

## Metadata

### Description

**Dataset name:** dataset

The dataset has N=180 rows and 68 columns. 180 rows have no missing values on any column.

Metadata for search engines

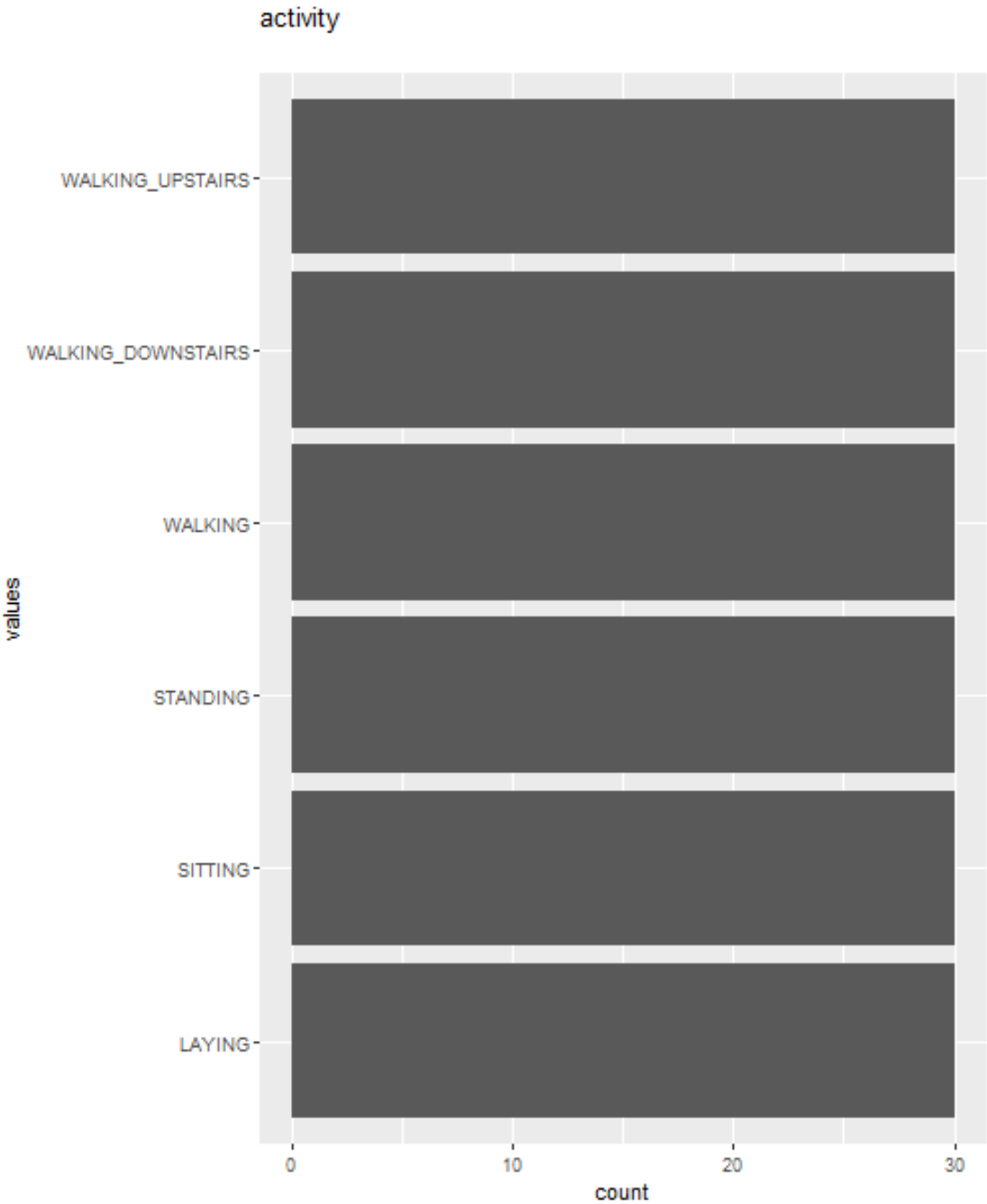
- **Date published:** 2019-05-05
  - **keywords:** *activity, subject, time Body Accelerometer -mean()-X, time Body Accelerometer -mean()-Y, time Body Accelerometer -mean()-Z, time Body Accelerometer -std()-X, time Body Accelerometer -std()-Y, time Body Accelerometer -std()-Z, time Gravity Accelerometer -mean()-X, time Gravity Accelerometer -mean()-Y, time Gravity Accelerometer -mean()-Z, time Gravity Accelerometer -std()-X, time Gravity Accelerometer -std()-Y, time Gravity Accelerometer -std()-Z, time Body Accelerometer Jerk-mean()-X, time Body Accelerometer Jerk-mean()-Y, time Body Accelerometer Jerk-mean()-Z, time Body Accelerometer Jerk-std()-X, time Body Accelerometer Jerk-std()-Y, time Body Accelerometer Jerk-std()-Z, time Body Gyroscope -mean()-X, time Body Gyroscope -mean()-Y, time Body Gyroscope -mean()-Z, time Body Gyroscope -std()-X, time Body Gyroscope -std()-Y, time Body Gyroscope -std()-Z, time Body Gyroscope Jerk-mean()-X, time Body Gyroscope Jerk-mean()-Y, time Body Gyroscope Jerk-mean()-Z, time Body Gyroscope Jerk-std()-X, time Body Gyroscope Jerk-std()-Y, time Body Gyroscope Jerk-std()-Z, time Body Accelerometer Magnitude -mean(), time Body Accelerometer Magnitude -std(), time Gravity Accelerometer Magnitude -mean(), time Gravity Accelerometer Magnitude -std(), time Body Accelerometer JerkMagnitude -mean(), time Body Accelerometer JerkMagnitude -std(), time Body Gyroscope Magnitude -mean(), time Body Gyroscope Magnitude -std(), time Body Gyroscope JerkMagnitude -mean(), time Body Gyroscope JerkMagnitude -std(), frequency Body Accelerometer -mean()-X, frequency Body Accelerometer -mean()-Y, frequency Body Accelerometer -mean()-Z, frequency Body Accelerometer -std()-X, frequency Body Accelerometer -std()-Y, frequency Body Accelerometer -std()-Z, frequency Body Accelerometer Jerk-mean()-X, frequency Body Accelerometer Jerk-mean()-Y, frequency Body Accelerometer Jerk-mean()-Z, frequency Body Accelerometer Jerk-std()-X, frequency Body Accelerometer Jerk-std()-Y, frequency Body Accelerometer Jerk-std()-Z, frequency Body Gyroscope -mean()-X, frequency Body Gyroscope -mean()-Y, frequency Body Gyroscope -mean()-Z, frequency Body Gyroscope -std()-X, frequency Body Gyroscope -std()-Y, frequency Body Gyroscope -std()-Z, frequency Body Accelerometer Magnitude -mean(), frequency Body Accelerometer Magnitude -std(), frequency BodyBody Accelerometer JerkMagnitude -mean(), frequency BodyBody Accelerometer JerkMagnitude -std(), frequency BodyBody Gyroscope Magnitude -mean(),*

*frequency BodyBody Gyroscope Magnitude -std(), frequency BodyBody Gyroscope JerkMagnitude -mean() and frequency BodyBody Gyroscope JerkMagnitude -std()*

Variables

activity

Distribution



*plot of chunk distribution*

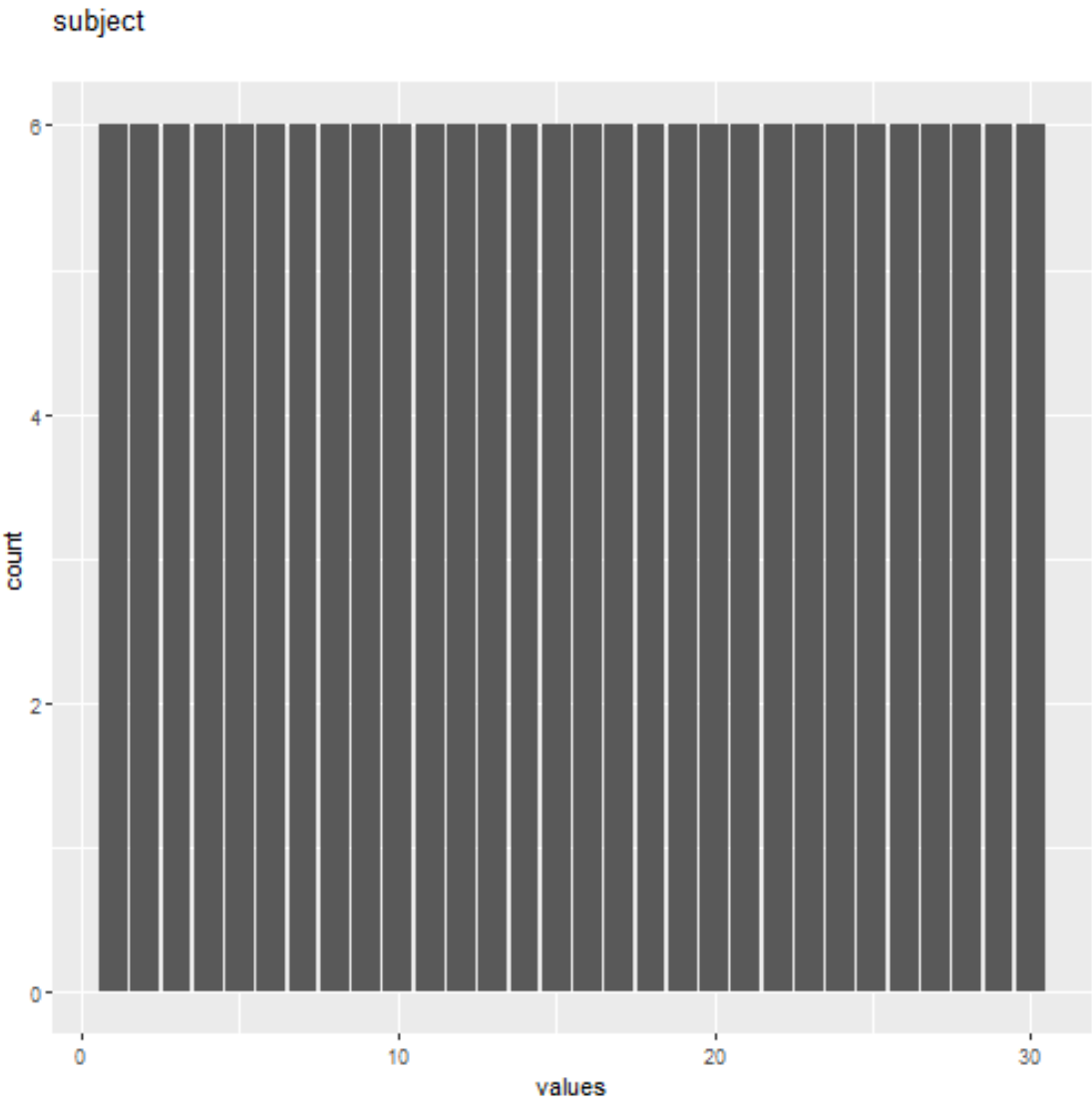
0 missing values.

Summary statistics

name	data_type	missing	complete	n	empty	n_unique	min	max
activity	character	0	180	180	0	6	6	18

subject

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

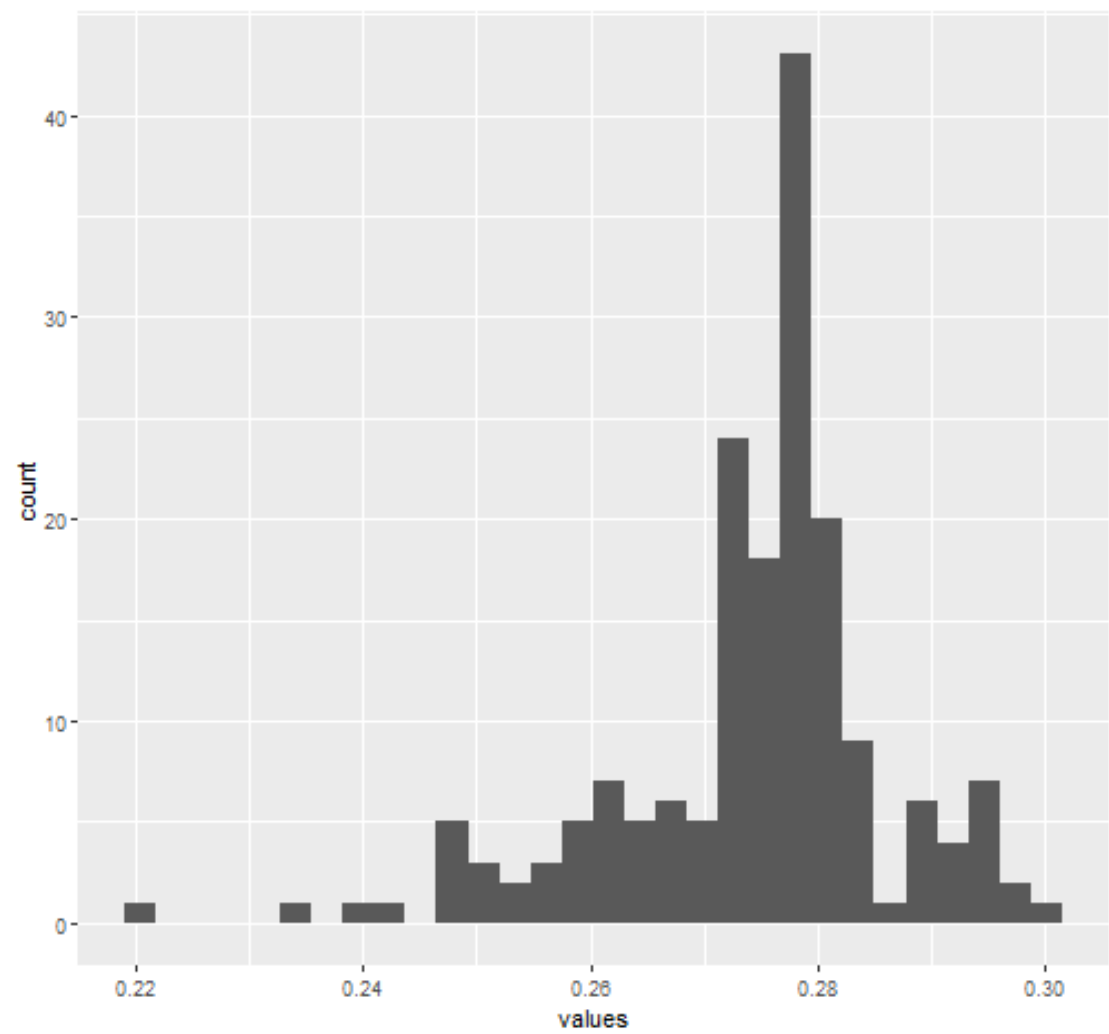
	dat	mi	co	m	p	p	p	p				
na	a_ty	ssi	mpl	n	ea	s	p	2	5	7	1	hist

me	pe	ng	ete	n		d	0	5	0	5	0	0
su	inte	0	180	1	1	8.	1	8	1	2	3	<U+2587><U+2587><U+2586><U+
bje	ger			8	5.	6			5.	3	0	2587><U+2587><U+2586><U+258
ct				0	5	8			5			7><U+2587>

time Body Accelerometer -mean()-X

Distribution

time Body Accelerometer -mean()-X



plot of chunk distribution

0 missing values.

Summary statistics

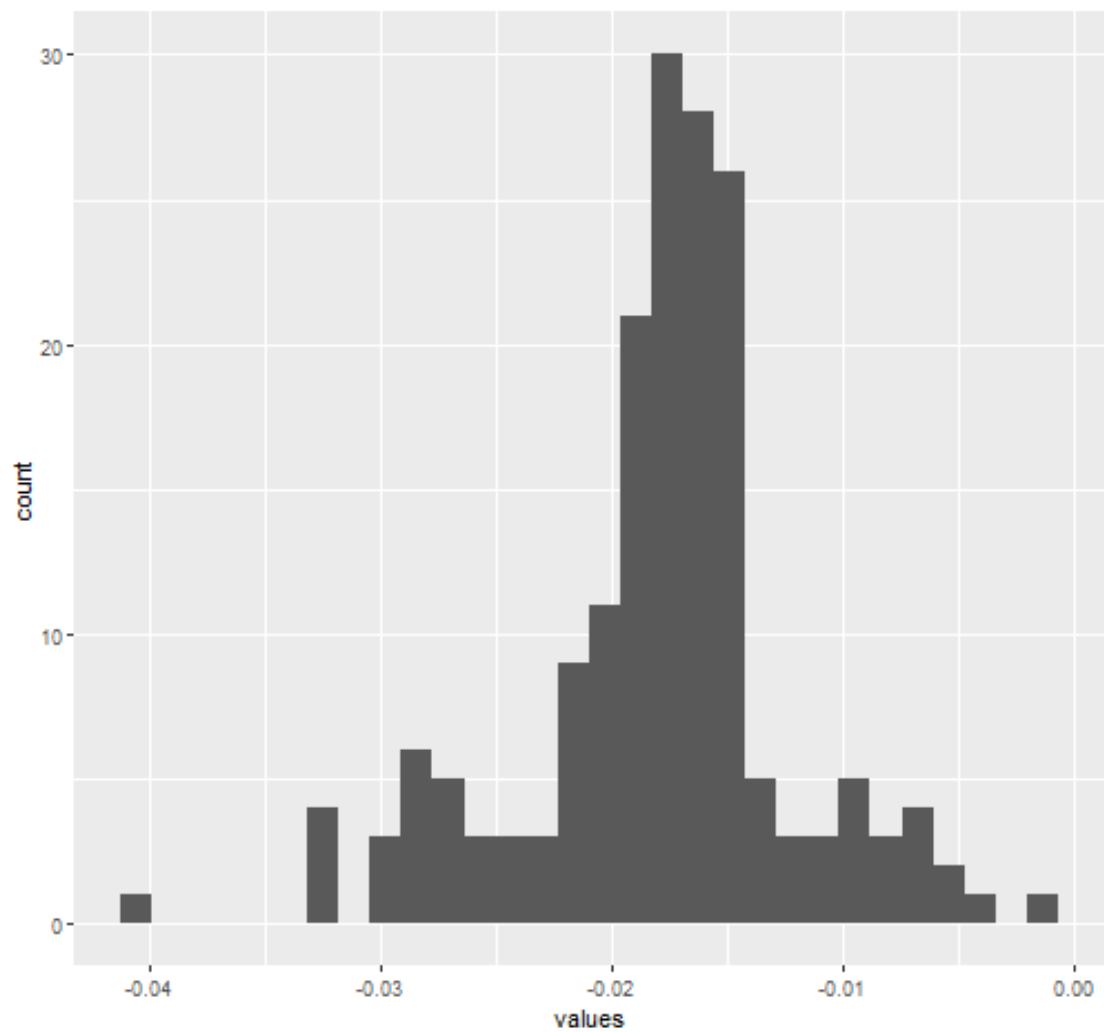
name	dat	mi	co	n	m	s	p	p	p	p	p	hist
------	-----	----	----	---	---	---	---	---	---	---	---	------

	a_type	ssi	mp	lete	e	d	0	2	5	7	1	
					a			5	0	5	0	
					n						0	
time	nu	0	18	1	0.	0.	0	0	0	0	0.	<U+2581><U+2581><U+2581><
Body	me		0	8	2	0	.	.	.	.	3	U+2581><U+2582><U+2587><U
Accel	ric			0	7	1	2	2	2	2		+2582><U+2581>
erom						2	2	7	8	8		
eter -												
mean												
()-X												

time Body Accelerometer -mean()-Y

Distribution

time Body Accelerometer -mean()-Y



plot of chunk distribution

0 missing values.

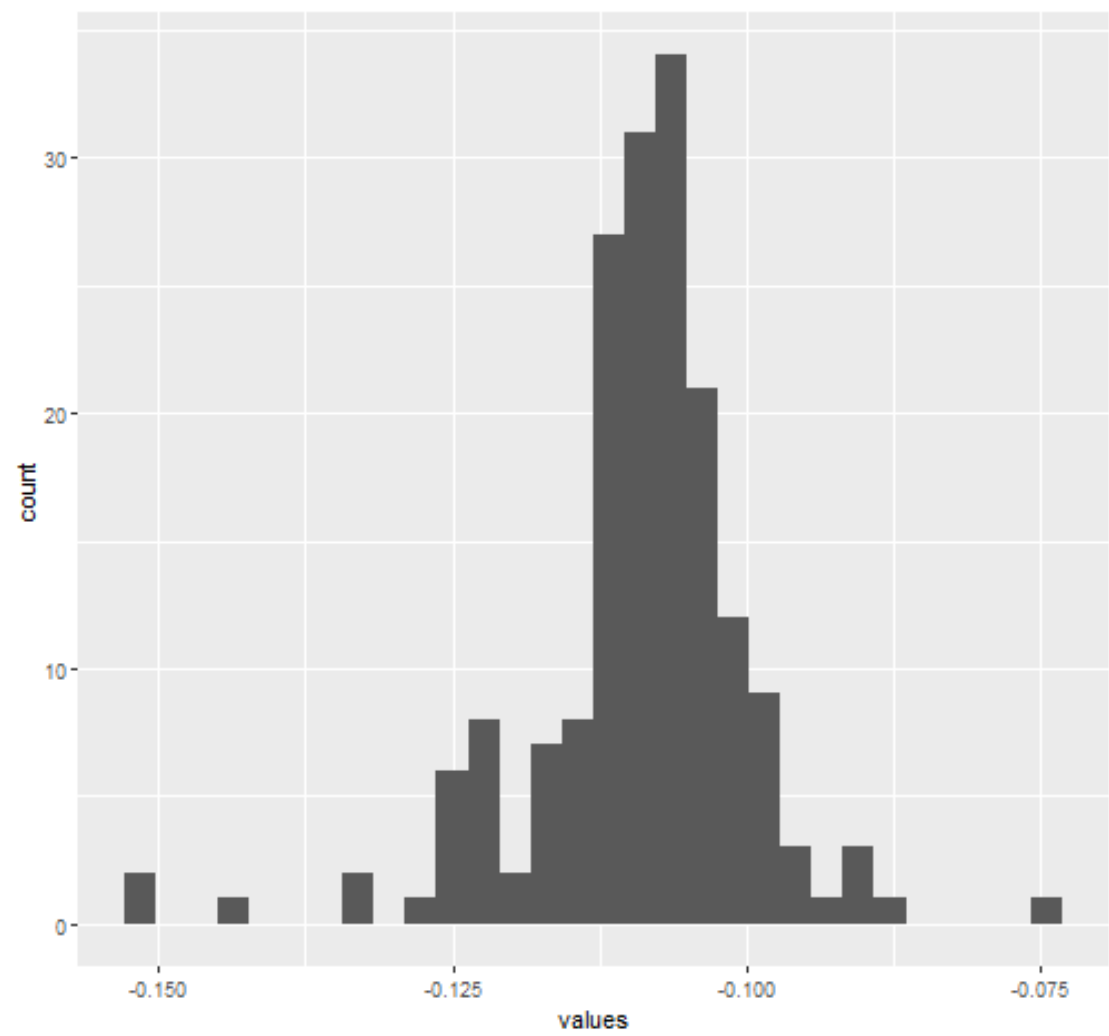
## Summary statistics

[illegible]

time Body Accelerometer -mean()-Z

Distribution

time Body Accelerometer -mean()-Z



plot of chunk distribution

0 missing values.

Summary statistics

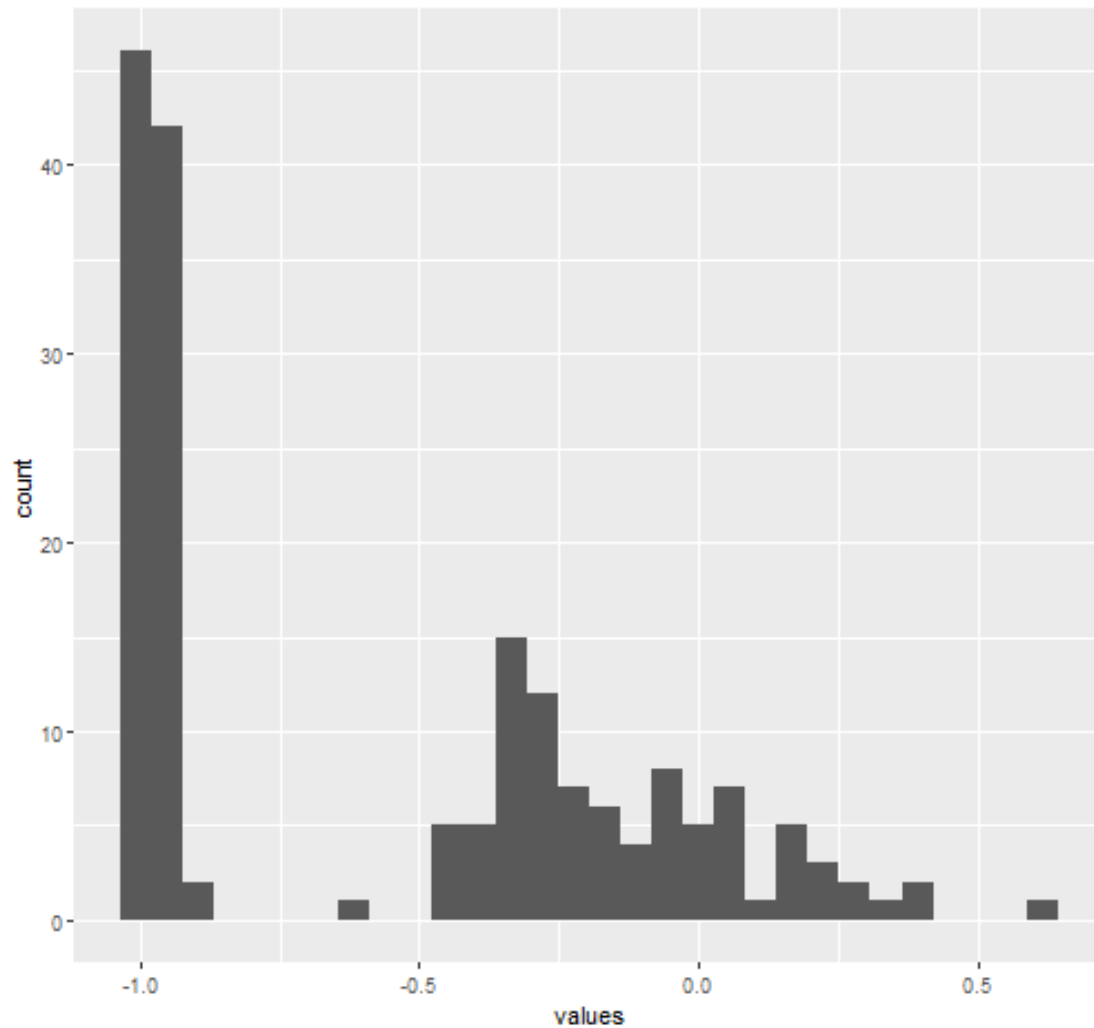
		co		m				p		p		hist
		dat	mi	mp	e			p	p	p	1	
		a_t	ssi	let	a	p	2	5	7	0	0	
name	type	ng	e	n	n	sd	0	5	0	5	0	
time	nu	0	18	1	-	0.	-	-	-	-	-	<U+2581><U+2581><U+2581><
Body	me		0	8	0.	00	0	0	0	0	0.	U+2582><U+2587><U+2583><U
Accel	ric			0	1	96	.	.	.	.	0	+2581><U+2581>

erom	1	1	1	1	7
eter -		5	1	1	5
mean					
0-Z					

## time Body Accelerometer -std()-X

## Distribution

time Body Accelerometer -std()-X



*plot of chunk distribution*

0 missing values.

