

# ON UNBALANCED OPTIMAL TRANSPORT: AN ANALYSIS OF SINKHORN ALGORITHM

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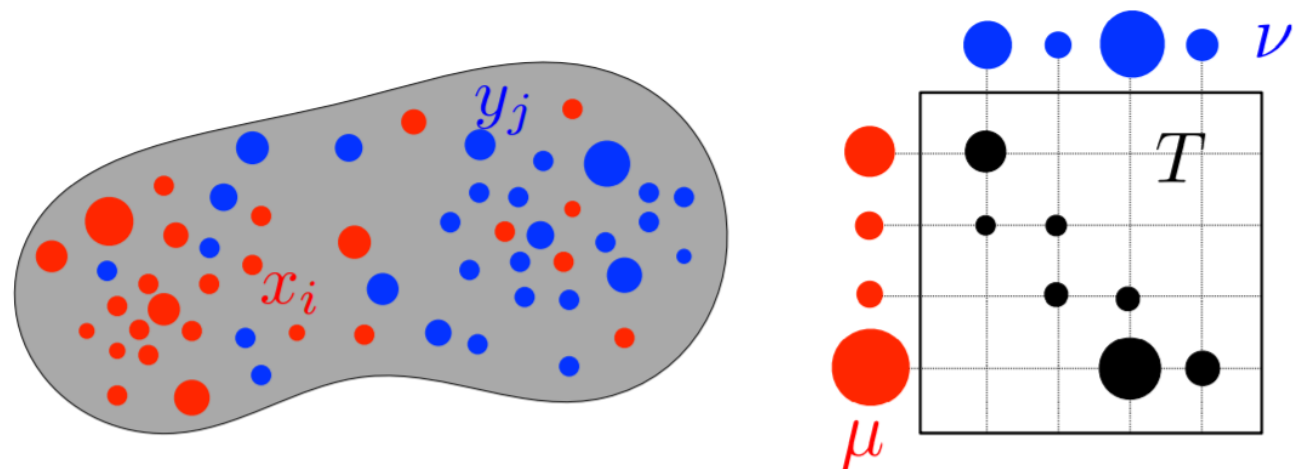
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## Introduction

We provide an complexity analysis for the **Sinkhorn algorithm** for solving the **Unbalanced Optimal Transport** problem, which is a generalized version of the Optimal Transport problem where marginal constraints are relaxed.

Concretely, the complexity is of order  $\tilde{\mathcal{O}}(n^2/\varepsilon^2)$ .

## Unbalanced Optimal Transport



Given two *probability* vectors  $\mathbf{a} \in \mathbb{R}^n, \mathbf{b} \in \mathbb{R}^m$  (i.e.  $\alpha = \beta = 1$ , where  $\alpha = \sum_i \mathbf{a}_i, \beta = \sum_j \mathbf{b}_j$ ), and a cost matrix  $C \in \mathbb{R}_+^{n \times m}$  the classical **Optimal Transport** (OT) problem aims to find a *transportation plan*  $X \in \mathbb{R}_+^{n \times m}$  that

$$\begin{aligned} & \text{minimizes} \quad \langle C, X \rangle, \\ & \text{subject to} \quad X \mathbf{1}_m = \mathbf{a}, X^T \mathbf{1}_n = \mathbf{b}. \end{aligned}$$

If we relax  $\mathbf{a}, \mathbf{b}$  to be arbitrary non-negative vectors, we have the **Unbalanced Optimal Transport** (UOT), that finds

$$\min_{X \in \mathbb{R}_+^{n \times m}} f(X) := \langle C, X \rangle + \tau \text{KL}(X \mathbf{1}_n || \mathbf{a}) + \tau \text{KL}(X^T \mathbf{1}_m || \mathbf{b}),$$

where  $\tau > 0$  tells how much we want the solutions to be close to two marginals.

**Remark 1.** When  $\mathbf{a}^T \mathbf{1}_n = \mathbf{b}^T \mathbf{1}_m$  and  $\tau \rightarrow \infty$ , UOT becomes OT.

**Remark 2.** Advantages of UOT over OT:

- enable transportation between measures of arbitrary masses,
- reduce effect of outliers via soft constraints.

## Dual Entropic-Regularized UOT

By introducing an entropy term  $H(X) = \sum_{i,j=1}^n X_{ij}(\log(X_{ij}) - 1)$  to the UOT objective, we have the **entropic UOT** problem, i.e.

$$\min_{X \in \mathbb{R}^{n \times m}} g(X) := \langle C, X \rangle - \eta H(X) + \tau \text{KL}(X \mathbf{1}_n || \mathbf{a}) + \tau \text{KL}(X^T \mathbf{1}_m || \mathbf{b}),$$

which removes the positive constrain on the variable. Besides, the optimal solution of this problem can be derived from the optimal solution of its dual problem, that reads

$$\min_{u, v \in \mathbb{R}^n} h(u, v) := \eta \sum_{i,j} e^{\frac{u_i + v_j - C_{ij}}{\eta}} + \tau \left\langle e^{-u/\tau}, \mathbf{a} \right\rangle + \tau \left\langle e^{-v/\tau}, \mathbf{b} \right\rangle,$$

which can be solved using the **Sinkhorn algorithm**.

