	R mass m Dre = 1 5 brabs du(b)
	m B
	P(161) dVol(b)
	B
references and describe describe and of the described which which was a described with an extraction of the contraction of the	$= 8ns \int bn P(161) S(161) 4(61)$
	To the state of th
	= S(1) Sps ( och p(x) doc hypersunface
***************************************	n m area of sphere
	e of readius III
WW-100-0 Wholes described with 1918 with a March Afficiation of the and	$= \frac{V_n \delta_n}{\delta_n} \int \frac{d^n f}{dx} \rho(x) dx$
	m o Vn = volume of unit ball
	P in View vo
	$Set \lambda = \frac{V_n \int x^{n+1} p(x) dx}{s}$
	m °
	Example $P = const. = \frac{m}{V(R)}$ , $\Omega = \frac{\sqrt{k}}{m} \int \frac{R}{R^2 / k} dx = \frac{R^2}{n+2}$
	A Sh
	Uniform man dist. : 2 = R/n+2
	$L = \lambda I$ $\mathcal{L} = 2\lambda I$ $\mathcal{V} = \sqrt{2\lambda}$
	R
	Example $P = const. \Rightarrow \gamma = \sqrt{\frac{2}{p+2}}$
	and consequent and the second of the second
	Note: Imgeneral 0 < 2 < R/n.
wash sand-the sandershow data as some Mine Property Sector Sector Sector Sec	
And the state of t	

	Pre-collision state (U, u) (U, u), (A, a,), (A, a,)
	$U_1 \in SD(n) \qquad  a_1 - a_2  = R_1 + R_2$
	$u_i \in \mathbb{R}^n$
	X in body i (X ∈ B; +a;) Velocity:
	The board of the second of the
	$\frac{\sqrt{ x }}{\sqrt{ x }} = \frac{\sqrt{ x }}{\sqrt{ x }} + \frac{ x }{\sqrt{ x }}$
	$V_{i}(Q) = R_{i} U_{i} V_{i}(Q) + u_{i}$
	$\sqrt{\left(\frac{1}{2}\left(\frac{1}{2}\right)\right)}$
-	
	Y(Q) = - Y(Q) = V
	1,021
	Given two states at q = (I, a, I, a2)!
**************************************	
	$\xi = (u_1^{\xi}, u_2^{\xi}, u_2^{\xi}),  \eta = (u_1^{\eta}, u_1^{\eta}, u_2^{\eta}, u_2^{\eta})$
	Kinetic energy Riemannian metric:
	1/5 m - 5 m - 10 - 115 119 + 115 119 -
	$\left\langle \xi, \eta \right\rangle_{1} = \sum_{j=1,2} m_{j} \left[ \lambda_{j} T_{F} \left( u_{j}^{\dagger} U_{j}^{\dagger} \right) + u_{j}^{\dagger} \cdot u_{j}^{\dagger} \right]$
• • • • • • • • • • • • • • • • • • •	
	Normal vector $m_q = -\frac{1}{m_1} \left( 0, \sqrt{\frac{m_2}{m_1}} V_1(Q), 0, \sqrt{\frac{m_1}{m_1}} V_2(Q) \right)$
	$\frac{ \text{Normal Vector } \text{In}_q = -\frac{1}{ \text{Im} }  \text{O}, \sqrt{\frac{m}{m_1}} \text{V}_1(Q), \text{O}, \sqrt{\frac{m_1}{m_2}} \text{V}_2(Q)}{ \text{Im} }$
	$m = m_1 + m_2$
	$= \frac{1}{m_1} \left( 0, -\sqrt{\frac{m_2}{m_1}} \vee , 0, \sqrt{\frac{m_1}{m_2}} \vee \right)$
	$\sqrt{m_2}$
	mm, no notations
	$\frac{1}{m}$

 $\frac{R_2}{2\lambda_2}$   $V_1(0) \wedge V_2, V_2$ m, u, + m, u V · u; = 0 n-1 En but without the condition V. uj=0 Same as V,(Q1 No-dip vectors Q-a,) + " R,V R, U, V + U, = Orthogona G, DC, DRn,

	Let $\Sigma = (U_1, u_1, U_2, u_3)$ by a state at $f = (I_1, a_1, I_2, a_2)$
,	
Anter Anti-Bille State Manufallistation in Artiflet Have discussed in Anti-Bill Have been included the base	$\xi = \left( W_1, W_2, W_3, W_2 \right) + \left( \frac{R_1}{2\lambda_1} V \wedge Y_0, Y_1, -\frac{R_2}{2\lambda_2} V \wedge Y_2, Y_2 \right)$
**************************************	
<del></del>	$EG_{4}$ $+ S \perp \left(0, -\sqrt{\frac{m_{2}}{m}} \vee 0, \sqrt{\frac{m_{1}}{m}} \vee\right)$
ader stadt eine Sterlands uphade vom dant til 1840 för de stadt vandt ungen, algemente i venskapa	$\in \mathbb{G}_{q}$ $+ \underbrace{S \perp \left(0, -\sqrt{\frac{m_{2}}{m_{1}}}, 0, \sqrt{\frac{m_{1}}{m_{1}}}\right)}_{\sqrt{m}}$
	$V \cdot Y_{j} = 0 \qquad M \cdot Y_{j} + M_{j} Y_{j} = 0 \qquad \qquad M_{q}$
ak aan kirakunda darah araw adalah kirakun dalam kan	
	$R_1 W_1 v_1 + v_1 = -R_2 W_2 v_1 + v_2 = \Theta$
. /	Sanity check!
