Minimum spannig trees

Data Structures and Algorithms for Computational Linguistics III (ISCL-BA-07)

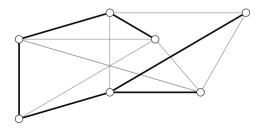
Çağrı Çöltekin ccoltekin@sfs.uni-tuebingen.de

University of Tübingen Seminar für Sprachwissenschaft

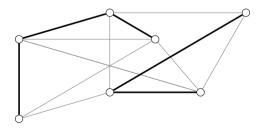
Winter Semester 2021/22

ersion: 3f846c9 @2021-12-08

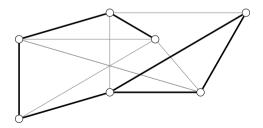
- A spanning subgraph: it includes all nodes
- It is a tree: it is acyclic, and connected



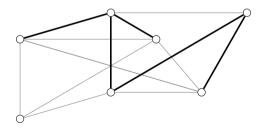
- A spanning subgraph: it includes all nodes
- It is a tree: it is acyclic, and connected



- A spanning subgraph: it includes all nodes
- It is a tree: it is acyclic, and connected

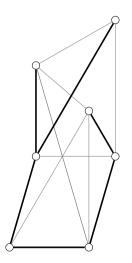


- A spanning subgraph: it includes all nodes
- It is a tree: it is acyclic, and connected



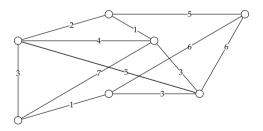
Minimum spanning trees

- A minimum spanning tree (MST) is a spanning tree of weighted graph with minimum total weigh
- MST is a fundamental problem with many applications, including
 - Network design (communication, transportation, electrical, ...)
 - Cluster analysis
 - Approximate solutions to traveling salesman problem
 - Object/network recognition in images
 - Avoiding cycles in broadcasting in communication networks
 - Dithering in images, audio, video
 - Error correction codes
 - DNA sequencing



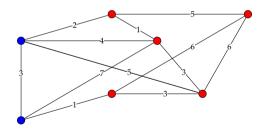
The 'cut property'

- A *cut* of a graph is a partition that divides its nodes into two disjoint (non-empty) sets
- Given any cut, the edge with the lowest weight across the cut is in the MST



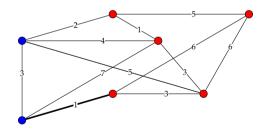
The 'cut property'

- A *cut* of a graph is a partition that divides its nodes into two disjoint (non-empty) sets
- Given any cut, the edge with the lowest weight across the cut is in the MST



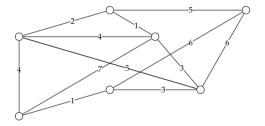
The 'cut property'

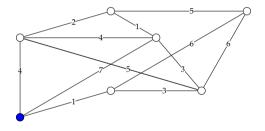
- A *cut* of a graph is a partition that divides its nodes into two disjoint (non-empty) sets
- Given any cut, the edge with the lowest weight across the cut is in the MST

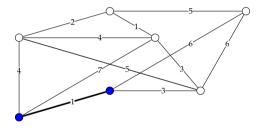


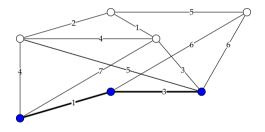
- Prim-Jarník algorithm is a greedy algorithm for finding an MST for a weighted undirected graph
- Algorithm starts with a single 'start' node, and grows the MST greedily
- At each step we consider a cut between nodes visited and the rest of the nodes, and select the minimum edge across the cut
- Repeat the process until all nodes are visited

