Next, use equation (7) to write

$$\mathbf{x}_1(t) = \begin{bmatrix} i \\ 2 \end{bmatrix} e^{-2t}(\cos 5t + i \sin 5t)$$

The real and imaginary parts of $\mathbf{x}_1$ provide real solutions:

$$\mathbf{y}_1(t) = \begin{bmatrix} -\sin 5t \\ 2\cos 5t \end{bmatrix} e^{-2t}, \qquad \mathbf{y}_2(t) = \begin{bmatrix} \cos 5t \\ 2\sin 5t \end{bmatrix} e^{-2t}$$

Since $\mathbf{y}_1$ and $\mathbf{y}_2$ are linearly independent functions, they form a basis for the two-dimensional real vector space of solutions of $\mathbf{x}' = A\mathbf{x}$. Thus the general solution is

$$\mathbf{x}(t) = c_1 \begin{bmatrix} -\sin 5t \\ 2\cos 5t \end{bmatrix} e^{-2t} + c_2 \begin{bmatrix} \cos 5t \\ 2\sin 5t \end{bmatrix} e^{-2t}$$

To satisfy $\mathbf{x}(0) = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$, we need $c_1 \begin{bmatrix} 0 \\ 2 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$, which leads to $c_1 = 1.5$ and $c_2 = 3$. Thus

$$\mathbf{x}(t) = 1.5 \begin{bmatrix} -\sin 5t \\ 2\cos 5t \end{bmatrix} e^{-2t} + 3 \begin{bmatrix} \cos 5t \\ 2\sin 5t \end{bmatrix} e^{-2t}$$

or

$$\begin{bmatrix} i_L(t) \\ v_C(t) \end{bmatrix} = \begin{bmatrix} -1.5\sin 5t + 3\cos 5t \\ 3\cos 5t + 6\sin 5t \end{bmatrix} e^{-2t}$$

See Fig. 5. ■

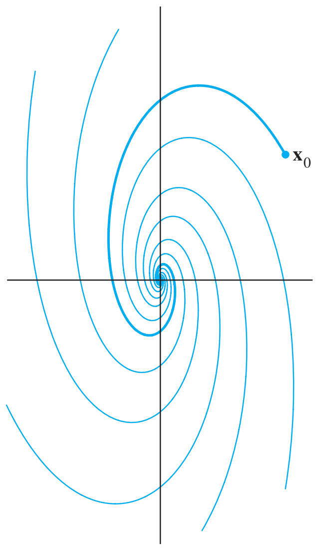


FIGURE 5
The origin as a spiral point.

In Fig. 5, the origin is called a **spiral point** of the dynamical system. The rotation is caused by the sine and cosine functions that arise from a complex eigenvalue. The trajectories spiral inward because the factor e^{-2t} tends to zero. Recall that -2 is the real part of the eigenvalue in Example 3. When A has a complex eigenvalue with positive real part, the trajectories spiral outward. If the real part of the eigenvalue is zero, the trajectories form ellipses around the origin.

PRACTICE PROBLEMS

A real 3×3 matrix A has eigenvalues $-.5$, $.2 + .3i$, and $.2 - .3i$, with corresponding eigenvectors

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1+2i \\ 4i \\ 2 \end{bmatrix}, \quad \text{and} \quad \mathbf{v}_3 = \begin{bmatrix} 1-2i \\ -4i \\ 2 \end{bmatrix}$$

1. Is A diagonalizable as $A = PDP^{-1}$, using complex matrices?
2. Write the general solution of $\mathbf{x}' = A\mathbf{x}$ using complex eigenfunctions, and then find the general real solution.
3. Describe the shapes of typical trajectories.

5.7 EXERCISES

1. A particle moving in a planar force field has a position vector $\mathbf{x}$ that satisfies $\mathbf{x}' = A\mathbf{x}$. The 2×2 matrix A has eigenvalues 4 and 2, with corresponding eigenvectors $\mathbf{v}_1 = \begin{bmatrix} -3 \\ 1 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$. Find the position of the particle at time t, assuming that $\mathbf{x}(0) = \begin{bmatrix} -6 \\ 1 \end{bmatrix}$.

2. Let A be a 2×2 matrix with eigenvalues -3 and -1 and corresponding eigenvectors $\mathbf{v}_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$. Let $\mathbf{x}(t)$ be the position of a particle at time t. Solve the initial value problem $\mathbf{x}' = A\mathbf{x}$, $\mathbf{x}(0) = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$.

In Exercises 3–6, solve the initial value problem $\mathbf{x}'(t) = A\mathbf{x}(t)$ for $t \geq 0$, with $\mathbf{x}(0) = (3, 2)$. Classify the nature of the origin as an attractor, repeller, or saddle point of the dynamical system described by $\mathbf{x}' = A\mathbf{x}$. Find the directions of greatest attraction and/or repulsion. When the origin is a saddle point, sketch typical trajectories.

3. $A = \begin{bmatrix} 2 & 3 \\ -1 & -2 \end{bmatrix}$

4. $A = \begin{bmatrix} -2 & -5 \\ 1 & 4 \end{bmatrix}$

5. $A = \begin{bmatrix} 7 & -1 \\ 3 & 3 \end{bmatrix}$

6. $A = \begin{bmatrix} 1 & -2 \\ 3 & -4 \end{bmatrix}$

In Exercises 7 and 8, make a change of variable that decouples the equation $\mathbf{x}' = A\mathbf{x}$. Write the equation $\mathbf{x}(t) = P\mathbf{y}(t)$ and show the calculation that leads to the uncoupled system $\mathbf{y}' = D\mathbf{y}$, specifying P and D.

7. A as in Exercise 5

8. A as in Exercise 6

In Exercises 9–18, construct the general solution of $\mathbf{x}' = A\mathbf{x}$ involving complex eigenfunctions and then obtain the general real solution. Describe the shapes of typical trajectories.

9. $A = \begin{bmatrix} -3 & 2 \\ -1 & -1 \end{bmatrix}$

10. $A = \begin{bmatrix} 3 & 1 \\ -2 & 1 \end{bmatrix}$

11. $A = \begin{bmatrix} -3 & -9 \\ 2 & 3 \end{bmatrix}$

12. $A = \begin{bmatrix} -7 & 10 \\ -4 & 5 \end{bmatrix}$

13. $A = \begin{bmatrix} 4 & -3 \\ 6 & -2 \end{bmatrix}$

14. $A = \begin{bmatrix} -2 & 1 \\ -8 & 2 \end{bmatrix}$

15. [**M**] $A = \begin{bmatrix} -8 & -12 & -6 \\ 2 & 1 & 2 \\ 7 & 12 & 5 \end{bmatrix}$

16. [**M**] $A = \begin{bmatrix} -6 & -11 & 16 \\ 2 & 5 & -4 \\ -4 & -5 & 10 \end{bmatrix}$

17. [**M**] $A = \begin{bmatrix} 30 & 64 & 23 \\ -11 & -23 & -9 \\ 6 & 15 & 4 \end{bmatrix}$

18. [**M**] $A = \begin{bmatrix} 53 & -30 & -2 \\ 90 & -52 & -3 \\ 20 & -10 & 2 \end{bmatrix}$

19. [**M**] Find formulas for the voltages v_1 and v_2 (as functions of time t) for the circuit in Example 1, assuming that $R_1 = 1/5$ ohm, $R_2 = 1/3$ ohm, $C_1 = 4$ farads, $C_2 = 3$ farads, and the initial charge on each capacitor is 4 volts.

