GRMON3

A debug monitor for LEON-based computer systems and SOC designs based on the GRLIB IP library

2020 User's Manual

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COBHAM
ADVANCED ELECTRONIC SOLUTIONS

GRMON3 User's Manual

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1. Introduction

1.1. Overview

GRMON is a general debug monitor for the LEON (SPARC V7/V8) processor, NOEL-V (RISC-V) and for SOC designs based on the GRLIB IP library. GRMON includes the following functions:

- Read/write access to all system registers and memory
- Built-in disassembler and trace buffer management
- Downloading and execution of LEON applications
- Breakpoint and watchpoint management
- Remote connection to GNU debugger (GDB)
- Support for USB, JTAG, UART, Ethernet and SpaceWire debug links
- Tcl interface (scripts, procedures, variables, loops etc.)
- Graphical user interface

1.2. Supported platforms and system requirements

GRMON is currently provided for platforms: Linux (GLIBC >2.11), Windows 7 and Windows 10. To run the GUI Java 8 is required. Both 32-bit and 64-bit versions are supported.

The professional version use a Sentinel LDK license key which has additional system requirements, which can be found the the readme that is included in Sentinel LDK Runtime installation package. See Appendix E, *License key installation* for more information.

The available debug communication links for each platform vary and they may have additional third-party dependencies that have additional system requirements. See Chapter 5, *Debug link* for more information.

1.3. Obtaining GRMON

The primary site for GRMON is Cobham Gaisler website [http://www.gaisler.com/], where the latest version of GRMON can be ordered and evaluation versions downloaded.

1.4. Installation

Follow these steps to install GRMON. Detailed information can be found futher down.

1. Extract the archive
2. Install the Sentinel LDK Runtime (GRMON Pro version only)
3. Optionally install third-party drivers for the debug interfaces.
4. Optionally setup the path for shared libraries (Linux only)
5. Optionally add GRMON to the environment variable PATH

To install GRMON, extract the archive anywhere on the host computer. The archive contains a directory for each OS that GRMON supports. Each OS-folder contains additional directories as described in the list below. The 32-bit and 64-bit version of each OS can be installed in parallel by extracting the archive to the same location.

```
grmon-pro-3.2.XX/<OS>/bin<BITS>
grmon-pro-3.2.XX/<OS>/lib<BITS>
grmon-pro-3.2.XX/<OS>/share
```

The professional version use a Sentinel LDK license key. See Appendix E, *License key installation* for installation of the Sentinel LDK runtime.

Some debug interfaces requires installation of third-party drivers, see Chapter 5, *Debug link* for more information.

The bin<BITS> directory contains the executable. For convenience it is recommended to add the bin<BITS> directory of the host OS to the environment variable PATH. See Appendix F, *Appending environment variables* for instructions on how to append environment variables.

To be able to run the GUI, it is required to install the same bitness version of GRMON as the Java installation. It is still possible to run both bit-versions of GRMON with the GUI. I.e to run GRMON 32-bit with a Java 64-bit, install both bit-versions of GRMON.

The `lib<BITS>` directory contains some additional libraries that GRMON requires. On the Windows platform the `lib<BITS>` directory is not available. On the Linux platform, if GRMON fails to start because of some missing libraries that are located in this directory, then add this path to the environment variable `LD_LIBRARY_PATH` or add it the `ld.so.cache` (see man pages about ldconfig for more information).

GRMON must find the `share` directory to work properly. GRMON will try to automatically detect the location of the folder. A warning will be printed when starting GRMON if it fails to find the `share` folder. If it fails to automatically detect the folder, then the environment variable `GRMON_SHARE` can be set to point the `share/ grmon` folder. For example on Windows it could be set to `c:\opt\grmon-pro\windows\share\grmon` or on Linux it could be set to `/opt/grmon-pro/linux/share/grmon`.

1.5. License

The GRMON license file can be found in the share folder of the installation. For example on Windows it can be found in `c:\opt\grmon-pro\windows\share\grmon` or on Linux it could be found in `/opt/gr-mon-pro/linux/share/grmon`.

1.6. NOEL-V Support

Only the evaluation version of GRMON supports the NOEL-V processor. The NOEL-V support is for the the December 2019 release and the June 2020 release of the NOEL-V processor. Additional features will be added in the future, including support in pro version of GRMON.

Many examples in this manual shows output from a LEON target system, however many of the commands will work with NOEL-V aswell.

See the NOEL-XCKU-EX Quick-start guide (noel-xcku-ex-qsg.pdf) for additional infomration on how use GR-MON with the NOEL-V.

1.6.1. Limitations

• Backtrace requires DWARF information.
• No specific GUI support
• No support for commands **ahb**, **attach**, **detach**, **float**
• No support for switches `-nb`, `-nswb`, `-dsudelay`, `-nic`, `-ndc`, `-mpgsz`

1.7. GRMON Evaluation version

The evaluation version of GRMON can be downloaded from Cobham Gaisler website [http://www.gaisler.com/]. The evaluation version may be used during a period of 21 days without purchasing a license. After this period, any commercial use of GRMON is not permitted without a valid license. The following features are *not* available in the evaluation version:

• GUI
• Support for LEON2, LEON3-FT, LEON4
• GRLIB commercial licensed cores
• FT support
• Custom JTAG configuration
• Profiling
• TCL API (drivers, init scripts, hooks, I/O forward to TCL channel etc)

1.8. Problem reports

Please send bug reports or comments to support@gaisler.com.

Customers with a valid support agreement may send questions to support@gaisler.com. Include a GRMON log when sending questions, please. A log can be obtained by starting GRMON with the command line switch -log *filename*.

The leon_sparc community at Yahoo may also be a source to find solutions to problems.

2. Debugging concept

2.1. Overview

The GRMON debug monitor is intended to debug system-on-chip (SOC) designs based on the LEON or NOEL-V processor. The monitor connects to a dedicated debug interface on the target hardware, through which it can perform read and write cycles on the on-chip bus (AHB). The debug interface can be of various types: the processor supports debugging over a serial UART, 32-bit PCI, JTAG, Ethernet and SpaceWire (using the GRESB Ethernet to SpaceWire bridge) debug interfaces. On the target system, all debug interfaces are realized as AHB masters with the Debug protocol implemented in hardware. There is thus no software support necessary to debug a target system, and a target system does in fact not even need to have a processor present.
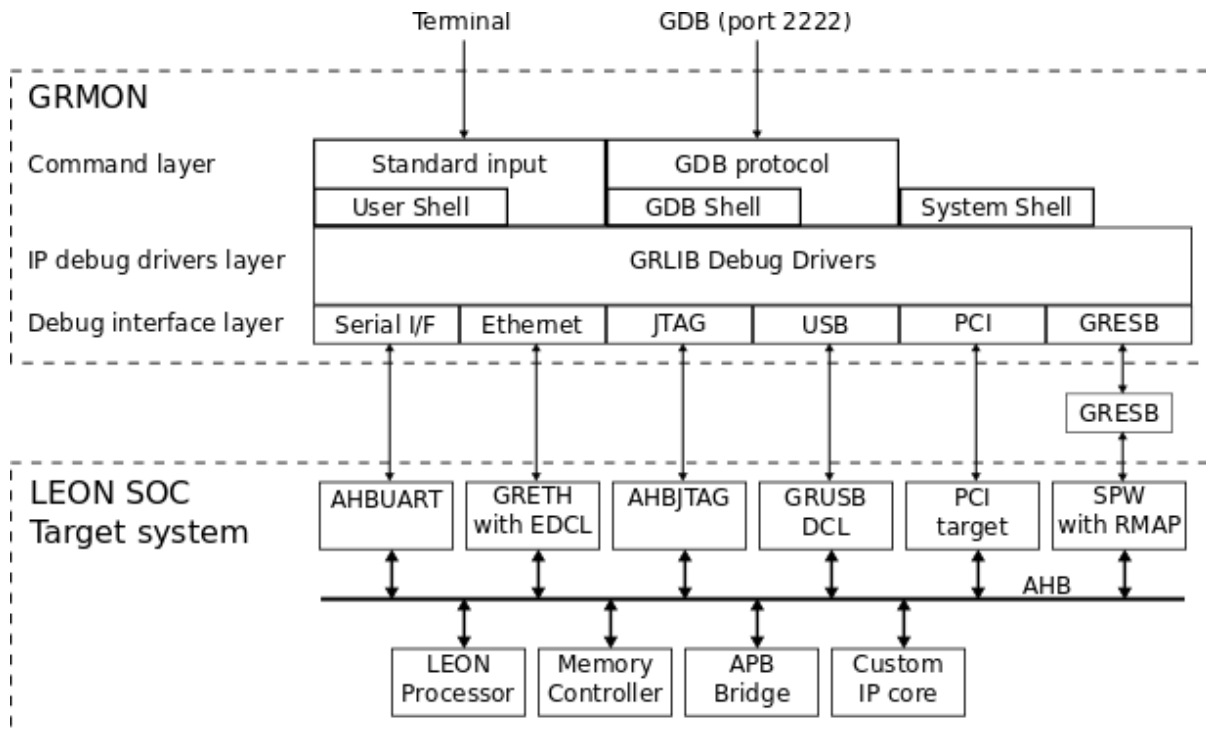
Figure 2.1. GRMON concept overview

GRMON can operate in two modes: command-line mode and GDB mode. In command-line mode, GRMON commands are entered manually through a terminal window. In GDB mode, GRMON acts as a GDB gateway and translates the GDB extended-remote protocol to debug commands on the target system.

GRMON is implemented using three functional layers: command layer, debug driver layer, and debug interface layer. The command layer takes input from the user and parses it in a Tcl Shell. It is also possible to start a GDB server service, which has its own shell, that takes input from GDB. Each shell has it own set of commands and variables. Many commands depends on drivers and will fail if the core is note present in the target system. More information about Tcl integration can be found in the Section 3.5, "Tcl integration".

The debug driver layer implements drivers that probes and initializes the cores. GRMON will scan the target system at start-up and detect which IP cores are present. The drivers may also provides information to the commands.

The debug interface layer implements the debug link protocol for each supported debug interface. Which interface to use for a debug session is specified through command line options during the start of GRMON. Only interfaces based on JTAG supports 8-/16-bit accesses, all other interfaces access subwords using read-modify-write. 32-bit accesses are supported by all interfaces. More information can be found in Chapter 5, *Debug link*.

2.2. Target initialization

When GRMON first connects to the target system, it scans the system to detect which IP cores are present. This is done by reading the plug and play information which is normally located at address 0xffffff000 on the AHB bus. A

debug driver for each recognized IP core is then initialized, and performs a core-specific initialization sequence if required. For a memory controller, the initialization sequence would typically consist of a memory probe operation to detect the amount of attached RAM. For a UART, it could consist of initializing the baud rate generator and flushing the FIFOs. After the initialization is complete, the system configuration is printed:

```
GRMON3 LEON debug monitor v3.0.0 32-bit professional version

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Comments or bug-reports to support@gaisler.com


GRLIB build version: 4111
Detected frequency:  40 MHz

Component                         Vendor
LEON3 SPARC V8 Processor          Cobham Gaisler
AHB Debug UART                    Cobham Gaisler
JTAG Debug Link                   Cobham Gaisler
GRSPW2 SpaceWire Serial Link      Cobham Gaisler
LEON2 Memory Controller           European Space Agency
AHB/APB Bridge                    Cobham Gaisler
LEON3 Debug Support Unit          Cobham Gaisler
Generic UART                      Cobham Gaisler
Multi-processor Interrupt Ctrl.   Cobham Gaisler
Modular Timer Unit                Cobham Gaisler
General Purpose I/O port          Cobham Gaisler

Use command 'info sys' to print a detailed report of attached cores

grmon3>
```

More detailed system information can be printed using the '**info sys**' command as listed below. The detailed system view also provides information about address mapping, interrupt allocation and IP core configuration. Information about which AMBA AHB and APB buses a core is connected to can be seen by adding the -v option. GRMON assigns a unique name to all cores, the core name is printed to the left. See Appendix C, *Tcl API* for information about Tcl variables and device names.

```
grmon3> info sys
  cpu0      Cobham Gaisler  LEON3 SPARC V8 Processor
            AHB Master 0
  ahbuart0  Cobham Gaisler  AHB Debug UART
            AHB Master 1
            APB: 80000700 - 80000800
            Baudrate 115200, AHB frequency 40000000.00
  ahbjtag0  Cobham Gaisler  JTAG Debug Link
            AHB Master 2
  grspw0    Cobham Gaisler  GRSPW2 SpaceWire Serial Link
            AHB Master 3
            APB: 80000A00 - 80000B00
            IRQ: 10
            Number of ports: 1
  mctrl0    European Space Agency  LEON2 Memory Controller
            AHB: 00000000 - 20000000
            AHB: 20000000 - 40000000
            AHB: 40000000 - 80000000
            APB: 80000000 - 80000100
            8-bit prom @ 0x00000000
            32-bit sdram: 1 * 64 Mbyte @ 0x40000000
            col 9, cas 2, ref 7.8 us
  apbmst0   Cobham Gaisler  AHB/APB Bridge
            AHB: 80000000 - 80100000
  dsu0      Cobham Gaisler  LEON3 Debug Support Unit
            AHB: 90000000 - A0000000
            AHB trace: 128 lines, 32-bit bus
            CPU0:  win 8, hwbp 2, itrace 128, V8 mul/div, srmmu, lddel 1
                   stack pointer 0x43fffff0
                   icache 2 * 4096 kB, 32 B/line lru
                   dcache 1 * 4096 kB, 16 B/line
  uart0     Cobham Gaisler  Generic UART
            APB: 80000100 - 80000200
            IRQ: 2
            Baudrate 38461
  irqmp0    Cobham Gaisler  Multi-processor Interrupt Ctrl.
            APB: 80000200 - 80000300
  gptimer0  Cobham Gaisler  Modular Timer Unit
            APB: 80000300 - 80000400
            IRQ: 8
            8-bit scalar, 2 * 32-bit timers, divisor 40
```

```
grgpio0   Cobham Gaisler  General Purpose I/O port
          APB: 80000800 - 80000900
```

2.2.1. LEON2 target initialization

The plug and play information was introduced in the LEON3 processor (GRLIB), and is not available for LEON2 systems. LEON2 is supported by starting GRMON with the `-sys leon2` switch or one of the switches that correspond to a known LEON2 device, see Section 6.12, "LEON2 support".

A LEON2 system has a fixed set of IP cores and address mapping. GRMON will use an internal plug and play table that describes this configuration. The plug and play table used for LEON2 is fixed, and no automatic detection of present cores is attempted. Only those cores that need to be initialized by GRMON are included in the table, so the listing might not correspond to the actual target. It is however possible to load a custom configuration file that describes the target system configuration using see Section 2.2.2, "Configuration file target initialization"

2.2.2. Configuration file target initialization

It is possible to provide GRMON with a configuration file that describes a static configuration by starting GRMON with the switch `-cfg filename`.

The format of the plug and play configuration file is described in section Appendix D, *Fixed target configuration file format*. It can be used for both LEON3 and LEON2 systems. An example configuration file is also supplied with the GRMON professional distribution in share/src/cfg/leon3.xml.

2.3. Memory register reset values

To ensure that the memory registers has sane values, GRMON will reset the registers when commands that access the memories are issued, for example **run**, **load** commands and similar commands. To modify the reset values, use the commands listed in Section 6.14.2, "Commands".

2.4. Hardware reset

The behaviour of GRMON will be undefined after a hardware resets signal is asserted. Most debug links will drop the connection, but some will remain connected, for example JTAG. Therefor it is recommended that you always restart GRMON after a reset signal has been assteted.

3. Operation

This chapter describes how GRMON can be controlled by the user in a terminal based interactive debug session and how it can be automated with scripts for batch execution. The first sections describe and exemplifies typical operations for interactive use. The later sections describe automation concepts. Most interactive commands are applicable also for automated use.

GRMON graphical user interface is described in Chapter 4, *Graphical user interface*.

3.1. Overview

An interactive GRMON debug session typically consists of the following steps:

1. Starting GRMON and attaching to the target system
2. Examining the hardware configuration
3. Uploading application program
4. Setup debugging, for example insert breakpoints and watchpoints
5. Executing the application
6. Debugging the application and examining the CPU and hardware state

Step 2 though 6 is performed using the GRMON terminal interface or by attaching GDB and use the standard GDB interface. The GDB section describes how GRMON specific commands are accessed from GDB.

The following sections will give an overview how the various steps are performed.

3.2. Starting GRMON

On a Linux host, GRMON is started by giving the **grmon** command together with command line options in a terminal window. It can run either the GUI or a commandline interface depending on if a debug link option is provided or not.

On Windows hosts, there are two executable provided. The file **grmon.exe** is intended to be started in a Windows command prompt (**cmd.exe**). It can run either the GUI or a commandline interface depending on if a debug link option is provided or not. The executable **grmon-gui.exe** will always spawn a gui.

Command line options are grouped by function as indicated below.

- The debug link options: setting up a connection to GRLIB target
- General options: debug session behavior options
- Debug driver options: configure the hardware, skip core auto-probing etc.

If any debug-link option is given to **grmon** or **grmon.exe**, then the GRMON command line interface will be started.

If *no* debug-link option is given to **grmon** or **grmon.exe**, then the GRMON graphical user interface will be started. For more information, see Chapter 4, *Graphical user interface*.

Below is an example of GRMON connecting to a GR712 evaluation board using the FTDI USB serial interface, tunneling the UART output of APBUART0 to GRMON and specifying three RAM wait states on read and write:

```
$ grmon -ftdi -u -ramws 3
```

To connect to a target using the AHBUART debug link, the following example can be used:

```
$ grmon -uart -u
```

The `-uart` option uses the first UART of the host (ttyS0 or COM1) with a baud rate of 115200 baud by default.

3.2.1. Debug link options

GRMON connects to a GRLIB target using one debug link interface, the command line options selects which interface the PC uses to connect to the target and optionally how the debug link is configured. All options are described in Chapter 5, *Debug link*.

3.2.2. Debug driver options

The debug drivers provide an interface to view and access AMBA devices during debugging and they offer device specific ways to configure the hardware when connecting and before running the executable. Drivers usually auto-probe their devices for optimal configuration values, however sometimes it is useful to override the auto-probed values. Some options affects multiple drivers. The debug driver options are described in Chapter 6, *Debug drivers*.

3.2.3. General options

The general options are mostly target independent options configuring the behavior of GRMON. Some of them affects how the target system is accessed both during connection and during the whole debugging session. All general options are described below.

grmon [options]

Options:

-abaud *baudrate*
> Set baud-rate for all UARTs in the system, (except the debug-link UART). By default, 38400 baud is used.

-ambamb *[maxbuses]*
> Enable auto-detection of AHBCTRL_MB system and (optionally) specifies the maximum number of buses in the system if an argument is given. The optional argument to -ambamb is decoded as below:
> 0, 1: No Multi-bus (MB) (max one bus)
> 2..3: Limit MB support to 2 or 3 AMBA PnP buses
> 4 or no argument: Selects Full MB support

-c *filename*
> Run the commands in the batch file at start-up.

-cfg *filename*
> Load fixed PnP configuration from a xml-file.

-echo
> Echo all the commands in the batch file at start-up. Has no effect unless -c is also set.

-edac
> Enable EDAC operation in memory controllers that support it.

-freq *sysclk*
> Overrides the detected system frequency. The frequency is specified in MHz.

-gdb *[port]*
> Listen for GDB connection directly at start-up. Optionally specify the port number for GDB communications. Default port number is 2222.

-gui
> Start the GRMON graphical user interface. This option must be combined with an option which specifies the debug-link to use. See Chapter 4, *Graphical user interface* for more information.

-ioarea *address*
> Specify the location of the I/O area. (Default is 0xfff00000).

-log *filename*
> Log session to the specified file. If the file already exists the new session is appended. This should be used when requesting support.

-ni
> Read plug n' play and detect all system device, but don't do any target initialization. See Section 3.4.11, "Attaching to a target system without initialization" for more information.

-nopnp
> Disable the plug n' play scanning. GRMON won't detect any hardware and any hardware dependent functionality won't work.

-u *[device]*
> Put UART 1 in FIFO debug mode if hardware supports it, else put it in loop-back mode. Debug mode will enable both reading and writing to the UART from the monitor console. Loop-back mode will only enable reading. See Section 3.9, "Forwarding application console I/O". The optional device parameter is used to select a specific UART to be put in debug mode. The device parameter is an index starting with 0 for the first UART and then increasing with one in the order they are found in the bus scan. If the device parameter is not used the first UART is selected.

-ucli *[device]*
> Put UART in debug or loop-back mode to forward application console I/O to GRMON CLI on startup. The command line shell will be used for forwarding instead of the regular prompt. See Section 3.9, "Forwarding application console I/O". The optional device parameter is used to select a specific UART to be put in debug mode. The device parameter is an index starting with 0 for the first UART and then increasing with one in the order they are found in the bus scan. If the device parameter is not used the first UART is selected.

-udm *[device]*
> Put UART 1 in FIFO debug mode if hardware supports it. Debug mode will enable both reading and writing to the UART from the monitor console. See Section 3.9, "Forwarding application console I/O". The optional device parameter is used to select a specific UART to be put in debug mode. The device parameter is an index starting with 0 for the first UART and then increasing with one in the order they are found in the bus scan. If the device parameter is not used the first UART is selected.

-ulb *[device]*
> Put UART 1 in loop-back mode. Loop-back mode will only enable reading from the UART to the monitor console. See Section 3.9, "Forwarding application console I/O". The optional device parameter is used to select a specific UART to be put in debug mode. The device parameter is an index starting with 0 for the first UART and then increasing with one in the order they are found in the bus scan. If the device parameter is not used the first UART is selected.

-ucmd *filename*
> Load script specified by filename into all shells, including the system shell.

-udrv *filename*
> Load script specified by filename into system shell.

3.3. GRMON command-line interface (CLI)

The GRMON3 command-line interface features a Tcl 8.6 interpreter which will interpret all entered commands substituting variables etc. before GRMON is actually called. Variables exported by GRMON can also be used to access internal states and hardware registers without going through commands. The GRMON Tcl interface is described in Section 3.5, "Tcl integration".

Short forms of the commands are allowed, e.g lo, loa, or load, are all interpreted as load. Tab completion is available for commands, Tcl variables, text-symbols, file names, etc.

The commands can be separated in to three categories:

- Tcl internal commands and reserved key words
- GRMON built-in commands always available regardless of target
- GRMON commands accessing debug drivers

Tcl internal and GRMON built-in commands are available regardless of target hardware present whereas debug driver commands may only be present on supported systems. The Tcl and driver commands are described in Section 3.5, "Tcl integration" and Chapter 6, *Debug drivers* respectively. In Table 3.1 is a summary of all GRMON built-in commands. For the full list of commands, see Appendix A, *Command index*.

Table 3.1. BUILT-IN commands

amem	Asynchronous bus read
batch	Execute batch script
bdump	Dump memory to a file
bload	Load a binary file
disassemble	Disassemble memory
dtb	Setup a DTB to be uploaded or print filenames of DTB files
dump	Dump memory to a file
dwarf	print or lookup dwarf information
eeload	Load a file into an EEPROM
execsh	Run commands in the execution shell

exit	Exit GRMON
gdb	Controll the builtin GDB remote server
gui	Control the graphical user interface
help	Print all commands or detailed help for a specific command
info	Show information
load	Load a file or print filenames of uploaded files
memb	AMBA bus 8-bit memory read access, list a range of addresses
memd	AMBA bus 64-bit memory read access, list a range of addresses
memh	AMBA bus 16-bit memory read access, list a range of addresses
mem	AMBA bus 32-bit memory read access, list a range of addresses
nolog	Suppress stdout of a command
quit	Quit the GRMON console
reset	Reset drivers
rtg4fddr	Print initialization sequence
rtg4serdes	Print initialization sequence
sf2mddr	Print initialization sequence
sf2serdes	Print initialization sequence
shell	Execute shell process
silent	Suppress stdout of a command
symbols	Load, print or lookup symbols
tps	Control the TPS service
usrsh	Run commands in threaded user shell
verify	Verify that a file has been uploaded correctly
wash	Clear or set memory areas
wmemb	AMBA bus 8-bit memory write access
wmemd	AMBA bus 64-bit memory write access
wmemh	AMBA bus 16-bit memory write access
wmems	Write a string to an AMBA bus memory address
wmem	AMBA bus 32-bit memory write access

3.4. Common debug operations

This section describes and gives some examples of how GRMON is typically used, the full command reference can be found in Appendix A, *Command index*.

3.4.1. Examining the hardware configuration

When connecting for the first time it is essential to verify that GRMON has auto-detected all devices and their configuration correctly. At start-up GRMON will print the cores and the frequency detected. From the command line one can examine the system by executing **info sys** as below:

```
grmon3> info sys
  cpu0      Cobham Gaisler  LEON3-FT SPARC V8 Processor
            AHB Master 0
  cpu1      Cobham Gaisler  LEON3-FT SPARC V8 Processor
            AHB Master 1
  greth0    Cobham Gaisler  GR Ethernet MAC
            AHB Master 3
            APB: 80000E00 - 80000F00
            IRQ: 14
  grspw0    Cobham Gaisler  GRSPW2 SpaceWire Serial Link
            AHB Master 5
            APB: 80100800 - 80100900
```

```
            IRQ: 22
            Number of ports: 1
  grspw1    Cobham Gaisler  GRSPW2 SpaceWire Serial Link
            AHB Master 6
            APB: 80100900 - 80100A00
            IRQ: 23
            Number of ports: 1
  mctrl0    Cobham Gaisler  Memory controller with EDAC
            AHB: 00000000 - 20000000
            AHB: 20000000 - 40000000
            AHB: 40000000 - 80000000
            APB: 80000000 - 80000100
            8-bit prom @ 0x00000000
            32-bit static ram: 1 * 8192 kbyte @ 0x40000000
            32-bit sdram: 2 * 128 Mbyte @ 0x60000000
            col 10, cas 2, ref 7.8 us
  apbmst0   Cobham Gaisler  AHB/APB Bridge
            AHB: 80000000 - 80100000
  dsu0      Cobham Gaisler  LEON3 Debug Support Unit
            AHB: 90000000 - A0000000
            AHB trace: 256 lines, 32-bit bus
            CPU0:  win 8, hwbp 2, itrace 256, V8 mul/div, srmmu, lddel 1, GRFPU
                   stack pointer 0x407ffff0
                   icache 4 * 4096 kB, 32 B/line lru
                   dcache 4 * 4096 kB, 16 B/line lru
            CPU1:  win 8, hwbp 2, itrace 256, V8 mul/div, srmmu, lddel 1, GRFPU
                   stack pointer 0x407ffff0
                   icache 4 * 4096 kB, 32 B/line lru
                   dcache 4 * 4096 kB, 16 B/line lru
  uart0     Cobham Gaisler  Generic UART
            APB: 80000100 - 80000200
            IRQ: 2
            Baudrate 38461, FIFO debug mode
  irqmp0    Cobham Gaisler  Multi-processor Interrupt Ctrl.
            APB: 80000200 - 80000300
            EIRQ: 12
  gptimer0  Cobham Gaisler  Modular Timer Unit
            APB: 80000300 - 80000400
            IRQ: 8
            16-bit scalar, 4 * 32-bit timers, divisor 80
  grgpio0   Cobham Gaisler  General Purpose I/O port
            APB: 80000900 - 80000A00
  uart1     Cobham Gaisler  Generic UART
            APB: 80100100 - 80100200
            IRQ: 17
            Baudrate 38461
...
```

The memory section for example tells us that GRMON are using the correct amount of memory and memory type. The parameters can be tweaked by passing memory driver specific options on start-up, see Section 3.2, "Starting GRMON". The current memory settings can be viewed in detail by listing the registers with **info reg** or by accessing the registers by the Tcl variables exported by GRMON:

```
grmon3> info sys
 ...
  mctrl0    Cobham Gaisler  Memory controller with EDAC
            AHB: 00000000 - 20000000
            AHB: 20000000 - 40000000
            AHB: 40000000 - 80000000
            APB: 80000000 - 80000100
            8-bit prom @ 0x00000000
            32-bit static ram: 1 * 8192 kbyte @ 0x40000000
            32-bit sdram: 2 * 128 Mbyte @ 0x60000000
            col 10, cas 2, ref 7.8 us
 ...
 grmon3> info reg
 ...
  Memory controller with EDAC
      0x80000000  Memory config register 1            0x1003c0ff
      0x80000004  Memory config register 2            0x9ac05463
      0x80000008  Memory config register 3            0x0826e000
 ...
grmon3> puts [format 0x%08x $mctrl0::           [TAB-COMPLETION]
mctrl0::mcfg1    mctrl0::mcfg2    mctrl0::mcfg3    mctrl0::pnp::
mctrl0::mcfg1::  mctrl0::mcfg2::  mctrl0::mcfg3::
grmon3> puts [format 0x%08x $mctrl0::mcfg1]
  0x0003c0ff

grmon3> puts [format 0x%08x $mctrl0::mcfg2 ::       [TAB-COMPLETION]
mctrl0::mcfg2::d64         mctrl0::mcfg2::sdramcmd
mctrl0::mcfg2::rambanksz   mctrl0::mcfg2::sdramcolsz
mctrl0::mcfg2::ramrws      mctrl0::mcfg2::sdramrf
```

```
mctrl0::mcfg2::ramwidth        mctrl0::mcfg2::sdramtcas
mctrl0::mcfg2::ramwws          mctrl0::mcfg2::sdramtrfc
mctrl0::mcfg2::rbrdy           mctrl0::mcfg2::sdramtrp
mctrl0::mcfg2::rmw             mctrl0::mcfg2::se
mctrl0::mcfg2::sdpb            mctrl0::mcfg2::si
mctrl0::mcfg2::sdrambanksz
grmon3> puts [format %x $mctrl0::mcfg2::ramwidth]
  2
```

3.4.2. Uploading application and data to target memory

A software application can be uploaded to the target system memory using the **load** command:

```
grmon3> load v8/stanford.exe
  40000000 .text                    54.8kB /  54.8kB  [===============>] 100%
  4000DB30 .data                     2.9kB /   2.9kB  [===============>] 100%
  Total size: 57.66kB (786.00kbit/s)
  Entry point 0x40000000
  Image /home/daniel/examples/v8/stanford.exe loaded
```

The supported file formats are SPARC ELF-32, SPARC ELF-64 (MSB truncated to 32-bit addresses), RISC-V ELF-64, srecord and a.out binaries. Each section is loaded to its link address. The program entry point of the file is used to set the %PC, %NPC when the application is later started with run. It is also possible to load binary data by specifying file and target address using the **bload** command.

One can use the **verify** command to make sure that the file has been loaded correctly to memory as below. Any discrepancies will be reported in the GRMON console.

```
grmon3> verify v8/stanford.exe
  40000000 .text                    54.8kB /  54.8kB  [===============>] 100%
  4000DB30 .data                     2.9kB /   2.9kB  [===============>] 100%
  Total size: 57.66kB (726.74kbit/s)
  Entry point 0x40000000
  Image of /home/daniel/examples/v8/stanford.exe verified without errors
```

On-going DMA can be turned off to avoid that hardware overwrites the loaded image by issuing the **reset** command prior to **load**. This is important after the CPU has been executing using DMA in for example Ethernet network traffic.

3.4.3. Running applications

After the application has been uploaded to the target with **load** the **run** command can be used to start execution. The entry-point taken from the ELF-file during loading will serve as the starting address, the first instruction executed. The **run** command issues a driver reset, however it may be necessary to perform a reset prior to loading the image to avoid that DMA overwrites the image. See the **reset** command for details. Applications already located in FLASH can be started by specifying an absolute address. The **cont** command resumes execution after a temporary stop, e.g. a breakpoint hit. **go** also affects the CPU execution, the difference compared to **run** is that the target device hardware is not initialized before starting execution.

```
grmon3> reset
grmon3> load v8/stanford.exe
  40000000 .text                    54.8kB /  54.8kB  [===============>] 100%
  4000DB30 .data                     2.9kB /   2.9kB  [===============>] 100%
  Total size: 57.66kB (786.00kbit/s)
  Entry point 0x40000000
  Image /home/daniel/examples/v8/stanford.exe loaded

grmon3> run
Starting
    Perm   Towers   Queens   Intmm     Mm  Puzzle   Quick  Bubble    Tree     FFT
      34       67       33     117   1117     367      50      50     250    1133

Nonfloating point composite is       144

Floating point composite is       973

  CPU 0:  Program exited normally.
  CPU 1:  Power down mode
```

The output from the application normally appears on the target system UARTs and thus not in the GRMON console. However, if GRMON is started with the −u switch, the UART is put into debug mode and the output

is tunneled over the debug-link and finally printed on the console by GRMON. See Section 3.9, "Forwarding application console I/O". Note that older hardware (GRLIB 1.0.17-b2710 and older) has only partial support for −u, it will not work when the APBUART software driver uses interrupt driven I/O, thus Linux and vxWorks are not supported on older hardware. Instead, a terminal emulator should be connected to UART 1 of the target system.

Since the application changes (at least) the .data segment during run-time the application must be reloaded before it can be executed again. If the application uses the MMU (e.g. Linux) or installs data exception handlers (e.g. eCos), GRMON should be started with −nb to avoid going into break mode on a page-fault or data exception. Likewise, when a software debugger is running on the target (e.g. GDB natively in Linux user-space or WindRiver Workbench debugging a task) soft breakpoints ("TA 0x01" instruction) will result in traps that the OS will handle and tell the native debugger. To prevent GRMON from interpreting it as its own breakpoints and stop the CPU one must use the −nswb switch.

3.4.4. Inserting breakpoints and watchpoints

All breakpoints are inserted with the **bp** command. The subcommand (soft, hard, watch, bus, data, delete) given to **bp** determine which type of breakpoint is inserted, if no subcommand is given **bp** defaults to a software breakpoint.

Instruction breakpoints are inserted using **bp soft** or **bp hard** commands. Inserting a software breakpoint will add a (TA 0x1) instruction by modifying the target's memory before starting the CPU, while **bp hard** will insert a hardware breakpoint using one of the IU watchpoint registers. To debug instruction code in read-only memories or memories which are self-modifying the only option is hardware breakpoints. Note that it's possible to debug any RAM-based code using software breakpoints, even where traps are disabled such as in trap handlers. Since hardware breakpoints triggers on the CPU instruction address one must be aware that when the MMU is turned on, virtual addresses are triggered upon.

CPU data address watchpoints (read-only, write-only or read-write) are inserted using the **bp watch** command. Watchpoints can be setup to trigger within a range determined by a bit-mask where a one means that the address must match the address pattern and a zero mask indicate don't care. The lowest 2-bits are not available, meaning that 32-bit words are the smallest address that can be watched. Byte accesses can still be watched but accesses to the neighboring three bytes will also be watched.

AMBA-bus watchpoints can be inserted using **bp bus** or **bp data**. When a bus watchpoint is hit the trace buffer will freeze. The processor can optionally be put in debug mode when the bus watchpoint is hit. This is controlled by the **tmode** command:

```
grmon3> tmode break N
```

If N = 0, the processor will not be halted when the watchpoint is hit. A value > 0 will break the processor and set the AHB trace buffer delay counter to the same value.

For hardware supported break/watchpoints the target must have been configured accordingly, otherwise a failure will be reported. Note also that the number of watchpoints implemented varies between designs.

3.4.5. Displaying processor registers

The registers of the processor can be displayed using the **reg** command (for a LEON processor it will print the current window) or by accessing the Tcl cpu namespace that GRMON provides. GRMON exports cpu and cpuN where *N* selects which CPU's registers are accessed, the cpu namespace points to the active CPU selected by the **cpu** command.

```
grmon3> reg
        INS         LOCALS      OUTS        GLOBALS
   0:   00000008    0000000C    00000000    00000000
   1:   80000070    00000020    00000000    00000001
   2:   00000000    00000000    00000000    00000002
   3:   00000000    00000000    00000000    00300003
   4:   00000000    00000000    00000000    00040004
   5:   00000000    00000000    00000000    00005005
   6:   407FFFF0    00000000    407FFFF0    00000606
   7:   00000000    00000000    00000000    00000077

  psr: F34010E0   wim: 00000002   tbr: 40000060   y: 00000000
```

```
  pc:    40003E44  be  0x40003FB8
  npc:   40003E48  nop
grmon3> puts [format %x $::cpu::iu::o6]
  407ffff0
```

For a LEON processor the other register windows can be displayed using **reg wN**, when *N* denotes the window number.

Use the **float** command to show the FPU registers (if present).

3.4.6. Backtracing function calls

When debugging an application it is often most useful to view how the CPU entered the current function. The **bt** command analyze the previous stack frames to determine the backtrace. GRMON reads the register windows and then switches to read from the stack depending on the %WIM and %PSR register.

The backtrace is presented with the caller's program counter (%PC) to return to (below where the CALL instruction was issued) and the stack pointer (%SP) at that time. The first entry (frame #0) indicates the current location of the CPU and the current stack pointer. The right most column print out the %PC address relative the function symbol, i.e. if symbols are present.

```
grmon3> bt

       %pc          %sp
  #0   0x40003e24   0x407ffdb8   <Fft+0x4>
  #1   0x40005034   0x407ffe28   <main+0xfc4>
  #2   0x40001064   0x407fff70   <_start+0x64>
  #3   0x4000cf40   0x407fffb0   <_hardreset_real+0x78>
```

On a LEON system, in order to display a correct backtrace for optimized code, where optimized leaf functions are present, a symbol table must exist.

NOEL-V requires DWARF information to display backtrace correctly

In a MP system the backtrace of a specific CPU can be printed, either by changing the active CPU with the **cpu** command or by passing the CPU index to **bt**.

3.4.7. Displaying memory contents

Any memory location can be displayed and written using the commands listed in the table below. Memory commands that are prefixed with a *v* access the virtual address space seen by doing MMU address lookups for active CPU.

Table 3.2. Memory access commands

Command Name	Description
mem	AMBA bus 32-bit memory read access, list a range of addresses
wmem	AMBA bus 32-bit memory write access
vmem	AMBA bus 32-bit virtual memory read access, list a range of addresses
memb	AMBA bus 8-bit memory read access, list a range of addresses
memh	AMBA bus 16-bit memory read access, list a range of addresses
vmemb	AMBA bus 8-bit virtual memory read access, list a range of addresses
vmemh	AMBA bus 16-bit virtual memory read access, list a range of addresses
vwmemb	AMBA bus 8-bit virtual memory write access
vwmemh	AMBA bus 16-bit virtual memory write access
vwmems	Write a string to an AMBA bus virtual memory address
vwmem	AMBA bus 32-bit virtual memory write access

Command Name	Description
wmemb	AMBA bus 8-bit memory write access
wmemh	AMBA bus 16-bit memory write access
wmems	Write a string to an AMBA bus memory address
amem	AMBA bus 32-bit asynchronous memory read access

Most debug links only support 32-bit accesses, only JTAG links support unaligned access. An unaligned access is when the address or number of bytes are not evenly divided by four. When an unaligned data read request is issued, then GRMON will read some extra bytes to align the data, but only return the requested data. If a write request is issued, then an aligned read-modify-write sequence will occur.

The **mem** command requires an address and an optional length, if the length is left out 64 bytes are displayed. If a program has been loaded, text symbols can be used instead of a numeric address. The memory content is displayed in hexadecimal-decimal format, grouped in 32-bit words. The ASCII equivalent is printed at the end of the line.

```
grmon> mem 0x40000000

 40000000   a0100000   29100004   81c52000   01000000      ...)..... .....
 40000010   91d02000   01000000   01000000   01000000      . .............
 40000020   91d02000   01000000   01000000   01000000      . .............
 40000030   91d02000   01000000   01000000   01000000      . .............

grmon> mem 0x40000000 16

 40000000   a0100000   29100004   81c52000   01000000      ...)..... .....

grmon> mem main 48

 40003278   9de3bf98   2f100085   31100037   90100000      ..../...1..7....
 40003288   d02620c0   d025e178   11100033   40000b4b      & .%.x...3@..K
 40003298   901223b0   11100033   40000af4   901223c0      ..#....3@.....#.
```

The memory access commands listed in Table 3.2 are not restricted to memory: they can be used on any bus address accessible by the debug link. However, for access to peripheral control registers, the command **info reg** can provide a more user-friendly output.

All commands in Table 3.2, , except for **amem**, return to the caller when the bus access has completed, which means that a sequence of these commands generates a sequence of bus accesses with the same ordering. In situations where the bus accesses order is not critical, the command **amem** can be used to schedule multiple concurrent read accesses whose results can be retrieved at a later time. This is useful when GRMON is automated using Tcl scripts.

3.4.8. Instruction disassembly

If the memory contents is SPARC machine code, the contents can be displayed in assembly code using the **disassemble** command:

```
grmon3> disassemble 0x40000000 10
  0x40000000: 88100000   clr  %g4                        <start+0>
  0x40000004: 09100034   sethi  %hi(0x4000d000), %g4     <start+4>
  0x40000008: 81c12034   jmp  %g4 + 0x34                 <start+8>
  0x4000000c: 01000000   nop                             <start+12>
  0x40000010: a1480000   mov  %psr, %l0                  <start+16>
  0x40000014: a7500000   mov  %wim, %l3                  <start+20>
  0x40000018: 10803401   ba  0x4000d01c                  <start+24>
  0x4000001c: ac102001   mov  1, %l6                      <start+28>
  0x40000020: 91d02000   ta  0x0                         <start+32>
  0x40000024: 01000000   nop                             <start+36>

grmon3> dis main
  0x40004070: 9de3beb8   save  %sp, -328, %sp            <main+0>
  0x40004074: 15100035   sethi  %hi(0x4000d400), %o2     <main+4>
  0x40004078: d102a3f4   ld  [%o2 + 0x3f4], %f8          <main+8>
  0x4000407c: 13100035   sethi  %hi(0x4000d400), %o1     <main+12>
  0x40004080: 39100088   sethi  %hi(0x40022000), %i4     <main+16>
  0x40004084: 3710003a   sethi  %hi(0x4000e800), %i3     <main+20>
  0x40004088: d126e2e0   st  %f8, [%i3 + 0x2e0]          <main+24>
```

```
0x4000408c: d1272398   st   %f8, [%i4 + 0x398]      <main+28>
0x40004090: 400006a9   call  0x40005b34             <main+32>
0x40004094: 901262f0   or   %o1, 0x2f0, %o0         <main+36>
0x40004098: 11100035   sethi  %hi(0x4000d400), %o0  <main+40>
0x4000409c: 40000653   call  0x400059e8             <main+44>
0x400040a0: 90122300   or   %o0, 0x300, %o0         <main+48>
0x400040a4: 7ffff431   call  0x40001168             <main+52>
0x400040a8: 3510005b   sethi  %hi(0x40016c00), %i2  <main+56>
0x400040ac: 2510005b   sethi  %hi(0x40016c00), %l2  <main+60>
```

3.4.9. Using the trace buffer

The processor and associated debug support unit (DSU or RVDM) can be configured with trace buffers to store both the latest executed instructions and the latest AHB bus transfers. The trace buffers are automatically enabled by GRMON during start-up , but can also be individually enabled and disabled using **tmode** command. The command **ahb** is used to show the AMBA buffer. The command **inst** is used to show the instruction buffer. The command **hist** is used to display the contents of the instruction and the AMBA buffers mixed together. Below is an example debug session that shows the usage of breakpoints, watchpoints and the trace buffer:

```
grmon3> lo v8/stanford.exe
  40000000 .text                      54.8kB /  54.8kB  [===============>] 100%
  4000DB30 .data                       2.9kB /   2.9kB  [===============>] 100%
  Total size: 57.66kB (786.00kbit/s)
  Entry point 0x40000000
  Image /home/daniel/examples/v8/stanford.exe loaded

grmon3> bp Fft
  Software breakpoint 1 at <Fft>

grmon3> bp watch 0x4000eae0
  Hardware watchpoint 2 at 0x4000eae0

grmon3> bp
  NUM   ADDRESS     MASK        TYPE        SYMBOL
    1 : 0x40003e20              (soft)      Fft+0
    2 : 0x4000eae0  0xfffffffc  (watch rw)  floated+0

grmon3> run

  CPU 0:  watchpoint 2 hit
          0x40001024: c0388003  std  %g0, [%g2 + %g3]  <_start+36>
  CPU 1:  Power down mode

grmon3> inst
      TIME      ADDRESS   INSTRUCTION               RESULT
       84675    40001024  std  %g0, [%g2 + %g3]     [4000eaf8 00000000 00000000]
       84678    4000101c  subcc  %g3, 8, %g3        [00000440]
       84679    40001020  bge,a  0x4000101c         [00000448]
       84682    40001024  std  %g0, [%g2 + %g3]     [4000eaf0 00000000 00000000]
       84685    4000101c  subcc  %g3, 8, %g3        [00000438]
       84686    40001020  bge,a  0x4000101c         [00000440]
       84689    40001024  std  %g0, [%g2 + %g3]     [4000eae8 00000000 00000000]
       84692    4000101c  subcc  %g3, 8, %g3        [00000430]
       84693    40001020  bge,a  0x4000101c         [00000438]
       84694    40001024  std  %g0, [%g2 + %g3]     [   TRAP  ]

grmon3> ahb
      TIME      ADDRESS  TYPE   D[31:0]   TRANS SIZE BURST MST LOCK RESP HIRQ
       84664    4000eb08 write 00000000   2    2     1     0   0    0    0000
       84667    4000eb0c write 00000000   3    2     1     0   0    0    0000
       84671    4000eb00 write 00000000   2    2     1     0   0    0    0000
       84674    4000eb04 write 00000000   3    2     1     0   0    0    0000
       84678    4000eaf8 write 00000000   2    2     1     0   0    0    0000
       84681    4000eafc write 00000000   3    2     1     0   0    0    0000
       84685    4000eaf0 write 00000000   2    2     1     0   0    0    0000
       84688    4000eaf4 write 00000000   3    2     1     0   0    0    0000
       84692    4000eae8 write 00000000   2    2     1     0   0    0    0000
       84695    4000eaec write 00000000   3    2     1     0   0    0    0000

grmon3> reg
      INS       LOCALS     OUTS      GLOBALS
    0:  80000200  00000000  00000000  00000000
    1:  80000200  00000000  00000000  00000000
    2:  0000000C  00000000  00000000  4000E6B0
    3:  FFF00000  00000000  00000000  00000430
    4:  00000002  00000000  00000000  4000CC00
    5:  800FF010  00000000  00000000  4000E680
    6:  407FFFB0  00000000  407FFF70  4000CF34
    7:  4000CF40  00000000  00000000  00000000
```

```
     psr: F30010E7   wim: 00000002   tbr: 40000000   y: 00000000


     pc:   40001024  std  %g0, [%g2 + %g3]
     npc:  4000101c  subcc  %g3, 8, %g3

grmon3> bp del 2

grmon3> cont
  Towers  Queens   Intmm      Mm  Puzzle   Quick   Bubble    Tree     FFT
  CPU 0:  breakpoint 1 hit
          0x40003e24: a0100018  mov  %i0, %l0  <Fft+4>
  CPU 1:  Power down mode

grmon3>
grmon3> hist
     TIME      ADDRESS    INSTRUCTIONS/AHB SIGNALS      RESULT/DATA
     30046975  40003e20   AHB read   mst=0  size=2      [9de3bf90]
     30046976  40005030   or  %l2, 0x1e0, %o3           [40023de0]
     30046980  40003e24   AHB read   mst=0  size=2      [91d02001]
     30046981  40005034   call 0x40003e20               [40005034]
     30046985  40003e28   AHB read   mst=0  size=2      [b136201f]
     30046990  40003e2c   AHB read   mst=0  size=2      [f83fbff0]
     30046995  40003e30   AHB read   mst=0  size=2      [82040018]
     30047000  40003e34   AHB read   mst=0  size=2      [d11fbff0]
     30047005  40003e38   AHB read   mst=0  size=2      [9a100019]
     30047010  40003e3c   AHB read   mst=0  size=2      [9610001a]
```

When printing executed instructions, the value within brackets denotes the instruction result, or in the case of store instructions the store address and store data. The value in the first column displays the relative time, equal to the DSU timer. The time is taken when the instruction completes in the last pipeline stage (write-back) of the processor. In a mixed instruction/AHB display, AHB address and read or write value appears within brackets. The time indicates when the transfer completed, i.e. when HREADY was asserted.

As the AHB trace is disabled when a breakpoint is hit, AHB accesses related to instruction cache fetches after the time of break can be missed. The command **ahb force** can be used enable AHB tracing even when the processor is in debug mode.

When switching between tracing modes with **tmode** the contents of the trace buffer will not be valid until execution has been resumed and the buffer refilled.

3.4.10. Profiling

GRMON supports profiling of LEON applications when run on real hardware. The profiling function collects (statistical) information on the amount of execution time spent in each function. Due to its non-intrusive nature, the profiling data does not take into consideration if the current function is called from within another procedure. Even so, it still provides useful information and can be used for application tuning.

To increase the number of samples, use the fastest debug link available on the target system. I.a. do not use I/O forwarding (start GRMON *without* the -u commandline option)

```
grmon3> lo v8/stanford.exe
  40000000 .text                    54.8kB /  54.8kB  [===============>] 100%
  4000DB30 .data                     2.9kB /   2.9kB  [===============>] 100%
  Total size: 57.66kB (786.00kbit/s)
  Entry point 0x40000000
  Image /home/daniel/examples/v8/stanford.exe loaded

grmon3> profile on

grmon3> run
Starting
    Perm  Towers  Queens   Intmm      Mm  Puzzle   Quick  Bubble    Tree     FFT

  CPU 0:  Interrupted!
          0x40003ee4: 95a0c8a4  fsubs  %f3, %f4, %f10  <Fft+196>
  CPU 1:  Interrupted!
          0x40000000: 88100000  clr  %g4  <start+0>

grmon3> prof
    FUNCTION                      SAMPLES    RATIO(%)
    Trial                         0000000096 27.35
```

```
__window_overflow_rettseq_ret 0000000060 17.09
main                          0000000051 14.52
__window_overflow_slow1       0000000026  7.40
Fft                           0000000023  6.55
Insert                        0000000016  4.55
Permute                       0000000013  3.70
tower                         0000000013  3.70
Try                           0000000013  3.70
Quicksort                     0000000011  3.13
Checktree                     0000000007  1.99
_malloc_r                     0000000005  1.42
start                         0000000004  1.13
outbyte                       0000000003  0.85
Towers                        0000000002  0.56
__window_overflow_rettseq     0000000002  0.56
___st_pthread_mutex_lock      0000000002  0.56
_start                        0000000001  0.28
Perm                          0000000001  0.28
__malloc_lock                 0000000001  0.28
___st_pthread_mutex_trylock   0000000001  0.28
```

3.4.11. Attaching to a target system without initialization

When GRMON connects to a target system, it probes the configuration and initializes memory and registers. To determine why a target has crashed, or to debug an application that is running, it might be desirable to connect to the target without performing a (destructive) initialization. This can be done by specifying the `-ni` switch during the start-up of GRMON. The CPUs cores still be forced into debug mode during GRMON startup.

The system information print-out (**info sys**) will not be able to display infortmation correctly that depens on initialization, for exmple the correct memory settings.

To continue the execution of the application, issue the **cont** or the **detach** command.

The **run** and **reset** commands may not have the intended effect since the debug drivers have not been initialized during start-up.

If the user runs a software bootloader or initializes the system manually, then **go** command can be used to restart the application. Otherwise it recomended to restart GRMON without `-ni` to resrart the application.

3.4.12. Attaching to a target system without Plug and Play scanning

When GRMON connects to a target system, it will scan the Plug and play information (or read a configuration file), to determine which kind of system it has connected to. If the `-ni` switch during the start-up of GRMON then this will be skipped, and GRMON will not have any knowledge about the hardware. Therefore GRMON will not make any access to the system during startup.

Most hardware dependent commands will have undefined behaviour. But the basic memory access commands will work, i.e. **mem**, **wmem** and similar.

This mode can be used to check register values after a hardware reset has been asserted, or other situations when you want stop GRMON from doing any accesses during startup.

3.4.13. Multi-processor support

In systems with more than one processor, the **cpu** command can be used to control the state and debugging focus of the processors. In MP systems, the processors are enumerated with 0..N-1, where *N* is the number of processors. Each processor can be in two states; enabled or disabled. When enabled, a processor can be started by LEON software or by GRMON. When disabled, the processor will remain halted regardless. One can pause a MP operating system and disable a CPU to debug a hanged CPU for example.

Most per-CPU debugging commands such as displaying registers, backtrace or adding breakpoints will be directed to the active processor only. Switching active processor can be done using the **'cpu active N'** command, see example below. The Tcl `cpu` namespace exported by GRMON is also changed to point to the active CPU's namespace, thus accessing `cpu` will be the same as accessing `cpu1` if CPU1 is the currently active CPU.

```
grmon3> cpu
```

```
   cpu 0: enabled   active
   cpu 1: enabled

grmon3> cpu act 1

grmon3> cpu
   cpu 0: enabled
   cpu 1: enabled   active

grmon3> cpu act 0

grmon3> cpu dis 1

grmon3> cpu
   cpu 0: enabled   active
   cpu 1: disabled

grmon3> puts $cpu::fpu::f1
  -1.984328031539917

grmon3> puts $cpu0::fpu::f1
  -1.984328031539917

grmon3> puts $cpu1::fpu::f1
  2.3017966689845248e+18
```

Non-MP software can still run on the first CPU unaffected of the additional CPUs since it is the target software that is responsible for waking other CPUs. All processors are enabled by default.

Note that it is possible to debug MP systems using GDB, but the user are required to change CPU itself. GRMON specific commands can be entered from GDB using the **monitor** command.

3.4.14. Stack and entry point

The stack pointer is located in %O6 (%SP) register of SPARC CPUs. GRMON sets the stack pointer before starting the CPU with the **run** command. The address is auto-detected to end of main memory, however it is overridable using the -stack when starting GRMON or by issuing the **stack** command. Thus stack pointer can be used by software to detect end of main memory.