## Summary statistics

	dat	mi	co		m		p	p	p	p		
	a_t	ssi	mp		e	s	p	2	5	7	1	
name	ype	ng	lete	n	a	d	0	5	0	5	0	hist

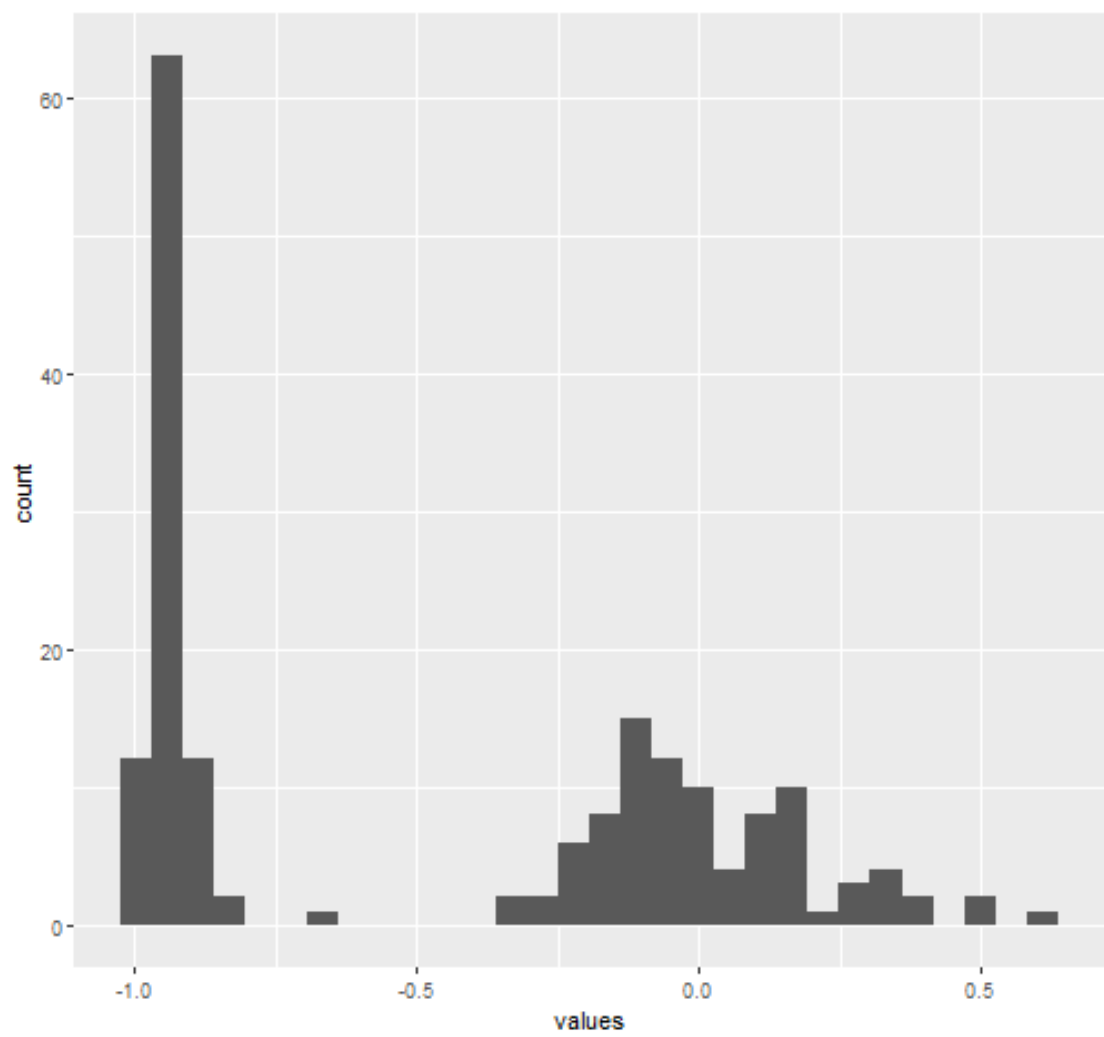


				n						0	
time	nu	0	18	1	-	0.	-	-	-	0.	<U+2587><U+2581><U+2581><U
Body	me		0	8	0.	4	1	0.	0.	0	+2583><U+2582><U+2582><U+2
Accel	ric			0	5	5		9	7	.	581><U+2581>
erom					6			8	5	2	
eter -											
std()-											
X											

time Body Accelerometer -std()-Y

Distribution

time Body Accelerometer -std()-Y



plot of chunk distribution

0 missing values.

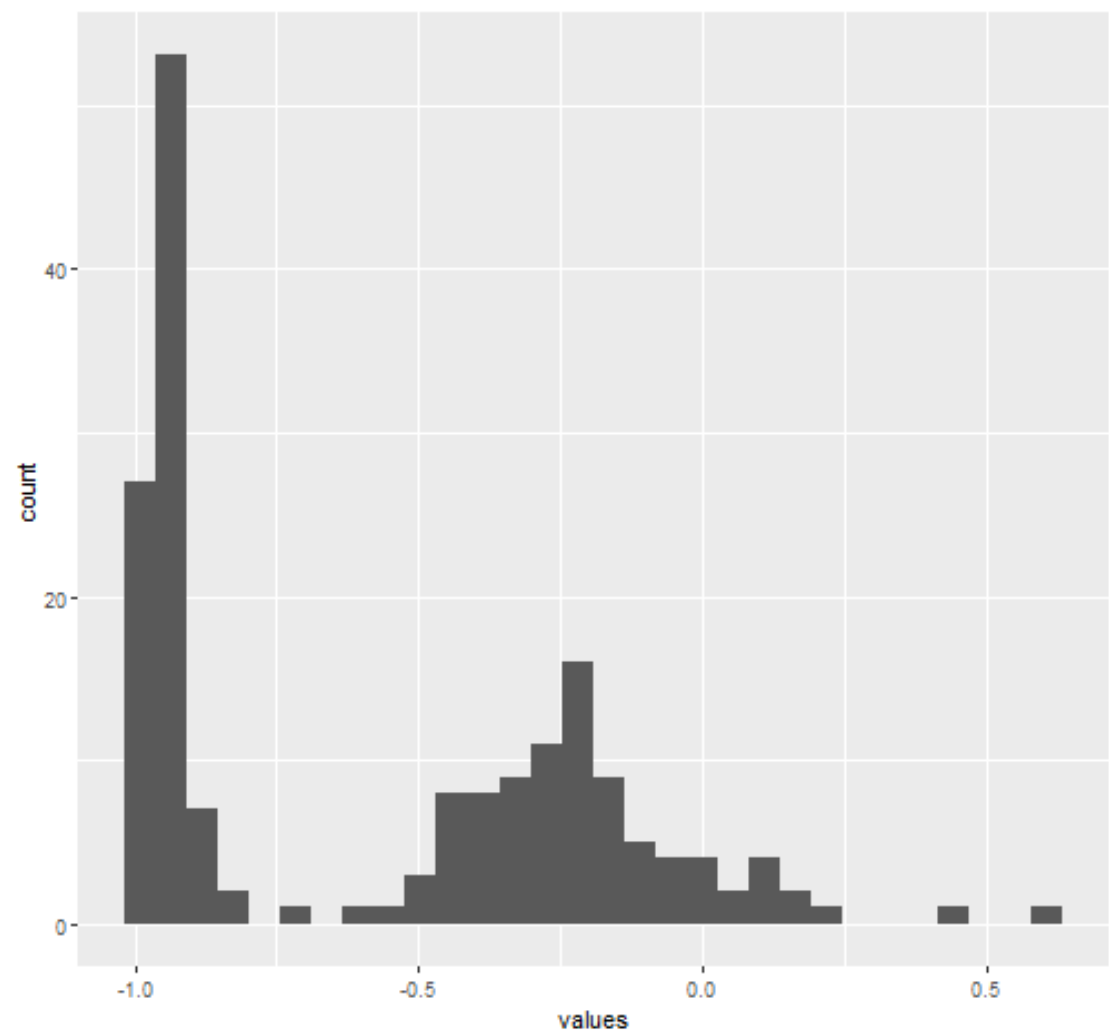
## Summary statistics

[illegible]

time Body Accelerometer -std()-Z

Distribution

time Body Accelerometer -std()-Z



plot of chunk distribution

0 missing values.

Summary statistics

name	data type	missing	complete	mean							p1	hist
				n	min	std	p0	p2	p5	p7		
time	numeric	0	18	1	-0.80	0.49	-	-	-	-	0.6	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581>
Body	me		0	8	0.	.	0.	0.	0.	0.	6	
Accel	ric			0	5	4	9	9	6	2	1	

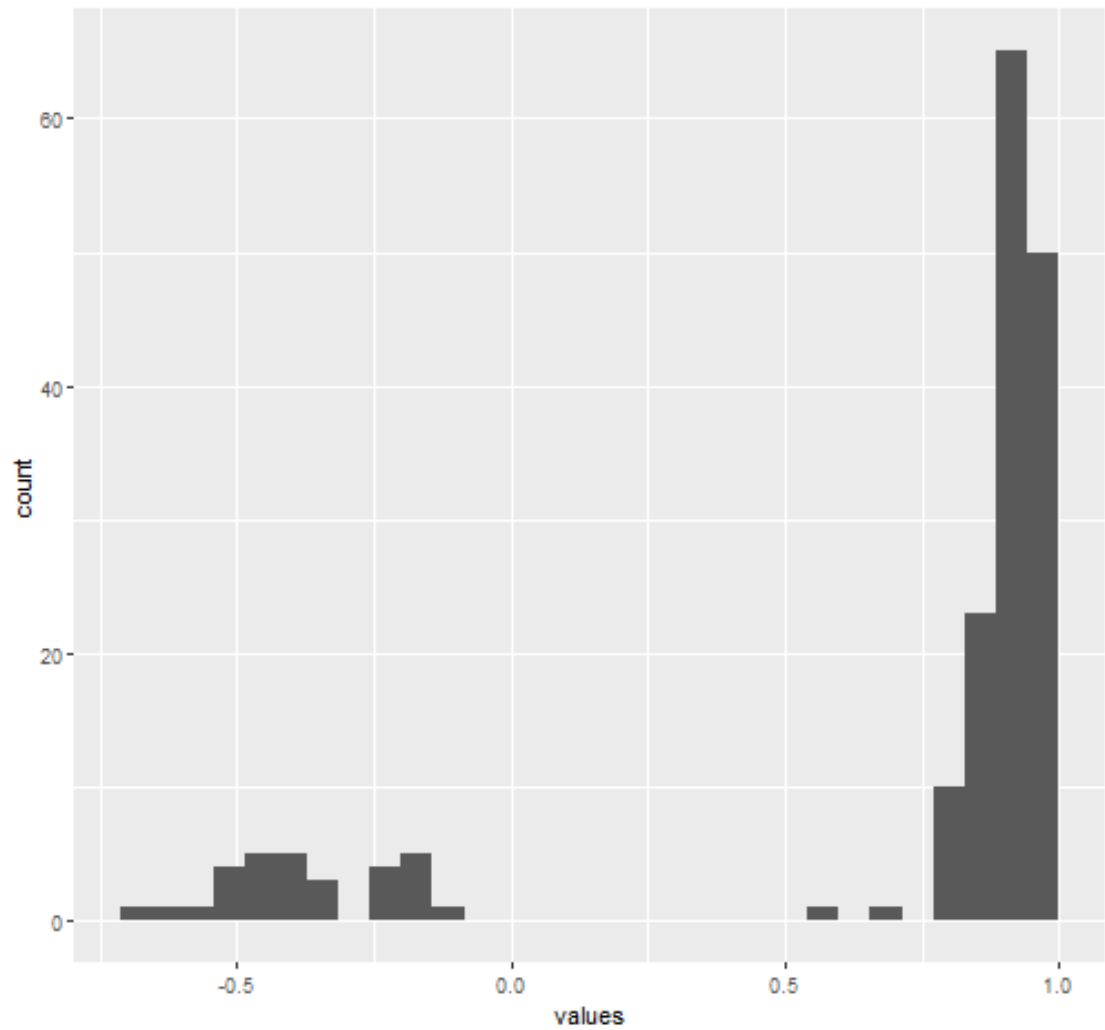
erom  
eter -  
std()-  
Z

8 9 5 5 3

time Gravity Accelerometer -mean()-X

Distribution

time Gravity Accelerometer -mean()-X



plot of chunk distribution

0 missing values.

Summary statistics

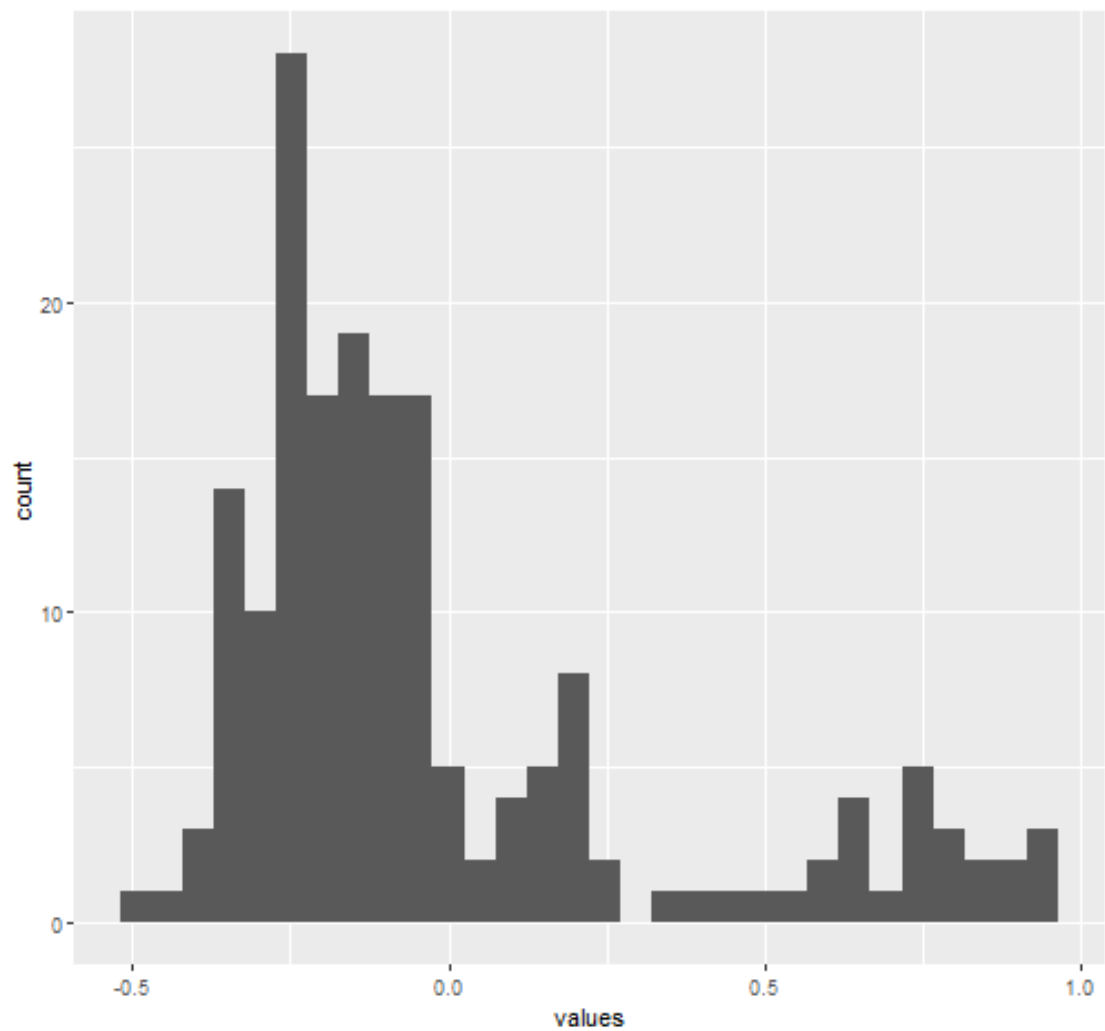
	dat	mi	co	m		p	p	p	p	
	a_t	ssi	mp	e	s	p	2	5	7	1
name	type	ng	lete	n	a	d	0	5	0	hist

					n						0	
time	nu	0	18	1	0.	0	-	0	0	0	0.	<U+2581><U+2581><U+2581><
Gravi	me		0	8	7	.	0	.	.	.	9	U+2581><U+2581><U+2581><U
ty	ric			0		4	.	8	9	9	7	+2581><U+2587>
Accel						9	6	4	2	4		
erom							8					
eter -												
mean												
()-X												

time Gravity Accelerometer -mean()-Y

Distribution

time Gravity Accelerometer -mean()-Y



plot of chunk distribution

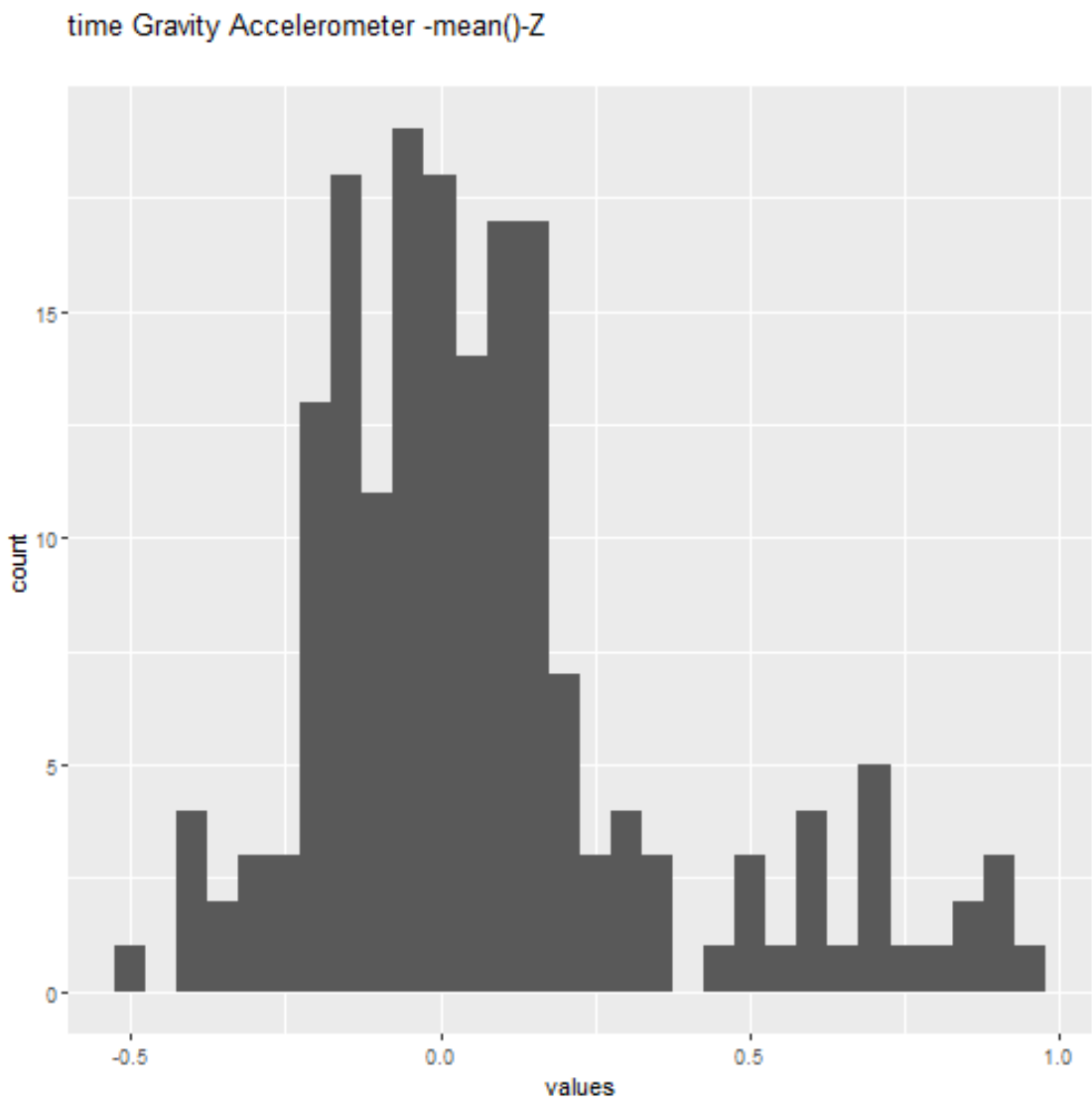
0 missing values.

