))(1 - \cos(2\pi y)) \\ (1 - \cos(2\pi x))(2\pi \sin(2\pi y)) \end{bmatrix}$$

Also need

$$\int_{\Omega} p = 0$$

$$\iint_{\Omega} p(x,y) dy dx = 0$$

$$\iint_{\Omega} p(x,y) dy dx = \int_0^1 p(x) dx \int_0^1 p(y) dy$$

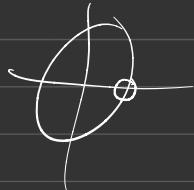
$$\int_0^1 p(x) dx = p(1) - p(0) \quad p(x) = (x-1)(2x-1)$$

$$p(x) = x(x-1) \quad \frac{\partial}{\partial x} p(x) = 2x - 1$$

$$\begin{aligned}
 \int_0^1 \int_0^1 p(x,y) dx dy &= \int_0^1 2x - 1 dx \int_0^1 (2y - 1) dy \\
 &= (x^2 - x) \Big|_0^1 (y^2 - y) \Big|_0^1 \\
 &= x(1-x) \Big|_0^1 y(y-1) \Big|_0^1 \\
 &= 0 \cdot 0 = 0
 \end{aligned}$$

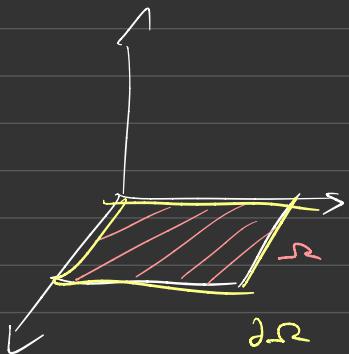
$$\int_0^1 p(x) dx = 0 \quad \text{and} \quad p(1) = p(0) = 0$$

$$\begin{aligned}
 \text{if } p(x) &= \sin(2\pi x) \\
 \int_0^1 \sin(2\pi x) dx &= -\frac{\cos 2\pi x}{2\pi} \Big|_0^1
 \end{aligned}$$



$$= \frac{1}{2\pi} - \frac{1}{2\pi} = 0$$

$$\left\{ \begin{array}{l} \nabla \cdot ((1+u) \nabla u) = f(x,y) \\ u(x,y) = (u_x(x,y), u_y(x,y)) \end{array} \right.$$



$$\Omega = [0, 1] \times [0, 1]$$

Unsteady Stokes

$$\rho \frac{\partial \vec{u}}{\partial t} + \nu \nabla^2 \vec{u} - \nabla p = \vec{f}$$

$$\frac{\partial p}{\partial t} + \nabla \cdot \rho \vec{u} = 0$$

Time discretisation gives

$$\left(\frac{\partial \vec{u}}{\partial t} \right)^{n+1} \approx \frac{\vec{u}^{n+1} - \vec{u}^n}{\Delta t}$$

So

$$\rho \left(\frac{\partial \vec{u}}{\partial t} \right)^{n+1} + \nu \nabla^2 \vec{u}^{n+1} - \nabla p^{n+1} = \vec{f}$$

$$= \rho \frac{\vec{u}^{n+1} - \vec{u}^n}{\Delta t} + \nu \nabla^2 \vec{u}^{n+1} - \nabla p^{n+1} = \vec{f}$$

$$= \rho \vec{u}^{n+1} - \rho \vec{u}^n + \Delta t \nu \nabla^2 \vec{u}^{n+1} - \Delta t \nabla p^{n+1} = \Delta t \vec{f}$$

$$\Rightarrow \rho \vec{u}^{n+1} + \Delta t \nu \nabla^2 \vec{u}^{n+1} - \Delta t \nabla p^{n+1} = \Delta t \vec{f} + \rho \vec{u}^n$$

\Downarrow

$$\sum_i u_i^{n+1} \int (\rho \partial_i \varphi_i + \Delta t \nu \nabla \varphi_i \cdot \nabla \varphi_i) dx - \sum_i \rho_i \int (\partial_i \nabla \varphi_i) dx \\ = \int (\Delta t \vec{f} + \rho \vec{u}^n) \varphi_i dx$$