	D G, L C,
	$\frac{\sum_{j} m_{j} \left\{ \lambda_{j} \right\} T_{r} \left( \frac{R_{j}}{2\lambda_{j}} V_{j} \lambda_{j} V_{j}^{\dagger} \right) + w_{j} \cdot y_{j}^{\dagger} }{2} \cdot \frac{1}{R_{j} V_{j} V_{j} V_{j}^{\dagger}} $
	22) R. W. V. V. V.
	$-R_j T_r(v_i, v_j, W_i) = R_j(W_i, v_i, y_i, W_i, v_i)$
	2
	$\sum e_k \cdot (v_j \wedge y_j \cdot W_i \cdot e_k) = \sum y_j \cdot w_i \cdot e_k \cdot y_j \cdot e_k - \sum y_j \cdot w_j \cdot e_k$
	K - landamental integration of the control of the c
, , , , , , , , , , , , , , , , , , ,	Vj. Wjek yj - Yj. Wjek V
	$= \sum_{i=1}^{n} \frac{1}{i} \frac{1}{i$
-P-10-Mark Phonois Symbology der North-Symbol and Salak Society	
	A independe of =0
The shift World Clark Commence and appropriate of the Warrance and any analysis	
diturba <u>aan d</u> alah disamban persahah mendidi 1944 dan saman persaha	

	None of the second of the seco
	2 E, 1 M2.
	$\left\langle \left( \frac{R_1}{2\lambda_1} \vee \Lambda_{y_1}, \frac{1}{y_1}, -\frac{R_2}{2\lambda_2} \vee \Lambda_{y_2}, \frac{1}{y_2} \right), \left( 0, -\sqrt{\frac{m_2}{m_1}} \vee, 0, \sqrt{\frac{m_1}{m_2}} \vee \right) \right\rangle$
	$= -m_1 y_1 \cdot \sqrt{\frac{m_2}{m_1}} + m_2 y_2 \cdot \sqrt{\frac{m_1}{m_2}} = \sqrt{m_1 m_2} (y_2 - y_1) \cdot v = 0.$
	Normal component of 8
	$S = \left\langle F, \Pi_{q} \right\rangle = \left\langle \left( U_{1}, u_{1}, U_{2}, u_{2} \right), \frac{1}{\sqrt{m}} \left( \sigma, -\sqrt{\frac{m_{2}}{m}} V, \sigma, \sqrt{\frac{m_{1}}{m_{2}}} V \right) \right\rangle$ $S = \left\langle \overline{m_{1}m_{2}} \left( u_{2} - u_{1} \right), V \right\rangle$
	The end projection to $T_{1}$ $\partial M$ The end of $F$ $G$
	Ym · · · · · · ·
	$= \left( \bigcup_{i}, \underbrace{u_{1} + \frac{m_{2}}{m}}_{i} \left( u_{2} - u_{i} \right) \cdot V \cdot V \right) \cdot \underbrace{U_{2}, \underbrace{u_{2} - \frac{m_{1}}{m}}_{i} \left( u_{2} - u_{i} \right) \cdot V \cdot V \right)}_{1}$
	$\frac{1}{m} + u_1 \cdot v + \frac{m_2(u_2 - u_1) \cdot v \cdot v}{m} + \frac{m_1 u_1 + m_2 u_2 \cdot v \cdot v}{m}$
	$\overline{u}$ , + $m_1 u_1$ + $m_2 u_2$ , $v_1 v_2$