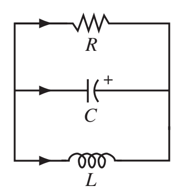
20. [**M**] Find formulas for the voltages v_1 and v_2 for the circuit in Example 1, assuming that $R_1 = 1/15$ ohm, $R_2 = 1/3$ ohm, $C_1 = 9$ farads, $C_2 = 2$ farads, and the initial charge on each capacitor is 3 volts.

21. [**M**] Find formulas for the current i_L and the voltage v_C for the circuit in Example 3, assuming that $R_1 = 1$ ohm, $R_2 = .125$ ohm, $C = .2$ farad, $L = .125$ henry, the initial current is 0 amp, and the initial voltage is 15 volts.

22. [**M**] The circuit in the figure is described by the equation

$$\begin{bmatrix} i'_L \\ v'_C \end{bmatrix} = \begin{bmatrix} 0 & 1/L \\ -1/C & -1/(RC) \end{bmatrix} \begin{bmatrix} i_L \\ v_C \end{bmatrix}$$

where i_L is the current through the inductor L and v_C is the voltage drop across the capacitor C. Find formulas for i_L and v_C when $R = .5$ ohm, $C = 2.5$ farads, $L = .5$ henry, the initial current is 0 amp, and the initial voltage is 12 volts.



SOLUTIONS TO PRACTICE PROBLEMS

1. Yes, the 3×3 matrix is diagonalizable because it has three distinct eigenvalues. Theorem 2 in Section 5.1 and Theorem 5 in Section 5.3 are valid when complex scalars are used. (The proofs are essentially the same as for real scalars.)

2. The general solution has the form

$$\mathbf{x}(t) = c_1 \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} e^{-.5t} + c_2 \begin{bmatrix} 1 + 2i \\ 4i \\ 2 \end{bmatrix} e^{(.2+.3i)t} + c_3 \begin{bmatrix} 1 - 2i \\ -4i \\ 2 \end{bmatrix} e^{(.2-.3i)t}$$

The scalars c_1, c_2, c_3 here can be any complex numbers. The first term in $\mathbf{x}(t)$ is real. Two more real solutions can be produced using the real and imaginary parts of the which can be rearranged to produce

$$\begin{aligned}\|\mathbf{u}\|\,\|\mathbf{v}\|\cos\vartheta &= \frac{1}{2}\left[\|\mathbf{u}\|^2 + \|\mathbf{v}\|^2 - \|\mathbf{u}-\mathbf{v}\|^2\right]\\ &= \frac{1}{2}\left[u_1^2 + u_2^2 + v_1^2 + v_2^2 - (u_1-v_1)^2 - (u_2-v_2)^2\right]\\ &= u_1v_1 + u_2v_2\\ &= \mathbf{u}\cdot\mathbf{v}\end{aligned}$$

The verification for $\mathbb{R}^3$ is similar. When $n > 3$, formula (2) may be used to *define* the angle between two vectors in $\mathbb{R}^n$. In statistics, for instance, the value of $\cos\vartheta$ defined by (2) for suitable vectors $\mathbf{u}$ and $\mathbf{v}$ is what statisticians call a *correlation coefficient*.

PRACTICE PROBLEMS

Let $\mathbf{a} = \begin{bmatrix}-2\\1\end{bmatrix}$, $\mathbf{b} = \begin{bmatrix}-3\\1\end{bmatrix}$, $\mathbf{c} = \begin{bmatrix}4/3\\-1\\2/3\end{bmatrix}$, and $\mathbf{d} = \begin{bmatrix}5\\6\\-1\end{bmatrix}$.

1. Compute $\dfrac{\mathbf{a}\cdot\mathbf{b}}{\mathbf{a}\cdot\mathbf{a}}$ and $\left(\dfrac{\mathbf{a}\cdot\mathbf{b}}{\mathbf{a}\cdot\mathbf{a}}\right)\mathbf{a}$.
2. Find a unit vector $\mathbf{u}$ in the direction of $\mathbf{c}$.
3. Show that $\mathbf{d}$ is orthogonal to $\mathbf{c}$.
4. Use the results of Practice Problems 2 and 3 to explain why $\mathbf{d}$ must be orthogonal to the unit vector $\mathbf{u}$.

6.1 EXERCISES

Compute the quantities in Exercises 1–8 using the vectors

$$\mathbf{u} = \begin{bmatrix}-1\\2\end{bmatrix},\quad \mathbf{v} = \begin{bmatrix}4\\6\end{bmatrix},\quad \mathbf{w} = \begin{bmatrix}3\\-1\\-5\end{bmatrix},\quad \mathbf{x} = \begin{bmatrix}6\\-2\\3\end{bmatrix}$$

1. $\mathbf{u}\cdot\mathbf{u}$, $\mathbf{v}\cdot\mathbf{u}$, and $\dfrac{\mathbf{v}\cdot\mathbf{u}}{\mathbf{u}\cdot\mathbf{u}}$

2. $\mathbf{w}\cdot\mathbf{w}$, $\mathbf{x}\cdot\mathbf{w}$, and $\dfrac{\mathbf{x}\cdot\mathbf{w}}{\mathbf{w}\cdot\mathbf{w}}$

3. $\dfrac{1}{\mathbf{w}\cdot\mathbf{w}}\mathbf{w}$

4. $\dfrac{1}{\mathbf{u}\cdot\mathbf{u}}\mathbf{u}$

5. $\left(\dfrac{\mathbf{u}\cdot\mathbf{v}}{\mathbf{v}\cdot\mathbf{v}}\right)\mathbf{v}$

6. $\left(\dfrac{\mathbf{x}\cdot\mathbf{w}}{\mathbf{x}\cdot\mathbf{x}}\right)\mathbf{x}$

7. $\|\mathbf{w}\|$

8. $\|\mathbf{x}\|$

In Exercises 9–12, find a unit vector in the direction of the given vector.

