Half Title Page

Title Page

LOC Page

Vince: to Riggins

Geraint: also, to Riggins

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Foreword

This is the foreword

Preface

This is the preface.

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______ Getting Started

Introduction

HANK you for starting to read this book. This book aims to bring together two fascinating topics:

- Problems that can be solved using mathematics;
- Software that is free to use and change.

What we mean by both of those things will become clear through reading this chapter and the rest of the book.

1.1 WHO IS THIS BOOK FOR?

Anyone who is interested in using mathematics and computers to solve problems will hopefully find this book helpful.

If you are a student of a mathematical discipline, a graduate student of a subject like operational research, a hobbyist who enjoys solving the travelling salesman problem or even if you get paid to do this stuff: this book is for you. We will introduce you to the world of open source software that allows you to do all these things freely.

If you are a student learning to write code, a graduate student using databases for their research, an enthusiast who programmes applications to help coordinate the neighbourhood watch, or even if you get paid to write software: this book is for you. We will introduce you to a world of problems that can be solved using your skill sets.

It would be helpful for the reader of this book to:

- Have access to a computer and be able to connect to the internet (at least once) to be able to download the relevant software.
- Be prepared to read some mathematics. Technically you do not need to understand the specific mathematics to be able to use the tools in this book. The topics covered use some algebra, calculus and probability.

1.2 WHAT DO WE MEAN BY APPLIED MATHEMATICS?

We consider this book to be a book on applied mathematics. This is not however a universal term, for some applied mathematics is the study of mechanics and involves

modelling projectiles being fired out of canons. We will use the term a bit more freely here and mean any type of real world problem that can be tackled using mathematical tools. This is sometimes referred to as operational research, operations research, mathematical modelling or indeed just mathematics.

One of the authors, Vince, used mathematics to plan the sitting plan at his wedding. Using a particular area of mathematics call graph theory he was able to ensure that everyone sat next to someone they liked and/or knew.

The other author, Geraint, used mathematics to find the best team of Pokemon. Using an area of mathematics call linear programming which is based on linear algebra he was able to find the best makeup of pokemon.

Here, applied mathematics is the type of mathematics that helps us answer questions that the real world asks.

1.3 WHAT IS OPEN SOURCE SOFTWARE

Strictly speaking open source software is software with source code that anyone can read, modify and improve. In practice this means that you do not need to pay to use it which is often one of the first attractions. This financial aspect can also be one of the reasons that someone will not use a particular piece of software due to a confusion between cost and value: if something is free is it really going to be any good?

In practice open source software is used all of the world and powers some of the most important infrastructure around. For example, one should never use any cryptographic software that is not open source: if you cannot open up and read things than you should not trust it (this is indeed why most cryptographic systems used are open source).

Today, open source software is a lot more than a licensing agreement: it is a community of practice. Bugs are fixed faster, research is implemented immediately and knowledge is spread more widely thanks to open source software. Bugs are fixed faster because anyone can read and inspect the source code. Most open source software projects also have a clear mechanisms for communicating with the developers and even reviewing and accepting code contributions from the general public. Research is implemented immediately because when new algorithms are discovered they are often added directly to the software by the researchers who found them. This all contributes to the spread of knowledge: open source software is the modern should of giants that we all stand on.

Open source software is software that, like scientific knowledge is not restricted in its use.

1.4 HOW TO GET THE MOST OUT OF THIS BOOK

The book itself is open source. You can find the source files for this book online at github.com/drvinceknight/ampwoss. There will will also find a number of *Jupyter notebooks* and *R markdown files* that include code snippets that let you follow along.

We feel that you can choose to read the book from cover to cover, writing out

the code examples as you go; or it could also be used as a reference text when faced with particular problem and wanting to know where to start.

The book is made up of 10 chapters that are paired in two 4 parts. Each part corresponds to a particular area of mathematics, for example "Emergent Behaviour". Two chapters are paired together for each chapter, usually these two chapters correspond to the same area of mathematics but from a slightly different scale that correspond to different ways of tackling the problem.

Every chapter has the following structure:

- 1. Introduction a brief overview of a given problem type. Here we will describe the problem at hand in general terms.
- 2. An Example problem. This will provide a tangible example problem that offers the reader some intuition for the rest of the discussion.
- 3. Solving with Python. We will describe the mathematical tools available to us in a programming language called Python to solve the problem.
- 4. Solving with R. Here we will do the same with the R programming language.
- 5. Brief theoretic background with pointers to reference texts. Some readers might like to delve in to the mathematics of the problem a bit further, we will include those details here.
- 6. Examples of research using these methods. Finally, some readers might even be interested in finding out a bit more of what mathematicians are doing on these problems. Often this will include some descriptions of the problem considered but perhaps at a much larger scale than the one presented in the example.

For a given reader, not all sections of a chapter will be of interest. Perhaps a reader is only interested in R and finding out more about the research. Please do take from the book what you find useful.

		_

Software

This book will involve using software, the particular interface to software we will use is to write code. There are numerous reasons why this is the correct way to do things but one of them is reproducibility.

This chapter will go over the basics of getting your computer set up to use the software discussed in this book: the programming languages R and Python. It will also briefly discuss using the command line: a particular interface to your whole computer. Finally it will give a brief introduction to R and Python.

This chapter (and indeed this whole book) is not a place to learn R and Python completely. We will cover specific tasks and how to carry them out in each language, but we will not cover the every intricacy of each language. There are numerous sources (books, websites, courses) that are available to do that. A lot of these places would argue that you should not learn multiple programming languages from one book, and instead concentrate on a single skill at a time. We agree, and the single skill to concentrate on with this book is the use of software to solve applied mathematical problems. The particular software itself is not the most important component.

2.1 SOFTWARE INSTALLATION

There are a number of different places from which you can buy your vegetables, you can grow them yourself, you can go to a market and pick fresh fruit from specific stalls, you can go to a supermarket and buy a bag of a collection of vegetables and in some places you can even get a box of vegetables regularly posted to you. Software is similar, there are a variety of places from which you can get it and a number of different forms in which it can be obtained.

If you're comfortable with using R and Python then you probably do not need to read this section and you might even use different so called "distributions" of each piece of software, but for the purpose of this book here is where we will be getting what we need:

- Python: we will use the Anaconda distribution: https://www.anaconda.com/distribution/
- R: we will be getting this directly from the Comprehensive R Archive Network (commonly referred to as CRAN): https://cran.r-project.org. We will also use another piece of software called Rstudio: https://rstudio.com.

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2.1.1 Installing Python

Installing Python and all the software we need around it is done by downloading and running the installer for the Anaconda distribution.

- 1. Go to this webpage: https://www.anaconda.com/download/.
- 2. Identify and download the version of Python 3 for your operating system (Windows, Mac OSX, Linux). Run the installer.

2.1.2 Installing R

There are actually two pieces of software we need to install to use R for the purposes of this book, first the R language itself and second an application with which we will write R code.

- 1. Go to this webpage: https://cran.r-project.org.
- 2. Identify and download the latest version of R for your operating system (Windows, Mac OSX, Linux). Run the installer.
- 3. Go to this webpage: https://rstudio.com.
- 4. Identify and download the latest version of Rstudio for your operating system (Windows, Mac OSX, Linux). Run the installer.

2.2 USING THE COMMAND LINE

There are various interfaces to using a computer, the most common one is to use a mouse and keyboard and click on programmes we want to use. Another approach is to use what is called a command line interface this is where we do not interact graphically with a computer but we type in specific commands.

We can use our command line to navigate the various directories on our computer. There are two types of operating systems that we consider here:

- Windows
- Nix: this includes OSX (the Mac operating system) and Linux

Not all commands are the same on each type of operating system. So let us start by opening our command line interface:

- Windows: after having installed Anaconda look to open the Anaconda Prompt.
 There are a number of other command line interfaces available but this is the one we recommend for the purposes of this book.
- Nix: look to open the Terminal.

This should open something that looks like and somewhat resembles a black box with some text in it. This is where we will write our commands to the computer.

For example to list the contents of the directory we are currently in:

On nix:

	Cli input
	ls
•	15
	On Windows
	Cli input
	CII Input
:	dir
	It is also possible to get the page of the directory we are suggested in
	It is also possible to get the name of the directory we are currently in:
	On nix:
	Cli input
3	pwd
_	
	On Windows
	On windows
	Cli input
	cd
_	
	Finally we can also use the command line to move to another directory. The
C	command for this are the same on Nix and on Windows.
	minume for this are the same on this and on willdows.
	Cli input
	-

The command line is an important tool to learn to use when doing tasks:

cd <name_of_subdirectory>

• If we want to scale the tasks, a commonly heard phrase is that 'mouse clicks do not scale' highlighting that to repeat a task many times when using a graphical interface is inefficient.

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• If we want someone else to be able to repeat the tasks, we can use screenshots of graphical interfaces but there will always be a level of ambiguity whereas the commands used in the command line are precise.

We can use our two programming languages right within the command line interface (we will actually be using a different tool that we will describe shortly).

To use Python, simply type the following and press Enter:

```
Cli input _______
```

This should make something like the following appear:

```
Python 3.7.1 | packaged by conda-forge | (default, Nov 13 2018, 10:30:07)

[Clang 4.0.1 (tags/RELEASE_401/final)] :: Anaconda, Inc. on darwin

Type "help", "copyright", "credits" or "license" for more information.

>>>
```

The >>> is a prompt ready to accept a Python command. Let us start with the following:

```
Python input >>> 2 + 2
```

When you press Enter, this will give:

```
Python output

4
```

This particular way of using Python is called a REPL which stands for: 'Read Eval Print Loop' which indicates that it takes a command, evaluates it and waits for the next one.