orth.	proj. to v m
	$TT \xi = \left( \bigcup_{i} \overline{u}_{i} + \frac{m_{i}u_{i} + m_{2}u_{2}}{m}, \forall V, \bigcup_{2} \overline{u}_{2} + \frac{m_{i}u_{i} + m_{2}u_{2}}{m}, \forall V \right)$

	$TT^{\perp}: \mathbb{R}^{n} \to V^{\perp} \qquad \mathbb{R}! = \frac{1}{2}$
	$u \mapsto \overline{u}$ $2\lambda$ ; $R_i^2 y_i^2$
promotes and the section of the sect	
**************************************	
	$\frac{1}{R_{2}} \frac{2}{R_{2}} \frac{V_{2} - V_{2}}{R_{2}}$
•	1\2 ^2
	$\sqrt{(3)} m_1 w_1 + m_2 w_2 = m_1 z_1 + m_2 z_2$
	$\frac{\left( \left( L_{1}\right)  W_{1} \cdot V_{1}}{\left( L_{1}\right)  W_{2} \cdot V_{2}} = \mathcal{Z}_{1} \cdot V_{2}$
	112
	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
	$\frac{1}{6} R_1 W_1 V + W_1 = -R_2 W_2 V + W_2$
****	$(y_{\lambda}a)\dot{y} = a - a_{i}vy$
	① b ② x ⑥ =>
	$\frac{R_{1}(Z_{1}-\frac{1}{R_{1}Y_{2}^{2}})V+W_{1}=-R_{2}(Z_{2}+\frac{1}{R_{2}Y_{2}^{2}})V+W_{2}}{R_{1}Y_{2}^{2}}$
the black on the Affire relative plants of the second company and a second company and a second the Second comp	$R_1 Y_1^2$
	$R.Z.V - \frac{1}{2}(ZW.) + W. = -R.Z.V - \frac{1}{2}(ZW.) + W.$
	$\frac{R.Z_1V - \frac{1}{2}(Z_1 - W_1) + W_1}{Y_1^2} = -R_2Z_2V - \frac{1}{2}(Z_2 - W_2) + W_2$
	$\frac{(R_1 Z_1 + R_2 Z_2) v - \frac{v}{2} (Z_1 - w_1) + \frac{v}{2} (Z_2 - w_2) = w_2 - w_1}{\gamma_1^2}$
	R7+R7 V+17 12 W W
	$\frac{\left(R_{1}Z_{1}+R_{2}Z_{1}\right)\vee+\frac{1}{2}Z_{2}-\frac{1}{2}Z_{1}-\frac{1}{2}W_{2}-W_{1}+\left(\frac{1}{2}W_{2}-\frac{1}{2}W_{1}\right)}{\gamma_{2}^{2}\gamma_{1}^{2}}$
	f <sub>2</sub> (1)

	$\frac{1 - (1 + \frac{1}{\gamma^2}) w_1 + (1 + \frac{1}{\gamma^2}) w_2 = (R_1 Z_1 + R_2 Z_2) v - \frac{1}{\gamma_1^2} \frac{Z_1 + \frac{1}{\gamma^2}}{\gamma_2^2}$
	$\lambda_{r}$ $\lambda_{r}$
The state of the s	$m, w, + m_2 w_2 = m, z_1 + m_2 z_2$
	~1
	$\left[\begin{array}{c c} W_1 \end{array}\right] \qquad \left[\begin{array}{c c} W_$
	$-m_2$ $1+\frac{1}{x_2}$
	$\frac{m_2\left(1+\frac{1}{\gamma_1^2}\right)+m_1\left(1+\frac{1}{\gamma_2^2}\right)}{m_1}\frac{1+\frac{1}{\gamma_1^2}}{m_2^2}$
