

kickd_pic32_ubl.dll

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kickd_pic32_ubl

Updating firmware on Microchip PIC32 devices from your own Windows application.

kickd_pic32_ubl.dll is a simple Windows 32 bit DLL API that offers the functionality of the Microchip PIC32UBL.exe Windows PC application. No additional dependencies.

How to Use:

- Alternative 1: Use the [kickd_pic32_ubl.h](#) DLL include header and the kickd_pic32_ubl.lib file for implicit / static linking of the kickd_pic32_ubl.dll.
- Alternative 2: Use the [Pic32UblRtLink](#) C++ class for explicit linking at runtime. I.e. the DLL is only loaded on use, and not required at startup of your application.

See also [Pic32UblRtLink - How to use](#) for more information and example code.

This DLL is based on the "Microchip PC Application" MFC programming example PIC32UBL.exe. Copyright (c) 2013 Microchip Technology Inc. All rights reserved.

See the Microchip Application Note AN1388 and the related source code ("PC Application" folder) for copyright and additional information:

http://ww1.microchip.com/downloads/en/AppNotes/AN1388%20Source%20Code%202014_02_14.zip

For the modifications and DLL wrapper around the Microchip PIC32UBL code, the following applies:

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kickd_pic32_ubl.dll and the related example have been compiled using Visual Studio 2008, but there is no need to recompile kickd_pic32_ubl.dll yourself. kickd_pic32_ubl.dll can be used "as is" - It is linked statically and does not require additional runtime DLLs.

\$Id: kickd_pic32_ubl_doc.h 339 2014-02-28 13:00:04Z oliver \$

Pic32UblRtLink - How to use

The [Pic32UblRtLink](#) adapter class implements explicit linking of the kickd_pic32_ubl.dll. This is to avoid external references to the DLL during compile time and allows starting your application even when the kickd_pic32_ubl.dll is not available.

How to use:

- Make sure the PIC_DLL_PATH define in [Pic32UblRtLink.h](#) contains the correct path to the DLL.
- Create a [Pic32UblRtLink](#) object, and get your downloader started, e.g using something like this:

```
Pic32UblRtLink *pUpdater;  
pUpdater = new Pic32UblRtLink(); // (with pUpdater a Pic32UblRtLink * pointer)  
bool success = (pUpdater->getDLLStatus() == 0);  
if (!success) {  
    // indicate error  
}  
else {  
    success = pUpdater->ConnectAndProgram("myfile.hex", 0x4d8, 0x3c);  
    if (!success) {  
        // indicate error  
    }  
}  
if (!success) {  
    delete pUpdater;  
    pUpdater = NULL;  
}
```

- Then periodically call the message pump and check the status of the current programming task. E.g something like

```
bool finished = false;  
int status = -1;  
while (!finished) {  
    pUpdater->MessagePump();  
    Sleep(10);  
    int newStatus = pUpdater->GetStatus();  
    if (newStatus != status) {  
        status = newStatus;  
        switch (status) {  
            case UBLAPI_READY:  
                cout << "Could not connect to device. Aborting." << endl;  
                finished = true;  
                success = false;  
                break;  
            case UBLAPI_CONNECTING:  
                cout << "Connecting..." << endl;  
                break;  
            case UBLAPI_ERASE:  
                cout << "Erasing..." << endl;  
                break;  
            case UBLAPI_PROGRAM:  
                cout << "Programming..." << endl;  
                break;  
            case UBLAPI_VERIFY:  
                cout << "Verifying..." << endl;  
                break;  
            case UBLAPI_APPSTART:  

```

```

        cout << "Programming completed. Application started." << endl;
        finished = true;
        break;
    case UBLAPI_ERROR:
        cout << "Error while programming." << endl;
        finished = true;
        success = false;
        break;
    }
}
}
pUpdater->Disconnect();
delete pUpdater;
pUpdater = NULL;

```

A fully working example is "pic32_firmware_upload_demo.exe", source code in folder .

It uses a Microchip example .hex file name by default, "Demo_App_PIC32_Starter_Kits.hex".

A sample run, using a custom firmware file for our own device "usb2drive" looked like this:

```

Kickdrive / Microchip PIC32 UBL Demo application. Use at own risk!
PIC32 UBL bootloader must be active.
Firmware hex file used: usb2drive_V1.1.1.353.hex
Press any key to continue . . .
Starting...
Connecting...
Erasing...
Programming...
Verifying...
Programming completed. Application started.
Microchip PIC32 UBL demo ended.
Press any key to continue . . .