9. $\begin{bmatrix}-30\\40\end{bmatrix}$

10. $\begin{bmatrix}-6\\4\\-3\end{bmatrix}$

11. $\begin{bmatrix}7/4\\1/2\\1\end{bmatrix}$

12. $\begin{bmatrix}8/3\\2\end{bmatrix}$

13. Find the distance between $\mathbf{x} = \begin{bmatrix}10\\-3\end{bmatrix}$ and $\mathbf{y} = \begin{bmatrix}-1\\-5\end{bmatrix}$.

14. Find the distance between $\mathbf{u} = \begin{bmatrix}0\\-5\\2\end{bmatrix}$ and $\mathbf{z} = \begin{bmatrix}-4\\-1\\8\end{bmatrix}$.

Determine which pairs of vectors in Exercises 15–18 are orthogonal.

15. $\mathbf{a} = \begin{bmatrix}8\\-5\end{bmatrix}$, $\mathbf{b} = \begin{bmatrix}-2\\-3\end{bmatrix}$

16. $\mathbf{u} = \begin{bmatrix}12\\3\\-5\end{bmatrix}$, $\mathbf{v} = \begin{bmatrix}2\\-3\\3\end{bmatrix}$

17. $\mathbf{u} = \begin{bmatrix}3\\2\\-5\\0\end{bmatrix}$, $\mathbf{v} = \begin{bmatrix}-4\\1\\-2\\6\end{bmatrix}$

18. $\mathbf{y} = \begin{bmatrix}-3\\7\\4\\0\end{bmatrix}$, $\mathbf{z} = \begin{bmatrix}1\\-8\\15\\-7\end{bmatrix}$

In Exercises 19 and 20, all vectors are in $\mathbb{R}^n$. Mark each statement True or False. Justify each answer.

19. a. $\mathbf{v}\cdot\mathbf{v} = \|\mathbf{v}\|^2$.

b. For any scalar c, $\mathbf{u}\cdot(c\mathbf{v}) = c(\mathbf{u}\cdot\mathbf{v})$.

c. If the distance from $\mathbf{u}$ to $\mathbf{v}$ equals the distance from $\mathbf{u}$ to $-\mathbf{v}$, then $\mathbf{u}$ and $\mathbf{v}$ are orthogonal.

d. For a square matrix A, vectors in Col A are orthogonal to vectors in Nul A.

e. If vectors $\mathbf{v}_1, \ldots, \mathbf{v}_p$ span a subspace W and if $\mathbf{x}$ is orthogonal to each $\mathbf{v}_j$ for $j = 1, \ldots, p$, then $\mathbf{x}$ is in $W^{\perp}$.

20. a. $\mathbf{u}\cdot\mathbf{v} - \mathbf{v}\cdot\mathbf{u} = 0$.

b. For any scalar c, $\|c\mathbf{v}\| = c\|\mathbf{v}\|$.

c. If $\mathbf{x}$ is orthogonal to every vector in a subspace W, then $\mathbf{x}$ is in $W^{\perp}$.

d. If $\|\mathbf{u}\|^2 + \|\mathbf{v}\|^2 = \|\mathbf{u}+\mathbf{v}\|^2$, then $\mathbf{u}$ and $\mathbf{v}$ are orthogonal.

e. For an $m \times n$ matrix A, vectors in the null space of A are orthogonal to vectors in the row space of A.

21. Use the transpose definition of the inner product to verify parts (b) and (c) of Theorem 1. Mention the appropriate facts from Chapter 2.

22. Let $\mathbf{u} = (u_1, u_2, u_3)$. Explain why $\mathbf{u}\cdot\mathbf{u} \geq 0$. When is $\mathbf{u}\cdot\mathbf{u} = 0$?

23. Let $\mathbf{u} = \begin{bmatrix} 2 \\ -5 \\ -1 \end{bmatrix}$ and $\mathbf{v} = \begin{bmatrix} -7 \\ -4 \\ 6 \end{bmatrix}$. Compute and compare $\mathbf{u}\cdot\mathbf{v}$, $\|\mathbf{u}\|^2$, $\|\mathbf{v}\|^2$, and $\|\mathbf{u}+\mathbf{v}\|^2$. Do not use the Pythagorean Theorem.

24. Verify the *parallelogram law* for vectors $\mathbf{u}$ and $\mathbf{v}$ in $\mathbb{R}^n$:

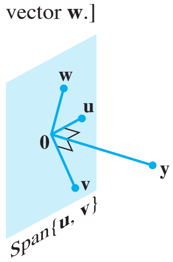
$$\|\mathbf{u}+\mathbf{v}\|^2 + \|\mathbf{u}-\mathbf{v}\|^2 = 2\|\mathbf{u}\|^2 + 2\|\mathbf{v}\|^2$$

25. Let $\mathbf{v} = \begin{bmatrix} a \\ b \end{bmatrix}$. Describe the set H of vectors $\begin{bmatrix} x \\ y \end{bmatrix}$ that are orthogonal to $\mathbf{v}$. [*Hint:* Consider $\mathbf{v} = \mathbf{0}$ and $\mathbf{v} \neq \mathbf{0}$.]

26. Let $\mathbf{u} = \begin{bmatrix} 5 \\ -6 \\ 7 \end{bmatrix}$, and let W be the set of all $\mathbf{x}$ in $\mathbb{R}^3$ such that $\mathbf{u}\cdot\mathbf{x} = 0$. What theorem in Chapter 4 can be used to show that W is a subspace of $\mathbb{R}^3$? Describe W in geometric language.

27. Suppose a vector $\mathbf{y}$ is orthogonal to vectors $\mathbf{u}$ and $\mathbf{v}$. Show that $\mathbf{y}$ is orthogonal to the vector $\mathbf{u}+\mathbf{v}$.

28. Suppose $\mathbf{y}$ is orthogonal to $\mathbf{u}$ and $\mathbf{v}$. Show that $\mathbf{y}$ is orthogonal to every $\mathbf{w}$ in Span $\{\mathbf{u}, \mathbf{v}\}$. [*Hint:* An arbitrary $\mathbf{w}$ in Span $\{\mathbf{u}, \mathbf{v}\}$ has the form $\mathbf{w} = c_1\mathbf{u} + c_2\mathbf{v}$. Show that $\mathbf{y}$ is orthogonal to such a vector $\mathbf{w}$.]



29. Let $W = \text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$. Show that if $\mathbf{x}$ is orthogonal to each $\mathbf{v}_j$, for $1 \leq j \leq p$, then $\mathbf{x}$ is orthogonal to every vector in W.

