#### How to enable SPI under BananaPi BPI-R4 v3.

#### 1. Intro

All necessary files are located in my repo: <a href="https://github.com/drozdi70/bananapi">https://github.com/drozdi70/bananapi</a> bpir4
Especially <a href="https://github.com/drozdi70/bananapi">Adafruit</a> Blinka SPI Pack.tar used in point 5.

2. Image preparation.

Add in DTS file section related to enabling spi/spidev (~/openwrt/target/linux/mediatek/files-6.6/arch/arm64/boot/dts/mediatek/mt7988a-bananapi-bpi-r4.dts):

```
&spi1 {
    #address-cells = <1>;
    \#size-cells = <0>;
    pinctrl-names = "default";
    pinctrl-0 = <&spi1_pins>;
    status = "okay";
    spidev0: spidev@0 {
         compatible = "sitronix,st7789v";
         spi-max-frequency = <32000000>;
         #address-cells = <1>;
         \#size-cells = <0>;
         reg = <0>;
         dc-gpios = <&pio 50 GPIO_ACTIVE_HIGH>; //GPIO50/pin 15
         reset-gpios = <&pio 53 GPIO_ACTIVE_LOW>; //pin 22 / GPIO53
         spi-cpol;
         spi-cpha;
         status = "okay";
    };
};
```

Install a patch for st7789v – 0004-spidev-lcd-6.6.patch in your directory where you compile openwrt:

cp 0004-spidev-lcd-6.6.patch ~/openwrt/target/linux/mediatek/patches-6.6/

In menuconfig → enable spi/spipdev to be sure all is installed as kmod-spi-dev spi\_tools spidev\_test kmod-spi-gpio

Write image to SD and start router from SD card. Make connection to internet working from your router.

```
# apk update
# apk upgrade
```

```
root@BPI-R4:~# ls -ltr /dev/spi*
                                          0 Nov 23 20:27 /dev/spidev1.0
                                   153,
crw----
            1 root
                         root
root@BPI-R4:~# lsmod | grep spi
crc itu t
                       12288 1 mmc spi
                       12288 1 mmc spi
crc7
mmc spi
of mmc spi
                             1 mmc spi
spi bitbang
                       12288
                              1 spi gpio
                       16384
spi gpio
spidev
                       20480
oot@BPI-R4:~#
```

#### 3. SPI bus check

If nothing is connected to the bus:

```
root@BPI-R4:~# spidev test -D /dev/spidev1.0 -v
spi mode: 0x0
bits per word: 8
max speed: 500000 Hz (500 kHz)
FF FF F0 0D |.....@....
00 00 |.....
Next we short pin19 and pin21:
```

```
root@BPI-R4:~# spidev_test -D /dev/spidev1.0 -v
spi mode: 0x0
bits per word: 8
max speed: 500000 Hz (500 kHz)
FF FF F0 0D |.....@.....
FF FF F0 0D |.....@....
root@BPI-R4:~#
```

```
root@BPI-R4:~# spi-config -d /dev/spidev1.0 -q
/dev/spidev1.0: mode=0, lsb=0, bits=8, speed=32000000, spiready=0
```

## 4. LCD screen wiring to the board

## BPI-R4 GPIO pinout:

https://docs.banana-pi.org/en/BPI-R4/GettingStarted\_BPI-R4#\_gpio\_define

```
SPI - 1.69inch LCD Module 240x280 pixels, ST7789V2
SPI - 1.54inch LCD module 240x240 pixels, ST7789
VCC -> 3.3V (pin 17)
GND -> GND (pin 20)
SCL -> SPI1_CLK (pin 23)
                               GPIO31
SDA -> SPI1_MOSI (pin 19)
                               GPIO30
RST -> pin 22 / GPIO53
DC
     -> pin 15 / GPIO50
CS
      -> pin26 / GPIO52
      -> +VCC or not connected
BL
SPI1_CSB (24)
                   GPIO28 -- not connected!
```

How to check which GPIO line is free and can be used?