The entry point (EP) determines at which address the CPU start its first instruction execution. The EP defaults to main memory start and normally overridden by the **load** command when loading the application. ELF-files has support for storing entry point. The entry point can manually be set with the **ep** command.

In a MP systems if may be required to set EP and stack pointer individual per CPU, one can use the **cpu** command in conjunction with **ep** and **stack**.

3.4.15. Memory Management Unit (MMU) support

The LEON optionally implements the reference MMU (SRMMU) described in the SPARCv8 specification. GRMON support viewing and changing the MMU registers through the DSU, using the **mmu** command. GRMON also supports address translation by reading the MMU table from memory similar to the MMU. The **walk** command looks up one address by walking the MMU table printing out every step taken and the result. To simply print out the result of such a translation, use the **va** command.

The memory commands that are prefixed with a *v* work with virtual addresses, the addresses given are translated before listing or writing physical memory. If the MMU is not enabled, the **vmem** command for example is an alias for **mem**. See Section 3.4.7, "Displaying memory contents" for more information.

Many commands are affected by that the MMU is turned on, such as the **disassemble** command.

3.4.16. CPU cache support

The target system optionally implements Level-1 instruction-cache and data-cache. GRMON supports the CPU's cache by adopting certain operations depending on if the cache is activated or not. The user may also be able to access the cache directly. This is however not normally needed, but may be useful when debugging or analyzing

different cache aspects. By default the L1-cache is turned on by GRMON , the **cctrl** command can be used to change the cache control register. The commandline switches `-nic` and `-ndc` disables instruction and data cache respectively.

With the **icache** and **dcache** commands it is possible to view and modify the current content of the cache or check if the cache is consistent with the memory. Both caches can be flushed instantly using the commands **cctrl flush**. The data cache can be flushed instantly using the commands **dcache flush**. The instruction cache can be flushed instantly using the commands **icache flush**.

The GRLIB Level-2 cache is supported using the **l2cache** command.

3.5. Tcl integration

GRMON has built-in support for Tcl 8.6. All commands lines entered in the terminal will pass through a Tcl-interpreter. This enables loops, variables, procedures, scripts, arithmetics and more for the user. I.a. it also provides an API for the user to extend GRMON.

3.5.1. Shells

GRMON creates several independent TCL shells, each with its own set of commands and variables. I.e. changing active CPU in one shell does not affect any other shell. In the commandline version there one shell available for the user by default, the CLI shell, which is accessed from the terminal. In the GUI is possible to create and view multiple shells.

Additional custom user shells for the commandline interface can be created with the command **usrsh**. Each custom user shell has an associated Tcl interpreter running in a separate execution thread.

When the GDB service is running, a GDB shell is also available from GDB by using the command **mon**.

There is also a system shell and an execution shell running in the background that GRMON uses internally. Some hooks must be loaded into these shells to work, see Appendix C, *Tcl API* for more information.

3.5.2. Commands

There are two groups of commands, the native Tcl commands and GRMON's commands. Information about the native Tcl commands and their syntax can be found at the Tcl website [http://www.tcl.tk/]. The GRMON commands' syntax documentation can be found in Appendix B, *Command syntax*.

The commands have three types of output:

1. **Standard output**. GRMON's commands prints information to standard output. This information is often structured in a human readable way and cannot be used by other commands. Most of the GRMON commands print some kind of information to the standard output, while very few of the Tcl commands does that. Setting the variable `::grmon::settings:suppress_output` to 1 will stop GRMON commands from printing to the standard output, i.e. the TCL command **puts** will still print it's output. It is also possible to put the command **silent** in front of another GRMON command to suppress the output of a single command, e.g. `grmon3> puts [expr [silent mem 0x40000000 4] + 4]`
2. **Return values.** The return value from GRMON is seldom the same as the information that is printed to standard output, it's often the important data in a raw format. Return values can be used as input to other commands or to be saved in variables. All TCL commands and many GRMON commands have return values. The return values from commands are normally not printed. To print the return value to standard output one can use the Tcl command **puts**. I.a. if the variable `::grmon::settings:echo_result` to 1, then GRMON will always print the result to stdout.
3. **Return code.** The return code from a command can be accessed by reading the variable `errorCode` or by using the Tcl command **catch**. Both Tcl and GRMON commands will have an error message as return value if it fails, which is also printed to standard output. More about error codes can be read about in the Tcl tutorial or on the Tcler's Wiki [http://wiki.tcl.tk/].

For some of the GRMON commands it is possible to specify which core the commands is operation on. This is implemented differently depending for each command, see the commands' syntax documentation in Appendix B,

Command syntax for more details. Some of these commands use a device name to specify which core to interact with, see Appendix C, *Tcl API* for more information about device names.

3.5.3. API

It is possible to extend GRMON using Tcl. GRMON provides an API that makes it possible do write own device drivers, implement hooks and to write advanced commands. See Appendix C, *Tcl API* for a detailed description of the API.

3.6. Symbolic debug information

GRMON will automatically extract the symbol information from ELF-files, debug information is never read from ELF-files. The symbols can be used to GRMON commands where an address is expected as below. Symbols are tab completed.

```
grmon3> load v8/stanford.exe
  40000000 .text                  54.8kB /  54.8kB  [===============>] 100%
  4000DB30 .data                   2.9kB /   2.9kB  [===============>] 100%
  Image /home/daniel/examples/v8/stanford.exe loaded

grmon3> bp main
  Software breakpoint 1 at <main>

grmon3> dis strlen 5
  0x40005b88: 808a2003  andcc  %o0, 0x3, %g0          <strlen+0>
  0x40005b8c: 12800012  bne  0x40005BD4               <strlen+4>
  0x40005b90: 94100008  mov  %o0, %o2                 <strlen+8>
  0x40005b94: 033fbfbf  sethi  %hi(0xFEFEFC00), %g1   <strlen+12>
  0x40005b98: da020000  ld  [%o0], %o5                <strlen+16>
```

The **symbols** command can be used to display all symbols, lookup the address of a symbol, or to read in symbols from an alternate (ELF) file:

```
grmon3> symbols load v8/stanford.exe

grmon3> symbols lookup main
  Found address 0x40004070

grmon3> symbols list
  0x40005ab8  GLOBAL  FUNC      putchar
  0x4000b6ac  GLOBAL  FUNC      _mprec_log10
  0x4000d9d0  GLOBAL  OBJECT    __mprec_tinytens
  0x4000bbe8  GLOBAL  FUNC      cleanup_glue
  0x4000abfc  GLOBAL  FUNC      _hi0bits
  0x40005ad4  GLOBAL  FUNC      _puts_r
  0x4000c310  GLOBAL  FUNC      _lseek_r
  0x4000eaac  GLOBAL  OBJECT    piecemax
  0x40001aac  GLOBAL  FUNC      Try
  0x40003c6c  GLOBAL  FUNC      Uniform11
  0x400059e8  GLOBAL  FUNC      printf
...
```

Reading symbols from alternate files is necessary when debugging self-extracting applications (MKPROM), when switching between virtual and physical address space (Linux) or when debugging a multi-core ASMP system where each CPU has its own symbol table. It is recommended to clear old symbols with **symbols clear** before switching symbol table, otherwise the new symbols will be added to the old table.

3.6.1. Multi-processor symbolic debug information

When loading symbols into GRMON it is possible to associate them with a CPU. When all symbols/images are associated with CPU index 0, then GRMON will assume its a single-core or SMP application and lookup all symbols from the symbols table associated with CPU index 0.

If different CPU indexes are specified (by setting active CPU or adding cpu# argument to the commands) when loading symbols/images, then GRMON will assume its an AMP application that has been loaded. GRMON will use the current active CPU (or cpu# argument) to determine which CPU index to lookup symbols from.

```
grmon3> cpu active 1

grmon3> symbols ../tests/threads/rtems-mp2
  Loaded 1630 symbols
```

```
grmon3> bp _Thread_Handler
  Software breakpoint 1 at <_Thread_Handler>

grmon3> symbols ../tests/threads/rtems-mp1 cpu0
  Loaded 1630 symbols

grmon3> bp _Thread_Handler cpu0
  Software breakpoint 2 at <_Thread_Handler>

grmon3> bp
  NUM  ADDRESS     MASK        TYPE       CPU  SYMBOL
    1 : 0x40418408             (soft)       1  _Thread_Handler+0
    2 : 0x40019408             (soft)       0  _Thread_Handler+0
```

3.7. GDB interface

This section describes the GDB interface support available in GRMON. GRMON supports GDB version 6.3, 6.4, 6.8 and 8.2. Other tools that communicate over the GDB protocol may also attach to GRMON, some tools such as Eclipse Workbench and DDD communicate with GRMON via GDB.

GDB must be built for the SPARC architecture, a native PC GDB does not work together with GRMON. The toolchains that Cobham Gaisler distributes comes with a patched and tested version of GDB targeting all SPARC LEON development tools.

Please see the GDB documentation available from the official GDB homepage [http://www.gnu.org/software/gdb/].

3.7.1. Connecting GDB to GRMON

GRMON can act as a remote target for GDB, allowing symbolic debugging of target applications. To initiate GDB communications, start the monitor with the −gdb switch or use the GRMON **gdb start** command:

```
$ grmon -gdb
...
 Started GDB service on port 2222.
...
grmon3> gdb status
  GDB Service is waiting for incoming connection
  Port: 2222
```

Then, start GDB in a different window and connect to GRMON using the extended-remote protocol. By default, GRMON listens on port 2222 for the GDB connection:

```
$ sparc-gaisler-elf-gdb /opt/bcc-2.0.7-rc.1-gcc/src/examples/stanford/stanford
GNU gdb (GDB) 8.2
Copyright (C) 2018 Free Software Foundation, Inc.
License GPLv3+: GNU GPL version 3 or later <http://gnu.org/licenses/gpl.html>
This is free software: you are free to change and redistribute it.
There is NO WARRANTY, to the extent permitted by law.
Type "show copying" and "show warranty" for details.
This GDB was configured as "--host=x86_64-pc-linux-gnu --target=sparc-gaisler-elf".
Type "show configuration" for configuration details.
For bug reporting instructions, please see:
<http://www.gnu.org/software/gdb/bugs/>.
Find the GDB manual and other documentation resources online at:
    <http://www.gnu.org/software/gdb/documentation/>.

For help, type "help".
Type "apropos word" to search for commands related to "word"...
Reading symbols from /opt/bcc-2.0.7-rc.1-gcc/src/examples/stanford/stanford...done.
(gdb) target extended-remote :2222
Remote debugging using :2222
__bcc_entry_point () at /opt/bcc-2.0.7-rc.1-gcc/src/libbcc/shared/trap/trap_table_mvt.S:81
81  RESET_TRAP(__bcc_trap_reset_mvt);      ! 00 reset
(gdb)
```

3.7.2. Executing GRMON commands from GDB

While GDB is attached to GRMON, most GRMON commands can be executed using the GDB monitor command. Output from the GRMON commands is then displayed in the GDB console like below. Some DSU commands are naturally not available since they would conflict with GDB. All commands executed from GDB are executed in a separate Tcl interpreter, thus variables created from GDB will not be available from the GRMON terminal.

```
(gdb) monitor hist
```

```
     TIME      ADDRESS    INSTRUCTIONS/AHB SIGNALS      RESULT/DATA
    30046975  40003e20   AHB read   mst=0  size=2       [9de3bf90]
    30046976  40005030   or  %l2, 0x1e0, %o3            [40023de0]
    30046980  40003e24   AHB read   mst=0  size=2       [91d02001]
    30046981  40005034   call  0x40003e20               [40005034]
    30046985  40003e28   AHB read   mst=0  size=2       [b136201f]
    30046990  40003e2c   AHB read   mst=0  size=2       [f83fbff0]
    30046995  40003e30   AHB read   mst=0  size=2       [82040018]
    30047000  40003e34   AHB read   mst=0  size=2       [d11fbff0]
    30047005  40003e38   AHB read   mst=0  size=2       [9a100019]
    30047010  40003e3c   AHB read   mst=0  size=2       [9610001a]
(gdb)
```

3.7.3. Running applications from GDB

To load and start an application, use the GDB **load** and **run** command.

```
$ sparc-rtems-gdb v8/stanford.exe
(gdb) target extended-remote :2222
Remote debugging using :2222
main () at stanford.c:1033
1033 {
(gdb) load
Loading section .text, size 0xdb30 lma 0x40000000
Loading section .data, size 0xb78 lma 0x4000db30
Start address 0x40000000, load size 59048
Transfer rate: 18 KB/sec, 757 bytes/write.
(gdb) b main
Breakpoint 1 at 0x40004074: file stanford.c, line 1033.
(gdb) run
The program being debugged has been started already.
Start it from the beginning? (y or n) y
Starting program: /home/daniel/examples/v8/stanford.exe

Breakpoint 1, main () at stanford.c:1033
1033 {
(gdb) list
1028    /* Printcomplex( 6, 99, z, 1, 256, 17 ); */
1029        };
1030 } /* oscar */ ;
1031
1032 main ()
1033 {
1034     int i;
1035     fixed = 0.0;
1036     floated = 0.0;
1037     printf ("Starting \n");
(gdb)
```

To interrupt execution, Ctrl-C can be typed in GDB terminal (similar to GRMON). The program can be restarted using the GDB **run** command but the program image needs to be reloaded first using the **load** command. Software trap 1 (TA 0x1) is used by GDB to insert breakpoints and should not be used by the application.

GRMON translates SPARC traps into (UNIX) signals which are properly communicated to GDB. If the application encounters a fatal trap, execution will be stopped exactly before the failing instruction. The target memory and register values can then be examined in GDB to determine the error cause.

GRMON implements the GDB breakpoint and watchpoint interface and makes sure that memory and cache are synchronized.

3.7.4. Running SMP applications from GDB

If GRMON is running on the same computer as GDB, or if the executable is available on the remote computer that is running GRMON, it is recommended to issue the GDB command **set remote exec-file <remote-file-path>**. After this has been set, GRMON will automatically load the file, and symbols if available, when the GDB command **run** is issued.

```
$ sparc-rtems-gdb /opt/rtems-4.11/src/rtems-4.11/testsuites/libtests/ticker/ticker.exe
GNU gdb 6.8.0.20090916-cvs
Copyright (C) 2008 Free Software Foundation, Inc.
License GPLv3+: GNU GPL version 3 or later <http://gnu.org/licenses/gpl.html>
This is free software: you are free to change and redistribute it.
There is NO WARRANTY, to the extent permitted by law.  Type "show copying"
and "show warranty" for details.
This GDB was configured as "--host=i686-pc-linux-gnu --target=sparc-rtems"...
```

```
(gdb) target extended-remote :2222
Remote debugging using :2222
0x00000000 in ?? ()
(gdb) set remote exec-file /opt/rtems-4.11/src/rtems-4.11/testsuites/libtests/ticker/ticker.exe
(gdb) break Init
Breakpoint 1 at 0x40001318: file ../../../../../leon3smp/lib/include/rtems/score/thread.h, line 627.
(gdb) run
The program being debugged has been started already.
Start it from the beginning? (y or n) y
Starting program: /opt/rtems-4.11/src/rtems-4.11/testsuites/libtests/ticker/ticker.exe
```

If the executable is not available on the remote computer where GRMON is running, then the GDB command **load** can be used to load the software to the target system.

```
$ sparc-rtems-gdb /opt/rtems-4.11/src/rtems-4.11/testsuites/libtests/ticker/ticker.exe
GNU gdb 6.8.0.20090916-cvs
Copyright (C) 2008 Free Software Foundation, Inc.
License GPLv3+: GNU GPL version 3 or later <http://gnu.org/licenses/gpl.html>
This is free software: you are free to change and redistribute it.
There is NO WARRANTY, to the extent permitted by law.  Type "show copying"
and "show warranty" for details.
This GDB was configured as "--host=i686-pc-linux-gnu --target=sparc-rtems"...
(gdb) target extended-remote :2222
Remote debugging using :2222
trap_table () at /opt/rtems-4.11/src/rtems-4.11/c/src/lib/libbsp/sparc/leon3/../../sparc/shared/start
/start.S:69
69 /opt/rtems-4.11/src/rtems-4.11/c/src/lib/libbsp/sparc/leon3/../../sparc/shared/start/start.S: No
such file or directory.
 in /opt/rtems-4.11/src/rtems-4.11/c/src/lib/libbsp/sparc/leon3/../../sparc/shared/start/start.S
Current language:  auto; currently asm
(gdb) load
Loading section .text, size 0x1aed0 lma 0x40000000
Loading section .data, size 0x5b0 lma 0x4001aed0
Start address 0x40000000, load size 111744
Transfer rate: 138 KB/sec, 765 bytes/write.
(gdb) run
The program being debugged has been started already.
Start it from the beginning? (y or n) y
Starting program: /opt/rtems-4.11/src/rtems-4.11/testsuites/libtests/ticker/ticker.exe
```

3.7.5. Running AMP applications from GDB

If GRMON is running on the same computer as GDB, or if the executables are available on the remote computer that is running GRMON, it is recommended to issue the GDB command **set remote exec-file <remote-file-path>**. When this is set, GRMON will automatically load the file, and symbols if available, when the GDB command **run** is issued. The second application needs to be loaded into GRMON using the GRMON command **load <remote-file-path> cpu1**. In addition the stacks must also be set manually in GRMON using the command **stack <address> cpu#** for both CPUs.

```
$ sparc-rtems-gdb /opt/rtems-4.10/src/samples/rtems-mp1
GNU gdb 6.8.0.20090916-cvs
Copyright (C) 2008 Free Software Foundation, Inc.
License GPLv3+: GNU GPL version 3 or later <http://gnu.org/licenses/gpl.html>
This is free software: you are free to change and redistribute it.
There is NO WARRANTY, to the extent permitted by law.  Type "show copying"
and "show warranty" for details.
This GDB was configured as "--host=i686-pc-linux-gnu --target=sparc-rtems"...
(gdb) target extended-remote :2222
Remote debugging using :2222
(gdb) set remote exec-file /opt/rtems-4.10/src/samples/rtems-mp1
(gdb) mon stack 0x403fff00 cpu0
 CPU 0 stack pointer: 0x403fff00
(gdb) mon load /opt/rtems-4.10/src/samples/rtems-mp2 cpu1
Total size: 177.33kB (1.17Mbit/s)
Entry point 0x40400000
Image /opt/rtems-4.10/src/samples/rtems-mp2 loaded
(gdb) mon stack 0x407fff00 cpu1
 CPU 1 stack pointer: 0x407fff00
(gdb) run
Starting program: /opt/rtems-4.10/src/samples/rtems-mp1
NODE[0]: is Up!
NODE[0]: Waiting for Semaphore A to be created (0x53454d41)
NODE[0]: Waiting for Semaphore B to be created (0x53454d42)
NODE[0]: Waiting for Task A to be created (0x54534b41)
^C[New Thread 151060481]

Program received signal SIGINT, Interrupt.
[Switching to Thread 151060481]
pwdloop () at /opt/rtems-4.10/src/rtems-4.10/c/src/lib/libbsp/sparc/leon3/startup/bspidle.S:26
```

```
warning: Source file is more recent than executable.
26          retl
Current language:  auto; currently asm
(gdb)
```

If the executable is not available on the remote computer where GRMON is running, then the GDB command **file** and **load** can be used to load the software to the target system. Use the GRMON command **cpu act <num>** before issuing the GDB command **load** to specify which CPU is the target for the software being loaded. In addition the stacks must also be set manually in GRMON using the command **stack <address> cpu#** for both CPUs.

```
$ sparc-rtems-gdb
GNU gdb 6.8.0.20090916-cvs
Copyright (C) 2008 Free Software Foundation, Inc.
License GPLv3+: GNU GPL version 3 or later <http://gnu.org/licenses/gpl.html>
This is free software: you are free to change and redistribute it.
There is NO WARRANTY, to the extent permitted by law.  Type "show copying"
and "show warranty" for details.
This GDB was configured as "--host=i686-pc-linux-gnu --target=sparc-rtems".
(gdb) target extended-remote :2222
Remote debugging using :2222
0x40000000 in ?? ()
(gdb) file /opt/rtems-4.10/src/samples/rtems-mp2
A program is being debugged already.
Are you sure you want to change the file? (y or n) y
Reading symbols from /opt/rtems-4.10/src/samples/rtems-mp2...done.
(gdb) mon cpu act 1
(gdb) load
Loading section .text, size 0x2b3e0 lma 0x40400000
Loading section .data, size 0x1170 lma 0x4042b3e0
Loading section .jcr, size 0x4 lma 0x4042c550
Start address 0x40400000, load size 181588
Transfer rate: 115 KB/sec, 759 bytes/write.
(gdb) file /opt/rtems-4.10/src/samples/rtems-mp1
A program is being debugged already.
Are you sure you want to change the file? (y or n) y

Load new symbol table from "/opt/rtems-4.10/src/samples/rtems-mp1"? (y or n) y
Reading symbols from /opt/rtems-4.10/src/samples/rtems-mp1...done.
(gdb) mon cpu act 0
(gdb) load
Loading section .text, size 0x2b3e0 lma 0x40001000
Loading section .data, size 0x1170 lma 0x4002c3e0
Loading section .jcr, size 0x4 lma 0x4002d550
Start address 0x40001000, load size 181588
Transfer rate: 117 KB/sec, 759 bytes/write.
(gdb) mon stack 0x407fff00 cpu1
 CPU 1 stack pointer: 0x407fff00
(gdb) mon stack 0x403fff00 cpu0
 CPU 0 stack pointer: 0x403fff00
(gdb) run
The program being debugged has been started already.
Start it from the beginning? (y or n) y
Starting program: /opt/rtems-4.10/src/samples/samples/rtems-mp1
```

3.7.6. GDB Thread support

GDB is capable of listing a operating system's threads, however it relies on GRMON to implement low-level thread access. GDB normally fetches the threading information on every stop, for example after a breakpoint is reached or between single-stepping stops. GRMON have to access the memory rather many times to retrieve the information, GRMON. See Section 3.8, "Thread support" for more information.

Start GRMON with the `-nothreads` switch to disable threads in GRMON and thus in GDB too.

Note that GRMON must have access to the symbol table of the operating system so that the thread structures of the target OS can be found. The symbol table can be loaded from GDB by one must bear in mind that the path is relative to where GRMON has been started. If GDB is connected to GRMON over the network one must make the symbol file available on the remote computer running GRMON.

```
(gdb) mon puts [pwd]
/home/daniel
(gdb) pwd
Working directory /home/daniel.
(gdb) mon sym load /opt/rtems-4.10/src/samples/rtems-hello
(gdb) mon sym
0x00016910  GLOBAL  FUNC    imfs_dir_lseek
```

```
0x00021f00  GLOBAL  OBJECT  Device_drivers
0x0001c6b4  GLOBAL  FUNC    _mprec_log10
...
```

When a program running in GDB stops GRMON reports which thread it is in. The command **info threads** can be used in GDB to list all known threads, **thread N** to switch to thread *N* and **bt** to list the backtrace of the selected thread.

```
Program received signal SIGINT, Interrupt.
[Switching to Thread 167837703]

0x40001b5c in console_outbyte_polled (port=0, ch=113 `q`) at rtems/.../leon3/console/debugputs.c:38
38        while ((LEON3_Console_Uart[LEON3_Cpu_Index+port]->status & LEON_REG_UART_STATUS_THE) == 0);

(gdb) info threads

  8 Thread 167837702 (FTPD Wevnt) 0x4002f760 in _Thread_Dispatch () at rtems/.../threaddispatch.c:109
  7 Thread 167837701 (FTPa Wevnt) 0x4002f760 in _Thread_Dispatch () at rtems/.../threaddispatch.c:109
  6 Thread 167837700 (DCtx Wevnt) 0x4002f760 in _Thread_Dispatch () at rtems/.../threaddispatch.c:109
  5 Thread 167837699 (DCrx Wevnt) 0x4002f760 in _Thread_Dispatch () at rtems/.../threaddispatch.c:109
  4 Thread 167837698 (ntwk ready) 0x4002f760 in _Thread_Dispatch () at rtems/.../threaddispatch.c:109
  3 Thread 167837697 (UI1  ready) 0x4002f760 in _Thread_Dispatch () at rtems/.../threaddispatch.c:109
  2 Thread 151060481 (Int. ready) 0x4002f760 in _Thread_Dispatch () at rtems/.../threaddispatch.c:109
* 1 Thread 167837703 (HTPD ready ) 0x40001b5c in console_outbyte_polled (port=0, ch=113 `q`)
    at ../../../rtems/c/src/lib/libbsp/sparc/leon3/console/debugputs.c:38
  (gdb) thread 8

[Switching to thread 8 (Thread 167837702)]#0  0x4002f760 in _Thread_Dispatch ()
 at rtems/.../threaddispatch.c:109
109        _Context_Switch( &executing->Registers, &heir->Registers );
(gdb) bt

#0  0x4002f760 in _Thread_Dispatch () at rtems/cpukit/score/src/threaddispatch.c:109
#1  0x40013ee0 in rtems_event_receive(event_in=33554432, option_set=0, ticks=0, event_out=0x43fecc14)
    at ../../../../leon3/lib/include/rtems/score/thread.inl:205
#2  0x4002782c in rtems_bsdnet_event_receive (event_in=33554432, option_set=2, ticks=0,
    event_out=0x43fecc14) at rtems/cpukit/libnetworking/rtems/rtems_glue.c:641
#3  0x40027548 in soconnsleep (so=0x43f0cd70) at rtems/cpukit/libnetworking/rtems/rtems_glue.c:465
#4  0x40029118 in accept (s=3, name=0x43feccf0, namelen=0x43feccec) at rtems/.../rtems_syscall.c:215
#5  0x40004028 in daemon () at rtems/c/src/libnetworking/rtems_servers/ftpd.c:1925
#6  0x40053388 in _Thread_Handler () at rtems/cpukit/score/src/threadhandler.c:123
#7  0x40053270 in __res_mkquery (op=0, dname=0x0, class=0, type=0, data=0x0, datalen=0, newrr_in=0x0,
                        buf=0x0, buflen=0)
    at ../rtems/cpukit/libnetworking/libc/res_mkquery.c:199
#8  0x00000008 in ?? ()
#9  0x00000008 in ?? ()
Previous frame identical to this frame (corrupt stack?)
```

In comparison to GRMON the **frame** command in GDB can be used to select a individual stack frame. One can also step between frames by issuing the **up** or **down** commands. The CPU registers can be listed using the **info registers** command. Note that the **info registers** command only can see the following registers for an inactive task: g0-g7, l0-l7, i0-i7, o0-o7, PC and PSR. The other registers will be displayed as 0:

```
gdb) frame 5

#5  0x40004028 in daemon () at rtems/.../rtems_servers/ftpd.c:1925
1925       ss = accept(s, (struct sockaddr *)&addr, &addrLen);

(gdb) info reg

g0            0x0       0
g1            0x0       0
g2            0xffffffff     -1
g3            0x0       0
g4            0x0       0
g5            0x0       0
g6            0x0       0
g7            0x0       0
o0            0x3       3
o1            0x43feccf0     1140772080
o2            0x43feccec     1140772076
o3            0x0       0
o4            0xf34000e4     -213909276
o5            0x4007cc00     1074252800
sp            0x43fecc88     0x43fecc88
o7            0x40004020     1073758240
l0            0x4007ce88     1074253448
l1            0x4007ce88     1074253448
l2            0x400048fc     1073760508
l3            0x43feccf0     1140772080
l4            0x3       3
```

```
l5              0x1       1
l6              0x0       0
l7              0x0       0
i0              0x0       0
i1              0x40003f94        1073758100
i2              0x0       0
i3              0x43ffafc8        1140830152
i4              0x0       0
i5              0x4007cd40        1074253120
fp              0x43fecd08        0x43fecd08
i7              0x40053380        1074082688
y               0x0       0
psr             0xf34000e0        -213909280
wim             0x0       0
tbr             0x0       0
pc              0x40004028        0x40004028 <daemon+148>
npc             0x4000402c        0x4000402c <daemon+152>
fsr             0x0       0
csr             0x0       0
```

It is not supported to set thread specific breakpoints. All breakpoints are global and stops the execution of all threads. It is not possible to change the value of registers other than those of the current thread.

3.7.7. Virtual memory

There is no way for GRMON to determine if an address sent from GDB is physical or virtual. If an MMU unit is present in the system and it is enabled, then GRMON will assume that all addresses are virtual and try to translate them. When debugging an application that uses the MMU one typically have an image with physical addresses used to load data into the memory and a second image with debug-symbols of virtual addresses. It is therefore important to make sure that the MMU is enabled/disabled when each image is used.

The example below will show a typical case on how to handle virtual and physical addresses when debugging with GDB. The application being debugged is Linux and it consists of two different images created with Linuxbuild. The file image.ram contains physical addresses and a small loader, that among others configures the MMU, while the file image contains all the debug-symbols in virtual address-space.

First start GRMON and start the GDB server.

```
$ grmon -nb -gdb
```

Then start GDB in a second shell, load both files into GDB, connect to GRMON and then upload the application into the system. The addresses will be interpreted as physical since the MMU is disabled when GRMON starts.

```
$ sparc-linux-gdb
GNU gdb 6.8.0.20090916-cvs
Copyright (C) 2008 Free Software Foundation, Inc.
License GPLv3+: GNU GPL version 3 or later <http://gnu.org/licenses/gpl.html>
This is free software: you are free to change and redistribute it.
There is NO WARRANTY, to the extent permitted by law.  Type "show copying"
and "show warranty" for details.
This GDB was configured as "--host=i686-pc-linux-gnu --target=sparc-linux".
(gdb) file output/images/image.ram
Reading symbols from /home/user/linuxbuild-1.0.2/output/images/image.ram...(no d
ebugging symbols found)...done.
(gdb) symbol-file output/images/image
Reading symbols from /home/user/linuxbuild-1.0.2/output/images/image...done.
(gdb) target extended-remote :2222
Remote debugging using :2222
t_tflt () at /home/user/linuxbuild-1.0.2/linux/linux-2.6-git/arch/sparc/kernel/h
ead_32.S:88
88 t_tflt: SPARC_TFAULT                     /* Inst. Access Exception
 */
Current language:  auto; currently asm
(gdb) load
Loading section .text, size 0x10b0 lma 0x40000000
Loading section .data, size 0x50 lma 0x400010b0
Loading section .vmlinux, size 0x3f1a60 lma 0x40004000
Loading section .startup_prom, size 0x7ee0 lma 0x403f5a60
Start address 0x40000000, load size 4172352
Transfer rate: 18 KB/sec, 765 bytes/write.
```

The program must reach a state where the MMU is enabled before any virtual address can be translated. Software breakpoints cannot be used since the MMU is still disabled and GRMON won't translate them into a physical.

Hardware breakpoints don't need to be translated into physical addresses, therefore set a hardware assisted break-point at 0xf0004000, which is the virtual start address for the Linux kernel.

```
(gdb) hbreak *0xf0004000
Hardware assisted breakpoint 1 at 0xf0004000: file /home/user/linuxbuild-1.0.2/l
inux/linux-2.6-git/arch/sparc/kernel/head_32.S, line 87.
(gdb) cont
Continuing.

Breakpoint 1, trapbase_cpu0 () at /home/user/linuxbuild-1.0.2/linux/linux-2.6-gi
t/arch/sparc/kernel/head_32.S:87
87 t_zero: b gokernel; nop; nop; nop;
```

At this point the loader has enabled the MMU and both software breakpoints and symbols can be used.

```
(gdb) break leon_init_timers
Breakpoint 2 at 0xf03cff14: file /home/user/linuxbuild-1.0.2/linux/linux-2.6-git
/arch/sparc/kernel/leon_kernel.c, line 116.

(gdb) cont
Continuing.

Breakpoint 2, leon_init_timers (counter_fn=0xf00180c8 <timer_interrupt>)
    at /home/user/linuxbuild-1.0.2/linux/linux-2.6-git/arch/sparc/kernel/leon_ke
rnel.c:116
116  leondebug_irq_disable = 0;
Current language:  auto; currently c
(gdb) bt
#0  leon_init_timers (counter_fn=0xf00180c8 <timer_interrupt>)
    at /home/user/linuxbuild-1.0.2/linux/linux-2.6-git/arch/sparc/kernel/leon_ke
rnel.c:116
#1  0xf03ce944 in time_init () at /home/user/linuxbuild-1.0.2/linux/linux-2.6-gi
t/arch/sparc/kernel/time_32.c:227
#2  0xf03cc13c in start_kernel () at /home/user/linuxbuild-1.0.2/linux/linux-2.6
-git/init/main.c:619
#3  0xf03cb804 in sun4c_continue_boot ()
#4  0xf03cb804 in sun4c_continue_boot ()
Backtrace stopped: previous frame identical to this frame (corrupt stack?)
(gdb) info locals
eirq = <value optimized out>
rootnp = <value optimized out>
np = <value optimized out>
pp = <value optimized out>
len = 13
ampopts = <value optimized out>
(gdb) print len
$2 = 13
```

If the application for some reason need to be reloaded, then the MMU must first be disabled via the GRMON command **gdb reset**. It is similar to the regular **reset** command, but it will retain some of the state which GDB exptects to be intact.

In addition all software breakpoints should be deleted before the application is restarted since the MMU has been disabled and GRMON won't translate virtual addresses anymore.

```
(gdb) mon mmu mctrl 0
mctrl: 006E0000  ctx: 00000000  ctxptr: 40440800  fsr: 00000000  far: 00000000
(gdb) delete
Delete all breakpoints? (y or n) y
(gdb) monitor gdb reset

(gdb) load
Loading section .text, size 0x10b0 lma 0x40000000
Loading section .data, size 0x50 lma 0x400010b0
Loading section .vmlinux, size 0x3f1a60 lma 0x40004000
Loading section .startup_prom, size 0x7ee0 lma 0x403f5a60
Start address 0x40000000, load size 4172352
Transfer rate: 18 KB/sec, 765 bytes/write.
(gdb) hbreak *0xf0004000
Hardware assisted breakpoint 3 at 0xf0004000: file /home/user/linuxbuild-1.0.2/l
inux/linux-2.6-git/arch/sparc/kernel/head_32.S, line 87.
(gdb) run
The program being debugged has been started already.
Start it from the beginning? (y or n) y
Starting program: /home/user/linuxbuild-1.0.2/output/images/image.ram

Breakpoint 3, trapbase_cpu0 () at /home/user/linuxbuild-1.0.2/linux/linux-2.6-gi
t/arch/sparc/kernel/head_32.S:87
87 t_zero: b gokernel; nop; nop; nop;
Current language:  auto; currently asm
```

```
(gdb) break leon_init_timers
Breakpoint 4 at 0xf03cff14: file /home/user/linuxbuild-1.0.2/linux/linux-2.6-git
/arch/sparc/kernel/leon_kernel.c, line 116.
(gdb) cont
Continuing.

Breakpoint 4, leon_init_timers (counter_fn=0xf00180c8 <timer_interrupt>)
    at /home/user/linuxbuild-1.0.2/linux/linux-2.6-git/arch/sparc/kernel/leon_ke
rnel.c:116
116  leondebug_irq_disable = 0;
Current language:  auto; currently c
```

3.7.8. Specific GDB optimization

GRMON detects GDB access to register window frames in memory which are not yet flushed and only reside in the processor register file. When such a memory location is read, GRMON will read the correct value from the register file instead of the memory. This allows GDB to form a function trace-back without any (intrusive) modification of memory. This feature is disabled during debugging of code where traps are disabled, since no valid stack frame exist at that point.

3.7.9. GRMON GUI considerations

The Graphical User Interface of GRMON can be used in parallel with GDB C/C++ level debugging. More details are described in Section 4.7, "C/C++ level debugging".

3.7.10. Limitations of GDB interface

GDB must be built for the SPARC architecture, a native PC GDB does not work together with GRMON. The toolchains that Cobham Gaisler distributes comes with a patched and tested version of GDB targeting all SPARC LEON development tools.

Do not use the GDB **where** commands in parts of an application where traps are disabled (e.g.trap handlers). Since the stack pointer is not valid at this point, GDB might go into an infinite loop trying to unwind false stack frames. The thread support might not work either in some trap handler cases.

The step instruction commands **si** or **stepi** are implemented by GDB inserting software breakpoints through GR-MON. This is an approach that is not possible when debugging in read-only memory such as boot sequences executed in PROM/FLASH. One can instead use hardware breakpoints using the GDB command **hbreak** manually.

3.8. Thread support

GRMON has thread support for the operating systems shown below. The thread information is accessed using the GRMON **thread** command. The GDB interface of GRMON is also thread aware and the related GDB commands are described in the GDB documentation and in Section 3.7.6, "GDB Thread support".

Supported operating systems

- RTEMS
- VXWORKS
- eCos
- Bare-metal

GRMON needs the symbolic information of the image that is being debugged in order to retrieve the addresses of the thread information. Therefore the symbols of the OS must be loaded automatically by the ELF-loader using **load** or manually by using the **symbols** command. GRMON will traverse the thread structures located in the target's memory when the **thread** command is issued or when GDB requests thread information. Bare-metal threads are used by default if no OS threads can be found. In addition the startup switch `-bmthreads` can be used to force bare-metal threads.

The target's thread structures are never changed, and they are only accessed when the **thread** command is executed. Starting GRMON with the `-nothreads` switch disables the thread support in GRMON and the GDB server.

During debugging sessions it can help the developer a lot to view all threads, their stack traces and their states to understand what is happening in the system.

3.8.1. GRMON thread options

The following command-line options are available for selecting how GRMON3 will handle threads.

   `-nothreads`
      Disable thread support.

   `-bmthreads`
      Force bare-metal thread support

   `-rtems version`
      Set RTEMS version for thread support, where the required argument `version` is one of the following:

      `rcc-1.3.0`

      `rcc-1.3-rc9`

      `rcc-1.3-rc8`

      `rcc-1.3-rc7`

      `rcc-1.3-rc6`

      `rtems-6.0`

      `rtems-5.1`

      `rtems-5.0`

      `rtems-4.12`

      `rtems-4.11`

      `rtems-4.10`

      `rtems-4.8`

      `rtems-4.6`

3.8.2. GRMON thread commands

thread info lists all threads currently available in the operating system. The currently running thread is marked with an asterisk.

```
grmon> thread info

  Name | Type     | Id         | Prio | Ticks   | Entry point               | PC         | State
  ------------------------------------------------------------------------------------------------
  Int. | internal | 0x09010001 | 255  |     138 | _CPU_Thread_Idle_body     | 0x4002f760 | READY
  ------------------------------------------------------------------------------------------------
  UI1  | classic  | 0x0a010001 | 120  |     290 | Init                      | 0x4002f760 | READY
  ------------------------------------------------------------------------------------------------
  ntwk | classic  | 0x0a010002 | 100  |      11 | rtems_bsdnet_schedneti    | 0x4002f760 | READY
  ------------------------------------------------------------------------------------------------
  DCrx | classic  | 0x0a010003 | 100  |       2 | rtems_bsdnet_schedneti    | 0x4002f760 | Wevnt
  ------------------------------------------------------------------------------------------------
  DCtx | classic  | 0x0a010004 | 100  |       4 | rtems_bsdnet_schedneti    | 0x4002f760 | Wevnt
  ------------------------------------------------------------------------------------------------
  FTPa | classic  | 0x0a010005 |  10  |       1 | split_command             | 0x4002f760 | Wevnt
  ------------------------------------------------------------------------------------------------
  FTPD | classic  | 0x0a010006 |  10  |       1 | split_command             | 0x4002f760 | Wevnt
  ------------------------------------------------------------------------------------------------
* HTPD | classic  | 0x0a010007 |  40  |      79 | rtems_initialize_webse    | 0x40001b60 | READY
  ------------------------------------------------------------------------------------------------
```

thread bt ?id? lists the stack backtrace. **bt** lists the backtrace of the currently executing thread as usual.

```
grmon> thread bt 0x0a010003

     %pc
#0   0x4002f760   _Thread_Dispatch + 0x11c
#1   0x40013ed8   rtems_event_receive + 0x88
#2   0x40027824   rtems_bsdnet_event_receive + 0x18
#3   0x4000b664   websFooter + 0x484
#4   0x40027708   rtems_bsdnet_schednetisr + 0x158
```

A backtrace of the current thread (equivalent to the **bt** command):

```
grmon> thread bt 0x0a010007

     %pc          %sp
#0   0x40001b60   0x43fea130   console_outbyte_polled + 0x34
#1   0x400017fc   0x43fea130   console_write_support + 0x18
#2   0x4002dde8   0x43fea198   rtems_termios_puts + 0x128
#3   0x4002df60   0x43fea200   rtems_termios_puts + 0x2a0
#4   0x4002dfe8   0x43fea270   rtems_termios_write + 0x70
```

```
#5   0x400180a4   0x43fea2d8   rtems_io_write + 0x48
#6   0x4004eb98   0x43fea340   device_write + 0x2c
#7   0x40036ee4   0x43fea3c0   write + 0x90
#8   0x4001118c   0x43fea428   trace + 0x38
#9   0x4000518c   0x43fea498   websOpenListen + 0x108
#10  0x40004fb4   0x43fea500   websOpenServer + 0xc0
#11  0x40004b0c   0x43fea578   rtems_initialize_webserver + 0x204
#12  0x40004978   0x43fea770   rtems_initialize_webserver + 0x70
#13  0x40053380   0x43fea7d8   _Thread_Handler + 0x10c
#14  0x40053268   0x43fea840   __res_mkquery + 0x2c8
```

3.9. Forwarding application console I/O

If GRMON is started with `-u [N]` (N defaults to zero - the first UART), the LEON UART[N] is placed in FIFO debug mode or in loop-back mode. Debug mode was added in GRLIB 1.0.17-b2710 and is reported by **info sys** in GRMON as *"DSU mode (FIFO debug)"*, older hardware is still supported using loop-back mode. In both modes flow-control is enabled. Both in loop-back mode and in FIFO debug mode the UART is polled regularly by GRMON during execution of an application and all console output is printed on the GRMON console. When `-u` is used there is no point in connecting a separate terminal to UART1.

In addition it is possible to enable or disable UART forwarding using the command **forward**. Optionally it is also possible to forward the I/O to a custom TCL channel using this command.

With FIFO debug mode it is also possible to enter text in GRMON which is inserted into the UART receive FIFO. These insertions will trigger interrupts if receiver FIFO interrupts are enabled. This makes it possible to use GRMON as a terminal when running an interrupt-driven O/S such as Linux or VxWorks.

The following restrictions must be met by the application to support either loop-back mode or FIFO debug mode:

1. The UART control register must not be modified such that neither loop-back nor FIFO debug mode is disabled
2. In loop-back mode the UART data register must not be read

This means that `-u` cannot be used with PROM images created by MKPROM. Also loop-back mode can not be used in kernels using interrupt driven UART consoles (e.g. Linux, VxWorks).

The **forward start**, or the commandline option `-ucli [N]`, can be used to make the current shell start forwarding I/O. This can be used when running applications from GDB to redirect I/O to the GRMON terminal instead of the GDB terminal.

RXVT must be disabled for debug mode to work in a MSYS console on Windows. This can be done by deleting or renaming the file `rxvt.exe` inside the bin directory, e.g., `C:\msys\1.0\bin`. Starting with MSYS-1.0.11 this will be the default.

3.9.1. UART debug mode

When the application is running with UART debug mode enabled the following key sequences will be available. The sequences can be used to adjust the input to what the target system expects. For a key sequence to take effect, both key presses must be pressed within 1.5 seconds of each other. Otherwise, they will be forwarded as is.

Table 3.3. Uart control sequences

Key sequence	Action
Ctrl+A B	Toggle delete to backspace conversion
Ctrl+A C	Send break (Ctrl+C) to the running application
Ctrl+A D	Toggle backspace to delete conversion
Ctrl+A E	Toggle local echo on/off
Ctrl+A H	Show a help message
Ctrl+A N	Enable/disable newline insertion on carriage return
Ctrl+A S	Show current settings
Ctrl+A Z	Send suspend (Ctrl+Z) to the running application

Key sequence	Action
Ctrl+A Ctrl+A	Send a single Ctrl+A to the running application

3.10. EDAC protection

3.10.1. Using EDAC protected memory

Some LEON Fault-Tolerant (FT) systems use EDAC protected memory. To enable the memory EDAC during execution, GRMON should be started with the -edac switch. Before any application is loaded, the **wash** command might be issued to write all RAM memory locations and thereby initialize the EDAC check-sums. If a LEON CPU is present in the system GRMON will instruct the CPU to clear memory, clearing memory on a CPU-less system over a slow debug-link can be very time consuming.

```
$ grmon -edac
...
grmon3> wash
  40000000                        8.0MB /   8.0MB  [===============>] 100%
  60000000                      256.0MB / 256.0MB  [===============>] 100%
  Finished washing!
```

By default **wash** writes to all EDAC protected writable memory (SRAM, SDRAM, DDR, etc.) areas which has been detected or forced with a command line switch. *start* and *stop* parameters can also be given to wash a range. Washing memory with EDAC disabled will not generate check bits, however it can be used to clear or set a memory region even if the memory controller does not implement EDAC.

```
grmon3> wash 0x40000000 0x41000000
  40000000                       16.0MB /  16.0MB  [===============>] 100%
  Finished washing!
```

If the memory controller has support for EDAC with 8-bit wide SRAM memory, the upper part of the memory will consist of check bits. In this case the wash will only write to the data area (the check bits will automatically be written by the memory controller). The amount of memory written will be displayed in GRMON.

GRMON will *not* automatically write the check bits for flash PROMs. For 8-bit flash PROMs, the check bits can be generated by the mkprom2 utility and included in the image. But for 32-bit flash PROMs the check bits must be written by the user via the TCB field in MCFG3.

3.10.2. LEON3-FT error injection

All RAM blocks (cache and register-file memory) in LEON3-FT are Single Event Upset (SEU) protected. Error injection function emulates SEU in LEON3-FT memory blocks and lets the user test the fault-tolerant operation of LEON3-FT by inserting random bit errors in LEON3-FT memory blocks during program execution. An injected error flips a randomly chosen memory bit in one of the memory blocks, effectively emulating a SEU. The user defines error rate and can choose between two error distribution modes:

1. **Uniform error distribution mode.** The **'ei un NR T'** command instructs GRMON to insert *NR* errors during the time period of *T* minutes. After *T* minutes has expired no more errors are inserted, but the application will continue its execution.
2. **Average error rate mode.** With the **'ei av R'** command the user selects at which rate errors are injected. Average error rate is *R* errors per second. Randomly generated noise is added to every error injection sample. The time between two samples vary between zero up to two periods depending on the noise, where one period is *1/R* seconds. Errors are inserted during the whole program execution.

GRMON can also perform error correction monitoring and report error injection statistics including number of detected and injected errors and error coverage, see **ei** command reference.

Error injection is performed during the run-loop of GRMON, to improve the performance and accuracy other services in the run-loop should be disabled. For example profiling and UART tunneling should be disabled, and one should select the fastest debug-link.

```
grmon> load rtems-tasks
  40000000, .text                113.9kB / 113.9kB   [===============>] 100%
  4001c7a0, .data                  2.7kB /   2.7kB   [===============>] 100%
  Total size: 116.56kB (786.00kbit/s)
  Entry point 0x40000000
  Image /home/daniel/examples/v8/stanford.exe loaded
```

```
grmon> ei un 100 1
Error injection enabled
100 errors will be injected during 1.0 min

grmon> ei stat en
Error injection statistics enabled

grmon> run

...

grmon> ei stat
 itag  :    5/   5 (100.0%)    idata:     5/  18 ( 27.8%)
 dtag  :    1/   1 (100.0%)    ddata:     4/  22 ( 18.2%)
 IU RF :    4/  10 ( 25.0%)
 FPU RF:    0/   4 (  0.0%)
 Total :   19/  60 ( 31.7%)
grmon>
```

The real time elapsed is always greater than LEON CPU experienced since the LEON is stopped during error injection. Times and rates given to GRMON are relative the experienced time of the LEON. The time the LEON is stopped is taken into account by GRMON, however minor differences is to be expected.

3.11. FLASH programming

3.11.1. CFI compatible Flash PROM

GRMON supports programming of CFI compatible flash PROMs attached to the external memory bus, through the **flash** command. Flash programming is only supported if the target system contains one of the following memory controllers MCTRL, FTMCTRL, FTSRCTRL or SSRCTRL. The PROM bus width can be 8-, 16- or 32-bit. It is imperative that the PROM width in the MCFG1 register correctly reflects the width of the external PROM.

To program 8-bit and 16-bit PROMs, GRMON must be able to do byte (or half-word) accesses to the target system. To support this either connect with a JTAG debug link or have at least one working SRAM/SDRAM bank and a CPU available in the target system.

Programming the EDAC checkbits for 8- or 32-bit PROMs is also supported. GRMON will automatically program the checkbits if EDAC is enabled. EDAC can be enabled by the -edac commandline option, using the mcfg3 command or setting the register bit via the TCL variable mctrl#::mcfg3::pe. When programming 32-bit EDAC checkbits it is required that no other AHB master is accessing the memory. Other masters can for example be DMA or Spacewire RMAP accesses. When programming 8-bit EDAC checkbits, GRMON will ignore any data that should have been written to the EDAC area of the memory.

There are many different suppliers of CFI devices, and some implements their own command set. The command set is specified by the CFI query register 14 (MSB) and 13 (LSB). The value for these register can in most cases be found in the datasheet of the CFI device. GRMON supports the command sets that are listed in Table 3.4, "Supported CFI command set".

Table 3.4. Supported CFI command set

Q13	Q14	Description
0x01	0x00	Intel/Sharp Extended Command Set
0x02	0x00	AMD/Fujitsu Standard Command Set
0x03	0x00	Intel Standard Command Set
0x00	0x02	Intel Performance Code Command

Some flash chips provides lock protection to prevent the flash from being accidentally written. The user is required to actively lock and unlock the flash. Note that the memory controller can disable all write cycles to the flash also, however GRMON automatically enables PROM write access before the flash is accessed.

The flash device configuration is auto-detected, the information is printed out like in the example below. One can verify the configuration so that the auto-detection is correct if problems are experienced. The block lock status (if implement by the flash chip) can be viewed like in the following example:

```
grmon3> flash
  Manuf.        : Intel
  Device        : MT28F640J3
  Device ID     : 09169e01734a9981
  User ID       : ffffffffffffffff

  1 x 8 Mbytes = 8 Mbytes total @ 0x00000000

  CFI information
  Flash family  : 1
  Flash size    : 64 Mbit
  Erase regions : 1
  Erase blocks  : 64
  Write buffer  : 32 bytes
  Lock-down     : Not supported
  Region  0     : 64 blocks of 128 kbytes

 grmon3> flash status
  Block lock status: U = Unlocked; L = Locked; D = Locked-down
  Block   0 @ 0x00000000 : L
  Block   1 @ 0x00020000 : L
  Block   2 @ 0x00040000 : L
  Block   3 @ 0x00060000 : L
...
  Block  60 @ 0x00780000 : L
  Block  61 @ 0x007a0000 : L
  Block  62 @ 0x007c0000 : L
  Block  63 @ 0x007e0000 : L
```

A typical command sequence to erase and re-program a flash memory could be:

```
grmon3> flash unlock all
  Unlock complete

grmon3> flash erase all
  Erase in progress
  Block @ 0x007e0000 : code = 0x80  OK
  Erase complete

grmon3> flash load rom_image.prom
...
grmon3> flash lock all
  Lock complete
```

3.11.2. SPI memory device

GRMON supports programming of SPI memory devices that are attached to a SPICTRL or SPIMCTRL core. The flash programming commands are available through the cores' debug drivers. A SPI flash connected to the SPIC-TRL controller is programmed using **'spi flash'**, for SPIMCTRL connected devices the **'spim flash'** command is used instead. See the command reference for respective command for the complete syntax, below are some typical use cases exemplified.

When interacting with a memory device via SPICTRL the driver assumes that the clock scaler settings have been initialized to attain a frequency that is suitable for the memory device. When interacting with a memory device via SPIMCTRL all commands are issued with the normal scaler setting unless the alternate scaler has been enabled.

A command sequence to save the original first 32 bytes of data before erasing and programming the SPI memory device connected via SPICTRL could be:

```
spi set div16
spi flash select 1
spi flash dump 0 32 32bytes.srec
spi flash erase
spi flash load romfs.elf
```

The first command initializes the SPICTRL clock scaler. The second command selects a SPI memory device configuration and the third command dumps the first 32 bytes of the memory device to the file 32bytes.srec. The fourth command erases all blocks of the SPI flash. The last command loads the ELF-file romfs.elf into the device, the addresses are determined by the ELF-file section address.

Below is a command sequence to dump the data of a SPI memory device connected via SPIMCTRL. The first command tries to auto-detect the type of memory device. If auto-detection is successful GRMON will report the device selected. The second command dumps the first 128 bytes of the memory device to the file 128bytes.srec.

```
spim flash detect
spim flash dump 0 128 128bytes.srec
```

3.12. Automated operation

GRMON can be used to perform automated non-interactive tasks. Some examples are:

- Test suite execution and checking
- Stand-alone memory test with scripted access patterns
- Generate SpaceWire or Ethernet traffic
- Peripheral register access during hardware bring-up without involving a CPU
- Evaluate how a large set of compiler option permutations affect application performance

3.12.1. Tcl commanding during CPU execution

In many situations it is necessary to execute GRMON Tcl commands at the same time as the processor is executing. For example to monitor a specific register or a memory region of interest. Another use case is to change system state independent of the processor, such as error injection.

When the target executes, the GRMON terminal is assigned to the target system console and is thus not available for GRMON shell input. Furthermore, commands such as **run** and **cont** return to the user first when execution has completed, which could be never for a non-behaving program.

Three different methods for executing Tcl commands during target execution are described below:

- *Spawn one or more user Tcl shells.* The user shells run in their own thread independent of the shell controlling CPU execution. This is done with the **usrsh** command.
- *Detach GRMON from the target.* This means that the application continues running with GRMON no longer having control over the execution. This is done with the **detach** and **attach** commands.