To quit Python's REPL type the following (note that (), more about that later):

```
Python input

>>> quit()
```

We can do the same for R. To start R's REPL, in your command line type the following and press Enter:

```
Cli input

R
```

This should make something like the following appear:

```
_____ Cli output _____
    R version 3.5.1 (2018-07-02) -- "Feather Spray"
15
    Copyright (C) 2018 The R Foundation for Statistical Computing
16
    Platform: x86_64-apple-darwin13.4.0 (64-bit)
17
18
    R is free software and comes with ABSOLUTELY NO WARRANTY.
19
    You are welcome to redistribute it under certain conditions.
20
    Type 'license()' or 'licence()' for distribution details.
21
22
      Natural language support but running in an English locale
23
24
    R is a collaborative project with many contributors.
25
    Type 'contributors()' for more information and
26
    'citation()' on how to cite R or R packages in publications.
27
28
    Type 'demo()' for some demos, 'help()' for on-line help, or
29
    'help.start()' for an HTML browser interface to help.
30
    Type 'q()' to quit R.
31
32
33
```

The > is a prompt ready to accept an R command. Let us start with the following:

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		R input
34	> 2 + 2	
34	7 2 1 2	

When you press Enter, this will give:

```
R output

4
```

To quit R's REPL type the following:

```
R input > q()
```

This will bring up a further prompt asking you to save some information about what you just did. You can type n for now:

```
R input

> Save workspace image? [y/n/c]: n
```

These two REPLs are not unique and also not the most efficient way of using the languages, however they can at times be useful if you just want to type a very short command or perhaps check something quickly.

Another approach is to save a collection of commands in a plain text file and pass it to the interpreter at the command line.

For example, if we had a number of Python commands in main.py we could run this at the command line using:

```
Cli input

python main.py
```

Similarly for a file with a number of R commands main.R:

Cli input

Rscript main.R

These are just a few of many ways to use Python and R. An important notion to understand is that Python and R are not the particular tools that we use to interface to them. On a day to day basis the authors of this book will use both of the above approaches as well as the next ones, we recommend readers take time to experiment and understand the particular use cases for which each tool works best for them.

The two tools we recommend to use in this book are:

- For Python: the Jupyter notebook, a tool that behaves similarly to a REPL, runs in the web browser and is very popular in research.
- For R: RStudio, an integrated development environment with a lot of helpful features.

The best way to start the Jupyter notebook is to type the following in your command line:

Jupyter notebook

This will create a *notebook server* that runs on your computer and should open a page that looks like Note that despite running in a web browser this does not need the internet to run.

We can create a new notebook and write and run code in the cells.

To start Rstudio, locate the application on your computer and double click on it. This will open an application that looks like

Rstudio includes its on REPL, so we can type and run single commands there but we can also write in a file that we can run

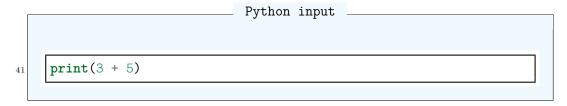
In the next sections we will cover some basics of Python and R.

2.3 BASIC PYTHON

This section gives a very brief overview of some introductory aspects of Python, there are excellent resources available for learning Python and we recommend the reader goes there if they feel they need an in depth understanding of the language

In the previous section, we saw how to get Python to perform a single calculation:

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which will give:

```
Python output

8
```

We can also assign values to a variable:

```
Python input

a = 3
b = 5
c = a + b
print(c)
```

This makes a point at 3 etc...

which will give:

```
Python output

8
```

There are a number of different types of variables in Python, here is a very brief list of some of them:

- Integers int for example 2, 4, -459060.
- Floats float for example 2.0, 3.4, -3.459060.
- Strings str for example "two", "hello world", "3450".
- Booleans bool for example True or False.

Based on the values of a variable it is possible to construct Booleans:

```
Python input

is_a_larger_than_b = a > b
```

The variable is_a_larger_than_b will be the boolean variable False.

This is an important concept as boolean variable allow us to use conditional statements that let us write code that does specific things based on the value of variables. For example the following code will add 5 to the smallest variable:

```
Python input
     a = 3
49
     b = 5
50
     if a < b:
51
         a = a + 3
52
     elif a > b:
53
         b = b + 5
54
     else:
55
          a = a + 3
56
         b = b + 3
57
     print(a, b)
58
```

which gives:

```
Python output

6 5
```

If you are experimenting by typing the code as you go change the value of a or b to see how the behaviour changes. What happens if they are equal?

It is also possible to use these conditional statements to repeat code. For example the following code will repeatedly add 1 to the smallest variable until it becomes equal to the largest one:

```
Python input

a = 3
b = 5
while a != b:
    if a < b:
        a = a + 1
else:
    b = b + 1
```

It is important to be able to reuse code, this is done using a programming concept called a *function*, which acts similarly to a mathematical function.

The following code, creates a function that takes two variables as input and outputs the largest number and the smallest increased by 3.

```
def add_3_to_smallest(a, b):

"""This function adds 3 to the smallest of a or b."""

if a < b:

return a + 3, b

return a, b + 3
```

Once we have defined the function, the following is how we use it:

```
Python input

print(add_3_to_smallest(a=5, b=-42))
```

which gives:

```
Python output

(5, -39)
```

Python has a type of variable that is in fact a collection of pointers to other variables. This is called a list. Here for example is a collection of strings:

```
Python input

tennis_players = [
    "Federer",
    "S. Williams",
    "V. Williams",
    "King",
]
```

There are a number of things that can be done with lists but one particular aspect is that they are a sub type of something called an iterable in Python which means we can iterate over them. We do this in Python using a **for** loop. For example, the following code will iterate over the list and print all the values:

```
Python input

for name in tennis_players:
    print(name)
```

which gives:

```
Python output

Federer
S. Williams
V. Williams
King
```

We will often want to iterate over a set of integers, Python has a range command that can create such a set with ease. The following code will print every 3 integers from 30 to 50:

```
Python input

for integer in range(30, 50, 3):
    print(integer)
```

which will give:

```
Python output

30
33
36
91
92
42
45
48
```

A final important aspect of Python is that of libraries. The code examples above are from the so called 'standard library' but Python has numerous libraries specific to given problems. A lot of these libraries came bundled with the anaconda distribution but if you want to download one that is not you can always do so as long as you have an internet connection.

For example, to download a library for studying queueing systems ciw open your command line interface and type the following:

```
95 pip install ciw
```

Once you restart your python interpreter, for example if you are using a Jupyter notebook then restart the Kernel, you can then run the following to make ciw available to you:

```
Python input

import ciw
```

2.4 BASIC R

This section gives a very brief overview of some introductory aspects of R, there are excellent resources available for learning R [1] and we recommend the reader goes there if they feel they need an in depth understanding of the language

In the previous section, we saw how to get R to perform a single calculation:

```
Print(3 + 5)
```

which will give:

We can also assign values to a variable:

```
R input

a <- 3
b <- 5
c <- a + b
print(c)
```

which will give:

An important difference between R and Python is that in R the base structure is in fact a vector, even if it only contains a single variable. We can use the ${\tt c}$ command to concatenate these base structures together:

```
R input

print(c(a, 4))
```

giving:

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```
R output

[1] 3 4
```

There are a number of different types of variables in R, here is a very brief list of some of them:

- Integers integer for example 2, 4, -459060.
- Floats double for example 2.0, 3.4, -3.459060.
- Strings character for example "two", "hello world", "3450".
- Booleans logical for example TRUE or FALSE.

Based on the values of a variable it is possible to construct Booleans:

```
R input

[is_a_larger_than_b <- a > b]
```

The variable is a larger than b will be the boolean variable FALSE.

This is an important concept as boolean variable allow us to use conditional statements that let us write code that does specific things based on the value of variables. For example the following code will add 5 to the smallest variable:

```
R input
      a <- 3
107
      b <- 5
108
      if (a < b) {
109
        a < -a + 3
110
      } else if (a > b) {
111
        b < -b + 3
112
      } else {
113
        a < -a + 3
114
        b < -b + 3
115
116
      print(c(a, b))
117
```

which gives:

If you are experimenting by typing the code as you go, change the value of a or b to see how the behaviour changes. What happens if they are equal?

R is a so called "vectorized" language which means that there is often a more appropriate approach to doing things repeatedly using vectors. This applies to the if statement in that there exists a ifelse statement that applies to vectors of booleans. For example:

```
R input

booleans <- c(FALSE, TRUE, FALSE, FALSE)

print(ifelse(booleans, "cat", "dog"))
```

which gives:

```
R output

[1] "dog" "cat" "dog" "dog"
```

It is also possible to use conditional statements to repeat code. For example the following code will repeatedly add 1 to the smallest variable until it becomes equal to the largest one:

```
_____ R input _
      a <- 3
122
      b <- 5
123
      while (a != b) {
124
        if (a < b) {
125
          a < -a + 1
126
        }
127
        else {
128
          b < -b + 1
129
        }
130
131
```

It is important to be able to reuse code, this is done using a programming concept called a *function*, which acts similarly to a mathematical function.

The following code creates a function that takes two variables as input and outputs the largest number and the smallest increased by 3.

```
R input
     add 3 to smallest <- function(a, b) {
132
        # This function adds 3 to the smallest of a or b.
133
        if (a < b) {
134
          return(c(a + 3, b))
135
        }
136
        else {
137
          return(c(a, b + 3))
138
139
140
```

Note that R will implicitly return the last computed expression without the need for a return statement. So the above can also be written as:

```
R input
      add 3 to smallest <- function(a, b) {
141
        # This function adds 3 to the smallest of a or b.
142
        if (a < b) {
143
          c(a + 3, b)
144
        }
145
        else {
146
          c(a, b + 3)
147
        }
148
149
```

Once we have defined the function, the following is how we use it:

```
R input

print(add_3_to_smallest(a = 5, b = -42))
```

which gives:

```
R output

[1] 5 -39
```

It is possible to iterate over elements inside R vectors:

```
tennis_players <- c("Federer",
"S. Williams",
"V. Williams",
"King")
```

The following will print all the names contained in the vector:

```
for (name in tennis_players) {
    print(name)
}
```

which gives:

```
R output

[1] "Federer"
[1] "S. Williams"
[1] "V. Williams"
[1] "King"
```

We will often want to iterate over a vector of integers, R has a seq command that can create such a vector with ease. The following code will print every 3 integers from 30 to 50:

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```
R input

for (i in seq(30, 50, 3)) {
 print(i)
}
```

which will give:

```
R output

[1] 30
[1] 33
[1] 36
[1] 39
[1] 42
[1] 45
[1] 45
[1] 48
```

A final important aspect of R is that of packages. The code examples above are from the so called 'base R' but R has numerous packages specific to given problems. If you want to download and use one you can always do so as long as you have an internet connection.