### Summary statistics

name	data type	missing	complete	n	mean	std	p0	p2	p5	p7	p10	hist
time	numeric	0	18	1	-	0	-	-	-	0.	0.	<U+2582><U+2587><U+2585><
Gravity	metric		0	8	0.	.	0	0	0	0	9	U+2582><U+2581><U+2581><U
Acceleration - mean				0	0	3	.	.	.	8	6	+2581><U+2581>
Q-Y					1	5	4	2	1	8		
					6		8	3	3			

time Gravity Accelerometer -mean()-Z

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

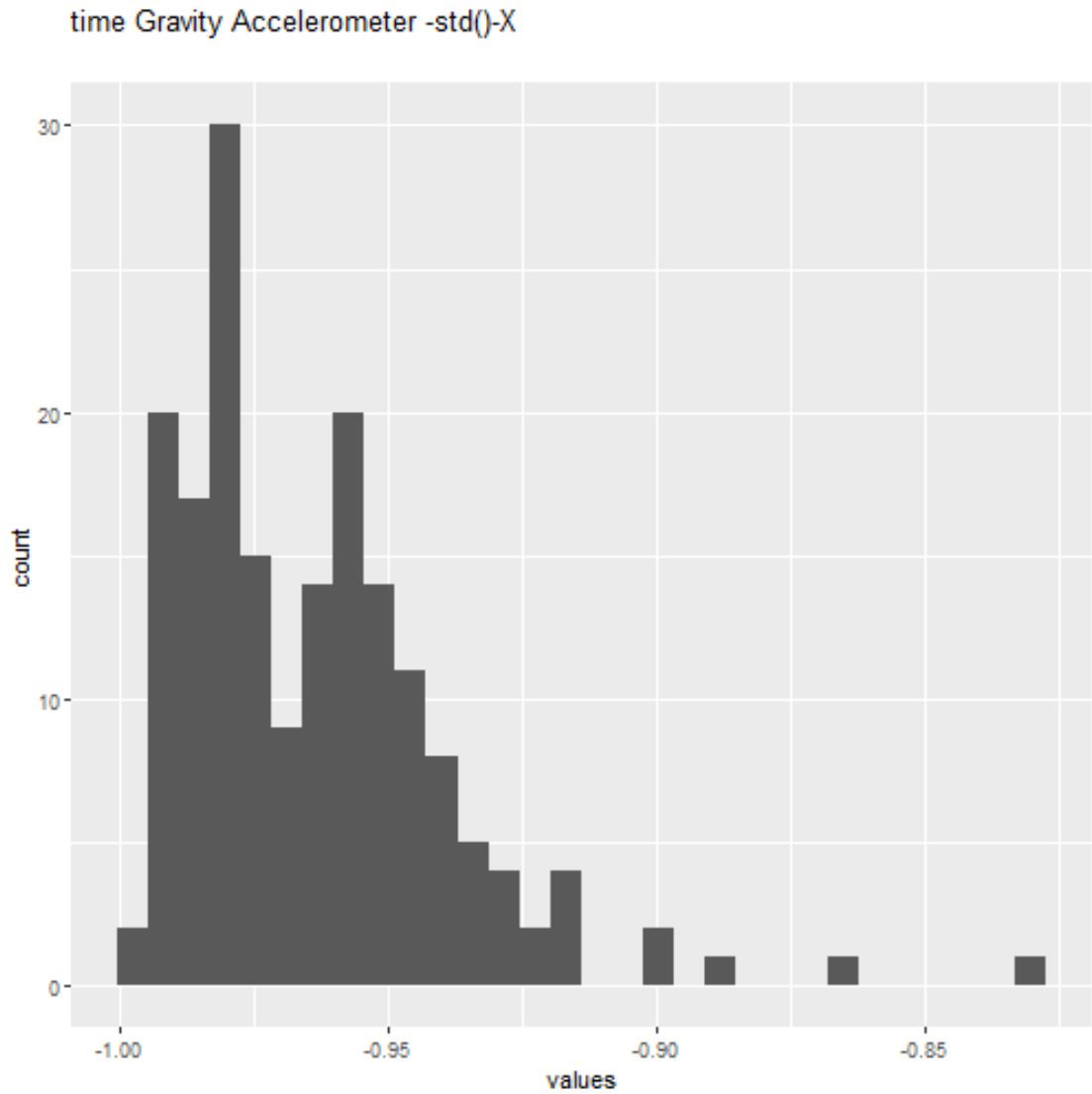
p										
1										
0										
hist										
name	type	count	missing	complete	min	max	std	p2	p5	p7
time Gravity Accelerometer -mean()-Z	numeric	180	0	180	1.08	0.72	0.2	0.0	0.0	0.1

Accelerometer - mean() - Z

4 9 5 1 4 5  
2

time Gravity Accelerometer -std()-X

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

	dat	mi	co	m	p	p	p	p	p			
name	a_t	ssi	mp	n	e	sd	0	2	5	7	1	hist

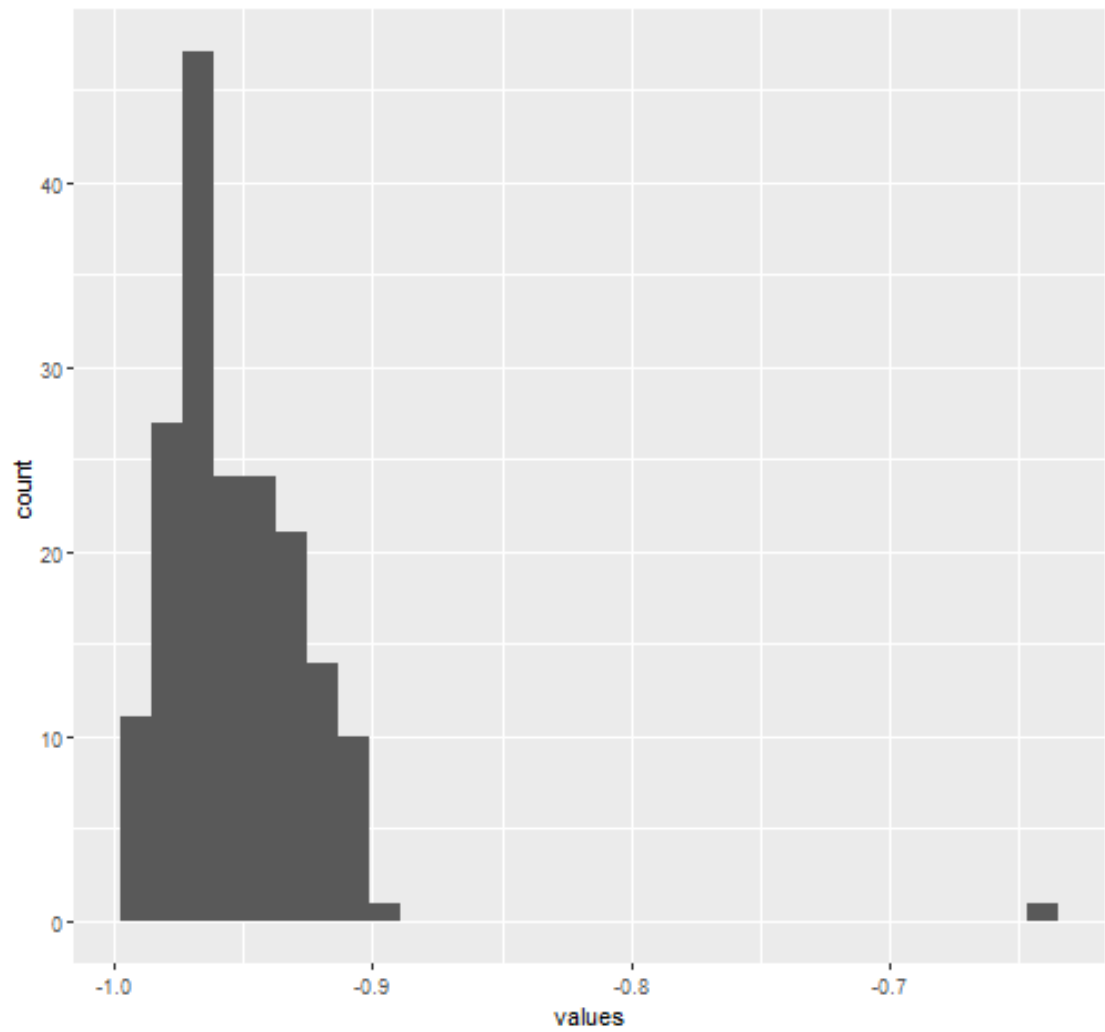


	type	ng	lete	a		5		0		5		0	
				n									
time	nu	0	18	1	-	0.	-	-	-	-	-	<U+2587><U+2586><U+2585><	
Gravi	me		0	8	0.	0	1	0.	0.	0.	0.	U+2582><U+2581><U+2581><U	
ty	ric			0	9	2		9	9	9	8	+2581><U+2581>	
Accel				6	5			8	7	5	3		
erom													
eter -													
std()-													
X													

time Gravity Accelerometer -std()-Y

Distribution

time Gravity Accelerometer -std()-Y



plot of chunk distribution

0 missing values.

### Summary statistics

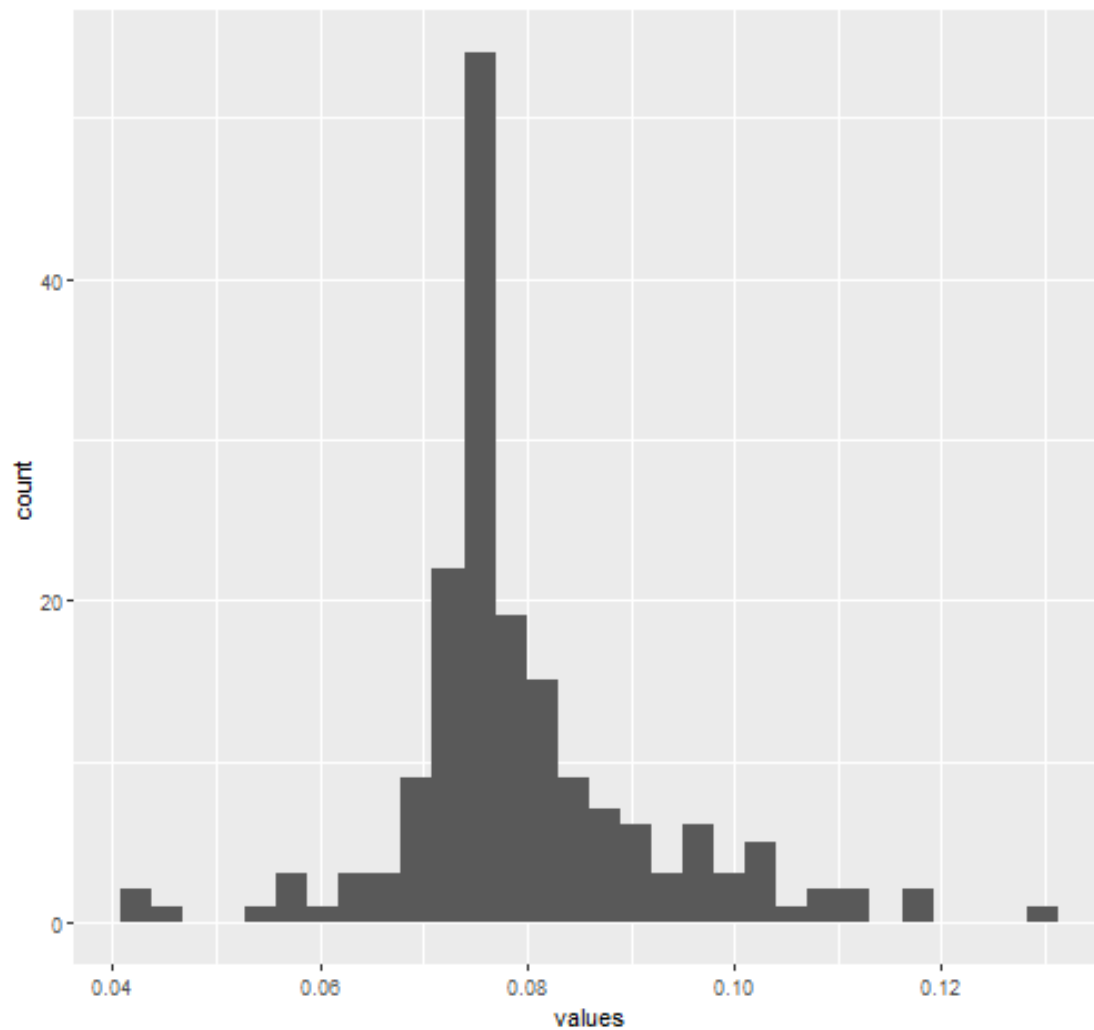
name	data type	missing	complete	mean				prop				hist
				n	min	std	prop	2.5	5	7.5	max	
time	numeric	0	18	1	-	0.	-	-	-	-	-	<U+2587><U+2585><U+2581><
Gravity	numeric		0	8	0.	0	0	0	0	0	0.	U+2581><U+2581><U+2581><U
Accelerometer - std() - Y				0	9	3	.	.	.	.	6	+2581><U+2581>
					5	3	9	9	9	9	4	
							9	7	6	4		



4	4	9	9	9	9	1
		9	6	5	2	

## Distribution

time Body Accelerometer Jerk-mean()-X



*plot of chunk distribution*

0 missing values.

## Summary statistics

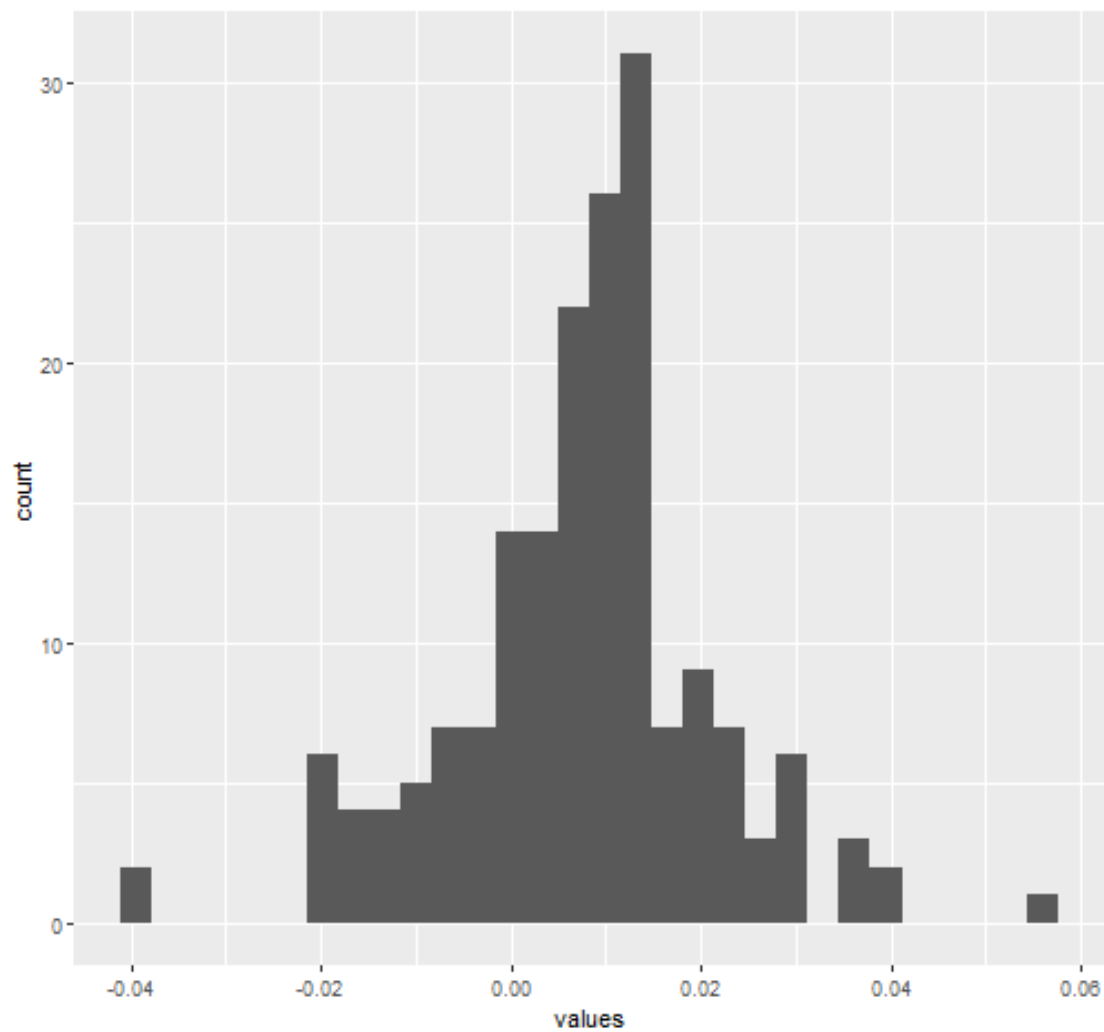
	dat	mi	co		m	s	p	p	p	p			
name	a	t	ssi	mp	n	e	d	0	2	5	7	1	hist

	ype	ng	let e	a n		5	0	5	0		
time	nu	0	18	1	0.	0.	0.	0.	0.	0.	<U+2581><U+2581><U+2587><
Body	me		0	8	0	0	0	0	0	1	U+2587><U+2582><U+2581><
Accel	ric			0	7	1	4	7	7	8	U+2581><U+2581>
erom					9	3	3	4	6	3	
eter											
Jerk-											
mean											
()-X											

time Body Accelerometer Jerk-mean()-Y

Distribution

time Body Accelerometer Jerk-mean()-Y



plot of chunk distribution

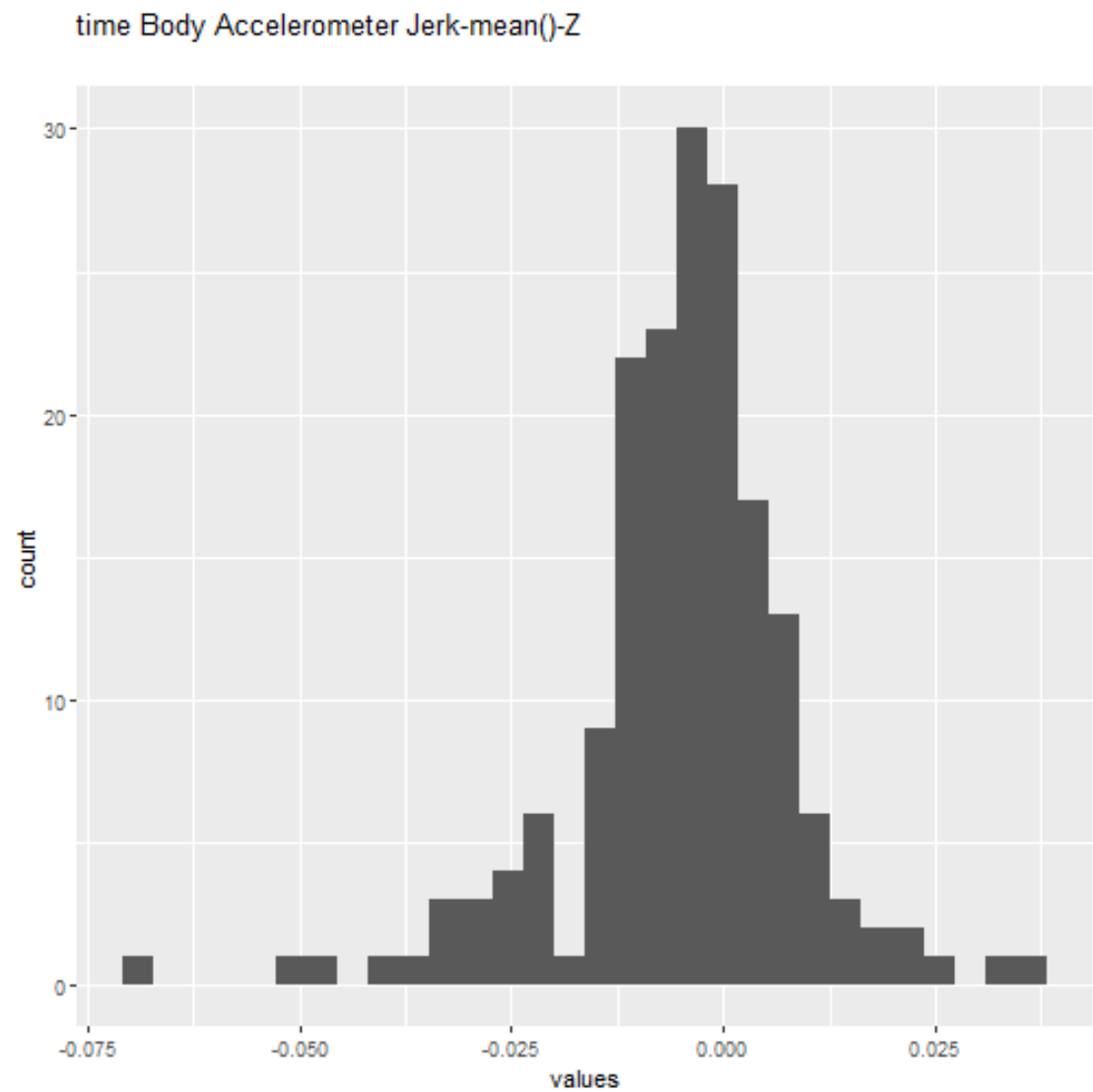
0 missing values.

## Summary statistics

[illegible]

time Body Accelerometer Jerk-mean()-Z

Distribution



plot of chunk distribution

0 missing values.

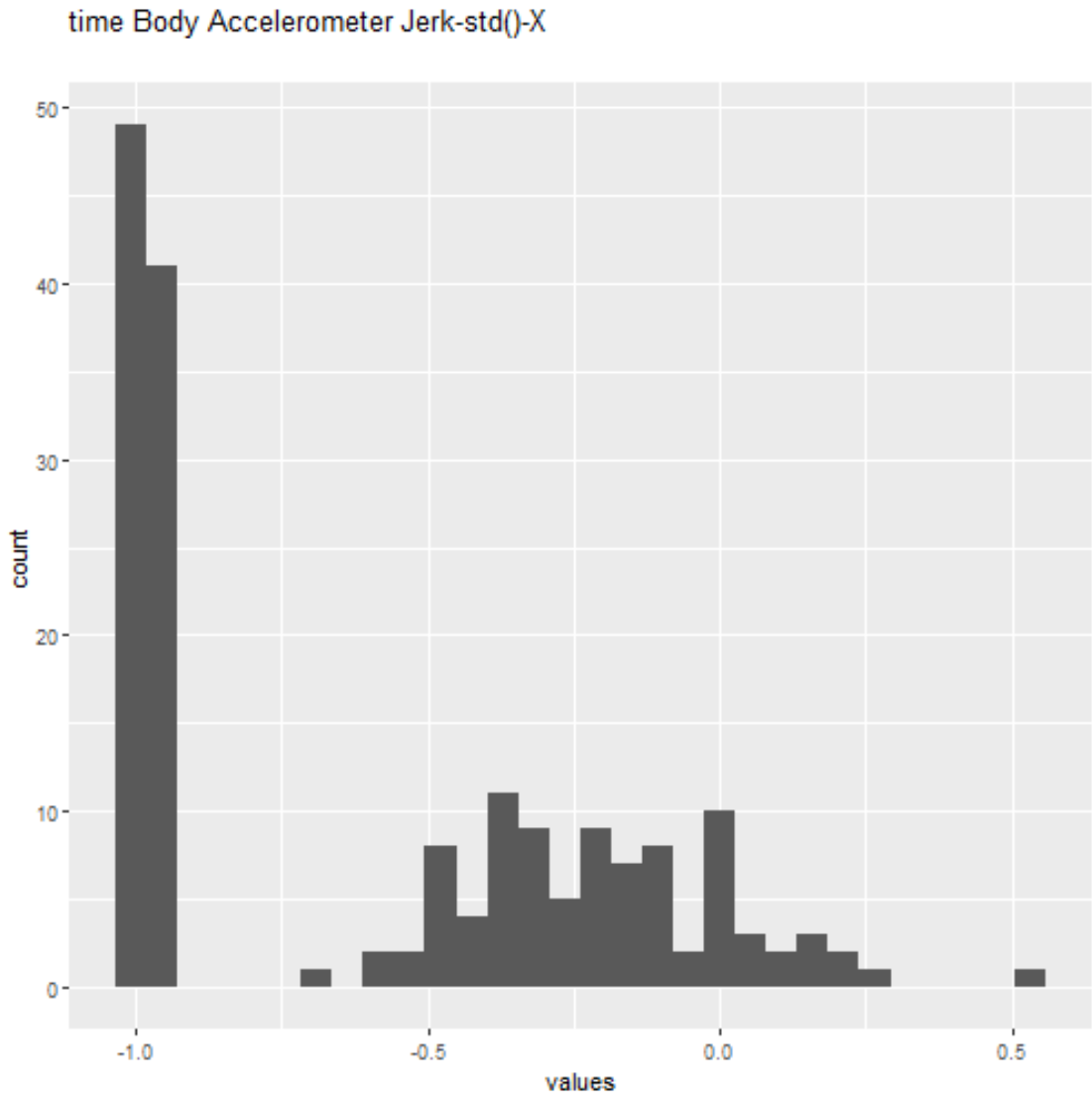
Summary statistics

name	type	n	missing	count	min	max	std	p0	p2.5	p5	p7.5	p10	hist
time	numeric	0	18	1	-	0.	-	-	-	0.	0.	0.	<U+2581><U+2581><U+2581>
Body	me		0	8	0.	0.	0.	0.	0.	0.	0	0	<U+2581><U+2587><U+2586>
Accel	ric			0	0	1	0	0	00	0	3		<U+2581><U+2581>

erom 0 3 6 1 39 2 8  
eter 5 7 1  
Jerk-  
mean  
()-Z

time Body Accelerometer Jerk-std()-X

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

	dat	mi	co	m	s	p	p	p	p	p		
name	a_t	ssi	mp	n	e	d	0	2	5	7	1	hist

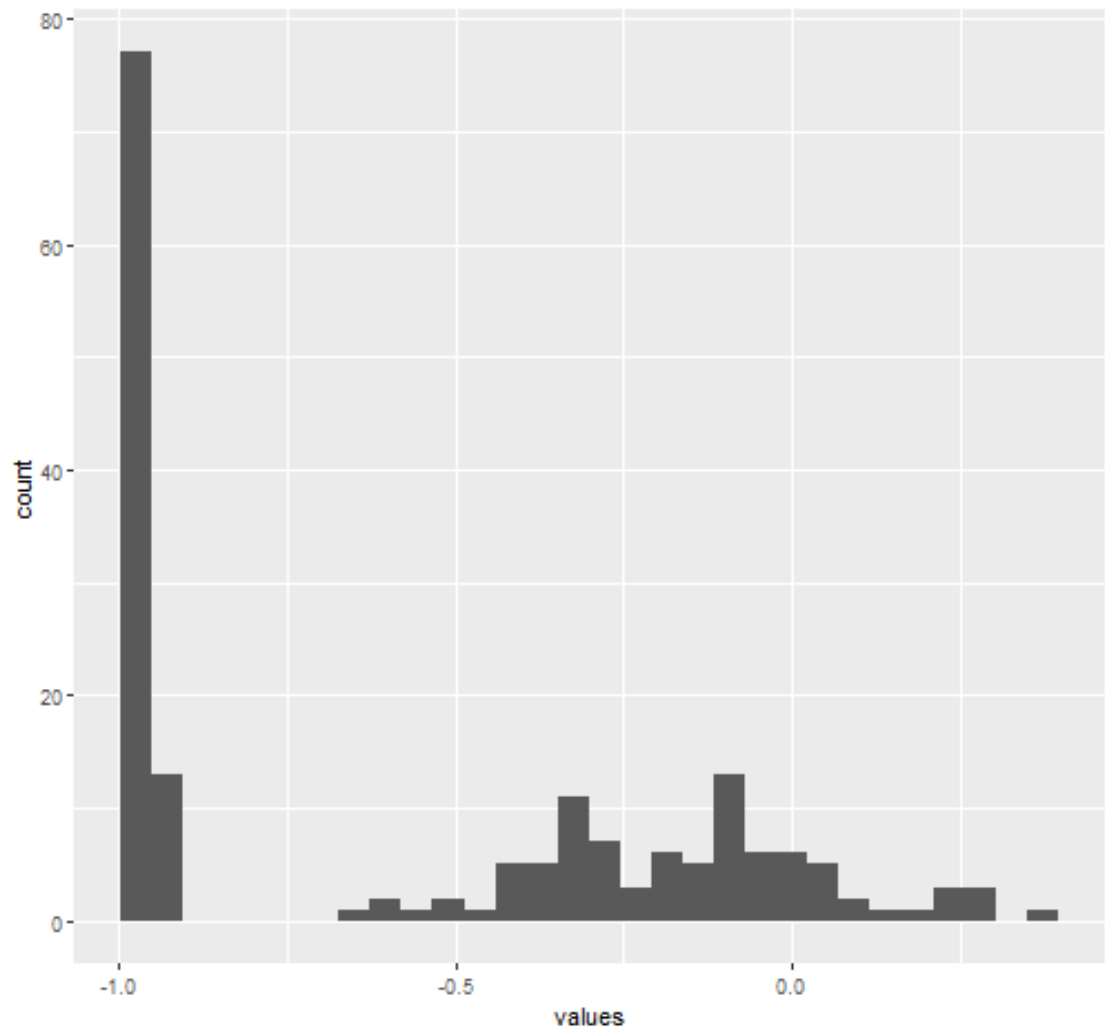


	ype	ng	lete	a		5		0	5	0		
				n						0		
time	nu	0	18	1	-	0	-	-	-	-	0.	<U+2587><U+2581><U+2581><
Body	me		0	8	0.	.	0	0	0	0	5	U+2582><U+2582><U+2582><U
Accel	ric			0	5	4	.	.	.	.	4	+2581><U+2581>
erom					9	2	9	9	8	2		
eter							9	8	1	2		
Jerk-												
std()-												
X												

time Body Accelerometer Jerk-std()-Y

Distribution

time Body Accelerometer Jerk-std()-Y



plot of chunk distribution

0 missing values.