3.12.2. Communication channel between target and monitor

A communication channel between GRMON and the target can be created by sharing memory. Use cases include when a target produces log or trace data in memory at run-time which is continuously consumed by GRMON reading out the the data over the debug link. For this to work safely without the need to stop execution, some arbitration over the data has to be implemented, such as a wait-free software FIFO.

As an example, the target processors could produce log entries into dedicated memory buffers which are monitored by an exec hook. When new data is available for the consumer, the exec hook schedules an asynchronous bus read with **amem** to fetch all new data. When the asynchronous bus read has finished, the exec hook acknowledges that the data has been consumed so that the buffer can be reused for more produce data. One benefit of using **amem** is that multiple buffers can be defined and fetched simultaneously independent of each other.

3.12.3. Test suite driver

GRMON can be used with a driver script for automatic execution of a test suite consisting of self-checking LEON applications. For this purpose a script is created which contains multiple **load** and **run** commands followed by system state checking at end of each target execution. State checking could by implemented by checking an application return value in a CPU register using the **reg** command. In case an anomaly is detected by the driver script, the system state is dumped with commands such as **reg**, **bt**, **inst** and **ahb** for later inspection. All command output is written to a log file specified with the GRMON command line option -log. It is also useful to implement a time-out mechanism in an exec hook to mitigate against non-terminating applications.

The example below shows a simple test suite driver which uses some of the techniques described in this section to test the applications named test000.elf, test001.elf and test002.elf. It can be run by issuing

```
$ grmon <debuglink> -u -c testsuite.tcl -log testsuite.log
$ grep FAIL testsuite.log
```

in the host OS shell. Target state will be dumped in the log file testsuite.log for each test case which returns nonzero or crashes.

Example 3.1. Test suite driver example

```
# This is testsuite.tcl
set nfail 0

proc dumpstate {} {
        bt; thread info; reg; inst 256; ahb 256; info reg
}

proc testprog {tname} {
        global nfail
        puts "### TEST $tname BEGIN"
        load $tname
        set tstart [clock seconds]
        set results [run]
        set tend [clock seconds]
        puts [format "### Test executed %d seconds" [expr $tend - $tstart]]
        set exec_ok 0
        foreach result $results {
                if {$result == "SIGTERM"} {
                        set exec_ok 1
                }
        }
        if {$exec_ok == 1} {
                puts "### PASS: $tname"
        } else {
                incr nfail 1
                puts "### FAIL: $tname ($results)"
                dumpstate
        }
        puts "### TEST $tname END"
}

proc printsummary {} {
        global nfail
        if {0 == $nfail} {
                puts "### SUMMARY: ALL TESTS PASSED"
        } else {
                puts "### SUMMARY: $nfail TEST(S) FAILED"
        }
}

after 2000
testprog test000.elf
testprog test001.elf
testprog test002.elf
printsummary
exit
```

4. Graphical user interface

This chapter describes how to operate the Grapical User Interface (GUI) introduced with GRMON3.

4.1. Overview

The GUI provides the user with a fully interactive environment with the possibility to monitor and control different parts of the system in parallel. All functionality of the GRMON Tcl command line interface are accessible from the terminal emulator view.

GRMON visualises hardware state by views includes the following functions:

- Debug-link and system configuration dialog
- Multi-core LEON and OS threads execution status and backtrace view
- Disassembly view with symbol and breakpoint information
- Memory, CPU register and I/O register inspection and edit views
- Optimized SPARC/LEON IU register view
- Basic execution control such as single-stepping, continuing, breaking
- Application launch dialog
- Tcl terminal views with history, tab-completion, etc.
- Application terminals via UART forwarding
- GRLIB SOC system hardware overview
- Breakpoints view showing breakpoint and watchpoint information

Users which are already familiar with the GRMON CLI can use the GUI as a drop-in replacement with the added interactive functionality.
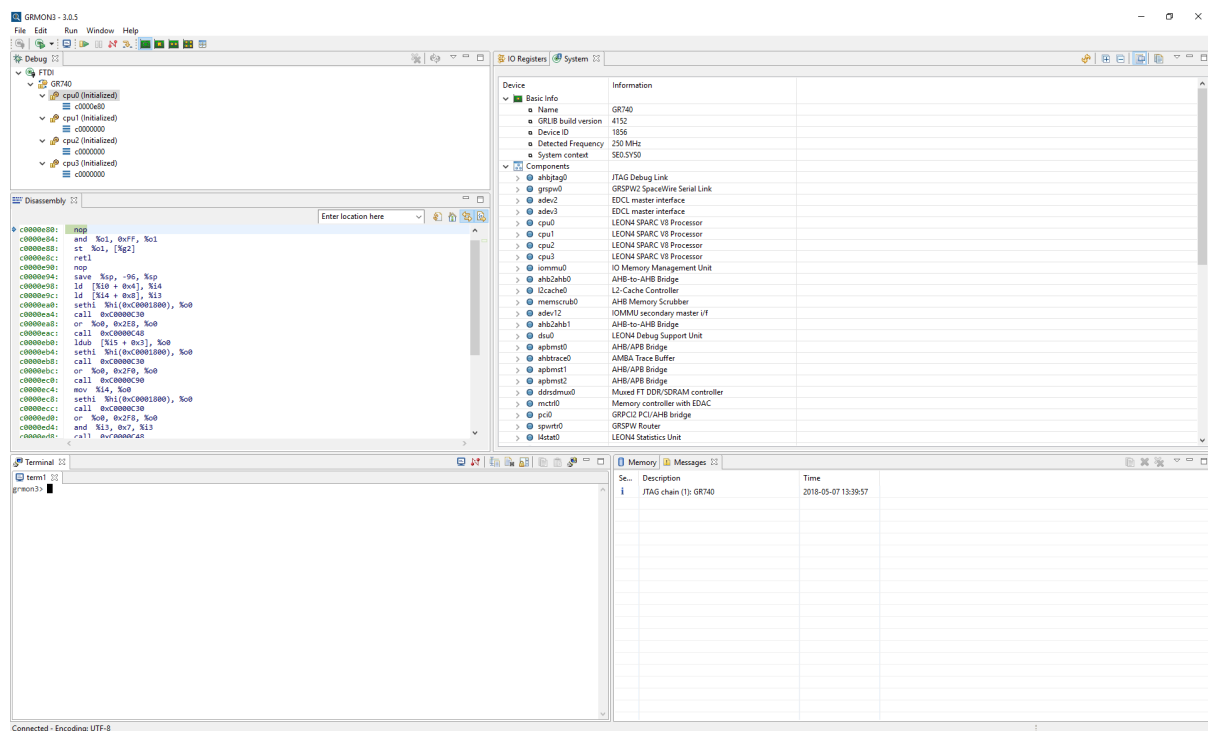

Figure 4.1. The GRMON graphical user interface

4.2. Starting GRMON GUI

GRMON is started by executing the same **grmon** or **grmon.exe** binary as the CLI version. The switches described in Section 3.2.3, "General options" determine the start-up operation.

If GRMON is started without any debug link command line options, then GRMON will start the GUI and open a dialog window which allows for selecting debug link. This is described in Section 4.3, "Connect to target".

```
$ grmon
```

GRMON can optionally be started with the `-gui` option which will skip the dialog for selecting debug link. In this case the GUI will start and the connection will be done according to the full command line, which must specify a debug-link. Below is an example of starting the GUI and connecting to a LEON system using the FTDI USB serial interface:

```
$ grmon -gui -ftdi
```

It is also possible to start the GUI from the command line interface by issuing the **gui** command. This is useful if GRMON is first operated as a command line tool but the user selects to continue debugging using the graphical representation of the system. The on-going debug session and hardware state will not be altered but can be operated and inspected from the GUI.

4.3. Connect to target

The *System Configurations* dialog is used to connect to the target system. It allows for selecting the debug link and parameters which system initialization. See Figure 4.2.

The *System Configurations* is split into several tabs with group related settings. Here follows a brief summary of each tab. Please browse the tabs to discover relevant settings.

- Debug Link - Choose debug link and set parameters
- System - Options related to initializations performed by GRMON when connecting to the target
- Operation - Controls how GRMON interacts with the target after connect
- Memory - Options related to memory controllers
- Misc - Driver specific options which need to be determined at connect
- GUI - Options related to how the GUI views are synchronized with the current target state
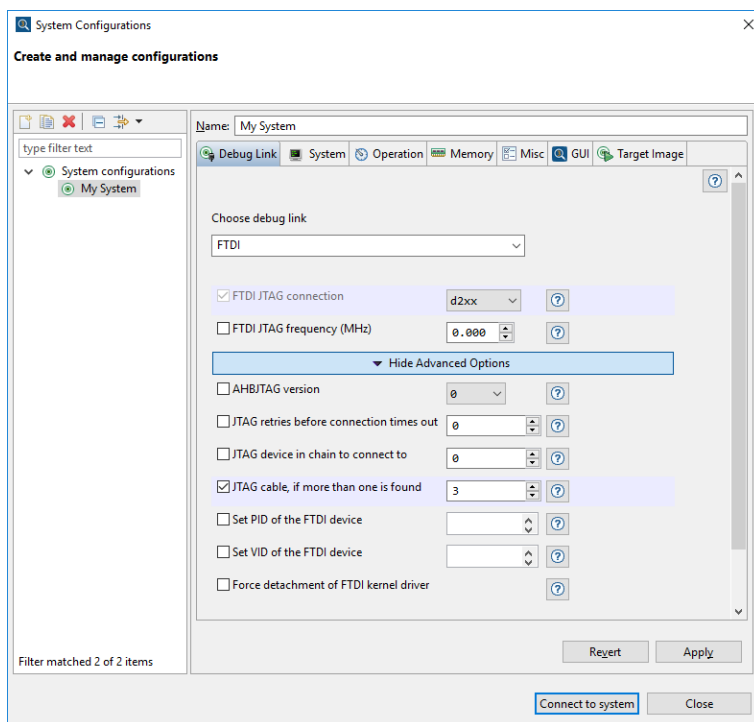

Figure 4.2. System Configurations dialog. The Debug Link tab is selected and Advanced Parameters are displayed.

4.3.1. Debug link

The debug link to use is selected in the *Choose debug link* drop down menu in the *Debug Link* tab. as illustrated in Figure 4.2. When a debug link has been selected, parameters specific for that debug link are displayed.

All debug links supported by GRMON3 are displayed in the drop down menu, including those which may not be available on the host and target system. For more information on the GRMON3 debug links and their individual options, see Chapter 5, *Debug link*.

4.3.2. Options

The options presented in *System Configurations* are equivalent to the command-line options available in GRMON3 CLI. Clicking on the *"?"* icon next to an option will open the option specific documentation. Target initialization and system related options can be activated in the different tabs of the connection dialog. This is done by clicking on the button to the left of the parameter name, or on the name itself. A selected parameter is marked with a button with an *"X"* and a different background color.
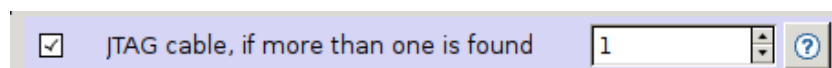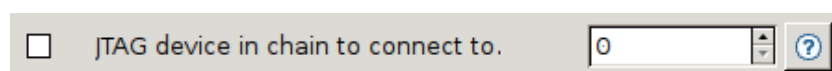

Figure 4.3. A selected parameter

Figure 4.4. A non-selected parameter

The most common GRMON options are always displayed in the respective tab. More GRMON options can be displayed by clicking the *Show Advanced Parameters...* button.

4.3.3. Argument contribution

When a parameter or setting is selected, the corresponding command line argument is shown in the *Argument contribution* box. All selected parameters and settings from the current tab is shown in the box. Switching tabs will show different argument contributions.

Note that the debug link always contributes with an argument to the *Argument contribution* box. For example choosing the USB debug link will add the argument -usb.

4.3.4. Configurations

Multiple system configurations can be used and managed in the connection dialog. This is useful for example when the same host is used to connect to many different target systems. Another use case for the system configurations is as a convenient way for connecting to the same target, but with different initialization options.

To create a new System Configuration, either click the new configuration button , or clone the current config-uration by clicking the copy button . Delete a configuration using the delete button . These options are also available from the context menu of the configuration in the listing on the left of the dialog.

When a configuration is modified, the two buttons *Revert* and *Apply* become enabled. Pressing the *Apply* button stores the configuration, and *Revert* will undo any changes since last storage.

4.3.5. Connect

When the System Configuration is done, press the *Connect to system* button.

4.4. Launch configurations

A Launch configuration is a combination of application images and custom system preparations for images. In its most basic form a launch configuration consists of a single application image selected by the user which is loaded and started.

4.4.1. Target image setup

Once connected to a system, an image can be uploaded to the system. To setup the image and related settings, click the Target Image Configuration button 🖐 in the main tool bar, or in the main menu under File > Launch Target Image...

Figure 4.5. The Target Image Configuration dialog

A *Target Image Launch Configuration* consists of one or several application images which are associated to different CPUs. There are three different types of image launch configurations:

- *Single Core Image Launch*
- *SMP Target Image Launch*
- *AMP Target Image Launch*

An *Single Core Target Image Launch* also provides a simple interface to setup the application. This image launch type is appropriate for applications that will use a single core. In the *Single Core Target Image Launch*, properties are always assigned to the first cpu.

An *SMP Target Image Launch* provides an interface to setup the application for multiple cores. This image launch type is appropriate for applications based on an SMP operating system, such as RTEMS SMP or VxWorks SMP. In the *SMP Target Image Launch*, properties are always assigned to all CPUs.

In an *AMP Target Image Launch*, the user has full flexibility to assign launch properties for each CPU. This is useful when different operating system instances are executed on different processors or sets of processors.

CPUs are added or removed by the user to match the target system. Each setting has a value and some of them can be individually associated with one or more CPUs. For instance a breakpoint and symbol file might be associated with CPU1, but not CPU2.

Associate a setting with a CPU by clicking the cell that intersect the setting and the CPU and tick the check box. Untick the check-box to reverse the association. Some settings can occur more than one time for the same CPU (i.e. *Symbol file*), meaning that several symbol files can be supplied. If an incompatible or unsupported combination of settings is associated to a CPU, then the background of the cells for the settings are set to bright red.

To edit the value of a setting click the cell in the *Value* column. Different settings are edited in different ways. If the cell after clicking it shows a button with "...", this button opens a dialog to change the value. For example the Image setting is edited by choosing a file from a dialog.

If any of the settings are invalid, then the dialog shows an error message at the top, and the button Launch Target Image are disabled. Once the invalid settings are corrected, the button becomes enabled and the Target Image can be launched.

A Target Image Configuration can be launched automatically at connect to the system. This can be selected in the System configuration dialog option named *Launch Target Image Configuration when connected*.

4.4.2. Launch properties

A simple launch configuration typicaly consists of only the *Image* and *Run Mode* properties. Additional properties can be added as required. The following list describes all available properties.

Properties:

Image

> File name of an image file to load. More than one image can be added and each image can be assigned to any number of CPUs.
>
> *Command:* **load**

Verify Image

> Verify each image after load to memory. The property is not CPU specific. Only one *Verify Image* property can be specified.
>
> *Command:* **verify**

Symbol file

> File name of a symbol file to load. The symbols will be loaded into GRMON but no content from the file will be loaded into the target memory. More than one image can be added and each image can be assigned to any number of CPUs.
>
> *Command:* **symbols**

Run Mode

> - *Run* - Reset GRMON drivers and start the execution from the beginning of the application.
> - *Go* - Start the execution from the beginning of the application with the current system CPU state.
>
> At most one *Run Mode* can be specified. The recommended mode is *Run* for most applications. *Go* is useful when the application itself is initilizing the target, such as a boot loader. The property is not CPU specific.
>
> Note that it is also possible to omit the *Run Mode* property. In that case, the application could be started with the **run** command in a shell.
>
> *Command:* **run**, **go**

Break at Application

> Inserts a breakpoint at application start. The breakpoint location is OS dependent, for example `main()` in a bare-metal application and `Init()` in an RTEMS application. At most one *Break at Application* property can be specified.

Command: **bp**

Break at Entry

Inserts a breakpoint at the entry point of the loaded image. At most one *Break at Application* property can be specified.

Command: **bp**

Breakpoint

Inserts a software (soft) breakpoint. The *Value* field can be either an address or a symbol name. More than one soft breakpoints can be added and each can be assigned to any number of CPUs.

Command: **bp soft**

HW Breakpoint

Inserts a hardware (hard) breakpoint. The *Value* field can be either an address or a symbol name. More than one hard breakpoint can be added and each can be assigned to any number of CPUs. Note that the number of available hardware breakpoints is target specific.

Command: **bp hard**

R/W Watchpoint, Read Watchpoint, Write Watchpoint

Inserts a read/write, read or write hardware watchpoint. The *Value* field can be either an address or a symbol name. More than one hard breakpoint can be added and each can be assigned to any number of CPUs.

Command: **bp watch**

Command: **bp watch -read**

Command: **bp watch -write**

Wash Memory

Clear all or part of memory before loading images. Multiple ranges can be defined by adding more *Wash Memory* properties. The property is not CPU specific.

Command: **wash**

Stack Pointer, Entrypoint

Override stack pointer or entry point setting. An address or symbol can be specified. At most one stack pointer per CPU can be assigned. At most one entry point per CPU can be assigned.

Command: **stack**

Command: **ep**

4.5. Views

GRMON3 GUI provides different *views* for displaying and managing the target system state. Some views are derived from the Eclipse framework, such as the *Memory View*, the *Breakpoints View* and the *Disassembly View*. Other views are customized for GRLIB/LEON systems and will be described in this section.

4.5.1. CPU Registers View

The CPU Registers view shows a selection of the CPU registers in a fixed and compact format. Which CPU registers are shown for, depends on what CPU is relevant for the selected context in the Debug view.

Values are retrieved for the registers in two situation; either the register values is changed by a known mechanism such as editing the value, or when the CPU execution is suspended. Values that have changed since last retrieval are highlighted with a yellow background.
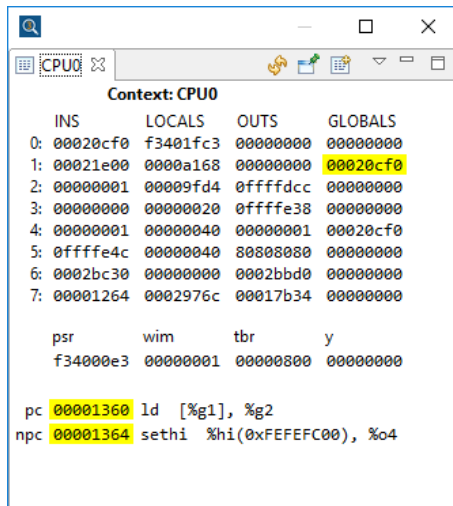
Figure 4.6. The cpu registers view

4.5.1.1. Pinning

The CPU Registers view can be pinned to a context. When the view is pinned it continues to show registers for the same context even when the selection changes in the debug view. The view then shows the pinned CPU name in the top of the view, e.g. "cpu0".

4.5.1.2. Context menu

Right click on any register value in the view to show the context menu (not relevant for the disassembly). If the text in the register value box is a valid hexadecimal value the two commands >>Open address in Memory view<< and >>Show disassembly at address<< will be available.
Open address in Memory view

Shows the Memory view and adds a memory monitor at the selected register value used as an address. The user must select the visualization, e.g. "Hex Integer".
Show disassembly at address

If no disassembly editors are open one will be opened, otherwise any opened will be used. The editor will focus on the selected register value used as an address.

4.5.2. IO Registers View

The IO Registers view allows users to inspect and modify I/O registers of AMBA devices available on the target hardware. Individual registers may be expanded into bit-fields which are presented as bit-masks or numbers. It functions much like the Eclipse Registers view, but is optimized for GRLIB SoC systems.

Registers are grouped under the AMBA device it belongs to. A device may have registers from both APB and AHB I/O space. The view presents the same information as the info CLI command.

The register view adapts to the register information available in GRMON. Users can add registers and bit-field declarations for custom IP-cores by means of Tcl drivers as described in Appendix C, *Tcl API*. Registers unknown to GRMON will not appear in the view.

Figure 4.7. The I/O registers view

Register values that are changed since last update are highlighted with yellow. When expanding the register nodes in the tree of the view, the left column is auto expanded to fit the content.

For bit registers consisting of only one bit, a flag, the value can be toggled by clicking the value, and then checking or un-checking the check-box.

By default the most common registers are presented in the view. However all registers known to GRMON may be presented by pressing the icon on the right top corner. Note that doing so may change the state of the hardware since reading certain registers may affect the state of the hardware.

Values for registers are retrieved only when they are to be shown in the view. Unless another view or operation requires the values of the registers to be loaded, the values are not retrieved until they are visible in the view.

The register values are updated from the target hardware because of a few different reason.
- Edit - when the value of a register changes as result of an edit
- Suspend - when a process is suspended, the visible registers are updated
- Refresh - the values can be re-fetched from the target hardware by pressing the refresh button, or by using the periodic refresh.

Note that changed values will not be highlighted if the register values are updated via refresh, either by clicking the refresh button or by periodic refreshes.

Click the arrow down icon in the toolbar to access the view pull down menu. Under the Layout item are different options on how to customize the appearance of the view. For instance which columns to display can be specified under *Select Columns...*.

Figure 4.8. The I/O registers menu

4.5.3. System Information View

This view shows a system overview with information about the IP-cores. The cores are listed with name, vendor, function, bus connection, address range when relevant and the driver info available.

The information shown is retrieved by GRMON from the system. If any changes are expected in the available IP-cores, or their related information, all the information can be retrieved anew from the system by pressing the *Refresh* button.

As default, the view shows only basic information for the IP-cores. Press the *Show Details* button in the toolbar to toggle between showing basic and all information.
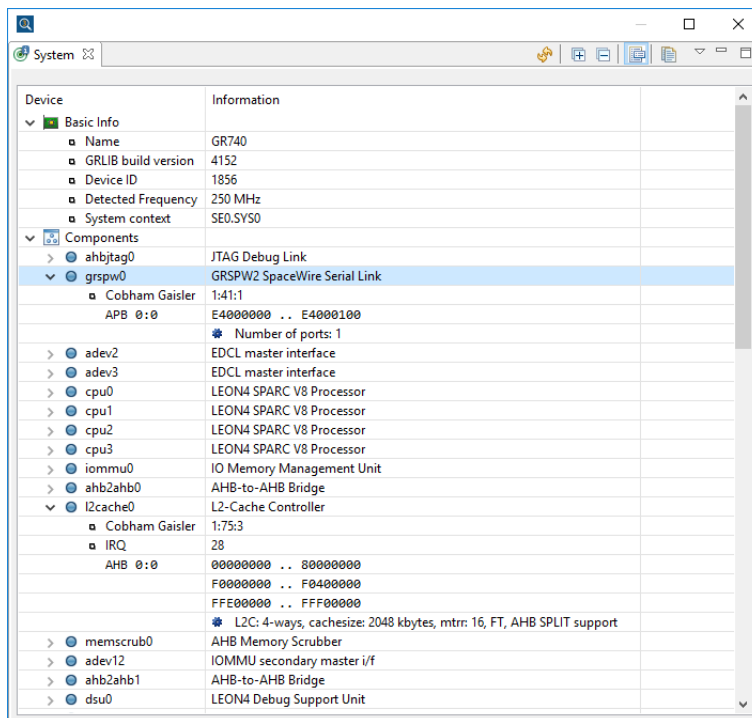
Figure 4.9. The system information view

4.5.4. Terminals View

Terminals can be opened to interact with GRMON or to display the output from an application on the target system.
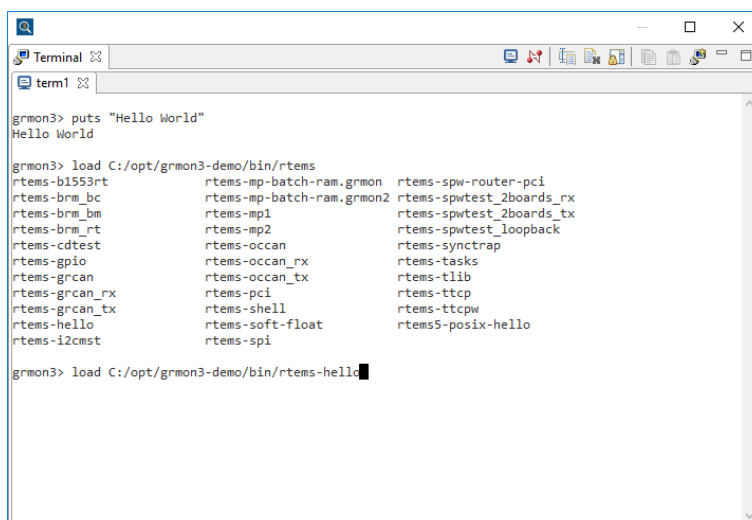
Figure 4.10. The terminals view showing a GRMON terminal

Opening a new terminal

To open a new terminal tab to either GRMON or an application on the target system, click the new terminal button ![terminal icon] in the view's toolbar. A dialog will ask for the type of the terminal. This can be either *GRMON Terminal* or *Application terminal*. The GRMON terminal has no settings that can be made.

When opening an Application terminal the dialog ask for what UART of the system to use. Already busy UARTs will be grayed out and not selectable.
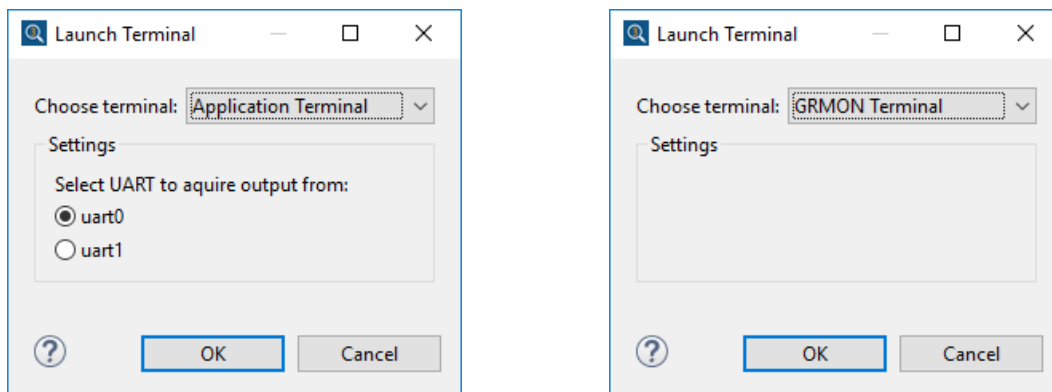
Figure 4.11. Opening a new terminal view

To open a whole new Terminals View click the new Terminal View button ![icon] in the view's toolbar.

Control characters in GRMON Terminal

The terminal accepts control characters such as Ctrl+C to break execution, and tab for auto completion, among many. Other examples are arrow up and down to access previous entries.

This also means that copy-paste can't be done via keyboard commands, and is only available from the context menu of the terminal tab.

For more information visit *Eclipse's TM Terminal site* [http://www.eclipse.org/tm/doc/index.php].

4.5.5. Memory View

The *Memory View* can be used to monitor and manipulate memory in the target system. It provides flexibility by allowing different presentations (renderings) of target memory area.

Memory View is available from the main menu under Window > Show View > Memory. When adding a new memory monitor, a dialog is displayed where the target address is specified.
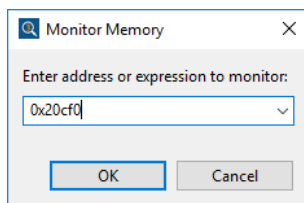
Figure 4.12. Opening a new message view

Memory content is modified by double-clicking a cell and typing in a new value. The new value is written to the target when enter is pressed.
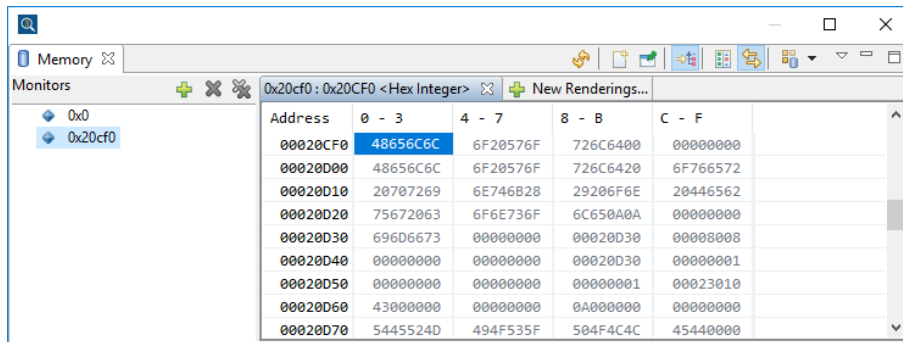
Figure 4.13. The memory view

The *Memory View* can be used to access any addressable locations as seen by the current debug link. For example IO registers in raw format. It is possible to specify the memory content presentation, for example ASCII string, by adding a new rendering from the *New Renderings...* tab. Endian can also be selected in the right-click context menu on a cell.

The Memory View is updated automatically at certain system events, for example when execution stops, or when a breakpoint is hit and after single-step by the user. This behavior can be disabled as described in Section 4.6.1, "Memory view update".

Even though GRMON GUI is CPU and context aware, the *Memory View* is global and always operate on physical addresses: no MMU translation is performed by the *Memory View*.

4.5.6. Breakpoints View

Breakpoints View keeps track of all breakpoints and watchpoints, regardless if they were created in the GUI or from the terminal. Here the user can modify or remove existing breakpoints and watchpoints and create new ones. To open the view, go to Window > Show View > Other > Debug > Breakpoints.
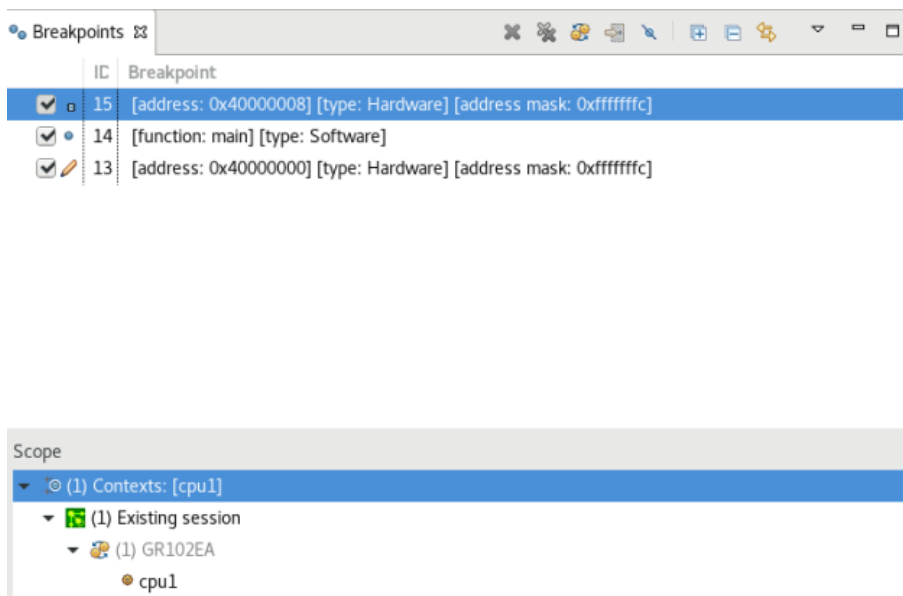
Figure 4.14. Breakpoints view

In Figure 4.14, "Breakpoints view" we see a hard breakpoint at 0x40000008 , a soft breakpoint on the function main , and a write watchpoint on 0x40000000 . There are two other watchpoint types, read , and read/write . Selecting a breakpoint or watchpoint allows us to see its scope, which in the example above is cpu1.

A breakpoint/watchpoint can be removed by clicking ![icon]. Clicking ![icon] removes all.

Clicking ![icon] disables all existing breakpoints/watchpoints, as well as any that are created and they can not be enabled again until pushing the button again. This is useful if you temporarily want to skip all breakpoints/watchpoints.

Clicking ![icon] opens up a dropdown menu.
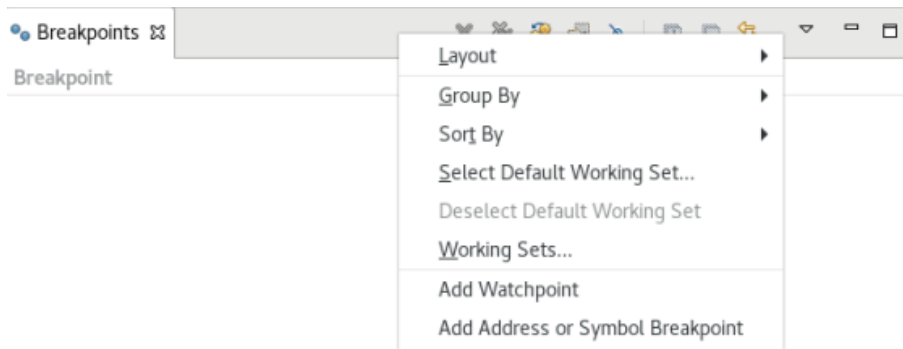
Figure 4.15. Drop down menu

Group By sorts the breakpoints in different ways, for instance by *Breakpoint Type* or *Scope*.

Add Address or Symbol Breakpoint opens up a breakpoint property page where the user can choose breakpoint type, either Regular (soft) or Hard, what address or symbol to place the breakpoint on and whether the breakpoint should be disabled or not. There is also an address mask which becomes available when choosing a Hard breakpoint.
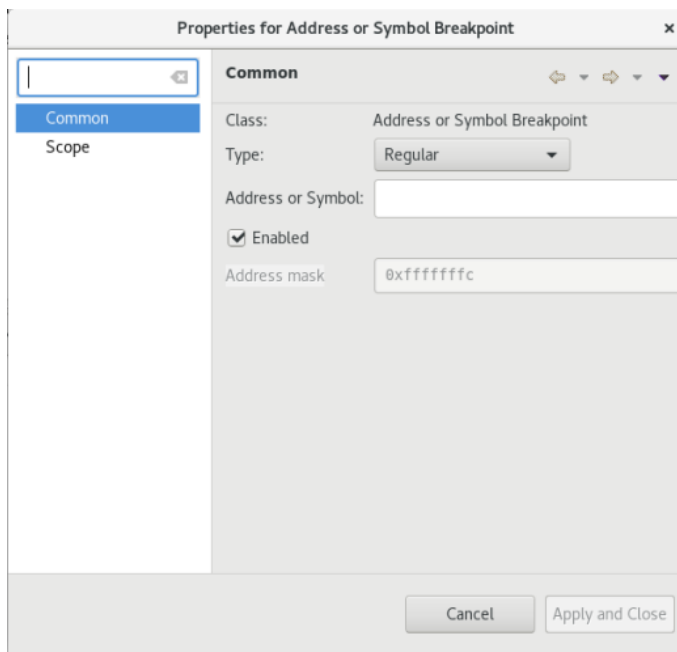
Figure 4.16. Breakpoint property page

Add Watchpoint opens up a watchpoint property page, which is similar to the breakpoint property page explained above, with the difference that you cannot choose the breakpoint type (watchpoints are always Hard type) and you can choose whether the watchpoint should be read, write or both.
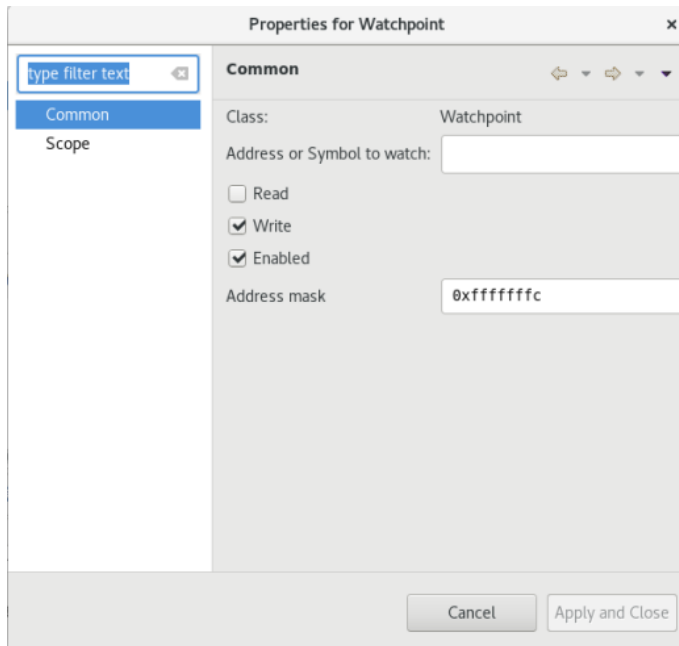
Figure 4.17. Watchpoint property page

Both of the property pages have a tab called *Scope*, where the user can choose which CPUs to place the break-point/watchpoint on. It is equivalent to specifying a cpu when placing a breakpoint/watchpoint in the terminal, i.e. putting a watchpoint on main with scope cpu0 has the same effect as typing "bp watch main cpu0" in the terminal.
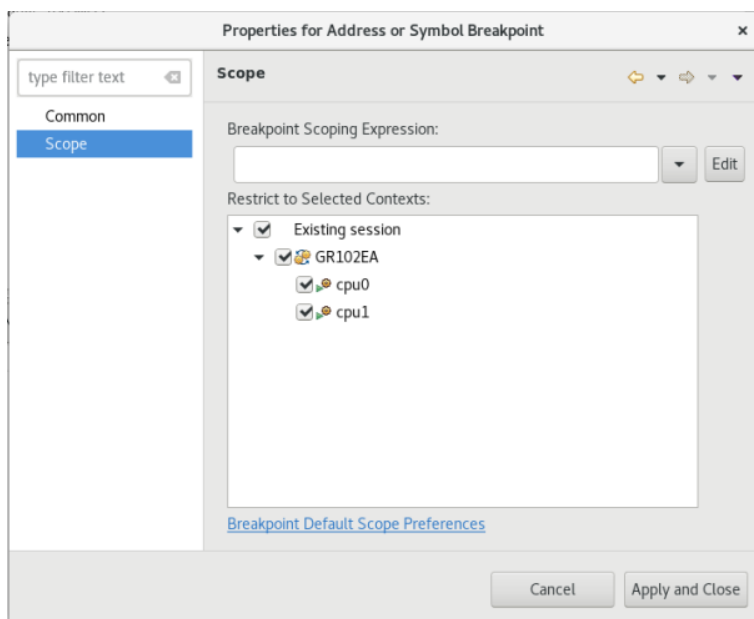
Figure 4.18. Scope page

Right-clicking in the Breakpoints view without selecting a breakpoint/watchpoint opens up a context menu.
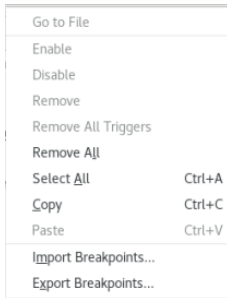
Figure 4.19. Breakpoints view context menu

Here the user can save any breakpoint/watchpoint to a *.bkpt* file by *Export Breakpoints* and import it at some other time with *Import Breakpoints*.

4.5.7. Disassembly View

Disassembly View provides a convenient method to inspect the instruction memory of an application. This view has support for adding and removing breakpoints on a target address. It also provides, in combination with the *CPU Registers View*, a powerful method for inspecting how CPU state is updated on instruction level when single-stepping.

Disassembly View is available from the main menu under Window > Show View > Other > Debug > Disassembly. When adding a new memory monitor, the user a dialog is displayed where the target address is specified.

The currently highlighted row represents the instruction which is to be issued when execution continues. Execution history is also highlighted in shaded color to represent instructions which have been recently executed. The right-most column of the *Disassembly View* describes the name of the function which the instruction belongs to, together with the offset from the function symbol.
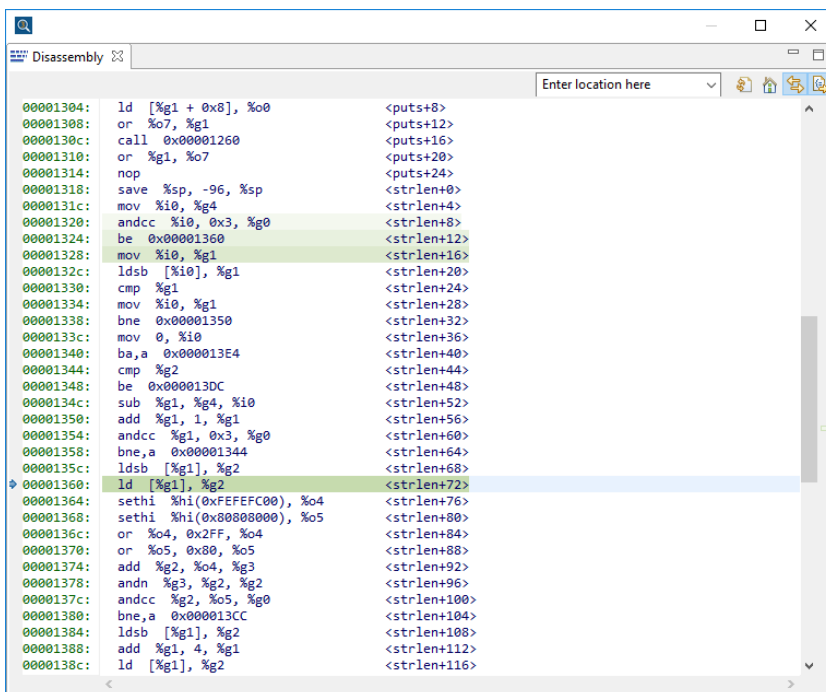
Figure 4.20. The disassembly view

Disassembly View is updated each time execution stops, for example at single-step or a breakpoint. Methods for instruction stepping include:

- Single-step using the **step** command in a Tcl terminal.

- Single-step by clicking the toolbar button named *Step Into*, also available via the **F5** shortkey.

A custom memory location can be disassembled by typing the address in the box at the top of the *Disassembly View* labelled *Enter location here*. It can be used to disassemble instructions not related to the current CPU program counter. Note that the input should be an address and not a symbol name.

The *Disassembly View* is context aware and will disassemble virtual memory as determined by the current CPU or thread context.
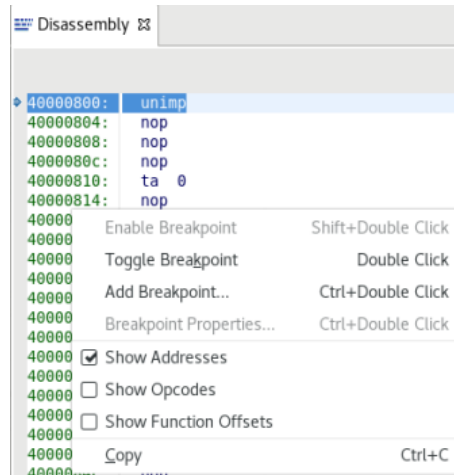
Figure 4.21. Disassembly view context menu

Right-clicking on an address opens a context menu, where the user can add a breakpoint. Choosing *Toggle Breakpoint* adds a soft breakpoint on the target address, this can also be achieved by double-clicking on the address. Clicking instead on *Add Breakpoint*, or Ctrl+double-click opens a breakpoint property page with more breakpoint options, see Figure 4.16, "Breakpoint property page" in Breakpoints view. Existing breakpoints can be removed by double-clicking on them and enabling/disabling a breakpoint can be done by Shift+double-click or from the context menu.

Another useful feature in the context menu is *Show Opcodes*, which when clicked, creates a column to the right of the address column and displays the op code of the respective address.

In the context menu you have the option of not displaying the address column with *Show Addresses* and also the option to display the function offsets with *Show Function Offsets*. This will be displayed in a column to the right of the addresses, however this offset is already displayed in the column to the far right, regardless.
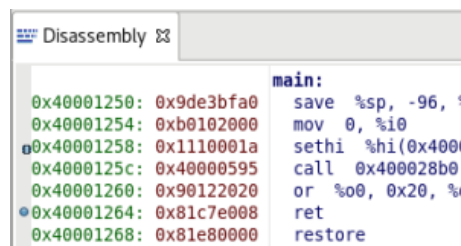
Figure 4.22. Breakpoints and op codes

In Figure 4.22, "Breakpoints and op codes" the op codes are enabled and can be seen in red. We also see two breakpoints: a hard breakpoint at 0x40001258 and a soft breakpoint at 0x40001264.

4.5.8. Messages View
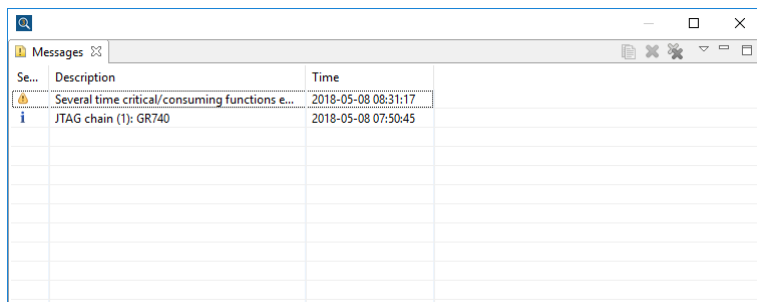
The Messages view displays messages from the application that may be helpful for the user. The messages ranges from critical errors to less critical information of helpful nature. Messages can arise from many different situations, such when running a target image, or changing a setting.

Messages are sorted by the date they were created, showing newer messages on the top of the list.

To see the full message with all information, double click the message in the view. This will open a dialog with all information available.

Copy messages to the clipboard by selecting one or many and press the Copy button , or press the copy command keyboard combination.

Remove one or more messages by selecting them and pressing the Remove button , or press delete on the keyboard. Remove all messages by clicking the Remove All button .

Figure 4.23. The message view

4.6. Target communication

4.6.1. Memory view update

GRMON3 GUI normally updates the memory views when target execution stops, for example on a breakpoint or after single step. This can generate a large amount of traffic on a slow debug link in combination with large memory views. To save bandwidth on the debug link, there is an option named *Disable auto-updating memory view after execution*, available in the connection dialog *GUI* tab. The corresponding command-line option is `-tcf-nomemupdate`.

4.7. C/C++ level debugging

The GUI does not include C/C++ level debugging functionality. However the GUI can be used simultaneously to C/C++ level debugging via the GDB socket as described in Section 3.7, "GDB interface". When GDB has connected to GRMON, GDB is in control of the debugging. Similar to the command line interface it is not possible to alter processor state or breakpoints without destroying GDB's internal representation. Doing so will leave GDB in an undefined state and cause various GDB C/C++ level issues.

When GDB has stopped the execution the GUI can be used to view all hardware state. It is also possible to update hardware state not specifically controlled by GDB such as I/O registers.

4.8. Limitations

This section describes limitation of GRMON3 GUI and areas of incompatibility with GRMON3 CLI.

Address location input

Address location inputs to the GUI currently has to be specified as addresses and not as symbol names, except for in the Breakpoints view. Commands entered in the GRMON Tcl terminals can be specified either as addresses or symbol names.

4.9. Troubleshooting the GUI

This section lists some useful tips for troubleshooting the GUI.

The GUI doesn't start

Check the log for errors. On Linux it is located in `~/.grmon-3.2/workspace/.metadata/.log` and in `$APPDATA$/Cobham Gaisler/GRMON/3.2/workspace/.metadata/.log` for Windows.

Clear the workspace folder and try again. This folder is located in `~/.grmon-3.2/workspace/` for Linux and `$APPDATA$/Cobham Gaisler/GRMON/3.2/workspace` for Windows.

Check your Java version. Java 8 is required.

5. Debug link

GRMON supports several different links to communicate with the target board. However all of the links may not be supported by the target board. Refer to the board user manual to see which links that are supported. There are also boards that have built-in adapters.

Refer to the board user manual to see which links that are supported.

The default communication link between GRMON and the target system is the host's serial port connected to a serial debug interface (AHBUART) of the target system. Connecting using any of the other supported link can be performed by using the switches listed below. More switches that may affect the connection are listed at each subsection.

`-altjtag`	Connect to the target system using Altera Blaster cable (USB or parallel).
`-eth`	Connect to the target system using Ethernet. Requires the EDCL core to be present in the target system.
`-digilent`	Connect to the target system Digilent HS1 cable.
`-ftdi`	Connect to the target system using a JTAG cable based on a FTDI chip.
`-gresb`	Connect to the target system through the GRESB bridge. The target needs a SpW core with RMAP.
`-jtag`	Connect to the target system the JTAG Debug Link using Xilinx Parallel Cable III or IV.
`-usb`	Connect to the target system using the USB debug link. Requires the GRUSB_DCL core to be present in the target.
`-xilusb`	Connect to the target system using a Xilinx Platform USB cable.
`-uart <device>`	Connect to the target system using a serial cable.
`-user`	Connect to the target system using a custom user defined library.

8-/16-bit access to the target system is only supported by the JTAG debug links, all other interfaces access sub-words using read-modify-write. All links supports 32-bit accesses. 8-bit access is generally not needed. An example of when it is needed is when programming a 8 or 16-bit flash memory on a target system *without* a LEON CPU available. Another example is when one is trying to access cores that have byte-registers, for example the CAN_OC core, but almost all GRLIB cores have word-registers and can be accessed by any debug link.

The speed of the debug links affects the performance of GRMON. It is most noticeable when loading large applications, for example Linux or VxWorks. Another case when the speed of the link is important is during profiling, a faster link will increase the number of samples. See Table 5.1 for a list of estimated speed of the debug links.

Table 5.1. Estimated debug link application download speed

Name	Estimated speed
UART	~100 kbit/s
JTAG (Parallel port)	~200 kbit/s
JTAG (USB)	~1 Mbit/s
GRESB	~25 Mbit/s
USB	~30 Mbit/s
Ethernet	~35 Mbit/s

5.1. UART debug link

To attach GRMON using the AHBUART debug link, first connect a cable between the UART connectors on target board and the host system. Then power-up and reset the target board and start GRMON with the `-uart` option. Use the `-uart <device>` option in case the target is not connected to the first UART port of your host. On some hosts, it might be necessary to lower the baud rate in order to achieve a stable connection to the target. In

this case, use the `-baud` switch with the 57600 or 38400 options. Below is a list of start-up switches applicable for the AHBUART debug link.

Extra options for UART debug link:

`-uart <device>`
> By default, GRMON communicates with the target using the first uart port of the host. This can be overridden by specifying an alternative device. Device names depend on the host operating system. On Linux systems serial devices are named as `/dev/tty##` and on Windows they are named `\\.\com#`.

`-baud <baudrate>`
> Use baud rate for the DSU serial link. By default, 115200 baud is used. Possible baud rates are 9600, 19200, 38400, 57600, 115200, 230400, 460800. Rates above 115200 need special uart hardware on both host and target.

When using an USB-to-Serial adapter based on FTDI chips, there is a latency timer that will be a bottleneck, especially when reading small amounts of data very often. For example when the I/O Forwarding is enabled or collecting profiling information. In Linux this timer will be adjusted automactically by GRMON, but in Windows it must be set manually. Open the Windows "Device Manager" and locate the serial port device. Right-click on the device and select properties. In the tab "Port Settings", push the "Advanced" button. Set the "Latency Timer" to lowest possible value and press the button "OK".

5.2. Ethernet debug link

If the target system includes a GRETH core with EDCL enabled then GRMON can connect to the system using Ethernet. The default network parameters can be set through additional switches.

Extra options for Ethernet:

`-eth [<ipnum>][:<port>]`
> Use the Ethernet connection and optionally use *ipnum* for the target system IP number and/or *:port* to select which UDP port to use. Default IP address is 192.168.0.51 and port 10000.

`-edclmem <kB>`
> The EDCL hardware can be configured with different buffer size. Use this option to force the buffer size (in KB) used by GRMON during EDCL debug-link communication. By default the GRMON tries to autodetect the best value. Valid options are: 1, 2, 4, 8, 16, 32, 64.

`-edclus <us>`
> Increase the EDCL timeout before resending a packet. Use this option if you have a large network delays.

The default IP address of the EDCL is normally determined at synthesis time. The IP address can be changed using the **edcl** command. If more than one core is present i the system, then select core by appending the name. The name of the core is listed in the output of **info sys**.

Note that if the target is reset using the reset signal (or power-cycled), the default IP address is restored. The **edcl** command can be given when GRMON is attached to the target with any interface (serial, JTAG, PCI ...), allowing to change the IP address to a value compatible with the network type, and then connect GRMON using the EDCL with the new IP number. If the **edcl** command is issued through the EDCL interface, GRMON must be restarted using the new IP address of the EDCL interface. The current IP address is also visible in the output from **info sys**.

```
grmon3> edcl
  Device index: greth0
  Edcl ip 192.168.0.51, buffer 2 kB

grmon3> edcl greth1
  Device index: greth1
  Edcl ip 192.168.0.52, buffer 2 kB

grmon3> edcl 192.168.0.53 greth1
  Device index: greth1
  Edcl ip 192.168.0.53, buffer 2 kB

grmon3> info sys greth0 greth1
  greth0    Cobham Gaisler  GR Ethernet MAC
            APB: FF940000 - FF980000
            IRQ: 24
            edcl ip 192.168.0.51, buffer 2 kbyte
  greth1    Cobham Gaisler  GR Ethernet MAC
            APB: FF980000 - FF9C0000
```

```
IRQ: 25
edcl ip 192.168.0.53, buffer 2 kbyte
```

5.3. JTAG debug link

The subsections below describe how to connect to a design that contains a JTAG AHB debug link (AHBJTAG). The following commandline options are common for all JTAG interfaces. If more than one cable of the same type is connected to the host, then you need to specify which one to use, by using a commandline option. Otherwise it will default to the first it finds.

Extra options common for all JTAG cables:

-jtaglist
    List all available cables and exit application.

-jtagcable <n>
    Specify which cable to use if more than one is connected to the computer. If only one cable of the same type is connected to the host computer, then it will automatically be selected. It's also used to select parallel port.

-jtagserial <sn>
    Specify which cable to use by serial number if more than one is connected to the computer.

-jtagdevice <n>
    Specify which device in the chain to debug. Use if more than one is device in the chain is debuggable.

-jtagcomver <version>
    Specify JTAG debug link version.

-jtagretry <num>
    Set the number of retries.

-jtagcfg <filename>
    Load a JTAG configuration file, defining unknown devices.