For example, to download a very common collection of data science tools called tidyverse we use the following line of code inside of an R session:

```
R input

install.packages("simmer")
```

Once this package is installed it is loaded using

```
R input

library(simmer)
```

2.5 A NOTE ON HOW CODE IS DISPLAYED IN THIS BOOK

FURTHER READING

- Becskei, A. and Serrano, L. (2000). Engineering stability in gene networks by autoregulation. *Nature*, 405: 590–593.
- Rosenfeld, N., Elowitz, M.B., and Alon, U. (2002). Negative auto-regulation speeds the response time of transcription networks. *J. Mol. Biol.*, 323: 785–793.
- Savageau, M.A. (1976). Biochemical Systems Analysis: A study of Function and Design in Molecular Biology. Addison-Wesley. Chap. 16.
- Savageau, M.A. (1974). Comparison of classical and auto-genous systems of regulation in inducible operons. *Nature*, 252: 546–549.

Probabilistic Modelling

Markov Chains

Many real world situations have some level of unpredictability through randomness: the flip of a coin, the number of orders of coffee in a shop, the winning numbers of the lottery. However, mathematics can in fact let us make predictions about what we expect to happen. One tool used to understand randomness is Markov chains, an area of mathematics sitting at the intersection of probability and linear algebra.

3.1 PROBLEM

Consider a barber shop. The shop owners have noticed that customers will not wait if there is no room in their waiting room and will choose to take their business elsewhere. The Barber shop would like to make an investment so as to avoid this situation. They know the following information:

- They currently have 2 barber chairs (and 2 barbers).
- They have waiting room for 4 people.
- They usually have 10 customers arrive per hour.
- Each Barber takes about 15 minutes to serve a customer so they can serve 4 customers an hour.

This is represented diagrammatically in Figure 3.1.

They are planning on reconfiguring space to either have 2 extra waiting chairs or another barber's chair and barber.

The mathematical tool used to model this situation is a Markov chain.

3.2 THEORY

A Markov chain is a model of a sequence of random events that is defined by a collection of **states** and rules that define how to move between these states.

For example, in the barber shop a single number is sufficient to describe the status of the shop. If that number is 1 this implies that 1 customer is currently having their

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Figure 3.1 Diagrammatic representation of the barber shop as a queuing system.

hair cut. If that number is 5 this implies that 2 customers are being served and 3 are waiting. The entire state space is, in this case a finite set of integers from 0 to 6. If the system is full (all barbers and waiting room occupied) then we are in state 6 and if there is no one at the shop then we are in state 0. This is denoted mathematically as:

$$S = \{0, 1, 2, 3, 4, 5, 6\} \tag{3.1}$$

As customers arrive and leave the system goes between states as shown in Figure 3.2.

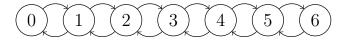


Figure 3.2 Diagrammatic representation of the state space

The rules that govern how to move between these states can be defined in two ways:

- Using probabilities of changing state (or not) in a well defined time period. This is called a discrete Markov chain.
- Using rates of change from one state to another. This is called a continuous time Markov chain.

For our barber shop we will consider it as a continuous Markov chain as shown in Figure 3.3

Note that a Markov chain assumes the rates follow an exponential distribution. One interesting property of this distribution is that it is considered memoryless which means that if a customer has been having their hair cut for 5 minutes this does not change the rate at which their service ends. This distribution is quite common in the real world and therefore a common assumption.

These states and rates can be represented mathematically using a transition matrix Q where Q_{ij} represents the rate of going from state i to state j. In this case we have:

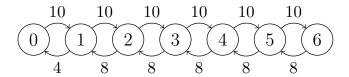


Figure 3.3 Diagrammatic representation of the state space and the transition rates

$$Q = \begin{pmatrix} -10 & 10 & 0 & 0 & 0 & 0 & 0 \\ 4 & -14 & 10 & 0 & 0 & 0 & 0 \\ 0 & 8 & -18 & 10 & 0 & 0 & 0 \\ 0 & 0 & 8 & -18 & 10 & 0 & 0 \\ 0 & 0 & 0 & 8 & -18 & 10 & 0 \\ 0 & 0 & 0 & 0 & 8 & -18 & 10 \\ 0 & 0 & 0 & 0 & 0 & 8 & -8 \end{pmatrix}$$
(3.2)

You will see that Q_{ii} are negative and ensure the rows of Q sum to 0. This gives the total rate of change leaving state i.

We can use Q to understand the probability of being in a given state after t time unis. This is can be represented mathematically using a matrix P_t where $(P_t)_{ij}$ is the probability of being in state j after t time units having started in state i. We can use Q to calculate P_t using the matrix exponential:

$$P_t = e^{Qt} (3.3)$$

What is also useful is understanding the long run behaviour of the system. This allows us to answer questions such as "what state are we most likely to be in on average?" or "what is the probability of being in the last state on average?".

This long run probability distribution over the state can be represented using a vector π where π_i represents the probability of being in state i. This vector is in fact the solution to the following matrix equation:

$$\pi Q = 0 \tag{3.4}$$

In the upcoming sections we will demonstrate all of the above concepts.

3.3 SOLVING WITH PYTHON

The first step we will take is to write a function to obtain the transition rates between two given states:

```
Python input
     def get_transition_rate(
175
          in_state, out_state, waiting_room=4, num_barbers=2,
176
     ):
177
          """Return the transition rate for two given states.
178
179
          Args:
180
              in_state: an integer
181
              out_state: an integer
182
              waiting_room: an integer (default: 4)
183
              num_barbers: an integer (default: 2)
184
          Returns:
186
              A real.
187
188
          arrival_rate = 10
189
          service_rate = 4
190
191
          capacity = waiting_room + num_barbers
192
          delta = out_state - in_state
193
194
          if delta == 1 and in_state < capacity:</pre>
195
              return arrival rate
196
197
          if delta == -1:
198
              return min(in_state, num_barbers) * service_rate
199
200
          return 0
201
```

Next, we write a function that creates an entire transition rate matrix Q for a given problem. We will use the numpy to handle all the linear algebra and the itertools library for some iterations:

```
import itertools
202
      import numpy as np
203
204
205
      def get_transition_rate_matrix(waiting_room=4, num_barbers=2):
206
          """Return the transition matrix Q.
207
208
          Args:
209
              waiting_room: an integer (default: 4)
210
              num_barbers: an integer (default: 2)
211
212
          Returns:
213
              A matrix.
214
215
          capacity = waiting_room + num_barbers
216
          state_pairs = itertools.product(
217
              range(capacity + 1), repeat=2
218
          )
219
220
          flat_transition_rates = [
221
              get_transition_rate(
222
                   in_state=in_state,
223
                   out_state=out_state,
224
                   waiting room=waiting room,
225
                   num_barbers=num_barbers,
226
227
              for in state, out state in state pairs
228
          ]
229
          transition_rates = np.reshape(
230
              flat_transition_rates, (capacity + 1, capacity + 1)
231
232
          np.fill_diagonal(
233
              transition_rates, -transition_rates.sum(axis=1)
234
235
236
          return transition_rates
237
```

Using this we can obtain the matrix Q for our default system:

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```
Python input

Q = get_transition_rate_matrix()
print(Q)
```

which gives:

```
Python output
      [[-10
              10
                                       0]
240
          4 - 14
                   10
                         0
                                       0]
                             0
241
               8 -18 10
                                       0]
                             0
                                  0
242
                                       0]
               0
                    8 -18
                            10
                                  0
243
                         8 -18
                                10
                                       0]
               0
                    0
244
                                     10
                             8 -18
          0
               0
                    0
                         0
245
               0
                         0
                                  8
                                     -8]]
                             0
246
```

We can take the matrix exponential as discussed above. To do this, we need to use the scipy library. To see what would happen after .5 time units we obtain:

```
Python input

import scipy.linalg

print(scipy.linalg.expm(Q * 0.5).round(5))
```

which gives:

```
Python output

[[0.10492 0.21254 0.20377 0.17142 0.13021 0.09564 0.0815 ]
[0.08501 0.18292 0.18666 0.1708 0.14377 0.1189 0.11194]
[0.06521 0.14933 0.16338 0.16478 0.15633 0.14751 0.15346]
[0.04388 0.10931 0.13183 0.15181 0.16777 0.18398 0.21142]
[0.02667 0.07361 0.10005 0.13422 0.17393 0.2189 0.27262]
[0.01567 0.0487 0.07552 0.11775 0.17512 0.24484 0.32239]
[0.01068 0.03668 0.06286 0.10824 0.17448 0.25791 0.34914]]
```

To see what would happen after 500 time units we obtain:

```
Python input

print(scipy.linalg.expm(Q * 500).round(5))
```

which gives:

```
Python output
     [[0.03431 0.08577 0.10722 0.13402 0.16752 0.2094
                                                          0.26176]
258
      [0.03431 0.08577 0.10722 0.13402 0.16752 0.2094
                                                          0.26176]
259
      [0.03431 0.08577 0.10722 0.13402 0.16752 0.2094
                                                          0.26176]
260
      [0.03431 0.08577 0.10722 0.13402 0.16752 0.2094
                                                          0.26176]
261
      [0.03431 0.08577 0.10722 0.13402 0.16752 0.2094
                                                          0.26176]
262
      [0.03431 0.08577 0.10722 0.13402 0.16752 0.2094
                                                          0.26176]
263
      [0.03431 0.08577 0.10722 0.13402 0.16752 0.2094
                                                          0.26176]]
264
```

We see that no matter what state (row) the system is in, after 500 time units the probabilities are all the same. We could in fact stop our analysis here, however our choice of 500 time units was arbitrary and might not be the correct amount for all possible scenarios, as such we will continue to aim to solve the underlying equation 3.4 directly.

To do this we will solve the underlying system using a numerically efficient algorithm called least squares optimisation (available from the numpy library):

```
Python input
     def get_steady_state_vector(Q):
265
          """Return the steady state vector of any given continuous
266
          time transition rate matrix.
267
268
          Arqs:
269
             Q: a transition rate matrix
270
271
          Returns:
272
              A vector
273
274
         state space size, = Q.shape
275
         A = np.vstack((Q.T, np.ones(state_space_size)))
276
         b = np.append(np.zeros(state_space_size), 1)
277
         x, _, _, = np.linalg.lstsq(A, b, rcond=None)
278
          return x
279
```

So if we now see the steady state vector for our default system:

```
Python input

print(get_steady_state_vector(Q).round(5))
```

we get:

```
Python output

[0.03431 0.08577 0.10722 0.13402 0.16752 0.2094 0.26176]
```

We can see that the shop is expected to be empty approximately 3.4% of the time and full 26.2% of the time.

The final function we will write is one that uses all of the above to just return the probability of the shop being full.

