

## **APPENDIX-01**

### ***Turnitin Originality Report***

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Thesis Title: Multisensory Fusion For Underwater Robot Localization and Exploration

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Institution: University Of Gujrat Hafiz Hayat Campus

#### **PRIMARY SOURCES**

<b>SIMILARITY INDEX</b>	<b>INTERNET SOURCES</b>	<b>PUBLICATIONS</b>	<b>STUDENT PAPERS</b>
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<b>Internet Source</b>			<b>07%</b>
1. <a href="http://www.sajad-saeedi.ca">www.sajad-saeedi.ca</a>			
2. <a href="http://www.gel.usherbrooke.ca">www.gel.usherbrooke.ca</a>			
3. <a href="http://classic.austlii.edu.au">classic.austlii.edu.au</a>			
<b>Publications</b>			<b>02%</b>
1. Luo, Junhai, Ying Han, and Liying Fan. "Underwater acoustic target tracking: A review." <i>Sensors</i> 18, no. 1 (2018): 112.			
<b>Student Papers</b>			<b>05%</b>
1. Submitted to San Mateo Union High School District			
2. Submitted to University of Applied Sciences Berlin			
3. Submitted to University of Tasmania			