JTAG debug link version. The JTAG interface has in the past been unreliable in systems with very high bus loads, or extremely slow AMBA AHB slaves, that lead to GRMON reading out AHB read data before the access had actually completed on the AHB bus. Read failures have been seen in systems where the debug interface needed to wait hundreds of cycles for an AHB access to complete. With version 1 of the JTAG AHB debug link the reliability of the debug link has been improved. In order to be backward compatible with earlier versions of the debug link, GRMON cannot use all the features of AHBJTAG version 1 before the debug monitor has established that the design in fact contains a core with this version number. In order to do so, GRMON scans the plug and play area. However, in systems that have the characteristics described above, the scanning of the plug and play area may fail. For such systems the AHBJTAG version assumed by GRMON during plug and play scanning can be set with the switch -jtagcomver<version>. This will enable GRMON to keep reading data from the JTAG AHB debug interface until the AHB access completes and valid data is returned. Specifying the version in systems that have AHBJTAG version 0 has no benefit and may lead to erroneous behavior. The option -jtagretry<num> can be used to set the number of attempts before GRMON gives up.

JTAG chain devices. If more than one device in the JTAG chain are recognized as debuggable (FPGAs, ASICs etc), then the device to debug must be specified using the commandline option -jtagdevice. In addition, all devices in the chain must be recognized. GRMON automatically recognizes the most common FPGAs, CPLDs, proms etc. But unknown JTAG devices will cause GRMON JTAG chain initialization to fail. This can be solved by defining a JTAG configuration file. GRMON is started with -jtagcfg switch. An example of JTAG configuration file is shown below. If you report the device ID and corresponding JTAG instruction register length to Cobham Gaisler, then the device will be supported in future releases of GRMON.

```
# JTAG Configuration file
# Name       Id            Mask          Ir length   Debug I/F   Instr. 1   Instr. 2
xc2v3000     0x01040093    0x0fffffff    6           1           0x2        0x3
xc18v04      0x05036093    0x0ffeffff    8           0
ETH          0x103cb0fd    0x0fffffff    16          0
```

Each line consists of device name, device id, device id mask, instruction register length, debug link and user instruction 1 and 2 fields, where:

Name	String with device name
Id	Device identification code

Mask	Device id mask is ANDed with the device id before comparing with the identification codes obtained from the JTAG chain. Device id mask allows user to define a range of identification codes on a single line, e.g. mask 0x0fffffff will define all versions of a certain device.
Ir length	Length of the instruction register in bits
Debug I/F	Set debug link to 1 if the device implements JTAG Debug Link, otherwise set to 0.
Instr. 1	Code of the instruction used to access JTAG debug link address/command register (default is 0x2). Only used if debug link is set to 1.
Instr. 2	Code of the instruction used to access JTAG debug link data register (default is 0x3). Used only if debug link is set to 1.

The JTAG configuration file can not be used with Altera blaster cable (`-altjtag`).

5.3.1. Xilinx parallel cable III/IV

If target system has the JTAG AHB debug link, GRMON can connect to the system through Xilinx Parallel Cable III or IV. The cable should be connected to the host computers parallel port, and GRMON should be started with the `-jtag` switch. Use `-jtagcable` to select port. On Linux, you must have read and write permission, i.e. make sure that you are a member of the group 'lp'. I.a. on some systems the Linux module lp must be unloaded, since it uses the port.

Extra options for Xilinx parallel cable:

`-jtag`
    Connect to the target system using a Xilinx parallel cable III/IV cable

5.3.2. Xilinx Platform USB cable

JTAG debugging using the Xilinx USB Platform cable is supported on Linux and Windows 7 systems. The platform cable models DLC9G and DLC10 are supported. The legacy model DLC9 is not supported. GRMON should be started with `-xilusb` switch. Certain FPGA boards have a USB platform cable logic implemented directly on the board, using a Cypress USB device and a dedicated Xilinx CPLD. GRMON can also connect to these boards, using the `--xilusb` switch.

Extra options for Xilinx USB Platform cable:

`-xilusb`
    Connect to the target system using a Xilinx USB Platform cable.
`-xilmhz[`*12|6|3|1.5|0.75*`]`
    Set Xilinx Platform USB frequency. Valid values are 12, 6, 3, 1.5 or 0.75 MHz. Default is 3 MHz.

On Linux systems, the Xilinx USB drivers must be installed by executing ’./setup_pcusb’ in the ISE bin/`bin/lin` directory (see ISE documentation). I.a. the program **fxload** must be available in `/sbin` on the used host, and libusb must be installed.

On Windows hosts follow the instructions below. The USB cable drivers should be installed from Xilinx ISE, ISE Webpack or Vivado Lab Tools. Xilinx ISE 9.2i or later is required, or Xilinx Vivado Lab Tools 2017.4. Then install the *filter driver*, from the libusb-win32 project [http://libusb-win32.sourceforge.net], by running install-filter-win.exe from the libusb package.

1. Install the ISE, ISE-Webpack, iMPACT or Vivado Lab Tools by following their instructions. This will install the drivers for the Xilinx Platform USB cable. Xilinx ISE 9.2i or later is required, or Vivado 2017.4. After the installation is complete, make sure that the Xilinx tools can find the Platform USB cable.
2. Then run **libusb-win32-devel-filter-1.2.6.0.exe**, which can be found in the folder **'<grmon-ver>/share/grmon/'**, where **<grmon-ver>** is the path to the extracted win32 or win64 folder from the the GRMON archive. This will install the libusb filter driver tools. Step through the installer dialog boxes as seen in Figure 5.1 until the last dialog. The **libusb-win32-devel-filter-1.2.6.0.exe** installation is compatible with both 64-bit and 32-bit Windows.
3. Make sure that '**Launch filter installer wizard**' is checked, then press **Finish**. The wizard can also be launched from the start menu.
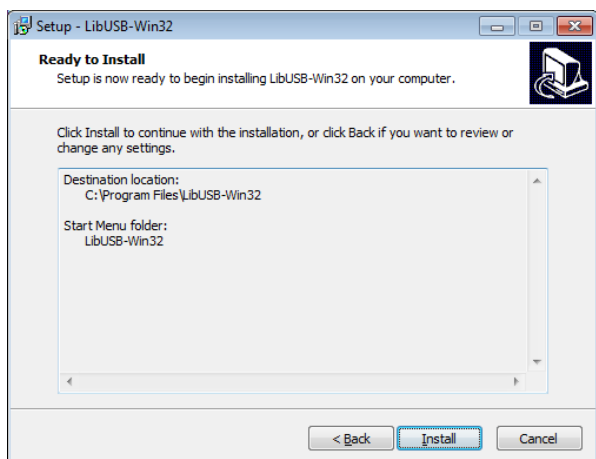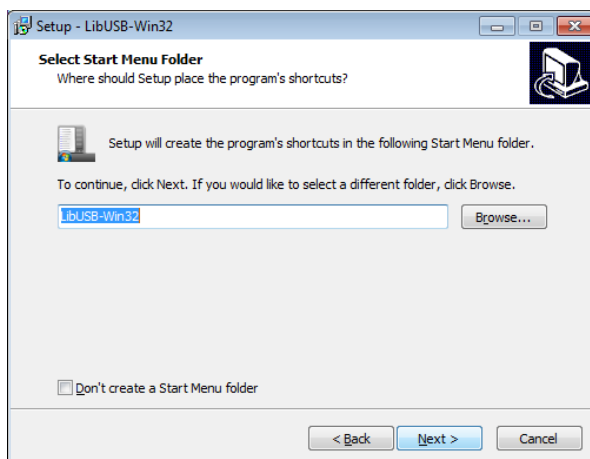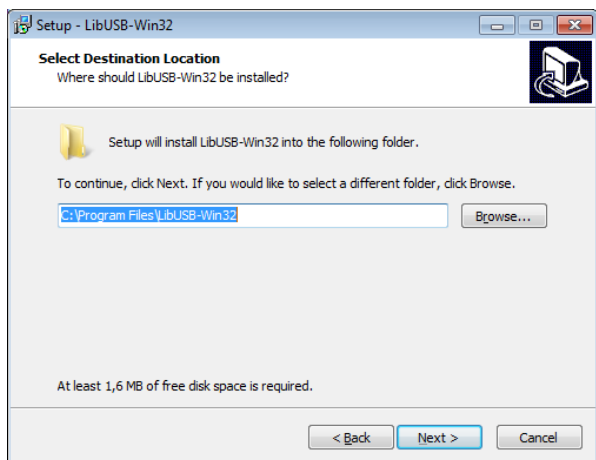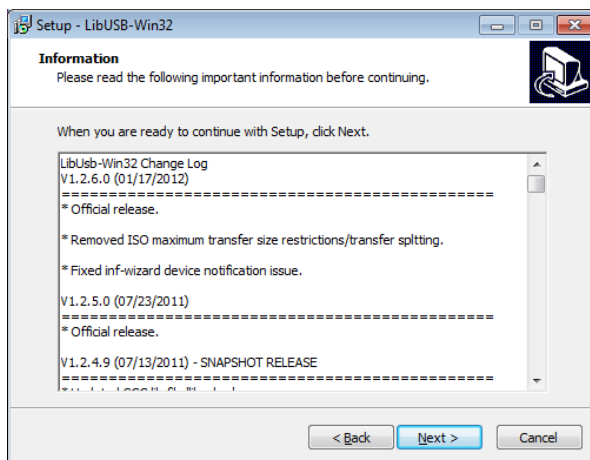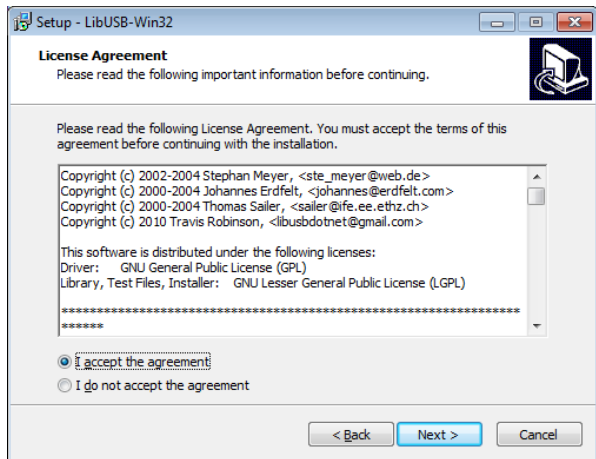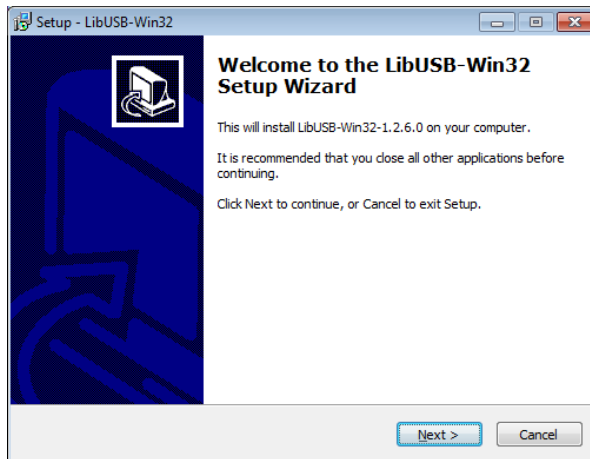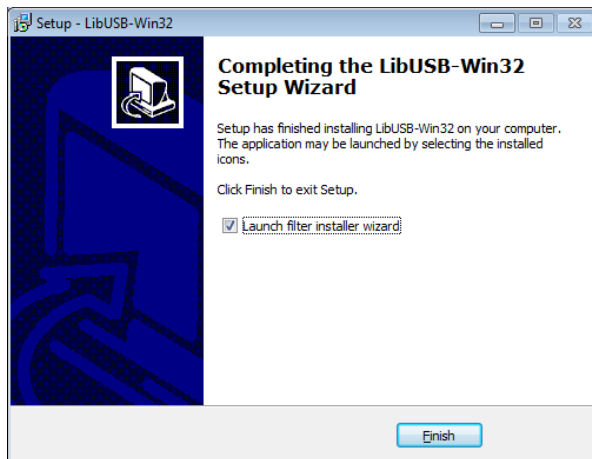
Figure 5.1.

4. At the first dialog, as seen in Figure 5.2, choose '**Install a device filter**' and press **Next**.
5. In the second dialog, mark the Xilinx USB cable. You can identify it either by name `Xilinx USB Cable` in the 'Description' column or `vid:03fd` in the 'Hardware ID' column. Then press **Install** to continue.
6. Press **OK** to close the pop-up dialog and then **Cancel** to close the filter wizard. You should now be able to use the Xilinx Platform USB cable with both GRMON and iMPACT.
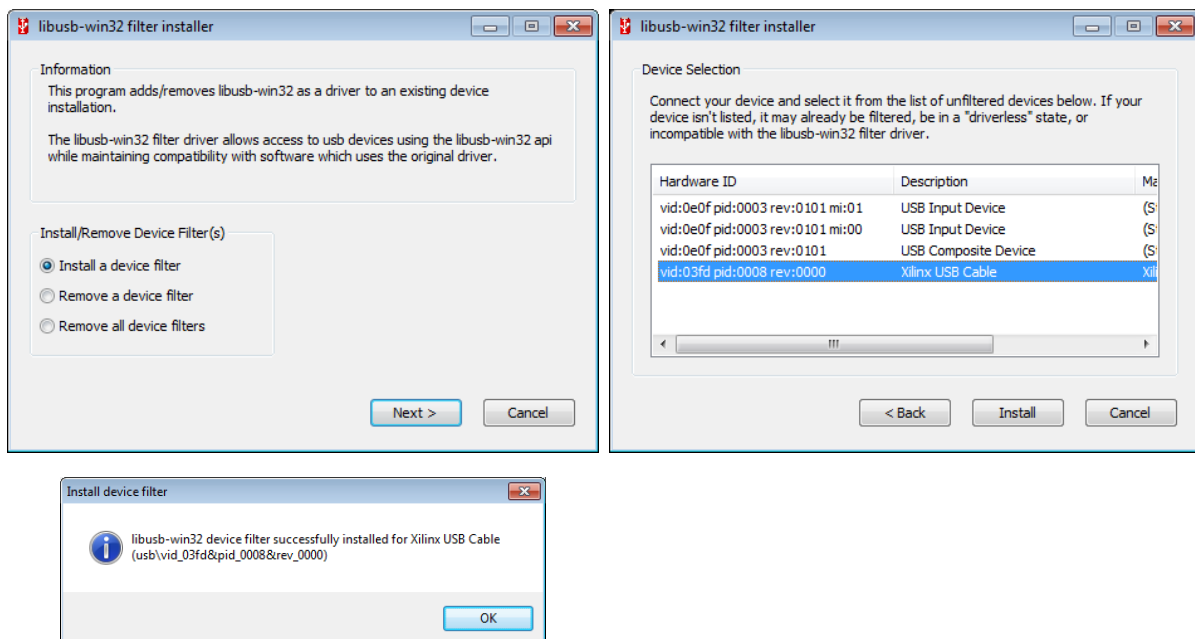
Figure 5.2.

The *libusb-win32 filter installer wizard* may have to be run again if the Xilinx Platform USB cable is connected to another USB port or through a USB hub.

5.3.3. Altera USB Blaster or Byte Blaster

For GRLIB systems implemented on Altera devices GRMON can use USB Blaster or Byte Blaster cable to connect to the system. GRMON is started with `-altjtag` switch. Drivers are included in the the Altera Quartus software, see Actel's documentation on how to install on your host computer.

The connection is only supported by the 32-bit version of GRMON. And it also requires Altera Quartus version less then or equal to 13.

On Linux systems, the path to Quartus shared libraries has to be defined in the LD_LIBRARY_PATH environment variable, i.e.

```
$ export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:/usr/local/quartus/linux
$ grmon -altjtag

 GRMON3 LEON debug monitor v3.0.0 32-bit professional version
 ...
```

On Windows, the path to the Quartus binary folder must the added to the environment variable `PATH`, see Appendix F, *Appending environment variables* in how to this. The default installation path to the binary folder should be similar to `C:\altera\11.1sp2\quartus\bin`, where *11.1sp2* is the version of Quartus.

Extra options for Altera Blaster:

`-altjtag`
> Connect to the target system using Altera Blaster cable (USB or parallel).

5.3.4. FTDI FT4232/FT2232

JTAG debugging using a FTDI FT2232/FT4232 chip in MPSSE-JTAG-emulation mode is supported in Linux and Windows. GRMON has support for two different back ends, one based on libftdi 0.20 and the other based on FTDI's official d2xx library.

When using Windows, GRMON will use the d2xx back end per default. FTDI's D2XX driver must be installed. Drivers and installation guides can be found at FTDI's website [http://www.ftdichip.com].

In Linux, the libftdi back end is used per default. The user must also have read and write permission to the device file. This can be achieved by creating a udev rules file, `/etc/udev/rules.d/51-ftdi.rules`, containing the lines below and then reconnect the USB cable.

```
ATTR{idVendor}=="0403", ATTR{idProduct}=="6010", MODE="666"
    ATTR{idVendor}=="0403", ATTR{idProduct}=="6011", MODE="666"
    ATTR{idVendor}=="0403", ATTR{idProduct}=="6014", MODE="666"
    ATTR{idVendor}=="0403", ATTR{idProduct}=="cff8", MODE="666"
```

Extra options for FTDI:

`-ftdi [libftdi|d2xx]`
> Connect to the target system using a JTAG cable based on a FTDI chip. Optionally a back end can be specified. Defaults to libftdi on Linux and d2xx on Windows

`-ftdidetach`
> On Linux, force the detachment of any kernel drivers attached to the USB device.

`-ftdimhz <mhz>`
> Set FTDI frequency divisor. Values between 0.0 and 30.0 are allowed (values higher then 6.0 MHz are hardware dependent) The frequency will be rounded down to the closest supported frequency supported by the hardware. Default value of *mhz* is 1.0 MHz

`-ftdivid <vid>`
> Set the vendor ID of the FTDI device you are trying to connect to. This can be used to add support for 3rd-party FTDI based cables.

`-ftdipid <pid>`
> Set the product ID of the FTDI device you are trying to connect to. This can be used to add support for 3rd-party FTDI based cables.

`-ftdigpio <val>`
> Set the GPIO signals of the FTDI device. The lower 16bits sets the level of the GPIO and the upper bits set the direction.

Bits 0-3	Reserved
Bits 4-3	GPIOL 0-3 level
Bits 8-15	GPIOH 0-7 level
Bits 16-19	Reserved
Bits 20-23	GPIOL 0-3 direction
Bits 24-31	GPIOH 0-7 direction

5.3.5. Amontec JTAGkey

The Amontec JTAGkey is based on a FTDI device, therefore see Section 5.3.4, "FTDI FT4232/FT2232" about FTDI devices on how to connect. Note that the user does *not* need to specify VID/PID for the Amontec cable. The drivers and installation guide can be found at Amontec's website [http://www.amontec.com].

5.3.6. Actel FlashPro 3/3x/4/5

Support for Actel FlashPro 3/3x/4/5 is only supported by the professional version.

On Windows 32-bit, JTAG debugging using the Microsemi FlashPro 3/3x/4 is supported for GRLIB systems implemented on Microsemi devices. This also requires FlashPro 11.4 software or later to be installed on the host computer (to be downloaded from Microsemi's website). Windows support is detailed at the website. GRMON is started with the `-fpro` switch. Technical support is provided through Cobham Gaisler only via support@gaisler.com.

JTAG debugging using the Microsemi FlashPro 5 cable is supported on both Linux and Windows, for GRLIB systems implemented on Microsemi devices, using the FTDI debug link. See Section 5.3.4, "FTDI FT4232/FT2232" about FTDI devices on how to connect. Note that the user does *not* need to specify VID/PID for the FlashPro 5 cable. This also requires FlashPro 11.4 software or later to be installed on the host computer (to be downloaded from Microsemi's website). Technical support is provided through Cobham Gaisler only via support@gaisler.com.

Extra options for Actel FlashPro:

`-fpro`
  Connect to the target system using the Actel FlashPro cable. (Windows)

5.3.7. Digilent HS1

JTAG debugging using a Digilent JTAG HS1 cable is supported on Linux and Windows systems. Start GRMON with the `-digilent` switch to use this interface.

On Windows hosts, the Digilent Adept System software must be installed on the host computer, which can be downloaded from Digilent's website.

On Linux systems, the Digilent Adept Runtime x86 must be installed on the host computer, which can be downloaded from Digilent's website. The Adept v2.10.2 Runtime x86 supports the Linux distributions listed below.

CentOS 4 / Red Hat Enterprise Linux 4
CentOS 5 / Red Hat Enterprise Linux 5
openSUSE 11 / SUSE Linux Enterprise 11
Ubuntu 8.04
Ubuntu 9.10
Ubuntu 10.04
On 64-bit Linux systems it's recommended to install the 32-bit runtime using the manual instructions from the README provided by the runtime distribution. Note that the 32-bit Digilent Adept runtime depends on 32-bit versions of FTDI's libd2xx library and the libusb-1.0 library.

Extra options for Digilent HS1:

`-digilent`
  Connect to the target system using the Digilent HS1 cable.
`-digifreq <hz>`
  Set Digilent HS1 frequency in Hz. Default is 1 MHz.

5.4. USB debug link

GRMON can connect to targets equipped with the GRUSB_DCL core using the USB bus. To do so start GRMON with the `-usb` switch. Both USB 1.1 and 2.0 are supported. Several target systems can be connected to a single host at the same time. GRMON scans all the USB buses and claims the first free USBDCL interface. If the first target system encountered is already connected to another GRMON instance, the interface cannot be claimed and the bus scan continues.

On Linux the GRMON binary must have read and write permission. This can be achieved by creating a udev rules file, `/etc/udev/rules.d/51-gaisler.rules`, containing the line below and then reconnect the USB cable.

```
SUBSYSTEM=="usb", ATTR{idVendor}=="1781", ATTR{idProduct}=="0aa0", MODE="666"
```

On Windows a driver has to be installed. The first the time the device is plugged in it should be automatically detected as an unknown device, as seen in Figure 5.3. Follow the instructions below to install the driver.
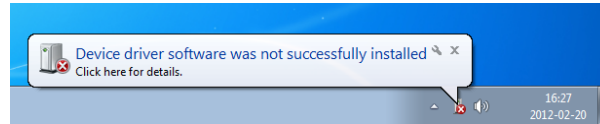
Figure 5.3.

1. Open the device manager by writing '`mmc devmgmt.msc`' in the run-field of the start menu.
2. In the device manager, find the unknown device. Right click on it to open the menu and choose '`Update Driver Software...`' as Figure 5.4 shows.
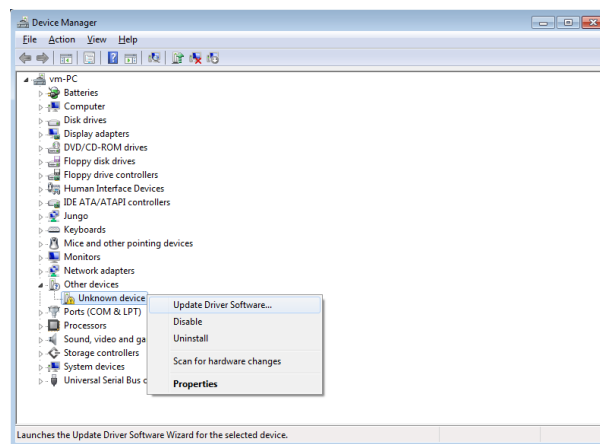
Figure 5.4.

3. In the dialog that open, the first image in Figure 5.5, choose '`Browse my computer for driver software`'.
4. In the next dialog, press the `Browse` button and locate the path to `<grmon-win32>/share/grmon/drivers`, where grmon-win32 is the path to the extracted win32 folder from the the GRMON archive. Press '`Next`' to continue.
5. A warning dialog might pop-up, like the third image in Figure 5.5. Press '`Install this driver software anyway`' if it shows up.
6. Press '`Close`' to exit the dialog. The USB DCL driver is now installed and GRMON should be able to connect to the target system using the USB DCL connection.
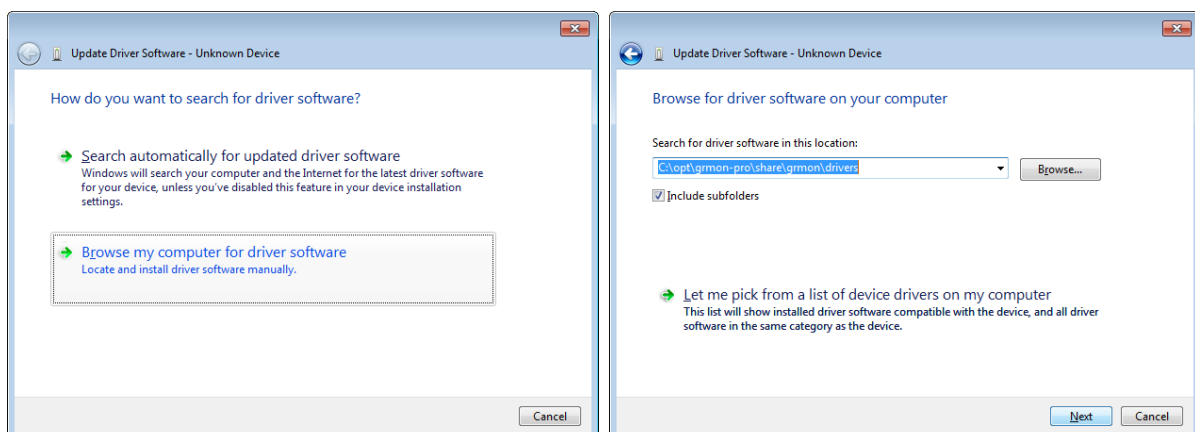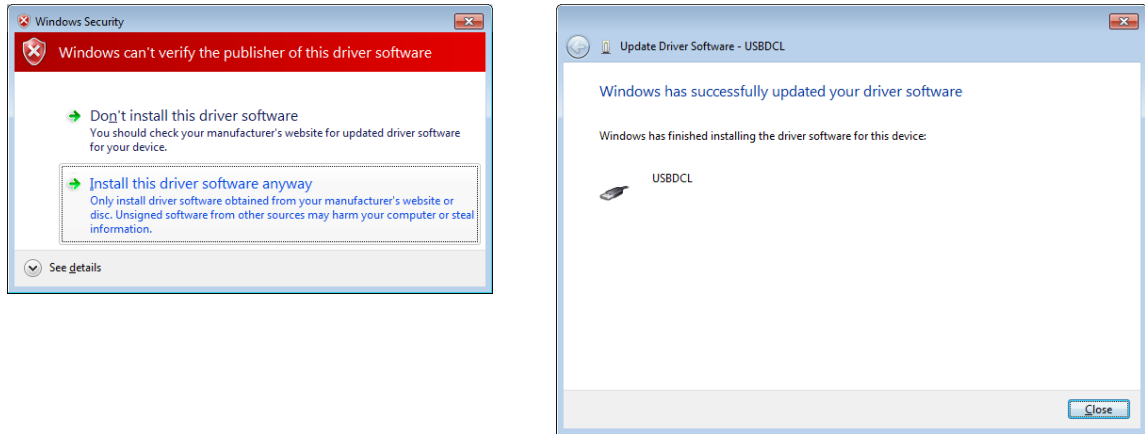
Figure 5.5.

5.5. GRESB debug link

Targets equipped with a SpaceWire core with RMAP support can be debugged through the GRESB debug link using the GRESB Ethernet to SpaceWire bridge. To do so start GRMON with the `-gresb` switch and use the any of the switches below to set the needed parameters.

For further information about the GRESB bridge see the GRESB manual.

Extra options for the GRESB connection:

`-gresb[<ipnum>]`
> Use the GRESB connection and optionally use *ipnum* for the target system IP number. Default is 192.168.0.50.

`-link <num>`
> Use link *linknum* on the bridge. Defaults to 0.

`-dna <dna>`
> The destination node address of the target. Defaults to 0xfe.

`-sna <sna>`
> The SpW node address for the link used on the bridge. Defaults to 32.

`-dpa <dpa1>[,<dpa2>,...,<dpa12>]`
> The destination path address. Comma separated list of addresses.

`-spa <spa1>[,<spa2>,...,<spa12>]`
> The source path address. Comma separated list of addresses.

`-dkey <key>`
> The destination key used by the targets RMAP interface. Defaults to 0.

`-clkdiv <div>`
> Divide the TX bit rate by div. If not specified, the current setting is used.

`-gresbtimeout <sec>`
> Timeout period in seconds for RMAP replies. Defaults is 8.

`-gresbretry <n>`
> Number of retries for each timeout. Defaults to 0.

5.5.1. AGGA4 SpaceWire debug link

It is possible to debug the AGGA4 via SpaceWire, using the GRESB Ethernet SpaceWire Bridge, by combining the commandline switches '`-gresb`' and '`-sys agga4`' when starting GRMON. In addition, the following options can also be added: `-link`, `-clkdiv`, `-gresbtimeout` and `-gresbretry`.

The AGGA4 SpaceWire debug link does not use a regular SpaceWire packet protocol, therefore the GRESB must be setup to tunnel all the packets as raw data. To achieve this the GRESB must be configured to use separate routing tables, this setting can only be enabled via the web interface.

The GRESB routing tables for the SpaceWire port and the TCP port that will be used must also be configured. The routing tables can be setup via the web interface or using the software distributed with the GRESB. All the node addresses in the routing table for the SpaceWire port must be configured to forward packets to the TCP port without any header deletion. The routing table for the TCP port must be setup in the same way but to forward the packets from all nodes to the SpaceWire port instead. A Linux bash script and a Windows bat-script is provided with GRMON professional distribution in folder `share/grmon/tools`, that can be used with the GRESB software to setup the routing tables. The scripts must be able to find the GRESB software, so either the PATH environment variable must be setup or execute the scripts from the GRESB software folder.

GRESB separate routing table mode shall be used when connecting to the AGGA4 SpaceWire debug link. This can be configured in the GRESB web interface: "Routing table configuration"->"Set/view Mode"->"Set Separate mode".

5.6. User defined debug link

In addition to the supported DSU communication interfaces (Serial, JTAG, ETH and PCI), it is possible for the user to add a custom interface using a loadable module. The custom DSU interface must provide functions to read and write data on the target system's AHB bus.

Extra options for the user defined connection:

-dback `<filename>`
> Use the user defined debug link. The debug link should be implemented in a loadable module pointed out by the filename parameter.

-dbackarg `<arg>`
> Set a custom argument to be passed to the user defined debug link during start-up.

5.6.1. API

The loadable module must export a pointer variable named `DsuUserBackend` that points to a `struct ioif`, as described below:

```
struct ioif {
 int (*wmem) (unsigned int addr, const unsigned int *data, int len);
 int (*gmem) (unsigned int addr, unsigned int *data, int len);
 int (*open) (char *device, int baudrate, int port);
 int (*close) ();
 int (*setbaud) (int baud, int pp);
 int (*init) (char* arg);
};

struct ioif my_io = {my_wmem, my_gmem, NULL, my_close, NULL, my_init};
struct ioif *DsuUserBackend = &my_io;
```

On the Linux platform, the loadable module should be compiled into a library and loaded into GRMON as follows:

```
> gcc -fPIC -c my_io.c
> gcc -shared my_io.o -o my_io.so
> grmon -dback my_io.so -dbackarg "my argument"
```

On the Windows platform, the loadable module should be compiled into a library and loaded into GRMON as follows:

```
> gcc -c my_io.c
> gcc -shared my_io.o -o my_io.dll
> grmon -dback my_io.dll -dbackarg "my argument"
```

The members of the `struct ioif` are defined as:

`int (*wmem) (unsigned int addr, const unsigned int *data, int len);`

> A function that performs one or more 32-bit writes on the AHB bus. The parameters indicate the AHB (start) address, a pointer to the data to be written, and the number of words to be written. The data is in little-endian format (note that the AMBA bus on the target system is big-endian). If the len parameter is zero, no data should be written. The return value should be the number of words written.

`int (*gmem) (unsigned int addr, unsigned int *data, int len);`

> A function that reads one or more 32-bit words from the AHB bus. The parameters indicate the AHB (start) address, a pointer to where the read data should be stored, and the number of words to be read. The returned

data should be in little-endian format (note that the AMBA bus on the target system is big-endian). If the len parameter is zero, no data should be read. The return value should be the number of words read.

```
int (*open) (char *device, int baudrate, int port);
```

Not used, provided only for backwards compatibility. This function is replaced by the function `init`.

```
int (*close) ();
```

Called when disconnecting.

```
int (*setbaud) (int baud, int pp);
```

Not used, provided only for backwards compatibility.

```
int (*init) (char* arg);
```

Called when initiating a connection to the target system. The parameter arg is set using the GRMON start-up switch `-dbackarg <arg>`. This allows to send arbitrary parameters to the DSU interface during start-up.

An example module is provided with the professional version of GRMON located at `<grmon3>/share/gr-mon/src/dsu_user_backend`.

6. Debug drivers

This section describes GRMON debug commands available through the TCL GRMON shell.

6.1. AMBA AHB trace buffer driver

The **at** command and its subcommands are used to control the AHBTRACE buffer core. It is possible to record AHB transactions without interfering with the processor. With the commands it is possible to set up triggers formed by an address and an address mask indicating what bits in the address that must match to set the trigger off. When the triggering condition is matched the AHBTRACE stops the recording of the AHB bus and the log is available for inspection using the **at** command. The **at delay** command can be used to delay the stop of the trace recording after a triggering match.

Note that this is an stand alone AHB trace buffer it is not to be confused with the DSU AHB trace facility. When a break point is hit the processor will not stop its execution.

The **info sys** command displays the size of the trace buffer in number of lines.

```
ahbtrace0 Cobham Gaisler  AMBA Trace Buffer
          AHB: FFF40000 - FFF60000
          Trace buffer size: 512 lines
```

6.2. Clock gating

The GRCLKGATE debug driver provides an interface to interact with a GRCLKGATE clock gating unit. A command line switch can be specified to automatically reset and enable all clocks, controlled by clock gating units, during GRMON's system initialization.

The GRCLKGATE core is accessed using the command **grcg**, see command description in Appendix B, *Command syntax* for more information.

6.2.1. Switches

-cginit [,*<mask>*,*<mask>*,...]
    Reset and enable all clock-signals controlled by GRCLKGATE during initialization. If no mask is set then all clock-signals will be enabled. If a mask is specified, then clock-signals that will be enabled depends on the mask. One mask per GRCLKGATE core.

6.3. DSU Debug drivers

The DSU debug drivers for the LEON processor(s) is a central part of GRMON. It handles most of the functions regarding application execution, debugging, processor register access, cache access and trace buffer handling. The most common interactions with the DSU are explained in Chapter 3, *Operation*. Additional information about the configuration of the DSU and the LEON CPUs on the target system can be listed with the command **info sys**.

```
dsu0       Cobham Gaisler  LEON4 Debug Support Unit
           AHB: D0000000 - E0000000
           AHB trace: 64 lines, 32-bit bus
           CPU0:  win 8, hwbp 2, itrace 64, V8 mul/div, srmmu, lddel 1, GRFPU-lite
                  stack pointer 0x4ffffff0
                  icache 2 * 8 kB, 32 B/line lrr
                  dcache 2 * 4 kB, 32 B/line lrr
           CPU1:  win 8, hwbp 2, itrace 64, V8 mul/div, srmmu, lddel 1, GRFPU-lite
                  stack pointer 0x4ffffff0
                  icache 2 * 8 kB, 32 B/line lrr
                  dcache 2 * 4 kB, 32 B/line lrr
```

6.3.1. Switches

Below is a list of commandline switches that affects how the DSU driver interacts with the DSU hardware.

-nb
    When the -nb flag is set, the CPUs will not go into debug mode when a error trap occurs. Instead the OS must handle the trap.

`-nswb`

When the -nswb flag is set, the CPUs will not go into debug mode when a software breakpoint occur. This option is required when a native software debugger like GDB is running on the target LEON.

`-dsudelay <ms>`

Set the DSU polling period. Normally GRMON will poll the DSU as fast as possible.

`-nic`

Disable instruction cache

`-ndc`

Disable data cache

`-stack <addr>`

Set addr as stack pointer for applications, overriding the auto-detected value.

`-mpgsz`

Enable support for MMU page sizes larger then 4kB. Must be supported by hardware.

6.3.2. Commands

The driver for the debug support unit provides the commands listed in Table 6.1.

Table 6.1. DSU commands

about	Show information about GRMON
ahb	Print AHB transfer entries in the trace buffer
attach	Stop execution and attach GRMON to processor again
at	Print AHB transfer entries in the trace buffer
bp	Add, delete or list breakpoints
bt	Print backtrace
cctrl	Display or set cache control register
cont	Continue execution
cpu	Enable, disable CPU or select current active cpu
dcache	Show, enable or disable data cache
dccfg	Display or set data cache configuration register
detach	Resume execution with GRMON detached from processor
ei	Error injection
ep	Set entry point
float	Display FPU registers
forward	Control I/O forwarding
go	Start execution without any initialization
hist	Print AHB transfer or intruction entries in the trace buffer
icache	Show, enable or disable instruction cache
iccfg	Display or set instruction cache configuration register
inst	Print intruction entries in the trace buffer
leon	Print leon specific registers
mmu	Print or set the SRMMU registers
perf	Measure performance
profile	Enable, disable or show simple profiling
reg	Show or set integer registers.
run	Reset and start execution
stack	Set or show the intial stack-pointer
step	Step one ore more instructions

stop	Interrupts current CPU execution
tmode	Select tracing mode between none, processor-only, AHB only or both.
va	Translate a virtual address
vmemb	AMBA bus 8-bit virtual memory read access, list a range of addresses
vmemd	AMBA bus 64-bit virtual memory read access, list a range of addresses
vmemh	AMBA bus 16-bit virtual memory read access, list a range of addresses
vmem	AMBA bus 32-bit virtual memory read access, list a range of addresses
vwmemb	AMBA bus 8-bit virtual memory write access
vwmemd	AMBA bus 64-bit virtual memory write access
vwmemh	AMBA bus 16-bit virtual memory write access
vwmems	Write a string to an AMBA bus virtual memory address
vwmem	AMBA bus 32-bit virtual memory write access
walk	Translate a virtual address, print translation

6.3.3. Tcl variables

The DSU driver exports one Tcl variable per CPU (`cpuN`), they allow the user to access various registers of any CPU instead of using the standard **reg**, **float** and **cpu** commands. The variables are mostly intended for Tcl scripting. See Section 3.4.13, "Multi-processor support" for more information how the `cpu` variable can be used.

6.4. Ethernet controller

The GRETH debug driver provides commands to configure the GRETH 10/100/1000 Mbit/s Ethernet controller core. The driver also enables the user to read and write Ethernet PHY registers. The info sys command displays the core's configuration settings:

```
greth0    Cobham Gaisler  GR Ethernet MAC
          AHB Master 2
          APB: C0100100 - C0100200
          IRQ: 12
          edcl ip 192.168.0.201, buffer 2 kbyte
```

If more than one GRETH core exists in the system, it is possible to specify which core the internal commands should operate on. This is achieved by appending a device name parameter to the command. The device name is formatted as *greth#* where the # is the GRETH device index. If the device name is omitted, the command will operate on the first device. The device name is listed in the **info sys** information.

The IP address must have the numeric format when setting the EDCL IP address using the **edcl** command, i.e. `edcl 192.168.0.66`. See command description in Appendix B, *Command syntax* and Ethernet debug interface in Section 5.2, "Ethernet debug link" for more information.

6.4.1. Commands

The driver for the greth core provides the commands listed in Table 6.2.

Table 6.2. GRETH commands

edcl	Print or set the EDCL ip
mdio	Show PHY registers
phyaddr	Set the default PHY address
wmdio	Set PHY registers

6.5. GRPWM core

The GRPWM debug driver implements functions to report the available PWM modules and to query the waveform buffer. The **info sys** command will display the available PWM modules.

```
grpwm0    Cobham Gaisler   PWM generator
          APB: 80010000 - 80020000
          IRQ: 13
          cnt-pwm: 3
```

The GRPWM core is accessed using the command **grpwm**, see command description in Appendix B, *Command syntax* for more information.

6.6. USB Host Controller

The GRUSBHC host controller consists of two host controller types. GRMON provides a debug driver for each type. The info sys command displays the number of ports and the register setting for the enhanced host controller or the universal host controller:

```
usbehci0  Cobham Gaisler   USB Enhanced Host Controller
          AHB Master 4
          APB: C0100300 - C0100400
          IRQ: 6
          2 ports, byte swapped registers
usbuhci0  Cobham Gaisler   USB Universal Host Controller
          AHB Master 5
          AHB: FFF00200 - FFF00300
          IRQ: 7
          2 ports, byte swapped registers
```

If more than one ECHI or UCHI core exists in the system, it is possible to specify which core the internal commands should operate on. This is achieved by appending a device name parameter to the command. The device name is formatted as $usbehci\#/usbuhci\#$ where the # is the device index. If the device name is omitted, the command will operate on the first device. The device name is listed in the **info sys** information.

6.6.1. Switches

```
-nousbrst
```
    Prevent GRMON from automatically resetting the USB host controller cores.

6.6.2. Commands

The drivers for the USB host controller cores provides the commands listed in Table 6.3.

Table 6.3. GRUSBHC commands

| **ehci** | Controll the USB host ECHI core |
| **uhci** | Controll the USB host UHCI core |

6.7. I^{2}C

The I^{2}C-master debug driver initializes the core's prescaler register for operation in normal mode (100 kb/s). The driver supplies commands that allow read and write transactions on the I^{2}C-bus. I.a. it automatically enables the core when a read or write command is issued.

The I2CMST core is accessed using the command **i2c**, see command description in Appendix B, *Command syntax* for more information.

6.8. I/O Memory Management Unit

The debug driver for GRIOMMU provides commands for configuring the core, reading core status information, diagnostic cache accesses and error injection to the core's internal cache (if implemented). The debug driver also has support for building, modifying and decoding Access Protection Vectors and page table structures located in system memory.

The GRIOMMU core is accessed using the command **iommu**, see command description in Appendix B, *Command syntax* for more information.

The **info sys** command displays information about available protection modes and cache configuration.

```
iommu0    Cobham Gaisler   IO Memory Management Unit
```

```
AHB Master 4
AHB: FF840000 - FF848000
IRQ: 31
Device index: 0
Protection modes: APV and IOMMU
msts: 9, grps: 8, accsz: 128 bits
APV cache lines: 32, line size: 16 bytes
cached area: 0x00000000 - 0x80000000
IOMMU TLB entries: 32, entry size: 16 bytes
translation mask: 0xff000000
Core has multi-bus support
```

6.9. Multi-processor interrupt controller

The debug driver for IRQMP provides commands for forcing interrupts and reading core status information. The debug driver also supports ASMP and other extension provided in the IRQ(A)MP core. The IRQMP and IRQAMP cores are accessed using the command **irq**, see command description in Appendix B, *Command syntax* for more information.

The **info sys** command displays information on the cores memory map. I.a. if extended interrupts are enabled it shows the extended interrupt number.

```
irqmp0    Cobham Gaisler  Multi-processor Interrupt Ctrl.
          APB: FF904000 - FF908000
          EIRQ: 10
```

6.10. L2-Cache Controller

The debug driver for L2C is accessed using the command **l2cache**, see command description in Appendix B, *Command syntax* for more information. It provides commands for showing status, data and hit-rate. It also provides commands for enabling/disabling options and flushing or invalidating the cache lines.

If the L2C core has been configured with memory protection, then the **l2cache error** subcommand can be used to inject check bit errors and to read out error detection information.

L2-Cache is enabled by default when GRMON resets the system. This behavior can be disabled by giving the -nl2c command line option which instead disables the cache. L2-Cache can be enabled/disabled later by the user or by software in either case. If -ni is given, then L2-Cache state is not altered when GRMON starts.

When GRMON is started without -ni and -nl2c, the L2-Cache controller will be configured with EDAC disabled, LRU replacement policy, no locked ways, copy-back replacement policy and not using *HPROT* to determine cachability. Pending EDAC error injection is also removed.

When connecting without -ni, if the L2-Cache is disabled, the L2-Cache contents will be invalidated to make sure that any random power-up values will not affect execution. If the L2-Cache was already enabled, it is assumed that the contents are valid and L2-Cache is flushed to backing memory and then invalidated.

When enabling L2-Cache, the subcommand **l2cache disable flushinvalidate** can be used to atomically invalidate and write back dirty lines. The inverse operation is **l2cache invalidate** followed by **l2cache enable**. For debugging the state of L2-Cache itself, it may be more appropriate to use **l2cache disable** as it does not have any side effects on cache tags.

The **info sys** command displays the cache configuration.

```
l2cache0  Cobham Gaisler  L2-Cache Controller
          AHB Master 0
          AHB: 00000000 - 80000000
          AHB: F0000000 - F0400000
          AHB: FFE00000 - FFF00000
          IRQ: 28
          L2C: 4-ways, cachesize: 128 kbytes, mtrr: 16
```

6.10.1. Switches

```
-nl2c
```
   Disable L2-Cache on start-up.

6.11. Statistics Unit

The debug driver for L4STAT provides commands for reading and configuring the counters available in a L4STAT core. The L4STAT core can be implemented with two APB interfaces. GRMON treats a core with dual interfaces the same way as it would treat a system with multiple instances of L4STAT cores. If several L4STAT APB interfaces are found the l4stat command must be followed by an interface index reported by **info sys**. The **info sys** command displays also displays information about the number of counters available and the number of processor cores supported.

```
l4stat0    Cobham Gaisler  LEON4 Statistics Unit
           APB: E4000100 - E4000200
           cpus: 2, counters: 4, i/f index: 0

l4stat1    Cobham Gaisler  LEON4 Statistics Unit
           APB: FFA05000 - FFA05100
           cpus: 2, counters: 4, i/f index: 1
```

The L4STAT core is accessed using the command **l4stat**, see command description in Appendix B, *Command syntax* for more information.

If the core is connected to the DSU it is possible to count several different AHB events. In addition it is possible to apply filter to the signals connected to the L4STAT (if the DSU supports filter), see command **ahb filter performance** in Appendix B, *Command syntax*.

The **l4stat set** command is used to set up counting for a specific event. All allowed values for the event parameters are listed with **l4stat events**. The number and types of events may vary between systems. Example 6.1 shows how to set counter zero to count data cache misses on processor one and counter one to count instruction cache misses on processor zero.

Example 6.1.

```
grmon3> l4stat 1 events
  icmiss      - icache miss
  itmiss      - icache tlb miss
  ichold      - icache hold
  ithold      - icache mmu hold
  dcmiss      - dcache miss
 ... more events are listed ...

grmon3> l4stat 1 set 0 1 dcmiss
  cnt0: Enabling dcache miss on cpu/AHB 1

grmon3> l4stat 1 set 1 0 icmiss
  cnt1: Enabling icache miss on cpu/AHB 0

grmon3> l4stat 1 status
     CPU    DESCRIPTION                  VALUE
  0: cpu1  dcache miss                   0000000000
  1: cpu0  icache miss                   0000000000
  2: cpu0  icache miss                   0000000000 (disabled)
  3: cpu0  icache miss                   0000000000 (disabled)
```

Some of the L4STAT events 0x40-0x7F can be counted either per AHB master or independent of master. The **l4stat** command will only count events generated by the AHB master specified in the **l4stat set** command.

The L4STAT debug driver provides two modes that are used to continuously sample L4STAT counters. The driver will print out the latest read value(s) together with total accumulated amount(s) of events while polling. A poll operation can either be started directly or be deferred until the run command is issued. In both cases, counters should first be configured with the type of event to count. When this is done, one of the two following commands can be issued: **l4stat poll** `st sp int hold` or **l4stat runpoll** `st sp int`

The behavior of the first command, **l4stat poll**, depends on the hold argument. If hold is 0 or not specified, the specified counter(s) (st - sp) will be enabled and configured to be cleared on read. These counters will then be polled with an interval of int seconds. After each read, the core will print out the current and accumulated values for all counters. If the hold argument is 1, GRMON will not initialize the counters. Instead the first specified counter

(st) will be polled. When counter st is found to be enabled the polling operating will begin. This functionality can be used to, for instance, let software signal when measurements should take place.

Polling ends when at least one of the following is true: User pressed CTRL+C (SIGINT) or counter st becomes disabled. When polling stops, the debug driver will disable the selected counter(s) and also disable the automatic clear feature.

The second command, **l4stat runpoll**, is used to couple the poll operation with the run command. When **l4stat runpoll** $st\ sp\ int$ has been issued, counters st - sp will be polled after the run command is given. The interval argument in this case does not specify the poll interval seconds but rather in terms of iterations when GRMON polls the Debug Support Unit to monitor execution. A suitable value for the int argument in this case depends on the speed of the host computer, debug link and target system.

Example 6.2 is a transcript from a GRMON session where a vxWorks image is loaded and statistics are collected while it runs.

Example 6.2.

```
grmon3> l4stat 1 set 0 0 icmiss 0
  cnt0: Configuring icache miss on cpu/AHB 0

grmon3> l4stat 1 set 1 0 dcmiss 0
  cnt1: Configuring dcache miss on cpu/AHB 0

grmon3> l4stat 1 set 2 0 load 0
  cnt2: Configuring load instructions on cpu/AHB 0

grmon3> l4stat 1 set 3 0 store 0
  cnt3: Configuring store instructions on cpu/AHB

grmon3> l4stat 1 status
     CPU    DESCRIPTION                  VALUE
  0: cpu0   icache miss                  0000000000 (disabled)
  1: cpu0   dcache miss                  0000000000 (disabled)
  2: cpu0   load instructions            0000000000 (disabled)
  3: cpu0   store instructions           0000000000 (disabled)

grmon3> l4stat 1 runpoll 0 3 5000
  Setting up callbacks so that polling will be performed during 'run'

grmon3> load vxWorks
  00003000 .text                   1.5MB /   1.5MB   [===============>] 100%
  0018F7A8 .init$00                 12B             [===============>] 100%
  0018F7B4 .init$99                 8B              [===============>] 100%
  0018F7BC .fini$00                 12B             [===============>] 100%
  0018F7C8 .fini$99                 8B              [===============>] 100%
  0018F7E0 .data                 177.5kB / 177.5kB  [===============>] 100%
  Total size: 1.72MB (2.03Mbit/s)
  Entry point 0x3000
  Image vxWorks loaded

grmon3> run
  TIME      COUNTER     CURRENT READ     CURRENT RATE      TOTAL READ     TOTAL RATE
        5.88       0       1973061          335783          1973061        335783
        5.88       1       7174279         1220946          7174279       1220946
        5.88       2      22943354         3904587         22943354       3904587
        5.88       3        491916           83716           491916         83716
       11.16       0             0               0          1973061        176718
       11.16       1      11014132         2082460         18188411       1629056
       11.16       2      33072417         6253057         56015771       5017087
       11.16       3         15751            2978           507667         45470
   ... output removed ...
       51.35       0             0               0          1973061         38425
       51.35       1      12113004         2079486        101754132       1981657
       51.35       2      36365101         6242936        306891414       5976697
       51.35       3         17273            2965           627067         12212
```

And alternative to coupling polling to the run command is to break execution, issue **detach** and then use the **l4stat poll** command. There are a few items that may be worth considering when using poll and runpoll.

- All counters are not read in the same clock cycle. Depending on the debug link used there may be a significant delay between the read of the first and the last counter.
- Measurements are timed on the host computer and reads experience jitter from several sources.
- A counter may overflow after 232 target clock cycles. The poll period (interval) should take this into account so that counters are read (and thereby cleared) before an overflow can occur.

- Counters are disabled when polling stops
- **l4stat runpoll** is only supported for uninterrupted run. Commands like **bp** and **cont** may disrupt measurements.
- If the L4STAT core has two APB interfaces, initialize it via the interface to which traffic causes the least disturbance to other system bus traffic.

6.12. LEON2 support

A LEON2 system has a fixed set of IP cores and address mapping. GRMON will use an internal plug and play table that describes this configuration. The plug and play table used for LEON2 is fixed, and no automatic detection of present cores is attempted. Only those cores that need to be initialized by GRMON are included in the table, so the listing might not correspond to the actual target.

By default, GRMON will enable the UART receivers and transmitters for the AT697E/F by setting the corresponding bits in the IODIR register to output. This can be disabled by providing the commandline switch `-at697-nouart`, GRMON will then reset the IODIR to inputs on all bits.

6.12.1. Switches

```
-sys at697
-sys at697e
```
    Disable plug and play scanning and configure GRMON for an AT697E system

```
-sys at697f
```
    Disable plug and play scanning and configure GRMON for an AT697F system

```
-at697-nouart
```
    Disable GPIO alternate UART function. When this is set, GRMON will reset the GPIO dir register bits to input. By default GRMON will setup the GPIO dir register to enable both UARTs for the AT697E/F.

```
-sys agga4
```
    Disable plug and play scanning and configure GRMON for an AGGA4 system

```
-agga4-nognss
```
    Disable the built-in support for the GNSS core to make sure that GRMON never makes any accesses to the core. This flag should be used if no clock is provided to the GNSS core.

```
-sys leon2
```
    Disable plug and play scanning and configure GRMON for a LEON2 system

6.13. On-chip logic analyzer driver

The LOGAN debug driver contains commands to control the LOGAN on-chip logic analyzer core. It allows to set various triggering conditions and to generate VCD waveform files from trace buffer data.

The LOGAN core is accessed using the command **la**, see command description in Appendix B, *Command syntax* for more information.

The LOGAN driver can create a VCD waveform file using the **la dump** command. The file `setup.logan` is used to define which part of the trace buffer belong to which signal. The file is read by the debug driver before a VCD file is generated. An entry in the file consists of a signal name followed by its size in bits separated by white-space. Rows not having these two entries as well as rows beginning with an # are ignored. GRMON will look for the file in the current directory. I.e. either start GRMON from the directory where `setup.logan` is located or use the Tcl command **cd**, in GRMON, to change directory.

