NOPT042 Constraint programming: Tutorial 8 - Global constraints

```
In [1]: %load_ext ipicat
```

Picat version 3.5#5

About the constraint cummulative

- Picat on GitHub (unofficial)
- Global Constraint Catalog: the cumulative constraint see the references

The constraint global_cardinality

```
global cardinality(List, Pairs)
```

Let List be a list of integer-domain variables [X1, . . ., Xd], and Pairs be a list of pairs [K1-V1, . . ., Kn-Vn], where each key Ki is a unique integer, and each Vi is an integer-domain variable. The constraint is true if every element of List is equal to some key, and, for each pair Ki-Vi, exactly Vi elements of List are equal to Ki . This constraint can be defined as follows:

```
global_cardinality(List,Pairs) =>
    foreach($Key-V in Pairs)
        sum([B : E in List, B#<=>(E#=Key)]) #= V
    end.
```

---from the guide

Example: Magic sequence

A magic sequence of length n is a sequence of integers x_0, \ldots, x_{n-1} between 0and n-1, such that for all $i\in\{0,\ldots,n-1\}$, the number i occurs exactly x_i times in the sequence. For instance, 6,2,1,0,0,0,1,0,0,0 is a magic sequence since 0 occurs 6 times in it, 1 occurs twice, etc.

(Problem from the book.)

Let's maximize the sum of the numbers in the sequence.

```
0m10.022s
  real
     0m10.008s
  user
     0m0.008s
  sys
In [3]: # !cat magic-sequence/magic-sequence.pi
In [4]: !time picat magic-sequence/magic-sequence2.pi 64
   !time picat magic-sequence/magic-sequence2.pi 256
  0m0.044s
  real
  user
     0m0.030s
  sys
     0m0.008s
  0,0,1,0,0,0]
     0m1.660s
  real
     0m1.595s
  user
     0m0.065s
  sys
   # !cat magic-sequence/magic-sequence2.pi
In [5]:
   !time picat magic-sequence/magic-sequence3.pi 256
In [6]:
   !time picat magic-sequence/magic-sequence3.pi 1024
```

```
0m0.117s
real
user
0m0.089s
sys
0m0.024s
0,0,0,0,0,0,0,0,0,0,0,0,0,0,1,0,0,0]
```

real 0m3.772s user 0m3.487s sys 0m0.284s

In [7]:

!cat magic-sequence/magic-sequence3.pi

The order of constraints

The order might matter to the solver, the above model is an example. When the cp solver parses a constraint, it tries to reduce their domains. The implicit (redundant) constraint using scalar_product can reduce the model a lot, which is much better to do before parsing global_cardinality. (Note: e.g. MiniZinc doesn't preserve the order of constraints during compilation, the behaviour is a bit unpredictable.)

(Heuristic: easy constraints and constraints that are strong (in reducing the search space) should go first??)

The circuit constraint

The constraint <code>circuit(L)</code> requires that the list L represents a permutation of $1,\ldots,n$ consisting of a single cycle, i.e., the graph with edges $i\to L[i]$ is a cycle. A similar constraint is <code>subcircuit(L)</code> which requires that elements for which $L[i]\neq i$ form a cycle.

Example: Knight tour

Given an integer N, plan a tour of the knight on an $N \times N$ chessboard such that the knight visits every field exactly once and then returns to the starting field. You can assume that N is even.

Hint: For a matrix M is a matrix, use M.vars() to extract its elements into a list.

```
In [8]: !picat knight-tour/knight-tour.pi 6
     5,36,33,17},{27,28,20,26,24,23}}
     X:
      9 13 7 8 16 10
     15 19 5 18 3 4
     21 1 2 12 6 29
      32 31 25 30 34 11
      14 22 35 36 33 17
     27 28 20 26 24 23
     Tour:
      1 32 29 6 3 18
     30 7 2 19 28 5
      33 36 31 4 17 20
      8 23 34 15 12 27
      35 14 25 10 21 16
      24 9 22 13 26 11
```

In [9]: !cat knight-tour/knight-tour.pi

```
Adapted from
 knight_tour.pi
 from Constraint Solving and Planning with Picat, Springer
 by Neng-Fa Zhou, Hakan Kjellerstrand, and Jonathan Fruhman
import cp.
main([N]) \Rightarrow
 N := N.to_int,
 knight(N,X),
 println(x=X),
 println("X:"),
 print_matrix(X),
 extract_tour(X,Tour),
 println("Tour:"),
 print_matrix(Tour).
% Knight's tour for even N*N.
knight(N, X) =>
 X = new_array(N,N),
 X :: 1..N*N,
 XVars = X.vars(),
 % restrict the domains of each square
 foreach (I in 1..N, J in 1..N)
    D = [-1, -2, 1, 2],
    Dom = [(I+A-1)*N + J+B : A in D, B in D,
            abs(A) + abs(B) == 3,
            member(I+A,1..N), member(J+B,1..N)],
    Dom.length > 0,
    X[I,J] :: Dom
 end,
 circuit(XVars),
 solve([ff,split],XVars).
extract_tour(X,Tour) =>
 N = X.length,
 Tour = new_array(N,N),
 K = 1,
 Tour[1,1] := K,
 Next = X[1,1],
 while (K < N*N)
   K := K + 1,
   I = 1+((Next-1) div N),
   J = 1 + ((Next-1) \mod N),
   Tour[I,J] := K,
   Next := X[I,J]
 end.
print_matrix(M) =>
 N = M.length,
 V = (N*N).to_string().length,
 Format = "% " ++ (V+1).to_string() ++ "d",
 foreach(I in 1..N)
    foreach(J in 1..N)
       printf(Format,M[I,J])
```

```
end,
nl
end,
nl.
```

Homework: routing

Vehicle routing is a geralization of the Traveling Salesman Problem. There are N cities. Their pairwise (integer) distances are given by a matrix Distance. We have K vehicles. Each vehicle has a depot in one of the cities 1..N. The depots are given by a list Depots.

The goal is to plan routes for each vehicle so that each city is visited exactly once and each vehicle returns to its original depot. It is also possible for a vehicle not to move at all. In that case it has visited itsWe want to minimize total distance traveled by the vehicles.

(You can assume that the depot cities are already visited. The route of a vehicle may be empty, if it happens to be optimal.)

Use the constraint subcircuit in your model. Running

```
picat routing.pi instance.pi
```

should return the optimal value of 31 and some representation of the route of each vehicle.

```
In [10]: !cat routing/instance.pi
```