## Sinkhorn Algorithm

**Input:**  $k = 0$  and  $u^0 = v^0 = 0$ , accuracy  $\varepsilon$   
**while**  $k < \tilde{c}^{\frac{\log(n)}{\varepsilon}}$  **do**  
 $a^k = B(u^k, v^k) \mathbf{1}_n, \quad b^k = B(u^k, v^k)^T \mathbf{1}_m.$   
**if**  $k$  is even **then**  
 $u^{k+1} = \left[ \frac{u^k}{\eta} + \log(a) - \log(a^k) \right] \frac{\eta\tau}{\eta + \tau}, \quad v^{k+1} = v^k$   
**else**  
 $v^{k+1} = \left[ \frac{v^k}{\eta} + \log(b) - \log(b^k) \right] \frac{\eta\tau}{\eta + \tau}, \quad u^{k+1} = u^k.$   
**end if**  
 $k = k + 1.$   
**end while**  
**Output:**  $B(u^k, v^k).$

## $\varepsilon$ -approximation

For any  $\varepsilon > 0$ , we call  $X$  an  $\varepsilon$ -approximation transportation plan if the following holds

$$\begin{aligned} & \langle C, X \rangle + \tau \text{KL}(X \mathbf{1}_n || \mathbf{a}) + \tau \text{KL}(X^T \mathbf{1}_m || \mathbf{b}) \\ & \leq \left\langle C, \hat{X} \right\rangle + \tau \text{KL}(\hat{X} \mathbf{1}_n || \mathbf{a}) + \tau \text{KL}(\hat{X}^T \mathbf{1}_m || \mathbf{b}) + \varepsilon, \end{aligned}$$

where  $\hat{X}$  is an optimal transportation plan for the UOT problem.

## Our contribution

We show that the complexity of the Sinkhorn algorithm is

$$\mathcal{O}\left(\frac{\tau(\alpha + \beta)n^2}{\varepsilon} \log(n) \left[ \log(\|C\|_\infty) + \log(\log(n)) + \log\left(\frac{1}{\varepsilon}\right) \right]\right).$$

## Detailed Analysis

Denote  $u^k, v^k$  the partial solution at the  $k$ -th iteration and  $u^*, v^*$  the optimal solution of the dual problem. Our main theorems are:

**Theorem 1.** The update  $(u^{k+1}, v^{k+1})$  from Sinkhorn Algorithm satisfies the following bound

$$\max \left\{ \|u^{k+1} - u^*\|_\infty, \|v^{k+1} - v^*\|_\infty \right\} \leq \left( \frac{\tau}{\tau + \eta} \right)^k \times \tau \times R$$

where  $R := \|\log(\mathbf{a})\|_\infty + \|\log(\mathbf{b})\|_\infty + \max \left\{ \log(n), \frac{1}{\eta} \|C\|_\infty - \log(n) \right\}.$

→ This shows that the Sinkhorn algorithm converges at a **geometric rate**.

**Theorem 2.** Let

$$\begin{aligned} S &= \frac{1}{2}(\alpha + \beta) + \frac{1}{2} + \frac{1}{4 \log(n)}, \quad S = \tilde{\mathcal{O}}(\alpha + \beta) \\ T &= \left( \frac{\alpha + \beta}{2} \right) \left[ \log\left( \frac{\alpha + \beta}{2} \right) + 2 \log(n) - 1 \right] + \log(n) + \frac{5}{2}, \quad T = \tilde{\mathcal{O}}((\alpha + \beta) \log(n)) \\ U &= \max \left\{ S + T, 2\varepsilon, \frac{4\varepsilon \log(n)}{\tau}, \frac{4\varepsilon(\alpha + \beta) \log(n)}{\tau} \right\}. \quad U = \tilde{\mathcal{O}}((\alpha + \beta) \log(n)) \end{aligned}$$

For  $\eta = \frac{\varepsilon}{U}$  and  $k \geq 1 + \left( \frac{\tau U}{\varepsilon} + 1 \right) \left[ \log(8\eta R) + \log(\tau(\tau + 1)) + 3 \log\left( \frac{U}{\varepsilon} \right) \right]$ , the solution  $X^k$  is an  $\varepsilon$ -approximation of  $\hat{X}$ .

→ With an additional  $O(n^2)$  per iteration, we get the claimed complexity.

## Experiment