Then

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{u} = 0$$

$$\Rightarrow \left(\frac{\partial \rho}{\partial t} \right)^{n+1} + \nabla \cdot \rho^{n+1} u^{n+1} = 0$$

$$= \frac{\rho^{n+1} - \rho^n}{\Delta t} + \nabla \cdot \rho^{n+1} \vec{u}^{n+1} = 0$$

$$\Rightarrow \rho^{n+1} + \Delta t \nabla \cdot (\rho^{n+1} \vec{u}^{n+1}) = \rho^n$$

$$\rho^{n+1} + \Delta t \left[(\rho^{n+1} \nabla \cdot \vec{u}^{n+1}) + (\nabla \rho^{n+1} \cdot \vec{u}^{n+1}) \right]$$

$$= \rho^{n+1} + \Delta t (\rho^{n+1} \nabla \cdot \vec{u}^{n+1}) + \Delta t (\nabla \rho^{n+1} \cdot \vec{u}^{n+1}) = \rho^n$$

Weak form

$$\rho^{n+1} \varphi_i + \Delta t (\rho^{n+1} \nabla \cdot \vec{u}^{n+1}) \varphi_i + \Delta t (\nabla \rho^{n+1} \cdot \vec{u}^{n+1}) \varphi_i = \rho^n \varphi_i$$

$$\rho' \rightsquigarrow \sum_i p'_i q_i \quad , \quad q \rightsquigarrow q_j$$

$$\int \sum_i p'_i (q_j +$$

Doing time discretisation for NS

$$\rho \frac{\partial \vec{u}}{\partial t} - \nu \nabla^2 \vec{u} + \rho (\vec{u} \cdot \vec{\nabla}) \vec{u} + \vec{\nabla} p = \vec{f}$$

$$\frac{\partial p}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} = 0$$

$$\left(\frac{\partial u}{\partial t} \right)^{n+1} \approx \frac{u^{n+1} - u^n}{\Delta t}$$

$$\rho \frac{\partial u_i}{\partial t} - \nu \nabla^2 u_i + \rho (\vec{u} \cdot \vec{\nabla}) u_i + \vec{\nabla} p = \vec{f}$$

Time discretization
 $\rightarrow u_i^{n+1}$
 $\left(\frac{\partial u}{\partial t} \right)^{n+1}$
 $\nabla^2 u_i^{n+1}$

$$\rho \left(\frac{u_i^{n+1} - u_i^n}{\Delta t} \right) - \nu \nabla^2 u_i^{n+1} + \rho (\vec{u}^{n+1} \cdot \vec{\nabla}) u_i^{n+1} + \vec{\nabla} p^{n+1} = f^{n+1}$$

$$\rho u_i^{n+1} - \rho u_i^n - \nu \Delta t \nabla^2 u_i^{n+1} + \rho \Delta t (\vec{u}^{n+1} \cdot \vec{\nabla}) u_i^{n+1} + \Delta t \vec{\nabla} p^{n+1} = \Delta t f^{n+1}$$

$$\rho u_i^{n+1} - \rho u_i^n - \nu \Delta t \nabla^2 u_i^{n+1} + \rho \Delta t (\vec{u}^{n+1} \cdot \vec{\nabla}) u_i^{n+1} + \Delta t \vec{\nabla} p^{n+1} = \Delta t f^{n+1}$$

$$\rho u_i^{n+1} - \nu \Delta t \nabla^2 u_i^{n+1} + \rho \Delta t (\vec{u}^{n+1} \cdot \vec{\nabla}) u_i^{n+1} + \Delta t \vec{\nabla} p^{n+1} = \Delta t f_i^{n+1} + \rho u_i^n$$

Weak form

$$\int_{\Omega} u_i \varphi_i - \nu \Delta t \int_{\Omega} \nabla u_i^{n+1} \cdot \nabla \varphi_i + \int_{\Omega} \rho \Delta t (\vec{u}^{n+1} \cdot \vec{\nabla}) u_i^{n+1} \varphi_i \\ + \Delta t \int_{\Omega} p^{n+1} \nabla \varphi_i = \int_{\Omega} (\Delta t f_i^{n+1} + \rho u_i^n) \varphi_i$$

$$\Rightarrow \rho \frac{D\vec{u}}{Dt} = \rho \left[\frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \vec{\nabla}) \vec{u} \right] \\ = \rho \vec{f} - \vec{\nabla} P + \eta \vec{\nabla}^2 \vec{u} + \left(\frac{2}{3} + \frac{1}{3} \right) \vec{\nabla} (\vec{\nabla} \cdot \vec{u})$$