```
Python input _____
     def get_probability_of_full_shop(
282
          waiting_room=4, num_barbers=2
283
     ):
284
          """Return the probability of the barber shop being full.
285
286
          Args:
287
              waiting_room: an integer (default: 4)
288
              num_barbers: an integer (default: 2)
289
290
          Returns:
291
              A real.
292
293
          Q = get_transition_rate_matrix(
294
              waiting_room=waiting_room, num_barbers=num_barbers,
295
296
         pi = get_steady_state_vector(Q)
297
         return pi[-1]
298
```

We can now confirm the previous probability calculated probability of the shop being full:

```
Python input

print(round(get_probability_of_full_shop(), 6))
```

which gives:

```
Python output

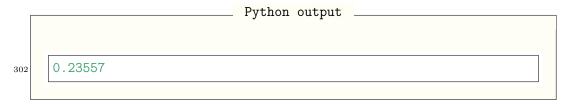
0.261756
```

If we were too have 2 extra space in the waiting room:

```
Python input

print(round(get_probability_of_full_shop(waiting_room=6), 6))
```

which gives:



This is a slight improvement however, increasing the number of barbers has a substantial effect:

```
Python input

print(round(get_probability_of_full_shop(num_barbers=3), 6))
```

```
Python output

0.078636
```

3.4 SOLVING WITH R

The first step we will take is write a function to obtain the transition rates between two given states:

```
R input
      #' Return the transition rate for two given states.
305
      # '
306
      #' @param in_state an integer
307
      #' @param out_state an integer
308
      #' @param waiting_room an integer (default: 4)
309
      #' @param num_barbers an integer (default: 2)
310
311
      #' @return A real
312
      get_transition_rate <- function(in state,</pre>
313
                                          out_state,
314
                                          waiting_room = 4,
315
                                          num_barbers = 2){
316
        arrival_rate <- 10
317
        service_rate <- 4
318
319
        capacity <- waiting_room + num_barbers</pre>
320
        delta <- out_state - in_state</pre>
321
322
        if (delta == 1) {
323
          if (in state < capacity) {</pre>
324
            return(arrival_rate)
325
          }
326
        }
327
328
        if (delta == -1) {
329
          return(min(in state, num barbers) * service rate)
330
331
        return(0)
332
333
```

We will not actually use this function but a vectorized version of this:

```
vectorized_get_transition_rate <- Vectorize(
   get_transition_rate,
   vectorize.args = c("in_state", "out_state")
)</pre>
```

This function can now take a vector of inputs for the in_state and out_state variables which will allow us to simplify the following code that creates the matrices:

```
R input
         Return the transition rate matrix Q
338
339
      #' @param waiting_room an integer (default: 4)
340
      #' @param num_barbers an integer (default: 2)
341
342
      #' @return A matrix
343
      get_transition_rate_matrix <- function(waiting_room = 4,</pre>
344
                                                  num_barbers = 2){
345
        max_state <- waiting_room + num_barbers</pre>
346
347
        Q <- outer(0:max_state,</pre>
348
          0:max_state,
349
          vectorized_get_transition_rate,
350
          waiting_room = waiting_room,
351
          num_barbers = num_barbers
352
353
        row_sums <- rowSums(Q)</pre>
354
355
        diag(Q) <- -row sums
356
357
      }
358
```

Using this we can obtain the matrix Q for our default system:

```
R input

Q <- get_transition_rate_matrix()
print(Q)
```

which gives:

```
R output
                   [,2] [,3] [,4] [,5]
                                              [,6]
361
       [1,]
              -10
                      10
                              0
                                     0
                                            0
                                                  0
362
       [2,]
                 4
                     -14
                             10
                                     0
                                           0
                                                  0
                                                         0
363
       [3,]
                        8
                            -18
                                   10
                 0
                                           0
                                                  0
                                                         0
364
       [4,]
                              8
                                  -18
                 0
                        0
                                          10
                                                  0
                                                         0
365
       [5,]
                 0
                        0
                              0
                                     8
                                         -18
                                                 10
                                                         0
366
       [6,]
                        0
                              0
                                     0
                                           8
                                                -18
                 0
                                                       10
367
       [7,]
                                           0
                                                       -8
368
                        0
                              0
                                     0
                                                  8
```

One immediate thing we can do with this matrix is take the matrix exponential discussed above. To do this, we need to use an R library call expm.

To be able to make use of the nice %>% "pipe" operator we are also going to load the magrittr library. Now if we wanted to see what would happen after .5 time units we obtain:

```
R input

library(expm, warn.conflicts = FALSE, quietly = TRUE)
library(magrittr, warn.conflicts = FALSE, quietly = TRUE)

print( (Q * .5) %>% expm %>% round(5))
```

which gives:

```
R output
              [,1]
                      [,2]
                               [,3]
                                       [,4]
                                                [,5]
373
     [1,] 0.10492 0.21254 0.20377 0.17142 0.13021 0.09564 0.08150
374
     [2,] 0.08501 0.18292 0.18666 0.17080 0.14377 0.11890 0.11194
375
     [3,] 0.06521 0.14933 0.16338 0.16478 0.15633 0.14751 0.15346
376
     [4,] 0.04388 0.10931 0.13183 0.15181 0.16777 0.18398 0.21142
377
     [5,] 0.02667 0.07361 0.10005 0.13422 0.17393 0.21890 0.27262
378
     [6,] 0.01567 0.04870 0.07552 0.11775 0.17512 0.24484 0.32239
379
     [7,] 0.01068 0.03668 0.06286 0.10824 0.17448 0.25791 0.34914
380
```

After 500 time units we obtain:

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```
R input

print( (Q * 500) %>% expm %>% round(5))
```

which gives:

```
R output
              [,1]
                               [,3]
                      [,2]
                                       [,4]
                                                [,5]
                                                       [,6]
                                                                [,7]
382
     [1,] 0.03431 0.08577 0.10722 0.13402 0.16752 0.2094 0.26176
383
     [2,] 0.03431 0.08577 0.10722 0.13402 0.16752 0.2094 0.26176
384
     [3,] 0.03431 0.08577 0.10722 0.13402 0.16752 0.2094 0.26176
385
     [4,] 0.03431 0.08577 0.10722 0.13402 0.16752 0.2094 0.26176
386
     [5,] 0.03431 0.08577 0.10722 0.13402 0.16752 0.2094 0.26176
387
     [6,] 0.03431 0.08577 0.10722 0.13402 0.16752 0.2094 0.26176
388
     [7,] 0.03431 0.08577 0.10722 0.13402 0.16752 0.2094 0.26176
389
```

We see that no matter what state (row) we are in, after 500 time units the probabilities are all the same. We could in fact stop our analysis here, however our choice of 500 time units was arbitrary and might not be the correct amount for all possible scenarios, as such we will continue to aim to solve the underlying equation 3.4 directly.

To be able to do this, we will make use of the versatile pracma package which includes a number of numerical analysis functions for efficient computations.

```
R input
     library(pracma, warn.conflicts = FALSE, quietly = TRUE)
390
391
      #' Return the steady state vector of any given continuous time
392
      #' transition rate matrix
393
394
      #' @param Q a transition rate matrix
395
396
      #' @return A vector
397
     get steady state vector <- function(Q){</pre>
398
        state_space_size <- dim(Q)[1]</pre>
399
        A <- rbind(t(Q), 1)
400
        b <- c(integer(state_space_size), 1)</pre>
401
        mldivide(A, b)
402
403
```

This is making use of pracma's mldivide function which chooses the best numerical algorithm to find the solution to a given matrix equation Ax = b.

So if we now see the steady state vector for our default system:

```
R input

print(get_steady_state_vector(Q))
```

we get:

```
R output
                  [,1]
405
      [1,] 0.03430888
406
      [2,] 0.08577220
407
      [3,] 0.10721525
408
      [4,] 0.13401906
409
      [5,] 0.16752383
410
      [6,] 0.20940479
411
      [7,] 0.26175598
412
```

We can see that the shop is expected to be empty approximately 3.4% of the time and full 26.2% of the time.

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The final piece of this puzzle is to create a single function that uses all of the above to just return the probability of the shop being full.

```
R input
      #' Return the probability of the barber shop being full
413
414
      #' @param waiting_room (default: 4)
415
      #' @param num barbers (default: 2)
416
417
      #' @return A real
418
     get_probability_of_full_shop <- function(waiting_room = 4,</pre>
419
                                                  num barbers = 2){
420
        arrival_rate <- 10
421
        service rate <- 4
422
        pi <- get_transition_rate_matrix(</pre>
423
          waiting_room = waiting_room,
424
          num_barbers = num_barbers
425
          ) %>%
426
          get_steady_state_vector()
427
428
        capacity <- waiting room + num barbers</pre>
429
        pi[capacity + 1]
430
431
```

Now we can run this code efficiently with both scenarios:

```
R input

print(get_probability_of_full_shop(waiting_room = 6))
```

which decreases the probability of a full shop to:

```
R output

[1] 0.2355699
```

but adding another barber and chair:

```
R input

print(get_probability_of_full_shop(num_barbers = 3))

gives:

R output

[1] 0.0786359
```

3.5 RESEARCH

TBA

		_

Discrete Event Simulation

OMPLEX situations further compounded by randomness appear throughout our daily lives. For example, data flowing through a computer network, patients being treated at an emergency services, and daily commutes to work. Mathematics can be used to understand these complex situations so as to make predictions which in turn can be used to make improvements. One tool used to do this is to let a computer create a dynamic virtual representation of the scenario in question, the particular type we are going to cover here is called Discrete Event Simulation.