Example 6.3.

```
#Name      Size
clk        1
seq        14
edclstate  4
txdstate   5
dataout0   32
dataout1   32
dataout2   32
dataout3   32
writem     1
writel     1
nak        1
```

```
lock      1
```

The Example 6.3 has a total of 128 traced bits, divided into twelve signals of various widths. The first signal in the configuration file maps to the most significant bits of the vector with the traced bits. The created VCD file can be opened by waveform viewers such as GTKWave or Dinotrace.
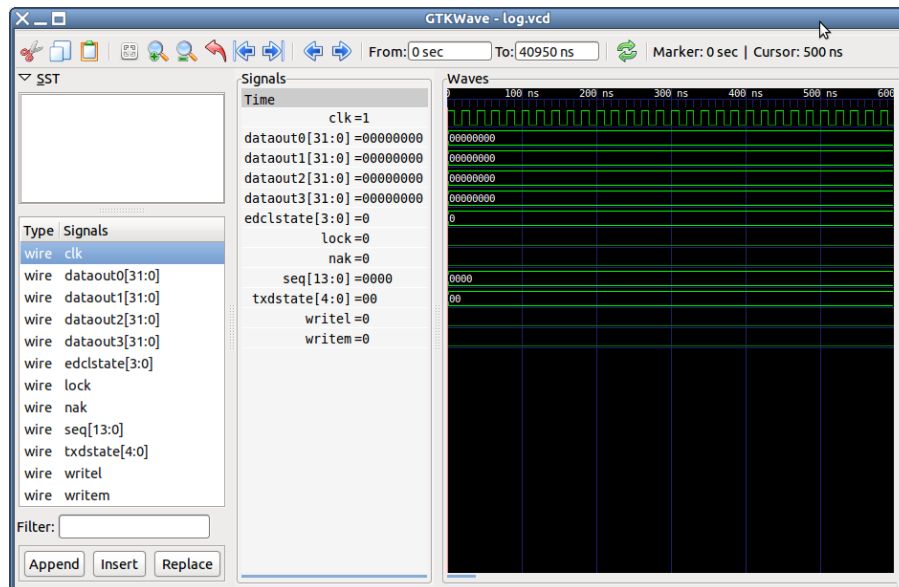
Figure 6.1. GTKWave

6.14. Memory controllers

SRAM/SDRAM/PROM/IO memory controllers.   Most of the memory controller debug drivers provides switches for timing, wait state control and sizes. They also probes the memory during GRMON's initialization. In addition they also enables some commands. The **mcfg#** sets the reset value [1] of the registers. The **info sys** shows the timing and amount of detected memory of each type. Supported cores: MCTRL, SRCTRL, SSRCTRL, FTMCTRL, FTSRCTRL, FTSRCTRL8

```
  mctrl0     European Space Agency  LEON2 Memory Controller
             AHB: 00000000 - 20000000
             AHB: 20000000 - 40000000
             AHB: 40000000 - 80000000
             APB: 80000000 - 80000100
             8-bit prom @ 0x00000000
             32-bit sdram: 1 * 64 Mbyte @ 0x40000000
             col 9, cas 2, ref 7.8 us
```

PC133 SDRAM Controller .   PC133 SDRAM debug drivers provides switches for timing. It also probes the memory during GRMON's initialization. In addition it also enables the **sdcfg1** affects, that sets the reset value [1] of the register. Supported cores: SDCTRL, FTSDCTRL

DDR memory controller.   The DDR memory controller debug drivers provides switches for timing. It also performs the DDR initialization sequence and probes the memory during GRMON's initialization. It does not enable any commands. The **info sys** shows the DDR timing and amount of detected memory. Supported cores: DDRSPA

DDR2 memory controller.   The DDR2 memory controller debug driver provides switches for timing. It also performs the DDR2 initialization sequence and probes the memory during GRMON's initialization. In addition it also enables some commands. The **ddr2cfg#** only affect the DDR2SPA, that sets the reset value [1] of the register. The commands **ddr2skew** and **ddr2delay** can be used to adjust the timing. The **info sys** shows the DDR timing and amount of detected memory Supported cores: DDR2SPA

```
  ddr2spa0  Cobham Gaisler  Single-port DDR2 controller
            AHB: 40000000 - 80000000
```

---

[1] The memory register reset value will be written when GRMON's resets the drivers, for example when **run** or **load** is called.

```
AHB: FFE00100 - FFE00200
  32-bit DDR2 : 1 * 256 MB @ 0x40000000, 8 internal banks
  200 MHz, col 10, ref 7.8 us, trfc 135 ns
```

SPI memory controller.   The SPI memory controller debug driver is affected by the common memory commands, but provides commands **spim** to perform basic communication with the core. The driver also provides functionality to read the CSD register from SD Card and a command to reinitialize SD Cards. The debug driver has bindings to the SPI memory device layer. These commands are accessed via **spim flash**. Please see Section 3.11.2, "SPI memory device" for more information. Supported cores: SPIMCTRL

6.14.1. Switches

-edac
>   Enable EDAC operation (FTMCTRL, FTSRCTRL, FTSRCTRL8)

-edac8*[4|5]*
>   Overrides the auto-probed EDAC area size for 8-bit RAM. Valid values are 4 if the EDAC uses a quarter of the memory, or 5 if the EDAC uses a fifth. (FTMCTRL)

-rsedac
>   Enable Reed-Solomon EDAC operation (FTMCTRL)

-mcfg1 *<val>*
>   Set the reset value for memory configuration register 1 (MCTRL, FTMCTRL, SSRCTRL)

-mcfg2 *<valn>*
>   Set the reset value for memory configuration register 2 (MCTRL, FTMCTRL)

-mcfg3 *<val>*
>   Set the reset value for memory configuration register 3 (MCTRL, FTMCTRL, SSRCTRL)

-pageb
>   Enable SDRAM page burst (FTMCTRL)

-normw
>   Disables read-modify-write cycles for sub-word writes to 16- bit 32-bit areas with common write strobe (no byte write strobe). (MCTRL, FTMCTRL)

ROM switches:

-romwidth *[8|16|32]*
>   Set the rom bit width. Valid values are 8, 16 or 32. (MCTRL, FTMCTRL, SRCTRL, FTSRCTRL, FTSRCTRL8)

-romrws *<n>*
>   Set *n* number of wait-states for rom reads. (MCTRL, FTMCTRL, SSRCTRL)

-romwws *<n>*
>   Set *n* number of wait-states for rom writes. (MCTRL, FTMCTRL, SSRCTRL)

-romws *<n>*
>   Set *n* number of wait-states for rom reads and writes. (MCTRL, FTMCTRL, SSRCTRL)

SRAM switches:

-nosram
>   Disable SRAM and map SDRAM to the whole plug and play bar. (MCTRL, FTMCTRL, SSRCTRL)

-nosram5
>   Disable SRAM bank 5 detection. (MCTRL, FTMCTRL)

-ram *<kB>*
>   Overrides the auto-probed amount of static ram bank size. Bank size is given in kilobytes. (MCTRL, FTMCTRL)

-rambanks *<n>*
>   Overrides the auto-probed number of populated ram banks. (MCTRL, FTMCTRL)

-ramwidth *[8|16|32]*
>   Overrides the auto-probed ram bit width. Valid values are 8, 16 or 32. (MCTRL, FTMCTRL)

-ramrws *<n>*
>   Set *n* number of wait-states for ram reads. (MCTRL, FTMCTRL)

-ramwws *<n>*
>   Set *n* number of wait-states for ram writes. (MCTRL, FTMCTRL)

`-ramws <n>`
Set *n* number of wait-states for rom reads and writes. (MCTRL, FTMCTRL)

SDRAM switches:

`-cas <cycles>`
Programs SDRAM to either 2 or 3 cycles CAS latency and RAS/CAS delay. Default is 2. (MCTRL, FTM-CTRL, SDCTRL, FTSDCTRL)

`-ddr2cal`
Run delay calibration routine on start-up before probing memory (see **ddr2delay scan** command).(DDR2SPA) (DDR2SPA)

`-nosdram`
Disable SDRAM. (MCTRL, FTMCTRL)

`-ref <us>`
Set the refresh reload value, default is 7.8us (64ms, 8,192-cycle refresh). (MCTRL, FTMCTRL, SDCTRL, FTSDCTRL)

`-regmem`
Enable registered memory. (DDR2SPA)

`-trcd <cycles>`
Programs SDRAM to either 2 or 3 cycles RAS/CAS delay. Default is 2. (DDRSPA, DDR2SPA)

`-trfc <ns>`
Programs the SDRAM trfc to the specified timing. (MCTRL, FTMCTRL, DDRSPA, DDR2SPA, SDC-TRL, FTSDCTRL)

`-trp3`
Programs the SDRAM trp timing to 3. Default is 2. (MCTRL, FTMCTRL, DDRSPA, DDR2SPA, SDC-TRL, FTSDCTRL)

`-twr`
Programs the SDRAM twr to the specified timing. (DDR2SPA)

`-sddel <value>`
Set the SDCLK value. (MCTRL, FTMCTRL)

`-sd2tdis`
Disable SDRAM 2T signaling. By default 2T is enabled on GR740 during GRMON initialization. (GR740 SDCTRL)

`-sdfreq <mhz>`
Set SDRAM frequency in MHz. Default is the system frequency (except for GR740 which defaults to 50MHz). (MCTRL, FTMCTRL, SDCTRL, FTSDCTRL)

6.14.2. Commands

The driver for the Debug support unit provides the commands listed in Table 6.4.

Table 6.4. MEMCTRL commands

ddr2cfg1	Show or set the reset value of the memory register
ddr2cfg2	Show or set the reset value of the memory register
ddr2cfg3	Show or set the reset value of the memory register
ddr2cfg4	Show or set the reset value of the memory register
ddr2cfg5	Show or set the reset value of the memory register
ddr2delay	Change read data input delay.
ddr2skew	Change read skew.
mcfg1	Show or set reset value of the memory controller register 1
mcfg2	Show or set reset value of the memory controller register 2
mcfg3	Show or set reset value of the memory controller register 3
sdcfg1	Show or set reset value of SDRAM controller register 1
sddel	Show or set the SDCLK delay

   spim   Commands for the SPI memory controller

6.15. Memory scrubber

The MEMSCRUB core is accessed using the command **scrub**, see command description in Appendix B, *Command syntax* for more information. It provides commands for reading the core's status, and performing some basic operations such as clearing memory.

The **info sys** command displays information on the configured burst length of the scrubber.

```
memscrub0 Cobham Gaisler  AHB Memory Scrubber
        AHB Master 1
        AHB: FFE01000 - FFE01100
        IRQ: 28
        burst length: 32 bytes
```

6.16. MIL-STD-1553B Interface

The **info sys** command displays the enabled parts of the core, and the configured codec clock frequency. The GR1553B core is accessed using the command **mil**, see command description in Appendix B, *Command syntax* for more information.

```
gr1553b0  Cobham Gaisler  MIL-STD-1553B Interface
        APB: FFA02000 - FFA02100
        IRQ: 26
        features: BC RT BM, codec clock: 20 MHz
        Device index: 0
```

Examining data structures.   The **mil bcx** and **mil bmx** commands prints the contents of memory interpreted as BC descriptors or BM entries, in human readable form, as seen in Example 6.4.

Example 6.4.

```
grmon3> mil bcx 0x40000080
  Address     TType  RTAddr:SA  WC Bus  Tries   SlTime TO Options Result   vStat BufPtr
  =========== ===== =========== == === ======= ====== == ======= ======= ==== ========
  0x40000080 BC-RT    05:30     1  B  01:Same      0 14       s   NoRes 1 0000 40000000
  0x40000090 RT-BC    05:30     1  B  01:Same      0 14       s   [Not written] 40000040
  0x400000a0 BC-RT    05:30     2  B  01:Same      0 14       s   [Not written] 40000000
  0x400000b0 RT-BC    05:30     2  B  01:Same      0 14       s   [Not written] 40000040
  0x400000c0 BC-RT    05:30     3  B  01:Same      0 14       s   [Not written] 40000000
  0x400000d0 RT-BC    05:30     3  B  01:Same      0 14       s   [Not written] 40000040
  0x400000e0 BC-RT    05:30     4  B  01:Same      0 14       s   [Not written] 40000000
```

Data transfers.   If the GR1553B core is BC capable, you can perform data transfers directly from the GRMON command line. The commands exist in two variants: **mil get** and **mil put** that specify data directly on the command line and through the terminal, and **mil getm** and **mil putm** that sends/receives data to an address in RAM.

In order to perform BC data transfers, you must have a temporary buffer in memory to store descriptors and data, this is set up with the **mil buf** command.

The data transfer commands use the asynchronous scheduling feature of the core, which means that the command can be performed even if a regular BC schedule is running in parallel. The core will perform the transfer while the primary schedule is idle and will not affect the schedule. It can even be run with BC software active in the background, as long as the software does not make use of asynchronous transfer lists.

If the primary schedule blocks the asynchronous transfer for more than two seconds, the transfer will be aborted and an error message is printed. This can happen if the running schedule does not have any slack, or if it is stuck in suspended state or waiting for a sync pulse with no previous slot time left. In this case, you need to stop the ordinary processing (see mil halt) and retry the transfer.

Temporary data buffer.   Many of the mil subcommands need a temporary data buffer in order to do their work. The address of this buffer is set using the **mil buf** command and defaults to the start of RAM. By default the driver will read out the existing contents and write it back after the transfer is done, this can be changed using the **mil bufmode** command.

If the core is on a different bus where the RAM is at another address range, the scratch area address in the core's address space should be given as an additional *coreaddr* argument to the **mil buf** command.

Halting and resuming. The **mil halt** command will stop and disable the RT, BC and BM parts of the core, preventing them from creating further DMA and 1553 bus traffic during debugging. Before this is done, the current enable state is stored, which allows it to later be restored using **mil resume**. The core is halted gracefully and the command will wait for current ongoing transfers to finish.

The state preserved between mil halt and mil resume are:
- BC schedules' (both primary and async) states and next positions. If schedule is not stopped, the last transfer status is also preserved (as explained below)
- BC IRQ ring position
- RT address, enable status, subaddress table location, mode code control register, event log size and position
- BM enable status, filter settings, ring buffer pointers, time tag setup

State that is not preserved is:
- IRQ set/clear status
- BC schedule time register and current slot time left.
- RT bus words and sync register
- RT and BM timer values
- Descriptors and other memory contents

For the BC, some extra handling is necessary as the last transfer status is not accessible via the register interface. In some cases, the BC must be probed for the last transfer status by running a schedule with conditional suspends and checking which ones are taken. This requires the temporary data buffer to be setup (see **mil buf**).

Loop-back test. The debug driver contains a loop-back test command **mil lbtest** for testing 1553 transmission on both buses between two devices. In this test, one of the devices is configured as RT with a loop-back subaddress 30. The other device is configured as BC, sends and receives back data with increasing transfer size up to the maximum of 32 words.

The **mil lbtest** command needs a 16K RAM scratch area, which is either given as extra argument or selected using the **mil buf** command as described in the previous section.

Before performing the loop-back test, the routine performs a test of the core's internal time base, by reading out the timer value at a time interval, and displays the result. This is to quickly identify if the clock provided to the core has the wrong frequency.

In the RT case, the command first configures the RT to the address given and enables subaddress 30 in loop-back mode with logging. The RT event log is then polled and events arriving are printed out to the console. The command exits after 60 seconds of inactivity.

In the BC case, the command sets up a descriptor list with alternating BC-to-RT and RT-to-BC transfers of increasing size. After running through the list, the received and transmitted data are compared. This is looped twice, for each bus.

6.17. PCI

The debug driver for the PCI cores are mainly useful for PCI host systems. It provides a command that initializes the host. The initialization sets AHB to PCI memory address translation to 1:1, AHB to PCI I/O address translation to 1:1, points BAR1 to 0x40000000 and enables PCI memory space and bus mastering, but it will not configure target bars. To configure the target bars on the pci bus, call **pci conf** after the core has been initialized. Commands for scanning the bus, disabling byte twisting and displaying information are also provided.

The PCI cores are accessed using the command **pci**, see command description in Appendix B, *Command syntax* for more information. Supported cores are GRPCI, GRPCI2 and PCIF.

The PCI commands have been split up into several sub commands in order for the user to have full control over what is modified. The init command initializes the host controller, which may not be wanted when the LEON target software has set up the PCI bus. The typical two different use cases are, GRMON configures PCI or GRMON scan PCI to viewing the current configuration. In the former case GRMON can be used to debug PCI hardware and the setup, it enables the user to set up PCI so that the CPU or GRMON can access PCI boards over I/O, Memory and/or Configuration space and the PCI board can do DMA to the 0x40000000 AMBA address. The latter case

is often used when debugging LEON PCI software, the developer may for example want to see how Linux has configured PCI but not to alter anything that would require Linux to reboot. Below are command sequences of the two typical use cases on the ML510 board:

```
grmon3> pci init

grmon3> pci conf

  PCI devices found:

  Bus 0 Slot 1 function: 0 [0x8]
   Vendor id: 0x10b9 (ULi Electronics Inc.)
   Device id: 0x5451 (M5451 PCI AC-Link Controller Audio Device)
   IRQ INTA#  LINE: 0
   BAR 0: 1201 [256B]
   BAR 1: 82206000 [4kB]

  Bus 0 Slot 2 function: 0 [0x10]
   Vendor id: 0x10b9 (ULi Electronics Inc.)
   Device id: 0x1533 (M1533/M1535/M1543 PCI to ISA Bridge [Aladdin IV/V/V+])

  Bus 0 Slot 3 function: 0 [0x18]
   Vendor id: 0x10b9 (ULi Electronics Inc.)
   Device id: 0x5457 (M5457 AC'97 Modem Controller)
   IRQ INTA#  LINE: 0
   BAR 0: 82205000 [4kB]
   BAR 1: 1101 [256B]

  Bus 0 Slot 6 function: 0 [0x30] (BRIDGE)
   Vendor id: 0x3388 (Hint Corp)
   Device id: 0x21 (HB6 Universal PCI-PCI bridge (non-transparent mode))
   Primary: 0  Secondary: 1  Subordinate: 1
   I/O:   BASE: 0x0000f000, LIMIT: 0x00000fff (DISABLED)
   MEMIO: BASE: 0x82800000, LIMIT: 0x830fffff (ENABLED)
   MEM:   BASE: 0x80000000, LIMIT: 0x820fffff (ENABLED)

  Bus 0 Slot 9 function: 0 [0x48] (BRIDGE)
   Vendor id: 0x104c (Texas Instruments)
   Device id: 0xac23 (PCI2250 PCI-to-PCI Bridge)
   Primary: 0  Secondary: 2  Subordinate: 2
   I/O:   BASE: 0x00001000, LIMIT: 0x00001fff (ENABLED)
   MEMIO: BASE: 0x82200000, LIMIT: 0x822fffff (ENABLED)
   MEM:   BASE: 0x82100000, LIMIT: 0x821fffff (ENABLED)

  Bus 0 Slot c function: 0 [0x60]
   Vendor id: 0x10b9 (ULi Electronics Inc.)
   Device id: 0x7101 (M7101 Power Management Controller [PMU])

  Bus 0 Slot f function: 0 [0x78]
   Vendor id: 0x10b9 (ULi Electronics Inc.)
   Device id: 0x5237 (USB 1.1 Controller)
   IRQ INTA#  LINE: 0
   BAR 0: 82204000 [4kB]

  Bus 1 Slot 0 function: 0 [0x100]
   Vendor id: 0x102b (Matrox Electronics Systems Ltd.)
   Device id: 0x525 (MGA G400/G450)
   IRQ INTA#  LINE: 0
   BAR 0: 80000008 [32MB]
   BAR 1: 83000000 [16kB]
   BAR 2: 82800000 [8MB]
   ROM:   82000001 [128kB] (ENABLED)

  Bus 2 Slot 2 function: 0 [0x210]
   Vendor id: 0x10b9 (ULi Electronics Inc.)
   Device id: 0x5237 (USB 1.1 Controller)
   IRQ INTB#  LINE: 0
   BAR 0: 82202000 [4kB]

  Bus 2 Slot 2 function: 1 [0x211]
   Vendor id: 0x10b9 (ULi Electronics Inc.)
   Device id: 0x5237 (USB 1.1 Controller)
   IRQ INTC#  LINE: 0
   BAR 0: 82201000 [4kB]

  Bus 2 Slot 2 function: 2 [0x212]
   Vendor id: 0x10b9 (ULi Electronics Inc.)
   Device id: 0x5237 (USB 1.1 Controller)
   IRQ INTD#  LINE: 0
   BAR 0: 82200000 [4kB]

  Bus 2 Slot 2 function: 3 [0x213]
```

```
 Vendor id: 0x10b9 (ULi Electronics Inc.)
 Device id: 0x5239 (USB 2.0 Controller)
 IRQ INTA#  LINE: 0
 BAR 0: 82203200 [256B]


Bus 2 Slot 3 function: 0 [0x218]
 Vendor id: 0x1186 (D-Link System Inc)
 Device id: 0x4000 (DL2000-based Gigabit Ethernet)
 IRQ INTA#  LINE: 0
 BAR 0: 1001 [256B]
 BAR 1: 82203000 [512B]
 ROM:   82100001 [64kB] (ENABLED)
```

When analyzing the system, the sub commands *info* and *scan* can be called without altering the hardware configuration:

```
grmon3> pci info

 GRPCI initiator/target (in system slot):

   Bus master:    yes
   Mem. space en: yes
   Latency timer: 0x0
   Byte twisting: disabled

   MMAP:          0x8
   IOMAP:         0xfff2

   BAR0:          0x00000000
   PAGE0:         0x40000001
   BAR1:          0x40000000
   PAGE1:         0x40000000

grmon3> pci scan
 Warning: PCI driver has not been initialized
 Warning: PCI driver has not been initialized

 PCI devices found:

 Bus 0 Slot 1 function: 0 [0x8]
  Vendor id: 0x10b9 (ULi Electronics Inc.)
  Device id: 0x5451 (M5451 PCI AC-Link Controller Audio Device)
  IRQ INTA#  LINE: 0
  BAR 0: 1201 [256B]
  BAR 1: 82206000 [4kB]

 Bus 0 Slot 2 function: 0 [0x10]
  Vendor id: 0x10b9 (ULi Electronics Inc.)
  Device id: 0x1533 (M1533/M1535/M1543 PCI to ISA Bridge [Aladdin IV/V/V+])

 Bus 0 Slot 3 function: 0 [0x18]
  Vendor id: 0x10b9 (ULi Electronics Inc.)
  Device id: 0x5457 (M5457 AC'97 Modem Controller)
  IRQ INTA#  LINE: 0
  BAR 0: 82205000 [4kB]
  BAR 1: 1101 [256B]

 Bus 0 Slot 6 function: 0 [0x30] (BRIDGE)
  Vendor id: 0x3388 (Hint Corp)
  Device id: 0x21 (HB6 Universal PCI-PCI bridge (non-transparent mode))
  Primary: 0  Secondary: 1  Subordinate: 1
  I/O:   BASE: 0x0000f000, LIMIT: 0x00000fff (DISABLED)
  MEMIO: BASE: 0x82800000, LIMIT: 0x830fffff (ENABLED)
  MEM:   BASE: 0x80000000, LIMIT: 0x820fffff (ENABLED)

 Bus 0 Slot 9 function: 0 [0x48] (BRIDGE)
  Vendor id: 0x104c (Texas Instruments)
  Device id: 0xac23 (PCI2250 PCI-to-PCI Bridge)
  Primary: 0  Secondary: 2  Subordinate: 2
  I/O:   BASE: 0x00001000, LIMIT: 0x00001fff (ENABLED)
  MEMIO: BASE: 0x82200000, LIMIT: 0x822fffff (ENABLED)
  MEM:   BASE: 0x82100000, LIMIT: 0x821fffff (ENABLED)

 Bus 0 Slot c function: 0 [0x60]
  Vendor id: 0x10b9 (ULi Electronics Inc.)
  Device id: 0x7101 (M7101 Power Management Controller [PMU])

 Bus 0 Slot f function: 0 [0x78]
  Vendor id: 0x10b9 (ULi Electronics Inc.)
  Device id: 0x5237 (USB 1.1 Controller)
  IRQ INTA#  LINE: 0
  BAR 0: 82204000 [4kB]
```

```
 Bus 1 Slot 0 function: 0 [0x100]
  Vendor id: 0x102b (Matrox Electronics Systems Ltd.)
  Device id: 0x525 (MGA G400/G450)
  IRQ INTA#  LINE: 0
  BAR 0: 80000008 [32MB]
  BAR 1: 83000000 [16kB]
  BAR 2: 82800000 [8MB]
  ROM:   82000001 [128kB] (ENABLED)

 Bus 2 Slot 2 function: 0 [0x210]
  Vendor id: 0x10b9 (ULi Electronics Inc.)
  Device id: 0x5237 (USB 1.1 Controller)
  IRQ INTB#  LINE: 0
  BAR 0: 82202000 [4kB]

 Bus 2 Slot 2 function: 1 [0x211]
  Vendor id: 0x10b9 (ULi Electronics Inc.)
  Device id: 0x5237 (USB 1.1 Controller)
  IRQ INTC#  LINE: 0
  BAR 0: 82201000 [4kB]

 Bus 2 Slot 2 function: 2 [0x212]
  Vendor id: 0x10b9 (ULi Electronics Inc.)
  Device id: 0x5237 (USB 1.1 Controller)
  IRQ INTD#  LINE: 0
  BAR 0: 82200000 [4kB]

 Bus 2 Slot 2 function: 3 [0x213]
  Vendor id: 0x10b9 (ULi Electronics Inc.)
  Device id: 0x5239 (USB 2.0 Controller)
  IRQ INTA#  LINE: 0
  BAR 0: 82203200 [256B]

 Bus 2 Slot 3 function: 0 [0x218]
  Vendor id: 0x1186 (D-Link System Inc)
  Device id: 0x4000 (DL2000-based Gigabit Ethernet)
  IRQ INTA#  LINE: 0
  BAR 0: 1001 [256B]
  BAR 1: 82203000 [512B]
  ROM:   82100001 [64kB] (ENABLED)

grmon3> pci bus reg

grmon3> info sys pdev0 pdev5 pdev10
  pdev0      Bus 00 Slot 01 Func 00 [0:1:0]
             vendor: 0x10b9 ULi Electronics Inc.
             device: 0x5451 M5451 PCI AC-Link Controller Audio Device
             class:  040100 (MULTIMEDIA)
             BAR1: 00001200 - 00001300 I/O-32 [256B]
             BAR2: 82206000 - 82207000 MEMIO  [4kB]
             IRQ INTA# -> IRQX
  pdev5      Bus 00 Slot 09 Func 00 [0:9:0]
             vendor: 0x104c Texas Instruments
             device: 0xac23 PCI2250 PCI-to-PCI Bridge
             class:  060400 (PCI-PCI BRIDGE)
             Primary: 0  Secondary: 2  Subordinate: 2
             I/O Window:     00001000 - 00002000
             MEMIO Window:  82200000 - 82300000
             MEM Window:     82100000 - 82200000
  pdev10     Bus 02 Slot 03 Func 00 [2:3:0]
             vendor: 0x1186 D-Link System Inc
             device: 0x4000 DL2000-based Gigabit Ethernet
             class:  020000 (ETHERNET)
             subvendor: 0x1186, subdevice: 0x4004
             BAR1: 00001000 - 00001100 I/O-32 [256B]
             BAR2: 82203000 - 82203200 MEMIO  [512B]
             ROM:  82100000 - 82110000 MEM    [64kB]
             IRQ INTA# -> IRQW
```

A configured PCI system can be registered into the GRMON device handling system similar to the on-chip AMBA bus devices, controlled using the **pci bus** commands. GRMON will hold a copy of the PCI configuration in memory until a new **pci conf**, **pci bus unreg** or **pci scan** is issued. The user is responsible for updating GRMON's PCI configuration if the configuration is updated in hardware. The devices can be inspected from **info sys** and Tcl variables making read and writing PCI devices configuration space easier. The Tcl variables are named in a similar fashion to AMBA devices, for example **puts $pdev0::status** prints the STATUS register of PCI device0. See **pci bus** reference description and Appendix C, *Tcl API*.

Only the **pci info** command has any effect on non-host systems.

Also note that the **pci conf** command can fail to configure all found devices if the PCI address space addressable by the PCI Host controller is smaller than the amount of memory needed by the devices.

The **pci scan** command may fail if the PCI buses (PCI-PCI bridges) haven't been enumerated correctly in a multi-bus PCI system.

After registering the PCI bus into GRMON's device handling system commands may access device information and Tcl may access variables (PCI configuration space registers). Accessing bad PCI regions may lead to target deadlock where the debug-link may disconnect/hang. It is the user's responsibility to make sure that GRMON's PCI information is correct. The PCI bus may need to be re-scanned/unregistered when changes to the PCI configuration has been made by the target OS running on the LEON.

6.17.1. PCI Trace

The **pci trace** commands are supported by the cores PCITRACE, GRPCI2 and GRPCI2_TB. The commands can be used to control the trace and viewing trace data. With the commands it is possible to set up trigger conditions that must match to set the trigger off. When the triggering condition is matched the AHBTRACE stops the recording of the PCI bus and the log is available for inspection using the **pci trace log** command. The **pci trace tdelay** command can be used to delay the stop of the trace recording after a trigging match.

The **info sys** command displays the size of the trace buffer in number of lines.

```
pcitrace0 Cobham Gaisler  32-bit PCI Trace Buffer
          APB: C0101000 - C0200000
          Trace buffer size: 128 lines
pci0      Cobham Gaisler  GRPCI2 PCI/AHB bridge
          AHB Master 5
          AHB: C0000000 - D0000000
          AHB: FFF00000 - FFF40000
          APB: 80000600 - 80000700
          IRQ: 6
          Trace buffer size: 1024 lines
pcitrace1 Cobham Gaisler  GRPCI2 Trace buffer
          APB: 80040000 - 80080000
          Trace buffer size: 1024 lines
```

6.18. SPI

The SPICTRL debug driver provides commands to configure the SPI controller core. The driver also enables the user to perform simple data transfers. The **info sys** command displays the core's FIFO depth and the number of available slave select signals.

```
spi0      Cobham Gaisler  SPI Controller
          APB: C0100000 - C0100100
          IRQ: 23
          FIFO depth: 8, 2 slave select signals
          Maximum word length: 32 bits
          Supports automated transfers
          Supports automatic slave select
          Controller index for use in GRMON: 0
```

The SPICTRL core is accessed using the command **spi**, see command description in Appendix B, *Command syntax* for more information.

The debug driver has bindings to the SPI memory device layer. These commands are accessed via **spi flash**. Please see Section 3.11.2, "SPI memory device" for more information.

For information about the SPI memory controller (SPIMCTRL), see Section 6.14, "Memory controllers ".

6.19. SpaceWire router

The SPWROUTER core is accessed using the command **spwrtr**, see command description in Appendix B, *Command syntax* for more information. It provides commands to display the core's registers. The command can also be used to display or setup the routing table.

The **info reg** command only displays a subset of all the registers available. Add `-all` to the **info reg** command to print all registers, or specify one or more register to print a subset. Add `-l` to **info reg** to list all the register names.

```
grmon3> info reg -all -l spwrtr0
  GRSPW Router
      0xff880004  rtpmap_1          Port  1 routing table map
      0xff880008  rtpmap_2          Port  2 routing table map
      0xff88000c  rtpmap_3          Port  3 routing table map
   ...

grmon3> info reg spwrtr0::pctrl_2 spwrtr0::rtpmap_2 spwrtr0::rtpmap_64
  GRSPW Router
      0xff880808  Port  2 control                     0x1300002c
  GRSPW Router
      0xff880008  Port  2 routing table map           0x00000021
  GRSPW Router
      0xff880100  Logical addr.  64 routing table map  0x00001c38
```

In addition, all registers and register fields are available as variables, see Tcl API more information.

The **info sys** command displays how many ports are implemented in the router.

```
  spwrtr0    Cobham Gaisler  GRSPW Router
             AHB: FF880000 - FF881000
             Instance id: 67
             SpW ports:  8  AMBA ports:  4  FIFO ports:  0
```

6.20. SVGA frame buffer

The SVGACTRL debug driver implements functions to report the available video clocks in the SVGA frame buffer, and to display screen patters for testing. The **info sys** command will display the available video clocks.

```
  svga0      Cobham Gaisler   SVGA frame buffer
             AHB Master 2
             APB: C0800000 - C0800100
             clk0: 25.00 MHz   clk1: 25.00 MHz   clk2: 40.00 MHz   clk3: 65.00 MHz
```

The SVGACTRL core is accessed using the command **svga**, see command description in Appendix B, *Command syntax* for more information.

The **svga draw test_screen** command will show a simple grid in the resolution specified via the format selection. The color depth can be either 16 or 32 bits.

The **svga draw** *file* command will determine the resolution of the specified picture and select an appropriate format (resolution and refresh rate) based on the video clocks available to the core. The required file format is ASCII PPM which must have a suitable amount of pixels. For instance, to draw a screen with resolution 640x480, a PPM file which is 640 pixels wide and 480 pixels high must be used. ASCII PPM files can be created with, for instance, the GNU Image Manipulation Program (The GIMP).

The **svga custom** *period horizontal-active-video horizontal-front-porch horizontal-sync horizontal-back-porch vertical-active-video vertical-front-porch vertical-sync vertical-back-porch* command can be used to specify a custom format. The custom format will have precedence when using the **svga draw** command.

7. Support

For support contact the Cobham Gaisler support team at support@gaisler.com.

When contacting support, please identify yourself in full, including company affiliation and site name and address. Please identify exactly what product that is used, specifying if it is an IP core (with full name of the library distribution archive file), component, software version, compiler version, operating system version, debug tool version, simulator tool version, board version, etc.

The support service is only for paying customers with a support contract.

Appendix A. Command index

This section lists all documented commands available in GRMON3.

Table A.1. GRMON command oveview

Command Name	Description
about	Show information about GRMON
ahb	Print AHB transfer entries in the trace buffer
amem	Asynchronous bus read
attach	Stop execution and attach GRMON to processor again
at	Print AHB transfer entries in the trace buffer
batch	Execute batch script
bdump	Dump memory to a file
bload	Load a binary file
bp	Add, delete or list breakpoints
bt	Print backtrace
cctrl	Display or set cache control register
cont	Continue execution
cpu	Enable, disable CPU or select current active cpu
dcache	Show, enable or disable data cache
dccfg	Display or set data cache configuration register
dcom	Print or clear debug link statistics
ddr2cfg1	Show or set the reset value of the memory register
ddr2cfg2	Show or set the reset value of the memory register
ddr2cfg3	Show or set the reset value of the memory register
ddr2cfg4	Show or set the reset value of the memory register
ddr2cfg5	Show or set the reset value of the memory register
ddr2delay	Change read data input delay.
ddr2skew	Change read skew.
detach	Resume execution with GRMON detached from processor
disassemble	Disassemble memory
dtb	Setup a DTB to be uploaded or print filenames of DTB files
dump	Dump memory to a file
dwarf	print or lookup dwarf information
edcl	Print or set the EDCL ip
eeload	Load a file into an EEPROM
ehci	Controll the USB host ECHI core
ei	Error injection
ep	Set entry point
execsh	Run commands in the execution shell
exit	Exit GRMON
flash	Write, erase or show information about the flash

Command Name	Description
float	Display FPU registers
forward	Control I/O forwarding
gdb	Controll the builtin GDB remote server
go	Start execution without any initialization
gr1553b	MIL-STD-1553B Interface commands
grcg	Control clockgating
grpwm	Controll the GRPWM core
grtmtx	Control GRTM devices
gui	Control the graphical user interface
help	Print all commands or detailed help for a specific command
hist	Print AHB transfer or intruction entries in the trace buffer
i2c	Commands for the I2C masters
icache	Show, enable or disable instruction cache
iccfg	Display or set instruction cache configuration register
info	Show information
inst	Print intruction entries in the trace buffer
iommu	Control IO memory management unit
irq	Force interrupts or read IRQ(A)MP status information
l2cache	L2 cache control
l3stat	Control Leon3 statistics unit
l4stat	Control Leon4 statistics unit
la	Control the LOGAN core
leon	Print leon specific registers
load	Load a file or print filenames of uploaded files
mcfg1	Show or set reset value of the memory controller register 1
mcfg2	Show or set reset value of the memory controller register 2
mcfg3	Show or set reset value of the memory controller register 3
mdio	Show PHY registers
memb	AMBA bus 8-bit memory read access, list a range of addresses
memd	AMBA bus 64-bit memory read access, list a range of addresses
memh	AMBA bus 16-bit memory read access, list a range of addresses
mem	AMBA bus 32-bit memory read access, list a range of addresses
mil	MIL-STD-1553B Interface commands
mmu	Print or set the SRMMU registers
nolog	Suppress stdout of a command
pci	Control the PCI bus master
perf	Measure performance
phyaddr	Set the default PHY address
profile	Enable, disable or show simple profiling
quit	Quit the GRMON console

Command Name	Description
reg	Show or set integer registers.
reset	Reset drivers
rtg4fddr	Print initialization sequence
rtg4serdes	Print initialization sequence
run	Reset and start execution
scrub	Control memory scrubber
sdcfg1	Show or set reset value of SDRAM controller register 1
sddel	Show or set the SDCLK delay
sf2mddr	Print initialization sequence
sf2serdes	Print initialization sequence
shell	Execute shell process
silent	Suppress stdout of a command
spim	Commands for the SPI memory controller
spi	Commands for the SPI controller
spwrtr	Spacewire router information
stack	Set or show the intial stack-pointer
step	Step one ore more instructions
stop	Interrupts current CPU execution
svga	Commands for the SVGA controller
symbols	Load, print or lookup symbols
thread	Show OS-threads information or backtrace
timer	Show information about the timer devices
tmode	Select tracing mode between none, processor-only, AHB only or both.
tps	Control the TPS service
uhci	Controll the USB host UHCI core
usrsh	Run commands in threaded user shell
va	Translate a virtual address
verify	Verify that a file has been uploaded correctly
vmemb	AMBA bus 8-bit virtual memory read access, list a range of addresses
vmemd	AMBA bus 64-bit virtual memory read access, list a range of addresses
vmemh	AMBA bus 16-bit virtual memory read access, list a range of addresses
vmem	AMBA bus 32-bit virtual memory read access, list a range of addresses
vwmemb	AMBA bus 8-bit virtual memory write access
vwmemd	AMBA bus 64-bit virtual memory write access
vwmemh	AMBA bus 16-bit virtual memory write access
vwmems	Write a string to an AMBA bus virtual memory address
vwmem	AMBA bus 32-bit virtual memory write access
walk	Translate a virtual address, print translation
wash	Clear or set memory areas
wmdio	Set PHY registers

Command Name	Description
wmemb	AMBA bus 8-bit memory write access
wmemd	AMBA bus 64-bit memory write access
wmemh	AMBA bus 16-bit memory write access
wmems	Write a string to an AMBA bus memory address
wmem	AMBA bus 32-bit memory write access

Appendix B. Command syntax

This section lists the syntax of all documented commands available in GRMON3

1. about - syntax

NAME

about - Show information about GRMON

SYNOPSIS

about

DESCRIPTION

   about

       Show information about GRMON

2. ahb - syntax

NAME

ahb - Print AHB transfer entries in the trace buffer

SYNOPSIS

ahb ?`length`?
ahb subcommand ?`args...`?

DESCRIPTION

ahb ?`length`?

Print the AHB trace buffer. The ?`length`? entries will be printed, default is 10.

ahb break `boolean`

Enable or disable if the AHB trace buffer should break the CPU into debug mode. If disabled it will freeze the buffer and the CPU will continue to execute. Default value of the boolean is true.

ahb force ?`boolean`?

Enable or disable the AHB trace buffer even when the processor is in debug mode. Default value of the boolean is true.

ahb performance ?`boolean`?

Enable or disable the filter on the signals connected to the performance counters, see "LEON3 Statistics Unit (L3STAT)" and "LEON4 Statistics Unit (L4STAT)". Only available for DSU3 version 2 and above, and DSU4.

ahb timer ?`boolean`?

Enable the timetag counter when in debug mode. Default value of the boolean is true. Only available for DSU3 version 2 and above, and DSU4.

ahb delay `cnt`

If `cnt` is non-zero, the CPU will enter debug-mode after delay trace entries after an AHB watchpoint was hit.

ahb filter reads ?`boolean`?
ahb filter writes ?`boolean`?
ahb filter addresses ?`boolean`? ?`address mask`?

Enable or disable filtering options if supported by the DSU core. When enabling the addresses filter, the second AHB breakpoint register will be used to define the range of the filter. Default value of the boolean is true. If left out, then the address and mask will be ignored. They can also be set with the command **ahb filter range**. (Not available in all implementations)

ahb filter range `address mask`

Set the base `address` and `mask` that the AHB trace buffer will include if the address filtering is enabled. (Only available in some DSU4 implementations).

ahb filter bwmask `mask`
ahb filter dwmask `mask`

Set which AHB bus/data watchpoints that the filter will affect.

ahb filter mmask `mask`
ahb filter smask `mask`

Set which AHB masters or slaves connected to the bus to exclude. (Only available in some DSU4 implementations)

ahb status

Print AHB trace buffer settings.

RETURN VALUE

Upon successful completion, **ahb** returns a list of trace buffer entries. Each entry is a sublist on the format format: {AHB *time addr data rw trans size master lock resp bp*}. The data field is a sublist of 1,2 or 4 words with MSB first, depending on the size of AMBA bus. Detailed description about the different fields can be found in the DSU core documentation in document grip.pdf. [http://gaisler.com/products/grlib/grip.pdf]

The other subcommands have no return value.

EXAMPLE

Print 10 rows

```
grmon3> ahb
     TIME     ADDRESS   D[127:96] D[95:64] D[63:32] D[31:0]  TYPE  ...
     266718 FF900004  00000084 00000084 00000084 00000084 read  ...
     266727 FF900000  0000000D 0000000D 0000000D 0000000D write ...
     266760 000085C0  C2042054 80A06000 02800003 01000000 read  ...
     266781 000085D0  C2260000 81C7E008 91E80008 9DE3BF98 read  ...
     266812 0000B440  00000000 00000000 00000000 00000000 read  ...
     266833 0000B450  00000000 00000000 00000000 00000000 read  ...
     266899 00002640  02800005 01000000 C216600C 82106040 read  ...
     266920 00002650  C236600C 40001CBD 90100011 1080062E read  ...
     266986 00000800  91D02000 01000000 01000000 01000000 read  ...
     267007 00000810  91D02000 01000000 01000000 01000000 read  ...
```

TCL returns:
```
{AHB 266718 0xFF900004 {0x00000084 0x00000084 0x00000084 0x00000084} R 0 2 2
0 0 0 0} {AHB 266727 0xFF900000 {0x0000000D 0x0000000D 0x0000000D 0x0000000D}
W 0 2 2 0 0 0 0} {AHB 266760 0x000085C0 {0xC2042054 0x80A06000 0x02800003
0x01000000} R 0 2 4 1 0 0 0} {AHB 266781 0x000085D0 ...
```

Print 2 rows

```
grmon3> ahb 2
     TIME     ADDRESS   D[127:96] D[95:64] D[63:32] D[31:0]  TYPE  ...
     266986 00000800  91D02000 01000000 01000000 01000000 read  ...
     267007 00000810  91D02000 01000000 01000000 01000000 read  ...
```

TCL returns:
```
{AHB 266986 0x00000800 {0x91D02000 0x01000000 0x01000000 0x01000000} R 0 2 4
1 0 0 0} {AHB 267007 0x00000810 {0x91D02000 0x01000000 0x01000000 0x01000000}
R 0 3 4 1 0 0 0}
```

SEE ALSO

Section 3.4.9, "Using the trace buffer"
tmode

3. amem - syntax

NAME

amem - Asynchronous bus read

SYNOPSIS

amem
amem *list*
amem *subcommand* ?*arg*?

DESCRIPTION

The **amem** command is used to schedule bus read transfers for later retrieval of the result. Each transfer is associated with a handle that has to be created before starting a transfer. Multiple concurrent transfers are supported by using separate handles per transfer.

amem
amem list

   List all amem handles and their states. An amem state is one of IDLE, RUN or DONE.

amem add *name*

   Create a new amem handle named named *name*. The name is used as an identifier for the handle when using other **amem** commands.

amem delete *name*

   Delete the amem handle named *name*.

amem eval *name address length*

   Schedule a bus read access for the handle *name* to read *length* bytes, starting at *address*. If a transfer is already in progress, then the command will fail with the error code set to EBUSY.

amem wait *name*

   Wait for an access to finish. The command returns when handle name is no longer in the RUN state.

amem result *name*

   Return the result of a previous read access if finished, or raise an error if not finished.

amem prio *name* ?*value*?

   Display or set debug link priority for a handle. 0 is the highest priority and 4 is the lowest.

amem state *name*

   Display and return the current state of a handle.

RETURN VALUE

amem list returns a list of amem handle entries. Each entry is a sublist of the format: {*name state*}.

amem result returns the read data.

amem prio returns the priority.

amem state returns one of the strings IDLE, RUN or DONE.

EXAMPLE

Create a handle named myhandle and schedule a read of 1 MiB from address 0 in the background.

```
grmon3> amem add myhandle
  Added amem handle: myhandle
```

```
grmon3> amem eval myhandle 0 0x100000

grmon3> set myresult [amem result myhandle]
```

List handles

```
grmon3> amem list

grmon3> amem list
  NAME       STATE  ADDRESS     LENGTH      PRIO  NREQ     BYTES  ERRORS
  myhandle   IDLE   -           -              4     1   1048576       0
  test0      DONE   0x00000004  0x00000064     4     1       100       0
```

SEE ALSO

mem
Section 3.4.7, "Displaying memory contents"

4. attach - syntax

attach - Stop execution and attach GRMON to processor again

SYNOPSIS

attach

DESCRIPTION

   attach

   This command will stop the execution on all CPUs that was started by the command **detach** and attach GRMON again.

RETURN VALUE

Command **attach** has no return value.

5. at - syntax

NAME

at - Print AHB transfer entries in the trace buffer

SYNOPSIS

at ?*length*?
at subcommand ?*args...*?

DESCRIPTION

at ?*length*? ?*devname*?

> Print the AHB trace buffer. The ?*length*? entries will be printed, default is 10.

at bp1 ?*options*? ?*address mask*? ?*devname*?
at bp2 ?*options*? ?*address mask*? ?*devname*?

> Sets trace buffer breakpoint to address and mask. Available options are -read or -write.

at bsel ?*bus*? ?*devname*?

> Selects bus to trace (not available in all implementations)

at delay ?*cnt*? ?*devname*?

> Delay the stops the trace buffer recording after match.

at disable ?*devname*?

> Stops the trace buffer recording

at enable ?*devname*?

> Arms the trace buffer and starts recording.

at filter reads ?*boolean*? ?*devname*?
at filter writes ?*boolean*? ?*devname*?
at filter addresses ?*boolean*? ?*address mask*? ?*devname*?

> Enable or disable filtering options if supported by the core. When enabling the addresses filter, the second AHB breakpoint register will be used to define the range of the filter. Default value of the boolean is true. If left out, then the address and mask will be ignored. They can also be set with the command **at filter range**.

at filter range ?*address mask*? ?*devname*?

> Set the base *address* and *mask* that the AHB trace buffer will include if the address filtering is enabled.

at filter mmask *mask* ?*devname*?
at filter smask *mask* ?*devname*?

> Set which AHB masters or slaves connected to the bus to exclude. (Only available in some DSU4 implementations)

at log ?*devname*?

> Print the whole AHB trace buffer.

at status ?*devname*?

> Print AHB trace buffer settings.

RETURN VALUE

Upon successful completion, **at** returns a list of trace buffer entries , on the same format as the command **ahb**. Each entry is a sublist on the format format: {AHB *time addr data rw trans size master lock resp irq bp*}. The data field is a sublist of 1,2 or 4 words with MSB first, depending on the size of AMBA bus. Detailed description about the different fields can be found in the DSU core documentation in document grip.pdf. [http://gaisler.com/products/grlib/grip.pdf]

The other sub commands have no return value.

EXAMPLE

Print 10 rows

```
grmon3> at
    TIME    ADDRESS  D[127:96] D[95:64] D[63:32] D[31:0]  TYPE  ...
    266718 FF900004  00000084 00000084 00000084 00000084 read  ...
    266727 FF900000  0000000D 0000000D 0000000D 0000000D write ...
    266760 000085C0  C2042054 80A06000 02800003 01000000 read  ...
    266781 000085D0  C2260000 81C7E008 91E80008 9DE3BF98 read  ...
    266812 0000B440  00000000 00000000 00000000 00000000 read  ...
    266833 0000B450  00000000 00000000 00000000 00000000 read  ...
    266899 00002640  02800005 01000000 C216600C 82106040 read  ...
    266920 00002650  C236600C 40001CBD 90100011 1080062E read  ...
    266986 00000800  91D02000 01000000 01000000 01000000 read  ...
    267007 00000810  91D02000 01000000 01000000 01000000 read  ...
```

TCL returns:
{AHB 266718 0xFF900004 {0x00000084 0x00000084 0x00000084 0x00000084} R 0 2 2 0
0 0 0 0} {AHB 266727 0xFF900000 {0x0000000D 0x0000000D 0x0000000D 0x0000000D}
W 0 2 2 0 0 0 0 0} {AHB 266760 0x000085C0 {0xC2042054 0x80A06000 0x02800003
0x01000000} R 0 2 4 1 0 0 0 0} {AHB 266781 0x000085D0 ...

Print 2 rows

```
grmon3> at 2
    TIME    ADDRESS  D[127:96] D[95:64] D[63:32] D[31:0]  TYPE  ...
    266986 00000800  91D02000 01000000 01000000 01000000 read  ...
    267007 00000810  91D02000 01000000 01000000 01000000 read  ...
```

TCL returns:
{AHB 266986 0x00000800 {0x91D02000 0x01000000 0x01000000 0x01000000} R 0 2 4 1
0 0 0 0} {at 267007 0x00000810 {0x91D02000 0x01000000 0x01000000 0x01000000}
R 0 3 4 1 0 0 0 0}

SEE ALSO

Section 3.4.9, "Using the trace buffer"
tmode

6. batch - syntax

NAME

batch - Execute a batch script

SYNOPSIS

batch ?*options*? *filename* ?*args...*?

DESCRIPTION

batch

Execute a TCL script. The **batch** is similar to the TCL command source, except that the batch command sets up the variables argv0, argv and argc in the global namespace. While executing the scrip, argv0 will contain the script filename, argv will contain a list of all the arguments that appear after the filename and argc will be the length of argv.

OPTIONS

-echo

Echo all commands/procedures that the TCL interpreter calls.

-prefix ?*string*?

Print a prefix on each row when echoing commands. Has no effect unless -echo is also set.

RETURN VALUE

Command **batch** has no return value.

7. bdump - syntax

NAME

bdump - Dump memory to a file.

SYNOPSIS

bdump `address length` ?`filename`?

DESCRIPTION

The bdump command may be used to store memory contents a binary file. It's an alias for 'dump -binary'.

   bdump `address length` ?`filename`?

   Dumps `length` bytes, starting at `address`, to a file in binary format. The default name of the file is "grmon-dump.bin"

RETURN VALUE

Command **bdump** has no return value.

EXAMPLE

Dump 32kB of data from address 0x40000000
```
grmon3> bdump 0x40000000 32768
```

8. bload - syntax

NAME

bload - Load a binary file

SYNOPSIS

bload ?`options...`? `filename` ?`address`? ?`cpu#`?

DESCRIPTION

The bload command may be used to upload a binary file to the system. It's an alias for 'load -binary'. When a file is loaded, GRMON will reset the memory controllers registers first.

bload ?`options...`? `filename` ?`address`? ?`cpu#`?

The load command may be used to upload the file specified by `filename`. If the `address` argument is present, then binary files will be stored at this address, if left out then they will be placed at the base address of the detected RAM. The `cpu#` argument can be used to specify which CPU it belongs to. The options is specified below.

OPTIONS

`-delay` ms

The `-delay` option can be used to specify a delay between each word written. If the delay is non-zero then the maximum block size is 4 bytes.

`-bsize` bytes

The `-bsize` option may be used to specify the size blocks of data in bytes that will be written. Sizes that are not even words may require a JTAG based debug link to work properly. See Chapter 5, *Debug link* for more information.

`-wprot`

If the `-wprot` option is given then write protection on the core will be disabled

RETURN VALUE

Command **bload** returns a guessed entry point.

EXAMPLE

Load and then verify a binary data file at a 16MBytes offset into the main memory starting at 0x40000000.

```
grmon3> bload release/ramfs.cpio.gz 0x41000000
grmon3> verify release/ramfs.cpio.gz 0x41000000
```

SEE ALSO

Section 3.4.2, "Uploading application and data to target memory"

9. bp - syntax

NAME

bp - Add, delete or list breakpoints

SYNOPSIS

bp ?*address*? ?*cpu#*?
bp *type* ?*options*? *address* ?*mask*? ?*cpu#*?
bp delete ?*index*?
bp enable ?*index*?
bp disable ?*index*?
bp map
bp map *vaddr paddr*
bp map clear

DESCRIPTION

The bp command may be used to list, add or delete all kinds of breakpoints. The *address* parameter that is specified when creating a breakpoint can either be an address or a symbol. The *mask* parameter can be used to break on a range of addresses. If omitted, the default value is 0xfffffffc (i.e. a single address).

Software breakpoints are inserted by replacing an instruction in the memory with a breakpoint instruction. I.e. any CPU in a multi-core system that encounters this breakpoint will break.

Hardware breakpoints/watchpoints will be set to a single CPU core.

When adding a breakpoint a cpu# may optionally be specified to associate the breakpoint with a CPU. The CPU index will be used to lookup symbols, MMU translations and for hardware breakpoints/watchpoints.

bp ?*address*? ?*cpu#*?

When omitting the address parameter this command will list breakpoints. If the address parameter is specified, it will create a software breakpoint.

bp soft *address* ?*cpu#*?

Create a software breakpoint.

bp hard *address* ?*mask*? ?*cpu#*?

Create a hardware breakpoint.

bp watch ?*options*? *address* ?*mask*? ?*cpu#*?