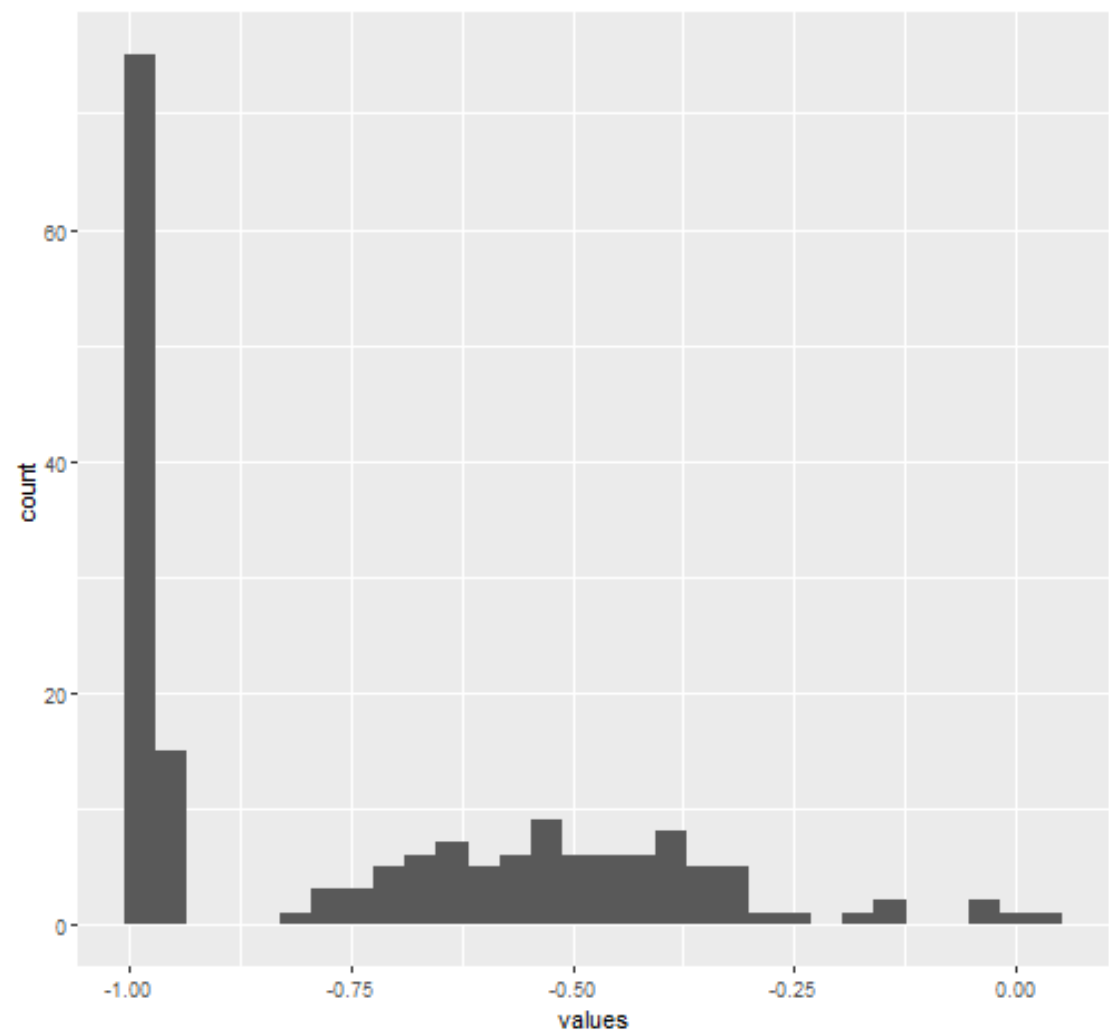
## Summary statistics

[illegible]

time Body Accelerometer Jerk-std()-Z

Distribution

time Body Accelerometer Jerk-std()-Z



plot of chunk distribution

0 missing values.

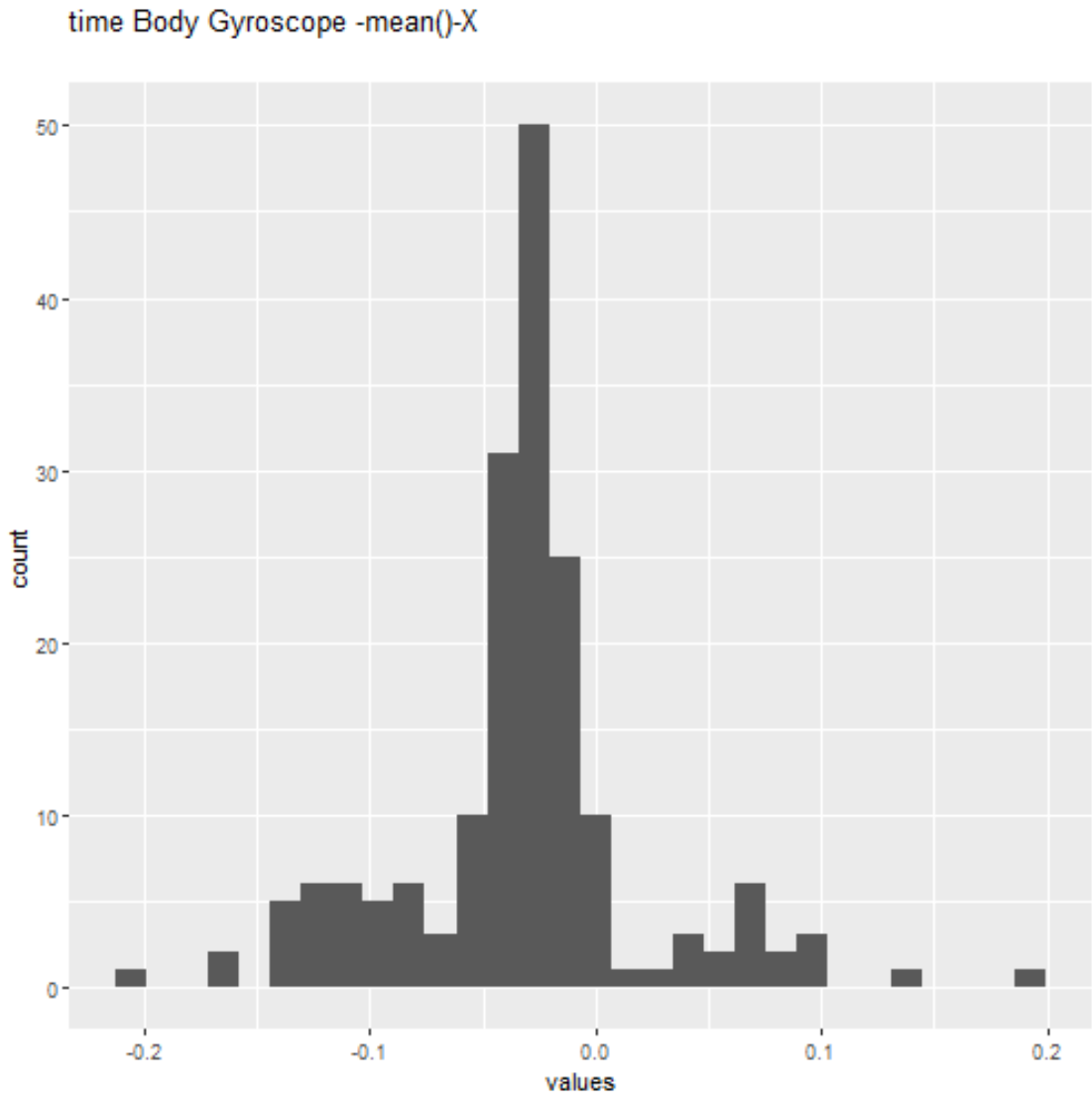
Summary statistics

name	data type	missing	complete	measures of central tendency					measures of dispersion			hist
				n	mean	std	var	sd	min	q1	q3	
time Body Accel	numeric	0	180	180	-0.87	0.07	0.005	0.02	-1.00	-0.95	-0.85	<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581>

erom 4 8 9 9 8 5 1  
eter 9 8 8 1  
Jerk-  
std()-  
Z

time Body Gyroscope -mean()-X

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

name	data_type	missing	count	mean	std	p0	p2	p5	p7	p1	hist
------	-----------	---------	-------	------	-----	----	----	----	----	----	------

[illegible]

	dat	mi	co	m			p			p		
na	a_t	ssi	mp	ea		p	2	5	7	0		
me	ype	ng	lete	n	n	sd	0	5	0	5	0	hist
tim	nu	0	18	1	-	0.	-	-	-	-	0.	<U+2581><U+2581><U+2581><U
e	me		0	8	0.	0	0	0.	0.	0.	0	+2583><U+2587><U+2582><U+2
Bod	ric			0	0	3	.	0	0	0	2	581><U+2581>

```

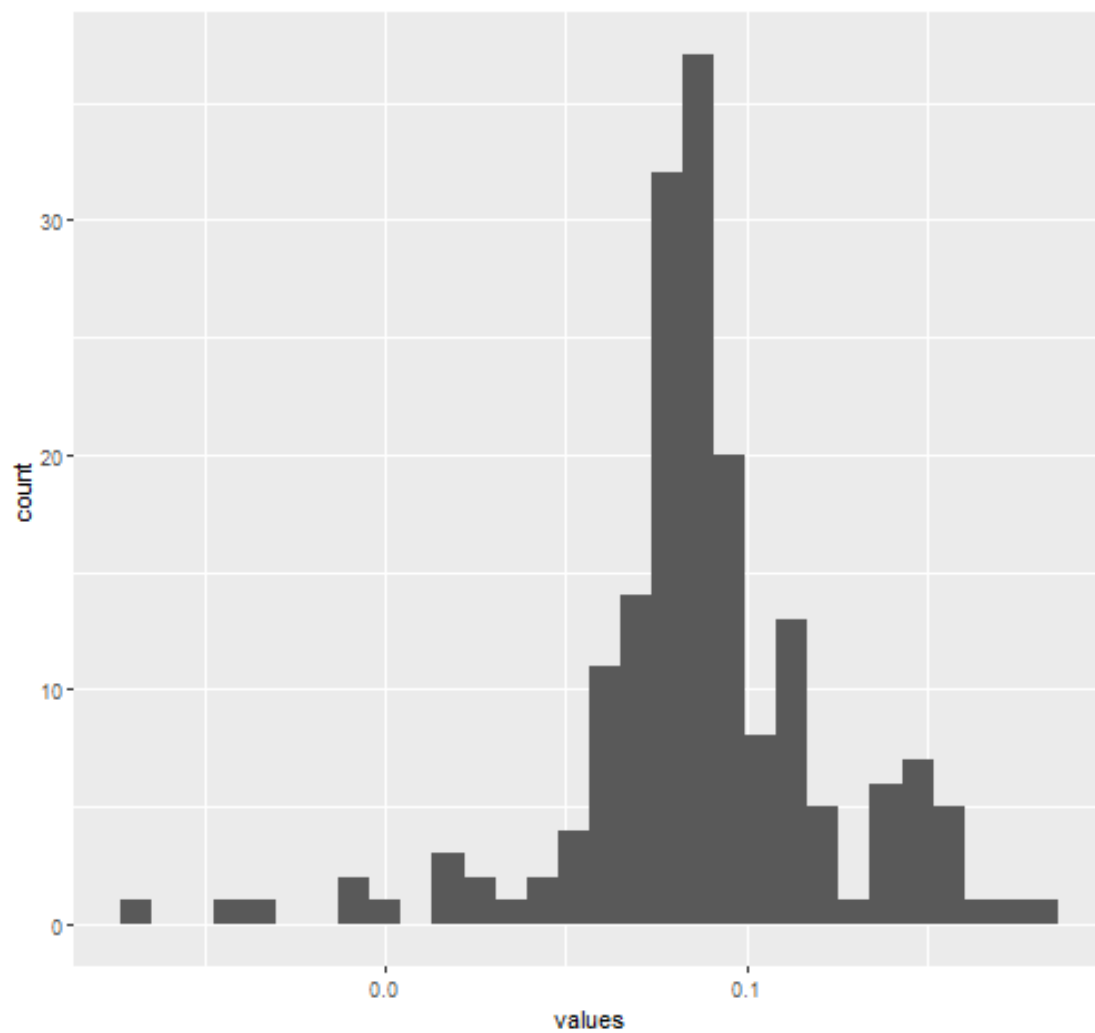
y
Gyr      7  6  2  9  7  6  7
osc      4          3  1
ope
-
mea
n()-
Y

```

time Body Gyroscope -mean()-Z

Distribution

time Body Gyroscope -mean()-Z



*plot of chunk distribution*

0 missing values.

[illegible]

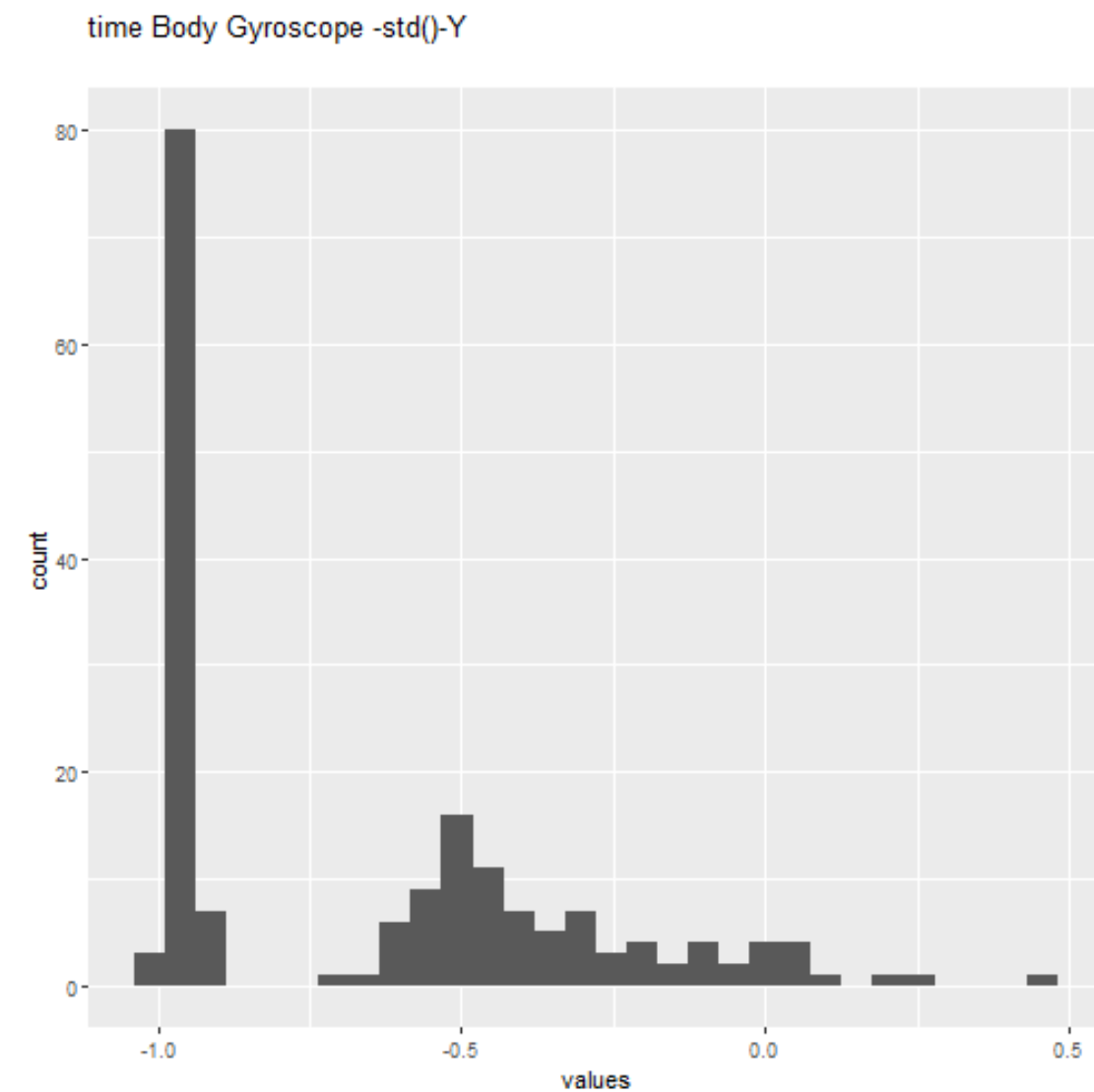


	dat	mi	co			m			p	p	p	p
na	a_ty	ssi	mp	ea	s	p	2	5	7	0	hist	
me	pe	ng	lete	n	n	d	0	5	0	5	0	
tim	nu	0	18	1	-	0.	-	-	-	-	0.	<U+2587><U+2581><U+2582><U
e	me		0	8	0.	2	0.	0.	0.	0.	2	+2583><U+2582><U+2581><U+2
Bod	ric			0	6	9	9	9	7	4	7	581><U+2581>

y  
Gyr  
osc  
ope  
-  
std(  
)-X

time Body Gyroscope -std()-Y

Distribution



plot of chunk distribution

0 missing values.

## Summary statistics

[illegible]

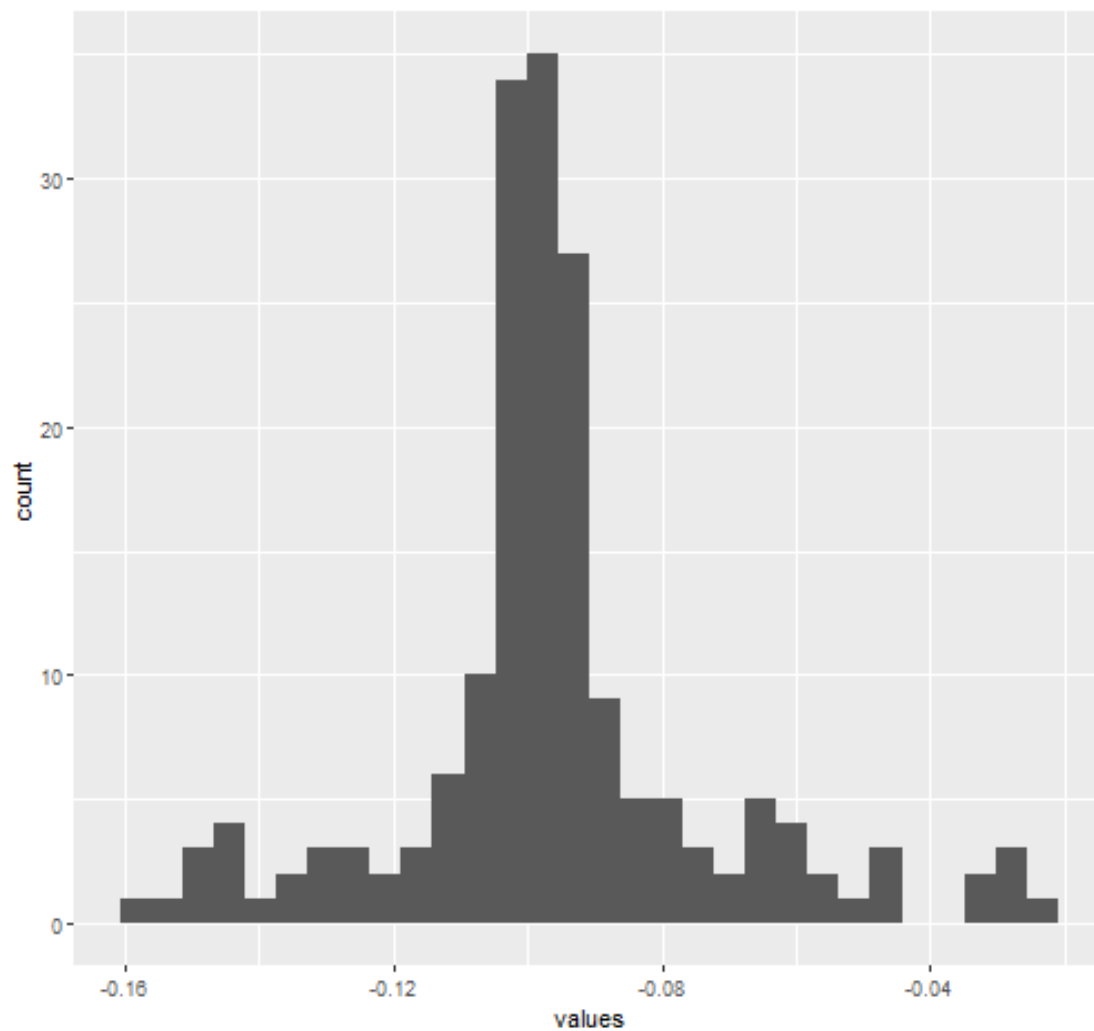
	dat	mi	co			m			p	p	p	p
nam	a_ty	ssi	mp	ea	s	p	2	5	0	5	0	hist
e	pe	ng	lete	n	n	d	0	5	0	5	0	
tim	nu	0	18	1	-	0.	-	-	-	-	0.	<U+2587><U+2581><U+2582><U
e	me		0	8	0.	3	0.	0.	0	0.	5	+2583><U+2582><U+2581><U+2
Bod	ric			0	6	7	9	9	.	3	6	581><U+2581>

y  
Gyr  
osc  
ope  
-  
std(  
)-Z

time Body Gyroscope Jerk-mean()-X

Distribution

time Body Gyroscope Jerk-mean()-X



*plot of chunk distribution*

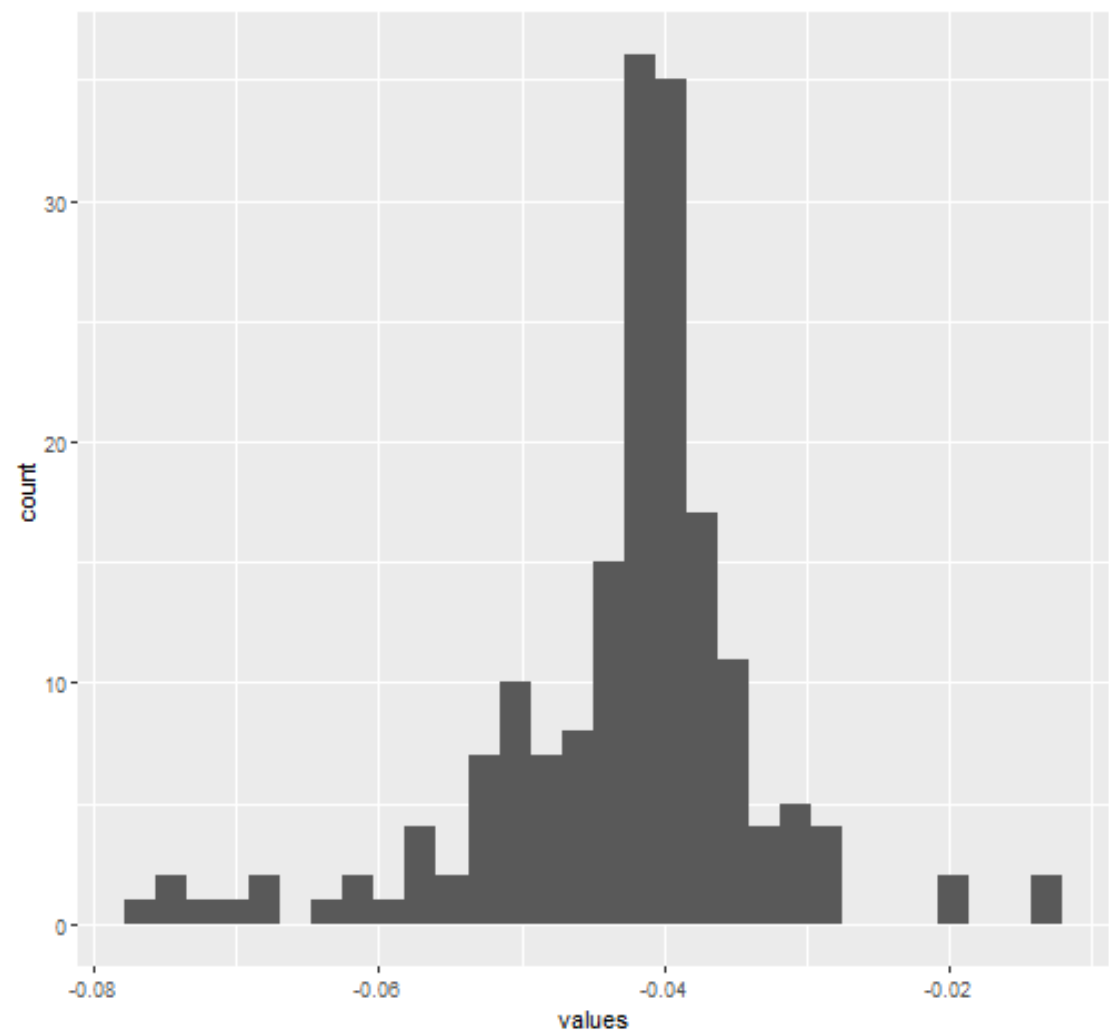
0 missing values.

[illegible]

time Body Gyroscope Jerk-mean()-Y

Distribution

time Body Gyroscope Jerk-mean()-Y



plot of chunk distribution

0 missing values.