30. Let W be a subspace of $\mathbb{R}^n$, and let $W^{\perp}$ be the set of all vectors orthogonal to W. Show that $W^{\perp}$ is a subspace of $\mathbb{R}^n$ using the following steps.

a. Take $\mathbf{z}$ in $W^{\perp}$, and let $\mathbf{u}$ represent any element of W. Then $\mathbf{z}\cdot\mathbf{u} = 0$. Take any scalar c and show that $c\mathbf{z}$ is orthogonal to $\mathbf{u}$. (Since $\mathbf{u}$ was an arbitrary element of W, this will show that $c\mathbf{z}$ is in $W^{\perp}$.)

b. Take $\mathbf{z}_1$ and $\mathbf{z}_2$ in $W^{\perp}$, and let $\mathbf{u}$ be any element of W. Show that $\mathbf{z}_1 + \mathbf{z}_2$ is orthogonal to $\mathbf{u}$. What can you conclude about $\mathbf{z}_1 + \mathbf{z}_2$? Why?

c. Finish the proof that $W^{\perp}$ is a subspace of $\mathbb{R}^n$.

31. Show that if $\mathbf{x}$ is in both W and $W^{\perp}$, then $\mathbf{x} = \mathbf{0}$.

32. [**M**] Construct a pair $\mathbf{u}$, $\mathbf{v}$ of random vectors in $\mathbb{R}^4$, and let

$$A = \begin{bmatrix} .5 & .5 & .5 & .5 \\ .5 & .5 & -.5 & -.5 \\ .5 & -.5 & .5 & -.5 \\ .5 & -.5 & -.5 & .5 \end{bmatrix}$$

a. Denote the columns of A by $\mathbf{a}_1, \dots, \mathbf{a}_4$. Compute the length of each column, and compute $\mathbf{a}_1\cdot\mathbf{a}_2$, $\mathbf{a}_1\cdot\mathbf{a}_3$, $\mathbf{a}_1\cdot\mathbf{a}_4$, $\mathbf{a}_2\cdot\mathbf{a}_3$, $\mathbf{a}_2\cdot\mathbf{a}_4$, and $\mathbf{a}_3\cdot\mathbf{a}_4$.

b. Compute and compare the lengths of $\mathbf{u}$, $A\mathbf{u}$, $\mathbf{v}$, and $A\mathbf{v}$.

c. Use equation (2) in this section to compute the cosine of the angle between $\mathbf{u}$ and $\mathbf{v}$. Compare this with the cosine of the angle between $A\mathbf{u}$ and $A\mathbf{v}$.

d. Repeat parts (b) and (c) for two other pairs of random vectors. What do you conjecture about the effect of A on vectors?

33. [**M**] Generate random vectors $\mathbf{x}$, $\mathbf{y}$, and $\mathbf{v}$ in $\mathbb{R}^4$ with integer entries (and $\mathbf{v} \neq \mathbf{0}$), and compute the quantities

$$\left(\frac{\mathbf{x}\cdot\mathbf{v}}{\mathbf{v}\cdot\mathbf{v}}\right)\mathbf{v},\ \left(\frac{\mathbf{y}\cdot\mathbf{v}}{\mathbf{v}\cdot\mathbf{v}}\right)\mathbf{v},\ \frac{(\mathbf{x}+\mathbf{y})\cdot\mathbf{v}}{\mathbf{v}\cdot\mathbf{v}}\mathbf{v},\ \frac{(10\mathbf{x})\cdot\mathbf{v}}{\mathbf{v}\cdot\mathbf{v}}\mathbf{v}$$

Repeat the computations with new random vectors $\mathbf{x}$ and $\mathbf{y}$. What do you conjecture about the mapping $\mathbf{x} \mapsto T(\mathbf{x}) = \left(\frac{\mathbf{x}\cdot\mathbf{v}}{\mathbf{v}\cdot\mathbf{v}}\right)\mathbf{v}$ (for $\mathbf{v} \neq \mathbf{0}$)? Verify your conjecture algebraically.

34. [**M**] Let $A = \begin{bmatrix} -6 & 3 & -27 & -33 & -13 \\ 6 & -5 & 25 & 28 & 14 \\ 8 & -6 & 34 & 38 & 18 \\ 12 & -10 & 50 & 41 & 23 \\ 14 & -21 & 49 & 29 & 33 \end{bmatrix}$. Construct a matrix N whose columns form a basis for Nul A, and construct a matrix R whose *rows* form a basis for Row A (see Section 4.6 for details). Perform a matrix computation with N and R that illustrates a fact from Theorem 3.

SOLUTION

$$U\mathbf{x} = \begin{bmatrix} 1/\sqrt{2} & 2/3 \\ 1/\sqrt{2} & -2/3 \\ 0 & 1/3 \end{bmatrix}\begin{bmatrix} \sqrt{2} \\ 3 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$$

$$\|U\mathbf{x}\| = \sqrt{9+1+1} = \sqrt{11}$$

$$\|\mathbf{x}\| = \sqrt{2+9} = \sqrt{11}$$

Theorems 6 and 7 are particularly useful when applied to *square* matrices. An **orthogonal matrix** is a square invertible matrix U such that $U^{-1} = U^T$. By Theorem 6, such a matrix has orthonormal columns.[1] It is easy to see that any *square* matrix with orthonormal columns is an orthogonal matrix. Surprisingly, such a matrix must have orthonormal *rows*, too. See Exercises 27 and 28. Orthogonal matrices will appear frequently in Chapter 7.

EXAMPLE 7 The matrix

$$U = \begin{bmatrix} 3/\sqrt{11} & -1/\sqrt{6} & -1/\sqrt{66} \\ 1/\sqrt{11} & 2/\sqrt{6} & -4/\sqrt{66} \\ 1/\sqrt{11} & 1/\sqrt{6} & 7/\sqrt{66} \end{bmatrix}$$

is an orthogonal matrix because it is square and because its columns are orthonormal, by Example 5. Verify that the rows are orthonormal, too!

PRACTICE PROBLEMS

1. Let $\mathbf{u}_1 = \begin{bmatrix} -1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix}$ and $\mathbf{u}_2 = \begin{bmatrix} 2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix}$. Show that $\{\mathbf{u}_1, \mathbf{u}_2\}$ is an orthonormal basis for $\mathbb{R}^2$.
2. Let $\mathbf{y}$ and L be as in Example 3 and Fig. 3. Compute the orthogonal projection $\hat{\mathbf{y}}$ of $\mathbf{y}$ onto L using $\mathbf{u} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ instead of the $\mathbf{u}$ in Example 3.
3. Let U and $\mathbf{x}$ be as in Example 6, and let $\mathbf{y} = \begin{bmatrix} -3\sqrt{2} \\ 6 \end{bmatrix}$. Verify that $U\mathbf{x}\cdot U\mathbf{y} = \mathbf{x}\cdot\mathbf{y}$.

6.2 EXERCISES

In Exercises 1–6, determine which sets of vectors are orthogonal.