	$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$
	$\left( w_{1} \right) \left( m_{1} \left[ \left( R, Z_{1} + R_{2} Z_{2} \right) v - \frac{z_{1}}{\gamma_{1}^{2}} + \frac{z_{2}}{\gamma_{1}^{2}} \right] + \left( 1 + \frac{1}{\gamma_{1}^{2}} \right) \left( m_{1} z_{1} + m_{2} z_{2} \right) \right)$
	$\frac{\left(-m_{2}\left(R,Z,+R,Z_{2}\right)\nu+\frac{m_{2}+2}{2}-\frac{m_{2}+2}{2}+\frac{m_{1}Z_{1}+m_{2}Z_{1}+\frac{m_{1}Z_{1}+m_{2}Z_{2}}{2}+\frac{m_{1}Z_{1}+m_{2}Z_{1}+\frac{m_{1}Z_{1}+m_{2}Z_{2}}{2}+\frac{m_{2}Z_{2}+2}{2}\right)}{2}$
	$ \frac{1}{\sqrt{2}} \frac{m_1(R,Z_1+R_2,Z_2)v - m_1Z_1 + m_1Z_2 + m_1Z_1 + m_2Z_2 + m_1Z_1 + m_2Z_2}{\sqrt{2}} $
	$= \frac{1}{1} - m_{2}(R_{1}Z_{1} + R_{2}Z_{2})v + \oplus Z_{1} + m_{2}(Z_{2} - Z_{1})$
	$[m_1(R_1Z_1+R_2Z_2)v+\Theta Z_2-m_1(Z_2-Z_1)]$

	$W_2 = Z_2 - M_1 \left[ Z_2 - Z_1 - (R_1 Z_1 + R_2 Z_2) V \right]$
	$W_{1} = Z_{1} + \frac{m_{2}}{\mathfrak{D}R_{1}\gamma_{1}^{*}} \vee_{\Lambda} \left[\overline{z}_{1} - \overline{z}_{1} - (R_{1}Z_{1} + R_{2}Z_{2})\vee\right]$
,,,,,	$W_{2} = Z_{2} + M_{1} \qquad \forall A = Z_{2} - (R, Z_{1} + R_{2} Z_{2}) \sqrt{\frac{1}{2}}$ $\Re R_{2} Y_{2}^{2}$ $\overline{Z_{2} - Z_{1}} - (R, Z_{1} + R_{2} Z_{2}) \sqrt{\frac{1}{2}}$
	Sanity check: []. V = 0
	$R_1W_1V_2+W_1-(-R_2W_2V_2+W_2)=(RW_1+R_2W_2)V_2+W_1-W_2$
	$= (R, Z, +R_2Z_2) \vee + (\frac{m_2}{\eta_1^2 \otimes} + \frac{m_1}{\eta_2^2 \otimes}) (\vee_{\Lambda} [\cdots]) \vee + \exists_1 - \exists_2 + \underline{m} [\cdots]$ $[\cdots] = [\cdots] - [\cdots] \cdot \vee_{\Lambda} \vee_{$
	$= \frac{\left(R, Z_1 + R_2 Z_2\right) \vee + \left(\frac{m_2}{\gamma_1^2} + \frac{m_1}{\gamma_2^2}\right) \perp \left[\dots\right]}{\left(\frac{m_2}{\gamma_1^2} + \frac{m_1}{\gamma_2^2}\right) \oplus } + \frac{1}{2} \cdot \frac{1}{2} \cdot \frac{1}{2} + \frac{m_1}{2} \cdot \frac{1}{2}$
	$= (R, Z, +R, Z,) \vee + Z, -Z, + [] = 0$ $-[]$

Orthogonal decomposition continued
Let $\mathcal{E} = (U_1, u_1, U_2, u_2)$ be a state at boundary
configuration $q = (I, a_1, I, a_2)$ , s.t. $(E, In_1) < 0$ .
(a pre-collision state).