Navier Stokes equations Seddy equations

along with the continuity equation

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

and some equation of state

$$\underbrace{\rho \frac{\partial \vec{u}}{\partial t} + \rho (\vec{u} \cdot \vec{\nabla}) \vec{u}}_{\text{time}} + \underbrace{\rho \vec{f} - \vec{\nabla} P + \eta \vec{\nabla}^2 \vec{u}}_{\text{non-linear}} + \underbrace{\left(\frac{2}{3} + \frac{1}{3} \right) \vec{\nabla} (\vec{\nabla} \cdot \vec{u})}_{\text{linear}}$$

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

$$\vec{\nabla} (\vec{\nabla} \cdot \vec{u}) = \vec{\nabla} \left(\frac{\partial_x u_x}{\partial_x} + \frac{\partial_y u_y}{\partial_y} + \frac{\partial_z u_z}{\partial_z} \right)$$

$$= \begin{bmatrix} \frac{\partial_x}{\partial_x} \left(\frac{\partial_x u_x}{\partial_x} + \frac{\partial_y u_y}{\partial_y} + \frac{\partial_z u_z}{\partial_z} \right) \\ \frac{\partial_y}{\partial_y} \left(\frac{\partial_x u_x}{\partial_x} + \frac{\partial_y u_y}{\partial_y} + \frac{\partial_z u_z}{\partial_z} \right) \\ \frac{\partial_z}{\partial_z} \left(\frac{\partial_x u_x}{\partial_x} + \frac{\partial_y u_y}{\partial_y} + \frac{\partial_z u_z}{\partial_z} \right) \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\partial_x^2 u_x}{\partial_x} + \frac{\partial_x}{\partial_x} \left(\frac{\partial_y u_y}{\partial_y} + \frac{\partial_z u_z}{\partial_z} \right) \\ \frac{\partial_y^2 u_y}{\partial_y} + \frac{\partial_y}{\partial_y} \left(\frac{\partial_x u_x}{\partial_x} + \frac{\partial_z u_z}{\partial_z} \right) \\ \frac{\partial_z^2 u_z}{\partial_z} + \frac{\partial_z}{\partial_z} \left(\frac{\partial_x u_x}{\partial_x} + \frac{\partial_y u_y}{\partial_y} \right) \end{bmatrix}$$

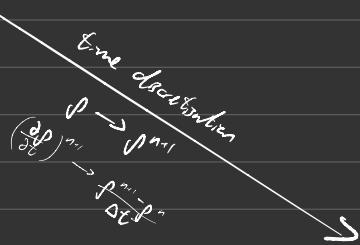
$$\partial_x^2 u_x + \partial_x (\partial_y u_y + \partial_z u_z)$$

$$F_i x \quad u_x = \sum u_{x_i} \mathcal{Q}_i$$

$$\partial_x^2 \sum u_{x_i} \mathcal{Q}_i + \partial_x (\partial_y \sum u_{y_i} \mathcal{Q}_i + \partial_z \sum u_{z_i} \mathcal{Q}_i)$$

$$= \sum u_{x_i} \partial_x^2 \mathcal{Q}_i + \sum_i u_{y_i} \partial_x \partial_y \mathcal{Q}_i + \sum_i u_{z_i} \partial_x \partial_z \mathcal{Q}_i$$

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} = 0$$



$$\frac{\rho^{n+1} - \rho^n}{\Delta t} + \vec{\nabla} \cdot \rho^{n+1} \vec{u} = 0$$

$$\rho^{n+1} - \rho^n + \Delta t \vec{\nabla} \cdot \rho^{n+1} \vec{u} = 0$$

$$\rho^{n+1} + \Delta t \vec{\nabla} \cdot (\rho^{n+1} \vec{u}) = \rho^n$$

$$\int_{\Omega} \rho^{n+1} \varphi + \Delta t \vec{\nabla} \cdot (\rho^{n+1} \vec{u}) \varphi = \int_{\Omega} \rho^n \varphi$$

$$\begin{aligned} \rho^{n+1} &= \sum_i \rho_i^{n+1} \varphi_i \\ u &= u^n \quad \rightarrow \quad \varphi = \varphi_i \end{aligned}$$

$$\int_{\Omega} \sum_i \rho_i^{n+1} \varphi_i \varphi_j + \Delta t \left(\vec{\nabla} \cdot \left(\sum_i \rho_i^{n+1} \varphi_i \vec{u} \right) \right) \varphi_j = \int_{\Omega} \rho^n \varphi_j$$

$$= \int_{\Omega} \sum_i \rho_i^{n+1} \varphi_i \varphi_j + \Delta$$

$$\vec{V} \cdot \sum_{i=1}^n Q_i \vec{u} = \vec{V} \cdot \left[\begin{array}{c} \sum_{i=1}^n Q_i u_1 \\ \sum_{i=1}^n Q_i u_2 \\ \sum_{i=1}^n Q_i u_3 \end{array} \right]$$