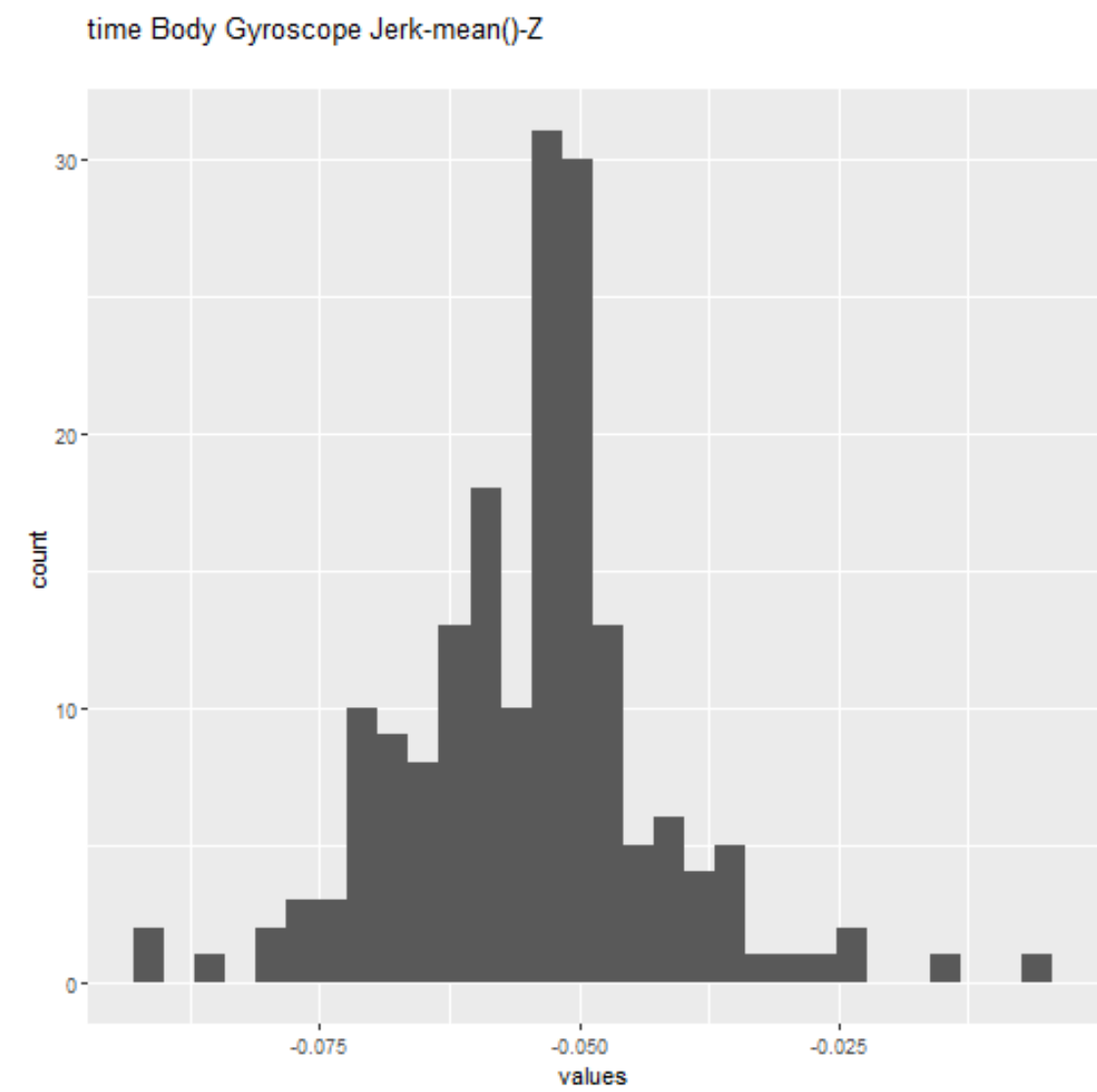
Summary statistics

		co	m								p
		dat	mi	mp	e		p	p	p	1	
na	a_t	ssi	let	n	a	p	2	5	7	0	hist
me	type	ng	e		sd	0	5	0	5	0	
tim	nu	0	18	1	-	0.	-	-	-	-	<U+2581><U+2581><U+2581><
e	me		0	8	0.	00	0.	0.	0.	0.	U+2582><U+2587><U+2582><U
Bod	ric			0	0	95	0	0	0	0	+2581><U+2581>

y	4	7	4	4	3	1
Gyr	3	7	6	1	8	3
osc						
ope						
Jerk						
-						
me						
an(						
)-Y						

time Body Gyroscope Jerk-mean()-Z

Distribution



plot of chunk distribution

0 missing values.

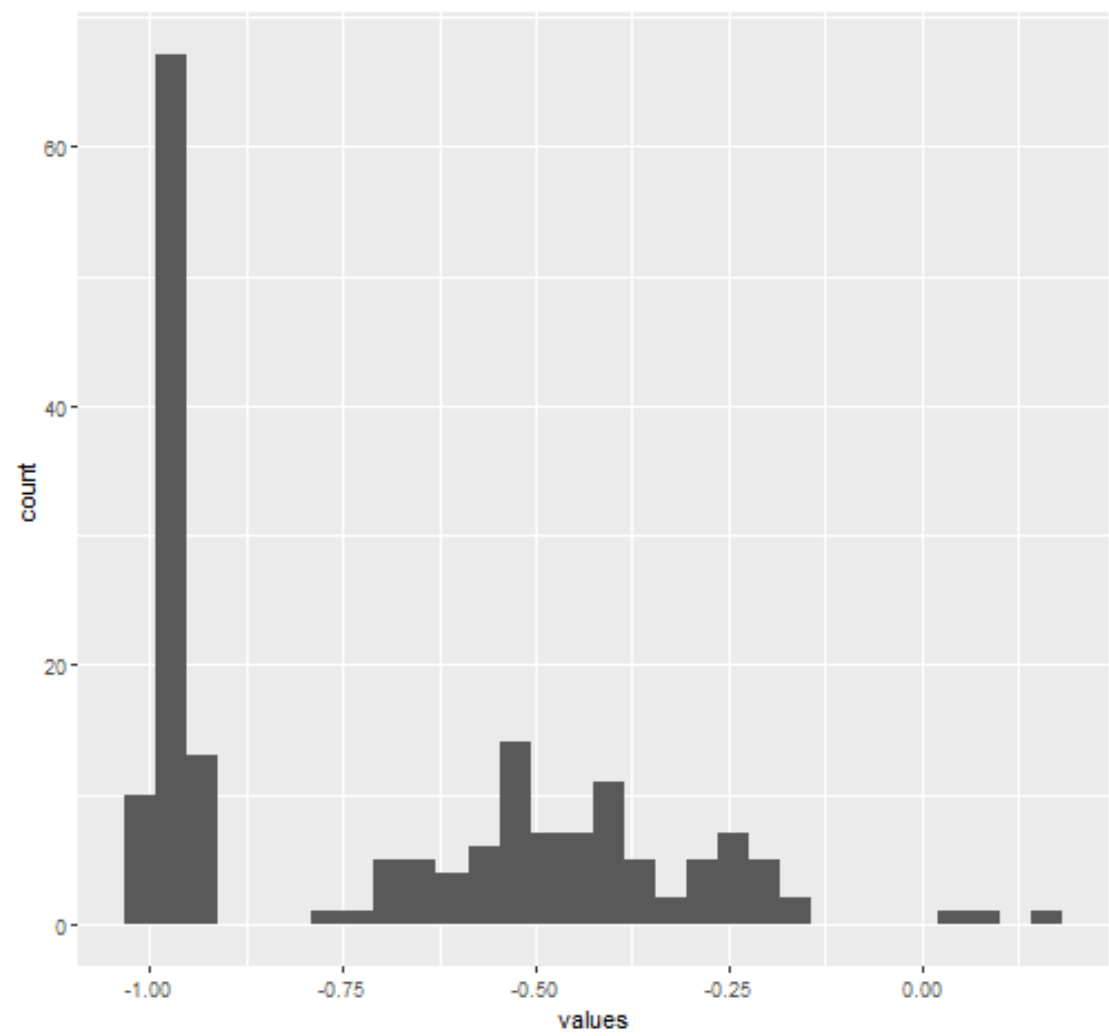


[illegible]

time Body Gyroscope Jerk-std()-X

Distribution

time Body Gyroscope Jerk-std()-X



plot of chunk distribution

0 missing values.

Summary statistics

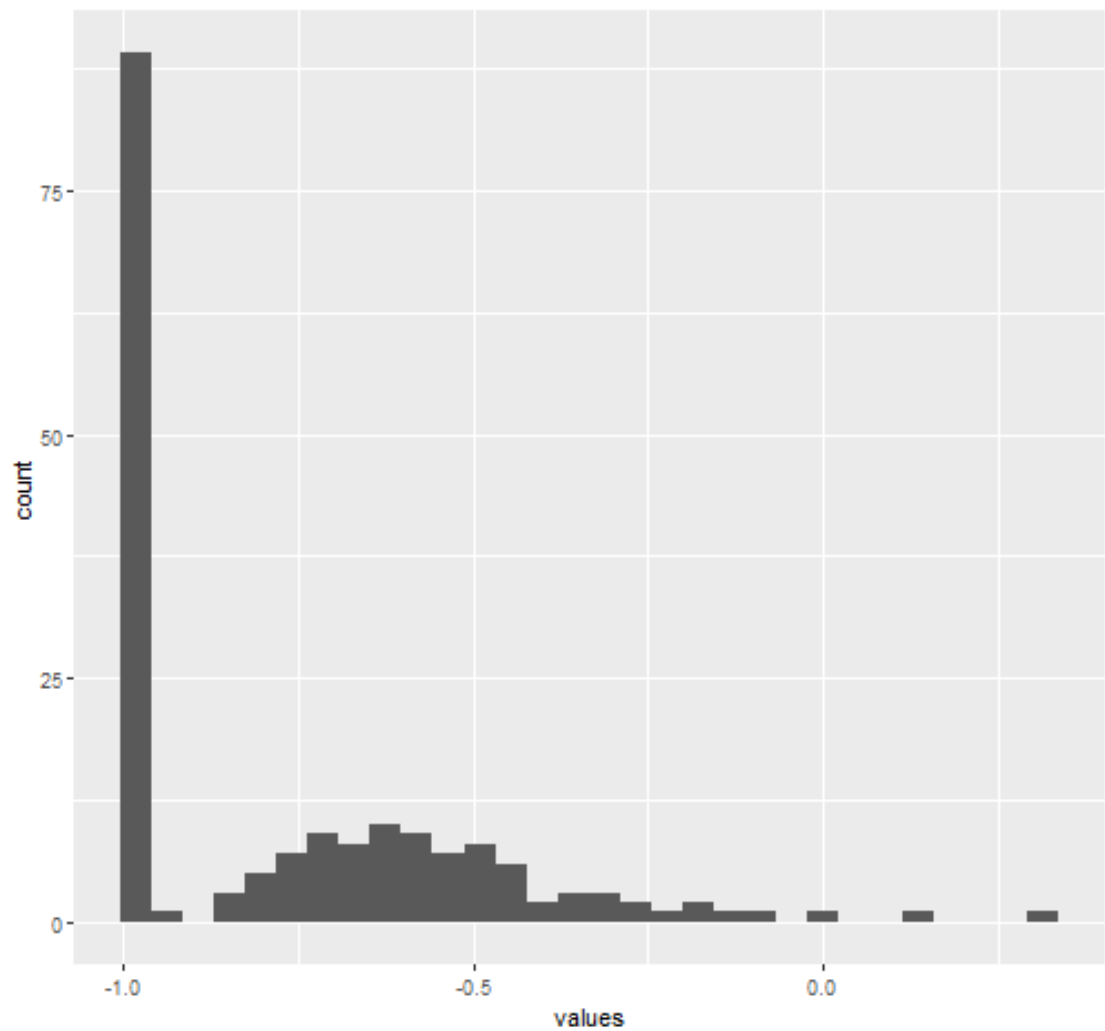
name	date	missing	complete	n	mean	std	p0	p2	p5	p7	p10	hist
time	numeric	0	180	180	-0.7	0.3	-0.9	-0.5	-0.2	-0.1	0.1	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581>

y  
Gyr  
osc  
ope  
Jerk  
-  
std(  
)-X

time Body Gyroscope Jerk-std()-Y

Distribution

time Body Gyroscope Jerk-std()-Y



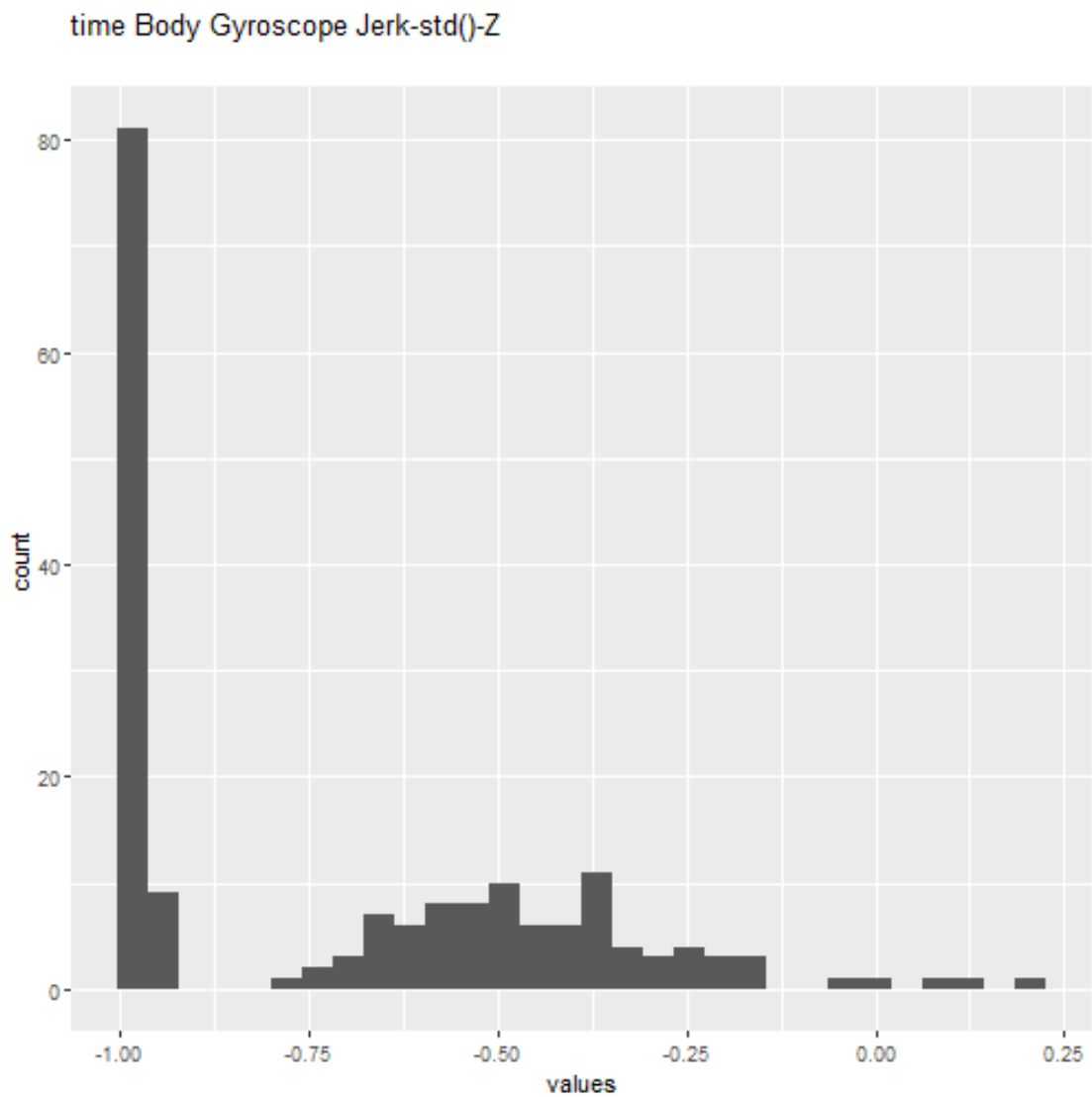
plot of chunk distribution

0 missing values.

[illegible]

time Body Gyroscope Jerk-std()-Z

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

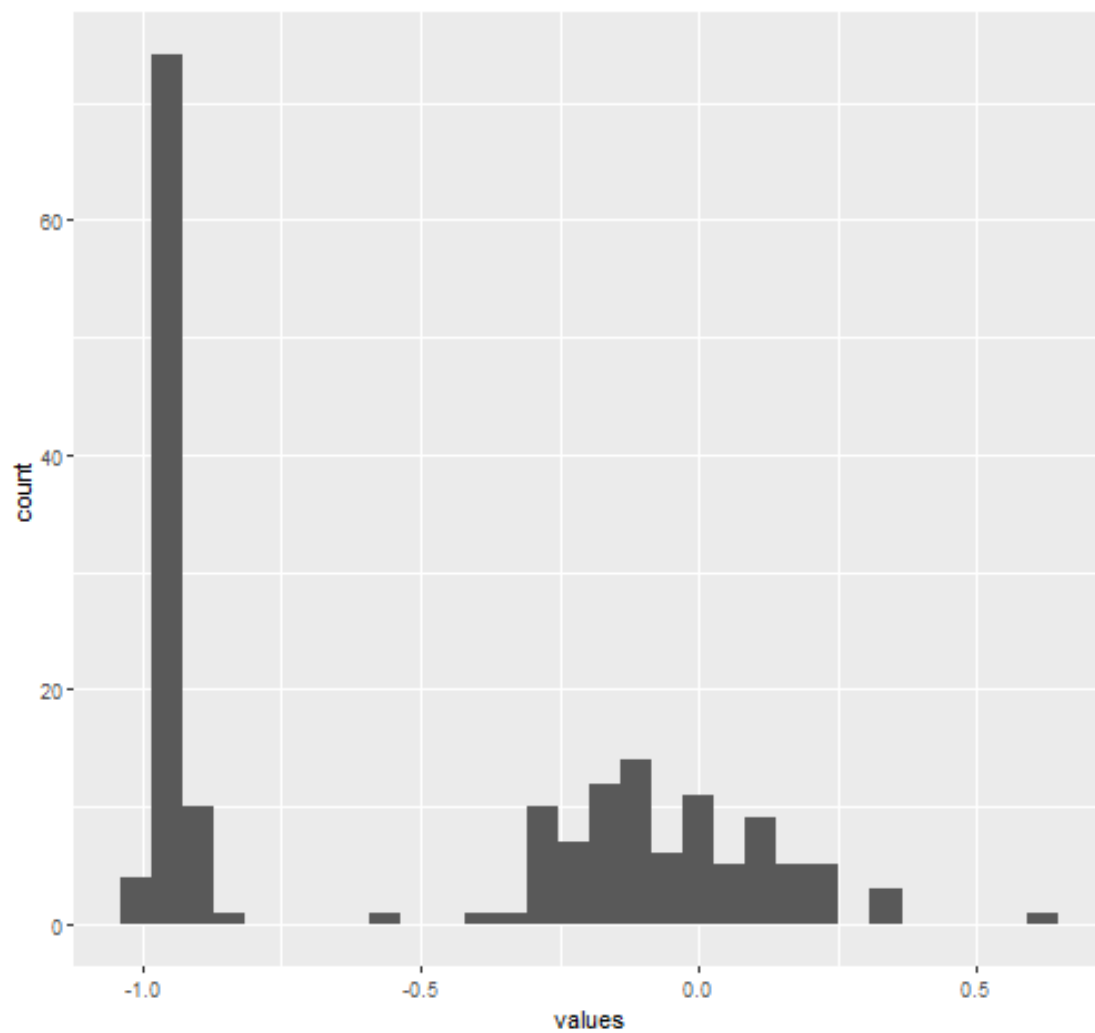
name	date	missing	complete	min	max	std	p0	p2	p5	p7	p10	hist
time	numeric	0	180	1	-	0	-	-	-	-	0.	<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581>
Body	ic			8	0.	.	1	0.	0.	0.	1	
				0	7	3		9	8	4	9	1><U+2581>

y  
Gyr  
osc  
ope  
Jerk  
-  
std(  
)-Z

time Body Accelerometer Magnitude -mean()

Distribution

time Body Accelerometer Magnitude -mean()



plot of chunk distribution

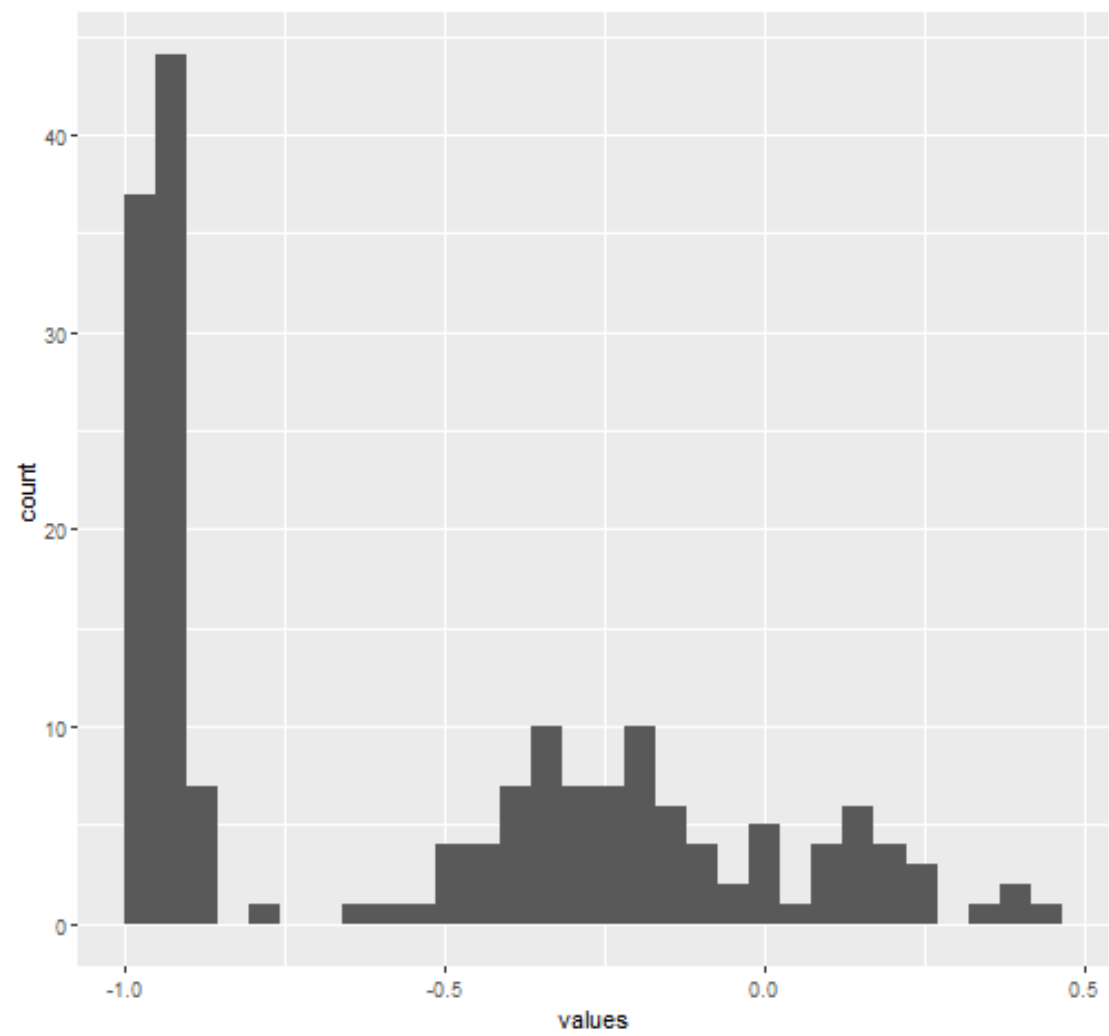
0 missing values.

[illegible]

time Body Accelerometer Magnitude -std()

Distribution

time Body Accelerometer Magnitude -std()



plot of chunk distribution

0 missing values.

Summary statistics

name	type	missing	complete	mean					p					hist
				n	std	var	min	max	0.05	0.25	0.5	0.75	0.95	
time	numeric	0	18	1	-0.8	0.54	-1.0	-0.5	-	-	-	-	0.4	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2582><U+2581>
Body	me		0	8	0.5	0.4			0	0	0	0	4	
Accel	ric			0	5	4							3	

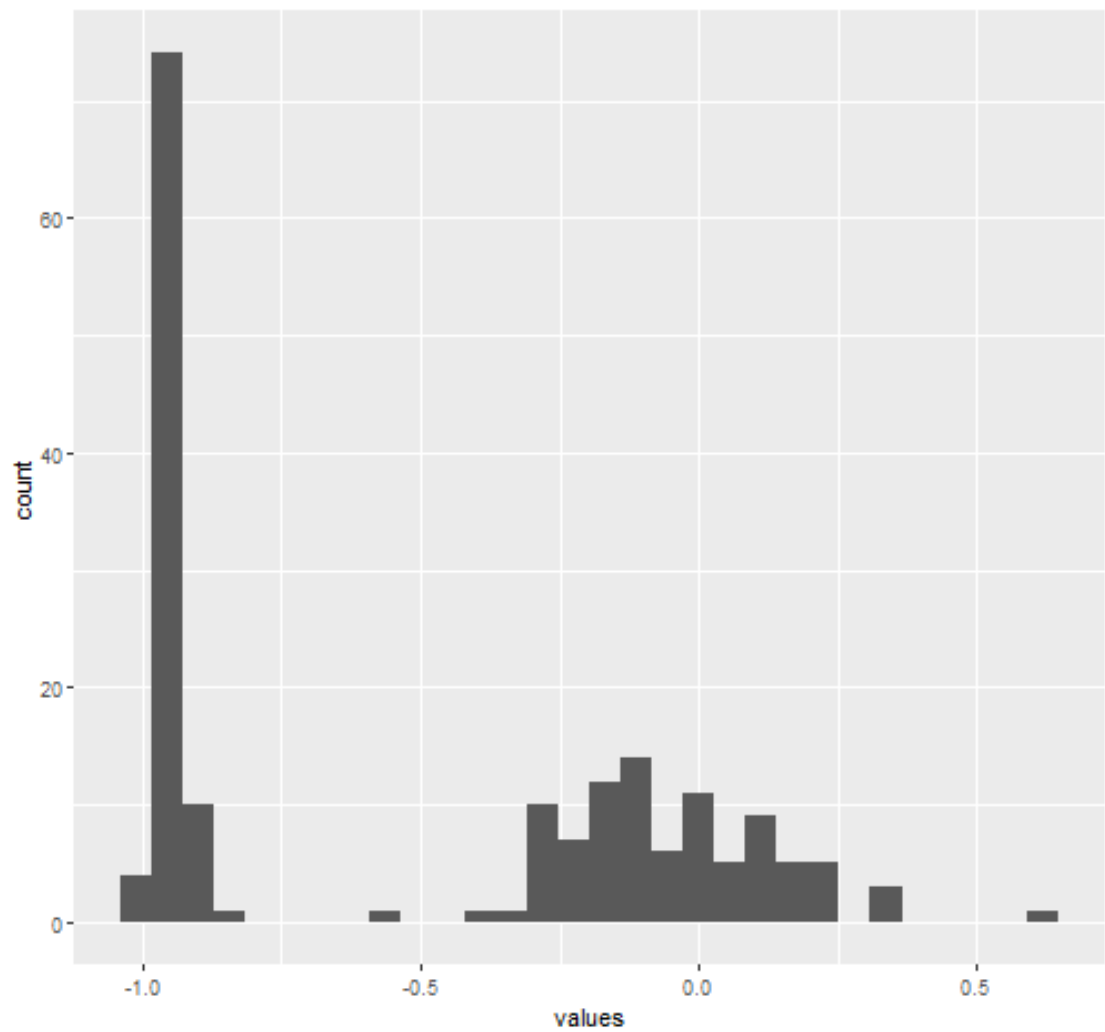


erom 4 3 9 9 6 2  
eter 9 4 1 1  
Magn  
itude  
-std()

time Gravity Accelerometer Magnitude -mean()

Distribution

time Gravity Accelerometer Magnitude -mean()



plot of chunk distribution

0 missing values.