```

Hierarchical Index

Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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Class Index

Class List

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Class Documentation

_HIDD_ATTRIBUTES Struct Reference

Public Attributes

- **ULONG** **Size**
- **USHORT** **VendorID**
- **USHORT** **ProductID**
- **USHORT** **VersionNumber**

CBootLoader Class Reference

Public Member Functions

- void **ShutdownThread** ()
- void **CreateRxTxThread** (HWND)
- void **TransmitTask** (void)
- void **ReceiveTask** (void)
- bool **SendCommand** (char cmd, unsigned short Retries, unsigned short RetryDelayInMs)
- void **BuildRxFrame** (unsigned char *, unsigned short)
- void **HandleResponse** (void)
- void **StopTxRetries** (void)
- void **NotifyEvent** (unsigned int IEvent)
- void **GetRxData** (char *buff)
- void **GetProgress** (int *Lower, int *Upper)
- void **HandleNoResponse** (void)
- unsigned short **CalculateFlashCRC** (void)
- bool **LoadHexFile** (const char *hexFilePath)
- void **OpenPort** (UINT portType, UINT comport, UINT baud, UINT vid, UINT pid, USHORT skt, ULONG ip, HWND hwnd)
- BOOL **GetPortOpenStatus** (UINT PortType)
- void **ClosePort** (UINT PortType)
- BOOL **NotifyDeviceChange** (UINT portType, char *devPath)

Public Attributes

- bool **ExitThread**
- bool **ThreadKilled**
- [CComPort](#) **ComPort**
- [CUsbHid](#) **UsbHid**
- [CEthernet](#) **Ethernet**

CComPort Class Reference

Public Member Functions

- void **OpenComPort** (unsigned int, unsigned int)
- void **CloseComPort** (void)
- void **SendComPort** (char *, int)
- bool **GetComPortOpenStatus** (void)
- unsigned short **ReadComPort** (char *, int)

CEthernet Class Reference

Public Member Functions

- **BOOL OpenUdpPort** (USHORT, ULONG)
- **void CloseUdpPort** (void)
- **void SendUdpPort** (BYTE *, INT)
- **USHORT ReadUdpPort** (BYTE *, INT)
- **BOOL GetSocketOpenStatus** (void)

CHexManager Class Reference

Public Member Functions

- bool **ResetHexFilePointer** (void)
- bool **LoadHexFile** (const char *myHexFilePath)
- unsigned short **GetNextHexRecord** (char *HexRec, unsigned int BuffLen)
- unsigned short **ConvertAsciiToHex** (void *VdAscii, void *VdHexRec)
- void **VerifyFlash** (unsigned int *StartAdress, unsigned int *ProgLen, unsigned short *crc)

Public Attributes

- unsigned int **HexTotalLines**
- unsigned int **HexCurrLineNo**

CKickdPic32Ubl Class Reference

Main header file for the kickd_pic32_ubl DLL.

#include <kickd_pic32_DLLmain.h>

Inherits CWinApp.

Public Member Functions

- virtual BOOL [InitInstance](#) ()
- virtual int [ExitInstance](#) ()

Detailed Description

Main header file for the kickd_pic32_ubl DLL.

DLL entry point

Member Function Documentation

BOOL CKickdPic32Ubl::InitInstance ()[virtual]

multithreading and multiple instances not supported, go through global object always (improvement should protect this with a critical section)

CPIC32UBLDlg Class Reference

Modified [CPIC32UBLDlg](#) code.

#include <PIC32UBLDlg.h>

Inherits CWnd.