Create a hardware watchpoint. The options `-read`/`-write` can be used to make it watch only reads or writes, by default it will watch both reads and writes.

bp bus ?*options*? *address* ?*mask*? ?*cpu#*?

Create an AMBA-bus watchpoint. The options `-read`/`-write` can be used to make it watch only reads or writes, by default it will watch both reads and writes.

bp data ?*options*? *value* ?*mask*? ?*cpu#*?

Create an AMBA data watchpoint. The *value* and *mask* parameters may be up to 128 bits, but number of bits used depends on width of the bus on the system. Valid options are `-addr` and `-invert`. If `-addr` is specified, then also `-read` or `-write` are valid. See below for a description of the options.

bp delete ?*index..*?

When omitting the index all breakpoints will be deleted. If one or more indexes are specified, then those breakpoints will be deleted. Listing all breakpoints will show the indexes of the breakpoints.

bp enable ?*index..*?

When omitting the index all breakpoints will be enabled. If one or more indexes are specified, then those breakpoints will be enabled. Listing all breakpoints will show the indexes of the breakpoints.

bp disable ?*index..*?

> When omitting the index all breakpoints will be disabled. If one or more indexes are specified, then those breakpoints will be disabled. Listing all breakpoints will show the indexes of the breakpoints.

bp map

> List the memory mapping used for soft breakpoints when the MMU is not yet available.

bp map *vaddr paddr*

> Setup memory mapping from virtual to physical addresses to be used with soft breakpoints when the MMU is not yet available.

bp map clear

> Clears the memory mapping used for soft breakpoints when the MMU is not yet available.

OPTIONS

`-read`

> This option will enable a watchpoint to only watch loads at the specified address. The `-read` and `-write` are mutual exclusive.

`-write`

> This option will enable a watchpoint to only watch stores at the specified address. The `-read` and `-write` are mutual exclusive.

`-addr address mask`

> This option will combine an AMBA data watchpoint with a a bus watchpoint so it will only trigger if a value is read accessed from a certain address range.

`-invert`

> The AMBA data watchpoint will trigger of value is NOT set.

`--`

> End of options. This might be needed to set if value the first parameter after the options is negative.

RETURN VALUE

Command **bp** returns an breakpoint id when adding a new breakpoint.

When printing all breakpoints, a list will be returned containing one element per breakpoint. Each element has the format: {ID ADDR MASK TYPE ENABLED CPU SYMBOL {DATA INV DATAMASK}}. AMBA watchpoints and AMBA data watchpoints will only have associated CPUs if has a symbol. The last subelement is only valid for AMBA data watchpoints.

EXAMPLE

Create a software breakpoint at the symbol main:
```
grmon3> bp soft main
```

Create a AMBA bus watchpoint that watches loads in the address range of `0x40000000` to `0x400000FF`:
```
grmon3> bp bus -read 0x40000000 0xFFFFFF00
```

SEE ALSO

Section 3.4.4, "Inserting breakpoints and watchpoints"

10. bt - syntax

NAME

bt - Print backtrace

SYNOPSIS

bt ?*cpu#*?

DESCRIPTION

> **bt** ?*cpu#*?

> Print backtrace on current active CPU, optionally specify which CPU to show.

RETURN VALUE

Upon successful completion **bt** returns a list of tuples, where each tuple consist of a PC- and SP-register values.

EXAMPLE

Show backtrace on current active CPU
```
grmon3> bt
```

TCL returns:
```
{1073746404 1342177032} {1073746020 1342177136} {1073781172 1342177200}
```

Show backtrace on CPU 1
```
grmon3> bt cpu1
```

TCL returns:
```
{1073746404 1342177032} {1073746020 1342177136} {1073781172 1342177200}
```

SEE ALSO

Section 1.6, "NOEL-V Support"
Section 3.4.6, "Backtracing function calls"

11. cctrl - syntax

NAME

cctrl - Display or set cache control register

SYNOPSIS

cctrl ?*value*? ?*cpu#*?
cctrl flush ?*cpu#*?

DESCRIPTION

   cctrl ?*value*? ?*cpu#*?

      Display or set cache control register

   cctrl flush ?*cpu#*?

      Flushes both instruction and data cache

RETURN VALUE

Upon successful completion **cctrl** will return the value of the cache control register.

SEE ALSO

`-nic` and `-ndc` switches described in Section 6.3.1, "Switches"

SEE ALSO

Section 3.4.16, "CPU cache support"

12. cont - syntax

NAME

cont - Continue execution

SYNOPSIS

cont ?*options*? ?*count*?

DESCRIPTION

cont ?*options*? ?*count*?

Continue execution. If ?*count*? is set, then only execute the specified number of instructions (only supported by DSU4).

OPTIONS

`-noret`

Do not evaluate the return value. Then this options is set, no return value will be set.

RETURN VALUE

Upon successful completion **cont** returns a list of signals, one per CPU. Possible signal values are SIGBUS, SIGFPE, SIGILL, SIGINT, SIGSEGV, SIGTERM or SIGTRAP. If a CPU is disabled, then a empty string will be returned instead of a signal value.

EXAMPLE

Continue execution from current PC
```
grmon3> cont
```

SEE ALSO

Section 3.4.3, "Running applications"

13. cpu - syntax

cpu - Enable, disable CPU or select current active CPU

SYNOPSIS

cpu
cpu enable *cpuid*
cpu enable *cpuid*
cpu active *cpuid*

DESCRIPTION

Control processors in LEON3 multi-processor (MP) systems.

cpu

> Without parameters, the cpu command prints the processor status.

cpu enable *cpuid*
cpu disable *cpuid*

> Enable/disable the specified CPU.

cpu active *cpuid*

> Set current active CPU

RETURN VALUE

Upon successful completion **cpu** returns the active CPU and a list of booleans, one per CPU, describing if they are enabled or disabled.

The sub commands has no return value.

EXAMPLE

Set current active to CPU 1
```
grmon3> cpu active 1
```

Print processor status in a two-processor system when CPU 1 is active and disabled.
```
grmon3> cpu
```

TCL returns:
```
1 {1 0}
```

SEE ALSO

Section 3.4.13, "Multi-processor support"

14. dcache - syntax

NAME

dcache - Show, enable or disable data cache

SYNOPSIS

dcache ?*boolean*? ?*cpu#*?
dcache diag ?*windex*? ?*lindex*? ?*cpu#*?
dcache flush ?*cpu#*?
dcache way *windex* ?*lindex*? ?*cpu#*?
dcache tag *windex lindex* ?*value*? ?*tbmask*? ?*cpu#*?

DESCRIPTION

In all forms of the **dcache** command, the optional parameter ?*cpu#*? specifies which CPU to operate on. The active CPU will be used if parameter is omitted.

    dcache ?*boolean*? ?*cpu#*?

        If ?*boolean*? is not given then show the content of all ways. If ?*boolean*? is present, then enable or disable the data cache.

    dcache diag ?*windex*? ?*lindex*? ?*cpu#*?

        Check if the data cache is consistent with the memory. Optionally a specific way or line can be checked.

    dcache flush ?*cpu#*?

        Flushes the data cache

    dcache way *windex* ?*lindex*? ?*cpu#*?

        Show the contents of specified way *windex* or optionally a specific line ?*lindex*?.

    dcache tag *windex lindex* ?*value*? ?*tbmask*? ?*cpu#*?

        Read or write a raw data cache tag value. Way and line is selected with *windex* and *lindex*. The parameter *value*, if given, is written to the tag. The optional parameter *tbmask* is xor-ed with the test check bits generated by the cache controller during the write.

RETURN VALUE

Command **dcache diag** returns a list of all inconsistent entries. Each element of the list contains CPU id, way id, line id, word id, physical address, cached data and the data from the memory.

Command **dcache tag** returns the tag value on read.

The other **dcache** commands have no return value.

SEE ALSO

Section 3.4.16, "CPU cache support"
icache

15. dccfg - syntax

NAME

dccfg - Display or set data cache configuration register

SYNOPSIS

dccfg ?*value*? ?*cpu#*?

DESCRIPTION

dccfg ?*value*? ?*cpu#*?

Display or set data cache configuration register for the active CPU. GRMON will not keep track of this register value and will not reinitialize the register when starting or resuming software execution.

RETURN VALUE

Upon successful completion **dccfg** will return the value of the data cache configuration register.

SEE ALSO

-nic and -ndc switches described in Section 6.3.1, "Switches"

SEE ALSO

Section 3.4.16, "CPU cache support"

16. dcom - syntax

NAME

dcom - Print or clear debug link statistics

SYNOPSIS

dcom
dcom clear

DESCRIPTION

   dcom
   dcom clear

      Print debug link statistics.

      Clear debug link statistics.

RETURN VALUE

Upon successful completion **dcom** has no return value.

17. ddr2cfg1 - syntax

ddr2cfg1 - Show or set the reset value of the memory register

SYNOPSIS

ddr2cfg1 ?*value*?

DESCRIPTION

ddr2cfg1 ?*value*?

Set the reset value of the memory register. If value is left out, then the reset value will be printed.

RETURN VALUE

Upon successful completion **ddrcfg1** returns a the value of the register.

SEE ALSO

Section 6.14, "Memory controllers "

18. ddr2cfg2 - syntax

ddr2cfg2 - Show or set the reset value of the memory register

SYNOPSIS

ddr2cfg2 ?*value*?

DESCRIPTION

   ddr2cfg2 ?*value*?

       Set the reset value of the memory register. If value is left out, then the reset value will be printed.

RETURN VALUE

Upon successful completion **ddrcfg2** returns a the value of the register.

SEE ALSO

Section 6.14, "Memory controllers "

19. ddr2cfg3 - syntax

ddr2cfg3 - Show or set the reset value of the memory register

SYNOPSIS

ddr2cfg3 ?*value*?

DESCRIPTION

ddr2cfg3 ?*value*?

Set the reset value of the memory register. If value is left out, then the reset value will be printed.

RETURN VALUE

Upon successful completion **ddrcfg3** returns a the value of the register.

SEE ALSO

Section 6.14, "Memory controllers "

20. ddr2cfg4 - syntax

ddr2cfg4 - Show or set the reset value of the memory register

SYNOPSIS

ddr2cfg4 ?*value*?

DESCRIPTION

ddr2cfg4 ?*value*?

Set the reset value of the memory register. If value is left out, then the reset value will be printed.

RETURN VALUE

Upon successful completion **ddrcfg4** returns a the value of the register.

SEE ALSO

Section 6.14, "Memory controllers "

21. ddr2cfg5 - syntax

ddr2cfg5 - Show or set the reset value of the memory register

SYNOPSIS

ddr2cfg5 ?*value*?

DESCRIPTION

   ddr2cfg5 ?*value*?

      Set the reset value of the memory register. If value is left out, then the reset value will be printed.

RETURN VALUE

Upon successful completion **ddrcfg5** returns a the value of the register.

SEE ALSO

Section 6.14, "Memory controllers "

22. ddr2delay - syntax

ddr2delay - Change read data input delay

SYNOPSIS

ddr2delay ?subcommand? ?args...?

DESCRIPTION

ddr2delay inc ?*steps*?
ddr2delay dec ?*steps*?
ddr2delay ?*value*?

> Use **inc** to increment the delay with one tap-delay for all data bytes. Use **dec** to decrement all delays. A *value* can be specified to calibrate each data byte separately. The *value* is written to the 16 LSB of the DDR2 control register 3.

ddr2delay reset

> Set the delay to the default value.

ddr2delay scan

> The scan subcommand will run a calibration routine that searches over all tap delays and read delay values to find working settings. Supports only Xilinx Virtex currently

> The scan may overwrite beginning of memory.

RETURN VALUE

Command **ddr2delay** has no return value.

SEE ALSO

Section 6.14, "Memory controllers "

23. ddr2skew - syntax

ddr2skew - Change read skew.

SYNOPSIS

ddr2skew ?subcommand? ?args...?

DESCRIPTION

ddr2skew inc ?*steps*?
ddr2skew dec ?*steps*?

Increment/decrement the delay with one step. Commands **inc** and **dec** can optionally be given the number of steps to increment/decrement as an argument.

ddr2skew reset

Set the skew to the default value.

RETURN VALUE

Command **ddr2skew** has no return value.

SEE ALSO

Section 6.14, "Memory controllers "

24. detach - syntax

detach - Resume execution with GRMON detached from processor

SYNOPSIS

detach

DESCRIPTION

  detach

     This command will detach GRMON and resume execution on enabled CPUs.

RETURN VALUE

Command **detach** has no return value.

25. disassemble - syntax

disassemble - Disassemble memory

SYNOPSIS

disassemble *?address? ?length? ?cpu#?*
disassemble -r *start stop ?cpu#?*

DESCRIPTION

disassemble *?address? ?length? ?cpu#?*

Disassemble memory. If length is left out it defaults to 16 and the address defaults to current PC value. Symbols may be used as address.

disassemble -r *start stop ?cpu#?*

Disassemble a range of instructions between address start and stop, including start and excluding stop.

RETURN VALUE

Command **disassemble** has no return value.

SEE ALSO

Section 3.4.7, "Displaying memory contents"

26. dtb - syntax

NAME

dtb - Setup a DTB to be uploaded or print filenames of DTB files.

SYNOPSIS

dtb ?`options...`? `filename` ?`address`? ?`cpu#...`?
dtb `subcommand` ?`arg`?

DESCRIPTION

The dtb command may be used to setup a DTB file that will be upload to the system when GRMON resets the system. It can also be used to list all DTBs that will be loaded.

   dtb ?`options...`? `filename` ?`address`? ?`cpu#...`?

     The dtb command may be used to setup a DRTB file, specified by `filename`, that will be uploaded when GRMON resets the system. If the `address` argument is present, then DTBs will be stored at this address, if left out then they will be placed at the top of the stack. GRMON will also write the addresss of the DTB to input registers of the CPU:s so the application can find it. On RISC-V architectures the address will stored in register a1. One or more `cpu#` arguments can be used to specify which CPUs it belongs to or all CPUs if omitted

   dtb clear ?`cpu#...`?

     This command will clear the information about the DTBs that will be loaded to the CPU:s. If one or more `cpu#` arguments is specified, then only those CPUs will be listed.

   dtb load ?`cpu#...`?

     This command will load the DTBs and write the address to CPU:s register. It can be used to manually initialize the system. If one or more `cpu#` arguments are specified, then only those CPUs will be initialized.

   dtb show ?`cpu#...`?

     This command will list which DTBs that will be loaded to the CPU:s. If one or more `cpu#` arguments are specified, then only those CPUs will be listed.

OPTIONS

   `-bsize` bytes

     The `-bsize` option may be used to specify the size blocks of data in bytes that will be written. Sizes that are not even words may require a JTAG based debug link to work properly. See Chapter 5, *Debug link* more information.

   `-delay` ms

     The `-delay` option can be used to specify a delay between each word written. If the delay is non-zero then the default block size will be 4 bytes, but can be changed using the `-bsize` option.

   `-wprot`

     If the `-wprot` option is given then write protection on the core will be disabled

   `-rom`

     If the DTB is already present in the memory and only the input registers needs to be setup. The `filename` argument must be omitted and `address` is required.

RETURN VALUE

Command **dtb show** returns the a list. Each entry is a sublist on the format format:{`filename address` {cpu-ids}}}. The filename will be be the keyword ROM if `-rom` was used. The address will be the keyword "Stack" if it located on the stack.

27. dump - syntax

NAME

dump - Dump memory to a file.

SYNOPSIS

dump ?*options...*? *address length* ?*filename*?

DESCRIPTION

   dump ?*options...*? *address length* ?*filename*?

Dumps *length* bytes, starting at *address*, to a file in Motorola SREC format. The default name of the file is "grmon-dump.srec"

OPTIONS

   -binary

The -binary option can be used to store data to a binary file

   -bsize

The -bsize option may be used to specify the size blocks of data in bytes that will be read. Sizes that are not even words may require a JTAG based debug link to work properly. See Chapter 5, *Debug link* more information.

   -append

Set the -append option to append the dumped data to the end of the file. The default is to truncate the file to zero length before storing the data into the file.

RETURN VALUE

Command **dump** has no return value.

EXAMPLE

Dump 32kB of data from address 0x40000000
```
grmon3> dump 0x40000000 32768
```

28. dwarf - syntax

NAME

dwarf - print or lookup DWARF debug information

SYNOPSIS

dwarf *subcommand* ?*arg*?

DESCRIPTION

The dwarf command can be used to retrieve line information of a file.

    dwarf addr2line addr ?*cpu#*?

        This command will lookup the filename and line number for a given address.

    dwarf clear ?*cpu#*?

        Remove all dwarf debug information to the active CPU or a specific CPU.

RETURN VALUE

Upon successful completion **dwarf addr2line** will return a list where the first element is the filename and the second element is the line number.

EXAMPLE

Retrieve the line information for address `0xf0014000`.
```
grmon3> dwarf addr2line 0xf0014000
```

SEE ALSO

load

29. edcl - syntax

NAME

edcl - Print or set the EDCL ip

SYNOPSIS

edcl ?*ip*? ?*greth#*?

DESCRIPTION

> **edcl** ?*ip*? ?*greth#*?
>
>> If an ip-address is supplied then it will be set, otherwise the command will print the current EDCL ip. The EDCL will be disabled if the ip-address is set to zero and enabled if set to a normal address. If more than one device exists in the system, the *dev#* can be used to select device, default is dev0.

RETURN VALUE

Command **edcl** has no return value.

EXAMPLE

Set ip-address 192.168.0.123
```
grmon3> edcl 192.168.0.123
```

SEE ALSO

Section 6.4, "Ethernet controller"

30. eeload - syntax

NAME

eeload - Load a file into an EEPROM

SYNOPSIS

eeload ?`options...`? `filename` ?`cpu#`?

DESCRIPTION

The eeload command may be used to upload a file to a EEPROM. It's an alias for 'load -delay 1 -bsize 4 -wprot'. When a file is loaded, GRMON will reset the memory controllers registers first.

eeload ?`options...`? `filename` ?`address`? ?`cpu#`?

The load command may be used to upload the file specified by `filename`. It will also try to disable write protection on the memory core. If the `address` argument is present, then binary files will be stored at this address, if left out then they will be placed at the base address of the detected RAM. The `cpu#` argument can be used to specify which CPU it belongs to. The options is specified below.

OPTIONS

`-binary`

The `-binary` option can be used to force GRMON to interpret the file as a binary file.

`-bsize` bytes

The `-bsize` option may be used to specify the size blocks of data in bytes that will be written. Valid value are 1, 2 or 4. Sizes 1 and 2 may require a JTAG based debug link to work properly See Chapter 5, *Debug link* more information.

`-debug`

If the `-debug` option is given the DWARF debug information is read in.

RETURN VALUE

Command **eeload** returns the entry point.

EXAMPLE

Load and then verify a hello_world application

```
grmon3> eeload ../hello_world/hello_world
grmon3> verify ../hello_world/hello_world
```

SEE ALSO

Section 3.4.2, "Uploading application and data to target memory"

NAME

ehci - Control the USB host's ECHI core

SYNOPSIS

ehci subcommand ?*args...*?

DESCRIPTION

ehci endian ?*devname*?

Displays the endian conversion setting

ehci capregs ?*devname*?

Displays contents of the capability registers

ehci opregs ?*devname*?

Displays contents of the operational registers

ehci reset ?*devname*?

Performs a Host Controller Reset

RETURN VALUE

Upon successful completion, **ehci** have no return value.

SEE ALSO

Section 6.6, "USB Host Controller"

32. ei - syntax

NAME

ei - Inject errors in CPU cache and register files

SYNOPSIS

ei *subcommand* ?*args...*?

DESCRIPTION

Errors will be injected according to the CPU configuration. Injection of errors in ITAG, IDATA, DTAG, DDATA, STAG, IU register file and FP register file is supported.

ei un ?*nr t*?

> Enable error injection, uniform error distribution mode. *nr* errors are inserted during the time period of *t* minutes. Errors are uniformly distributed over the time period.

ei av ?*r*?

> Enable error injection, average error rate mode. Errors will be inserted during the whole program execution. Average error rate is *r* errors per second.

ei disable

> Disable error injection.

ei log ?*filename*?
ei log *disable*

> Enable/disable error injection log. The error injection log is saved in file log_file.

ei stat
ei stat ?*enable*?
ei stat ?*disable*?

> Show, enable or disable error injection statistics. When enabled, the SEU correction counters are modified. This option should not be used with software which itself monitors SEU error counters.

ei prob
ei prob itag dtag idata ddata stag iurf fprf ?*cpu#*?

> Show or set probability of each error injection target. Each injection target has an associated probability value from 0.0 to 1.0. The value 0.0 means that no errors will be injected in the target. A value higher than 0.0 means that the error will be injected with the specified probability.

> When no parameter is given to **ei prob**, then the currently configured values are listed. The second form configures the probabilities from user supplied decimal numbers. Target CPU is selected with the *cpu#* parameter. If no CPU parameter is given, then the current CPU is used.

RETURN VALUE

Command **ei** has no return value.

EXAMPLE

Configure **ei** to inject errors only in the data cache tags and instruction cache tags (DTAG and ITAG) of cpu0:

```
grmon3> ei prob 1.0 1.0 0.0 0.0 0.0 0.0 0.0 cpu0

grmon3> ei prob 0.0 0.0 0.0 0.0 0.0 0.0 0.0 cpu1
```

List the currently configured target probabilities:
```
grmon3> ei prob
```

SEE ALSO

Section 3.10.2, "LEON3-FT error injection"
icache
dcache

33. ep - syntax

NAME

ep - Set entry point

SYNOPSIS

ep ?*cpu#*?
ep ?*--*? *value* ?*cpu#*?
ep disable ?*cpu#*?

DESCRIPTION

ep ?*cpu#*?

Show current active CPUs entry point, or the CPU specified by cpu#.

ep ?*--*? *value* ?*cpu#*?

Set the current active CPUs entry point, or the CPU specified by cpu#. The only option available is '--' and it marks the end of options. It should be used if a symbol name is in conflict with a subcommand (i.e. a symbol called "disable").

ep disable ?*cpu#*?

Remove the entry point from the current active CPU or the the CPU specified by cpu#.

RETURN VALUE

Upon successful completion **ep** returns a list of entry points, one for each CPU. If cpu# is specified, then only the entry point for that CPU will be returned.

EXAMPLE

Set current active CPUs entry point to 0x40000000
```
grmon3> ep 0x40000000
```

SEE ALSO

Section 3.4.13, "Multi-processor support"

34. grmon::execsh - syntax

NAME

grmon::execsh - Run commands in the execution shell

SYNOPSIS

grmon::execsh
grmon::execsh *subcommand* ?*arg*?

DESCRIPTION

The grmon::execsh command is used to execute scripts in the execution shell. This command should be used to manage execution hooks.

   grmon::execsh eval ?*options*? *arg* ?*arg ...*?

   Evaluate command *arg* in the execution shell. If a script is running, then the command will fail with the error result set to EBUSY.

   grmon::execsh interrupt *name*

   Send an interrupt to the excution shell.

OPTIONS

   -u

   The -u option may be added to use the I/O forwarding settings of the calling shell.

RETURN VALUE

grmon::execsh eval will return the result from the script.

EXAMPLE

Install an execution hook

```
grmon::execsh eval {
  proc myhook1 {} {puts "Hello World"}
  lappend ::hooks::preexec ::myhook1
}
```

SEE ALSO

Section 3.5, "Tcl integration"
Appendix C, *Tcl API*

35. exit - syntax

NAME

exit - Exit the GRMON application

SYNOPSIS

exit ?*code*?

DESCRIPTION

   exit ?*code*?

      Exit the GRMON application. GRMON will return 0 or the code specified.

RETURN VALUE

Command **exit** has no return value.

EXAMPLE

Exit the GRMON application with return code 1.
```
grmon3> exit 1
```

36. flash - syntax

NAME

flash - Write, erase or show information about the flash

SYNOPSIS

flash
flash blank all
flash blank *start* ?*stop*?
flash burst ?*boolean*?
flash erase all
flash erase *start* ?*stop*?
flash load ?*options...*? *filename* ?*address*? ?*cpu#*?
flash verify ?*options...*? *filename* ?*address*?
flash lock all
flash lock *start* ?*stop*?
flash lockdown all
flash lockdown *start* ?*stop*?
flash query
flash scan ?*addr*?
flash status
flash unlock all
flash unlock *start* ?*stop*?
flash wbuf *length*
flash write *address* *data*

DESCRIPTION

GRMON supports programming of CFI compatible flash PROM attached to the external memory bus of LEON2 and LEON3 systems. Flash programming is only supported if the target system contains one of the following memory controllers MCTRL, FTMCTRL, FTSRCTRL or SSRCTRL. The PROM bus width can be 8-, 16- or 32-bit. It is imperative that the prom width in the MCFG1 register correctly reflects the width of the external prom. To program 8-bit and 16-bit PROMs, the target system must also have at least one working SRAM or SDRAM bank.

When one of the flash commands are issued GRMON will probe for a CFI compatible memory at the beginning of the PROM area. GRMON will only control one flash memory at the time. If there are multiple CFI compatible flash memories connected to the PROM area, then it is possible to switch device using the command **flash scan** *addr*. If the PROM width or bank size is changed in the memory controller registers are changed, then GRMON will discard any probed CFI information, and a new **flash scan** command have to be issued.

There are many different suppliers of CFI devices, and some implements their own command set. The command set is specified by the CFI query register 14 (MSB) and 13 (LSB). The value for these register can in most cases be found in the datasheet of the CFI device. GRMON supports the command sets that are listed in Table 3.4, "Supported CFI command set" in section Section 3.11.1, "CFI compatible Flash PROM".

The sub commands erase, lock, lockdown and unlock works on memory blocks (the subcommand blank have the same parameters, but operates on addresses). These commands operate on the block that the *start* address belong. If the *stop* parameter is also given the commands will operate on all the blocks between and including the blocks that the *start* and *stop* belongs to. I.a the keyword 'all' can be given instead of the start address, then the command will operate on the whole memory.

  flash

      Print the flash memory configuration.
  flash blank all
  flash blank *start* ?*stop*?

      Check that the flash memory is blank, i.e. can be re-programmed. See description above about the parameters.

flash burst ?`boolean`?

> Enable or disable flash burst write. Disabling the burst will decrease performance and requires either that a CPU is available in the system or that a JTAG debug link is used. This feature is only has effect when a 8-bit or 16-bit Intel style flash memory that is connected to a memory controller that supports bursting.

flash erase all
flash erase `start` ?`stop`?

> Erase a flash block. See description above about the parameters.

flash load ?`options...`? `filename` ?`address`? ?`cpu#`?

> Program the flash memory with the contents file. The load command may be used to upload the file specified by `filename`. If the `address` argument is present, then binary files will be stored at this address, if left out then they will be placed at the base address of the detected ROM. The `cpu#` argument can be used to specify which CPU it belongs to.
>
> The `-binary` option can be used to force GRMON to interpret the file as a binary file.
>
> The `-erase` option to automatically erase the flash before writing. It will only erase the blocks where data will be written.
>
> The `-nolock` option can be used to prevent GRMON from checking the protection bits to see if the block is locked before trying to load data to the block.

flash verify ?`options...`? `filename` ?`address`?

> Verify that the file `filename` has been uploaded correctly, if EDAC is enabled then the checkbits will be verified aswell. If the `address` argument is present, then binary files will be compared against data at this address, if left out then they will be compared to data at the base address of the detected RAM.
>
> The `-binary` option can be used to force GRMON to interpret the file as a binary file.
>
> The `-max` option can be used to force GRMON to stop verifying when num errors have been found.

flash lock all
flash lock `start` ?`stop`?

> Lock a flash block. See description above about the parameters.

flash lockdown all
flash lockdown `start` ?`stop`?

> Lockdown a flash block. Work only on Intel-style devices which supports lock-down. See description above about the parameters.

flash query

> Print the flash query registers

flash scan ?`addr`?

> Probe the address for a CFI flash. If the addr parameter is set, then GRMON will probe for a new memory at the address. If the addr parameter is unset, GRMON will probe for a new memory at the beginning of the PROM area. If the addr parameter is unset, and a memory has already been probed, then GRMON will only return the address of the last probed memory.

flash status

> Print the flash lock status register

flash unlock all
flash unlock `start` ?`stop`?

> Unlock a flash block. See description above about the parameters.

flash wbuf `length`

> Limit the CFI auto-detected write buffer length. Zero disables the write buffer command and will perform single-word access only. -1 will reset to auto-detected value.

flash write *address data*

 Write a 32-bit data word to the flash at address addr.

RETURN VALUE

Command **flash scan** returns the base address of the CFI compatible memory.

The other **flash** commands has no return value.

EXAMPLE

A typical command sequence to erase and re-program a flash memory could be:

```
grmon3> flash unlock all
grmon3> flash erase all
grmon3> flash load file.prom
grmon3> flash lock all
```

SEE ALSO

Section 3.11.1, "CFI compatible Flash PROM"

37. float - syntax

NAME

float - Display FPU registers

SYNOPSIS

float

DESCRIPTION

float

Display FPU registers

RETURN VALUE

Upon successful completion **float** returns 2 lists. The first list contains the values when the registers represents floats, and the second list contain the double-values.

SEE ALSO

Section 3.4.5, "Displaying processor registers"

38. forward - syntax

NAME

forward - Control I/O forwarding

SYNOPSIS

forward
forward list
forward enable *devname* ?*channel*?
forward disable *devname*
forward mode *devname value*
forward start

DESCRIPTION

forward
forward list

List all enabled devices is the current shell.

forward enable *devname* ?*channel*?

Enable I/O forwarding for a device. If a custom channel is not specified, then the default channel for the shell will be enabled. The I/O forwarding configuration is stored per shell.

forward disable *devname*

Disable I/O forwarding for a device.

forward mode *devname value*

Set forwarding mode. Valid values are "loopback", "debug" or "none".

forward start

Start forwarding I/O in the current shell. When executing an application using GDB, this can be used to redirect I/O to the command line shell instead of to GDB. Issue an interrupt (Ctrl-C) to return to the %product; prompt.

RETURN VALUE

Upon successful completion **forward** has no return value.

EXAMPLE

Enable I/O forwarding
```
grmon3> forward enable uart0
```

Enable I/O forwarding to a file
```
grmon3> forward enable uart0 [open "grmon3.out" w]
```

39. gdb - syntax

NAME

gdb - Control the built in GDB remote server

SYNOPSIS

gdb ?*port*?
gdb stop
gdb status

DESCRIPTION

gdb ?*port*?

> Start the built in GDB remote server, optionally listen to the specified port. Default port is 2222.

gdb stop

> Stop the built in GDB remote server.

gdb status

> Print status

RETURN VALUE

Only the command '**gdb status**' has a return value. Upon successful completion **gdb status** returns a tuple, where the first value represents the status (0 stopped, 1 connected, 2 waiting for connection) and the second value is the port number.

SEE ALSO

Section 3.7, "GDB interface"
Section 3.2, "Starting GRMON"

40. go - syntax

go - Start execution without any initialization

SYNOPSIS

go ?*options*? ?*address*? ?*count*?

DESCRIPTION

go ?*options*? ?*address*? ?*count*?

This command will start the executing instruction on the active CPU, without resetting any drivers. When omitting the address parameter this command will start execution at the entry point from the last loaded application. If the *count* parameter is set then the CPU will run the specified number of instructions. Note that the *count* parameter is only supported by the DSU4.

OPTIONS

```
-noret
```

Do not evaluate the return value. Then this options is set, no return value will be set.

RETURN VALUE

Upon successful completion **go** returns a list of signals, one per CPU. Possible signal values are SIGBUS, SIGFPE, SIGILL, SIGINT, SIGSEGV, SIGTERM or SIGTRAP. If a CPU is disabled, then a empty string will be returned instead of a signal value.

EXAMPLE

Execute instructions starting at 0x40000000.
```
grmon3> go 0x40000000
```

SEE ALSO

Section 3.4.3, "Running applications"

41. gr1553b - syntax

gr1553b - MIL-STD-1553B Interface commands

SYNOPSIS

gr1553b ?subcommand? ?args...?

DESCRIPTION

The **gr1553b** command is an alias for the **mil>** command. See help of command **mil>** for more information.

42. grcg - syntax

NAME

grcg - Control clock gating

SYNOPSIS

grcg *subcommand* ?*args*? ?*grcg#*?

DESCRIPTION

This command provides functions to control the GRCLKGATE core. If more than one core exists in the system, then the name of the core to control should be specified as the last command option (after the subcommand). The 'info sys' command lists the controller names.

    grcg clkinfo ?*grcg#*?

      Show register values.

    grcg enable *number* ?*grcg#*?
    grcg disable *number* ?*grcg#*?

      Enable or disable a clock gate. Argument *number* may be replaced by the keyword all.

RETURN VALUE

Upon successful completion **grcg clkinfo** returns three masks, where each bit of the masks represents a clock gate. The first mask shows unlock-bits, the second enabled-bits and the third reset-bits.

The other sub commands has no return value.

EXAMPLE

Enable all clock gates
```
grmon3> grcg enable all
```

Clock enable function 7 on the GRCLKGATE core with index 1.
```
grmon3> grcg enable 7 grcg1
```

43. grpwm - syntax

NAME

grpwm - Control GRPWM core

SYNOPSIS

grpwm subcommand ?*args...*?

DESCRIPTION

grpwm info ?*devname*?

Displays information about the GRPWM core

grpwm wave ?*devname*?

Displays the waveform table

RETURN VALUE

Command **grpwm wave** returns a list of wave data.

The other **grpwm** commands have no return value.

44. grtmtx - syntax

grtmtx - Control GRTM devices

SYNOPSIS

grtmtx ?subcommand? ?args...?

DESCRIPTION

grtmtx

Display status

grtmtx reset

Reset DMA and TM encoder

grtmtx release

Release TM encoder

grtmtx rate *rate*

Set rate register

grtmtx len *nbytes*

Set frame length (actual number of bytes)

grtmtx limit *nbytes*

Set limit length (actual number of bytes)

grtmtx on
grtmtx off

Enable/disable the TM encoder

grtmtx reg

List register contents

grtmtx conf

List design options

RETURN VALUE

Command **grtmtx** has no return value.

45. gui - syntax

NAME

gui - Control the graphical user interface

SYNOPSIS

gui
gui status

DESCRIPTION

gui

> When GRMON has been started in CLI mode this command can be used to start the graphical user interface. This command has not effect if the GUI has already been started.

gui status

> Print status for the GUI connection.

RETURN VALUE

Only the command '**gui status**' has a return value. Upon successful completion **gui status** returns a tuple, where the first value represents the status (0 stopped, 1 started) and the second value is a reserved number.

SEE ALSO

Chapter 4, *Graphical user interface*
Section 4.2, "Starting GRMON GUI"

46. help - syntax

NAME

help - Print all GRMON commands or detailed help for a specific command

SYNOPSIS

help ?*command*?

DESCRIPTION

help ?*command*?

When omitting the command parameter this command will list commands. If the command parameter is specified, it will print a long detailed description of the command.

RETURN VALUE

Command **help** has no return value.

EXAMPLE

List all commands:
```
grmon3> help
```

Show detailed help of command 'mem':
```
grmon3> help mem
```

47. hist - syntax

NAME

hist - Print AHB transfers or instruction entries in the trace buffer

SYNOPSIS

hist ?*length*? ?*cpu#*?

DESCRIPTION

  hist ?*length*?

      Print the hist trace buffer. The ?*length*? entries will be printed, default is 10. Use cpu# to select CPU.

RETURN VALUE

Upon successful completion, **hist** returns a list of mixed AHB and instruction trace buffer entries, sorted after time. The first value in each entry is either the literal string `AHB` or `INST` indicating the type of entry. For more information about the entry values, see return values described for commands **ahb** and **inst**.

EXAMPLE

Print 10 rows

```
grmon3> hist
      TIME     ADDRESS    INSTRUCTIONS/AHB SIGNALS      RESULT/DATA
      266951   000021D4   restore  %o0, %o0            [0000000D]
      266954   000019E4   mov  0, %g1                  [00000000]
      266955   000019E8   mov  %g1, %i0                [00000000]
      266956   000019EC   ret                          [000019EC]
      266957   000019F0   restore                      [00000000]
      266960   0000106C   call  0x00009904             [0000106C]
      266961   00001070   nop                          [00000000]
      266962   00009904   mov  1, %g1                  [00000001]
      266963   00009908   ta  0x0                      [  TRAP  ]
      266986   00000800   AHB read   mst=0  size=4     [91D02000  01000000  01000000  0100]
```

TCL returns:
```
{INST 266951 0x000021D4 0x91E80008 0x0000000D 0 0 0} {INST 266954 0x000019E4
0x82102000 0x00000000 0 0 0} {INST 266955 0x000019E8 0xB0100001 0x00000000
0 0 0} {INST 266956 0x000019EC ...
```

Print 2 rows

```
grmon3> hist 2
      TIME     ADDRESS    INSTRUCTIONS/AHB SIGNALS      RESULT/DATA
      266963   00009908   ta  0x0                      [  TRAP  ]
      266986   00000800   AHB read   mst=0  size=4     [91D02000  01000000  01000000  0100]
```

TCL returns:
```
{INST 266963 0x00009908 0x91D02000 0x00000000 0 1 0} {AHB 266986 0x00000800
{0x91D02000 0x01000000 0x01000000 0x01000000} R 0 2 4 1 0 0 0}
```

SEE ALSO

Section 3.4.9, "Using the trace buffer"

48. i2c - syntax

NAME

i2c - Commands for the I2C masters

SYNOPSIS

i2c *subcommand* ?*args...*?
i2c *index subcommand* ?*args...*?

DESCRIPTION

This command provides functions to control the SPICTRL core. If more than one core exists in the system, then the index of the core to control should be specified after the **i2c** command (before the subcommand). The `info sys` command lists the device indexes.

i2c bitrate *rate*

    Initializes the prescaler register. Valid keywords for the parameter *rate* are `normal`, `fast` or `hispeed`.

i2c disable
i2c enable

    Enable/Disable the core

i2c read ?*options*? *i2caddr* ?*addr*? ?*cnt*?

    Performs *cnt* sequential reads starting at memory location *addr* from slave with *i2caddr*. Default value of *cnt* is 1. If only *i2caddr* is specified, then a simple read will be performed.

    Available options are `-d8`, `-d16` and `-d32` to control how many bits there are in each data word that is read. Defualt is 8 bits.

i2c scan

    Scans the bus for devices.

i2c status

    Displays some status information about the core and the bus.

i2c write ?*options*? *i2caddr* ?*addr*? *data*

    Writes *data* to memory location *addr* on slave with address *i2caddr*. If only *i2caddr* and *data* is specified, then a simple write will be performed.

    Available options are `-d8`, `-d16` and `-d32` to control how many bits there are in each data word that is written. Defualt is 8 bits.

Commands to interact with DVI transmitters:

i2c dvi devices

    List supported devices.

i2c dvi delay *direction*

    Change delay applied to clock before latching data. Valid keywords for *direction* are `inc` or `dec`.

i2c dvi init_l4itx_dvi ?*idf*?
i2c dvi init_l4itx_vga ?*idf*?

    Initializes Chrontel CH7301C DVI transmitter with values that are appropriate for the GR-LEON4-ITX board with DVI/VGA output. The optional *idf* value selects the multiplexed data input format, default is IDF 2.

i2c dvi init_ml50x_dvi *?idf?*
i2c dvi init_ml50x_vga *?idf?*

    Initializes Chrontel CH7301C DVI transmitter with values that are appropriate for a ML50x board with a" standard LEON/GRLIB template design for DVI/VGA output. The optional *idf* value selects the multi-plexed data input format, default is IDF 2.

i2c dvi setdev *devnr*

    Set DVI transmitter type. See command **i2c dvi devices** to list valid values of the parameter *devnr*.

i2c dvi showreg

    Show DVI transmitter registers

RETURN VALUE

Upon successful completion **i2c read** returns a list of values read. The **i2c dvi showreg** return a list of tuples, where the first element is the register address and the second element is the value.

The other sub commands has no return value.

49. icache - syntax

NAME

icache - Show, enable or disable instruction cache

SYNOPSIS

icache ?*boolean*? ?*cpu#*?
icache diag ?*windex*? ?*lindex*? ?*cpu#*?
icache flush ?*cpu#*?
icache way *windex* ?*lindex*? ?*cpu#*?
icache tag *windex lindex* ?*value*? ?*tbmask*? ?*cpu#*?

DESCRIPTION

In all forms of the **icache** command, the optional parameter ?*cpu#*? specifies which CPU to operate on. The active CPU will be used if parameter is omitted.

   icache ?*boolean*? ?*cpu#*?

      If ?*boolean*? is not given then show the content of all ways. If ?*boolean*? is present, then enable or disable the instruction cache.

   icache diag ?*windex*? ?*lindex*? ?*cpu#*?

      Check if the instruction cache is consistent with the memory. Optionally a specific way or line can be checked.

   icache flush ?*cpu#*?

      Flushes the instruction cache

   icache way *windex* ?*lindex*? ?*cpu#*?

      Show the contents of specified way *windex* or optionally a specific line ?*lindex*?.

   icache tag *windex lindex* ?*value*? ?*tbmask*? ?*cpu#*?

      Read or write a raw instruction cache tag value. Way and line is selected with *windex* and *lindex*. The parameter *value*, if given, is written to the tag. The optional parameter *tbmask* is xor-ed with the test check bits generated by the cache controller during the write.

RETURN VALUE

Command **icache diag** returns a list of all inconsistent entries. Each element of the list contains CPU id, way id, line id, word id, physical address, cached data and the data from the memory.

Command **icache tag** returns the tag value on read.

The other **icache** commands have no return value.

SEE ALSO

Section 3.4.16, "CPU cache support"
dcache

50. iccfg - syntax

NAME

iccfg - Display or set instruction cache configuration register

SYNOPSIS

iccfg ?*value*? ?*cpu#*?

DESCRIPTION

iccfg ?*value*? ?*cpu#*?

Display or set instruction cache configuration register for the active CPU. GRMON will not keep track of this register value and will not reinitialize the register when starting or resuming software execution.

RETURN VALUE

Upon successful completion **iccfg** will return the value of the instruction cache configuration register.

SEE ALSO

-nic and -ndc switches described in Section 6.3.1, "Switches"

SEE ALSO

Section 3.4.16, "CPU cache support"

51. info - syntax

NAME

info - GRMON extends the TCL command info with some subcommands to show information about the system.

SYNOPSIS

info subcommand ?`args...`?

DESCRIPTION

info drivers

List all available device-drivers

info mkprom2

List the most basic mkprom2 commandline switches. GRMON will print flags to use the first GPTIMER and IRQMP controller and it will use the same UART for output as GRMON (see Section 3.9, "Forwarding application console I/O"). I.a. it will produce switches for all memory controllers found. In case that there exist more the one controller it's up to the user make sure that only switches belonging to one controller are used.

info reg ?`options`? ?`dev`?

Show system registers. If a device name is passed to the command, then only the registers belonging to that device is printed. The device name can be suffixed with colon and a register name to only print the specified register.

If option `-v` is specified, then GRMON will print the field names and values of each registers. If a debug driver doesn't support this feature, then the register value is printed instead.

Setting `-l` will print the name of the registers, that can be used to access the registers via TCL variables. It also returns a list of all the register names. No registers values will be read.

Setting `-a` will also return the address in the list of all the register names. Will only have an effect if -l is also set.

Setting `-d` will also return the description in the list of all the register names. Will only have an effect if -l is also set.

Enabling `-all` will print all registers. Normally only a subset is printed. This option may print a lot of registers. I could also cause read accesses to FIFOs.

info sys ?`options`? ?`dev ...`?

Show system configuration. If one or more device names are passed to the command, then only the information about those devices are printed.

If option `-v` is specified, then GRMON will print verbose information about the devices.

The option `-xml <file>` can be used to print a xml description of the system to a file instead of printing information on the screen.

RETURN VALUE

info drivers has no return value.

info mkprom2 returns a list of switches.

The command **info reg** returns a list of all registers if the `-l` is specified. If both options `-l` and `-v` have been entered it returns a list where each element is a list of the register name and the name of the registers fields. Otherwise it has no return value.

Upon successful completion **info sys** returns a list of all device names.

For other info subcommands, see TCL documentation.

EXAMPLE

Show all devices in the system

```
grmon3> info sys
  ahbjtag0  Cobham Gaisler  JTAG Debug Link
            AHB Master 0
  adev1     Cobham Gaisler  EDCL master interface
            AHB Master 2
  ...
```

Show only the DSU

```
grmon3> info sys dsu0
  dsu0      Cobham Gaisler  LEON4 Debug Support Unit
            AHB: E0000000 - E4000000
            AHB trace: 256 lines, 128-bit bus
            CPU0:  win 8, hwbp 2, itrace 256, V8 mul/div, srmmu, lddel 1, GRFPU
                   stack pointer 0x07ffff0
                   icache 4 * 4 kB, 32 B/line lru
                   dcache 4 * 4 kB, 32 B/line lru
            CPU1:  win 8, hwbp 2, itrace 256, V8 mul/div, srmmu, lddel 1, GRFPU
                   stack pointer 0x07ffff0
                   icache 4 * 4 kB, 32 B/line lru
                   dcache 4 * 4 kB, 32 B/line lru
```

Show detailed information on status register of uart0.

```
grmon3> info reg -v uart0::status
  Generic UART
     0xff900004  UART Status register                    0x00000086
        31:26  rcnt            0x0         Rx FIFO count
        25:20  tcnt            0x0         Tx FIFO count
        10     rf              0x0         Rx FIFO full
  ...
```

SEE ALSO

Section 3.4.1, "Examining the hardware configuration"

52. inst - syntax

NAME

inst - Print AHB transfer or instruction entries in the trace buffer

SYNOPSIS

inst ?*length*?
inst subcommand ?*args...*?

DESCRIPTION

inst ?*length*? ?*cpu#*?

Print the inst trace buffer. The ?*length*? entries will be printed, default is 10. Use cpu# to select single CPU.

inst filter ?*cpu#*?

Print the instruction trace buffer filter.

inst filter ?*flt*? ?*cpu#*?

Set the instruction trace buffer filter. See DSU manual for values of *flt*. (Only available in some DSU4 implementations). Use cpu# to set filter select a single CPU.

inst filter asildigit ?*val...*? ?*cpu#*?

Set which last digits that should be filtered. Only valid if filter is set to 0xE. (Only available in some DSU implementations)

inst filter range ?*index*? ?*addr*? ?*mask*? ?*excl*? ?*cpu#*?

Setup a trace filter to include or exclude instructions that is within the range. Up to four range filters is supported. (Only available in some DSU implementations)

RETURN VALUE

Upon successful completion, **inst** returns a list of trace buffer entries. Each entry is a sublist on the format format: {INST *time addr inst result trap em mc*}. Detailed description about the different fields can be found in the DSU core documentation in document grip.pdf [http://gaisler.com/products/grlib/grip.pdf]

The other subcommands have no return value.

EXAMPLE

Print 10 rows

```
grmon3> inst
    TIME    ADDRESS   INSTRUCTION                RESULT
    266951  000021D4  restore  %o0, %o0          [0000000D]
    266954  000019E4  mov  0, %g1                [00000000]
    266955  000019E8  mov  %g1, %i0              [00000000]
    266956  000019EC  ret                        [000019EC]
    266957  000019F0  restore                    [00000000]
    266960  0000106C  call  0x00009904           [0000106C]
    266961  00001070  nop                        [00000000]
    266962  00009904  mov  1, %g1                [00000001]
    266963  00009908  ta  0x0                    [   TRAP  ]
    267009  00000800  ta  0x0                    [   TRAP  ]
```

TCL returns:
```
{INST 266951 0x000021D4 0x91E80008 0x0000000D 0 0 0} {INST 266954 0x000019E4
0x82102000 0x00000000 0 0 0} {INST 266955 0x000019E8 0xB0100001 0x00000000
0 0 0} {INST 266956 0x000019EC ...
```

Print 2 rows

```
grmon3> inst 2
```

```
  TIME     ADDRESS   INSTRUCTION                 RESULT
   266951  000021D4  restore  %o0, %o0           [0000000D]
   266954  000019E4  mov  0, %g1                 [00000000]
```

TCL returns:

```
{INST 266951 0x000021D4 0x91E80008 0x0000000D 0 0 0} {INST 266954 0x000019E4
0x82102000 0x00000000 0 0 0}
```

SEE ALSO

Section 3.4.9, "Using the trace buffer"

53. iommu - syntax

NAME

iommu - Control IO memory management unit

SYNOPSIS

iommu *subcommand* ?*args*?
iommu *index subcommand* ?*args*?

DESCRIPTION

This command provides functions to control the GRIOMMU core. If more than one core exists in the system, then the index of the core to control should be specified after the **iommu** command (before the subcommand). The 'info sys' command lists the controller indexes.

iommu apv allow *base start stop*

> Modify existing APV at *base* allowing access to the address range *start - stop*

iommu apv build *base prot*

> Create APV starting at *base* with default bit value *prot*

iommu apv decode *base*

> Decode APV starting at *base*

iommu apv deny *base start stop*

> Modify existing APV at *base* denying access to the address range *start - stop*

iommu cache addr *addr grp*

> Displays cached information for I/O address *addr* in group *grp*

iommu cache errinj *addr dt* ?*byte*?

> Inject data/tag parity error at set address *addr*, data byte *byte*. The parameter *dt* should be either 'tag' or 'data'

iommu cache flush

> Invalidate all entries in cache

iommu cache show *line* ?*count*?

> Shows information about *count* line starting at *line*

iommu cache write *addr data0 ... dataN tag*

> Write full cache line including tag at set address *addr*, i.e. the number of data words depends on the size of the cache line. See example below.

iommu disable
iommu enable

> Disables/enable the core

iommu group ?*grp*? ?*base passthrough active*?

> Show/set information about group(s). When no parameters are given, information about all groups will be shown. If the index *grp* is given then only that group will be shown. When all parameters are set, the fields will be assigned to the group.

iommu info

> Displays information about IOMMU configuration

iommu mstbmap ?*mst*? ?*grp*?

> Show/set information about master->group assignments. When no parameters are given, information about all masters will be shown. If the index *mst* is given then only that master will be shown. When all parameters are set, master *mst* will be assigned to group *grp*

iommu mstbmap ?*mst*? ?*ahb*?

> Show/set information about master->AHB interface assignments. When no parameters are given, information about all masters will be shown. If the index *mst* is given then only that master will be shown. When all parameters are set, master *mst* will be assigned to AHB interface *ahb*

iommu pagetable build *base writeable valid*

> Create page table starting at *base* with all writable fields set to *writeable* and all valid fields set to *valid*. 1:1 map starting at physical address 0.

iommu pagetable lookup *base ioaddr*

> Lookup specified IO address in page table starting at *base*.

iommu pagetable modify *base ioaddr phyaddr writeable valid*

> Modify existing PT at *base*, translate *ioaddr* to *phyaddr*, *writeable*, *valid*

iommu status

> Displays core status information

RETURN VALUE

Upon successful completion **iommu apv docode** returns a list of triples, where each triple contains start, stop and protection bit.

Command **iommu cache addr** returns a tuple, containing valid and protection bits.

Command **iommu cache show** returns a list of entries. Each entry contains line address, tag and the cached data words.

The other subcommands have no return value.

EXAMPLE

Show info on a system with one core
```
grmon3> iommu info
```

Show info of the second core in a system with multiple cores
```
grmon3> iommu 1 info
```

Writes set address 0x23 with the 128-bit cache line 0x000000008F000000FFFFFFFF00000000 and tag 0x1 (valid line)
```
grmon3> iommu cache write 0x23 0x0 0x8F000000 0xFFFFFFFF 0x0 0x1
```

54. irq - syntax

NAME

irq - Force interrupts or read IRQ(A)MP status information

SYNOPSIS

irq *subcommand args...*

DESCRIPTION

This command provides functions to force interrupts and reading IRQMP status information. The command also support the ASMP extension provided in the IRQ(A)MP core.

irq boot ?*mask*?

> Boot CPUs specified by mask (for IRQ(A)MP)

irq ctrl ?*index*?

> Show/select controller register interface to use (for IRQ(A)MP)

irq force *irq*

> Force interrupt *irq*

irq reg

> Display some of the core registers

irq routing

> Decode controller routing (for IRQ(A)MP)

irq tstamp

> Show time stamp registers (for IRQ(A)MP)

irq wdog

> Decode Watchdog control register (for IRQ(A)MP)

RETURN VALUE

Command **irq** has no return value.

55. l2cache - syntax

NAME

l2cache - L2 cache control

SYNOPSIS

l2cache *subcommand* ?*args*?

DESCRIPTION

l2cache lookup *addr*

Prints the data and status of a cache line if *addr* generates a cache hit.

l2cache show data ?*way*? ?*count*? ?*start*?

Prints the data of *count* cache line starting at cache line *start*.

l2cache show tag ?*count*? ?*start*?

Prints the tag of *count* cache line starting at cache line *start*.

l2cache enable

Enable the cache.

l2cache disable
l2cache disable flushinvalidate

Disable the cache. If *flushinvalidate* is given, all dirty cache lines are invalidated and written back to memory as an atomic operation.

l2cache ft ?*boolean*?

Enable or disable the EDAC. If boolean is not set, then the command will show if the EDAC is enabled or disabled.

l2cache flush
l2cache flush all ?*mode*?

Perform a cache flush to all cache lines using a flush *mode*.

l2cache flush mem *address* ?*mode*?

Perform a cache flush to the cache lines with a cache hit for address using a flush *mode*.

l2cache flush direct *address* ?*mode*?

Perform a cache flush to the cache lines addressed with address using a flush *mode*.

l2cache invalidate

Invalidate all cache lines

l2cache flushinvalidate

Flush and invalidate all cache lines (copy-back)

l2cache hit

Prints the hit rate statistics.

l2cache wt ?*boolean*?

Enable or disable the write-through. If boolean is not set, then the command will show if write-through is enabled or disabled.

l2cache hprot ?*boolean*?

Enable or disable the HPROT. If boolean is not set, then the command will show if HPROT is enabled or disabled.

l2cache smode ?*mode*?