$$\frac{\partial}{\partial x} \left(\sum_{i=1}^n Q_i u_i \right)$$

$$= \sum_{i=1}^n Q_i \frac{\partial}{\partial x} (Q_i u_i)$$

$$= \sum_{i=1}^n Q_i (Q'_i u_i + Q_i u'_i)$$

$$u_x = x^2(1-x)^2 y(1-y)(1-2y)$$

$$u_y = -x(1-x)(1-2x) y^2(1-y)^2$$

$$\frac{\partial u_y}{\partial y} = -x(1-x)(1-2x) \left(2y(1-y)^2 - 2y^2(1-y) \right)$$

$$= -2xy(1-x)(1-2x)(1-y)^2 - y(1-y))$$

$$= -2xy(1-x)(1-2x)(1-y)(1-y - y)$$

$$= \underline{-2xy} \underline{(1-x)} \underline{(1-2x)} \underline{(1-y)} \underline{(1-2y)}$$

$$\frac{\partial u_x}{\partial x} =$$

$$u_x = x^2(1-x)^2y(1-y)(1-2y)$$

$$u_y = -x(1-x)(1-2x)y^2(1-y)^2$$

$$\frac{\partial u_x}{\partial x} = \left[x^2 \left(2(1-x)(1) + 2x(1-x)^2 \right) + (2x^2)(1-x)^2 \right] y(1-y)(1-2y)$$

$$= \left[x^2 2(1-x)(1) + 2x(1-x)^2 \right] y(1-y)(1-2y)$$

$$= \left[-2x^2(1-x) + 2x(1-x)^2 \right] y(1-y)(1-2y)$$

$$= 2x(1-x) \left[-x + (1-x) \right] y(1-y)(1-2y)$$

$$= \boxed{2x(1-x)(1-2x)y(1-y)(1-2y)}$$

$$u_y = -x(1-x)(1-2x)y^2(1-y)^2$$

$$\frac{\partial u_y}{\partial y} = -x(1-x)(1-2x) \left[(2y^2)(1-y)^2 + y^2(1-y)^2 \right]$$

$$= -x(1-x)(1-2x) \left[2y(1-y)^2 + y^2 2(1-y)(-1) \right]$$

$$= -x(1-x)(1-2x) 2y(1-y) [(1-y) - y]$$

$$= \boxed{-x(1-x)(1-2x) 2y(1-y)(1-2y)}$$

$$\begin{aligned}
\frac{\partial^2 u_y}{\partial y^2} &= \frac{\partial}{\partial y} \left(-x(1-x)(1-2x)2y(1-y)(1-2y) \right) \\
&= -2x(1-x)(1-2x) \left[(\partial_y y)(1-y)(1-2y) + y \partial_y (1-y)(1-2y) \right] \\
&= -2x(1-x)(1-2x) \left[(1-y)(1-2y) + y \left[(\partial_y (1-y))(1-2y) + (1-y)(\partial_y (1-2y)) \right] \right] \\
&= -2x(1-x)(1-2x) \left[(1-y)(1-2y) + y(-1)(1-2y) + y(1-y)(-2) \right] \\
&= -2x(1-x)(1-2x) \left[(1-y)(1-2y) - y(1-2y) - 2y(1-y) \right]
\end{aligned}$$

$$\begin{aligned}
\frac{\partial^2 u_x}{\partial x^2} &= \frac{\partial}{\partial x} \left(2x(1-x)(1-2x)y(1-y)(1-2y) \right) \\
&= 2y(1-y)(1-2y) \frac{\partial}{\partial x} \left(x(1-x)(1-2x) \right) \\
&= 2y(1-y)(1-2y) \left[(1-x)(1-2x) + x(\partial_x(1-x))(1-2x) \right. \\
&\quad \left. + x(1-x)(\partial_x(1-2x)) \right] \\
&= 2y(1-y)(1-2y) \left[(1-x)(1-2x) - x(1-2x) - 2x(1-x) \right]
\end{aligned}$$

$$\begin{aligned}
u_x &= x^2(1-x)^2y(1-y)(1-2y) \\
u_y &= -x(1-x)(1-2x)y^2(1-y)^2
\end{aligned}$$

$$\frac{\partial u_x}{\partial y} = x^2(1-x)^2 \left[(\partial_y y)(1-y)(1-2y) + y(\partial_y((1-y)(1-2y))) \right]$$