Public Member Functions

- void [messagePump](#) ()
dispatches as messages and returns, when message queue empty
- void **OnBnClickedCancel** ()
- void **OnBnClickedButtonConnect** (UINT portType, INT comport, INT baud, UINT vid, UINT pid, ULONG ip, USHORT skt)
- void **Disconnect** ()
- void **ExtraInitialization** (void)
- void **StartSendReceiveTimers** (void)
- void **ProgressBarTask** (void)
- void **ProgramHexFile** (void)
- afx_msg LRESULT **OnReceiveResponse** (WPARAM, LPARAM)
- afx_msg LRESULT **OnTransmitFailure** (WPARAM, LPARAM)
- afx_msg void **OnTimer** (UINT nIDEvent)
- afx_msg void **OnBnClickedButtonErase** ()
- bool **OnBnClickedButtonLoadhex** (const char *hexFilePath)
- afx_msg void **OnBnClickedButtonProgram** ()
- afx_msg void **OnBnClickedButtonDisconnect** ()
- afx_msg void **OnBnClickedButtonVerify** ()
- afx_msg void **OnBnClickedButtonEraseProgVerify** ()
- afx_msg void **OnBnClickedButtonRunapplication** ()
- afx_msg void **OnBnClickedButtonBootVer** ()
- afx_msg void **OnBnClickedRadioEnableCom** ()
- afx_msg void **OnBnClickedCheckComEnable** ()
- afx_msg void **OnBnClickedCheckUsbEnable** ()
- afx_msg void **OnBnClickedCheckEthEnable** ()

Public Attributes

- char **TxCommand**
- char **TxData** [255]
- CString **cstringEditConsole**
- unsigned long **uLongEditBoxVID**
- unsigned long **uLongEditBoxPID**
- bool **boolRadioEnableCom**
- bool **boolRadioEnableUSB**
- BOOL **boolCheckComEnable**
- BOOL **boolCheckUsbEnable**
- CString **stringEditBoxUSBVID**
- CString **stringEditBoxUSBPID**
- BOOL **boolCheckEthEnable**
- DWORD **ip_value**
- UINT **valEditBoxSocket**
- int [ublApiStatus](#)

this is public information that is evaluated by UblApi

- int **ublApiProgress**

Protected Member Functions

- void **PrintKonsole** (CString string)
- void **ClearKonsole** (void)
- virtual BOOL **OnInitDialog** ()
- afx_msg void **OnSysCommand** (UINT nID, LPARAM lParam)

Protected Attributes

- [CBootLoader](#) mBootLoader
- bool **EraseProgVer**
- bool **ConnectionEstablished**
- UINT **PortSelected**

Detailed Description

Modified [CPIC32UBLDlg](#) code.

CUsbHid Class Reference

Public Member Functions

- **BOOL OpenUSBDevice** (UINT vid, UINT pid, HWND hwnd)
- **BOOL WriteUSBDevice** (CHAR *buffer, INT buflen)
- **USHORT ReadUSBDevice** (CHAR *buffer, INT buflen)
- **BOOL GetPortOpenStatus** (VOID)
- **VOID ClosePort** (VOID)
- **BOOL OnDeviceChange** (char *path)

Pic32UblRtLink Class Reference

kickd_pic32_ubl

Adapter class for accessing the kickd_pic32_ubl.dll without lib/header file.

#include <Pic32UblRtLink.h>

Public Member Functions

- int [getDLLStatus](#) () const
returns the current status of the FTDI DLL support
 - const char * [getDLLFilename](#) () const
the actual DLL name / path used
 - bool [ConnectAndProgram](#) (const char *hexFilePath, const int vid, const int pid)
wrapper for the MicrochipUblApi.h / kickd_pic32_ubl.dll function
 - void [Disconnect](#) ()
wrapper for the MicrochipUblApi.h / kickd_pic32_ubl.dll function
 - void [MessagePump](#) ()
wrapper for the MicrochipUblApi.h / kickd_pic32_ubl.dll function
 - int [GetStatus](#) ()
wrapper for the MicrochipUblApi.h / kickd_pic32_ubl.dll function
-

Detailed Description

Adapter class for accessing the kickd_pic32_ubl.dll without lib/header file.

See [Pic32UblRtLink - How to use](#) for more information and example code.

Member Function Documentation

int Pic32UblRtLink::getDLLStatus () const

returns the current status of the FTDI DLL support

Returns:

- 0 - DLL ok
- 1 - one or several DLL functions are not available
- 2 - DLL not found

T_HEX_RECORD Struct Reference

Public Attributes

- unsigned char **RecDataLen**
- unsigned int **Address**
- unsigned int **MaxAddress**
- unsigned int **MinAddress**
- unsigned char **RecType**
- unsigned char * **Data**
- unsigned char **Checksum**
- unsigned int **ExtSegAddress**
- unsigned int **ExtLinAddress**

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