GPIO29 -- not connected!

root@BPI-R4:~# apk add gpiod-tools

```
root@BPI-R4:~# gpioinfo gpiochip0 - 84 lines:
```

SPI1\_MISO (21)

1		
line 0:	unnamed	output consumer=tx-disable
line 1:	unnamed	input consumer=tx-fault
line 2:	unnamed	input consumer=los
line 3:	unnamed	input active-low consumer=rate-select0
line 4:	unnamed	input
line 5:	unnamed	output active-low consumer=reset
line 6:	unnamed	input
line 7:	unnamed	input
line 8:	unnamed	input
line 9:	unnamed	input consumer=kernel
line 10:	unnamed	input consumer=kernel
line 11:	unnamed	input
line 12:	unnamed	input active-low consumer=cd
line 13:	unnamed	input
line 14:	unnamed	input active-low consumer=WPS
line 15:	unnamed	input consumer=kernel
line 16:	unnamed	input consumer=kernel
line 17:	unnamed	input
line 18:	unnamed	input
line 19:	unnamed	input
line 20:	unnamed	input consumer=kernel
line 21:	unnamed	input active-low consumer=rate-select0
line 22:	unnamed	input consumer=kernel

line 2		unnamed	input consumer=kernel
line 2	24:	unnamed	input consumer=kernel
line 2		unnamed	input consumer=kernel
line 2		unnamed	input consumer=kernel
line 2	27:	unnamed	input consumer=kernel
line 2	28:	unnamed	input consumer=kernel
line 2	29:	unnamed	input consumer=kernel
line 3	30:	unnamed	input consumer=kernel
line 3	31:	unnamed	input consumer=kernel
line 3	32:	unnamed	input consumer=kernel
line 3	33:	unnamed	input consumer=kernel
line 3	34:	unnamed	input consumer=kernel
line 3	35:	unnamed	input consumer=kernel
line 3	36:	unnamed	input consumer=kernel
line 3	37:	unnamed	input consumer=kernel
line 3	38:	unnamed	input
line 3	39:	unnamed	input
line 4	40:	unnamed	input
line 4	41:	unnamed	input
line 4	42:	unnamed	input
line 4	43:	unnamed	input
line 4	44:	unnamed	input
line 4	45:	unnamed	input
line 4	46:	unnamed	input
line 4	47:	unnamed	input
line 4	48:	unnamed	input
line 4	49:	unnamed	input
line !	50:	unnamed	input
line !	51:	unnamed	input
line !	52:	unnamed	input
line !	53:	unnamed	input
line !	54:	unnamed	input consumer=los
line !	55:	unnamed	input consumer=kernel
line !	56:	unnamed	input consumer=kernel
line !	57:	unnamed	input consumer=kernel
line !	58:	unnamed	input consumer=kernel
line !	59:	unnamed	input consumer=kernel
line	60:	unnamed	input consumer=kernel
line	61:	unnamed	input consumer=kernel
line	62:	unnamed	input
line	63:	unnamed	output consumer=blue:wps
line	64:	unnamed	input consumer=kernel
line	65:	unnamed	input consumer=kernel
line	66:	unnamed	input consumer=kernel
line		unnamed	input consumer=kernel
line	68:	unnamed	input
line		unnamed	input consumer=tx-fault
line '		unnamed	output consumer=tx-disable
line '		unnamed	input consumer=kernel
line '		unnamed	input consumer=kernel
line '		unnamed	input
line '		unnamed	input consumer=kernel

line	75:	unnamed	input
line	76:	unnamed	input
line	77:	unnamed	input consumer=kernel
line	78:	unnamed	input consumer=kernel
line	79:	unnamed	output consumer=green:status
line	80:	unnamed	input consumer=kernel
line	81:	unnamed	input consumer=kernel
line	82:	unnamed	input active-low consumer=mod-def0
line	83:	unnamed	input active-low consumer=mod-def0

All lines consumer=kernel cannot be used as already reserved. We check lines (GPIO) 50,52,53

```
root@BPI-R4:~# gpioinfo |grep -e "50:" -e "52:" -e "53:"

line 50: unnamed input

line 52: unnamed input

line 53: unnamed input

root@BPI-R4:~#
```

We also check base numer for gpiochip  $\rightarrow$  in our case is 512 (needed for pin mapping).

```
root@BFI-R4:~# 1s -ltr /sys/class/gpio/
--w----- 1 root root 4096 Jan 1 1970 unexport
lrwxrwxrwx 1 root root 0 Jan 1 1970 ppiochip512
--w----- 1 root root 4096 Jan 1 1970 export
root@BFI-R4:~#
```

### 5. SPI configuration

SPI can work programmed in different ways, I decided to use Adafruit-Blinka package and adopt it a little bit as per now our board is not supported offcially there.