4.1 PROBLEM

Consider the following situation: a bicycle repair shop would like reconfigure their set-up in order to guarantee that all bicycles processed by the repair shop take a maximum of 30 minutes. Their current set-up is as follows:

- Bicycles arrive randomly at the shop at a rate of 15 per hour.
- They wait in line to be seen at an inspection counter, manned by one member of staff who can inspect one bicycle at a time. On average an inspection takes around 3 minutes.
- After inspection it is found that around 20% of bicycles do not need repair, and they are then ready for collection.
- After inspection is is found that around 80% of bicycles go on to be repaired.
 These then wait in line outside the repair workshop, which is manned by two
 members of staff who can each repair one bicycle at a time. On average a repair
 takes around 6 minutes.
- After repair the bicycles are ready for collection.

A diagram of the system is shown in Figure 4.1

We can also assume that there is infinite capacity at the bicycle repair shop for waiting bicycles. The shop will hire and extra member of staff in order to meet their target of a maximum time in the system of 30 minutes. They would like to know if they should work on the inspection counter or in the repair workshop?

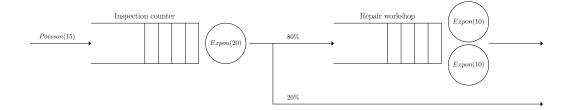


Figure 4.1 Diagrammatic representation of the bicycle repair shop as a queuing system.

4.2 THEORY

A number of the events that govern the behaviour of the bicycle shop above are probabilistic. For example the times that bicycles arrive at the shop, the duration of the inspection and repairs, and whether the bicycle would need to go on to be repaired or not. When a number of these probabilistic events are arranged in a complex system such as the bicycle shop, using analytical methods to manipulate these probabilities can become difficult. One method to deal with this is *simulation*.

Consider one probabilistic event, rolling a die. A die has six sides numbered 1 to 6, each side is equally likely to land. Therefore the probability of rolling a 1 is $\frac{1}{6}$, the probability of rolling a 2 is $\frac{1}{6}$, and so on. This means that that if we roll the die a large number of times, we would except $\frac{1}{6}$ of those rolls to be a 1. This is called the law of large numbers.

Now imagine we have an event in which we do not know the analytical probability of it occurring. Consider rolling a weighted die, in this case a die in which the probability of obtaining one number is much greater than the others. How can we estimate the probability of obtaining a 5 on this die?

Rolling the weighted die once does not give us much information. However due to the law of large numbers, we can roll this die a number of times, and find the proportion of those rolls which gave a 5. The more times we roll the die, the closer this proportion approaches the underlying probability of obtaining a 5.

For a complex system such as the bicycle shop, we would like to estimate the proportion of bicycles that take longer than 30 minutes to be processed. As it is a complex system it is difficult to work this out analytically. So, just like the weighted die, we would like to observe this system a number of times and record the overall proportions of bicycles spending longer than 30 minutes in the shop, which will converge to the true underlying proportion. However unlike rolling a weighted die, it it costly to observe this shop over a number of days with identical conditions. In this case it is costly in terms of time, as the repair shop already exists. However some scenarios, for example the scenario where the repair shop hires and additional member of staff, do not yet exist, so observing this this would be costly in terms of money also. We can however build a virtual representation of this complex system on a computer, and observe a virtual day of work much more quickly and much less costly on the computer, similar to a video game.

In order to do this, the computer needs to be able to generate random outcomes of

each of the smaller events that make up the large complex system. Generating random events are essentially doing things to random numbers, that need to be generated.

Computers are deterministic, therefore true randomness is not always possible. They can however generate pseudorandom numbers: sequences of numbers that look like random numbers, but are entirely determined from the previous numbers in the sequence. Most programming languages have methods of doing this.

In order to simulate an event we can again manipulate the law of large numbers. Let $X \sim U(0,1)$, a uniformly pseudorandom variable between 0 and 1. Let D be the outcome of a roll of an unbiased die. Then D can be defined as:

$$D = \begin{cases} 1 & \text{if } 0 \le X < \frac{1}{6} \\ 2 & \text{if } \frac{1}{6} \le X < \frac{2}{6} \\ 3 & \text{if } \frac{2}{6} \le X < \frac{3}{6} \\ 4 & \text{if } \frac{3}{6} \le X < \frac{4}{6} \\ 5 & \text{if } \frac{4}{6} \le X < \frac{5}{6} \\ 6 & \text{if } \frac{5}{6} \le X < 1 \end{cases}$$

$$(4.1)$$

The bicycle repair shop is a system made up of interactions of a number of other simpler random events. This can be thought of as many interactions of random variables, each generated using pseudorandom numbers.

In this case the fundamental random events that need to be generated are:

- the time each bicycle arrives to the repair shop,
- the time each bicycle spends at the inspection counter.
- whether each bicycle needs to go on the the repair workshop,
- the time each those bicycles spends at the repair shop.

As the simulation progresses these events will be generated, and will interact together as described in Section 5.1. The proportion of customers spending longer than 30 minutes in the shop can then be counted. This proportion itself is a random variable, and so just like the weighted die, running this simulation once does not give us much information. But we can run the simulation many times and take an average proportion, to smooth out any variability.

The process outlined above is a particular implementation of Monte Carlo simulation called discrete event simulation, which generates pseudorandom numbers and observes their interactions. In practice there are two main approaches to simulating complex probabilistic systems such as this one: the event scheduling approach, and process based simulation. It just so happens that the main implementations in Python and R use each of these approaches, so you will see both approaches used here.

4.2.1 **Event Scheduling Approach**

When using the event scheduling approach, we can think of the 'virtual representation' of the system as being the facilities that the bicycles use, shown in Figure 4.1. Then we let entities (the bicycles) interact with these facilities. It is these facilities that determine how the entities behave.

In a simulation that uses an event scheduling approach, a key concept is that events occur that cause further events to occur in the future, either immediately or after a delay, such as after some time in service. In the bicycle shop examples of such events include a bicycle joining a queue, a bicycle beginning service, and a bicycle finishing service. At each event the event list is updated, and the clock then jumps forward to the next event in this updated list.

4.2.2 Process Based Simulation

When using process based simulation, we can think of the 'virtual representation' of the system as being the sequence of actions that each entity (the bicycles) must take, and these sequences of actions might contain delays as a number of entities seize and release a finite amount of resources. It is the sequence of actions that determine how the entities behave.

For the bicycle repair shop an example of one possible sequence of actions would be:

 $arrive \rightarrow seize \ inspection \ counter \rightarrow delay \rightarrow release \ inspection \ counter \rightarrow seize \ repair \ shop \rightarrow delay \rightarrow release \ repair \ shop \rightarrow leave$

The scheduled delays in this sequence of events correspond to the time spend being inspected and the time spend being repaired. Waiting in line for service at these facilities are not included in the sequence of events; that is implicit by the 'seize' and 'release' actions, as an entity will wait for a free resource before seizing one. Therefore in process based simulations, in addition to defining a sequence of events, resource types and their numbers also need to be defined.

4.3 SOLVING WITH PYTHON

In this book we will use the Ciw library in order to conduct discrete event simulation in Python. Ciw uses the event scheduling approach, which means we must define the system's facilities, and then let customers loose to interact with them.

In this case there are two facilities to define: the inspection desk and the repair workshop. Let's order these as so. For each of these we need to define:

- the distribution of times between consecutive bicycles arriving,
- the distribution of times the bicycles spend in service,
- the number of servers available,
- the probability of routing to each of the other facilities after service.

In this case we will assume that the time between consecutive arrivals follow a exponential distribution, and that the service times also follow exponential distributions. These are common assumptions for this sort of queueing system.

In Ciw, these are defined in a Network object, created using the ciw.create network

function. The function below creates a Network object that defines the for a given set of parameters bicycle repair shop:

```
Python input
      import ciw
436
437
438
     def build network object(
439
          num_inspectors=1, num_repairers=2,
440
     ):
441
          """Returns a Network object that defines the repair shop.
442
443
          Args:
444
              num_inspectors: a positive integer (default: 1)
445
              num_repairers: a positive integer (default: 2)
446
447
          Returns:
448
              a Ciw network object
449
          11 11 11
450
          arrival_rate = 15
451
          inspection_rate = 20
452
          repair_rate = 10
453
          prob_need_repair = 0.8
454
          N = ciw.create_network(
455
              arrival_distributions=[
456
                   ciw.dists.Exponential(arrival rate),
457
                   ciw.dists.NoArrivals(),
458
              ],
459
              service distributions=[
460
                   ciw.dists.Exponential(inspection_rate),
461
                   ciw.dists.Exponential(repair_rate),
462
              ],
463
              number_of_servers=[num_inspectors, num_repairers],
464
              routing=[[0.0, prob_need_repair], [0.0, 0.0]],
465
466
          return N
467
```

A Network object is used by Ciw to access system parameters. For example one piece of information it holds is the number of nodes of the system:

```
Python input

N = build_network_object()
print(N.number_of_nodes)
```

which gives:

```
Python output

2
```

Now we have defined the system, we need to use this to build the virtual representation of the system: in Ciw this is a Simulation object. Once this is built the simulation can be run, that is observe it for one virtual day. The following function does this:

```
Python input
     def run simulation(network, seed=0):
471
          """Builds a simulation object and runs it for 8 time units.
472
473
          Args:
474
              network: a Ciw network object
              seed: a float (default: 0)
476
477
          Returns:
478
              a Ciw simulation object after a run of the simulation
479
480
         max_time = 8
481
          ciw.seed(seed)
482
          Q = ciw.Simulation(network)
483
          Q.simulate_until_max_time(max_time)
484
          return Q
485
```

Notice here a random seed is set. This is because there is some element of randomness when initialising this object, and much randomness in running the simulation, and in order to ensure reproducible results we force the pseudorandom number generator to produce the same sequence of pseudorandom numbers each time. Notice also that the simulation always begins with an empty system, so the first bicycle to arrive will never wait for service. Depending on the situation this may be an unwanted

feature, though not in this case as it is reasonable to assume that the bicycle shop will begin the day with no customers.