$T_{\frac{1}{2}}\partial M \ni T_{\frac{1}{2}} = \left( U_{1}, u_{1} + u_{2} \cdot VV \right) U_{2}, u_{2} + u_{2} \cdot VV \right)$ $Z_{1} = \left( U_{1}, u_{1} + u_{2} \cdot VV \right) U_{2}, u_{2} + u_{2} \cdot VV \right)$
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
$\overline{u}_{1} + u_{2} \cdot vv + \frac{m_{2}}{\otimes} \left[\overline{u}_{2} - \overline{u}_{1} - \left(\overline{R}_{1} U_{1} + \overline{R}_{2} U_{2}\right)v\right]$
$\frac{1}{\sqrt{2} + \frac{1}{2}} = \frac{1}{\sqrt{2}} = \frac{1}{\sqrt$
$n_2 + n_c \cdot v \cdot v - \frac{m_1}{\otimes}$
$\xi - \prod_{q} \xi = \left( -\frac{m_2}{R_i \gamma_i^* \Theta} \gamma_{\Lambda} \left[ \cdots \right], \left( u_i - u_i \right) \cdot \gamma_{\Lambda} - \frac{m_2}{\Theta} \left[ \cdots \right],$
$\frac{-m_1}{R_2Y_2^2 \otimes} \times \left[ \frac{(u_2 - u_2) \cdot v_2 + m_1 [\cdots]}{\otimes} \right] \in \mathcal{E}_{+}^{+}$
No-slip collision: \$ = \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
ξ+=-ξ+2[ξ H ξ]=-ξ+2Πξ

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	$(U_{1}^{+}, u_{1}^{+}, U_{2}^{+}, u_{2}^{+}) = (U_{1}^{-}, u_{1}^{-}, U_{2}^{-}, u_{2}^{-})$
	-2 (-m= VA[] (u,-v-u=.v)v -m=[]
	- m1 V/ [], (N2.4-Nc.1) N + m1 []
	$U_{1}^{+} = U_{1}^{-} + \frac{2m_{2}}{R_{1}\gamma_{1}^{2}Q_{2}} V_{1} \left[ u_{2}^{-} - u_{1}^{-} - (R_{1}U_{1}^{+} + R_{2}U_{2}^{-})V \right]$
	$U_{2}^{+} = U_{2} + 2 m_{1}   V_{A}   [u_{3}^{-} - u_{1}^{-} - (R_{1}U_{1}^{-} + R_{2}u_{2}^{-})V] $ $R_{3}   \chi^{2}                                    $
	$u_{i}^{+} = u_{i}^{-} - 2 \left[ \left[ u_{i}^{-} \cdot v - u_{z}^{-} \cdot v \right] v - \frac{m_{z}^{-}}{60} \left[ u_{z}^{-} - u_{i}^{-} - \left( R_{i} U_{i}^{-} + R_{z} U_{z}^{-} \right) v \right] \right]$
	$u_{1}^{+} = u_{2}^{-} - 2\left((u_{2}^{-}, v - u_{c}^{-}, v)v + \frac{m_{1}}{8}\left[u_{2}^{-} - u_{7}^{-} - (R_{1}U_{1}^{-} + R_{2}U_{2}^{-})v\right]\right)$
<u> </u>	
	$\begin{bmatrix} u_1 \end{bmatrix} = u_2 - R_2 U_2 V - \left( u_1 + R_1 U_1 V \right) = V_2(Q) - V_1(Q)$
,	
**************************************	
	12 1/2 to V
<del></del>	$\frac{U_1 - U_2 = U_1 - \frac{m_1 U_1 + m_2 U_2}{m}}{m}$
	$\frac{D_{1}m = 2 - 2 \cdot 3}{= \frac{m_{2}}{m} (u_{1} - u_{2})}$
	$u_2-u_1=-\frac{m_1}{m}(u_1-u_2)$
	Tro `

 $= C \int J = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ Dim 2  $c = \dot{\theta}$  $\dot{x} = \gamma Rc$ V(x) = U(x-a) + unetic energy  $K(U,u) = \frac{1}{2} \int |V(x)|^2 d\mu(x)$  area  $\frac{1}{2} \int \left( |U(x-a)|^2 + |u|^2 \right) P(x) dx \qquad body$   $\frac{1}{2} B \qquad |I|$  $c^2 \int |x-a|^2 f(x) dx + m|u|^2$  $= \frac{m}{2} \left( \frac{2\lambda c^2 + |\lambda|^2}{2} \right)$  $\frac{-m}{2}\left(\frac{\dot{s}^2 + |u|^2}{2}\right) = \frac{1}{2}m|v|^2$  $J = moment of inentia = R^2 V^2 c^2$ Two (disc) bodies N; = c; J -> v; t.e, = x, P; c;  $v_i^{\pm} = \left(v_i^{\pm}, e_i, u_i^{\pm}, e_2, u_i^{\pm}, e_3\right)$  $(\bigcup_{i} e_{3}) \cdot e_{i} = c_{i} (J_{V}) \cdot \overline{\iota} = c$ = - 8; R; C; / = - v; . e, v; R; v; R;  $T = e_2$   $TAV = e_1$ Y = e3  $||| = [\overline{u}_2 - \overline{u}_1 - (\beta_1 U_1 + \beta_2 U_2) V]$  $[n] \cdot e_3 = \overline{u_2} \cdot e_3 - \overline{u_1} \cdot e_3 = 0.