1. $\begin{bmatrix} -1 \\ 4 \\ -3 \end{bmatrix}, \begin{bmatrix} 5 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -4 \\ -7 \end{bmatrix}$

2. $\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix}$

3. $\begin{bmatrix} 2 \\ -7 \\ -1 \end{bmatrix}, \begin{bmatrix} -6 \\ -3 \\ 9 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix}$

4. $\begin{bmatrix} 2 \\ -5 \\ -3 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 \\ -2 \\ 6 \end{bmatrix}$

5. $\begin{bmatrix} 3 \\ -2 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 3 \\ -3 \\ 4 \end{bmatrix}, \begin{bmatrix} 3 \\ 8 \\ 7 \\ 0 \end{bmatrix}$

6. $\begin{bmatrix} 5 \\ -4 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} -4 \\ 1 \\ -3 \\ 8 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \\ 5 \\ -1 \end{bmatrix}$

In Exercises 7–10, show that $\{\mathbf{u}_1, \mathbf{u}_2\}$ or $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthogonal basis for $\mathbb{R}^2$ or $\mathbb{R}^3$, respectively. Then express $\mathbf{x}$ as a linear combination of the $\mathbf{u}$'s.

7. $\mathbf{u}_1 = \begin{bmatrix} 2 \\ -3 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} 6 \\ 4 \end{bmatrix}$, and $\mathbf{x} = \begin{bmatrix} 9 \\ -7 \end{bmatrix}$

[1] A better name might be *orthonormal matrix*, and this term is found in some statistics texts. However, *orthogonal matrix* is the standard term in linear algebra.

8. $\mathbf{u}_1 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -2 \\ 6 \end{bmatrix}$, and $\mathbf{x} = \begin{bmatrix} -6 \\ 3 \end{bmatrix}$

9. $\mathbf{u}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -1 \\ 4 \\ 1 \end{bmatrix}$, $\mathbf{u}_3 = \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}$, and $\mathbf{x} = \begin{bmatrix} 8 \\ -4 \\ -3 \end{bmatrix}$

10. $\mathbf{u}_1 = \begin{bmatrix} 3 \\ -3 \\ 0 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 2 \\ 2 \\ -1 \end{bmatrix}$, $\mathbf{u}_3 = \begin{bmatrix} 1 \\ 1 \\ 4 \end{bmatrix}$, and $\mathbf{x} = \begin{bmatrix} 5 \\ -3 \\ 1 \end{bmatrix}$

11. Compute the orthogonal projection of $\begin{bmatrix} 1 \\ 7 \end{bmatrix}$ onto the line through $\begin{bmatrix} -4 \\ 2 \end{bmatrix}$ and the origin.

12. Compute the orthogonal projection of $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ onto the line through $\begin{bmatrix} -1 \\ 3 \end{bmatrix}$ and the origin.

13. Let $\mathbf{y} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$ and $\mathbf{u} = \begin{bmatrix} 4 \\ -7 \end{bmatrix}$. Write $\mathbf{y}$ as the sum of two orthogonal vectors, one in Span $\{\mathbf{u}\}$ and one orthogonal to $\mathbf{u}$.

14. Let $\mathbf{y} = \begin{bmatrix} 2 \\ 6 \end{bmatrix}$ and $\mathbf{u} = \begin{bmatrix} 7 \\ 1 \end{bmatrix}$. Write $\mathbf{y}$ as the sum of a vector in Span $\{\mathbf{u}\}$ and a vector orthogonal to $\mathbf{u}$.

15. Let $\mathbf{y} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$ and $\mathbf{u} = \begin{bmatrix} 8 \\ 6 \end{bmatrix}$. Compute the distance from $\mathbf{y}$ to the line through $\mathbf{u}$ and the origin.

16. Let $\mathbf{y} = \begin{bmatrix} -3 \\ 9 \end{bmatrix}$ and $\mathbf{u} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$. Compute the distance from $\mathbf{y}$ to the line through $\mathbf{u}$ and the origin.

In Exercises 17–22, determine which sets of vectors are orthonormal. If a set is only orthogonal, normalize the vectors to produce an orthonormal set.

17. $\begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}, \begin{bmatrix} -1/2 \\ 0 \\ 1/2 \end{bmatrix}$

18. $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix}$

19. $\begin{bmatrix} -.6 \\ .8 \end{bmatrix}, \begin{bmatrix} .8 \\ .6 \end{bmatrix}$

20. $\begin{bmatrix} -2/3 \\ 1/3 \\ 2/3 \end{bmatrix}, \begin{bmatrix} 1/3 \\ 2/3 \\ 0 \end{bmatrix}$

21. $\begin{bmatrix} 1/\sqrt{10} \\ 3/\sqrt{20} \\ 3/\sqrt{20} \end{bmatrix}, \begin{bmatrix} 3/\sqrt{10} \\ -1/\sqrt{20} \\ -1/\sqrt{20} \end{bmatrix}, \begin{bmatrix} 0 \\ -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$

22. $\begin{bmatrix} 1/\sqrt{18} \\ 4/\sqrt{18} \\ 1/\sqrt{18} \end{bmatrix}, \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ -1/\sqrt{2} \end{bmatrix}, \begin{bmatrix} -2/3 \\ 1/3 \\ -2/3 \end{bmatrix}$

In Exercises 23 and 24, all vectors are in $\mathbb{R}^n$. Mark each statement True or False. Justify each answer.

23. a. Not every linearly independent set in $\mathbb{R}^n$ is an orthogonal set.

b. If $\mathbf{y}$ is a linear combination of nonzero vectors from an orthogonal set, then the weights in the linear combination can be computed without row operations on a matrix.

c. If the vectors in an orthogonal set of nonzero vectors are normalized, then some of the new vectors may not be orthogonal.

d. A matrix with orthonormal columns is an orthogonal matrix.

e. If L is a line through $\mathbf{0}$ and if $\hat{\mathbf{y}}$ is the orthogonal projection of $\mathbf{y}$ onto L, then $\|\hat{\mathbf{y}}\|$ gives the distance from $\mathbf{y}$ to L.

24. a. Not every orthogonal set in $\mathbb{R}^n$ is linearly independent.

b. If a set $S = \{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ has the property that $\mathbf{u}_i \cdot \mathbf{u}_j = 0$ whenever $i \neq j$, then S is an orthonormal set.

c. If the columns of an $m \times n$ matrix A are orthonormal, then the linear mapping $\mathbf{x} \mapsto A\mathbf{x}$ preserves lengths.

d. The orthogonal projection of $\mathbf{y}$ onto $\mathbf{v}$ is the same as the orthogonal projection of $\mathbf{y}$ onto $c\mathbf{v}$ whenever $c \neq 0$.

e. An orthogonal matrix is invertible.