$$= x^2(1-x)^2 \left[(1-y)(1-2y) - y(1-2y) - 2y(1-y) \right]$$

$$\frac{\partial^2 u_x}{\partial y^2} = x^2(1-x)^2 \left[-2(1-y) - (1-2y) - (1-2y) - y(-2) - 2(1-y) - 2(1-y) \right]$$

$$= x^2(1-x)^2 \left[-2(1-y) - (1-2y) - (1-2y) + 2y - 2(1-y) + 2y \right]$$

$$= x^2(1-x)^2 \left[-2(1-2y) - 4(1-y) + 4y \right]$$

$$\frac{\partial u_y}{\partial x} = -y^2(1-y)^2 \frac{\partial}{\partial x} \left(x((1-x)(1-2x)) \right)$$

$$= -y^2(1-y)^2 \left[(1-x)(1-2x) + x(1)(1-2x) + x(-2)(1-x) \right]$$

$$= -y^2(1-y)^2 \left[(1-x)(1-2x) - x(1-2x) - 2x(1-x) \right]$$

$$\frac{\partial^2 u_y}{\partial x^2} = -y^2(1-y)^2 \left[-(1-2x) - 2(1-x) - (1-2x) + 2x - 2(1-x) + 2x \right]$$

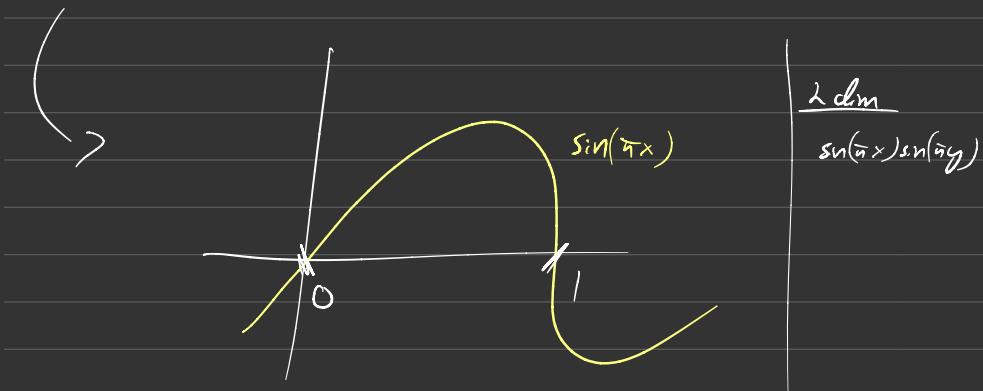
$$= y^2(1-y)^2 \left[2(1-2x) + 4(1-x) - 4x \right]$$

$$f(x,y) = \sin(2\pi x) \sin(2\pi y)$$

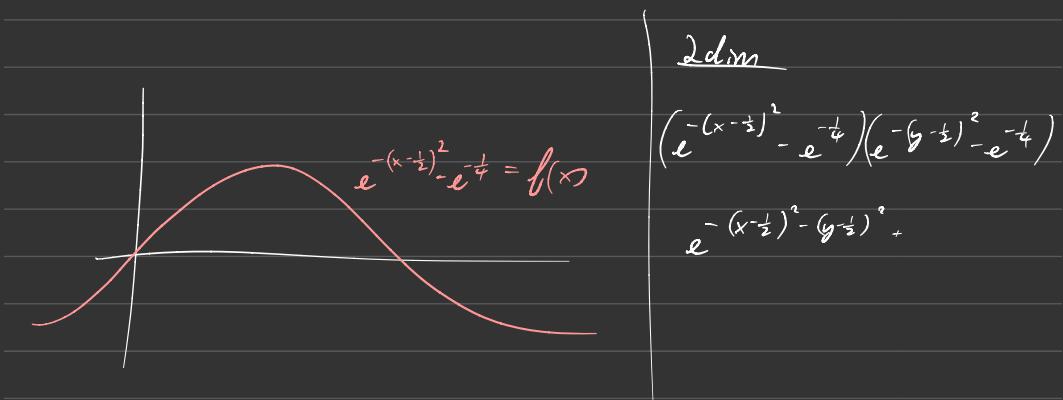
$$\frac{\partial f}{\partial x} = 2\pi \cos(2\pi x) \sin(2\pi y)$$