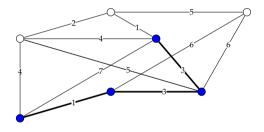
intuition

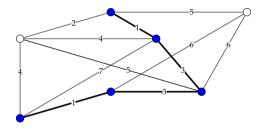




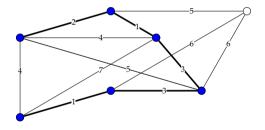




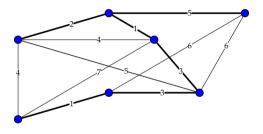




demonstration



5 / 16



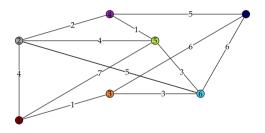
analysis

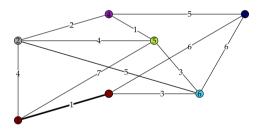
- Two loops over number of nodes n, O(n²) if we need to search
- If we use a priority queue for Q, then complexity becomes O(m log m)

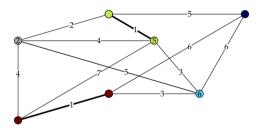
```
1: pick any node s
2: C[s] \leftarrow 0
 3: for each node y \neq s do
        C[v] \leftarrow \infty
    E[v] \leftarrow None
 6: T \leftarrow \emptyset
 7: O \leftarrow nodes
 8: while Q is not empty do
        Find the node \nu with min C[n]
10:
        Connect v to T
        for edge (v, w) in Q do
11:
12:
             if cost(v, w) < C[w] then
                 C[w] \leftarrow cost(v, w)
13:
                 E[w] \leftarrow v
14:
```

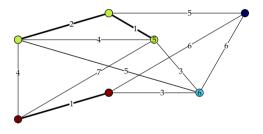
Kruskal's algorithm intuition

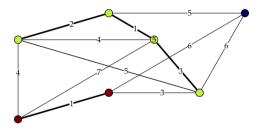
- Another popular algorithm for finding MST on undirected graphs
- The main idea is starting with each node in its own partition
- At each iteration, we choose the edge with the minimum weight across any two clusters, and join them
- Algorithm terminates when there are no clusters to join

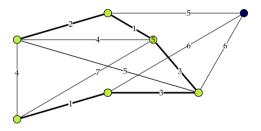


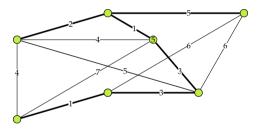












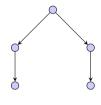
Kruskal's algorithm analysis

- Loop over edges, but beware of the sorting requirement
- With simple data structures then complexity is O(m log m)

```
    T ← Ø
    for each node v do
    create_cluster(v)
    for (u,v) in edges sorted by weight do
    if cluster(u) ≠ cluster(v) then
    T ← T ∪ {(u,v)}
    union(cluster(u), cluster(v))
```

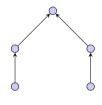
Directed trees

- Trees with directed edges come in few flavors
 - A rooted directed tree (arborescence) is an acyclic directed graph where all nodes are reachable from the root node through a single directed path (this is what computational linguists simply calls a tree)
 - An anti-arborescence is a rooted directed tree where all edges are reversed
 - A polytree (also called a directed tree) is a directed graph where undirected edges form a tree
- The equivalent of finding an MST in a directed graph is finding a rooted directed tree (arborescence)



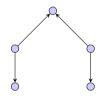
Directed trees

- Trees with directed edges come in few flavors
 - A rooted directed tree (arborescence) is an acyclic directed graph where all nodes are reachable from the root node through a single directed path (this is what computational linguists simply calls a tree)
 - An anti-arborescence is a rooted directed tree where all edges are reversed
 - A polytree (also called a directed tree) is a directed graph where undirected edges form a tree
- The equivalent of finding an MST in a directed graph is finding a rooted directed tree (arborescence)



