Suppose you have a point with coordinates x, y, and z. After rotating this point by  $\Theta$  (specified in radians), the location will have new coordinates which we will call x', y', and z'

## After a $\Theta$ rotation around the *x*-axis:

$$x' = x$$
  

$$y' = y \cos(\Theta) - z \sin(\Theta)$$
  

$$z' = y \sin(\Theta) + z \cos(\Theta)$$

## After a $\Theta$ rotation around the y-axis:

$$x' = x \cos(\Theta) + z \sin(\Theta)$$
  

$$y' = y$$
  

$$z' = -x \sin(\Theta) + z \cos(\Theta)$$

## After a $\Theta$ rotation around the z-axis:

$$x' = x \cos(\Theta) - y \sin(\Theta)$$
  
$$y' = x \sin(\Theta) + y \cos(\Theta)$$
  
$$z' = z$$