25. Prove Theorem 7. [*Hint:* For (a), compute $\|U\mathbf{x}\|^2$, or prove (b) first.]

26. Suppose W is a subspace of $\mathbb{R}^n$ spanned by n nonzero orthogonal vectors. Explain why $W = \mathbb{R}^n$.

27. Let U be a square matrix with orthonormal columns. Explain why U is invertible. (Mention the theorems you use.)

28. Let U be an $n \times n$ orthogonal matrix. Show that the rows of U form an orthonormal basis of $\mathbb{R}^n$.

29. Let U and V be $n \times n$ orthogonal matrices. Explain why UV is an orthogonal matrix. [That is, explain why UV is invertible and its inverse is $(UV)^T$.]

30. Let U be an orthogonal matrix, and construct V by interchanging some of the columns of U. Explain why V is an orthogonal matrix.

31. Show that the orthogonal projection of a vector $\mathbf{y}$ onto a line L through the origin in $\mathbb{R}^2$ does not depend on the choice of the nonzero $\mathbf{u}$ in L used in the formula for $\hat{\mathbf{y}}$. To do this, suppose $\mathbf{y}$ and $\mathbf{u}$ are given and $\hat{\mathbf{y}}$ has been computed by formula (2) in this section. Replace $\mathbf{u}$ in that formula by $c\mathbf{u}$, where c is an unspecified nonzero scalar. Show that the new formula gives the same $\hat{\mathbf{y}}$.

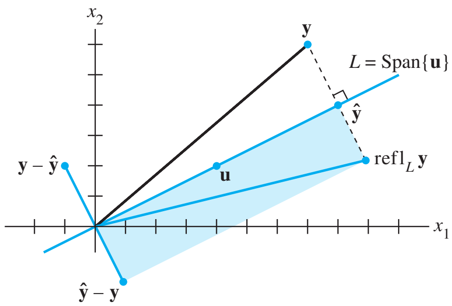
32. Let $\{\mathbf{v}_1, \mathbf{v}_2\}$ be an orthogonal set of nonzero vectors, and let c_1, c_2 be any nonzero scalars. Show that $\{c_1\mathbf{v}_1, c_2\mathbf{v}_2\}$ is also an orthogonal set. Since orthogonality of a set is defined in terms of pairs of vectors, this shows that if the vectors in an orthogonal set are normalized, the new set will still be orthogonal.

33. Given $\mathbf{u} \neq \mathbf{0}$ in $\mathbb{R}^n$, let $L = \text{Span}\{\mathbf{u}\}$. Show that the mapping $\mathbf{x} \mapsto \text{proj}_L\,\mathbf{x}$ is a linear transformation.

34. Given $\mathbf{u} \neq \mathbf{0}$ in $\mathbb{R}^n$, let $L = \text{Span}\{\mathbf{u}\}$. For $\mathbf{y}$ in $\mathbb{R}^n$, the **reflection of y in** L is the point $\text{refl}_L\,\mathbf{y}$ defined by

$\text{refl}_L\, \mathbf{y} = 2 \cdot \text{proj}_L\, \mathbf{y} - \mathbf{y}$

See the figure, which shows that $\text{refl}_L\, \mathbf{y}$ is the sum of $\hat{\mathbf{y}} = \text{proj}_L\, \mathbf{y}$ and $\hat{\mathbf{y}} - \mathbf{y}$. Show that the mapping $\mathbf{y} \mapsto \text{refl}_L\, \mathbf{y}$ is a linear transformation.



The reflection of $\mathbf{y}$ in a line through the origin.

35. [**M**] Show that the columns of the matrix A are orthogonal by making an appropriate matrix calculation. State the calculation you use.

$$A = \begin{bmatrix} -6 & -3 & 6 & 1 \\ -1 & 2 & 1 & -6 \\ 3 & 6 & 3 & -2 \\ 6 & -3 & 6 & -1 \\ 2 & -1 & 2 & 3 \\ -3 & 6 & 3 & 2 \\ -2 & -1 & 2 & -3 \\ 1 & 2 & 1 & 6 \end{bmatrix}$$

36. [**M**] In parts (a)–(d), let U be the matrix formed by normalizing each column of the matrix A in Exercise 35.

a. Compute U^TU and UU^T. How do they differ?

b. Generate a random vector $\mathbf{y}$ in $\mathbb{R}^8$, and compute $\mathbf{p} = UU^T\mathbf{y}$ and $\mathbf{z} = \mathbf{y} - \mathbf{p}$. Explain why $\mathbf{p}$ is in Col A. Verify that $\mathbf{z}$ is orthogonal to $\mathbf{p}$.

c. Verify that $\mathbf{z}$ is orthogonal to each column of U.

d. Notice that $\mathbf{y} = \mathbf{p} + \mathbf{z}$, with $\mathbf{p}$ in Col A. Explain why $\mathbf{z}$ is in $(\text{Col } A)^{\perp}$. (The significance of this decomposition of $\mathbf{y}$ will be explained in the next section.)

SOLUTIONS TO PRACTICE PROBLEMS

1. The vectors are orthogonal because

$$\mathbf{u}_1 \cdot \mathbf{u}_2 = -2/5 + 2/5 = 0$$

They are unit vectors because

$$\|\mathbf{u}_1\|^2 = (-1/\sqrt{5})^2 + (2/\sqrt{5})^2 = 1/5 + 4/5 = 1$$
$$\|\mathbf{u}_2\|^2 = (2/\sqrt{5})^2 + (1/\sqrt{5})^2 = 4/5 + 1/5 = 1$$

In particular, the set $\{\mathbf{u}_1, \mathbf{u}_2\}$ is linearly independent, and hence is a basis for $\mathbb{R}^2$ since there are two vectors in the set.

2. When $\mathbf{y} = \begin{bmatrix} 7 \\ 6 \end{bmatrix}$ and $\mathbf{u} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$,

$$\hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{u}}{\mathbf{u} \cdot \mathbf{u}}\mathbf{u} = \frac{20}{5}\begin{bmatrix} 2 \\ 1 \end{bmatrix} = 4\begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 8 \\ 4 \end{bmatrix}$$

This is the same $\hat{\mathbf{y}}$ found in Example 3. The orthogonal projection does not seem to depend on the $\mathbf{u}$ chosen on the line. See Exercise 31.