$  $[m], e_1 = u_1 \cdot e_2 - u_1 \cdot e_2 - [(R_1U_1 + R_2U_2)v] \cdot e_1$ 

	["]·e2 = 12·e2 - 11·e2 + 11·e1 + 12·e1
	$\gamma_{_{i}}$ $\gamma_{_{2}}$
W-St 40-2-M-11-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-	$= v_2 \cdot e_2 - v_1 \cdot e_2 + v_1 \cdot e_1 + v_2 \cdot e_1$
~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~	$\gamma_1 \qquad \gamma_2$
······································	$[] \cdot e_3 = V_2 \cdot e_3 - V_1 \cdot e_3$
	- A (m not ) [ ]
	$U_i = U_i + 2(m-m_i) \vee_{\Lambda} [\dots]$
****	R; V; 2 @ 11
	e <sub>3</sub> ^ ([m]-e, e,)
	- [] - e, e, A e3 -
	$= U_{i}^{-} - 2(m-m_{i}) [m]^{-} e_{2} J$
$\overline{}$	R. 1/2 €
	$C_{1}^{+} = C_{1}^{-} - 2(m-m_{1}) [] \cdot e_{2}$
	$\mathbb{R}, \gamma^{2}_{i}$
	$\gamma_i R_i c_i^{\dagger} = \gamma_i R_i c_i^{\dagger} - 2(m-m_i) [m_i] \cdot e_i$
	Y. €
	$v_{i}^{+} \cdot e_{i} = v_{i}^{-} \cdot e_{i} - 2[m-m; (v_{2} \cdot e_{2} - v_{1} \cdot e_{3} + v_{1}^{-} \cdot e_{1} + v_{2}^{-} \cdot e_{1})$
	7: 8
	$u_{i}^{+} = u_{i}^{-} - 2 \left\{ \left( u_{i}^{-} \cdot e_{3} - u_{c}^{-} \cdot e_{3} \right) e_{3} + (-1)^{2} \left[ m - m_{i}^{-} \right] \right\}$
	$\bigoplus$
$\overline{}$	

ショルュ 2(m-m;) v. T. e. ~ 60 2 (-1) (m - m;) (4) (Vi. e3 - (m, Vi. e3 + m2 V2. e3) + (-1) (m-mi) (v\_: e3/- v\_: e, W 2 + m, (3) = m + v, .e, + 2m2 V. e, 2 m2 V. e, \_ 2m2 v3. e, 学图 对大团 2 m2 V, c 2 m2 1, e + 2 m2 v. e, + 2 m2 v. c. γ,⊛ 8,0 7+e3 === Vi.e. + 2 M2 V2.e3 1 - 2 M2 4/2 m2 12 - N. 1.63 (E) v, + e = V, " e, + 2m, V, " ez V2. e, - 2m v. e. 7,7,B + 2 m, V, Te, 7,3 2 M. Vicy V, . e, 2 m O

	$\otimes$ $m_1m_2$ $\lceil 1 (1+1) + 1 (1+1) \rceil$
	m, 72/ m2 12-1
	m,
	B M2 (1+1) + 1+1 1+Y22
	$m_1 \setminus Y_1^2 \setminus Y_2^2$
	$m_1 \rightarrow \infty$
	$\bigcirc \qquad \qquad \bigcirc \qquad \qquad \bigcirc \qquad$
with air the anti-size and a decision of the CETA CETA CETA CETA CETA CETA CETA CETA	
	In this case $(M, \to \infty)$ $V, + = V, - (set = 0)$
	$v_2^+, e_1 = 1 - 2 $ $v_2^-, e_1 - 2 $ $v_2^-, e_2$
	1 1+ Y2 1+ Y2 1 + Y2 1
	(amount of the contract of the
	2 ×2
whealth tills delenant soon the laterance advantage described in the 1800 870 to 1900 1900 1900 1900 1900 1900	1+7,2
	+ 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
	$v_{5}^{+}, e_{5} = -\frac{2}{3} \frac{\chi_{5}^{+}}{v_{2}^{-}, e_{1}} + \left[1 - 2 \frac{\chi_{5}^{+}}{1 + \chi_{2}^{2}}\right] \frac{v_{2}^{-}, e_{2}}{1 + \chi_{2}^{2}}$
	Company Comments of the Commen
	2 1/2
	1+1/2 1+1/2
	V, t. e. = + V, T. e.