Summary statistics

name	dat a_t	mi ssi	co mp	n	m e	s d	p 0	p 2	p 5	p 7	p 1	hist
------	------------	-----------	----------	---	--------	--------	--------	--------	--------	--------	--------	------

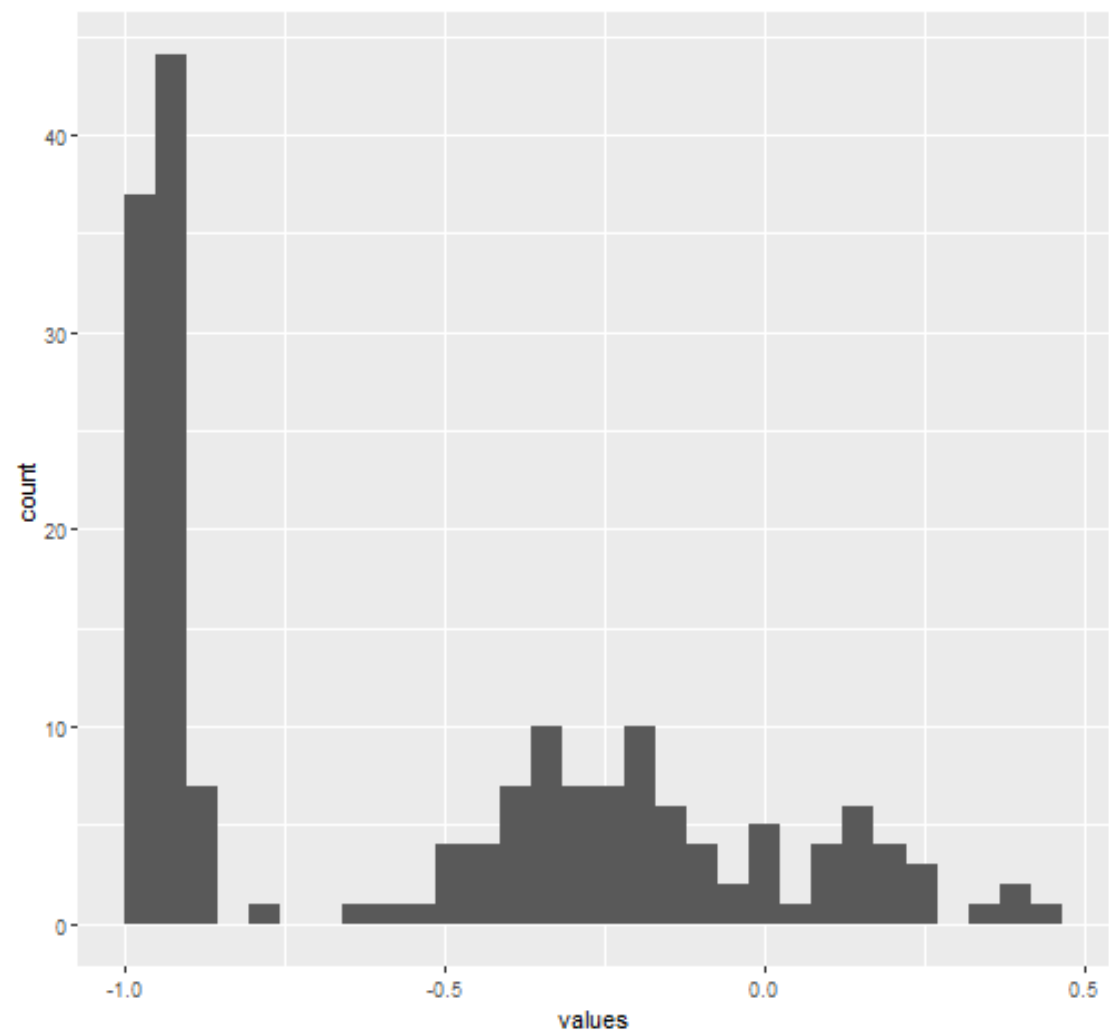
---

[illegible]

time Gravity Accelerometer Magnitude -std()

Distribution

time Gravity Accelerometer Magnitude -std()



plot of chunk distribution

0 missing values.

Summary statistics

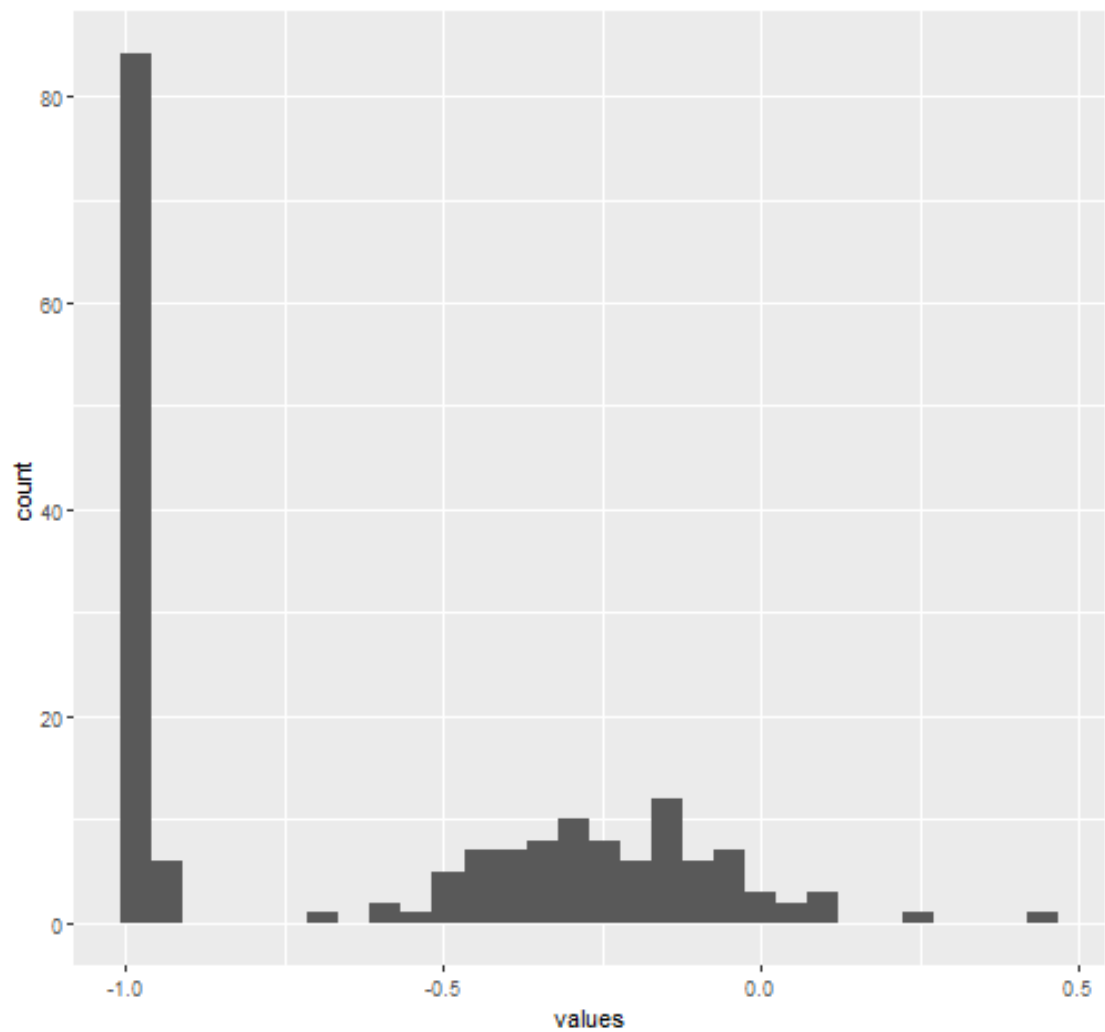
name	type	n	missing	complete	mean					p					hist
					min	max	std	p25	p50	p75	p1	p5	p10	p90	
time Gravity Accelerometer Magnitude -std()	numeric	180	0	180	-1.0	-0.1	0.4	-0.5	-0.2	0.1	0.0	0.0	0.1	0.3	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2582><U+2581>

Accelerometer JerkMagnitude-std()  
4 3 9 9 6 2  
9 4 1 1

time Body Accelerometer JerkMagnitude -mean()

Distribution

time Body Accelerometer JerkMagnitude -mean()



plot of chunk distribution

0 missing values.

Summary statistics

name	dat	mi	co	n	m	s	p	p	p	p	p	hist
------	-----	----	----	---	---	---	---	---	---	---	---	------

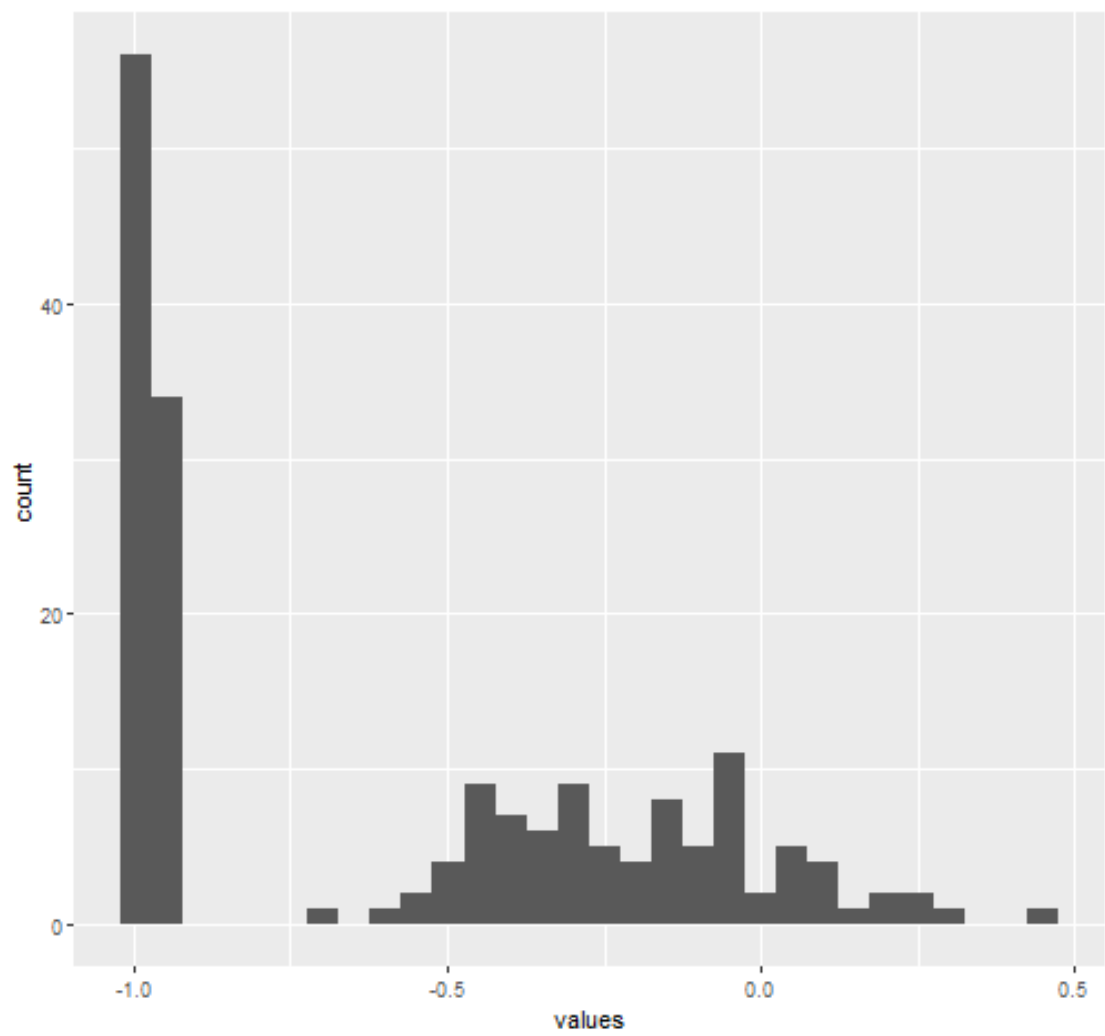
---

[illegible]

time Body Accelerometer JerkMagnitude -std()

Distribution

time Body Accelerometer JerkMagnitude -std()



plot of chunk distribution

0 missing values.

Summary statistics

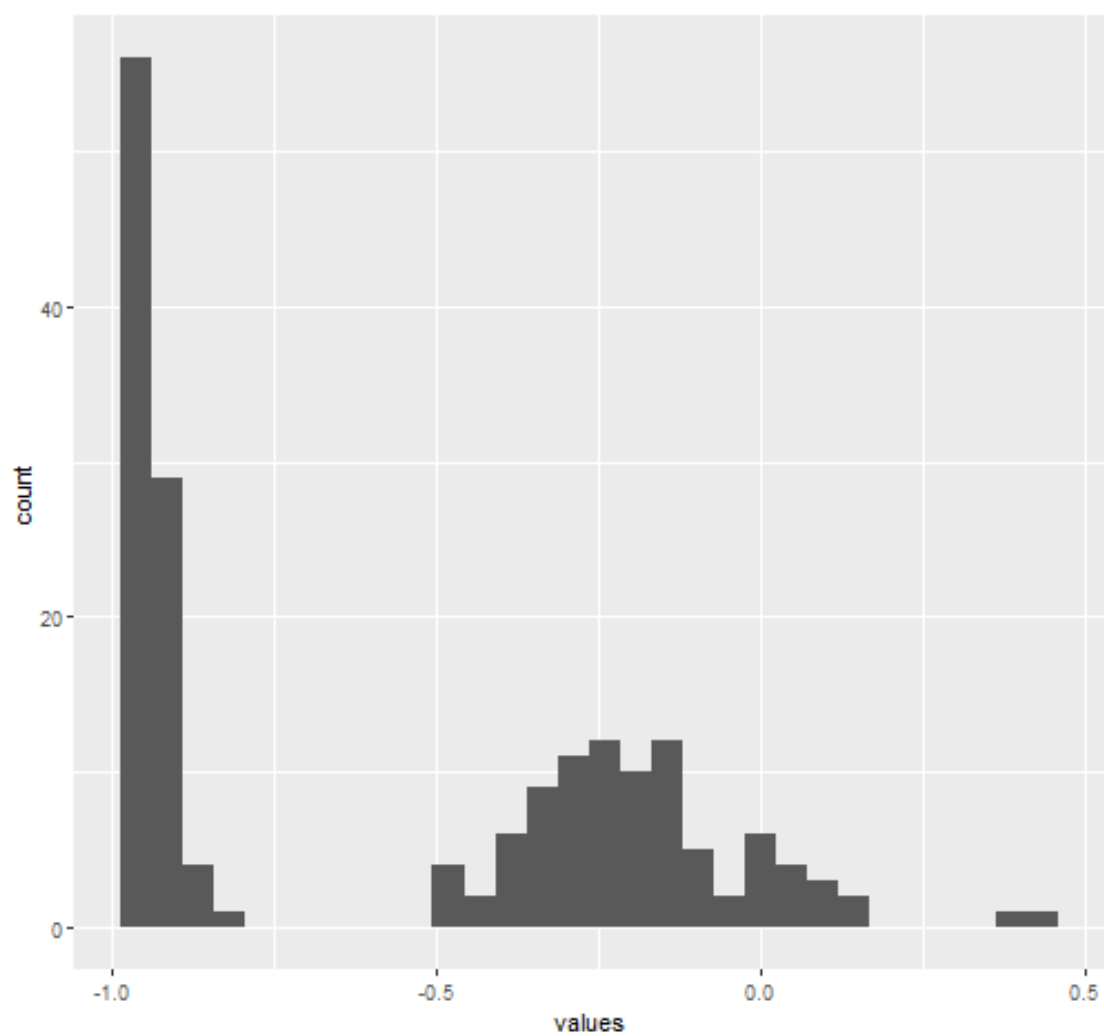
				m							p	
	dat	mi	co	e			p	p	p	1		
	a_t	ssi	mp	a	s	p	2	5	7	0		
name	ype	ng	lete	n	n	d	0	5	0	5	0	hist
time	nu	0	18	1	-	0	-	-	-	-	0.	<U+2587><U+2581><U+2581><
Body	me		0	8	0.	.	0	0	0	0	4	U+2582><U+2582><U+2582><U
Accel	ric			0	5	4	.	.	.	.	5	+2581><U+2581>

erom 8 2 9 9 8 2  
eter 9 8 2  
JerkM  
agnit  
ude -  
std()

time Body Gyroscope Magnitude -mean()

Distribution

time Body Gyroscope Magnitude -mean()



plot of chunk distribution

0 missing values.

Summary statistics

nam	dat	mi	co	n	m	s	p	p	p	p	p	hist
-----	-----	----	----	---	---	---	---	---	---	---	---	------

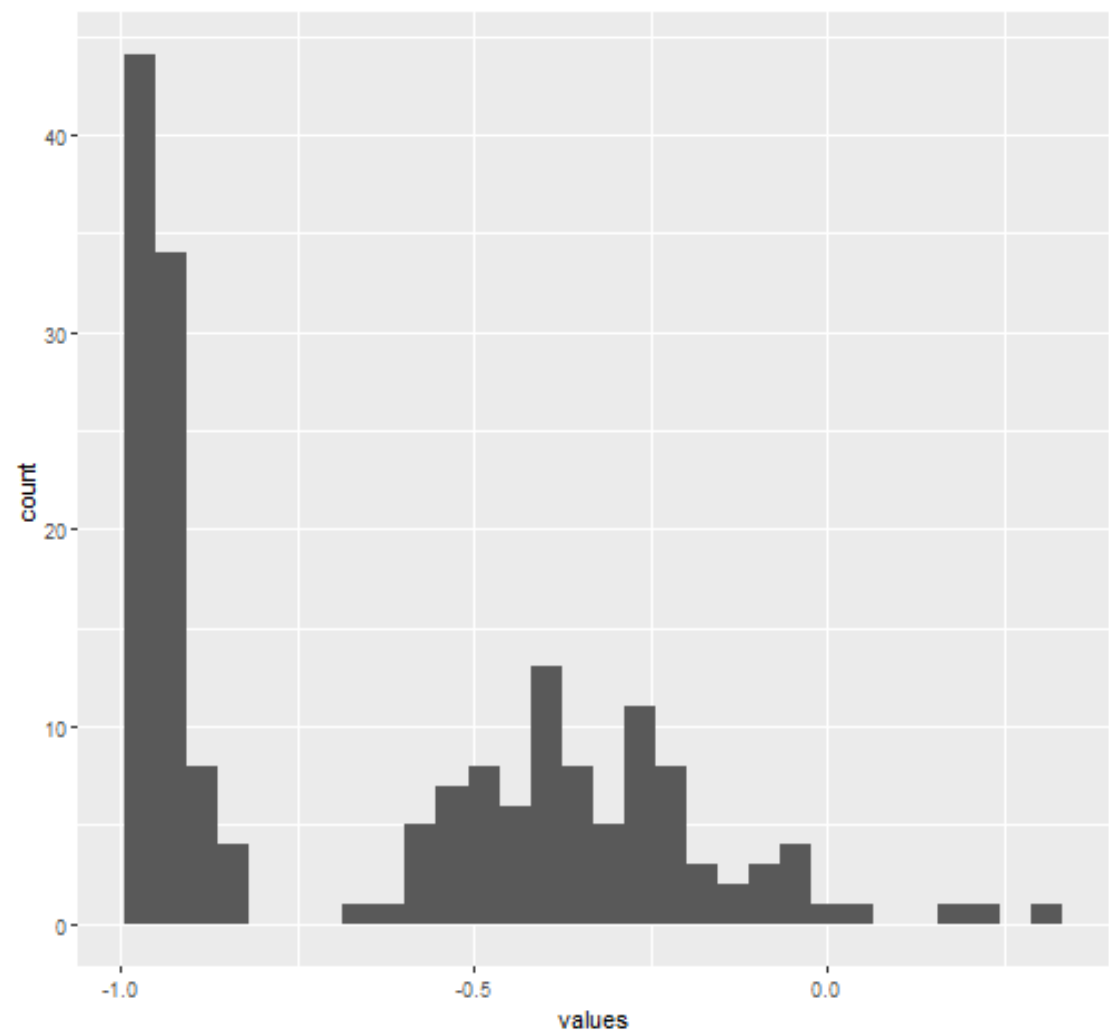
e	a_ty pe	ssi ng	mp lete		ea n	d	0	2	5	7	1	
								5	0	5	0	0
tim e Bod y Gyr osc ope Mag nitudo - mean()	nu me ric	0	18 0	1 8 0	- 0. 5	0 . . 4	- 0. 9	- 0. 9	- 0. 6	- 0. 2	0. 4 2	<U+2587><U+2581> +2582><U+2583> <U+2581>



time Body Gyroscope Magnitude -std()

Distribution

time Body Gyroscope Magnitude -std()



plot of chunk distribution

0 missing values.