Please remember one fact that in the case of any possible upgrade of the package Adafruit\_Blinka you need to repeat whole process as probably some files will be replaced by new ones from new release.

Adafruit-Blinka version: 8.50.0

Adafruit-platformdetect version: 3.75.0

apk update apk upgrade apk add python3 curl git git-http apk add python3-dev make apk add python3-setuptools apk add python3-pip sudo coreutils apk add python3-pillow apk add python3-gpiod

pip3 install Adafruit-Blinka

pip3 install adafruit-platformdetect pip3 install --upgrade adafruit-python-shell click pip3 install adafruit-circuitpython-st7789 pip install adafruit-circuitpython-display-text pip install Adafruit-GPIO

Some Hocus-Pocus (based on https://github.com/Dangku/Adafruit\_Python\_PlatformDetect)

cd /usr/lib/python3.11/site-packages mv adafruit\_platformdetect adafruit\_platformdetect.ORIG copy adafruit platformdetect.tar here and extract tar xvf adafruit\_platformdetect.tar mv board.py board.py.ORIG copy board.py here copy bananapi.tar to /usr/lib/python3.11/site-packages/adafruit\_blinka/board mv bananapi bananapi.ORIG tar xvf bananapi.tar copy mt7988a.tar to /usr/lib/python3.11/site-packages/adafruit blinka/microcontroller tar xvf mt7988a.tar in /usr/lib/python3.11/site-packages/ mv digitalio.py digitalio.py.ORIG in /usr/lib/python3.11/site-packages/ my microcontroller microcontroller.ORIG copy microcontroller.tar here and extract tar xvf microcontroller.tar

#### Tests:

root@BPI-R4:~# python3 detect.py Board Detection Test

Check that the Chip and Board IDs match your board and that this it is correctly detecting whether or not it is a Linux board.

#### Board deteted:

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Chip id: MT7988A

Board id: BANANA\_PI\_BPI\_R4

#### Linux Detection

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Is this an embedded Linux system? True

### Raspberry Pi Boards

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Is this a Pi 3B+? False

Is this a Pi 4B? False

Is this a 40-pin Raspberry Pi? False

Is this a Raspberry Pi Compute Module? False

#### Other Boards

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Is this a Siemens Simatic IOT2000 Gateway? False

Is this a BananaPi board? True

Is this a 96boards board? False

Is this a BeagleBone board? False

Is this a Giant board? False

Is this a Coral Dev board? False

Is this a MaaXBoard? False

Is this a SiFive board? False

Is this a PYNQ board? False

Is this a Rock Pi board? False

Is this a NanoPi board? False

Is this a Khadas VIM3 board? False

Is this a Clockwork Pi board? False

Is this a Seeed Board? False

Is this a UDOO board? False

Is this an ASUS Tinker board? False

Is this an STM32MP1 board? False

Is this a MilkV board? False

Is this a Luckfox Pico board? False

Is this a generic Linux PC? False

Is this an OS environment variable special case? False

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BananaPi board detected.

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```
root@BPI-R4:~# python3 blinktest.py
Hello, blinka!
Digital IO ok!
I2C ok!
SPI ok!
done!
root@BPI-R4:~#
```

#### Remark:

Adafruit-Blinka package could be probably pinned / hold to the current version/state as below by runnig:

```
# pip3 freeze > requirements.txt
```

and revert operation:

# pip3 install -r requirements.txt

Ref. <a href="https://builtin.com/software-engineering-perspectives/pip-freeze">https://builtin.com/software-engineering-perspectives/pip-freeze</a>

# 6. Examples

```
git clone <a href="https://github.com/adafruit/Adafruit CircuitPython ST7789">https://github.com/adafruit/Adafruit CircuitPython ST7789</a>
cd Adafruit_CircuitPython_ST7789/examples/
edit a file and adjust SPI lines parameteres as below:
spi = busio.SPI(board.D23, MOSI=board.D19)
tft_cs = board.D26
tft_dc = board.D15
tft_backlight = None
or
tft_dc = board.D15
tft_cs = board.D26
spi_clk = board.D23
spi_mosi = board.D19
tft_rst = board.D22
backlight = None
spi = busio.SPI(spi_clk, spi_mosi)
or
spi = board.SPI()
tft_cs = board.D26
tft_dc = board.D15
display_bus = FourWire(spi, command=tft_dc, chip_select=tft_cs, reset=board.D22)
```