Earl week " but make						,	
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$\begin{array}{c ccccccccccccccccccccccccccccccccccc$				$m_2$ $\begin{pmatrix} \chi_2^2 \end{pmatrix}$		de la companya de la	
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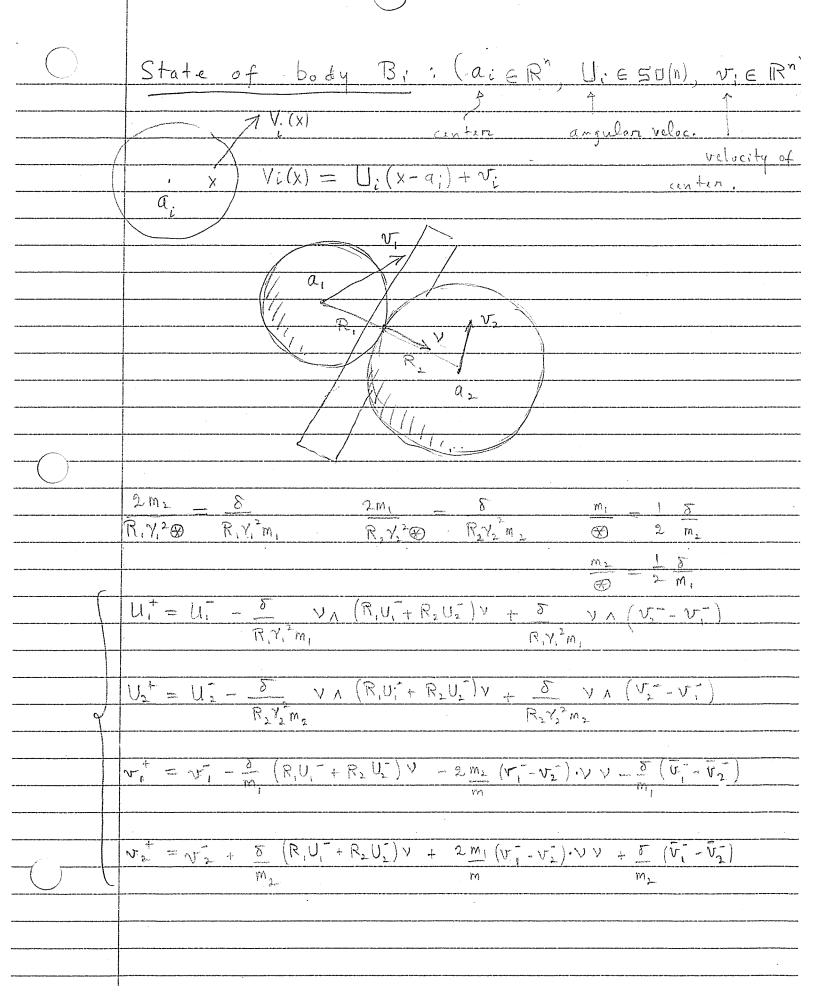
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	$\frac{V_{1}^{+} = U_{1}^{-} + \frac{\delta}{m_{1}R_{1}Y_{1}^{2}} \left(R_{1}\overline{U_{1}^{-}} + R_{2}\overline{U_{2}^{-}}\right) + \frac{\delta}{m_{1}R_{1}Y_{1}^{2}} e_{3} \times \left(\overline{V_{2}^{-}} - \overline{V_{1}^{-}}\right)}{m_{1}R_{1}Y_{1}^{2}}$
	$u_{3}^{+} = u_{2}^{-} + \frac{\delta}{m_{2}R_{2}Y_{2}^{2}} \left(R_{1}u_{1}^{-} + R_{3}u_{2}^{-}\right) + \frac{\delta}{m_{2}R_{2}Y_{3}^{2}} \epsilon_{3} \times \left(\overline{v_{3}^{-}} - \overline{v_{1}^{-}}\right)$
	$v_{i}^{+} = \frac{\delta}{m_{i}} e_{3} \times (P_{i} u_{i}^{-} + P_{2} u_{i}^{-}) + v_{i}^{-} - 2 \left\{ (v_{i}^{-} - v_{i}^{-}) \cdot e_{3} \cdot e_{3} \cdot \frac{\delta}{2m_{i}} (\overline{v_{i}^{-}} - \overline{v_{i}^{-}}) \right\}$
	$V_{2}^{\perp} = -\frac{\sigma}{m_{2}} \left( R_{1} u_{1}^{-} + R_{2} u_{2}^{-} \right) + V_{2}^{-} - 2 \left[ \left( V_{2}^{-} - V_{c}^{-} \right) \cdot e_{2} e_{2} - \frac{\sigma}{2 m_{2}} \left( V_{2}^{-} - V_{c}^{-} \right) \right]$
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	$-\frac{\delta}{\delta}\left(\overline{v_{1}}-\overline{v_{1}}\right)=\frac{\delta}{\delta}\left(\overline{v_{1}}-\overline{v_{2}}\right)$
	2 m, 2m, 0 1 0
es norma estados de es	$-\frac{\delta}{\sigma}(\bar{v},\bar{v}-\bar{v}-)=\frac{\delta}{\sigma}\left[\frac{1}{\sigma}(\bar{v},\bar{v}-\bar{v}-\bar{v})\right]$
	$\frac{2m_1}{2m_2} \qquad \frac{2m_2}{2m_2} \qquad 0 \qquad 0$
	$V_{1}^{-} - 2\left\{ \left(V_{1}^{-} - V_{2}^{-}\right) \cdot e_{3} e_{3} - \frac{\delta}{2m_{1}} \left(V_{2}^{-} - V_{1}^{-}\right) \right\}$
	2 M,
	5 m (15 - 17 - 1 2 - 1 3 )
	$= \sqrt{-2} \left\{ \frac{m_2}{m} \left( \sqrt{-\nu_2} \right) \cdot e_3 e_3 + \frac{\delta}{2m} \left( \sqrt{-\nu_2} \right) \right\}$