Summary statistics

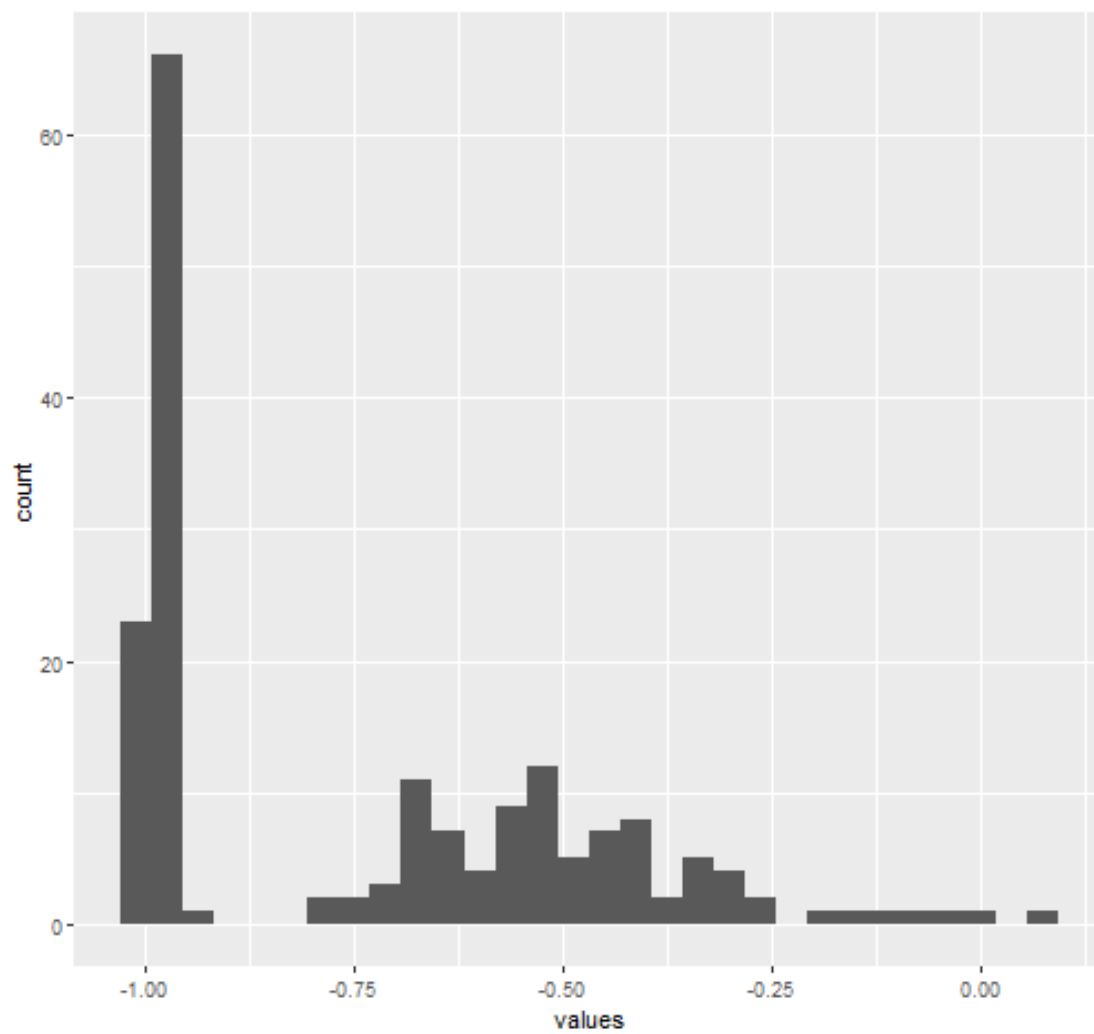
name	data type	missing	complete	n	mean	std	p0	p2	p5	p7	p10	hist
time	numeric	0	180	18	1.08	0.34	0.00	0.00	0.00	0.00	0.03	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

```
y
Gyr
osc
ope
Mag
nitu
de -
std(
)
```

time Body Gyroscope JerkMagnitude -mean()

Distribution

time Body Gyroscope JerkMagnitude -mean()



plot of chunk distribution

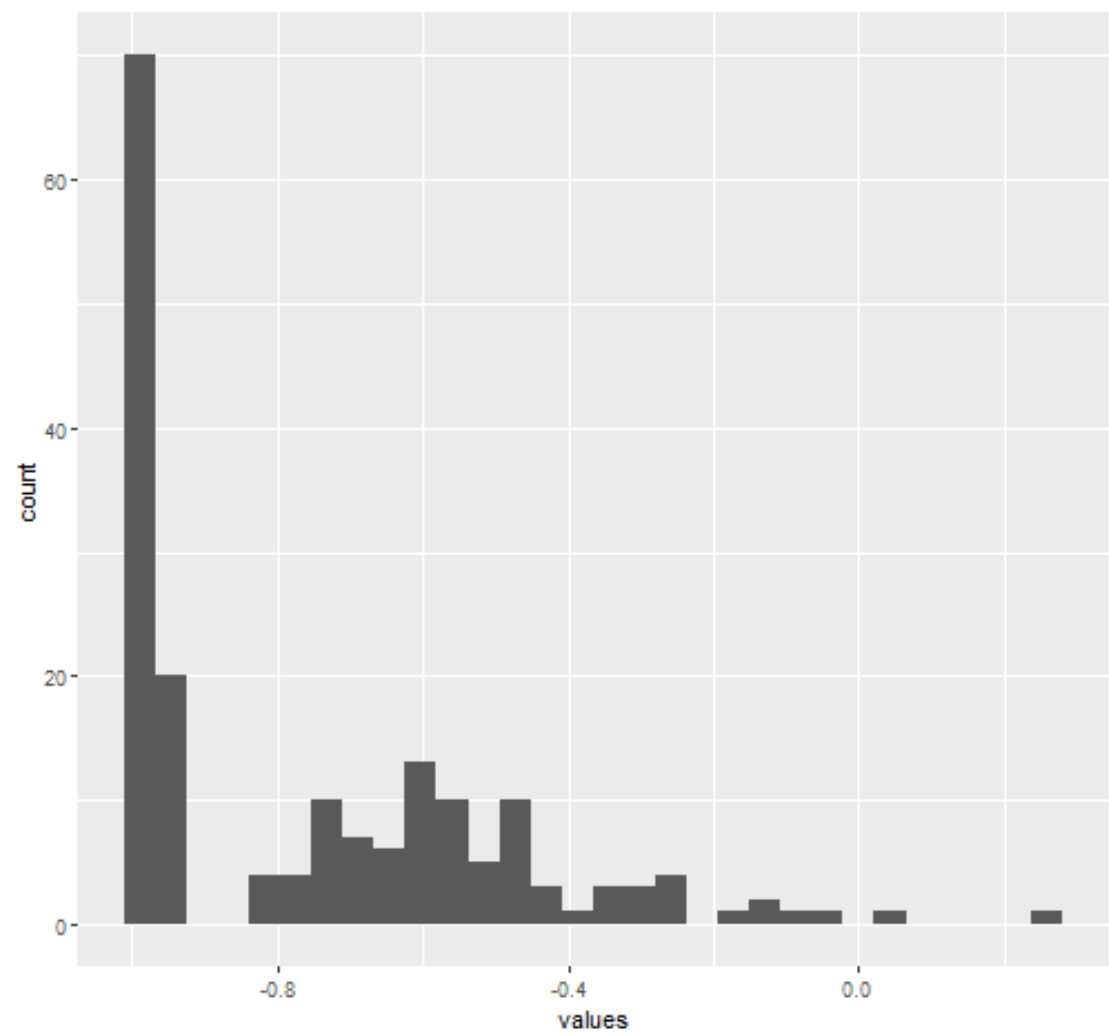
0 missing values.

[illegible][illegible]

time Body Gyroscope JerkMagnitude -std()

Distribution

time Body Gyroscope JerkMagnitude -std()



plot of chunk distribution

0 missing values.

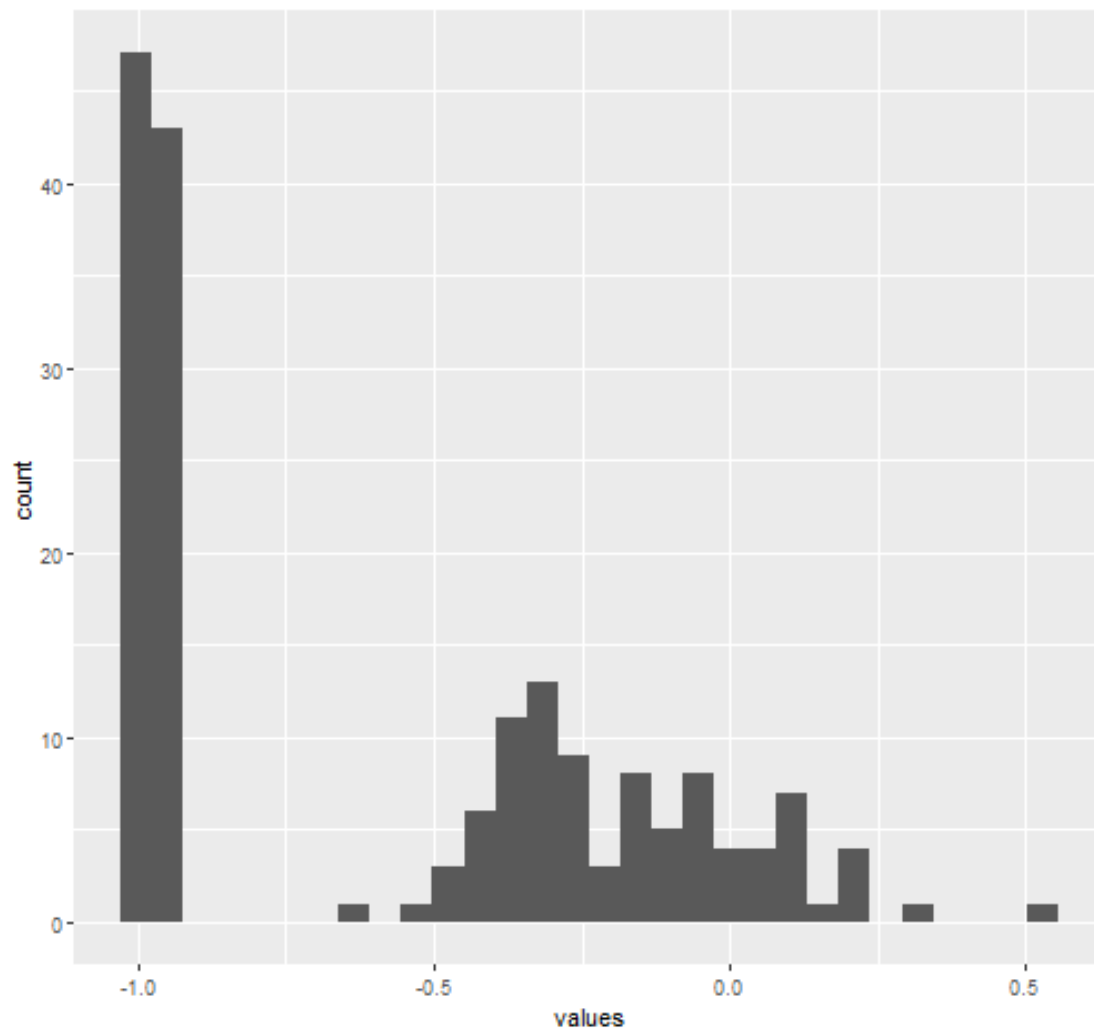
Summary statistics

name	m											hist
	dat	mi	co	e							p	
				a	s	p	2	5	7	1		
										0	5	
a_t	ssi	mp	n	n	d	0	5	0	5	0		
type	ng	lete										
time	nu	0	18	1	-	0.	-	-	-	-	0.	<U+2587><U+2582><U+2583><U
Body	me		0	8	0.	2	1	0.	0.	0.	2	+2582><U+2581><U+2581><U+2
Gyros	ric			0	7	7		9	8	5	5	581><U+2581>

6                      8    8    8

## Distribution

frequency Body Accelerometer -mean()-X



*plot of chunk distribution*

0 missing values.

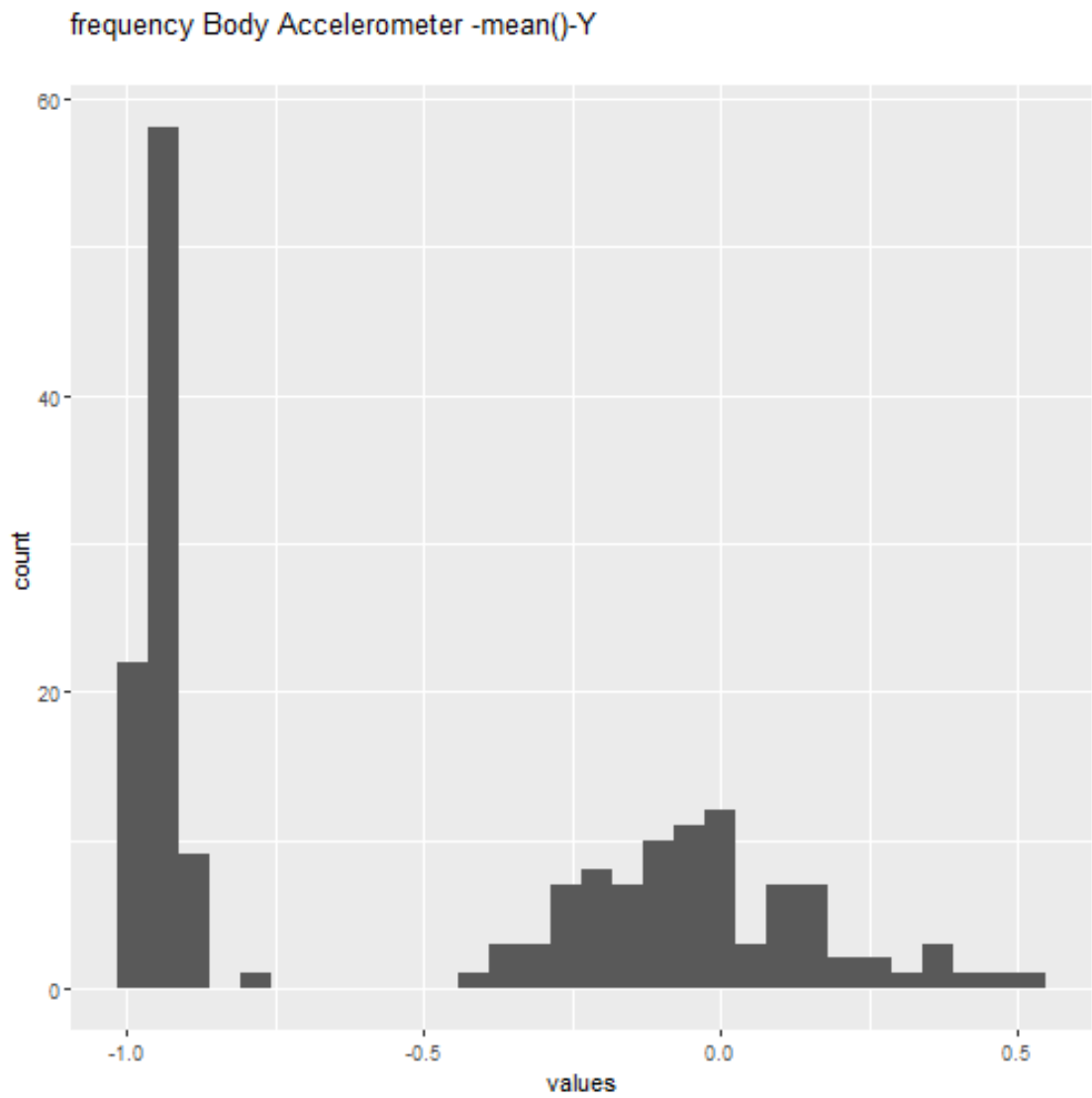
## Summary statistics

	dat	mi	co		m	s	p	p	p	p			
name	a	t	ssi	mp	n	e	d	0	2	5	7	1	hist

	ype	ng	lete	a		5		0		5		0	
				n								0	
frequ	nu	0	18	1	-	0.	-	-	-	-	0.	<U+2587><U+2581><U+2581><U	
ency	me		0	8	0.	4	1	0.	0.	0.	5	+2583><U+2582><U+2582><U+2	
Body	ric			0	5	3		9	7	2	4	581><U+2581>	
Accel				8				8	7	2			
erom													
eter -													
mean													
()-X													

frequency Body Accelerometer -mean()-Y

Distribution



plot of chunk distribution

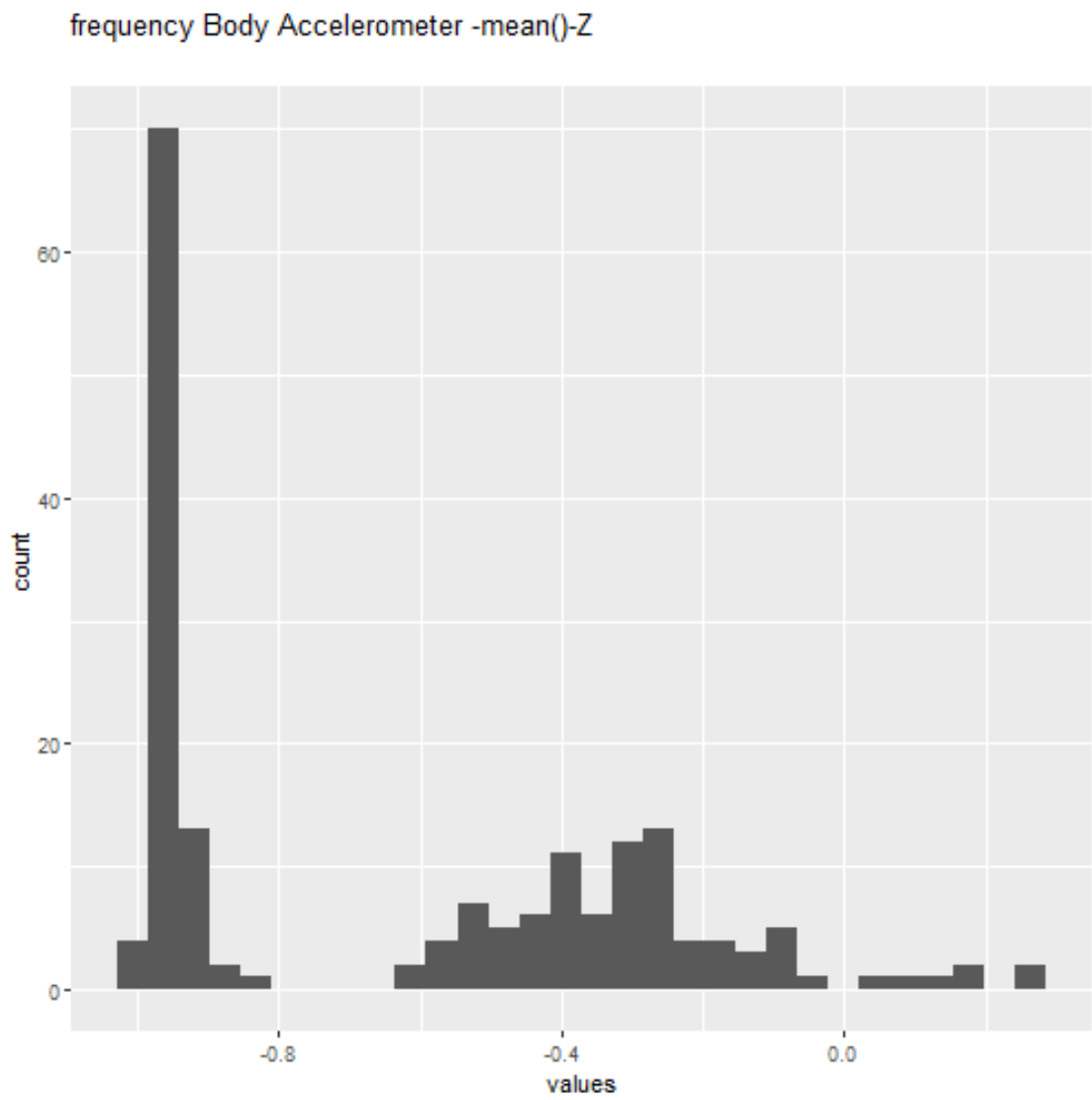
0 missing values.

### Summary statistics

name	data_type	missing	complete	n	mean	std	p0	p25	p50	p75	p100	hist
frequency	numeric	0	180	18	1.0	0.0	-	-	-	-	0.5	<U+2587><U+2581><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581>
Body Accelerometer - mean 0-Y	numeric	0	180	18	0.49	0.48	0.09	0.09	0.5	0.6	0.93	

frequency Body Accelerometer -mean()-Z

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

name	data type	missing	complete	mean					p			hist
				n	std	var	skew	kurt	2.5	5	7.5	
frequency Body	numeric	0	180	180	0.63	0.4	-0.0	-0.0	-0.0	0.0	0.8	<U+2587><U+2581><U+2581><U+2582><U+2583><U+2581><U+2581><U+2581>

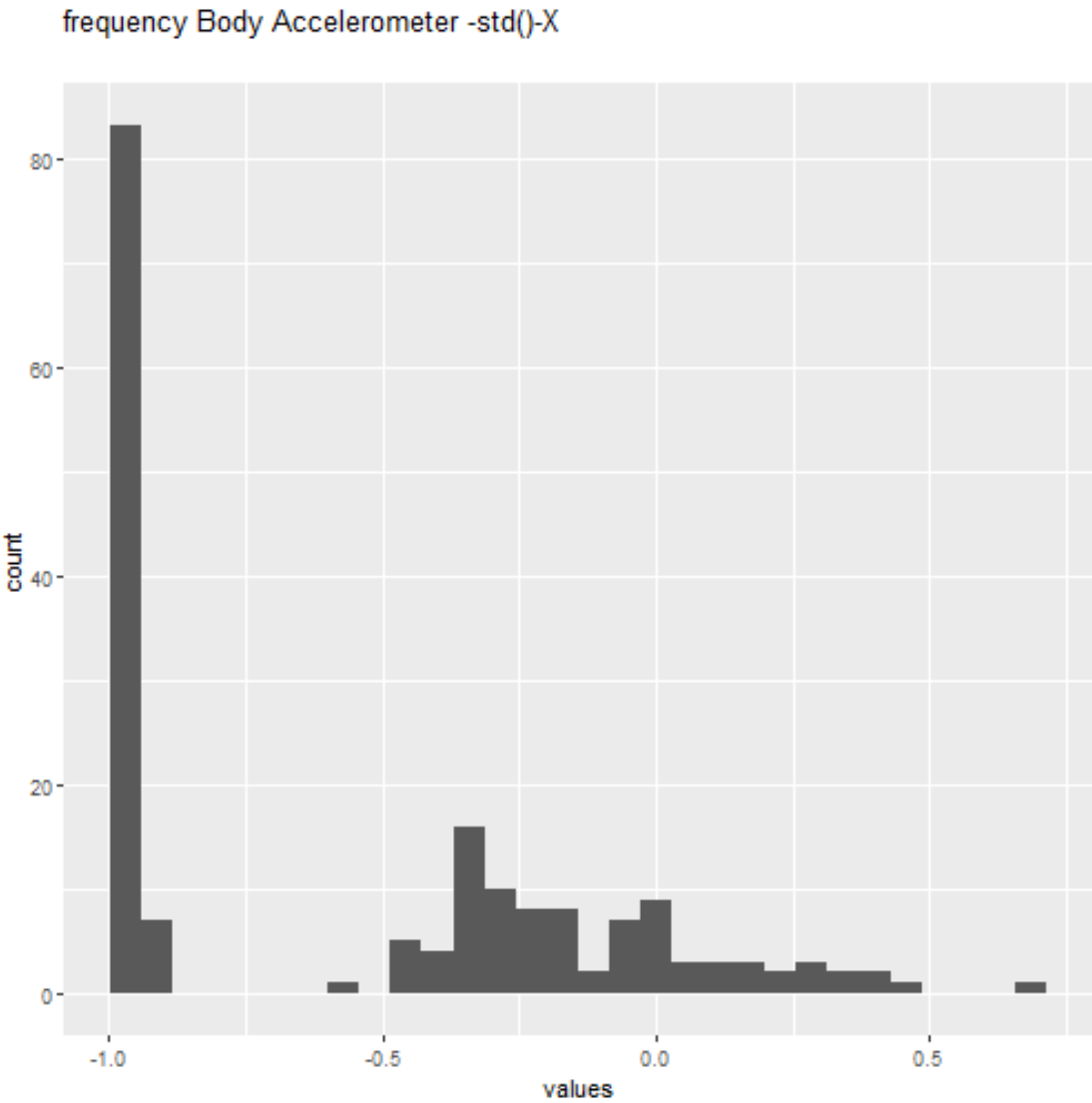


Accel  
erom  
eter -  
mean  
()-Z

3 6 9 9 7 3  
9 6 2 2

frequency Body Accelerometer -std()-X

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

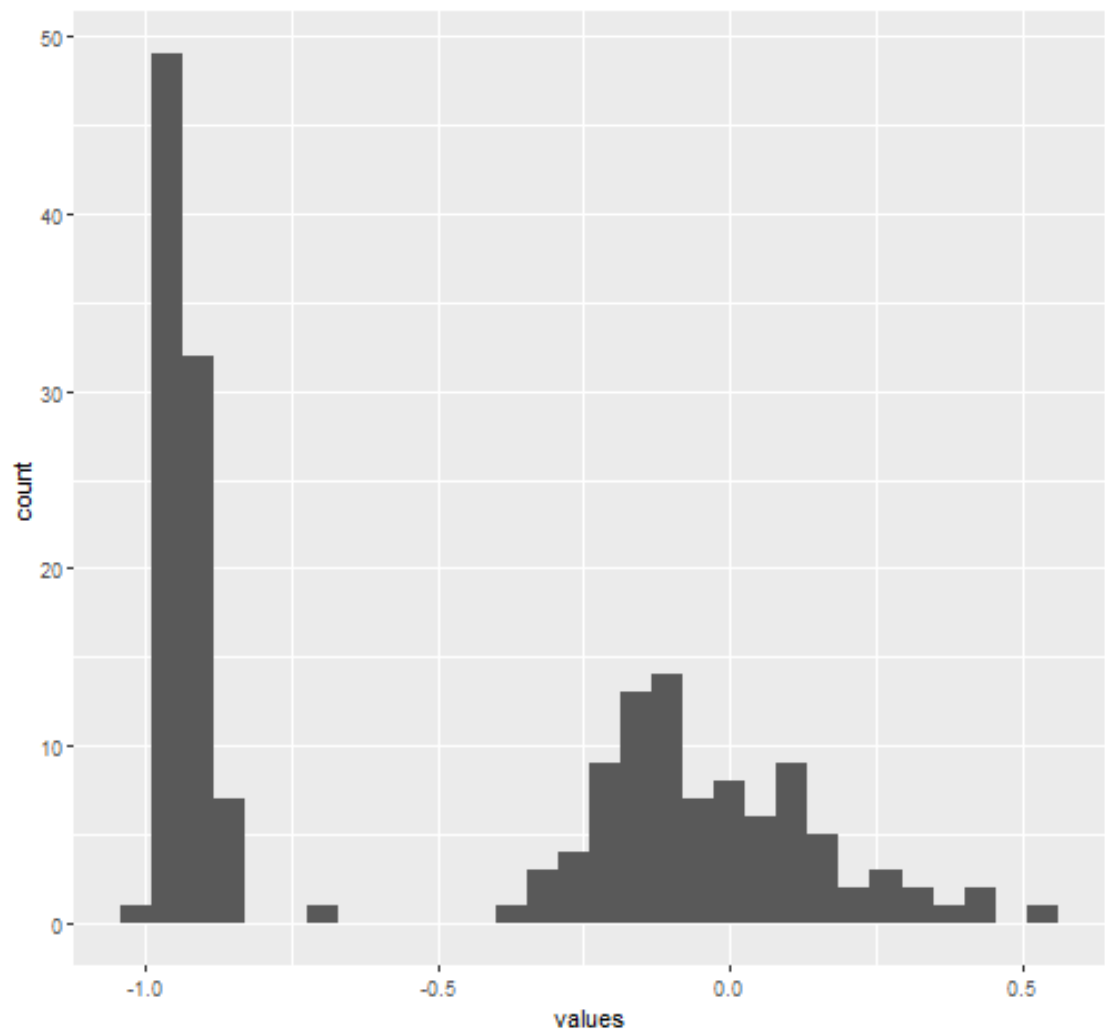
	dat	mi	co	m	s	p	p	p	p	p		
name	a_t	ssi	mp	n	e	d	0	2	5	7	1	hist

	type	ng	lete	a		5		0		5		0	
				n									
frequency	nu	0	18	1	-	0.	-	-	-	-	0.	<U+2587><U+2581><U+2581><U	
Body	me		0	8	0.	4	1	0.	0.	0	6	+2583><U+2582><U+2581><U+2	
Accelerometer -std()	ric			0	5	6		9	7	.	6	581><U+2581>	
X				5				8	5	2			

frequency Body Accelerometer -std()-Y

Distribution

frequency Body Accelerometer -std()-Y



plot of chunk distribution

0 missing values.

