MATH2270: Midterm 1 Practice Problems

Here are some practice problems for the first exam. This is not meant to mimic the length of the exam.

1. Inventions:

- Give an example of a linearly independent set of vectors in \mathbb{R}^3 that contains as many vectors as possible.
- Give an example of a 3×3 matrix A in reduced row echelon form such that the first and third columns of A are pivot columns, and $A \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$.
- Give an example of vectors \vec{v} and \vec{w} in \mathbb{R}^3 such that span $\{\vec{v}, \vec{w}\}$ is a line.
- 2. True/False: Determine if each statement is true or false.
 - A free variable in a linear system is a variable that corresponds to a pivot column in the coefficient matrix.
 - A consistent linear system always has infinitely many solutions.
 - If A is a 2×3 matrix, then the linear transformation $x \mapsto Ax$ has domain \mathbb{R}^3 .
 - If A is a 2×3 matrix, then the linear transformation $x \mapsto Ax$ cannot be onto.
 - If the columns of a matrix A are linearly dependent, then the equation Ax = 0 has only one solution.
 - If the columns of a matrix A are linearly dependent, the linear transformation $x \mapsto Ax$ is one-to-one.
- 3. For what values of h and k is the following system consistent?

$$2x_1 - x_2 = h$$
$$-6x_1 + 3x_2 = k$$

4. Give a parametric description of the solutions to the equation $A\vec{x} = \vec{0}$ where A is the matrix shown below:

$$\begin{bmatrix} 1 & -2 & 3 & -6 & 5 & 0 \\ 0 & 0 & 0 & 1 & 4 & -6 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

5. Determine if the vector $\vec{b} = \begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix}$ is in span $\{v_1, v_2\}$ where

$$\vec{v_1} = \begin{bmatrix} 1\\2\\2 \end{bmatrix}, \qquad \vec{v_2} = \begin{bmatrix} 5\\9\\7 \end{bmatrix}$$

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If the answer is yes, then write \vec{b} as a linear combination of $\vec{v_1}$ and $\vec{v_2}$.

- 6. If \vec{b} is in the span of the vectors $\vec{v_1}, \dots, \vec{v_k}$, what can you say about solutions to the matrix equation $A\vec{x} = \vec{b}$ where A is the matrix whose columns are $\vec{v_1}, \dots, \vec{v_k}$ (i.e., $A = [\vec{v_1} \ \vec{v_2} \ \dots \ \vec{v_k}]$)?
- 7. Is the set of vectors $\left\{ \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} 1\\1\\1 \end{bmatrix}, \begin{bmatrix} 0\\0\\0 \end{bmatrix} \right\}$ linearly independent? Why or why not?
- 8. Is the set of vectors $\{\text{span}\{[\frac{1}{0}]\}\}\$ linearly independent? Why or why not?
- 9. Determine if the linear transformation $T: \mathbb{R}^3 \to \mathbb{R}^2$, whose standard matrix is A, is 1-1. Is it onto?

 $A = \begin{pmatrix} 2 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}$

- 10. Suppose $S \colon \mathbb{R}^2 \to \mathbb{R}^3$ is a linear transformation such that $S\left(\left[\begin{smallmatrix}1\\0\end{smallmatrix}\right]\right) = \left[\begin{smallmatrix}3\\-2\\-1\end{smallmatrix}\right]$ and $S\left(\left[\begin{smallmatrix}0\\1\end{smallmatrix}\right]\right) = \left[\begin{smallmatrix}-1\\2\\2\end{smallmatrix}\right]$.
 - (a) Find $S\left(\begin{bmatrix} -3\\3 \end{bmatrix}\right)$.
 - (b) Find the standard matrix for S.
- 11. If the columns of a 6×4 matrix A are linearly dependent, then what is the maximum number of pivot positions of A?