Now we wish to count the number of bicycles that have finished service, and to count the number of those whose entire journey through the system lasted longer than 0.5 hours. In order to do so, we'll use the pandas library for efficient manipulation of data frames.

```
Python input
      import pandas as pd
486
487
488
      def get_proportion(Q):
489
          """Returns the proportion of bicycles spending over a given
490
          limit at the repair shop.
491
492
          Args:
493
              Q: a Ciw simulation object after a run of the
494
                  simulation
495
496
497
          Returns:
              a real
498
          n n n
499
         limit = 0.5
500
          inds = Q.nodes[-1].all_individuals
501
         recs = pd.DataFrame(
502
              dr for ind in inds for dr in ind.data records
503
          )
504
         recs["total time"] = (
505
              recs["exit date"] - recs["arrival date"]
506
507
          total_times = recs.groupby("id_number")["total_time"].sum()
508
         return (total_times > limit).mean()
509
```

Altogether these functions can define the system, run one day of our system, and then find the proportion of bicycles spending over half an hour in the shop:

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```
N = build_network_object()
Q = run_simulation(N)
p = get_proportion(Q)
print(round(p, 6))
```

This piece of code gives

```
Python output

0.261261
```

meaning 26.13% of all bicycles spent longer than half an hour at the repair shop. However this particular day may have contained a number of extreme events. For a more accurate proportion this experiment should be repeated, and an average proportion taken. In order to do so, let's write a function that performs the above experiment over a number of trials, then finds an average proportion:

Python input

```
def get_average_proportion(num_inspectors=1, num_repairers=2):
515
          """Returns the average proportion of bicycles spending over
516
          a given limit at the repair shop.
517
518
          Args:
519
              num_inspectors: a positive integer (default: 1)
520
              num_repairers: a positive integer (default: 2)
521
522
          Returns:
523
              a real
524
          .....
525
526
         num_trials = 100
         N = build_network_object(
527
              num inspectors=num inspectors,
528
              num_repairers=num_repairers,
529
530
         proportions = []
531
          for trial in range(num_trials):
532
              Q = run_simulation(N, seed=trial)
533
              proportion = get_proportion(Q=Q)
534
              proportions.append(proportion)
535
          return sum(proportions) / num trials
536
```

This can be used to find the average proportion over 100 trials for the current system of one inspector and two repair people:

```
Python input _
     p = get_average_proportion(num_inspectors=1, num_repairers=2)
537
     print(round(p, 6))
538
```

which gives:

```
______Python output _____
    0.159354
539
```

that is, on average 15.94% of bicycles will spend longer than 30 minutes at the repair shop.

Now consider the two possible future scenarios we wish top compare: hiring an extra member of staff to serve at the inspection desk, or hiring an extra member of staff at the repair workshop. Which scenario yields a smaller proportion of bicycles spending over 30 minutes at the shop? Let's investigate. First look at the situation where the additional member of staff works at the inspection desk:

```
Python input

p = get_average_proportion(num_inspectors=2, num_repairers=2)
print(round(p, 6))

which gives:

Python output

0.038477
```

that is 3.85% of bicycles.

Now look at the situation where the additional member of staff works at the repair workshop:

```
p = get_average_proportion(num_inspectors=1, num_repairers=3)
print(round(p, 6))

which gives:

Python input

p = get_average_proportion(num_inspectors=1, num_repairers=3)
print(round(p, 6))
```

that is 10.36% of bicycles.

Therefore an additional member of staff at the inspection desk would be more beneficial than an additional member of staff at the repair workshop.

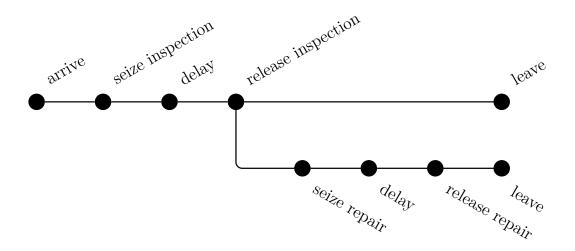


Figure 4.2 Diagrammatic representation of the forked trajectories a bicycle can take

4.4 SOLVING WITH R

In this book we will use the Simmer package in order to conduct discrete event simulation in R. Simmer uses the process based approach, which means we must define the each bicycle's sequence of actions, and then generate a number of bicycles with these sequences.

In Simmer these sequences of actions are made up of trajectories. The diagram in Figure ?? shows the branched trajectories than a bicycle would take at the repair shop:

The function below defines a simmer object that describes these trajectories:

```
R input
     library(simmer)
546
547
      #' Returns a simmer trajectory object outlining the bicycles
548
      #' path through the repair shop
549
550
      #' @return A simmer trajectory object
551
      define bicycle trajectories <- function() {</pre>
552
        inspection_rate <- 20</pre>
553
        repair_rate <- 10
554
        prob need repair <- 0.8
555
        bicycle <-
556
          trajectory("Inspection") %>%
557
          seize("Inspector") %>%
558
          timeout(function() {
559
            rexp(1, inspection_rate)
560
          }) %>%
561
          release("Inspector") %>%
562
          branch(
563
            function() (runif(1) < prob_need_repair),</pre>
564
            continue = c(F),
565
            trajectory("Repair") %>%
566
               seize("Repairer") %>%
567
               timeout(function() {
568
                 rexp(1, repair_rate)
569
              }) %>%
570
              release("Repairer"),
571
            trajectory("Out")
          )
573
        return(bicycle)
574
575
```

These trajectories are not very useful alone, we are yet to define the resources used, or a way to generate bicycles with these trajectories. This is done in the function below, which begins by defining a repair_shop with one resource labelled "Inspector", and two resources labelled "Repairer". Once this is built the simulation can be run, that is observe it for one virtual day. The following function does all this:

```
Runs one trial of the simulation.
576
     # '
577
     #' Oparam bicycle a simmer trajectory object
578
     #' Oparam num_inspectors positive integer (default: 1)
579
     #' Oparam num_repairers positive integer (default: 2)
580
     #' @param seed a float (default: 0)
581
582
     #' @return A simmer simulation object after one run of
583
                  the simulation
584
     run simulation <- function(bicycle,</pre>
585
                                  num_inspectors = 1,
                                   num_repairers = 2,
587
                                   seed = 0) {
588
       arrival rate <- 15
589
       max_time <- 8
590
       repair_shop <-
591
         simmer("Repair Shop") %>%
592
         add_resource("Inspector", num_inspectors) %>%
593
         add_resource("Repairer", num_repairers) %>%
594
```

add generator("Bicycle", bicycle, function() {

rexp(1, arrival rate)

repair_shop %>% run(until = 8)

595

596

597 598

599

600

601

602

}

})

set.seed(seed)

return(repair_shop)

R input

Notice here a random seed is set. This is because there are elements of randomness when running the simulation, and in order to ensure reproducible results we force the pseudorandom number generator to produce the same sequence of pseudorandom numbers each time. Notice also that the simulation always begins with an empty system, so the first bicycle to arrive will never wait for service. Depending on the situation this may be an unwanted feature, though not in this case as it is reasonable to assume that the bicycle shop will begin the day with no customers.

Now we wish to count the number of bicycles that have finished service, and to count the number of those whose entire journey through the system lasted longer than 0.5 hours. Using Simmer's get mon arrivals() function we can get a data frame of records to manipulate.

```
R input
        Returns the proportion of bicycles spending over 30
603
        minutes in the repair shop
604
605
        Oparam repair_shop a simmer simulation object
606
607
     #' @return a float between 0 and 1
608
     get proportion <- function(repair shop) {</pre>
609
       limit <- 0.5
610
       recs <- repair shop %>% get mon arrivals()
611
       total times <- recs$end time - recs$start time
612
       return(mean(total times > 0.5))
613
```

Altogether these functions can define the system, run one day of our system, and then find the proportion of bicycles spending over half an hour in the shop:

```
bicycle <- define_bicycle_trajectories()
repair_shop <- run_simulation(bicycle = bicycle)
print(get_proportion(repair_shop = repair_shop))
```

This piece of code gives

```
R output

[1] 0.04032258
```

meaning 4.03% of all bicycles spent longer than half an hour at the repair shop. However this particular day may have contained a number of extreme events. For a more accurate proportion this experiment should be repeated, and an average proportion taken. In order to do so, let's write a function that performs the above experiment over a number of trials, then finds an average proportion:

```
R input
      #' Returns the average proportion of bicycles spending over
619
      #' a given limit at the repair shop.
620
621
      #' Oparam num_inspectors positive integer (default: 1)
622
      #' Oparam num_repairers positive integer (default: 2)
623
624
      #' @return a float between 0 and 1
625
      get_average_proportion <- function(num_inspectors = 1,</pre>
626
                                             num_repairers = 2) {
627
        num_trials <- 100</pre>
628
        bicycle <- define bicycle trajectories()</pre>
629
        proportions <- c()</pre>
630
        for (trial in 1:num trials) {
631
          repair shop <- run simulation(</pre>
632
            bicycle = bicycle,
633
            num_inspectors = num_inspectors,
634
            num_repairers = num_repairers,
635
            seed = trial
636
637
          proportion <- get proportion(</pre>
638
            repair_shop = repair_shop
639
640
          proportions[trial] <- proportion</pre>
641
642
        return(mean(proportions))
643
644
```

This can be used to find the average proportion over 100 trials:

```
R input
     print(
645
       get average proportion(
646
         num_inspectors = 1,
647
         num_repairers = 2)
648
649
```

which gives:

```
R output

[1] 0.1551579
```

that is, on average 15.52% of bicycles will spend longer than 30 minutes at the repair shop.

Now consider the two possible future scenarios we wish top compare: hiring an extra member of staff to serve at the inspection desk, or hiring an extra member of staff at the repair workshop. Which scenario yields a smaller proportion of bicycles spending over 30 minutes at the shop? Let's investigate. First look at the situation where the additional member of staff works at the inspection desk:

```
Print(
get_average_proportion(
num_inspectors = 2,
num_repairers = 2)
)
```

which gives:

```
R output
[1] 0.04115338
```

that is 4.12% of bicycles.

Now look at the situation where the additional member of staff works at the repair workshop:

```
R input

print(
get_average_proportion(
num_inspectors = 1,
num_repairers = 3)
)
```

which gives:

that is 10.01% of bicycles.

Therefore an additional member of staff at the inspection desk would be more beneficial than an additional member of staff at the repair workshop.

4.5 RESEARCH

TBA

Systems Dynamics

In many situations systems are dynamical, in that the state or population of a number of entities or classes change according the the current state or population of the system. For example population dynamics, chemical reactions, and systems of macroeconomics. It is often useful to be able to predict how these systems will behave over time, though the rules which govern these changes can be complex, and are not necessarily solvable analytically. In these cases numerical methods and visualisation can be used, which is the focus of this chapter.

5.1 PROBLEM

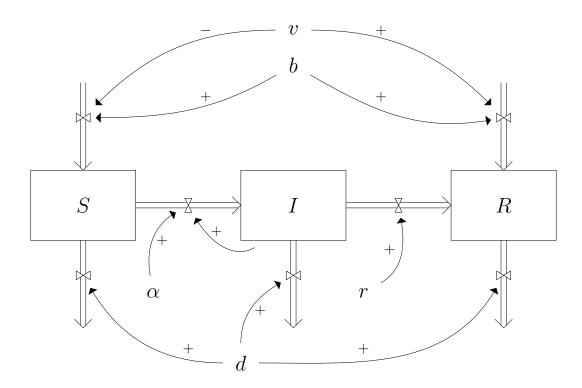
Consider the following scenario, where a population of 3000 people are susceptible to infection by some disease. This population can be described by the following parameters:

- They have a birth rate b of 0.01 per day;
- They have a death rate d of 0.01 per day;
- For every infectious individual, the infection rate α is 0.3 per day;
- Infectious people recover naturally (and thus gain an immunity from the disease), at a recovery rate r of 0.02 per day;
- For each day an individual is infected, they must take medication which costs a public healthcare system £10 per day.

A vaccine is produced, which allows new born individuals to gain an immunity. This vaccine costs the public health care system a one-off cost of £220 per vaccine. The healthcare providers would like to know if achieving a vaccination rate v of 85% would be beneficial financially.

5.2 THEORY

The above scenario can be described is called a compartmental model of disease, and can be shown in the stock and flow diagram in Figure 5.1.



 $Figure \ 5.1 \quad {\rm Diagram matic \ representation \ of \ the \ epidemiology \ model}$

The system has three 'stocks' of different types of individuals, those susceptible to disease (S), those infected with the disease (I), and those who have recovered from the disease and so have gained immunity (R). The levels on these stocks change according to the flows in, out, and between them, controlled by 'taps'. The amount of flow the taps let through are influenced multiplicatively (either negatively or positively), by other factors, such as external parameters (e.g. birth rate, infection rate) and the stock levels.

In this system the following taps exist, influences by the following parameters:

- $external \rightarrow S$: Influenced positively by the birth rate, and negatively by the vaccine rate.
- $S \to I$: Influenced positively by the infection rate, and the number of infected individuals.
- $S \to external$: Influenced positively by the death rate.
- $I \to R$: Influenced positively by the recovery rate.
- $I \rightarrow external$: Influenced positively by the death rate.
- $R \to external$: Influenced positively by the birth rate and the vaccine rate.
- $external \rightarrow R$: Influenced positively by the death rate.

Mathematically the change in stock levels are written as the derivatives, for example the change in the number of susceptible individuals over time is denoted by $\frac{dS}{dt}$. This can be equated to the sum of the taps in or out of that stock. Thus the system is described by the following system of differential equations:

$$\frac{dS}{dt} = -\frac{\alpha SI}{N} + (1 - v)bN - dS \tag{5.1}$$

$$\frac{dI}{dt} = \frac{\alpha SI}{N} - (r+d)I \tag{5.2}$$

$$\frac{dR}{dt} = rI - dR + vbN \tag{5.3}$$

Where N = S + I + R is the total number of individuals in the system.

We would like to understand the behaviour of the functions S, I and R under these rules, that is we would like to solve this system of differential equations. This system contains some non-linear terms, implying that this may be difficult to solve analytically, so we will use a numerical method instead.

There are a number of numerical methods, and the solvers we will use in Python and R cleverly choose the most appropriate for the problem at hand. In general methods for this kind of problems use the principle that the derivative denotes the rate of instantaneous change. Thus for a differential equation $\frac{dy}{dt} = f(t,y)$, consider the function y as a discrete sequence of points $\{y_0, y_1, y_2, y_3, \dots\}$ on $\{t_0, t_0 + h, t_0 + 2h, t_0 + 3h, \dots\}$ then

$$y_{n+1} = h \times f(t_0 + nh, y_n). \tag{5.4}$$

This sequence approaches the true solution y as $h \to 0$. Thus numerical methods, including the Runge-Kutta methods and the Euler method, step through this sequence $\{y_n\}$, choosing appropriate values of h and employing other methods of error reduction.

5.3 SOLVING WITH PYTHON

In this book we will use the odeint method of the SciPy library to numerically solve the above epidemiology models.

We first define the system of differential equations described in Equations 5.1, 5.2 and 5.3. This is a regular Python function, where the first two arguments are the system state and the current time respectively.

```
def derivatives(y, t, vaccine_rate, birth_rate=0.01):
663
          """Defines the system of differential equations that
664
          describe the epidemiology model.
665
666
          Arqs:
667
              y: a tuple of three integers
668
               t: a positive float
669
              vaccine_rate: a positive float <= 1</pre>
670
              birth_rate: a positive float <= 1
671
672
          Returns:
673
              A tuple containing dS, dI, and dR
674
          11 11 11
675
          infection_rate = 0.3
676
          recovery_rate = 0.02
677
          death_rate = 0.01
678
          S, I, R = y
679
          N = S + I + R
680
          dSdt = (-((infection_rate * S * I) / N)
681
                   + ((1 - vaccine rate) * birth rate * N)
682
                   - (death_rate * S))
683
          dIdt = (((infection rate * S * I) / N)
684
                   - (recovery_rate * I)
685
                   - (death_rate * I))
686
          dRdt = ((recovery_rate * I)
687
                   - (death_rate * R)
688
                   + (vaccine_rate * birth_rate * N))
689
          return dSdt, dIdt, dRdt
690
```

Using this function returns the instantaneous rate of change for each of the three stocks, S, I and R. If we begin at time 0.0, with 4 susceptible individuals, 1 infected individual, 0 recovered individuals, and a vaccine rate of 50%, then:

```
Python input
     derivatives (y=(4, 1, 0), t=0.0, vaccine_rate=0.5)
691
```

```
Python output

(-0.255, 0.21, 0.045)
```

we would expect the number of susceptible individuals to reduce by around 0.255 per time unit, the number of infected individuals to increase by 0.21 per time unit, and the number of recovered individuals to increase by 0.045 per time unit. Now of course, after a tiny fraction of a time unit the stock levels would change, and thus the rates of change will change. So we will require something more sophisticated in order to determine the true behaviour of the system.

The following function observes the system's behaviour over some time period, using SciPy's odeint to numerically solve the system of differential equations:

```
Python input
     from scipy.integrate import odeint
693
694
     def integrate ode (derivative function, t,
695
                         y0=(2999, 1, 0),
696
                         vaccine_rate=0.85,
697
                         birth_rate=0.01):
698
          """Numerically solve the system of differential equations
699
700
          Args:
701
              derivative_function: a function returning a tuple
702
                                      of three floats
703
              t: an array of increasing positive floats
704
              y0: a tuple of three integers (default: (2999, 1, 0))
705
              vaccine_rate: a positive float <= 1 (default: 0.85)</pre>
706
              birth_rate: a positive float <= 1 (default: 0.01)
707
708
          Returns:
709
              A tuple of three arrays
710
711
         results = odeint(
712
              derivative function,
713
714
              args=(vaccine_rate, birth_rate)
715
716
          S, I, R = results.T
717
          return S, I, R
718
```

Now we can use this function to investigate the difference in behaviour between a vaccination rate of 0% and a vaccination rate of 85%. Let's observe the system for two years, that is 730 days, in time steps of 0.01 days.

Begin with a vaccine rate of 0%:

```
Python input

import numpy as np
from scipy.integrate import odeint

t = np.arange(0, 730.01, 0.01)
S, I, R = integrate_ode(derivatives, t, vaccine_rate=0.0)
```

Now S, I and R are arrays of values of the stock levels of S, I and R over the time steps t. Using matplotlib we can plot these to visualise their behaviour. The following code gives the plot shown in Figure 5.2.

```
Python input
     import matplotlib.pyplot as plt
724
725
     fig, ax = plt.subplots(1)
726
     ax.plot(t, S, label='Susceptible')
727
     ax.plot(t, I, label='Infected')
728
     ax.plot(t, R, label='Recovered')
729
     ax.legend(fontsize=12)
730
     fig.savefig("plot_no_vaccine_python.pdf")
731
```

We observe that the number of infected individuals increases quickly, and in fact the rate of change increases as more individuals are infected. However this growth slows down as there are less susceptible individuals to infect. Due to the equal birth and death rates the overall population size remains constant; but we also see after some time period (around 300 time units) the levels of susceptible, infected, and recovered individuals becomes seemingly steady, and the disease becomes endemic. We can estimate once this steadiness occurs, around 10% of the population remain susceptible to the disease, 30% are infected, and 60% are recovered and immune.

Now with a vaccine rate of 85%:

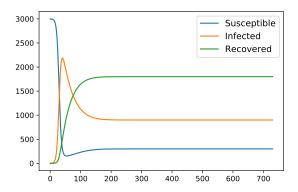


Figure 5.2 Output of code line 724-729

```
Python input

t = np.arange(0, 730.01, 0.01)
S, I, R = integrate_ode(derivatives, t, vaccine_rate=0.85)
```

And again we can plot these to visualise their behaviour. The following code gives the plot shown in Figure 5.3.