Set the statistics mode. If the *mode* is not set, then the command will show the current statistics mode.

l2cache error
l2cache error inject
l2cache error reset
l2cache error dcb ?*value*?
l2cache error tcb ?*value*?

The **l2cache error** used to show information about an error in the L2-cache and the information is cleared with **l2cache error reset**. I.a. the **l2cache error inject** can be used to create an error. The **l2cache error dcb** and **l2cache error tcb** can be used to read or write the data/tag check bits.

l2cache mtrr ?*index*? ?*value*?

Show all or a specific memory type range register. If value is present, then the specified register will be set.

l2cache split *boolean*

Enable or disable AHB SPLIT response support for the L2 cache controller.

RETURN VALUE

Upon successful completion **l2cache lookup** returns a list of addr, way, tag, index, offset, valid bit, dirty bit and LRU bit.

Commands **l2cache show data** and **l2cache show tags** returns a list of entries. For **data** each entry contains an address and 8 data words. The entry for **tag** contains index, address, LRU and list of valid bit, dirty bit and tag for each way.

Upon successful completion **l2cache ft**, **l2cache hprot**, **l2cache smode** and **l2cache wt** returns a boolean.

Command **l2cache hit** returns hit-rate and front bus usage-rate.

Command **l2cache status** returns control and status register values.

Upon successful completion **l2cache dcb** and **l2cache tcb** return check bits for data or tags.

Command **l2cache mtrr** returns a list of values.

SEE ALSO

Section 3.4.16, "CPU cache support"

56. l3stat - syntax

NAME

l3stat - Control Leon3 statistics unit

SYNOPSIS

l3stat *subcommand* ?*args...*?
l3stat *index subcommand* ?*args...*?

DESCRIPTION

This command provides functions to control the L3STAT core. If more than one core exists in the system, then the index of the core to control should be specified after the **l3stat** command (before the subcommand). The 'info sys' command lists the device indexes.

l3stat events

Show all events that can be selected/counted

l3stat status

Display status of all available counters.

l3stat clear *cnt*

Clear the counter *cnt*.

l3stat set *cnt cpu event* ?*enable*? ?*clearonread*?

Count the *event* using counter *cnt* on processor *cpu*. The optional *enable* parameter defaults to 1 if left out. The optional *clearonread* parameter defaults to 0 if left out.

l3stat duration *cnt enable* ?*lvl*?

Enable the counter *cnt* to save maximum time the selected event has been at lvl. When enabling the lvl parameter must be present, but when disabling it be left out.

l3stat poll *start stop interval hold*

Continuously poll counters between *start* and *stop*. The *interval* parameter sets how many seconds between each iteration. If hold is set to 1, then it will block until the first counter is enabled by other means (i.e. software). The polling stops when the first counter is disabled or a SIGINT signal (Ctrl-C) is sent to GRMON.

l3stat runpoll *start stop interval*

Setup counters between *start* and *stop* to be polled while running an application (i.e. 'run', 'go' or 'cont' commands). The *interval* argument in this case does not specify the poll interval seconds but rather in terms of iterations when GRMON polls the Debug Support Unit to monitor execution. A suitable value for the int argument in this case depends on the speed of the host computer, debug link and target system.

EXAMPLE

Enable maximum time count, on counter 1, when no instruction cache misses has occurred.

```
grmon3> l3stat set 1 0 icmiss
grmon3> l3stat duration 1 1 0
```

Disable maximum time count on counter 1.
```
grmon3> l3stat duration 1 0
```

Poll for cache misses when running.

```
grmon3> l3stat set 0 0 dcmiss
grmon3> l3stat set 1 0 icmiss
```

```
grmon3> l3stat runpoll 0 1 5000
grmon3> run
```

57. l4stat - syntax

NAME

l4stat - Control Leon4 statistics unit

SYNOPSIS

l4stat *subcommand* *?args...?*
l4stat *index subcommand* *?args...?*

DESCRIPTION

This command provides functions to control the L4STAT core. If more than one core exists in the system, then the index of the core to control should be specified after the **l4stat** command (before the subcommand). The `'info sys'` command lists the device indexes.

l4stat events

> Show all events that can be selected/counted

l4stat status

> Display status of all available counters.

l4stat clear *cnt*

> Clear the counter *cnt*.

l4stat set *cnt cpu event ?enable? ?clearonread?*

> Count the *event* using counter *cnt* on processor *cpu*. The optional *enable* parameter defaults to 1 if left out. The optional *clearonread* parameter defaults to 0 if left out.

l4stat duration *cnt enable ?lvl?*

> Enable the counter *cnt* to save maximum time the selected event has been at lvl. When enabling the lvl parameter must be present, but when disabling it be left out.

l4stat poll *start stop interval hold*

> Continuously poll counters between *start* and *stop*. The *interval* parameter sets how many seconds between each iteration. If hold is set to 1, then it will block until the first counter is enabled by other means (i.e. software). The polling stops when the first counter is disabled or a SIGINT signal (Ctrl-C) is sent to GRMON.

l4stat runpoll *start stop interval*

> Setup counters between *start* and *stop* to be polled while running an application (i.e. 'run', 'go' or 'cont' commands). The *interval* argument in this case does not specify the poll interval seconds but rather in terms of iterations when GRMON polls the Debug Support Unit to monitor execution. A suitable value for the int argument in this case depends on the speed of the host computer, debug link and target system.

EXAMPLE

Enable maximum time count, on counter 1, when no instruction cache misses has occurred.

```
grmon3> l4stat set 1 0 icmiss
grmon3> l4stat duration 1 1 0
```

Disable maximum time count on counter 1.
```
grmon3> l4stat duration 1 0
```

Poll for cache misses when running.

```
grmon3> l4stat set 0 0 dcmiss
grmon3> l4stat set 1 0 icmiss
```

```
grmon3> l4stat runpoll 0 1 5000
grmon3> run
```

58. la - syntax

NAME

la - Control the LOGAN core

SYNOPSIS

la
la *subcommand* ?*args...*?

DESCRIPTION

The LOGAN debug driver contains commands to control the LOGAN on-chip logic analyzer core. It allows to set various triggering conditions, and to generate VCD waveform files from trace buffer data. All logic analyzer commands are prefixed with la.

If more than one device exists in the system, the *logan#* can be used to select device, default is logan0.

la
la status ?*logan#*?

      Reports status of LOGAN.

la arm ?*logan#*?

      Arms the LOGAN. Begins the operation of the analyzer and sampling starts.

la config *filename* ?*logan#*?
la config ?*name bits...*? ?*logan#*?

      Set the configuration of the LOGAN device. Either a filename or an array of name and bits pairs.

la count ?*value*? ?*logan#*?

      Set/displays the trigger counter. The *value* should be between zero and depth-1 and specifies how many samples that should be taken after the triggering event.

la div ?*value*? ?*logan#*?

      Sets/displays the sample frequency divider register. If you specify e.g. "la div 5" the logic analyzer will only sample a value every 5th clock cycle.

la dump ?*filename*? ?*logan#*?

      This dumps the trace buffer in VCD format to the file specified (default is logan.vcd).

la mask *trigl bit* ?*value*? ?*logan#*?

      Sets/displays the specified bit in the mask of the specified trig level to 0/1.

la page ?*value*? ?*logan#*?

      Sets/prints the page register of the LOGAN. Normally the user doesn't have to be concerned with this because dump and view sets the page automatically. Only useful if accessing the trace buffer manually via the GRMON mem command.

la pat *trigl bit* ?*value*? ?*logan#*?

      Sets/displays the specified bit in the pattern of the specified trig level to 0/1.

la pm ?*trigl*? ?*pattern mask*? ?*logan#*?

      Sets/displays the complete pattern and mask of the specified trig level. If not fully specified the input is zero-padded from the left. Decimal notation only possible for widths less than or equal to 64 bits.

la qual ?*bit value*? ?*logan#*?

      Sets/displays which bit in the sampled pattern that will be used as qualifier and what value it shall have for a sample to be stored.

la reset ?*logan#*?

Stop the operation of the LOGAN. Logic Analyzer returns to idle state.

la trigctrl ?*trigl*? ?*count cond*? ?*logan#*?

Sets/displays the match counter and the trigger condition (1 = trig on equal, 0 = trig on not equal) for the specified trig level.

la view *start stop* ?*filename*? ?*logan#*?

Prints the specified range of the trace buffer in list format. If no filename is specified the commands prints to the screen.

SEE ALSO

Section 6.13, "On-chip logic analyzer driver"

NAME

leon - Print leon specific registers

SYNOPSIS

leon

DESCRIPTION

leon

Print leon specific registers

60. load - syntax

NAME

load - Load a file or print filenames of uploaded files.

SYNOPSIS

load ?*options...*? *filename* ?*address*? ?*cpu#*?
load *subcommand* ?*arg*?

DESCRIPTION

The load command may be used to upload a file to the system. It can also be used to list all files that have been loaded. When a file is loaded, GRMON will reset the memory controllers registers first.

To avoid overwriting the image file loaded, one must must make sure that DMA is not active to the address range(s) of the image. Drivers can be reset using the **reset** command prior to loading.

   load ?*options...*? *filename* ?*address*? ?*cpu#*?

      The load command may be used to upload the file specified by *filename*. If the *address* argument is present, then binary files will be stored at this address, if left out then they will be placed at the base address of the detected RAM. The *cpu#* argument can be used to specify which CPU it belongs to. The options is specified below.

   load clear ?*cpu#*?

      This command will clear the information about the files that have been loaded to the CPU:s. If the *cpu#* argument is specified, then only that CPU will be listed.

   load show ?*cpu#*?

      This command will list which files that have been loaded to the CPU:s. If the *cpu#* argument is specified, then only that CPU will be listed.

OPTIONS

   -binary

      The -binary option can be used to force GRMON to interpret the file as a binary file.

   -bsize bytes

      The -bsize option may be used to specify the size blocks of data in bytes that will be written. Sizes that are not even words may require a JTAG based debug link to work properly. See Chapter 5, *Debug link* more information.

   -data

      Only load sections containing data, i.e. skip instructions.

   -delay ms

      The -delay option can be used to specify a delay between each word written. If the delay is non-zero then the default block size will be 4 bytes, but can be changed using the -bsize option.

   -debug

      If the -debug option is given the DWARF debug information is read in.

   -nmcr

      If the -nmcr (No Memory Controller Reinitialize) option is given then the memory controller(s) are not reinitialized. Without the option set all memory controllers that data is loaded to are reinitialized.

   -wprot

      If the -wprot option is given then write protection on the core will be disabled

RETURN VALUE

Command **load** returns the entry point.

EXAMPLE

Load and then verify a hello_world application

```
grmon3> load ../hello_world/hello_world
grmon3> verify ../hello_world/hello_world
```

SEE ALSO

Section 3.4.2, "Uploading application and data to target memory"

61. mcfg1 - syntax

mcfg1 - Show or set reset value of the memory controller register 1

SYNOPSIS

mcfg1 ?*value*?

DESCRIPTION

  mcfg1 ?*value*?

      Set the reset value of the memory register. If value is left out, then the reset value will be printed.

SEE ALSO

Section 6.14, "Memory controllers "

62. mcfg2 - syntax

mcfg2 - Show or set reset value of the memory controller register 2

SYNOPSIS

mcfg2 ?*value*?

DESCRIPTION

   mcfg2 ?*value*?

      Set the reset value of the memory register. If value is left out, then the reset value will be printed.

SEE ALSO

Section 6.14, "Memory controllers "

63. mcfg3 - syntax

mcfg3 - Show or set reset value of the memory controller register 3

SYNOPSIS

mcfg3 ?*value*?

DESCRIPTION

   mcfg3 ?*value*?

      Set the reset value of the memory register. If value is left out, then the reset value will be printed.

SEE ALSO

Section 6.14, "Memory controllers "

64. mdio - syntax

NAME

mdio - Show PHY registers

SYNOPSIS

mdio *paddr raddr* ?*greth#*?
mdio info ?*greth#*? ?*paddr*?
mdio reg ?*greth#*? ?*paddr*?

DESCRIPTION

mdio *paddr raddr* ?*greth#*?

Show value of PHY address *paddr* and register *raddr*. If more than one device exists in the system, the *greth#* can be used to select device, default is dev0. The command tries to disable the EDCL duplex detection if enabled.

mdio info ?*greth#*? ?*paddr*?

Show PHY model and link state for each PHY accessible from each GRETH device. Use *greth#* and/or *paddr* to only show link state for a specific GRETH device or PHY.

mdio reg ?*greth#*? ?*paddr*?

Show all registers for each PHY accessible from each GRETH device. Use *greth#* and/or *paddr* to only show registers for a specific GRETH device or PHY.

SEE ALSO

Section 6.4, "Ethernet controller"

65. memb - syntax

NAME

memb - AMBA bus 8-bit memory read access, list a range of addresses

SYNOPSIS

memb ?*options*? *address* ?*length*?

DESCRIPTION

memb ?*options*? *address* ?*length*?

Do an AMBA bus 8-bit read access at *address* and print the the data. The optional length parameter should specified in bytes and the default size is 64 bytes.

Only JTAG debug links supports byte accesses. Other debug links will do a 32-bit read and then parse out the unaligned data.

OPTIONS

`-ascii`

If the `-ascii` flag has been given, then a single ASCII string is returned instead of a list of values.

`-cstr`

If the `-cstr` flag has been given, then a single ASCII string, up to the first null character, is returned instead of a list of values.

RETURN VALUE

Upon successful completion **memb** returns a list of the requested 8-bit words. Some options changes the result value, see options for more information.

EXAMPLE

Read 4 bytes from address 0x40000000:
```
grmon3> memb 0x40000000 4
```

TCL returns:
```
64 0 0 0
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"

66. memd - syntax

NAME

memd - AMBA bus 64-bit memory read access, list a range of addresses

SYNOPSIS

memd ?*options*? *address* ?*length*?

DESCRIPTION

memd ?*options*? *address* ?*length*?

Do an AMBA bus read access at *address* and print the data as 64-bit words. The optional length parameter should be specified in bytes and the default size is 64 bytes (8 64-bit words).

OPTIONS

-ascii

If the -*ascii* flag has been given, then a single ASCII string is returned instead of a list of values.

-cstr

If the -*cstr* flag has been given, then a single ASCII string, up to the first null character, is returned instead of a list of values.

RETURN VALUE

Upon successful completion **memd** returns a list of the requested 64-bit words. Some options changes the result value, see options for more information.

EXAMPLE

Read 2 64-bit words (16 bytes) from address 0x40000000:
```
grmon3> memd 0x40000000 16
```

TCL returns:
```
0xffff1244901022 0x543348
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"

67. memh - syntax

NAME

memh - AMBA bus 16-bit memory read access, list a range of addresses

SYNOPSIS

memh ?*options*? *address* ?*length*?

DESCRIPTION

memh ?*options*? *address* ?*length*?

Do an AMBA bus 16-bit read access at *address* and print the the data. The optional length parameter should specified in bytes and the default size is 64bytes (32 words).

Only JTAG debug links supports byte accesses. Other debug links will do a 32-bit read and then parse out the unaligned data.

OPTIONS

-ascii

If the *-ascii* flag has been given, then a single ASCII string is returned instead of a list of values.

-cstr

If the *-cstr* flag has been given, then a single ASCII string, up to the first null character, is returned instead of a list of values.

RETURN VALUE

Upon successful completion **memh** returns a list of the requested 16-bit words. Some options changes the result value, see options for more information.

EXAMPLE

Read 4 words (8 bytes) from address 0x40000000:
```
grmon3> memh 0x40000000 8
```

TCL returns:
```
16384 0 0 0
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"

68. mem - syntax

NAME

mem - AMBA bus 32-bit memory read access, list a range of addresses

SYNOPSIS

mem ?`-options`? `address` ?`length`?

DESCRIPTION

mem ?`-options`? `address` ?`length`?

Do an AMBA bus 32-bit read access at `address` and print the the data. The optional length parameter should specified in bytes and the default size is 64 bytes (16 words).

OPTIONS

`-bsize` bytes

The `-bsize` option can be used to specify the size blocks of data in bytes that will be read between each print to the screen. Setting a high value may increase performance but cause a less smooth printout when using a slow debug link.

`-ascii`

If the `-ascii` flag has been given, then a single ASCII string is returned instead of a list of values.

`-cstr`

If the `-cstr` flag has been given, then a single ASCII string, up to the first null character, is returned instead of a list of values.

`-hex`

Give the `-hex` flag to make the Tcl return values hex strings. The numbers are always 2, 4 or 8 characters wide strings regardless of the actual integer value.

`-x`

Give the `-x` flag to make the Tcl return values hex strings. The numbers are always 2, 4 or 8 characters wide strings regardless of the actual integer value. The return values are prefixed with 0x.

RETURN VALUE

Upon successful completion **mem** returns a list of the requested 32-bit words. Some options changes the result value, see options for more information.

EXAMPLE

Read 4 words from address 0x40000000:
```
grmon3> mem 0x40000000 16
```

TCL returns:
```
1073741824 0 0 0
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"

69. mil - syntax

mil - MIL-STD-1553B Interface commands

SYNOPSIS

mil ?subcommand? ?args...?

DESCRIPTION

mil active `bus device`

    Select which device to control and which bus to use for **mil put** and **mil get**.

mil status

    Display core status

mil bcx `addr` ?`count`?

    Print BC descriptor contents and result values

mil bmx `addr` ?`count`?

    Print BM log entries from the given memory address

mil bmlog ?`count`? ?`logaddr`?

    Print the latest entries from the currently running BM log

mil buf ?`bufaddr`? ?`coreaddr`?

    Set address of temporary buffer for transfer commands

mil bufmode ?`mode`?

    Select if the temporary buffer should be kept or restored. Valid `mode`-values are 'keep' or 'restore'

mil get `rtaddr subaddr count`

    Perform an RT-to-BC transfer and display the result

mil getm `rtaddr subaddr count memaddr`

    Perform an RT-to-BC transfer and store resulting data at `memaddr`

mil put `rtaddr subaddr count word0` ?`... word31`?

    Perform an BC-to-RT transfer

mil putm `rtaddr subaddr count memaddr`

    Perform an BC-to-RT transfer of data located at `memaddr`

mil halt

    Stop the core and store the state for resuming later.

mil resume

    Resume operation with state stored earlier by the **mil halt** command.

mil lbtest rt
mil lbtest bc

    Runs RT- or BC-part of loopback test

70. mmu - syntax

NAME

mmu - Print or set the SRMMU registers

SYNOPSIS

mmu ?*cpu#*?
mmu subcommand ?*args...*? ?*cpu#*?

DESCRIPTION

mmu ?*cpu#*?

Print the SRMMU registers

mmu mctrl ?*value*? ?*cpu#*?

Set the MMU control register

mmu ctxptr ?*value*? ?*cpu#*?

Set the context pointer register

mmu ctx *value*? ?*cpu#*?

Set the context register

mmu va *ctx*? ?*cpu#*?

Translate a virtual address. The command will use the MMU from the current active CPU and the cpu# can be used to select a different CPU.

mmu walk *ctx*? ?*cpu#*?

Translate a virtual address and print translation. The command will use the MMU from the current active CPU and the cpu# can be used to select a different CPU.

mmu table *ctx*? ?*cpu#*?

Print table, optionally specify context. The command will use the MMU from the current active CPU and the cpu# can be used to select a different CPU.

RETURN VALUE

The commands **mmu** returns a list of the MMU registers.

The commands **mmu va** and **mmu walk** returns the translated address.

The command **mmu table** returns a list of ranges, where each range has the following format: {*vaddr_start vaddr_end paddr_start paddr_end access pages*

EXAMPLE

Print MMU registers

```
grmon3> mmu
  mctrl: 00904001  ctx: 00000001  ctxptr: 00622000  fsr: 000002DC  far: 9CFB9000
```

TCL returns:
```
9453569 1 401920 732 -1661235200
```

Print MMU table

```
grmon3> puts [mmu table]
  MMU Table for CTX1 for CPU0
    0x00000000-0x00000fff -> 0x00000000-0x00000fff  crwxrwx [1 page]
    0x00001000-0x0061ffff -> 0x00001000-0x0061ffff  crwx--- [1567 pages]
    0x00620000-0x00620fff -> 0x00620000-0x00620fff  -r-xr-x [1 page]
```

```
     0x00621000-0x00621fff -> 0x00621000-0x00621fff  crwx--- [1 page]
  ...
```

TCL returns:

```
{0x00000000  0x00000fff  0x00000000  0x00000fff  crwxrwx  1}  {0x00001000
0x0061ffff  0x00001000  0x0061ffff  crwx---  1567}  {0x00620000  0x00620fff
0x00620000 0x00620fff -r-xr-x 1} {0x00621000 0x00621fff 0x00621000 0x00621fff
crwx--- 1} ...
```

SEE ALSO

Section 3.4.15, "Memory Management Unit (MMU) support"

71. nolog - syntax

NAME

nolog - Suppress logging of stdout of a command

SYNOPSIS

nolog *command* ?*args...*?

DESCRIPTION

nolog *command* ?*args...*?

The nolog command be put in front of other GRMON commands to suppress the logging of the output. This can be useful to remove unnecessary output when scripting.

EXAMPLE

Suppress the memory print.
```
grmon3>nolog mem 0x40000000
```

72. pci - syntax

NAME

pci - Control the PCI bus master

SYNOPSIS

pci subcommand ?`args...`?

DESCRIPTION

The PCI debug drivers are mainly useful for PCI host systems. The **pci init** command initializes the host's target BAR1 to point to RAM (PCI address 0x40000000 -> AHB address 0x4000000) and enables PCI memory space and bus mastering. Commands are provided for initializing the bus, scanning the bus, configuring the found resources, disabling byte twisting and displaying information. Note that on non-host systems only the info command has any effect.

The **pci scan** command can be used to print the current configuration of the PCI bus. If a OS has initialized the PCI core and the PCI bus (at least enumerated all PCI buses) the scan utility can be used to see how the OS has configured the PCI address space. Note that scanning a multi-bus system that has not been enumerated will fail.

The **pci conf** command can fail to configure all found devices if the PCI address space addressable by the host controller is smaller than the amount of memory needed by the devices.

A configured PCI system can be registered into the GRMON device handling system similar to the on-chip AMBA bus devices, controlled using the **pci bus** commands. GRMON will hold a copy of the PCI configuration in memory until a new **pci conf**, **pci bus unreg** or **pci scan** is issued. The user is responsible for updating GRMON's PCI configuration if the configuration is updated in hardware. The devices can be inspected from **info sys** and Tcl variables making read and writing PCI devices configuration space easier. The Tcl variables are named in a similar fashion to AMBA devices, for example **puts $pdev0::status** prints the STATUS register of PCI device0. See **pci bus** reference description below and the Tcl API description in the manual.

pci bt ?`boolean`?

> Enable/Disable the byte twisting (if supported by host controller)

pci bus reg

> Register a previously configured PCI bus into the GRMON device handling system. If the PCI bus has not been configured previously the **pci conf** is automatically called first (similar to **pci conf -reg**).

pci bus unreg

> Unregister (remove) a previously registered PCI bus from the GRMON device handling system.

pci cfg8 `deviceid offset`
pci cfg16 `deviceid offset`
pci cfg32 `deviceid offset`

> Read a 8-, 16- or 32-bit value from configuration space. The device ID selects which PCI device/function is address during the configuration access. The offset must must be located with the device's space and be aligned to access type. Three formats are allowed to specify the `deviceid`: 1. `bus:slot:func`, 2. device name (pdev#), 3. host. It's allowed to skip the bus index, i.e. only specifying `slot:func`, it will then default to bus index 0. The ID numbers are specified in hex. If "host" is given the Host Bridge Controller itself will be queried (if supported by Host Bridge). A device name (for example "pdev0") may also be used to identify a device found from the **info sys** command output.

pci conf ?`-reg`?

> Enumerate all PCI buses, configures the BARs of all devices and enables PCI-PCI bridges where needed. If -reg is given the configured PCI bus is registered into GRMON device handling system similar to **pci bus reg**, see above.

pci init

> Initializes the host controller as described above

pci info

Displays information about the host controller

pci io8 `addr value`
pci io16 `addr value`
pci io32 `addr value`

Write a 8-, 16- or 32-bit value to I/O space.

pci scan ?`-reg`?

Scans all PCI slots for available devices and their current configuration are printed on the terminal. The scan does not alter the values, however during probing some registers modified by rewritten with the original value. This command is typically used to look at the reset values (after pci init is called) or for inspecting how the Operating System has set PCI up (pci init not needed). Note that PCI buses are not enumerated during scanning, in multi-bus systems secondary buses may therefore not be accessible. If -reg is given the configured PCI bus is registered into GRMON device handling system similar to **pci bus reg**, see above.

pci wcfg8 `deviceid offset value`
pci wcfg16 `deviceid offset value`
pci wcfg32 `deviceid offset value`

Write a 8-, 16- or 32-bit value to configuration space. The device ID selects which PCI device/function is address during the configuration access. The offset must must be located with the device's space and be aligned to access type. Three formats are allowed to specify the `deviceid`: 1. `bus:slot:func`, 2. device name (pdev#), 3. host. It's allowed to skip the bus index, i.e. only specifying `slot:func`, it will then default to bus index 0. The ID numbers are specified in hex. If "host" is given the Host Bridge Controller itself will be queried (if supported by Host Bridge). A device name (for example "pdev0") may also be used to identify a device found from the **info sys** command output.

pci wio8 `addr value`
pci wio16 `addr value`
pci wio32 `addr value`

Write a 8-, 16- or 32-bit value to I/O space.

PCI Trace commands:

pci trace

Reports current trace buffer settings and status

pci trace address `pattern`

Get/set the address pattern register.

pci trace amask `pattern`

Get/set the address mask register.

pci trace arm

Arms the trace buffer and starts sampling.

pci trace log ?`length`? ?`offset`?

Prints the trace buffer data. Offset is relative the trigger point.

pci trace sig `pattern`

Get/set the signal pattern register.

pci trace smask `pattern`

Get/set the signal mask register.

pci trace start

Arms the trace buffer and starts sampling.

pci trace state

>   Prints the state of the PCI bus.

pci trace stop

>   Stops the trace buffer sampling.

pci trace tcount `value`

>   Get/set the number of matching trigger patterns before disarm

pci trace tdelay `value`

>   Get/set number of extra cycles to sample after disarm.

RETURN VALUE

Upon successful completion most **pci** commands have no return value.

The read commands return the read value. The write commands have no return value.

When the commands **pci trace address**, **pci trace amask**, **pci trace sig**, **pci trace smask**, **pci trace tcount** and **pci trace tdelay** are used to read values, they return their values.

The **pci trace log** command returns a list of triples, where the triple contains the address, a list of signals and buffer index.

Command **pci trace state** returns a tuple of the address and a list of signals.

EXAMPLE

Initialize host controller and configure the PCI bus

```
grmon3> pci init
grmon3> pci conf
```

Inspect a PCI bus that has already been setup
```
grmon3> pci scan
```

SEE ALSO

Section 6.17, "PCI"

73. perf - syntax

perf - Measure performance

SYNOPSIS

perf
perf ?*subcommand*? ?*args...*?

DESCRIPTION

The performance command is only available when a DSU4 exists in the system.

   perf

      Display result

perf ?*disable*?
perf ?*enable*?

      Enable or disable the performance measure.

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74. phyaddr - syntax

NAME

phyaddr - Set the default PHY address

SYNOPSIS

phyaddr *address* ?*greth#*?

DESCRIPTION

phyaddr *address* ?*greth#*?

Set the default PHY address to *address*. If more than one device exists in the system, the *greth#* can be used to select device, default is greth0.

EXAMPLE

Set PHY address to 1
```
grmon3> phyaddr 1
```

SEE ALSO

Section 6.4, "Ethernet controller"

75. profile - syntax

NAME

profile - Enable, disable or show simple profiling

SYNOPSIS

profile *?nlines? ?cpu#?*
profile clear *?cpu#?*
profile enable *?cpu#?*
profile disable *?cpu#?*

DESCRIPTION

If profiling is enabled then GRMON will profile the application being executed on the system.

profile *?nlines?*

Show profiling information for all CPUs or specified CPU. When printing the information for all the CPUs, only a single table with the sum of all CPUs will be printed. Optionally you can limit the number of printed lines with the a *nlines* argument.

profile clear

Clear collected information on all CPUs or specified CPU.

profile enable

Turn on profiling all CPUs or a single CPU.

profile disable

Turn off profiling for all CPUs or a single CPU.

SEE ALSO

Section 3.4.10, "Profiling"

76. quit - syntax

NAME

quit - Exit the GRMON console

SYNOPSIS

quit

DESCRIPTION

quit

When using the command line version (cli) of GRMON, this command will be the same as 'exit 0'. In the GUI version it will close down a single console window. Use 'exit' to close down the entire application when using the GUI version of GRMON.

EXAMPLE

Exit the GRMON console.
```
grmon3> quit
```

77. reg - syntax

reg - Show or set integer registers

SYNOPSIS

reg ?*name ...*? ?*name value ...*?

DESCRIPTION

reg ?*name ...*? ?*name value ...*? ?*cpu#*?

Show or set integer registers of the current CPU, or the CPU specified by cpu#. If no register arguments are given then the command will print the current window and the special purpose registers. The register arguments can to both set and show each individual register. If a register name is followed by a value, it will be set else it will only be shown.

Floating-point registers should be set with a decimal point value. A decimal-point value can be suffixed with an f character to force the value to be interpereated as a single precision value. If an integer is written to a floating-point register, the value will be interpereated as a binary representation of an floating-point value.

Valid LEON window register names are:
Registers
    r0, r1, r2, r3, r4, r5, r6, r7, r8, r9, r10, r11, r12, r13, r14, r15, r16, r17, r18, r19, r20, r21, r22, r23, r24, r25, r26, r27, r28, r29, r30, r31
Global registers
    g0, g1, g2, g3, g4, g5, g6, g7
Current window in registers
    i0, i1, i2, i3, i4, i5, i6, i7
Current window local registers
    l0, l1, l2, l3, l4, l5, l6, l7
Current window out registers
    o0, o1, o2, o3, o4, o5, o6, o7
Special purpose registers
    sp, fp
Windows (N is the number of implemented windows)
    w0, w1 ... wN
Single register from a window
    w1l3 w1o3 w2i5 etc.
In addition the following non-window related LEON registers are also valid:
Floating point registers
    f0, f1, f2, f3, f4, f5, f6, f7, f8, f9, f10, f11, f12, f13, f14, f15, f16, f17, f18, f19, f20, f21, f22, f23, f24, f25, f26, f27, f28, f29, f30, f31
Floating point registers (double precision)
    d0, d1, d2, d3, d4, d5, d6, d7, d8, d9, d10, d11, d12, d13, d14, d15,
Special purpose registers
    psr, tbr, wim, y, pc, npc, fsr
Application specific registers
    asr16, asr17, asr18

Valid NOEL-V register names are:
Registers
    x0, x1, x2, x3, x4, x5, x6, x7, x8, x9, x10, x11, x12, x13, x14, x15, x16, x17, x18, x19, x20, x21, x22, x23, x24, x25, x26, x27, x28, x29, x30, x31 zero, ra, sp, gp, tp, a0, a1, a2, a3, a4, a5, a6, a7, t0, t1, t2, t3, t4, t5, t6, s0, s1, s2, s3, s4, s5, s6, s7, s8, s9, s10, s11
CSR registers
    csr####, where #### is the register number, or the name of the CSR register

Floating point registers
f0, f1, f2, f3, f4, f5, f6, f7, f8, f9, f10, f11, f12, f13, f14, f15, f16, f17, f18, f19, f20, f21, f22, f23, f24, f25, f26, f27, f28, f29, f30, f31 fa0, fa1, fa2, fa3, fa4, fa5, fa6, fa7, ft0, ft1, ft2, ft3, ft4, ft5, ft6, ft7, ft8, ft9, ft10, ft11, fs0, fs1, fs2, fs3, fs4, fs5, fs6, fs7, fs8, fs9, fs10, fs11

RETURN VALUE

Upon successful completion, command **reg** returns a list of the requested register values. When register windows are requested, then nested list of all registers will be returned. If a float/double is requested, then a tuple of the decimal and the binary value is returned.

EXAMPLE

Display the current window and special purpose registers
```
grmon3> reg
```

TCL returns:
```
{0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0} -213905184
2 1073741824 0 1073741824 1073741828
```

Display the g0, l3 in window 2, f1, pc and w1.
```
grmon3> reg g0 w2l3 f1 pc w1
```

TCL returns:
```
0 0 {0.0 0} 1073741824 {0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0}
```

Set register g1 to the value 2 and display register g2
```
grmon3> reg g1 2 g2
```

TCL returns:
```
2 0
```

Set floating point registers
```
grmon3> reg f0 3.141593 f1 3.141593f d1 3.141593 d2 3.141593f
```

TCL returns:
```
{3.1415929794311523 0x40490fdc} {3.1415929794311523 0x40490fdc} {3.141593
0x400921fb82c2bd7f} {3.1415929794311523 0x400921fb80000000}
```

SEE ALSO

Section 3.4.5, "Displaying processor registers"

78. reset - syntax

NAME

reset - Reset drivers

SYNOPSIS

reset

DESCRIPTION

The **reset** will give all core drivers an opportunity to reset themselves into a known state. For example will the memory controllers reset it's registers to their default value and some drivers will turn off DMA. It is in many cases crucial to disable DMA before loading a new binary image since DMA can overwrite the loaded image and destroy the loaded Operating System.

EXAMPLE

Reset drivers
```
grmon3> reset
```

79. rtg4fddr - syntax

NAME

rtg4fddr - Print initialization sequence

SYNOPSIS

rtg4fddr *show* ?*fddr#*?

DESCRIPTION

    rtg4fddr *show* ?*fddr#*?

        Print initialization sequence

        The RTG4 FDDR initcode is loaded into a procedure in the system shell. The procedure is executed in init level 6, therefore it is possible to override the script in level 5 by redefining the the ::fdir#::init procedure using the init# hook.

EXAMPLE

Override the default initialization

```
proc MyInit5 {} {
    proc ::fddr0::init {} {
        # Add custom initialization code here
    }
    proc ::fddr1::init {} {
        # Add custom initialization code here
    }
}
lappend ::hooks::init5 MyInit5
```

SEE ALSO

Section 3, "User defined hooks"

80. rtg4serdes - syntax

NAME

rtg4serdes - Print initialization sequence

SYNOPSIS

rtg4serdes *show* ?*serdes#*?

DESCRIPTION

rtg4serdes *show* ?*serdes#*?

Print initialization sequence

The RTG4 SERDES initcode is loaded into a procedure in the system shell. The procedure is executed in init level 6, therefore it is possible to override the script in level 5 by redefining the the ::serdes#::init procedure using the init# hook.

EXAMPLE

Override the default initialization

```
proc MyInit5 {} {
    proc ::serdes0::init {} {
        # Add custom initialization code here
    }
}
lappend ::hooks::init5 MyInit5
```

SEE ALSO

Section 3, "User defined hooks"

81. run - syntax

run - Reset and start execution

SYNOPSIS

run ?*options*? ?*address*? ?*count*?

DESCRIPTION

run ?*options*? ?*address*? ?*count*?

This command will reset all drivers (see **reset** for more information) and start the executing instructions on the active CPU. When omitting the address parameter this command will start execution at the entry point of the last loaded application. If the *count* parameter is set then the CPU will run the specified number of instructions. Note that the *count* parameter is only supported by the DSU4.

OPTIONS

-noret

Do not evaluate the return value. When this options is set, no return value will be set.

RETURN VALUE

Upon successful completion **run** returns a list of signals, one per CPU. Possible signal values are SIGBUS, SIGFPE, SIGILL, SIGINT, SIGSEGV, SIGTERM or SIGTRAP. If a CPU is disabled, then an empty string will be returned instead of a signal value.

EXAMPLE

Execute instructions starting at the entry point of the last loaded file.
```
grmon3> run
```

SEE ALSO

Section 3.4.3, "Running applications"
reset

82. scrub - syntax

scrub - Control memory scrubber

SYNOPSIS

scrub ?subcommand? ?args...?

DESCRIPTION

scrub
scrub status

Display status and configuration

scrub ack

Clear error and done status and display status

scrub clear *start stop* ?*value*?

Set scrubber to clear memory area from address *start* up to *stop*. The parameter *value* defaults to 0.

scrub patttern *word1* ?*word2 ...*?

Write pattern words into the scrubbers initialization register. If the number of words specified are larger then the size if the burst length, then the remaining words be ignored. If the number of words are less then the burst length, the pattern will be repeated up to a complete burst.

scrub init *start stop*

Initialize the memory area from address *start* up to *stop*.

scrub rst

Clear status and reset configuration.

EXAMPLE

Write pattern 0 1 to the memory 0x0000000 to 0x0000003F

```
grmon3> scrub pattern 0 1
grmon3> scrub init 0 63
```

Clear a memory area
```
grmon3> scrub clear 0 63
```

83. sdcfg1 - syntax

sdcfg1 - Show or set reset value of SDRAM controller register 1

SYNOPSIS

sdcfg1 ?*value*?

DESCRIPTION

   sdcfg1 ?*value*?

      Set the reset value of the memory register. If value is left out, then the reset value will be printed.

SEE ALSO

Section 6.14, "Memory controllers "

84. sddel - syntax

sddel - Show or set the SDCLK delay

SYNOPSIS

sddel ?*value*?

DESCRIPTION

   sddel ?*value*?

      Set the SDCLK delay value.

SEE ALSO

Section 6.14, "Memory controllers "

85. sf2mddr - syntax

NAME

sf2mddr - Print initialization sequence

SYNOPSIS

sf2mddr *show ?mddr#?*

DESCRIPTION

sf2mddr *show ?mddr#?*

Print initialization sequence

The IGLOO2/SmartFusion2 DDR initcode is loaded into a procedure in the system shell. The procedure is executed in init level 6, therefore it is possible to override the script in level 5 by redefining the the ::mddr#::init procedure using the init# hook.

EXAMPLE

Override the default initialization

```
proc MyInit5 {} {
    proc ::mddr0::init {} {
        # Add custom initialization code here
    }
}
lappend ::hooks::init5 MyInit5
```

SEE ALSO

Section 3, "User defined hooks"

86. sf2serdes - syntax

NAME

sf2serdes - Print initialization sequence

SYNOPSIS

sf2serdes *show* ?*serdes#*?

DESCRIPTION

> **sf2serdes** *show* ?*serdes#*?
>
> > Print initialization sequence
> >
> > The IGLOO2/SmartFusion2 SERDES initcode is loaded into a procedure in the system shell. The procedure is executed in init level 6, therefore it is possible to override the script in level 5 by redefining the the ::serdes#::init procedure using the init# hook.

EXAMPLE

Override the default initialization

```
proc MyInit5 {} {
    proc ::serdes0::init {} {
        # Add custom initialization code here
    }
}
lappend ::hooks::init5 MyInit5
```

SEE ALSO

Section 3, "User defined hooks"

87. shell - syntax

NAME

shell - Execute a shell command

SYNOPSIS

shell

DESCRIPTION

shell

Execute a command in the host system shell. The grmon **shell** command is just an alias for the TCL command exec, wrapped with puts, i.e. its equivalent to `puts [exec ...]`. For more information see documentation about the exec command (http://www.tcl.tk/man/tcl8.6/TclCmd/exec.htm).

EXAMPLE

List all files in the current working directory (Linux)
```
grmon3> shell ls
```

List all files in the current working directory (Windows)
```
grmon3> shell dir
```

88. silent - syntax

NAME

silent - Suppress stdout of a command

SYNOPSIS

silent *command* ?*args...*?

DESCRIPTION

silent *command* ?*args...*?

The silent command be put in front of other GRMON commands to suppress their output and it will not be logged. This can be useful to remove unnecessary output when scripting.

EXAMPLE

Suppress the memory print and print the TCL result instead.
```
grmon3> puts [silent mem 0x40000000]
```

SEE ALSO

Section 2, "Variables"

89. spim - syntax

NAME

spim - Commands for the SPI memory controller

SYNOPSIS

spim *subcommand* ?*args...*?
spim *index subcommand* ?*args...*?

DESCRIPTION

This command provides functions to control the SPICTRL core. If more than one core exists in the system, then the index of the core to control should be specified after the **spim** command (before the subcommand). The '`info sys`' command lists the device indexes.

    spim altscaler

        Toggle the usage of alternate scaler to enable or disable.

    spim reset

        Core reset

    spim status

        Displays core status information

    spim tx *data*

        Shift a byte to the memory device

SD Card specific commands:

    spim sd csd

        Displays and decodes CSD register

    spim sd reinit

        Reinitialize card

SPI Flash commands:

    spim flash

        Prints a list of available commands

    spim flash help

        Displays command list or additional information about a specific command.

    spim flash detect

        Try to detect type of memory device

    spim flash dump *address length* ?*filename*?

        Dumps *length* bytes, starting at *address* of the SPI-device (i.e. not AMBA address), to a file. The default name of the file is "grmon-spiflash-dump.srec"

    spim flash erase
    spim flash erase *start* ?*stop*?

        Erase performs a bulk erase clearing the whole device or the blocks from address *start* to address *stop*.

    spim flash fast

        Enables or disables FAST READ command (memory device may not support this).

spim flash load ?`options...`? `filename` ?`address`? ?`cpu#`?

> Loads the contents in the file `filename` to the memory device. If the `address` is present, then binary files will be stored at the `address` of the SPI-device (i.e. not AMBA address), otherwise binary files will be written to the beginning of the device. The `cpu#` argument can be used to specify which CPU it belongs to.

> The only available option is '-binary', which forces GRMON to interpret the file as binary file.

spim flash select ?`index`?

> Select memory device. If `index` is not specified, a list of the supported devices is displayed.

spim flash set `pagesize address_bytes wren wrdi rdsr wrsr read fast_read pp se be bebytes` { `secount0 sebytes0` ?`secount1 sebytes1` ...? }

> Sets a custom memory device configuration.

`pagesize`	Page size
`address_bytes`	Number of ytes in address
`wren`	Write enable command
`wrdi`	Write disable command
`rdsr`	Read status register command
`wrsr`	Write status register command
`read`	Read data bytes command
`fast_read`	Fast read data bytes command
`pp`	Page programming command
`se`	Sector erase command
`be`	Bulk/Die erase command
`bebytes`	Number of bulk/die erase commnad bytes
`secount`	Number of sectors
`sebytes`	Number of bytes per sector

> Up to 4 secount/sebytes pairs can be added. They are used with the se command to erase a single sector. If sector erase is not supported, then add one pair with secount = 1 and sebytes = size of memory.

> Issue **spim flash show** to see a list of the available parameters.

spim flash show

> Shows current memory device configuration

spim flash ssval ?`value`?

> Sets slave value to be used with the SPICTRL core. When GRMON wants to select the memory device it will write this value to the slave select register. When the device is deselected, GRMON will write all ones to the slave select register. Example: Set slave select line 0 to low, all other lines high when selecting a device
> ```
> grmon3> spi flash ssval 0xfffffffe
> ```

> Note: This value is not used when communicating via the SPIMCTRL core, i.e. it is only valid for **spi flash**.

spim flash status

> Displays device specific information

spim flash strict ?`boolean`?

> Enable/Disable strict communication mode. Enable if programming fails. Strict communication mode may be necessary when using very fast debug links or for SPI implementations with a slow SPI clock

spim flash verify ?*options...*? *filename* ?*address*?

Verifies that data in the file *filename* matches data in memory device. If the *address* is present, then binary files will be compared with data at the *address* of the SPI-device (i.e. not AMBA address), otherwise binary files will be compared against data at the beginning of the device.

The `-binary` options forces GRMON to interpret the file as binary file.

The `-erase` option to automatically erase the flash before writing. It will only erase the sectors where data will be written.

The `-max` option can be used to force GRMON to stop verifying when num errors have been found.

When the `-errors` option is specified, the verify returns a list of all errors instead of number of errors. Each element of the list is a sublist whose format depends on the first item if the sublist. Possible errors can be detected are memory verify error (MEM), read error (READ) or an unknown error (UNKNOWN). The formats of the sublists are: MEM *address read-value expected-value* , READ *address num-failed-addresses* , UNKNOWN *address*

Upon successful completion **spim flash verify** returns the number of error detected. If the `-errors` has been given, it returns a list of errors instead.

spim flash wrdi
spim flash wren

Issue write disable/enable instruction to the device.

SEE ALSO

Section 3.11.2, "SPI memory device"
Section 6.14, "Memory controllers "

90. spi - syntax

NAME

spi - Commands for the SPI controller

SYNOPSIS

spi *subcommand* ?*args...*?
spi *index subcommand* ?*args...*?

DESCRIPTION

This command provides functions to control the SPICTRL core. If more than one core exists in the system, then the index of the core to control should be specified after the **spi** command (before the subcommand). The 'info sys' command lists the device indexes.

spi aslvsel *value*

> Set automatic slave select register

spi disable
spi enable

> Enable/Disable core

spi rx

> Read receive register

spi selftest

> Test core in loop mode

spi set ?*field ...*?

> Sets specified field(s) in Mode register.

> Available fields: cpol, cpha, div16, len *value*, amen, loop, ms, pm *value*, tw, asel, fact, od, tac, rev, aseldel *value*, tto, igsel, cite

spi slvsel *value*

> Set slave select register

spi status

> Displays core status information

spi tx *data*

> Writes data to transmit register. GRMON automatically aligns the data

spi unset ?*field ...*?

> Sets specified field(s) in Mode register.

> Available fields: cpol, cpha, div16, amen, loop, ms, tw, asel, fact, od, tac, rev, tto, igsel, cite

Commands for automated transfers:

spi am cfg ?*option ...*?

> Set AM configuration register.

> Available fields: seq, strict, ovtb, ovdb

spi am per *value*

> Set AM period register to *value*.

spi am act
spi am deact

>   Start/stop automated transfers.

spi am extact

>   Enable external activation of AM transfers

spi am poll `count`

>   Poll for `count` transfers

SPI Flash commands:

spi flash

>   Prints a list of available commands

spi flash help

>   Displays command list or additional information about a specific command.

spi flash detect

>   Try to detect type of memory device

spi flash dump `address length` ?`filename`?

>   Dumps `length` bytes, starting at `address` of the SPI-device (i.e. not AMBA address), to a file. The default name of the file is "grmon-spiflash-dump.srec"

spi flash erase
spi flash erase `start` ?`stop`?

>   Erase performs a bulk erase clearing the whole device or the blocks from address `start` to address `stop`.

spi flash fast

>   Enables or disables FAST READ command (memory device may not support this).

spi flash load ?`options...`? `filename` ?`address`? ?`cpu#`?

>   Loads the contents in the file `filename` to the memory device. If the `address` is present, then binary files will be stored at the `address` of the SPI-device (i.e. not AMBA address), otherwise binary files will be written to the beginning of the device. The `cpu#` argument can be used to specify which CPU it belongs to.

>   The option `-binary` forces GRMON to interpret the file as binary file.

>   Use the `-erase` option to automatically erase the flash before writing. It will only erase the sectors where data will be written.

spi flash select ?`index`?

>   Select memory device. If `index` is not specified, a list of the supported devices is displayed.

spi flash set `pagesize address_bytes wren wrdi rdsr wrsr read fast_read pp se be be-bytes` { `secount0 sebytes0` ?`secount1 sebytes1` ...? }

>   Sets a custom memory device configuration.

`pagesize`	Page size
`address_bytes`	Number of ytes in address
`wren`	Write enable command
`wrdi`	Write disable command
`rdsr`	Read status register command
`wrsr`	Write status register command
`read`	Read data bytes command

`fast_read`	Fast read data bytes command
`pp`	Page programming command
`se`	Sector erase command
`be`	Bulk/Die erase command
`bebytes`	Number of bulk/die erase commnad bytes
`secount`	Number of sectors
`sebytes`	Number of bytes per sector

Up to 4 secount/sebytes pairs can be added. They are used with the se command to erase a single sector. If sector erase is not supported, then add one pair with secount = 1 and sebytes = size of memory.

Issue **spi flash show** to see a list of the available parameters.

spi flash show

Shows current memory device configuration

spi flash ssval ?`value`?

Sets slave value to be used with the SPICTRL core. When GRMON wants to select the memory device it will write this value to the slave select register. When the device is deselected, GRMON will write all ones to the slave select register. Example: Set slave select line 0 to low, all other lines high when selecting a device

```
grmon3> spi flash ssval 0xfffffffe
```

Note: This value is not used when communicating via the SPIMCTRL core, i.e. it is only valid for **spi flash**.

spi flash status

Displays device specific information

spi flash strict ?`boolean`?

Enable/Disable strict communication mode. Enable if programming fails. Strict communication mode may be necessary when using very fast debug links or for SPI implementations with a slow SPI clock

spi flash verify ?`options...`? `filename` ?`address`?

Verifies that data in the file `filename` matches data in memory device. If the `address` is present, then binary files will be compared with data at the `address` of the SPI-device (i.e. not AMBA address), otherwise binary files will be compared against data at the beginning of the device.

The `-binary` option forces GRMON to interpret the file as binary file.

The `-max` option can be used to force GRMON to stop verifying when num errors have been found.

When the `-errors` option is specified, the verify returns a list of all errors instead of number of errors. Each element of the list is a sublist whose format depends on the first item if the sublist. Possible errors can be detected are memory verify error (MEM), read error (READ) or an unknown error (UNKNOWN). The formats of the sublists are: MEM `address read-value expected-value`, READ `address num-failed-addresses`, UNKNOWN `address`

Upon successful completion **spi flash verify** returns the number of error detected. If the `-errors` has been given, it returns a list of errors instead.

spi flash wrdi
spi flash wren

Issue write disable/enable instruction to the device.

EXAMPLE

Set AM configuration register
```
grmon3> spi am cfg strict ovdb
```

Set AM period register
```
grmon3> spi am per 1000
```

Poll queue 10 times
```
grmon3> spi am poll 10
```

Set fields in Mode register
```
grmon3> spi set ms cpha len 7 rev
```

Unset fields in Mode register
```
grmon3> spi unset ms cpha rev
```

SEE ALSO

Section 3.11.2, "SPI memory device"
Section 6.14, "Memory controllers "

91. spwrtr - syntax

NAME

spwrtr - SpaceWire router information

SYNOPSIS

spwrtr info *?port? ?spwrtr#?*
spwrtr rt *?options? ?port? ?endport? ?spwrtr#?*
spwrtr rt add *?options? port ?dst...? ?spwrtr#?*
spwrtr rt remove *?options? port ?dst...? ?spwrtr#?*

DESCRIPTION

spwrtr info *?port? ?spwrtr#?*

Print register information for the router or a single port.

spwrtr rt *?options? ?port? ?endport? ?spwrtr#?*

Print the routing table. A single port or a range of ports can be specified, otherwise all ports will be printed.

Options `-physical` or `-logical` can be used to filter out ports.

Options `-nh` can be used to suppress the printing of the header.

spwrtr rt add *?options? port ?dst...? ?spwrtr#?*

Enable one more destination ports to the routing table.

Options `-en`, `-hd`, `-pr`, `-sr` and `-pd` can be used to set the corresponding bits. If no destination port has been specified, the option flags will still set the corresponding bits.

spwrtr rt remove *?options? port ?dst...? ?spwrtr#?*

Disable one more destination ports to the routing table.

Options `-en`, `-hd`, `-pr`, `-sr` and `-pd` can be used to unset the corresponding bits. If no destination port has been specified, the option flags will still unset the corresponding bits.

RETURN VALUE

Command **spwrtr** has no return value.

SEE ALSO

Section 6.19, "SpaceWire router"

92. stack - syntax

NAME

stack - Set or show the initial stack-pointer.

SYNOPSIS

stack ?*cpu#*?
stack *address* ?*cpu#*?

DESCRIPTION

stack ?*cpu#*?

Show current active CPUs initial stack-pointer, or the CPU specified by cpu#.

stack *address* ?*cpu#*?

Set the current active CPUs initial stack-pointer, or the CPU specified by cpu#.

RETURN VALUE

Upon successful completion **stack** returns a list of initial stack-pointer addresses, one per CPU.

EXAMPLE

Set current active CPUs initial stack-pointer to 0x4FFFFFF0
```
grmon3> stack 0x4FFFFFF0
```

SEE ALSO

Section 6.3.1, "Switches"
Section 3.4.13, "Multi-processor support"

93. step - syntax

step - Step one ore more instructions

SYNOPSIS

step ?*nsteps*? ?*cpu#*?

DESCRIPTION

step ?*nsteps*? ?*cpu#*?

Step one or more instructions on all CPU:s. If *cpu#* is set, then only the specified CPU index will be stepped.

When single-stepping over a conditional or unconditional branch with the annul bit set, and if the delay instruction is effectively annulled, the delay instruction itself and the instruction thereafter are stepped over in the same go. That means that three instructions are executed by one single step command in this particular case.

EXAMPLE

Step 10 instructions
```
grmon3> step 10
```

94. stop - syntax

stop - Interrupt current CPU execution

SYNOPSIS

stop ?*-nowait*?

DESCRIPTION

> **stop** ?*-nowait*?

>> This command will interrupt the CPU execution initiated by another shell or by the graphical user interface. If the CPU is not currently executing the command will be ignored. By default **stop** will block until the CPU execution has stopped and it is safe to access CPU registers immediately after.

>> If *-nowait* option is given the command will not block until the CPU execution stop request has been completed. Instead the command will return immediately and accessing CPU registers afterwards might result in "CPU not in debug mode" messages a short time while GRMON stops the on-going CPU execution.

EXAMPLE

Block until on-going CPU execution has been interrupted and then read the registers of CPU0 safely.
```
grmon> stop; reg cpu0
```

Attempt to interrupt on-going CPU execution if started by another shell or GUI without blocking:
```
grmon> stop -nowait
```

95. svga - syntax

NAME

svga - Commands for the SVGA controller

SYNOPSIS

svga *subcommand* ?*args...*?
svga *index subcommand* ?*args...*?

DESCRIPTION

This command provides functions to control the SVGACTRL core. If more than one core exists in the system, then the index of the core to control should be specified after the **svga** command (before the subcommand). The 'info sys' command lists the device indexes.

