



Basic Techniques in Computer Graphics

Assignment 2

Date Published: October 31st 2022, Date Due: November 8th 2022, 10:15AM

- All assignments (programming and theory) have to be completed in teams of 3–4 students. Teams with fewer than 3 or more than 4 students will receive no points.
- Hand in one solution per team per assignment.
- Every team must work independently. Teams with identical solutions will receive no points.
- Solutions are due on November 8th 2022, 10:15AM via Moodle. Late submissions will receive zero points. No exceptions!
- Instructions for **programming assignments**:
 - Make sure you are part of a Moodle group with 3-4 members. See "Group Management" in the Moodle course room.
 - Download the solution template (a zip archive) through the Moodle course room.
 - Unzip the archive and populate the assignmentXX/MEMBERS.txt file. The names and student ids listed in this file **must match** your moodle group **exactly**.
 - Complete the solution.
 - Prepare a new zip archive containing your solution. It must contain exactly the files that you changed. **Only change the files you are explicitly asked to change in the task description.**The directory layout must be the same as in the archive you downloaded. (At the very least it must contain the assignmentXX/MEMBERS.txt.)
 - One team member uploads the zip archive through Moodle before the deadline, using the group submission feature.
 - Your solution must compile and run correctly on our lab computers by only inserting your assignment.cc and shader files into the Project. If it does not compile on our machines, you will receive no points. If in doubt you can test compilation in the virtual machine provided on our website.

• Instructions for **text assignments**:

- Prepare your solution as a single pdf file per group. Submissions on paper will not be accepted.
- If you write your solution by hand, write neatly! Anything we cannot decipher will receive zero points. No exceptions!
- Add the names and student ID numbers of all team members to every pdf.
- Unless explicitly asked otherwise, always justify your answer.
- Be concise!
- Submit your solution via Moodle, together with your coding submission.





Exercise 1 Linear Basis Transformations

[8 Points]

In the lecture you learned that points and vectors are always expressed with respect to a basis. In this task bases $\mathbf{B} = (\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3)$ with $\mathbf{b}_i \in \mathbb{R}^3$ and $\mathbf{C} = (\mathbf{c}_1, \mathbf{c}_2, \mathbf{c}_3)$ with $\mathbf{c}_i \in \mathbb{R}^3$ are given as 3-by-3 matrices.

(a) Change of Basis

[1 Points]

Give an expression for the matrix $\mathbf{M}_1 \in R^{3\times 3}$ that can be used to express a point $\mathbf{p}_B \in \mathbb{R}^3$ (represented in basis \mathbf{B}) with respect to basis \mathbf{C} , i.e. $\mathbf{p}_C = \mathbf{M}_1 \mathbf{p}_B$. Explain your answer in a few words.

(b) Transformation between Bases

[1 Points]

Give an expression for the matrix $M_2 \in \mathbb{R}^{3\times 3}$ that maps each basis vector of \mathbf{B} to the corresponding basis vector of \mathbf{C} .

(c) Inverse of an Orthonormal Matrix

[2 Points]

Assume that our bases are orthonormal, i.e. $\mathbf{b}_1 \perp \mathbf{b}_2$, $\mathbf{b}_1 \perp \mathbf{b}_3$, $\mathbf{b}_2 \perp \mathbf{b}_3$ and $||\mathbf{b}_1|| = ||\mathbf{b}_2|| = ||\mathbf{b}_3|| = 1$ (the same for \mathbf{C}). Show that $\mathbf{B}^\mathsf{T} = \mathbf{B}^{-1}$, where $\mathbf{B} = (\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3)$.

(d) Inverse of Rigid Linear Transformations

[2 Points]

Using your matrix M_2 derived in task (b), show that $M_2^T = M_2^{-1}$ when both **B** and **C** are orthonormal. Use the property shown in task (c).

(e) Change of Basis: Example

[2 Points]

Now assume the orthonormal bases B and C are given via

$$\mathbf{b}_{1} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{pmatrix}, \mathbf{b}_{2} = \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{pmatrix}, \mathbf{b}_{3} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix},$$

$$\mathbf{c}_{1} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \mathbf{c}_{2} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}, \mathbf{c}_{3} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}.$$

Express the point $\mathbf{p}_B = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{pmatrix}$ (given in basis **B**) in basis **C**.





Exercise 2 Meaningful Geometric Operations

[8 Points]

For any i, let \mathbf{p}_i be a **point** at location $\begin{pmatrix} x_i & y_i & z_i \end{pmatrix}^\mathsf{T}$. Use extended coordinates to explain whether each of the following operations yields either a **point**, a **vector**, or is **not geometrically meaningful** in general.