3. $$U\mathbf{y} = \begin{bmatrix} 1/\sqrt{2} & 2/3 \\ 1/\sqrt{2} & -2/3 \\ 0 & 1/3 \end{bmatrix}\begin{bmatrix} -3\sqrt{2} \\ 6 \end{bmatrix} = \begin{bmatrix} 1 \\ -7 \\ 2 \end{bmatrix}$$

Also, from Example 6, $\mathbf{x} = \begin{bmatrix} \sqrt{2} \\ 3 \end{bmatrix}$ and $U\mathbf{x} = \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$. Hence

$$U\mathbf{x} \cdot U\mathbf{y} = 3 + 7 + 2 = 12, \quad \text{and} \quad \mathbf{x} \cdot \mathbf{y} = -6 + 18 = 12$$

SG Mastering: Orthogonal Basis 6–4

PRACTICE PROBLEM

Let $\mathbf{u}_1 = \begin{bmatrix} -7 \\ 1 \\ 4 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -1 \\ 1 \\ -2 \end{bmatrix}$, $\mathbf{y} = \begin{bmatrix} -9 \\ 1 \\ 6 \end{bmatrix}$, and $W = \text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$. Use the fact that $\mathbf{u}_1$ and $\mathbf{u}_2$ are orthogonal to compute $\text{proj}_W \mathbf{y}$.

6.3 EXERCISES

In Exercises 1 and 2, you may assume that $\{\mathbf{u}_1, \ldots, \mathbf{u}_4\}$ is an orthogonal basis for $\mathbb{R}^4$.

1. $\mathbf{u}_1 = \begin{bmatrix} 0 \\ 1 \\ -4 \\ -1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 3 \\ 5 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{u}_3 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ -4 \end{bmatrix}$, $\mathbf{u}_4 = \begin{bmatrix} 5 \\ -3 \\ -1 \\ 1 \end{bmatrix}$, $\mathbf{x} = \begin{bmatrix} 10 \\ -8 \\ 2 \\ 0 \end{bmatrix}$. Write $\mathbf{x}$ as the sum of two vectors, one in Span $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ and the other in Span $\{\mathbf{u}_4\}$.

2. $\mathbf{u}_1 = \begin{bmatrix} 1 \\ 2 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -2 \\ 1 \\ -1 \\ 1 \end{bmatrix}$, $\mathbf{u}_3 = \begin{bmatrix} 1 \\ 1 \\ -2 \\ -1 \end{bmatrix}$, $\mathbf{u}_4 = \begin{bmatrix} -1 \\ 1 \\ 1 \\ -2 \end{bmatrix}$, $\mathbf{v} = \begin{bmatrix} 4 \\ 5 \\ -3 \\ 3 \end{bmatrix}$. Write $\mathbf{v}$ as the sum of two vectors, one in Span $\{\mathbf{u}_1\}$ and the other in Span $\{\mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$.

In Exercises 3–6, verify that $\{\mathbf{u}_1, \mathbf{u}_2\}$ is an orthogonal set, and then find the orthogonal projection of $\mathbf{y}$ onto Span $\{\mathbf{u}_1, \mathbf{u}_2\}$.

3. $\mathbf{y} = \begin{bmatrix} -1 \\ 4 \\ 3 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$

4. $\mathbf{y} = \begin{bmatrix} 6 \\ 3 \\ -2 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} 3 \\ 4 \\ 0 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -4 \\ 3 \\ 0 \end{bmatrix}$

5. $\mathbf{y} = \begin{bmatrix} -1 \\ 2 \\ 6 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}$

6. $\mathbf{y} = \begin{bmatrix} 6 \\ 4 \\ 1 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} -4 \\ -1 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$

In Exercises 7–10, let W be the subspace spanned by the $\mathbf{u}$'s, and write $\mathbf{y}$ as the sum of a vector in W and a vector orthogonal to W.

7. $\mathbf{y} = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 5 \\ 1 \\ 4 \end{bmatrix}$

8. $\mathbf{y} = \begin{bmatrix} -1 \\ 4 \\ 3 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -1 \\ 3 \\ -2 \end{bmatrix}$

9. $\mathbf{y} = \begin{bmatrix} 4 \\ 3 \\ 3 \\ -1 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -1 \\ 3 \\ 1 \\ -2 \end{bmatrix}$, $\mathbf{u}_3 = \begin{bmatrix} -1 \\ 0 \\ 1 \\ 1 \end{bmatrix}$

10. $\mathbf{y} = \begin{bmatrix} 3 \\ 4 \\ 5 \\ 6 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{u}_3 = \begin{bmatrix} 0 \\ -1 \\ 1 \\ -1 \end{bmatrix}$

In Exercises 11 and 12, find the closest point to $\mathbf{y}$ in the subspace W spanned by $\mathbf{v}_1$ and $\mathbf{v}_2$.

11. $\mathbf{y} = \begin{bmatrix} 3 \\ 1 \\ 5 \\ 1 \end{bmatrix}$, $\mathbf{v}_1 = \begin{bmatrix} 3 \\ 1 \\ -1 \\ 1 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}$

12. $\mathbf{y} = \begin{bmatrix} 3 \\ -1 \\ 1 \\ 13 \end{bmatrix}$, $\mathbf{v}_1 = \begin{bmatrix} 1 \\ -2 \\ -1 \\ 2 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} -4 \\ 1 \\ 0 \\ 3 \end{bmatrix}$

In Exercises 13 and 14, find the best approximation to $\mathbf{z}$ by vectors of the form $c_1\mathbf{v}_1 + c_2\mathbf{v}_2$.

13. $\mathbf{z} = \begin{bmatrix} 3 \\ -7 \\ 2 \\ 3 \end{bmatrix}$, $\mathbf{v}_1 = \begin{bmatrix} 2 \\ -1 \\ -3 \\ 1 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}$

14. $\mathbf{z} = \begin{bmatrix} 2 \\ 4 \\ 0 \\ -1 \end{bmatrix}$, $\mathbf{v}_1 = \begin{bmatrix} 2 \\ 0 \\ -1 \\ -3 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} 5 \\ -2 \\ 4 \\ 2 \end{bmatrix}$

15. Let $\mathbf{y} = \begin{bmatrix} 5 \\ -9 \\ 5 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} -3 \\ -5 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -3 \\ 2 \\ 1 \end{bmatrix}$. Find the distance from $\mathbf{y}$ to the plane in $\mathbb{R}^3$ spanned by $\mathbf{u}_1$ and $\mathbf{u}_2$.

16. Let $\mathbf{y}$, $\mathbf{v}_1$, and $\mathbf{v}_2$ be as in Exercise 12. Find the distance from $\mathbf{y}$ to the subspace of $\mathbb{R}^4$ spanned by $\mathbf{v}_1$ and $\mathbf{v}_2$.

17. Let $\mathbf{y} = \begin{bmatrix} 4 \\ 8 \\ 1 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} 2/3 \\ 1/3 \\ 2/3 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -2/3 \\ 2/3 \\ 1/3 \end{bmatrix}$, and $W = \text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$.

a. Let $U = [\,\mathbf{u}_1 \quad \mathbf{u}_2\,]$. Compute U^TU and UU^T.

b. Compute $\text{proj}_W\,\mathbf{y}$ and $(UU^T)\mathbf{y}$.