> **svga custom** ?*period horizontal_active_video horizontal_front_porch horizontal_sync horizontal_back_porch vertical_active_video vertical_front_porch vertical_sync vertical_back_porch*?

> The **svga custom** command can be used to specify a custom format. The custom format will have precedence when using the **svga draw** command. If no parameters are given, then is will print the current custom format.

> **svga draw** *file bitdepth*

> The **svga draw** command will determine the resolution of the specified picture and select an appropriate format (resolution and refresh rate) based on the video clocks available to the core. The required file format is ASCII PPM which must have a suitable amount of pixels. For instance, to draw a screen with resolution 640x480, a PPM file which is 640 pixels wide and 480 pixels high must be used. ASCII PPM files can be created with, for instance, the GNU Image Manipulation Program (The GIMP). The color depth can be either 16 or 32 bits.

> **svga draw test_screen** *fmt bitdepth*

> The **svga draw test_screen** command will show a simple grid in the resolution specified via the format *fmt* selection (see **svga formats** to list all available formats). The color depth can be either 16 or 32 bits.

> **svga frame** ?*address*?

> Show or set start address of framebuffer memory

> **svga formats**

> Show available display formats

> **svga formatsdetailed**

> Show detailed view of available display formats

EXAMPLE

Draw a 1024x768, 60Hz test image
```
grmon3> svga draw test_screen 12 32
```

96. symbols - syntax

NAME

symbols - Load, print or lookup symbols

SYNOPSIS

symbols ?*options*? *filename* ?*cpu#*?
symbols *subcommand* ?*arg*?

DESCRIPTION

The symbols command is used to load symbols from an object file. It can also be used to print all loaded symbols or to lookup the address of a specified symbol.

> **symbols** ?*options*? *filename* ?*cpu#*?
>
> Load the symbols from *filename*. If cpu# argument is omitted, then the symbols will be associated with the active CPU.
>
> Options:
> `-debug`
>
> Read in DWARF debug information

symbols clear ?*cpu#*?

> Remove all symbols associated with the active CPU or a specific CPU.

symbols list ?*options*? ?*cpu#*?

> This command lists loaded symbols. If no options are given, then all local and global functions and objects are listed. The optional argument cpu# can be used to limit the listing for a specific CPU.
>
> Options:
> `-global`
>
> List global symbols
> `-local`
>
> List local symbols
> `-func`
>
> List functions
> `-object`
>
> List objects
> `-all`
>
> List all symbols

symbols lookup *symbol* ?*cpu#*?

> Lookup the address of the specified symbol using the symbol table of the active CPU. If cpu# is specified, then it will only look in the symbol table associated with that CPU.

symbols lookup *address* ?*cpu#*?

> Lookup symbol for the specified address using the symbol table of the active CPU. If cpu# is specified, then it will only look in the symbol table associated with that CPU. At most one symbol is looked up.

RETURN VALUE

Upon successful completion **symbols list** will return a list of all symbols and their attributes.

Nothing will be returned when loading or clearing.

Command **symbols lookup** will return the corresponding address or symbol.

EXAMPLE

Load the symbols in the file `hello`.
```
grmon3> symbols hello
```

List symbols.
```
grmon3> symbols list
```

List all loaded symbols.
```
grmon3> symbols list -all
```

List all function symbols.
```
grmon3> symbols list -func -local -global
```

List all symbols that begins with the letter m
```
grmon3> puts [lsearch -index {3} -subindices -all -inline [symbols list] m*]
```

SEE ALSO

Section 3.6, "Symbolic debug information"

NAME

thread - Show OS-threads information or backtrace

SYNOPSIS

thread info ?*cpu#*?
thread bt *id* ?*cpu#*?

DESCRIPTION

The thread command may be used to list all threads or to show backtrace of a specified thread. Note that the only OS:s supported by GRMON are RTEMS, eCos and VxWorks.

The thread command tries to auto-detect the running OS on the target. If this mechanism doesn't work it is possible to force which OS thread backend to use by command line options to GRMON. For more information see for example the -rtems, -bmnothreads and -nothreads options.

    thread info ?*cpu#*?

        List information about the threads. This should be used to get the id:s for the **thread bt** command.

    thread bt *id* ?*cpu#*?

        Show backtrace of the thread specified by *id*. The command **thread info** can be used find the available id:s.

RETURN VALUE

Upon successful completion, **thread info** returns a list of threads. Each entry is a sublist on the format format: {*id name current pc sp* }. See table below for a detailed description.

Name	Description
id	OS specific identification number
name	Name of the thread
current	Boolean describing if the thread is the current running thread.
pc	Program counter
sp	Stack pointer
cpu	Value greater or equal to 0 means that the thread is executing on CPU. Negative value indicates that the thread is idle.

The **thread current** command returns information about the current thread only, using the format described for the return value of the command **thread info** above.

The other subcommands have no return value.

EXAMPLE

List all threads

```
grmon3> thread info
    NAME   TYPE      ID          PRIO  TIME (h:m:s)      ENTRY POINT             PC                ...
  * Int.   internal  0x09010001   255  0:0:0.000000000                           0x4000a5b4 <+0xFFF...
    TA1    classic   0x0a010002     1  0:0:0.064709999   Test_task               0x40016ab8 <_Threa...
    TA2    classic   0x0a010003     1  0:0:0.061212000   Test_task               0x40016ab8 <_Threa...
    TA3    classic   0x0a010004     1  0:0:0.060206998   Test_task               0x40016ab8 <_Threa...
```

TCL returns:
{151060481 Int. 1 1073784244 0} {167837698 {TA1 } 0 1073834680 0} {167837699 {TA2 } 0 1073834680 0} {167837700 {TA3 } 0 1073834680 0}

SEE ALSO

Section 3.8, "Thread support"
Section 3.8.1, "GRMON thread options"
Section 3.7.6, "GDB Thread support"

98. timer - syntax

timer - Show information about the timer devices

SYNOPSIS

timer ?*devname*?
timer reg ?*devname*?

DESCRIPTION

timer ?*devname*?

This command will show information about the timer device. Optionally which device to show information about can be specified. Device names are listed in 'info sys'.

timer reg ?*devname*?

This command will get the timers register. Optionally which device to get can be specified. Device names are listed in 'info sys'.

EXAMPLE

Execute instructions starting at 0x40000000.
```
grmon3> timer 0x40000000
```

99. tmode - syntax

tmode - Select tracing mode between none, processor-only, AHB only or both.

SYNOPSIS

tmode
tmode none
tmode both
tmode ahb *boolean*
tmode proc ?*boolean*? ?*cpu#*?

DESCRIPTION

> **tmode**
>
> > Print the current tracing mode
>
> **tmode none**
>
> > Disable tracing
>
> **tmode both**
>
> > Enable both AHB and instruction tracing
>
> **tmode ahb** ?*boolean*?
>
> > Enable or disable AHB transfer tracing
>
> **tmode proc** ?*boolean*? ?*cpu#*?
>
> > Enable or disable instruction tracing. Use cpu# to toggle a single CPU.

EXAMPLE

Disable AHB transfer tracing
```
grmon3> tmode ahb disable
```

SEE ALSO

Section 3.4.9, "Using the trace buffer"

100. tps - syntax

tps - Control the TPS service

SYNOPSIS

tps *?port? ?address?*
tps stop
tps status

DESCRIPTION

The **tps** command allows the VxWorks 7 workbench to use the active debug link to debug applications. This removes the need for hardware Ethernet support.

It implements the host side of a virtual interface that only uses memory reads/writes over the debug link for communication. Instead of connecting directly to the target, the workbench needs to connect to GRMON using the port specified when issuing the **tps** command.

See the "*LEON Architectural Support for VxWorks 7*" manual for information on how to configure the target side support.

> **tps** *?port? ?address?*
>
> Start the TPS service. The default port used is 5780 and the default address is taken from the symbol TPS_DRIVER_REGS if provided by the application. If the TPS service is already started the command will print the current status.

> **tps stop**
>
> Stop the TPS service.

> **tps status**
>
> Print status.

RETURN VALUE

The command **tps** returns a tuple with the port and address used.

101. uhci - syntax

NAME

uhci - Control the USB host's UHCI core

SYNOPSIS

uhci subcommand ?*args...*?

DESCRIPTION

uhci endian ?*devname*?

Displays the endian conversion setting

uhci opregs ?*devname*?

Displays contents of the I/O registers

uhci reset ?*devname*?

Performs a Host Controller Reset

RETURN VALUE

Upon successful completion, **uhci** have no return value.

SEE ALSO

Section 6.6, "USB Host Controller"

102. usrsh - syntax

NAME

usrsh - Run commands in threaded user shell

SYNOPSIS

usrsh
usrsh *subcommand* ?*arg*?

DESCRIPTION

The usrsh command is used to create custom user shells. Each custom shell has an associated Tcl interpreter running in a separate thread. Log output from a custom user shell is prefix with its name (see description of the `-log` option in Section 3.2.3, "General options").

usrsh
usrsh list

> List all custom user shells.

usrsh add *name*

> Create a user shell named *name*. The name is used as an identifier for the shell when using other **usrsh** commands.

usrsh delete *name*

> Delete user shell *name*.

usrsh eval ?`-bg`? ?`-std`? *name arg* ?*arg ...*?

> Evaluate command *arg* in the user shell identified as *name*. If a script is running, then the command will fail with the error code set to EBUSY.

> If the option `-bg` is set, then the script will be evaluated in the background, and GRMON will return to the prompt.

> If the option `-std`, in combination with option `-bg`, then output from the background operation will be forwarded to the current shells stdout.

usrsh result *name*

> Retrieve the result from the last evaluation. If a script is running, then the command will fail with the error code set to EBUSY.

RETURN VALUE

Upon successful completion **usrsh list** will return a list of all custom user shells.

usrsh eval will return the result from the script. If the option `-bg` then nothing will be returned. Instead the **usrsh result** will return the result when the script is finished.

EXAMPLE

Create a user shell named `myshell` and evaluate a command in it.

```
grmon3> usrsh add myshell
  Added user shell: myshell

grmon3> usrsh eval myshell puts "Hello World!"
  Hello World!
```

Evaluate command in user shell named `myshell` in the background and wait for it to finish.

```
grmon3> usrsh eval -bg myshell {after 2000; expr 1+1}
```

```
grmon3> while {[catch {usrsh result myshell}] && $errorCode == "EBUSY"} {puts "waiting"; after 1000}
  waiting
  waiting

grmon3> puts [usrsh result myshell]
  2
```

SEE ALSO

Section 3.5, "Tcl integration"

103. va - syntax

NAME

va - Translate a virtual address

SYNOPSIS

va *address* ?*cpu#*?

DESCRIPTION

> **va** *address* ?*cpu#*?
>
>> Translate a virtual address. The command will use the MMU from the current active CPU and the cpu# can be used to select a different CPU.

RETURN VALUE

Command **va** returns the translated address.

SEE ALSO

Section 3.4.15, "Memory Management Unit (MMU) support"

104. verify - syntax

NAME

verify - Verify that a file has been uploaded correctly.

SYNOPSIS

verify ?`options...`? `filename` ?`address`?

DESCRIPTION

verify ?`options...`? `filename` ?`address`?

Verify that the file `filename` has been uploaded correctly. If the `address` argument is present, then binary files will be compared against data at this address, if left out then they will be compared to data at the base address of the detected RAM.

RETURN VALUE

Upon successful completion **verify** returns the number of error detected. If the `-errors` has been given, it returns a list of errors instead.

OPTIONS

`-binary`

The `-binary` option can be used to force GRMON to interpret the file as a binary file.

`-max` *num*

The `-max` option can be used to force GRMON to stop verifying when num errors have been found.

`-bsize` bytes

The `-bsize` option may be used to specify the size of blocks of data in bytes that will be read. Sizes that are not even words may require a JTAG based debug link to work properly. See Chapter 5, *Debug link* more information.

`-errors`

When the `-errors` option is specified, the verify returns a list of all errors instead of number of errors. Each element of the list is a sublist whose format depends on the first item if the sublist. Possible errors can be detected are memory verify error (MEM), read error (READ) or an unknown error (UNKNOWN). The formats of the sublists are: MEM `address read-value expected-value`, READ `address num-failed-addresses`, UNKNOWN `address`

EXAMPLE

Load and then verify a hello_world application

```
grmon3> load ../hello_world/hello_world
grmon3> verify ../hello_world/hello_world
```

SEE ALSO

Section 3.4.2, "Uploading application and data to target memory"
bload
eeload
load

105. vmemb - syntax

NAME

vmemb - AMBA bus 8-bit virtual memory read access, list a range of addresses

SYNOPSIS

vmemb ?`-ascii`? `address` ?`length`?

DESCRIPTION

vmemb ?`-ascii`? `address` ?`length`?

> GRMON will translate `address` to a physical address, do an AMBA bus read 8-bit read access and print the data. The optional length parameter should specified in bytes and the default size is 64 bytes. If no MMU exists or if it is turned off, this command will behave like the command **vwmemb**

> Only JTAG debug links supports byte accesses. Other debug links will do a 32-bit read and then parse out the unaligned data.

OPTIONS

`-ascii`

> If the `-ascii` flag has been given, then a single ASCII string is returned instead of a list of values.

`-cstr`

> If the `-cstr` flag has been given, then a single ASCII string, up to the first null character, is returned instead of a list of values.

RETURN VALUE

Upon successful completion **vmemb** returns a list of the requested 8-bit words. Some options changes the result value, see options for more information.

EXAMPLE

Read 4 bytes from address 0x40000000:
```
grmon3> vmemb 0x40000000 4
```

TCL returns:
```
64 0 0 0
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"
Section 3.4.15, "Memory Management Unit (MMU) support"

106. vmemd - syntax

NAME

vmemd - AMBA bus 64-bit virtual memory read access, list a range of addresses

SYNOPSIS

vmemd ?*-ascii*? *address* ?*length*?

DESCRIPTION

vmemd ?*-ascii*? *address* ?*length*?

GRMON will translate *address* to a physical address, do an AMBA bus read access and print the data as 64-bit words. The optional length parameter should specified in bytes and the default size is 64 bytes (8 words).

OPTIONS

-ascii

If the *-ascii* flag has been given, then a single ASCII string is returned instead of a list of values.

-cstr

If the *-cstr* flag has been given, then a single ASCII string, up to the first null character, is returned instead of a list of values.

RETURN VALUE

Upon successful completion **vmemd** returns a list of the requested 64-bit words. Some options changes the result value, see options for more information.

EXAMPLE

Read 2 64-bit words (16 bytes) from address 0xfffffe000000000:
```
grmon3> vmemd 0xfffffe000000000 16
```

TCL returns:
```
0xffff1244901022 0x543348
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"
Section 3.4.15, "Memory Management Unit (MMU) support"

107. vmemh - syntax

NAME

vmemh - AMBA bus 16-bit virtual memory read access, list a range of addresses

SYNOPSIS

vmemh ?`-ascii`? `address` ?`length`?

DESCRIPTION

    vmemh ?`-ascii`? `address` ?`length`?

> GRMON will translate `address` to a physical address, do an AMBA bus read 16-bit read access and print the data. The optional length parameter should specified in bytes and the default size is 64 bytes (32 words). If no MMU exists or if it is turned off, this command will behave like the command **vwmemh**

> Only JTAG debug links supports byte accesses. Other debug links will do a 32-bit read and then parse out the unaligned data.

OPTIONS

    `-ascii`

> If the `-ascii` flag has been given, then a single ASCII string is returned instead of a list of values.

    `-cstr`

> If the `-cstr` flag has been given, then a single ASCII string, up to the first null character, is returned instead of a list of values.

RETURN VALUE

Upon successful completion **vmemh** returns a list of the requested 16-bit words. Some options changes the result value, see options for more information.

EXAMPLE

Read 4 words (8 bytes) from address 0x40000000:
```
grmon3> vmemh 0x40000000 8
```

TCL returns:
```
16384 0 0 0
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"
Section 3.4.15, "Memory Management Unit (MMU) support"

108. vmem - syntax

NAME

vmem - AMBA bus 32-bit virtual memory read access, list a range of addresses

SYNOPSIS

vmem ?`-ascii`? `address` ?`length`?

DESCRIPTION

vmem ?`-ascii`? `address` ?`length`?

GRMON will translate `address` to a physical address, do an AMBA bus read 32-bit read access and print the data. The optional length parameter should specified in bytes and the default size is 64 bytes (16 words). If no MMU exists or if it is turned off, this command will behave like the command **vwmem**

OPTIONS

`-ascii`

If the `-ascii` flag has been given, then a single ASCII string is returned instead of a list of values.

`-cstr`

If the `-cstr` flag has been given, then a single ASCII string, up to the first null character, is returned instead of a list of values.

RETURN VALUE

Upon successful completion **vmem** returns a list of the requested 32-bit words. Some options changes the result value, see options for more information.

EXAMPLE

Read 4 words from address 0x40000000:
```
grmon3> vmem 0x40000000 16
```

TCL returns:
```
1073741824 0 0 0
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"
Section 3.4.15, "Memory Management Unit (MMU) support"

109. vwmemb - syntax

NAME

vwmemb - AMBA bus 8-bit virtual memory write access

SYNOPSIS

vwmemb ?*options...*? *address data* ?*...*?

DESCRIPTION

vwmemb ?*options...*? *address data* ?*...*?

Do an AMBA write access. GRMON will translate *address* to a physical address and write the 8-bit value specified by *data*. If more than one data word has been specified, they will be stored at consecutive physical addresses. If no MMU exists or if it is turned off, this command will behave like the command **vwmemb**

Only JTAG debug links supports byte accesses. Other debug links will do a 32-bit read-modify-write when writing unaligned data.

OPTIONS

-bsize bytes

The -*bsize* option may be used to specify the size blocks of data in bytes that will be written.

-wprot

Disable memory controller write protection during the write.

RETURN VALUE

vwmemb has no return value.

EXAMPLE

Write 0xAB to address 0x40000000 and 0xCD to 0x40000004:
```
grmon3> vwmemb 0x40000000 0xAB 0xCD
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"
Section 3.4.15, "Memory Management Unit (MMU) support"

110. vwmemd - syntax

NAME

vwmemd - AMBA bus 64-bit virtual memory write access

SYNOPSIS

vwmemd ?*options...*? *address data* ?*...*?

DESCRIPTION

vwmemd ?*options...*? *address data* ?*...*?

Do an AMBA write access. GRMON will translate *address* to a physical address and write the 64-bit value specified by *data*. If more than one data word has been specified, they will be stored at consecutive physical addresses.

OPTIONS

-bsize bytes

The *-bsize* option may be used to specify the size blocks of data in bytes that will be written.

-wprot

Disable memory controller write protection during the write.

RETURN VALUE

vwmemd has no return value.

EXAMPLE

Write 0xffff1244901022 to address 0xfffffe000000000 and 0x1234 to 0xfffffe000000008:
```
grmon3> vwmemd 0xfffffe000000000 0xffff1244901022 0x1234
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"
Section 3.4.15, "Memory Management Unit (MMU) support"

111. vwmemh - syntax

NAME

vwmemh - AMBA bus 16-bit virtual memory write access

SYNOPSIS

vwmemh ?*options...*? *address data* ?*...*?

DESCRIPTION

vwmemh ?*options...*? *address data* ?*...*?

Do an AMBA write access. GRMON will translate *address* to a physical address and write the 16-bit value specified by *data*. If more than one data word has been specified, they will be stored at consecutive physical addresses. If no MMU exists or if it is turned off, this command will behave like the command **vwmemh**

Only JTAG debug links supports byte accesses. Other debug links will do a 32-bit read-modify-write when writing unaligned data.

OPTIONS

-bsize bytes

The *-bsize* option may be used to specify the size blocks of data in bytes that will be written.

-wprot

Disable memory controller write protection during the write.

RETURN VALUE

vwmemh has no return value.

EXAMPLE

Write 0xABCD to address 0x40000000 and 0x1234 to 0x40000004:
```
grmon3> vwmemh 0x40000000 0xABCD 0x1234
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"
Section 3.4.15, "Memory Management Unit (MMU) support"

112. vwmems - syntax

NAME

vwmems - Write a string to an AMBA bus virtual memory address

SYNOPSIS

vwmems *address data*

DESCRIPTION

vwmems *address data*

Do an AMBA write access. GRMON will translate *address* to a physical address and write the string value specified by *data*, including the terminating NULL-character. If no MMU exists or if it is turned off, this command will behave like the command **vwmems**'

Only JTAG debug links supports byte accesses. Other debug links will do a 32-bit read-modify-write when writing unaligned data.

RETURN VALUE

vwmems has no return value.

EXAMPLE

Write "Hello World" to address 0x40000000-0x4000000C:
grmon3> vwmems 0x40000000 "Hello World"

SEE ALSO

Section 3.4.7, "Displaying memory contents"
Section 3.4.15, "Memory Management Unit (MMU) support"

113. vwmem - syntax

NAME

vwmem - AMBA bus 32-bit virtual memory write access

SYNOPSIS

vwmem ?*options...*? *address data* ?*...*?

DESCRIPTION

vwmem ?*options...*? *address data* ?*...*?

Do an AMBA write access. GRMON will translate *address* to a physical address and write the 32-bit value specified by *data*. If more than one data word has been specified, they will be stored at consecutive physical addresses. If no MMU exists or if it is turned off, this command will behave like the command **vwmem**

OPTIONS

-bsize bytes

The *-bsize* option may be used to specify the size blocks of data in bytes that will be written.

-wprot

Disable memory controller write protection during the write.

RETURN VALUE

vwmem has no return value.

EXAMPLE

Write 0xABCD1234 to address 0x40000000 and to 0x40000004:
```
grmon3> vwmem 0x40000000 0xABCD1234 0xABCD1234
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"
Section 3.4.15, "Memory Management Unit (MMU) support"

114. walk - syntax

NAME

walk - Translate a virtual address, print translation

SYNOPSIS

walk *address* ?*cpu#*?

DESCRIPTION

  walk *address* ?*cpu#*?

    Translate a virtual address and print translation. The command will use the MMU from the current active
    CPU and the cpu# can be used to select a different CPU.

RETURN VALUE

Command **walk** returns the translated address.

SEE ALSO

Section 3.4.15, "Memory Management Unit (MMU) support"

115. wash - syntax

wash - Clear memory or set all words in a memory range to a value.

SYNOPSIS

wash ?*options...*? ?*start stop*? ?*value*?

DESCRIPTION

wash ?*options...*?

Clear all memories.

wash ?*options...*? *start stop* ?*value*?

Wash the memory area from *start* up to *stop* and set each word to *value*. The parameter *value* defaults to 0.

OPTIONS

-delay ms

The -delay option can be used to specify a delay between each word written.

-nic

Disable the instruction cache while washing the memory

-nocpu

Do not use the CPU to increase performance.

-wprot

If the -wprot option is given then write protection on the memory will be disabled

EXAMPLE

Clear all memories
```
grmon3> wash
```

Set a memory area to 1
```
grmon3> wash 0x40000000 0x40000FFF 1
```

SEE ALSO

Section 3.10.1, "Using EDAC protected memory"

116. wmdio - syntax

NAME

wmdio - Set PHY registers

SYNOPSIS

wmdio *paddr raddr value* ?*greth#*?

DESCRIPTION

 wmdio *paddr raddr value* ?*greth#*?

 Set *value* of PHY address *paddr* and register *raddr*. If more than one device exists in the system, the *greth#* can be used to select device, default is greth0. The command tries to disable the EDCL duplex detection if enabled.

SEE ALSO

Section 6.4, "Ethernet controller"

117. wmemb - syntax

NAME

wmemb - AMBA bus 8-bit memory write access

SYNOPSIS

wmemb ?*options...*? *address data* ?*...*?

DESCRIPTION

wmemb ?*options...*? *address data* ?*...*?

Do an AMBA write access. The 8-bit value specified by *data* will be written to *address*. If more than one data word has been specified, they will be stored at consecutive addresses.

Only JTAG debug links supports byte accesses. Other debug links will do a 32-bit read-modify-write when writing unaligned data.

OPTIONS

-bsize bytes

The -*bsize* option may be used to specify the size blocks of data in bytes that will be written.

-wprot

Disable memory controller write protection during the write.

RETURN VALUE

wmemb has no return value.

EXAMPLE

Write 0xAB to address 0x40000000 and 0xBC to 0x40000001:
```
grmon3> wmemb 0x40000000 0xAB 0xBC
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"

118. wmemd - syntax

NAME

wmemd - AMBA bus 64-bit memory write access

SYNOPSIS

wmemd ?*options...*? *address data* ?*...*?

DESCRIPTION

wmemd ?*options...*? *address data* ?*...*?

Do an AMBA write access. The 64-bit value specified by *data* will be written to *address*. If more than one data word has been specified, they will be stored at consecutive addresses.

OPTIONS

-bsize bytes

The *-bsize* option may be used to specify the size blocks of data in bytes that will be written.

-wprot

Disable memory controller write protection during the write.

RETURN VALUE

wmemd has no return value.

EXAMPLE

Write 0xffff1244901022 to address 0x40000000 and 0x1234 to 0x40000008:
```
grmon3> wmemd 0x40000000 0xffff1244901022 0x1234
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"

119. wmemh - syntax

NAME

wmemh - AMBA bus 16-bit memory write access

SYNOPSIS

wmemh ?*options...*? *address data* ?*...*?

DESCRIPTION

wmemh ?*options...*? *address data* ?*...*?

Do an AMBA write access. The 16-bit value specified by *data* will be written to *address*. If more than one data word has been specified, they will be stored at consecutive addresses.

Only JTAG debug links supports byte accesses. Other debug links will do a 32-bit read-modify-write when writing unaligned data.

OPTIONS

-bsize bytes

The *-bsize* option may be used to specify the size blocks of data in bytes that will be written.

-wprot

Disable memory controller write protection during the write.

RETURN VALUE

wmemh has no return value.

EXAMPLE

Write 0xABCD to address 0x40000000 and 0x1234 to 0x40000002:
```
grmon3> wmem 0x40000000 0xABCD 0x1234
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"

120. wmems - syntax

NAME

wmems - Write a string to an AMBA bus memory address

SYNOPSIS

wmems *address data*

DESCRIPTION

wmems *address data*

Write the string value specified by *data*, including the terminating NULL-character, to *address*.

Only JTAG debug links supports byte accesses. Other debug links will do a 32-bit read-modify-write when writing unaligned data.

RETURN VALUE

wmems has no return value.

EXAMPLE

Write "Hello World" to address 0x40000000-0x4000000C:
```
grmon3> wmems 0x40000000 "Hello World"
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"

121. wmem - syntax

NAME

wmem - AMBA bus 32-bit memory write access

SYNOPSIS

wmem ?*options...*? *address data* ?*...*?

DESCRIPTION

  wmem ?*options...*? *address data* ?*...*?

Do an AMBA write access. The 32-bit value specified by *data* will be written to *address*. If more than one data word has been specified, they will be stored at consecutive addresses.

OPTIONS

  `-bsize` bytes

The `-bsize` option may be used to specify the size blocks of data in bytes that will be written.

  `-wprot`

Disable memory controller write protection during the write.

RETURN VALUE

wmem has no return value.

EXAMPLE

Write 0xABCD1234 to address 0x40000000 and to 0x40000004:
```
grmon3> wmem 0x40000000 0xABCD1234 0xABCD1234
```

SEE ALSO

Section 3.4.7, "Displaying memory contents"

Appendix C. Tcl API

GRMON will automatically load the scripts in GRMON `appdata` folder. On Linux the `appdata` folder is located in `~/.grmon-3.2/` and on Windows it's typically located at `C:\Users\%username%\AppData\Roaming\Cobham Gaisler\GRMON\3.2`. In the folder there are two different sub folders where scripts may be found, `<appdata>/scripts/sys` and `<appdata>/scripts/user`. Scripts located in the sys-folder will be loaded into the system shell only, before the Plug and Play area is scanned, i.e. drivers and fix-ups should be defined here. The scripts found in the user-folder will be loaded into all shells (including the system shell), i.e. all user defined commands and hooks should be defined there.

In addition there are two commandline switches `-udrv <filename>` and `-ucmd <filename>` to load scripts into the system shell or all shells.

TCL API switches:

`-udrv<filename>`
> Load script specified by filename into system shell. This option is mainly used for user defined drivers.

`-ucmd<filename>`
> Load script specified by filename into all shells, including the system shell. This option is mainly used for user defined procedures and hooks.

Also the TCL command **source** or GRMON command **batch** can be used to load a script into a single shell.

The variable TCL `grmon_shell` can be used to identify a shell. This can used to run shell specific code from a script is intended to be used in multiple shells. GRMON creates the following shells:

sys	System shell
exec	Execution shell
cli	Command line interface shell
term#	GUI terminal shell (# is replaced by a number)
gdb	GDB remote server shell

Example using shell name:

```
if {$grmon_shell == "cli"} {
  puts "Hello CLI!"
}
```

1. Device names

All GRLIB cores are assigned a unique `adevN` name, where N is a unique number. The debug driver controlling the core also provides an alias which is easier to remember. For example the name `mctrl0` will point to the first MCTRL regardless in which order the AMBA Plug and Play is assigned, thus the name will be consistent between different chips. The names of the cores are listed in the output of the GRMON command **info sys**.

PCI devices can also be registered into GRMON's device handling system using one of the **pci conf -reg**, **pci scan -reg** or **pci bus reg** commands. The devices are handled similar to GRLIB devices, however their base name is `pdevN`.

It is possible to specify one or more device names as an argument to the GRMON commands **info sys** and **info reg** to show information about those devices only. For **info reg** a register name can also be specified by appending the register name to the device name separated by colon. Register names are the same as described in Section 2, "Variables".

For each device in a GRLIB system, a namespace will be created. The name of the namespace will be the same as the name of the device. Inside the namespace Plug and Play information is available as variables. Most debug drivers also provide direct access to APB or AHB registers through variables in the namespace. See Section 2, "Variables" for more details about variables.

Below is an example of how the first MCTRL is named and how the APB register base address is found using Plug and Play information from the GRMON `mctrl0` variable. The eleventh PCI device (a network card) is also listed using the unique name `pdev10`.

```
grmon3> info sys mctrl0
  mctrl0    Cobham Gaisler  Memory controller with EDAC
            AHB: 00000000 - 20000000
            AHB: 20000000 - 40000000
            AHB: 40000000 - 80000000
            APB: 80000000 - 80000100
            8-bit prom @ 0x00000000
            32-bit static ram: 1 * 8192 kbyte @ 0x40000000
            32-bit sdram: 2 * 128 Mbyte @ 0x60000000
            col 10, cas 2, ref 7.8 us
grmon3> info sys pdev10
  pdev10    Bus 02 Slot 03 Func 00 [2:3:0]
            vendor: 0x1186 D-Link System Inc
            device: 0x4000 DL2000-based Gigabit Ethernet
            class:  020000 (ETHERNET)
            subvendor: 0x1186, subdevice: 0x4004
            BAR1: 00001000 - 00001100 I/O-32 [256B]
            BAR2: 82203000 - 82203200 MEMIO  [512B]
            ROM:  82100000 - 82110000 MEM    [64kB]
            IRQ INTA# -> IRQW
```

2. Variables

GRMON provides variables that can be used in scripts. A list of the variables can be found below.

`grmon_version`

> The version number of GRMON

`grmon_shell`

> The name of the shell

`grmon::settings::suppress_output`

> The variable is a bitmask to control GRMON output.

bit 0	Block all output from GRMON commands to the terminal
bit 1	Block all output from TCL commands (i.e. puts) to the terminal
bit 2	Block all output to the log

`grmon::settings::echo_result`

> If setting this to one, then the result of a command will always be printed in the terminal.

`grlib_device`

> The device ID of the system, read from the plug and play area.

`grmon::interrupt`

> This variable will be set to 1 when a user issues an interrupt (i.e. pressing Ctrl-C from the commandline), it's always set to zero before a commands sequence is issued. It can be used to abort user defined commands.

> It is also possible to write this variable from inside hooks and procedures. E.g. writing a 1 from a `exec` hook will abort the execution

`grlib_build`

> The build ID of the system, read from the plug and play area.

`grlib_system`

> The name of the system. Only valid on known systems.

`grlib_freq`

> The frequency of the system in Hz.

```
<devname#>1::pnp::device
<devname#>1::pnp::vendor
<devname#>1::pnp::mst::custom0
<devname#>1::pnp::mst::custom1
<devname#>1::pnp::mst::custom2
<devname#>1::pnp::mst::irq
<devname#>1::pnp::mst::idx
<devname#>1::pnp::ahb::0::start
<devname#>1::pnp::ahb::0::mask
<devname#>1::pnp::ahb::0::type
<devname#>1::pnp::ahb::custom0
<devname#>1::pnp::ahb::custom1
<devname#>1::pnp::ahb::custom2
<devname#>1::pnp::ahb::irq
<devname#>1::pnp::ahb::idx
<devname#>1::pnp::apb::start
<devname#>1::pnp::apb::mask
<devname#>1::pnp::apb::irq
<devname#>1::pnp::apb::idx
```

The AMBA Plug and Play information is available for each AMBA device. If a device has an AHB Master (mst), AHB Slave (ahb) or APB slave (apb) interface, then the corresponding variables will be created.

---

[1]Replace with device name.

```
<devname#>1::vendor
<devname#>1::device
<devname#>1::command
<devname#>1::status
<devname#>1::revision
<devname#>1::ccode
<devname#>1::csize
<devname#>1::tlat
<devname#>1::htype
<devname#>1::bist
<devname#>1::bar0
<devname#>1::bar1
<devname#>1::bar2
<devname#>1::bar3
<devname#>1::bar4
<devname#>1::bar5
<devname#>1::cardbus
<devname#>1::subven
<devname#>1::subdev
<devname#>1::rombar
<devname#>1::pri
<devname#>1::sec
<devname#>1::sord
<devname#>1::sec_tlat
<devname#>1::io_base
<devname#>1::io_lim
<devname#>1::secsts
<devname#>1::memio_base
<devname#>1::memio_lim
<devname#>1::mem_base
<devname#>1::mem_lim
<devname#>1::mem_base_up
<devname#>1::mem_lim_up
<devname#>1::io_base_up
<devname#>1::io_lim_up
<devname#>1::capptr
<devname#>1::res0
<devname#>1::res1
<devname#>1::rombar
<devname#>1::iline
<devname#>1::ipin
<devname#>1::min_gnt
<devname#>1::max_lat
<devname#>1::bridge_ctrl
```

If the PCI bus has been registered into the GRMON's device handling system the PCI Plug and Play configuration space registers will be accessible from the Tcl variables listed above. Depending on the PCI header layout (standard or bridge) some of the variables list will not be available. Some of the read-only registers such as DEVICE and VENDOR are stored in GRMON's memory, accessing such variables will not generate PCI configuration accesses.

```
<devname#>1::<regname>2
<devname#>1::<regname>2::<fldname>3
```

Many devices exposes their registers, and register fields, as variables. When writing these variables, the registers on the target system will also be written.

---

[2] Replace with a register name
[3] Replace with a register field name

```
grmon3> info sys
...
  mctrl0    Cobham Gaisler  Memory controller with EDAC
            AHB: 00000000 - 20000000
            AHB: 20000000 - 40000000
            AHB: 40000000 - 80000000
            APB: 80000000 - 80000100
            8-bit prom @ 0x00000000
            32-bit static ram: 1 * 8192 kbyte @ 0x40000000
            32-bit sdram: 2 * 128 Mbyte @ 0x60000000
            col 10, cas 2, ref 7.8 us
...
grmon3> puts [ format 0x%x $mctrl0::                         [TAB-COMPLETION]
mctrl0::mcfg1     mctrl0::mcfg2    mctrl0::mcfg3     mctrl0::pnp::
mctrl0::mcfg1::   mctrl0::mcfg2::  mctrl0::mcfg3::
grmon3> puts [ format 0x%x $mctrl0::pnp::                    [TAB-COMPLETION]
mctrl0::pnp::ahb::    mctrl0::pnp::device  mctrl0::pnp::ver
mctrl0::pnp::apb::    mctrl0::pnp::vendor
grmon3> puts [ format 0x%x $mctrl0::pnp::apb::               [TAB-COMPLETION]
mctrl0::pnp::apb::irq    mctrl0::pnp::apb::mask   mctrl0::pnp::apb::start
grmon3> puts [ format 0x%x $mctrl0::pnp::apb::start ]
  0x80000000
```

3. User defined hooks

GRMON supports user implemented hooks using Tcl procedures. Each hook is variable containing a list of procedure names. GRMON will call all the procedures in the list.

Like normal procedures in TCL, each hook can return a code and a result value using the TCL command **return**. If a hook returns a code that is not equal to zero, then the GRMON will skip the rest of the hooks that are registered in that list. Some hooks will change GRMONs behavior depending on the return code, see hook descriptions below.

Hooks in the system shell can only be installed using a startup script, see -udrv*<filename>* for more information.api.udrv

Hooks can be installed in the execution shell using the command **grmon::execsh eval** *<script>* or using a startup script.

To uninstall hooks, either remove the procedure name from the list using the Tcl **lreplace** or delete the variable using **unset** to uninstall all hooks. Hooks in the system shell can only be uninstalled in the startup script or by letting the hook uninstall itself. Always use lreplace when uninstalling hooks in the system shell, otherwise it's possible to delete hooks the GRMON has installed that may lead to undefined behavior.

preinit
> The preinit hooks is called after GRMON has connected to the board and before any driver initialization is done. It is also called before the plug and play area is scanned. The hook may only be defined in the system shell.

postinit
> The post init hook is called after all drivers have been initialized. The hook may only be defined in the system shell.

init#
> During GRMON's startup, 9 hooks are executed. These hooks are called init1, init2, etc. Each hook is called before the corresponding init function in a user defined driver is called. In addition init1 is called after the plug and play area is scanned, but before any initialization. The init# hooks may only be defined in the system shell.

deinit
> Called when GRMON is closing down. The deinit hooks may only be defined in the system shell.

closedown
> Called when a TCL is closing down.

preexec
> These hooks are called before the CPU:s are started, when issuing a **run**, **cont** or **go** command. They must be defined in the execution shell.

exec
> The exec hooks are called once each iteration of the polling loop, when issuing a **run**, **cont** or **go** command. They must be defined in the execution shell.

postexec

These hooks are called after the CPU:s have stopped, when issuing a **run**, **cont** or **go** command. They must be defined in the execution shell.

load

This hook is called before each block of data is written to the target. See tables below for argument description and return code definitions for the hook procedure.

Argument	Type	Description
addr	integer	Destination addr
bytes	integer	Number of bytes

Return Code	Value	Description
0	-	The hook was successful, but let GRMON continue as usual. This can be used to do extra configuration or fix-ups. Any return value will be ignored.
-1	Integer value	The hook overrides GRMON and the access was successful. Any return value will be ignored.
1	Error text	The hook overrides GRMON and the access failed. Any return value will be ignored.

pcicfg

This hook is called when a PCI configuration read access is issued. It can be used to override GRMON's PCI configuration space access routines. See tables below for argument descriptions and return codes/value definitions for the hook procedure.

Argument	Type	Description
bus	integer	Bus index
slot	integer	Slot index
func	integer	Function index
ofs	integer	Offset into the device's configuration space
size	integer	Size in bits of the access (8, 16 or 32)

Return Code	Value	Description
0	-	The hook was successful, but let GRMON continue as usual. This can be used to do extra configuration or fix-ups. Any return value will be ignored.
-1	Integer value	The hook overrides GRMON and the access was successful. Return the value read.
1	Error text	The hook overrides GRMON and the access failed. Return an error description.

pciwcfg

This hook is called when a PCI configuration write access is issued. It can be used to override GRMON's PCI configuration space access routines. See tables below for argument descriptions and return codes/value definitions the hook procedure.

Argument	Type	Description
bus	integer	Bus index
slot	integer	Slot index
func	integer	Function index
ofs	integer	Offset into the device's configuration space
size	integer	Size in bits of the access (8, 16 or 32)
value	integer	The value to be written

Return Code	Value	Description
0	-	The hook was successful. GRMON continue doing the access. This can be used to do extra configuration or fix-ups. Any return value will be ignored.
-1	-	The hook overrides GRMON and the access was successful. Any return value will be ignored.
1	Error text	The hook overrides GRMON and the access failed. Return an error description.

reset
>   The reset hook is called after GRMON has connected to the board and when a command reset or run is
>   issued.

Example C.1. Using hooks

```
# Define hook procedures
grmon::execsh eval {
  proc myhook1 {} {puts "Hello World"}
  proc myhook2 {} {puts "Hello again"; return -code 1 "Blocking next hook"}
  proc myhook3 {} {puts "Will never run"}
  lappend ::hooks::preexec ::myhook1 ::myhook2 ::myhook3 ;# Add hooks
}

run
grmon::execsh eval {unset ::hooks::preexec ;# Remove all hooks}

proc mypcicfg {bus slot func ofs size} {
  if {$size == 32} {
    return -code -1 0x01234567
  } elseif {$size == 16} {
    return -code -1 0x89AB
  } elseif {$size == 8} {
    return -code -1 0xCD
  }
  return -code 1 "Unknown size"
}
lappend ::hooks::pcicfg ::mypcicfg  ;# Add hooks
puts [format 0x%x [pci cfg16 0:1:0 0]]
```

4. User defined driver

It is possible to extend GRMON with user defined drivers by implementing certain hooks and variables in Tcl.
GRMON scans the namespace `::drivers` for user defined drivers. Each driver must be located in the sub-
namespace with the name of the driver. Only the variables `vendor`, `device`, `version_min`, `version_max`
and `description` are required to be implemented, the other variables and procedures are optional. The script
must be loaded into the system shell.

Cores that GRMON finds while scanning the plug and play area, will be matched against the defined vendor,
device and version_min/max variables. If it matches, then the core will be paired with the driver. If a driver is
called 'mydrv', then the first found core will be named 'mydrv0', the second 'mydrv1',etc. This name will be passed
to the to all the procedures defined in the driver, and can be used to identify the core.

The name of the driver may *not* end with a number.

variable `vendor`
>   The plug and play vendor identification number.
variable `device`
>   The plug and play device identification number.
variable `version_min`
variable `version_min`
>   Minimum and maximum version of the core that this driver supports
variable `description`
>   A short description of the device

variable `regs` (optional)

    If implemented, the regs variable contains information used to parse the registers and present them to the user, i.e. they will be printed in 'info reg' and Tcl-variables will be created in each shell. All register descriptions must be put in the regs variable. Each register consists of a name, description and an optional list of fields. The field entries are a quadruple on the format {name pos bits description}.

proc **info** *devname* (optional)

    Optional procedure that may be used to present parsed information when 'info sys' is called. Returns a newline separated string.

proc **init** {*devname level*} (optional)

    Optional procedure that will be called during initialization. The procedure will be called nine times for each device, with level argument set to 1-9. This way drivers that depend on another driver can be initialized in a safe way. Normally initialization of devices is done in level 7.

proc **restart** *devname* (optional)

    Procedure to reinitialize the device to a known state. This is called when GRMON starts (after initialization) and when commands 'run' or 'reset' is issued.

proc **regaddr** {*devname regname*} (optional)

    Required only if registers have been defined. It returns the address of the requested register. It's required to be implemented if the variable regs is implemented.

If the variable *regs* is implemented, then the procedure *regaddr* is required.

```
namespace eval drivers::mydrv {
    # These variables are required
    variable vendor 0x1
    variable device 0x16
    variable version_min 0
    variable version_max 0
    variable description "My device desciption"

    # Proc     init
    # Args        devname: Device name
    #             level  : Which stage of initialization
    # Return  -
    #
    # Optional procedure that will be called during initialization. The procedure
    # will be called with level argmuent set to 1-9, this way drivers that depend
    # on another driver can be initialized in a safe way. Normally
    # initialization is done in level 7.
    #
    # Commands wmem and mem can be used to access the registers. Use the driver procedure
    # regaddr to calculate addresses or use static addresses.
    proc init {devname level} {
        puts "init $devname $level"
        if {$level == 7} {
          puts "Hello $devname!"
          puts "Reg1 = mem [regaddr $devname myreg1] 4"
        }
    }

    # Proc     restart
    # Args        devname: Device name
    # Return  -
    #
    # Optional procedure to reinit the device. This is called when GRMON start,
    # when commands 'run' or 'reset' is issued.
    proc restart devname {
        puts "restart $devname"
    }

    # Proc     info
    # Args        devname: Device name
    # Return  A newline-separated string
    #
    # Optional procedure that may be used to present parsed information when
    # 'info sys' is called.
    proc info devname {
        set str "Some extra information about $devname"
        append str "\nSome more information about $devname"
        return $str
    }

    # Proc     regaddr
    # Args        devname: Device name,
```

```
#           regname: Register name
# Return  Address of requested register
#
# Required only if any registers have been defined.
# This is a suggestion how the procedure could be implemented
proc regaddr {devname regname} {
    array set offsets {myreg1 0x0 myreg2 0x4}
    if {[namespace exists ::[set devname]::pnp::apb]} {
        set start [set ::[set devname]::pnp::apb::start]
    } elseif {[namespace exists ::[set devname]::pnp::ahb]} {
        set start [set ::[set devname]::pnp::ahb::0::start]
    } else {
        error "Unknown register address for $devnam::$regname"
    }
    return [format 0x%08x [expr ($start + $offsets($regname)) & 0xFFFFFFFF]]
}

# Register descriptions
#
# All description must be put in the regs-namespace. Each register concist
# of a name, description and an optional list of fields.
# The fields are quadruple of the format {name pos bits description}
#
# Registers and fields can be added, removed or changed up to initialization
# level 8. After level 8 TCL variables are created and the regs variable
# should be considered to a constant.
variable regs {
    {"myreg1" "Register1 description"
        {"myfld3" 4 8 "Field3 descpription"}
        {"myfld2" 1 1 "Field2 descpription"}
        {"myfld1" 0 1 "Field1 descpription"}
    }
    {"myreg2" "Register2 description"
    }
}
}; # End of mydrv
```

5. User defined commands

User defined commands can be implemented as Tcl procedures, and then loaded into all shells. See the documentation of the proc command [http://www.tcl.tk/man/tcl8.6/TclCmd/proc.htm] on the Tcl website for more information.

6. Links

More about Tcl, its syntax and other useful information can be found at:

Tcl Website [http://www.tcl.tk]
Tcl Commands [http://www.tcl.tk/man/tcl8.6/TclCmd/contents.htm]
Tcl Tutorial [http://www.tcl.tk/man/tcl8.5/tutorial/tcltutorial.html]
Tcler's Wiki [http://wiki.tcl.tk/]

Appendix D. Fixed target configuration file format

To use a fixed configuration file, GRMON should be started with `-cfg file`. A fixed configuration file can be used to describe the target system instead of reading the plug and play information. The configuration file describes which IP cores are present on the target and on which addresses they are mapped, using an XML format. An description file can be generated from an plug and play system using the command **info sys -xml** `file`.

Valid tags for the XML format are described below.

<grxml>
- Parents:
- Children: grlib

Attribute	Description
version	Version of the XML syntax

<grlib>
- Parents: grxml
- Children: bus

Attribute	Description
build	GRLIB build identification number
device	GRLIB device identification number

<bus>
- Parents: grlib, slave, bus
- Children: master, slave, bus

Attribute	Description
type	Valid values are AHB or APB
ffactor	Frequency factor relavtive parent bus

<master>
- Parents: bus
- Children:

Attribute	Description
vendor	Core vendor identification number
device	Core device identification number
version	Version number
irq	Assigned interrupt number

<slave>
- Parents: bus
- Children: bus, bar, custom

Attribute	Description
vendor	Core vendor identification number
device	Core device identification number
version	Version number
irq	Assigned interrupt number

<bar>
- Parents: slave

- Children:

Attribute	Description
address	Base address of the bar
length	Length of the bar in bytes

\<custom\>
- Parents: slave
- Children:

Attribute	Description
register	Value of the user defined bar

Below is an example configuration file for a simple LEON3 system.

```
<?xml version="1.0" standalone="yes"?>
<grxml version="1.0">
  <grlib device="0x0" build="4109">
    <bus type="AHB" ffactor="1.000000">
      <!-- LEON3 SPARC V8 Processor -->
      <master vendor="0x1" device="0x3">
      </master>
      <!-- JTAG Debug Link -->
      <master vendor="0x1" device="0x1c" version="1">
      </master>
      <!-- LEON2 Memory Controller -->
      <slave vendor="0x4" device="0xf">
        <bar address="0x00000000" length="0x20000000"/>
        <bar address="0x20000000" length="0x20000000"/>
        <bar address="0x40000000" length="0x40000000"/>
      </slave>
      <!-- AHB/APB Bridge -->
      <slave vendor="0x1" device="0x6">
        <bar address="0x80000000" length="0x100000"/>
        <bus type="APB" ffactor="1.000000">
          <!-- LEON2 Memory Controller -->
          <slave vendor="0x4" device="0xf">
            <bar address="0x80000000" length="0x100"/>
          </slave>
          <!-- Generic UART -->
          <slave vendor="0x1" device="0xc" irq="2" version="1">
            <bar address="0x80000100" length="0x100"/>
          </slave>
          <!-- Multi-processor Interrupt Ctrl. -->
          <slave vendor="0x1" device="0xd" version="3">
            <bar address="0x80000200" length="0x100"/>
          </slave>
          <!-- Modular Timer Unit -->
          <slave vendor="0x1" device="0x11" irq="8">
            <bar address="0x80000300" length="0x100"/>
          </slave>
          <!-- General Purpose I/O port -->
          <slave vendor="0x1" device="0x1a" version="1">
            <bar address="0x80000500" length="0x100"/>
          </slave>
        </bus>
      </slave>
      <!-- LEON3 Debug Support Unit -->
      <slave vendor="0x1" device="0x4" version="1">
        <bar address="0x90000000" length="0x10000000"/>
      </slave>
    </bus>
  </grlib>
</grxml>
```

Appendix E. License key installation

GRMON is licensed using a Sentinel LDK USB hardware key and has support for node-locked and floating license keys. The type of key can be identified by the color of the USB dongle. The node-locked keys are purple and the floating license keys are red.

1. Sentinel LDK Run-time

The latest run-time can be found at the GRMON download page. Included in the downloaded Sentinel LDK run-time archive is a README file which contains system requirements and detailed installation instructions. However, ignore all instructions about installing `haspvlib_<vendorID>.so` and/or `haspvlib_x86_64_<vendorID>.so`.

Administrator privileges are required on Windows. On Linux it is required that the run-time is installed as root user.

GRMON download page [http://www.gaisler.com/index.php/downloads/debug-tools]

2. Node-locked keys (purple USB key)

For node-locked keys, the Sentinel LDK Run-time for the key must be installed before the key can be used.

3. Floating keys (red USB key)

In the case of floating keys, the Sentinel LDK Run-time must be installed on the server and the client computer.

Sentinel LDK communicates via TCP and UDP on socket 1947. This socket is IANA-registered exclusively for this purpose. By default the client will find the server by issuing a UDP broadcast to local subnets on port 1947.

If broadcasting is not working or unwanted, then advanced network settings can be setup via the Sentinel Admin Control Center. The Sentinel Admin Control Center is accessed by opening the url localhost:1947 in an webbrowser. The network settings are reached by selecting "Configuration" in the menu and then selecting the "Access to Remote License Managers" tab. Detailed information on how to setup the network settings can be found by selecting "Help" in the menu.

Appendix F. Appending environment variables

1. Windows

Open the environment variables dialog by following the steps below:

Windows 7

1. Select `Computer` from the Start menu
2. Choose `System Properties` from the context menu
3. Click on `Advanced system settings`
4. Select `Advanced` tab
5. Click on `Environment Variables` button

Windows XP

1. Select `Control Panel` from the Start menu
2. Open `System`
3. Select `Advanced` tab
4. Click on `Environment Variables` button

Variables listed under `User variables` will only affect the current user and `System variables` will affect all users. Select the desired variable and press `Edit` to edit the variable value. If the variable does not exist, a new can be created by pressing the button `New`.

To append the `PATH`, find the variable under System variables or User variables (if the user variable does not exist, then create a new) and press `Edit`. At the end of the value string, append a single semicolon (;) as a separator and then append the desired path, e.g. `;C:\my\path\to\append`

2. Linux

Use the **export <name>=<value>** command to set an environment variable. The paths in the variables `PATH` or `LD_LIBRARY_PATH` should be separated with a single colon (:).

To append a path to `PATH` or `LD_LIBRARY_PATH`, add the path to the end of the variable. See example below.

```
$ export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:/my/path/to/appand
```

Appendix G. Compatibility

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G.1. Compatibility notes for GRMON2

Default startup-behavior

If GRMON3 is started without a debug link option on the command line, then the GRMON3 GUI connection dialog will be opened. Furthermore, if no debug link option is given on the command line, then any other command line options are also ignored. The user can select them in the connection dialog.

If GRMON version 2.0 and earlier is started without an explicit debug link option on the command line, then it will try to connect to the target using the serial debug link by default. The behavior of GRMON version 2.0 and earlier can be achieved in GRMON3 by giving the `-uart` option.

System-specific command-line options

The GRMON 2.0 options
* `-leon2`
* `-at697`
* `-at697e`
* `-at697f`
* `-agga4`

are no longer available. Corresponding options in GRMON3 are:
* `-sys leon2`
* `-sys at697`
* `-sys at697e`
* `-sys at697f`
* `-sys agga4`

Execution hooks

Execution hooks must be installed in the execution shell.

G.2. Compatibility notes for GRMON1

Breakpoints
Tcl has a native command called break, that terminates loops, which conflicts the the GRMON1 command break. Therefore **break**, **hbreak**, **watch** and **bwatch** has been replaces by the command **bp**.

Cache flushing
Tcl has a native command called flush, that flushed channels, which conflicts the the GRMON1 command flush. Therefore **flush** has been replaced by the command **cctrl flush**. In addition the command **icache flush** can be used to flush the instruction cache and the command **dcache flush** can be used to flush the data cache .

Case sensitivity
GRMON3 command interpreter is case sensitive whereas GRMON1 is insensitive. This is because Tcl is case sensitive.

-eth -ip
-ip flag is not longer required for the Ethernet debug link, i.e. it is enough with *-eth 192.168.0.51*.