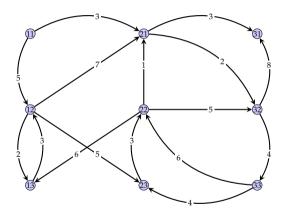
Directed trees

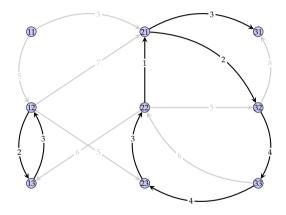
- Trees with directed edges come in few flavors
 - A rooted directed tree (arborescence) is an acyclic directed graph where all nodes are reachable from the root node through a single directed path (this is what computational linguists simply calls a tree)
 - An anti-arborescence is a rooted directed tree where all edges are reversed
 - A polytree (also called a directed tree) is a directed graph where undirected edges form a tree
- The equivalent of finding an MST in a directed graph is finding a rooted directed tree (arborescence)

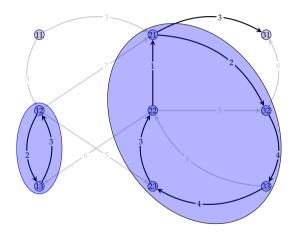


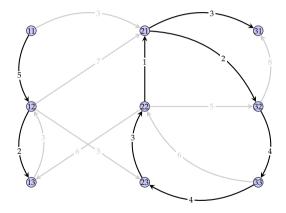
a sketch

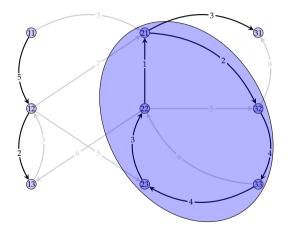
- The MST for a directed graph has to start from a designated root node
 - If selected node has any incoming edges, remove them
 - It is also a common practice to introduce an artificial root node with equal-weight edges to all nodes
- For all non-root nodes, select the incoming edge with lowest weight, remove others
- If the resulting graph has no cycles, it is an MST
- If there are cycles break them
 - Consider the cycle as a single node
 - Select the incoming edge that yields the lowest cost if used for breaking the cycle
- Repeat until no cycles remain

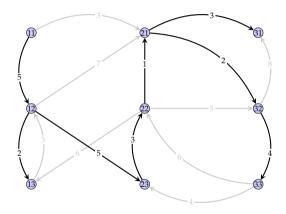








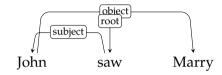




Chu-Liu/Edmonds algorithm analysis

- The algorithm is generally defined recursively: at each step, create new graph with a contracted cycle call the procedure with the new graph
- At most n recursions: the cycle has to include more nodes at every step
- At each call, m steps for finding minimum incoming edge (also finding a cycle with O(n), but $m \ge n$)
- The 'vanilla' algorithm runs in O(mn)
- There are improved versions

Chu–Liu/Edmonds algorithm in Computational Linguistics dependency parsing



- In a dependency analysis, the structure of the sentence is represented by asymmetric binary relations between syntactic units
- Each relation defines one of the words as the head and the other as dependent
- Often an artificial root node is used for computational convenience
- The links (relations) may have labels (dependency types)
- A dependency analysis (parse) is simply a rooted directed tree

Chu-Liu/Edmonds for dependency parsing

- Begin with fully connected weighted graph, except the root node has no incoming edges
- Weights are estimated from a treebank, typically determined by a machine learning method trained on a treebank
- We often use probabilities rather than costs/distances, so, rather than minimizing, maximize the weight of the tree
- Given the fully connected graph, now the parsing becomes finding the MST
- This method is one of the most common (and successful) approaches to dependency parsing

Summary

- Minimum spanning trees have many applications
- An MST of a undirected graph can be found (efficiently) using Prim-Jarník or Kruskal's algorithms
- For directed graph, the corresponding problem can be solved using Chu–Liu/Edmonds algorithm (technically what we find is a rooted directed tree, or arborescence)
- MST also has quite a few applications in CL/NLP

Next:

- Maps and hashing
- Reading: Goodrich, Tamassia, and Goldwasser (2013, chapter 10)

Acknowledgments, credits, references



Goodrich, Michael T., Roberto Tamassia, and Michael H. Goldwasser (2013). Data Structures and Algorithms in Python. John Wiley & Sons, Incorporated. ISBN: 9781118476734.

blank