18. Let $\mathbf{y} = \begin{bmatrix} 7 \\ 9 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} 1/\sqrt{10} \\ -3/\sqrt{10} \end{bmatrix}$, and $W = \text{Span}\,\{\mathbf{u}_1\}$.

a. Let U be the 2×1 matrix whose only column is $\mathbf{u}_1$. Compute U^TU and UU^T.

b. Compute $\text{proj}_W\,\mathbf{y}$ and $(UU^T)\mathbf{y}$.

19. Let $\mathbf{u}_1 = \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 5 \\ -1 \\ 2 \end{bmatrix}$, and $\mathbf{u}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$. Note that $\mathbf{u}_1$ and $\mathbf{u}_2$ are orthogonal but that $\mathbf{u}_3$ is not orthogonal to $\mathbf{u}_1$ or $\mathbf{u}_2$. It can be shown that $\mathbf{u}_3$ is not in the subspace W spanned by $\mathbf{u}_1$ and $\mathbf{u}_2$. Use this fact to construct a nonzero vector $\mathbf{v}$ in $\mathbb{R}^3$ that is orthogonal to $\mathbf{u}_1$ and $\mathbf{u}_2$.

20. Let $\mathbf{u}_1$ and $\mathbf{u}_2$ be as in Exercise 19, and let $\mathbf{u}_4 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$. It can be shown that $\mathbf{u}_4$ is not in the subspace W spanned by $\mathbf{u}_1$ and $\mathbf{u}_2$. Use this fact to construct a nonzero vector $\mathbf{v}$ in $\mathbb{R}^3$ that is orthogonal to $\mathbf{u}_1$ and $\mathbf{u}_2$.

In Exercises 21 and 22, all vectors and subspaces are in $\mathbb{R}^n$. Mark each statement True or False. Justify each answer.

21. a. If $\mathbf{z}$ is orthogonal to $\mathbf{u}_1$ and to $\mathbf{u}_2$ and if $W = \text{Span}\,\{\mathbf{u}_1, \mathbf{u}_2\}$, then $\mathbf{z}$ must be in $W^{\perp}$.

b. For each $\mathbf{y}$ and each subspace W, the vector $\mathbf{y} - \text{proj}_W\,\mathbf{y}$ is orthogonal to W.

c. The orthogonal projection $\hat{\mathbf{y}}$ of $\mathbf{y}$ onto a subspace W can sometimes depend on the orthogonal basis for W used to compute $\hat{\mathbf{y}}$.

d. If $\mathbf{y}$ is in a subspace W, then the orthogonal projection of $\mathbf{y}$ onto W is $\mathbf{y}$ itself.

e. If the columns of an $n \times p$ matrix U are orthonormal, then $UU^T\mathbf{y}$ is the orthogonal projection of $\mathbf{y}$ onto the column space of U.

22. a. If W is a subspace of $\mathbb{R}^n$ and if $\mathbf{v}$ is in both W and $W^{\perp}$, then $\mathbf{v}$ must be the zero vector.

b. In the Orthogonal Decomposition Theorem, each term in formula (2) for $\hat{\mathbf{y}}$ is itself an orthogonal projection of $\mathbf{y}$ onto a subspace of W.

c. If $\mathbf{y} = \mathbf{z}_1 + \mathbf{z}_2$, where $\mathbf{z}_1$ is in a subspace W and $\mathbf{z}_2$ is in $W^{\perp}$, then $\mathbf{z}_1$ must be the orthogonal projection of $\mathbf{y}$ onto W.

d. The best approximation to $\mathbf{y}$ by elements of a subspace W is given by the vector $\mathbf{y} - \text{proj}_W\,\mathbf{y}$.

e. If an $n \times p$ matrix U has orthonormal columns, then $UU^T\mathbf{x} = \mathbf{x}$ for all $\mathbf{x}$ in $\mathbb{R}^n$.

23. Let A be an $m \times n$ matrix. Prove that every vector $\mathbf{x}$ in $\mathbb{R}^n$ can be written in the form $\mathbf{x} = \mathbf{p} + \mathbf{u}$, where $\mathbf{p}$ is in Row A and $\mathbf{u}$ is in Nul A. Also, show that if the equation $A\mathbf{x} = \mathbf{b}$ is consistent, then there is a unique $\mathbf{p}$ in Row A such that $A\mathbf{p} = \mathbf{b}$.

24. Let W be a subspace of $\mathbb{R}^n$ with an orthogonal basis $\{\mathbf{w}_1, \ldots, \mathbf{w}_p\}$, and let $\{\mathbf{v}_1, \ldots, \mathbf{v}_q\}$ be an orthogonal basis for $W^{\perp}$.

a. Explain why $\{\mathbf{w}_1, \ldots, \mathbf{w}_p, \mathbf{v}_1, \ldots, \mathbf{v}_q\}$ is an orthogonal set.

b. Explain why the set in part (a) spans $\mathbb{R}^n$.

c. Show that $\dim W + \dim W^{\perp} = n$.

25. [**M**] Let U be the 8×4 matrix in Exercise 36 in Section 6.2. Find the closest point to $\mathbf{y} = (1, 1, 1, 1, 1, 1, 1, 1)$ in Col U. Write the keystrokes or commands you use to solve this problem.

26. [**M**] Let U be the matrix in Exercise 25. Find the distance from $\mathbf{b} = (1, 1, 1, 1, -1, -1, -1, -1)$ to Col U.

SOLUTION TO PRACTICE PROBLEM

Compute

$$\text{proj}_W\,\mathbf{y} = \frac{\mathbf{y}\cdot\mathbf{u}_1}{\mathbf{u}_1\cdot\mathbf{u}_1}\mathbf{u}_1 + \frac{\mathbf{y}\cdot\mathbf{u}_2}{\mathbf{u}_2\cdot\mathbf{u}_2}\mathbf{u}_2 = \frac{88}{66}\mathbf{u}_1 + \frac{-2}{6}\mathbf{u}_2$$

$$= \frac{4}{3}\begin{bmatrix} -7 \\ 1 \\ 4 \end{bmatrix} - \frac{1}{3}\begin{bmatrix} -1 \\ 1 \\ -2 \end{bmatrix} = \begin{bmatrix} -9 \\ 1 \\ 6 \end{bmatrix} = \mathbf{y}$$

In this case, $\mathbf{y}$ happens to be a linear combination of $\mathbf{u}_1$ and $\mathbf{u}_2$, so $\mathbf{y}$ is in W. The closest point in W to $\mathbf{y}$ is $\mathbf{y}$ itself.