

### **Decreasing Energy Aliasing in POD-ROMs**

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In collaboration with: T. Iliescu (VT), V. John (WIAS), S. Giere (WIAS)

June 28, 2017 Conference on Classical and Geophysical Fluid Dynamics Governing Equations
A Little on SUPG
Numerical Results
Summary

#### **Outline**

- Governing Equations
- A Little on Streamline-Upwind Petrov-Galerkin (SUPG)
- The SUPG-ROM
- Numerical Results
- Summary

### **Convection-Diffusion-Reaction Equation**

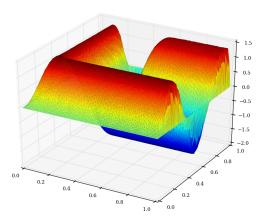
There are a few relevant model problems:

$$u_t - \varepsilon \Delta u + \vec{b} \cdot \nabla u + cu = f \tag{1}$$

$$-\varepsilon \Delta u + \vec{b} \cdot \nabla u + cu = f \tag{2}$$

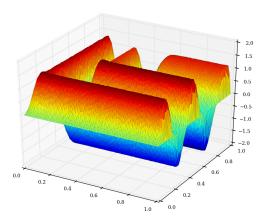
- $\varepsilon \ll 1$  and  $\varepsilon \ll h$
- Small diffusion implies wavelike behavior (*convection-dominated*): the relevant length scale is  $O(\sqrt{\varepsilon})$ , which may be too small to resolve.

# **Convection-Diffusion-Reaction Equation**



Third POD vector.

# **Convection-Diffusion-Reaction Equation**



Fifth POD vector.

$$\varepsilon u_{xx} + u_x = 0, u(0) = 0, u(1) = 1$$
 (3)

$$\varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2} + \frac{U_{i+1} - U_{i-1}}{2h} = 1 \tag{4}$$

known to be an unstable discretization for small a

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$$\left(\varepsilon + \frac{h}{2}\right) \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2} + \frac{U_{i+1} - U_{i-1}}{2h} = 1 \quad (7)$$

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# Stabilization by Streamline Upwinding (Petrov-Galerkin)

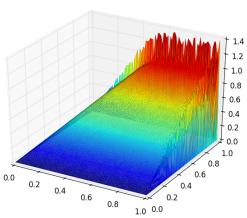
We can get a similar result for Finite Elements with the Petrov-Galerkin method by choosing test functions  $\varphi + \delta \varphi_x$ :

$$\varepsilon((\varphi + \delta\varphi_X)_X, u_X) + (\varphi + \delta\varphi_X, u_X) = (\varphi + \delta\varphi_X, f)$$
(8)

$$(\varepsilon + \delta)(\varphi_{\mathsf{X}}, \mathsf{U}_{\mathsf{X}}) + \varepsilon \delta(\varphi_{\mathsf{X}\mathsf{X}}, \mathsf{U}_{\mathsf{X}}) + (\varphi, \mathsf{U}_{\mathsf{X}}) = (\varphi + \delta\varphi_{\mathsf{X}}, \mathsf{f})$$
(9)

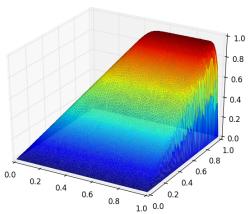
so the new viscous length scale is  $O(\sqrt{\delta})$ : if  $\delta = O(h)$  then this can be resolved.

# Stabilization by SUPG



 $f = 1, \varepsilon = 10^{-3}, \vec{b} = (\cos(\pi/3), \sin(\pi/3)), \text{ and } c = 10^{-3}$ : no stabilization.

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 $f=1,\, \varepsilon=10^{-3},\, \vec{b}=(\cos(\pi/3),\sin(\pi/3)),$  and  $c=10^{-3},$  with SUPG,  $\delta=h.$ 

- SUPG helps us avoid instabilities arising from unresolved modes
- Unresolved modes → aliasing onto the resolved parts (wiggles)
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#### **Error estimates**

We assume a centered trajectory  $u_s$ , ROM approximating the fluctuations  $u_r$ , and projection onto the POD space  $P_r$ :

$$u - (u_s + u_r) = (u - P_r(u_h)) + (P_r(u_h) - (u_s + u_r))$$
  
:=  $\eta - \phi_r$  (10)

Error estimate of the form (Giere, 2015 [1]

$$|||\phi_{r}|||_{\text{SUPG},r} \leq C \left[ \left( 1 + \frac{1}{\sqrt{\delta}} + \sqrt{\delta} \right) \|\eta\| + \sqrt{\varepsilon} \|\nabla \eta\| + \sqrt{\delta} \|\vec{b} \cdot \nabla \eta\| + \sqrt{\delta} \sqrt{\sum_{T} \|\Delta \eta\|_{0,T}^{2}} \right].$$

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# **The POD Option**

Seminorm bound on derivatives: [2, 4]

$$\sum_{n=0}^{R-1} \left| u_n - \sum_{j=0}^{r-1} \left\langle u_n, \phi_j \right\rangle \phi_j \right|_{s}^{2} = \sum_{j=r}^{R-1} \left| \phi_j \right|_{s}^{2} \sigma_j^{2}. \tag{12}$$

$$\|\eta\| \le C_1 \sqrt{\sum_{j=r}^{R-1} \sigma_j^2} := C_1 \Lambda_0$$
 (13)

$$\|\nabla \eta\| \le C_1 \sqrt{\sum_{j=r}^{R-1} \sigma_j^2 |\varphi_j|_1} := C_1 \Lambda_1 \tag{14}$$

$$\sqrt{\sum_{T \in \mathcal{T}_h} \|\delta \eta\|_T^2} \le C_1 \sqrt{\sum_{j=r}^{R-1} \sigma_j^2 |\varphi_j|_2} := C_1 \Lambda_2.$$
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# The Finite Element Option

Another option is to use finite element estimates [3] with order *m* polynomials and *s* derivatives:

$$|\eta|_{s} \le Ch^{m+1/2-s} \tag{17}$$

Solve the optimization problem for  $\delta$ :

$$\delta = \frac{\Lambda_0 h^2 + h^{m+\frac{5}{2}}}{(h^2 + \varepsilon + h)\Lambda_0 + \varepsilon h^{m+\frac{1}{2}} + h^{m+\frac{5}{2}} + h^{m+\frac{3}{2}}}$$
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If m > 2

$$\delta \approx \frac{\Lambda_0 h^2}{h\Lambda_0} = h \tag{19}$$

We are back where we started! In practice the two stabilization parameters are within about 10%.

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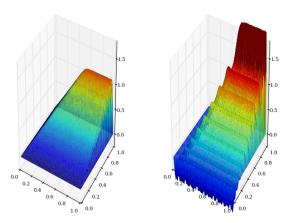
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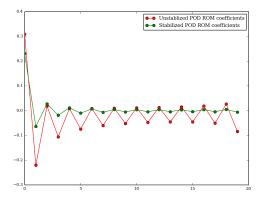
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#### **POD-ROM and SUPG-ROM**



Stabilized (left) and unstabilized (right) POD-ROMs at t = 1.0.

# **Comparison of POD coefficients**



Coefficients at t = 1.0 for the stabilized and unstabilized models.

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### **Summary**

- ROMs for convection-dominated problems have aliasing issues when scales are unresolved.
- We can overcome this problem with SUPG; tentatively, this implies that the usual FEM stabilization methods may be useful.

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# Thank You!



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