$$\frac{\partial f}{\partial y} = 2\pi \sin(2\pi x) \cos(2\pi y)$$

$\sin(\pi x)$ ← for making use of zero bcs



$$e^{-\left(x-\frac{1}{2}\right)^2} - a = 0 \quad \text{for } x = 0, 1$$



$$f(0) = f(1) = e^{-\frac{1}{4}} = a$$

$$u_1 = \left(e^{-(x-\frac{1}{2})^2} - e^{-\frac{1}{4}} \right) \left(e^{-(y-\frac{1}{2})^2} - e^{-\frac{1}{4}} \right)$$

$$\frac{\partial u_1}{\partial x} = -\left(e^{-(y-\frac{1}{2})^2} - e^{-\frac{1}{4}} \right) 2\left(x-\frac{1}{2}\right) \left(e^{-(x-\frac{1}{2})^2} \right)$$

$$-u_2 = -2\left(x-\frac{1}{2}\right) \left(e^{-(x-\frac{1}{2})^2} \right) \int \left(e^{-(y-\frac{1}{2})^2} - e^{-\frac{1}{4}} \right) dy$$

$$= -2\left(x-\frac{1}{2}\right) \left(e^{-(x-\frac{1}{2})^2} \right) \left(-\frac{1}{2} \sqrt{\pi} \operatorname{erf}\left(\frac{1}{2}-x\right) + f(x) \right)$$

Basis functions

$$Q_j(x) = \begin{cases} 0 & | x \leq j-h \\ \frac{x}{h} + \left(1 - \frac{j}{h}\right) & | j-h \leq x \leq j \\ -\frac{x}{h} + \left(1 + \frac{j}{h}\right) & | j \leq x \leq j+h \\ 0 & | x \geq j+h \end{cases}$$

$$Q'_j(x) = \begin{cases} 0 & | x \leq j-h \\ \frac{1}{h} & | j-h \leq x \leq j \\ -\frac{1}{h} & | j \leq x \leq j+h \\ 0 & | x \geq j+h \end{cases}$$

$$Q_{ij}(x, y) = Q_i(x) Q_j(y)$$

$$\nabla Q_{ij}(x, y) = \left(\frac{\partial}{\partial x} Q_{ij}(x, y), \frac{\partial}{\partial y} Q_{ij}(x, y) \right)$$

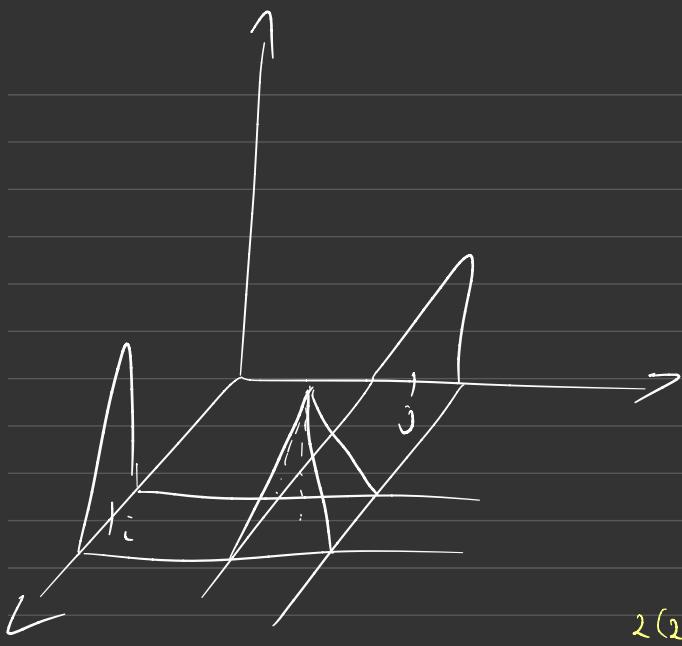
$$= \left(Q'_i(x) Q_j(y), Q_i(x) Q'_j(y) \right)$$

$$\nabla \varphi_{i,j} \cdot \nabla \varphi_{a,b} = \varphi'_i(x) \varphi_j(y) \varphi'_a(x) \varphi_b(y) \\ + \varphi_i(x) \varphi'_j(y) \varphi_a(x) \varphi'_b(y)$$

$$\nabla \varphi_{i,j} \cdot (\varphi_{a,b} \nabla u + (u+1) \nabla \varphi_{a,b})$$