(a)
$$p_1 - 2p_2 + p_3$$
 [2 Points]

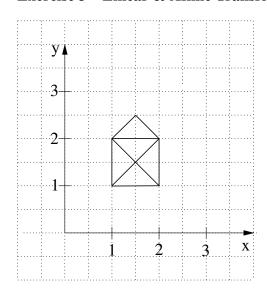
(b)
$$\mathbf{p}_0 + \sum_{i=1}^n (\mathbf{p}_i - \mathbf{p}_0)$$
 [2 Points]

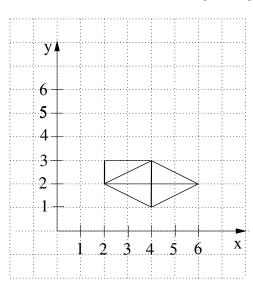
(c)
$$\alpha \mathbf{p}_0 + \beta \mathbf{p}_1$$
, with $\alpha, \beta \in \mathbb{R}$ [2 Points]

(d)
$$\alpha \mathbf{p}_0 + \beta \mathbf{p}_1 + (1 - \alpha - \beta) \mathbf{p}_2$$
, with $\alpha, \beta \in \mathbb{R}$ [2 Points]

Exercise 3 Linear & Affine Transformations

[8 Points]





(a) [6 Points]

Derive four transformation matrices (translation, rotation, scaling and translation) that together transform the house depicted in the left image to the house depicted in the right image. Also specify the final transformation matrix. Remember to use extended coordinates! By convention, points are multiplied from the right side!

Hint: Remember that $\sin 45^{\circ} = \cos 45^{\circ} = \sin 135^{\circ} = -\cos 135^{\circ} = \frac{1}{\sqrt{2}} = \frac{\sqrt{2}}{2}$.

(b) [2 Point]

Specify how the standard basis and the origin are transformed by this mapping.





Exercise 4 Programming: Transformations

[16 Points]

In this hands-on exercise, your task is to write a computer program simulating a simple 2D race track. We provide you with a function that draws a circle in a specified color. All you have to do is place differently transformed (and colored) versions of this circle into the scene.

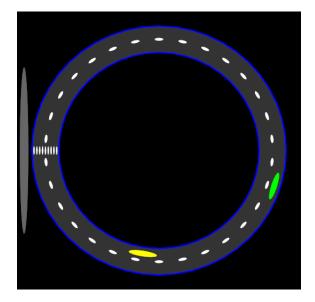
The draw routine is implemented in assignment.cpp. Only make modifications to that file! Do *not* modify any other file.

Each time the draw routine is called, you will have to compute the respective transformation matrices by hand (GLM does already offer function to create translation, rotation etc. matrices but you are not allowed to use them in this exercise. Instead, enter the values into the matrices yourself to show that you understood how they work. You can write your own helper functions for setting up different types of matrices. You can use the build-in matrix multiplications of GLM.). You can also use the matrix and vector classes from glm, e.g. glm::mat4 or glm::vec3 for colors.

The drawScene () routine gets two parameters, scene and runTime. You can neglect the first parameter as it is not used in this exercise. The second parameter holds the number of seconds passed since the first call (as floating point representation).

Notes:

- A non-transformed circle has a radius of 1.
- The local coordinate system is defined from -1 to 1.
- Transformations will be represented as 4-by-4 matrices in extended coordinates. For now, we are only interested in transformations within the x-y-plane, so the z-coordinate should stay untouched.
- GLM stores matrices in the *column-major* format. This means that the constructor glm::mat4(float x0,...float x15) uses the first four arguments x0,...x3 to build the first *column* of the matrix! This means that you either have to write down your matrices in a transposed form or call glm::transpose after construction.
- When b is pressed, the time passes faster, undo this by pressing a (useful for debugging).



(a) [4 Point]

Draw the track itself as a blue circle in which you draw a grey circle which is a little smaller, then another blue one and a black in the center to only let the outline of the blue one be visible.

The cars race clockwise.





(b) [2 Point]
Draw a stand for the spectators on the left of the track in grey.
(c) [4 Point]
Draw a start / finish line as nine white ellipses.
(d) [2 Point]
Add a white dotted line between the two lanes as ellipses.
(e) [4 Point]
Add the two race cars which race around the track. The outer car should be twice as fast as the inner car.