	$= \left( \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} - 2 M_2 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} - 5 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \right) \sqrt{1}$
	$\begin{bmatrix} 0 & 0 & 1 \end{bmatrix}$ $\begin{bmatrix} m & 0 & 0 & 1 \end{bmatrix}$ $\begin{bmatrix} m_1 & 0 & 0 & 0 \end{bmatrix}$
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	$\frac{1}{m} \left[ \frac{m}{0} \cdot \frac{m}{1} \cdot \frac{m}{0} \cdot \frac{m}{0} \cdot \frac{m}{1} \right]$
de tala de deputa persona any alamana garapa mandra di Banadania dan dan gan di	$\begin{bmatrix} 1 & \frac{1}{2} $
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	T1: R^-> V-
	Tonthogonal finalication
	$\Pi': \mathbb{R}^n \longrightarrow \mathbb{R}^{\vee}$
	$\Lambda': SO(n) \longrightarrow SO(n)$ $\Lambda'(U) = V \wedge U \vee$
	$\Lambda^{\circ}(U) = V \wedge U \rangle \qquad \Lambda^{\circ}(U)_{ij} = V_{i}(U \rangle)_{i} - V_{i}(U \rangle)_{j}$
	$\Gamma': SO(n) \rightarrow \mathbb{R}^n$ , $U \mapsto Uv$
	$E': \mathbb{R}^n \longrightarrow Sa(n)$ $E'(v) = v \wedge v$
	$U^{\dagger} = I - \frac{\varepsilon}{\kappa} \sqrt{U_{1}^{2} - \delta} = V_{1}^{2} - R_{2} \frac{\varepsilon}{\kappa} \sqrt{U_{2}^{2} - \delta} = \frac{\varepsilon^{2} v_{1}^{2}}{\kappa^{2} + \kappa^{2} + \kappa^{2}$
	$ \frac{\nabla_{+} = -R_{1} 5 \Gamma^{7} U_{1}}{m_{1}} + \left(\overline{1 - \frac{2m_{2}}{m}} \Gamma^{7} - \frac{5}{m_{1}} \Gamma^{7}\right) V_{1} - R_{2} 5 \Gamma^{7} U_{2}^{2} + \left(\frac{2m_{2}}{m} \Gamma^{7} + 5 \Gamma^{7}\right) V_{3}^{2}}{m_{1}} $
	K <sup>5</sup> W <sup>5</sup> X <sup>5</sup> W <sup>5</sup> K <sup>5</sup> X <sup>5</sup> W <sup>5</sup> W <sup>5</sup> X <sup>5</sup> X <sup>5</sup> X <sup>5</sup> W <sup>5</sup> W <sup>5</sup> X
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	R <sub>1</sub> 5 T <sup>V</sup>	2M1 TV + 5 TT m2	R25 (TV I	- 2mi   T - 5   T   m,
	$m_1 \rightarrow \infty$			
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