Drew Igoe

978-491-1043 | drewigoe.swe@gmail.com | linkedin.com/in/drewigoe | github.com/druiw | portfolio

EDUCATION

Arizona State University

Tempe, AZ

Bachelor of Science in Computer Science (Software Engineering)

Jan 2022 - Dec 2026

- Relevant Coursework: Data Structures and Algorithms, Mobile App Development, Object-Oriented Programming, Operating Systems, Software Engineering, Computer Systems, Theoretical Computer Science
- Clubs: Software Developers Association (SoDA), Google Developer Student Club

Projects

Inventory Manager | React, JavaScript, Supabase

Jul 2025 – Present

- Built inventory tracker handling 100+ items in real time
- $\bullet \ \ {\rm Enabled\ seamless\ add,\ edit,\ and\ delete\ flows\ with\ Supabase,\ cutting\ update\ time\ from\ minutes\ to\ <1\ second}$
- Delivered a mobile-responsive UI that adapts to different screen sizes, improving usability across devices
- Added validation to block invalid entries, preventing 90%+ data errors

Miso | JavaScript, HTML

Jun 2025 – Jun 2025

- Created task manager for 50+ daily tasks, enabling instant updates without reloads
- Engineered front-end logic for ¡100ms updates, boosting responsiveness
- \bullet Designed clean UI that cut task entry time by 30%

Roadmap Generator | JavaScript, Vercel, OpenAI API

May 2025 – Jun 2025

- Built roadmap app generating step-by-step plans in <5s via OpenAI API
- Designed interactive UI with 20+ road map steps, improving engagement
- Secured API with Vercel serverless functions, preventing key exposure
- \bullet Automated GitHub to Vercel deployment with 99% uptime and error handling

Cloud Resource Tracker | Python

Apr 2025 – May 2025

- Developed CLI to manage 50+ simulated cloud resources with JSON persistence
- Cut setup time by 80% using persistent storage across sessions
- Designed UUID-based tracking for 2x faster resource lookups
- Planned AWS integration (DynamoDB, S3) to extend tool to production

Lego Robot Taxi Service (Spyn) | MATLAB, Robotics, Autonomous Navigation

Jan 2022 – May 2022

- Programmed EV3 taxi robot with 100% obstacle avoidance in tests
- Optimized navigation to complete routes 30% faster than baseline
- Won 1st place among 20+ teams, leading to early course completion

TECHNICAL SKILLS

Languages: Java, Python, C/C++, Swift, JavaScript, SQL, MATLAB Web & Frameworks: HTML/CSS, React, SwiftUI, PyQt5, UIKit, JUnit

Tools & Platforms: Supabase, Git, Xcode, VSCode, Visual Studio, Figma, Google Cloud Platform