```
fig, ax = plt.subplots(1)
ax.plot(t, S, label='Susceptible')
ax.plot(t, I, label='Infected')
ax.plot(t, R, label='Recovered')
ax.legend(fontsize=12)
fig.savefig("plot_with_vaccine_python.pdf")
```

With vaccination the disease remains endemic, however now we estimate that once, steadiness occurs, around 10% of the population remain susceptible to the disease, 1.7% are infected, and 88.3% are immune or recovered and immune.

We've seen that vaccination lowers the percentage of the population living with the infection, which will lower the public healthcare system's medication costs. Let's now investigate if this saving is comparable to the cost of providing the vaccination to the newborns.

The following function calculates the total cost to the public healthcare system,

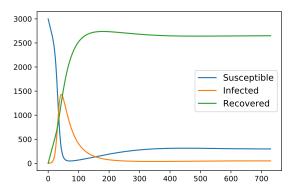


Figure 5.3 Output of code line 732-737

that is the sum of the medication costs for those living with the infection and the vaccination costs:

```
Python input
```

```
def daily_cost(
740
          derivative_function=derivatives, vaccine_rate=0.85
741
     ):
742
          11 11 11
743
          Calculates the daily cost to the public health system
744
          after 2 years
745
746
          Args:
747
              derivative_function: a function returning a tuple
748
                                      of three floats
749
              vaccine_rate: a positive float <= 1 (default: 0.85)</pre>
750
751
          Returns:
752
               the daily cost
753
754
          max\_time = 730
755
          time_step = 0.01
756
          birth_rate = 0.01
757
          vaccine_cost = 220
758
          medication cost = 10
759
          t = np.arange(0, max_time + time_step, time_step)
760
          S, I, R = integrate_ode(
761
              derivatives, t,
762
              vaccine rate=vaccine rate,
763
              birth_rate=birth_rate
764
765
          N = S[-1] + I[-1] + R[-1]
766
          daily_vaccine_cost = (N
767
768
                                   * birth_rate
                                  * vaccine_rate
769
                                  * vaccine_cost) / time_step
770
          daily_meds_cost = (I[-1] * medication_cost) / time_step
771
          return daily_vaccine_cost + daily_meds_cost
772
```

Now let's compare the total daily cost with and without vaccination. Without vaccinations:

```
rost = daily_cost(vaccine_rate=0.0)
print(round(cost, 2))

which gives

Python input

Python input

Python input

Python output
```

Therefore without vaccinations, once the infection is endemic, the public health care system would expect to spend £900,000 a day.

With a vaccine rate of 85%:

```
Python input

cost = daily_cost(vaccine_rate=0.85)
print(round(cost, 2))

which gives

Python output

611903.36
```

So vaccinating 85% of newborns would cost the public health care system, once the infection is endemic £611, 903.36 a day. That is a saving of around 32%.

5.4 SOLVING WITH R

In this book we will use the deSolve library to numerically solve the above epidemiology models.

We first define the system of differential equations described in Equations 5.1, 5.2 and 5.3. This is an R function where the arguments are the current time, the system state, and a list of other parameters, respectively.

```
R input
     #' Defines the system of differential equations that describe
779
     #' the epidemiology model.
780
781
     #' @param t a positive float
782
     #' @param y a tuple of three integers
783
     #' @param vaccine_rate a positive float <= 1
784
     #' @param birth_rate a positive float <= 1
785
786
     #' @return a list containing dS, dI, and dR
787
     derivatives <- function(t, y, parameters){</pre>
788
       infection_rate = 0.3
789
       recovery_rate = 0.02
790
       death_rate = 0.01
791
       with(as.list(c(y, parameters)), {
792
         N = S + I + R
793
          dSdt = (-((infection_rate * S * I) / N)
794
                 + ((1 - vaccine_rate) * birth_rate * N)
795
                 - (death rate * S))
796
          dIdt = (((infection_rate * S * I) / N)
797
                 - (recovery rate * I)
798
                 - (death_rate * I))
799
          dRdt = ((recovery rate * I)
800
                 - (death_rate * R)
801
                 + (vaccine rate * birth rate * N))
802
         list(c(dSdt, dIdt, dRdt))
803
     })
804
     }
805
```

Using this function returns the instantaneous rate of change for each of the three stocks, S, I and R. If we begin at time 0.0, with 4 susceptible individuals, 1 infected individual, 0 recovered individuals, a vaccine rate of 50% and a birth rate of 0.01, then:

```
R output

[[1]]
810
[1] -0.255 0.210 0.045
```

we would expect the number of susceptible individuals to reduce by around 0.255 per time unit, the number of infected individuals to increase by 0.21 per time unit, and the number of recovered individuals to increase by 0.045 per time unit. Now of course, after a tiny fraction of a time unit the stock levels would change, and thus the rates of change will change. So we will require something more sophisticated in order to determine the true behaviour of the system.

The following function observes the system's behaviour over some time period, using the deSolve library to numerically solve the system of differential equations:

```
R input
     library(deSolve)
812
813
     #' Numerically solve the system of differential equations
814
815
     #' Oparam t an array of increasing positive floats
816
     \#' @param y0 list of integers (default: c(S=2999, I=1, R=0))
817
     #' @param birth rate a positive float <= 1 (default: 0.01)
818
     #' @param vaccine_rate a positive float <= 1 (default: 0.85)</pre>
819
820
     #' @return a matrix of times, S, I and R values
821
     integrate ode <- function(times,</pre>
822
                                 y0=c(S=2999, I=1, R=0),
823
                                 birth rate=0.01,
824
                                 vaccine_rate=0.84){
825
       parameters = c(birth_rate=birth_rate,
826
                        vaccine_rate=vaccine_rate)
827
       ode(y=y0, times=times, func=derivatives, parms=parameters)
828
829
```

Now we can use this function to investigate the difference in behaviour between a vaccination rate of 0% and a vaccination rate of 85%. Let's observe the system for two years, that is 730 days, in time steps of 0.01 days.

Begin with a vaccine rate of 0%:

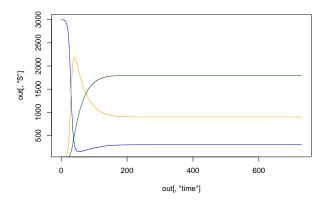


Figure 5.4 Output of code line 832-836

```
R input

times <- seq(0, 730, by = 0.01)
out <- integrate_ode(times, vaccine_rate=0.0)
```

Now out, is a matrix with four columns, time, S, I and R, which are arrays of values of the time points, and the stock levels of S, I and R over the time respectively. We can plot these to visualise their behaviour. The following code gives the plot shown in Figure 5.4.

```
pdf("plot_no_vaccine_R.pdf", width=7, height=5)
plot(out[, 'time'], out[, 'S'], type='l', col='blue')
lines(out[, 'time'], out[, 'I'], type='l', col='orange')
lines(out[, 'time'], out[, 'R'], type='l', col='darkgreen')
dev.off()
```

We observe that the number of infected individuals increases quickly, and in fact the rate of change increases as more individuals are infected. However this growth slows down as there are less susceptible individuals to infect. Due to the equal birth and death rates the overall population size remains constant; but we also see after some time period (around 300 time units) the levels of susceptible, infected, and recovered individuals becomes seemingly steady, and the disease becomes endemic.

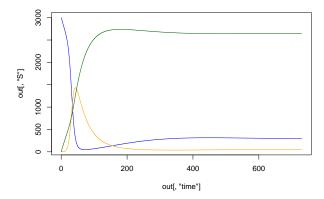


Figure 5.5 Output of code line 839-843

We can estimate once this steadiness occurs, around 10% of the population remain susceptible to the disease, 30% are infected, and 60% are recovered and immune.

Now with a vaccine rate of 85%:

```
R input

times <- seq(0, 730, by = 0.01)
out <- integrate_ode(times, vaccine_rate=0.85)
```

And again we can plot these to visualise their behaviour. The following code gives the plot shown in Figure 5.5.

```
R input

pdf("plot_with_vaccine_R.pdf", width=7, height=5)
plot(out[, 'time'], out[, 'S'], type='l', col='blue')
lines(out[, 'time'], out[, 'I'], type='l', col='orange')
lines(out[, 'time'], out[, 'R'], type='l', col='darkgreen')
dev.off()
```

With vaccination the disease remains endemic, however now we estimate that once, steadiness occurs, around 10% of the population remain susceptible to the disease, 1.7% are infected, and 88.3% are immune or recovered and immune.

We've seen that vaccination lowers the percentage of the population living with the infection, which will lower the public healthcare system's medication costs. Let's now investigate if this saving is comparable to the cost of providing the vaccination to the newborns.

The following function calculates the total cost to the public healthcare system, that is the sum of the medication costs for those living with the infection and the vaccination costs:

```
R input
      #' Calculates the daily cost to the public health
844
      #' system after 2 years
845
      # '
846
      #' @param derivative_function: a function returning a
847
                                        list of three floats
848
      #' @param vaccine_rate: a positive float <= 1 (default: 0.85)
849
850
      #' @return the daily cost
851
     daily_cost <- function(derivative_function=derivatives,</pre>
852
                               vaccine_rate=0.85){
853
       max_time = 730
854
       time_step = 0.01
855
       birth_rate = 0.01
856
       vaccine cost = 220
857
       medication_cost = 10
858
       times <- seq(0, max_time, by = time_step)
859
       out <- integrate_ode(times, vaccine_rate=vaccine_rate)</pre>
860
       N = sum(tail(out[, c('S', 'I', 'R')], n=1))
861
       daily_vaccine_cost <- (N</pre>
862
                                 * birth rate
863
                                 * vaccine_rate
864
                                 * vaccine_cost) / time_step
865
       daily_medication_cost <- ((tail(out[, 'I'], n=1)</pre>
866
                                     * medication_cost)) / time_step
867
       daily vaccine cost + daily medication cost
868
869
```

Now let's compare the total daily cost with and without vaccination. Without vaccinations:

```
R input

cost <- daily_cost(vaccine_rate=0.0)
print(cost)
```

which gives

```
R output

[1] 9e+05
```

Therefore without vaccinations, once the infection is endemic, the public health care system would expect to spend $\pounds 900,000$ a day.

With a vaccine rate of 85%:

```
R input

cost <- daily_cost(vaccine_rate=0.85)
print(cost)

which gives

R output
```

So vaccinating 85% of newborns would cost the public health care system, once the infection is endemic £611,903.40 a day. That is a saving of around 32%.

5.5 RESEARCH

		_

Bibliography

[1] Hadley Wickham. Advanced r. Chapman and Hall/CRC, 2014.