$$= \begin{bmatrix} \varphi'_i(x) \varphi_j(y) \\ \varphi_i(x) \varphi'_j(y) \end{bmatrix} \cdot \left(\begin{bmatrix} \varphi_{a,b} \frac{\partial}{\partial x} u \\ \varphi_{a,b} \frac{\partial}{\partial y} u \end{bmatrix} + \begin{bmatrix} (u+1) \varphi'_a(x) \varphi_b(y) \\ (u+1) \varphi_a(x) \varphi'_b(y) \end{bmatrix} \right)$$

$$= (\varphi'_i(x) \varphi_j(y)) (\varphi_a(x) \varphi_b(y) \frac{\partial u}{\partial x} + (u+1) \varphi'_a(x) \varphi_b(y)) \\ + (\varphi_i(x) \varphi'_j(y)) (\varphi_a(x) \varphi_b(y) \frac{\partial u}{\partial y} + (u+1) \varphi_a(x) \varphi'_b(y))$$



$$2(2h)^2 = c^2$$

$$8h^2 = c^2$$

$$c = 2\sqrt{2}h$$

$$(i-h, i+h) \quad (j-h, j+h)$$

$$2h$$

$$-\nabla \cdot (g(u) \nabla u)$$

$$= -\nabla \cdot (g(u)(\partial_x u, \partial_y u, \partial_z u))$$

$$= -\nabla \cdot (g(u) \partial_x u, g(u) \partial_y u, g(u) \partial_z u)$$

$$= -(\partial_x, \partial_y, \partial_z) \cdot (g(u) \partial_x u, g(u) \partial_y u, g(u) \partial_z u)$$

$$= -\partial_x(g(u) \partial_x u) + \partial_y(g(u) \partial_y u) + \partial_z(g(u) \partial_z u)$$

$$= -\partial_x g(u) \partial_x u + g(u) \partial_x^2 u +$$

$$\partial_y g(u) \partial_y u + g(u) \partial_y^2 u +$$

$$\partial_z g(u) \partial_z u + g(u) \partial_z^2 u$$

$$\frac{d}{dx} (\nabla u)^2 + \boxed{u \nabla^2 u}$$

$$\left[\begin{array}{c} < > & < > \\ \vdots & \vdots \\ \end{array} \right] \left[\begin{array}{c} u_{xx} + u_{yy} + u_{zz} \\ \vdots \\ \end{array} \right]$$

$$\boxed{\vec{D}u = \vec{f}} \quad u \text{ scalar}$$

$$\begin{bmatrix} d_x u \\ d_y u \end{bmatrix} = \begin{bmatrix} f_1(x, y) \\ f_2(x, y) \end{bmatrix}$$

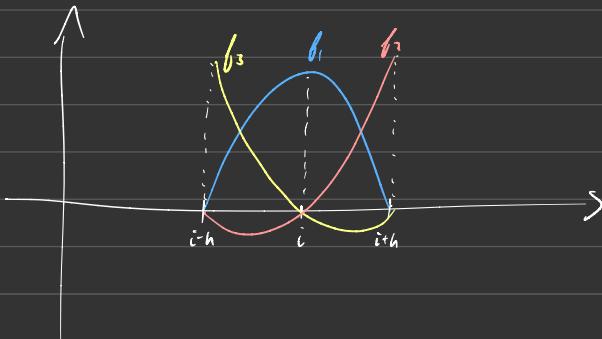
V = {arterial blood}

$$V_h = \left\{ Q_i(\infty) \mid \right. \quad \left. \vec{z} \right.$$

$$V_h = \left\{ (Q_i(\infty), Q_j(\infty)) \mid \right. \quad \left. \vec{z} \in \Phi(\infty) \right\}$$

$$\vec{D}u \cdot \Phi = \vec{f} \cdot \Phi$$

Quadratic Basis Functions



$$b_i(x) = b(x - (i-h))(x - (i+h))$$

$$b_i(i) = 1 \Rightarrow b_i(i) = b(i - i+h)(i - i-h)$$

$$= b(h)(-h) = -bh^2 = 1$$

$$b = -\frac{1}{h^2}$$

$$b_1(x) = -\frac{1}{h^2}(x - (i-h))(x - (i+h))$$

$$b_2(x) = b(x - i)(x - (i-h))$$

$$b_2(i+h) = b(i+h - i)(i+h - i-h) = 1$$

$$= 2bh^2 = 1 \Rightarrow b = \frac{1}{2h^2}$$

$$\left\{ \begin{array}{l} f_1(x) = -\frac{1}{h^2}(x - (c-h))(x - (c+h)) \\ f_2(x) = \frac{1}{2h^2}(x - c)(x - (c-h)) \\ f_3(x) = \frac{1}{2h^2}(x - c)(x - (c+h)) \end{array} \right.$$

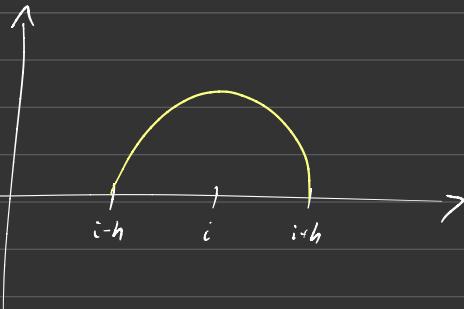
The function is

$$\text{quad_func}(x) = 1 - (f_2(x) + f_3(x)) \\ = 1 - \left(\frac{x-c}{2h^2} \right) \left((x - (c-h)) + (x - (c+h)) \right)$$

$$= 1 - \left(\frac{x-c}{2h^2} \right) (x - c + h + x - c - h)$$

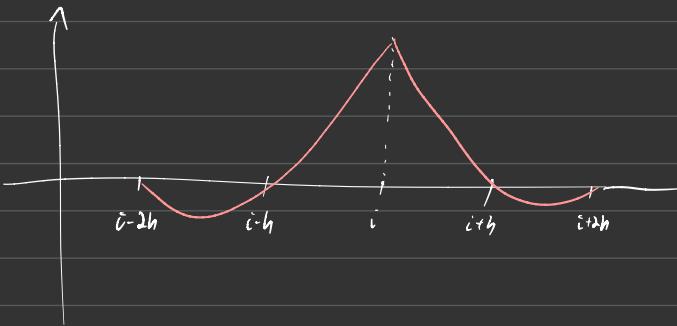
$$= 1 - \left(\frac{x-c}{2h^2} \right) (2x - 2c)$$

$$\boxed{= 1 - \left(\frac{x-c}{h} \right)^2} = f_1(x)$$



$$f(x) = 1 - \left(\frac{x-c}{h}\right)^2 = -\frac{1}{h^2}(x-(c-h))(x-(c+h))$$

$$f(x) = \begin{cases} 0 & x \leq c-h \\ 1 - \left(\frac{x-c}{h}\right)^2 & c-h < x < c+h \\ 0 & x \geq c+h \end{cases}$$



$$g_i(x) = b(x - (i-2h))(x - (i-h))$$

$$\begin{aligned} g_i(i) &= b(i - i + 2h)(i - i - h) = 1 \\ &= b(2h)(-h) = 1 \end{aligned}$$

$$\Rightarrow b = -\frac{1}{2h^2}$$

$$g_2(x) = b(x - (i+h))(x - (i+2h))$$

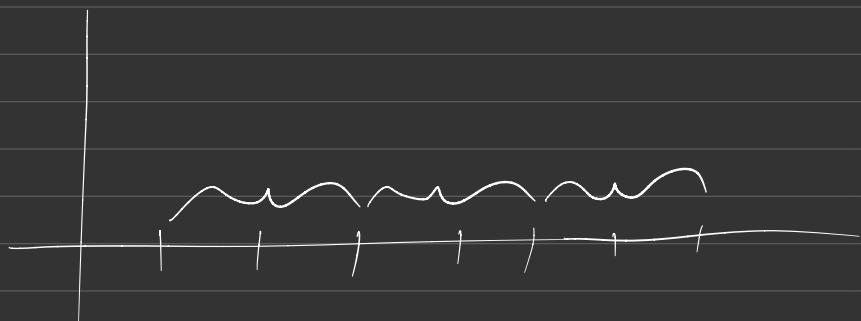
$$\begin{aligned} g_2(i) &= 1 = b(i - i - h)(i - i - 2h) \\ &= b(-h) - 2h = b2h^2 \end{aligned}$$

$$\Rightarrow b = \frac{1}{2h^2}$$

$$g(x) = \begin{cases} 0 & x \leq i-2h \\ \frac{1}{2h^2}(x - (i-2h))(x - (i-h)) & i-2h < x \leq i \\ \frac{1}{2h^2}(x - (i+h))(x - (i+2h)) & i < x \leq i+2h \\ 0 & x \geq i+2h \end{cases}$$

*N*um of vertices allowed with quadratic elements

$$H = 3 + 2n, n \in \mathbb{N}$$



Things to include in report

- 1Dm form
- A comment on base fractures and 2D pattern
- time dependence - Heat equations
- ~~Non linearities~~
- Stokes flow

- A comment on whether they could weakly form
- Navier Stokes