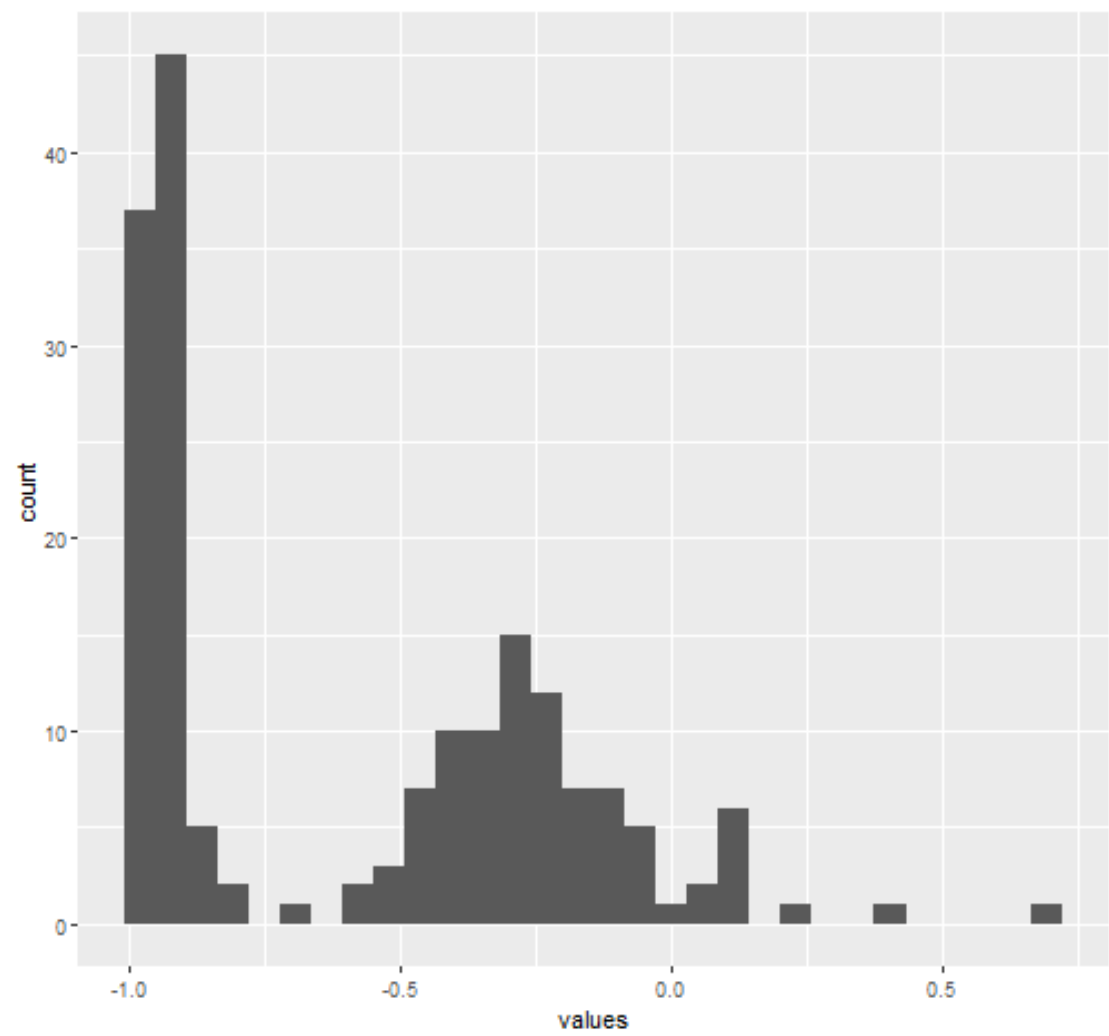
### Summary statistics

name	data_type	missing	complete	n	mean	std	p0	p25	p50	p75	p100	hist
frequency	numeric	0	180	18	1.0	0.0	-	-	-	-	0.5	<U+2587><U+2581><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581>
Body Accelerometer - std() - Y	numeric	0	180	18	0.4	0.7	0.9	0.9	0.5	0.7	0.9	

frequency Body Accelerometer -std()-Z

Distribution

frequency Body Accelerometer -std()-Z



plot of chunk distribution

0 missing values.

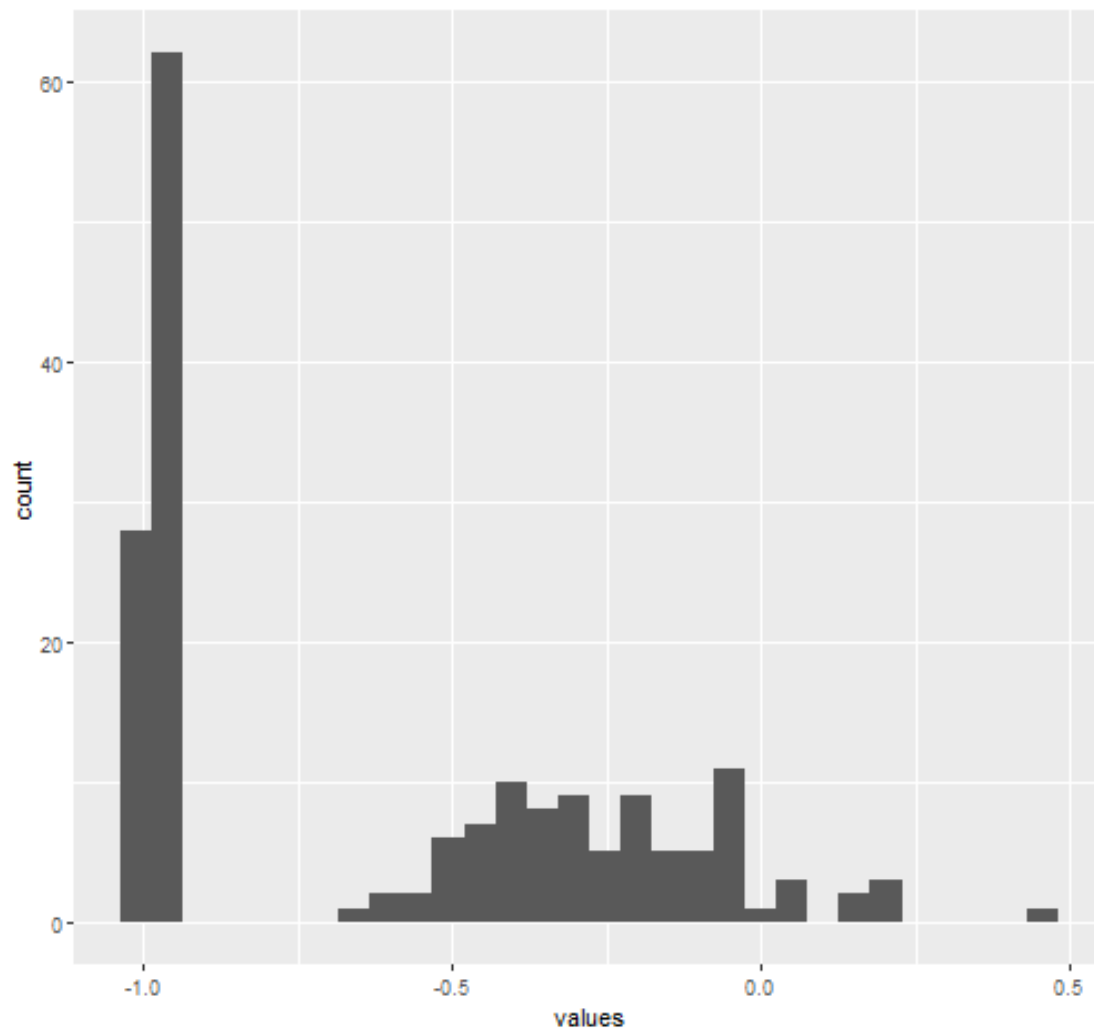
Summary statistics

name	m											hist
	dat	mi	co	e					p			
	a_t	ssi	mp	a	s	p	2	5	7	1		
	ype	ng	lete	n	n	d	0	5	0	5	0	
frequ	nu	0	18	1	-	0	-	-	-	-	0.	<U+2587><U+2581><U+2582><
ency	me		0	8	0.	.	0	0	0	0	6	U+2583><U+2581><U+2581><U
Body	ric			0	5	3	.	.	.	.	9	+2581><U+2581>

8	9	9	9	6	2
		9	5	4	7

## Distribution

frequency Body Accelerometer Jerk-mean()-X



*plot of chunk distribution*

0 missing values.

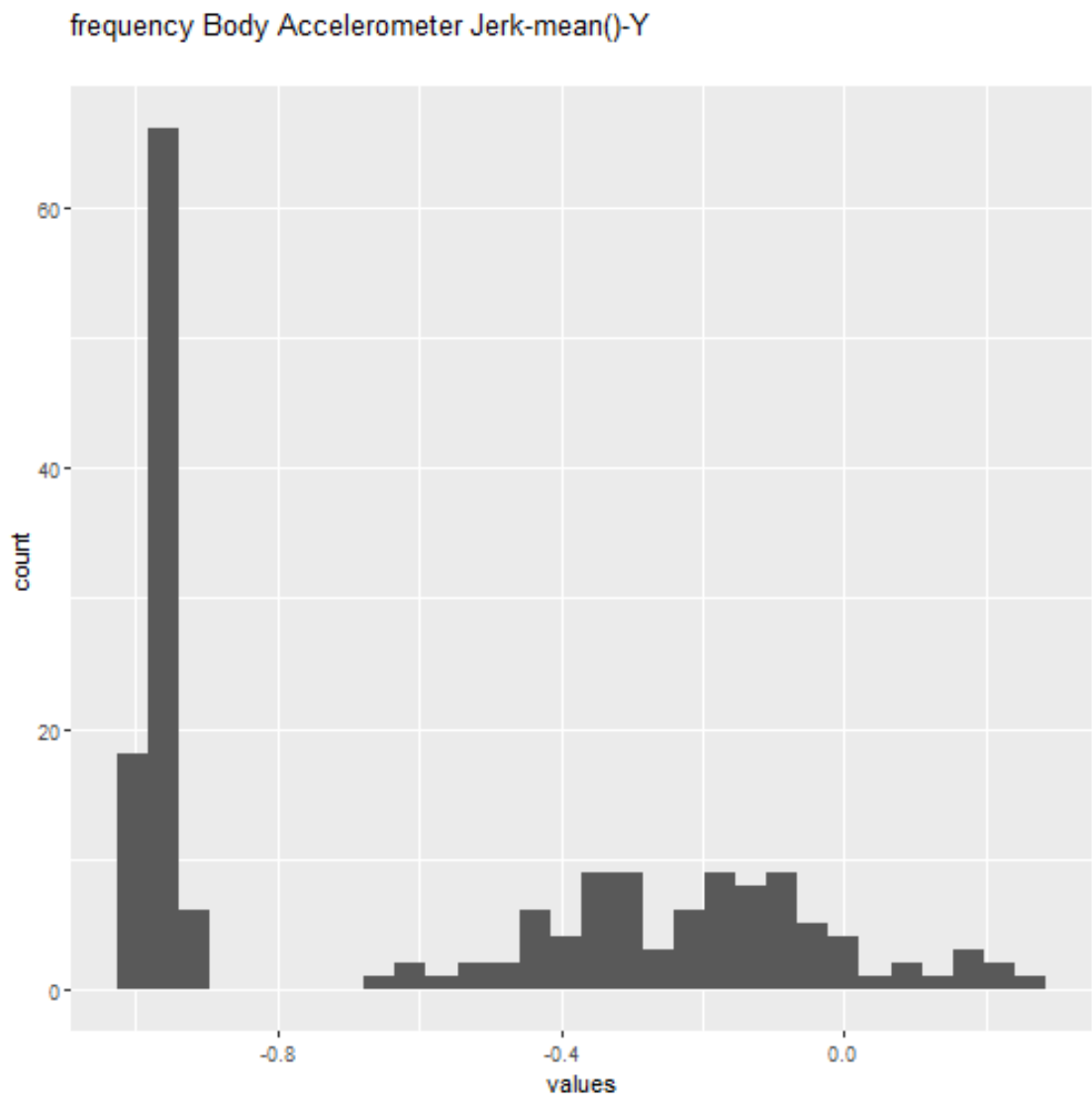
## Summary statistics

	dat	mi	co		m	s	p	p	p	p			
name	a	t	ssi	mp	n	e	d	0	2	5	7	1	hist

[illegible]

frequency Body Accelerometer Jerk-mean()-Y

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

name	type	n	missing	complete	min	max	std	var	p25	p50	p75	p100	hist
frequency Body	numeric	0	18	0	1	0.5	0.4	0.16	0.0	0.0	0.0	0.2	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>

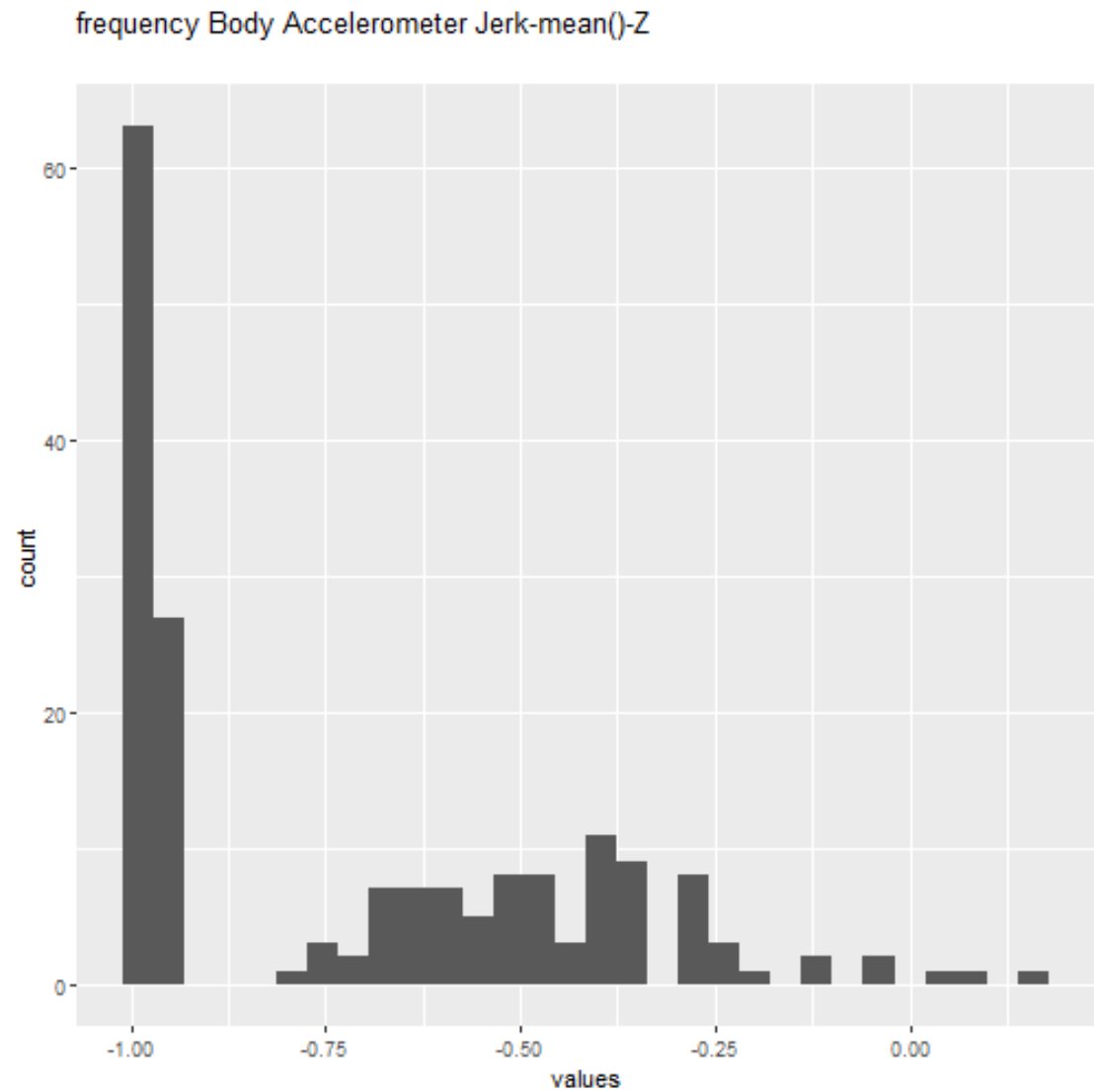
Accelerometer Jerk-mean()

99782

Y

frequency Body Accelerometer Jerk-mean()-Z

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

name	dat	mi	co	n	m	s	p	p	p	p	p	hist
------	-----	----	----	---	---	---	---	---	---	---	---	------



	a_t ype	ssi ng	mp lete	e a n	d	0	2	5	7	1	
							5	0	5	0	0
frequ ency Body Accel erom eter Jerk- mean ()~Z	nu me ric	0	18 0	1 8 0 7 1	- 0. 7 3 9	0 . 3 9	- 0. 9 9	- 0. 9 8	- 0. 8 7	- 0. 4 7	0. 1 6 581><U+2581>
											<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>

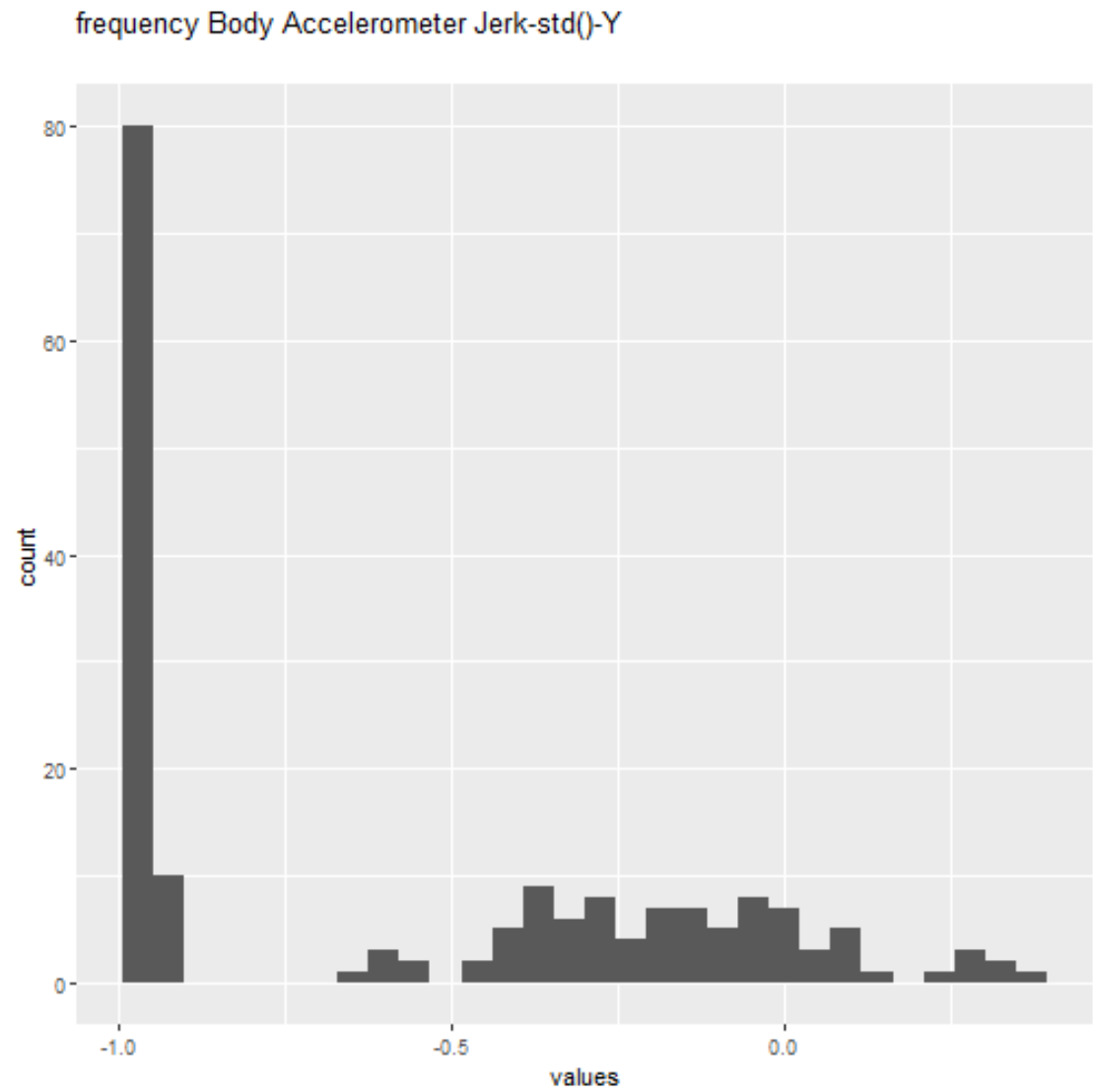
	dat	mi	co			m			p	p	p	p
	a_ty	ssi	mp			ea	s	p	2	5	7	0
name	pe	ng	lete	n	n	d	0	5	0	5	0	hist
frequ	nu	0	18	1	-	0	-	-	-	-	0.	<U+2587><U+2581><U+2581><U
ency	me		0	8	0.	.	1	0.	0.	0.	4	+2582><U+2582><U+2582><U+2
Body	ric			0	6	4		9	8	2	8	581><U+2581>

Accelerometer Jerk-std()-X

1 8 3 5

frequency Body Accelerometer Jerk-std()-Y

Distribution



plot of chunk distribution

0 missing values.

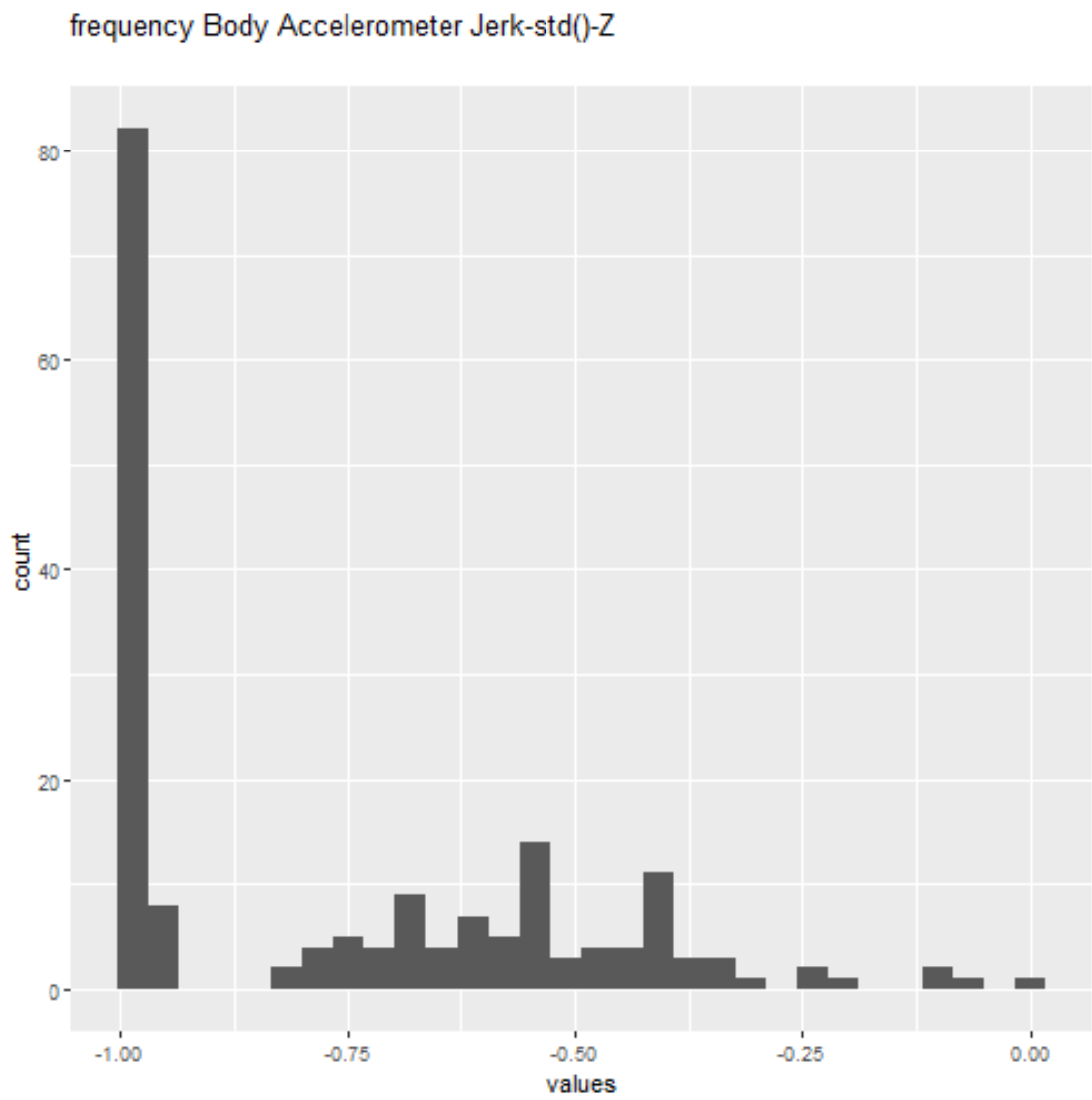
Summary statistics

name	dat	mi	co	n	m	s	p	p	p	p	p	hist
------	-----	----	----	---	---	---	---	---	---	---	---	------

	a_t ype	ssi ng	mp lete	e a n	d	0	2	5	7	1	
							5	0	5	0	0
frequ ency Body Accel erom eter Jerk- std()- Y	nu me ric	0	18 0	1 8 0	- 0. 5 7	0 . 4 3	- 0 . 9 9	- 0 . 9 7	- 0 . 7 9	- 0 . 1 7	0. 3 5  <U+2587><U+2581><U+2581>< U+2582><U+2582><U+2582><U +2581><U+2581>

frequency Body Accelerometer Jerk-std()-Z

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

m											
e											
a											
s											
p											
2											
5											
0											
p1											
name	dat	mi	co	n	n	d	0	5	0	5	hist
	a_t	ssi	mp								
	type	ng	lete								
frequ	nu	0	18	1	-	0	-	-	-	-	<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581>
ency	me		0	8	0.	.	0	0	0	0.	
Body	ric			0	7	2	.	.	.	00	

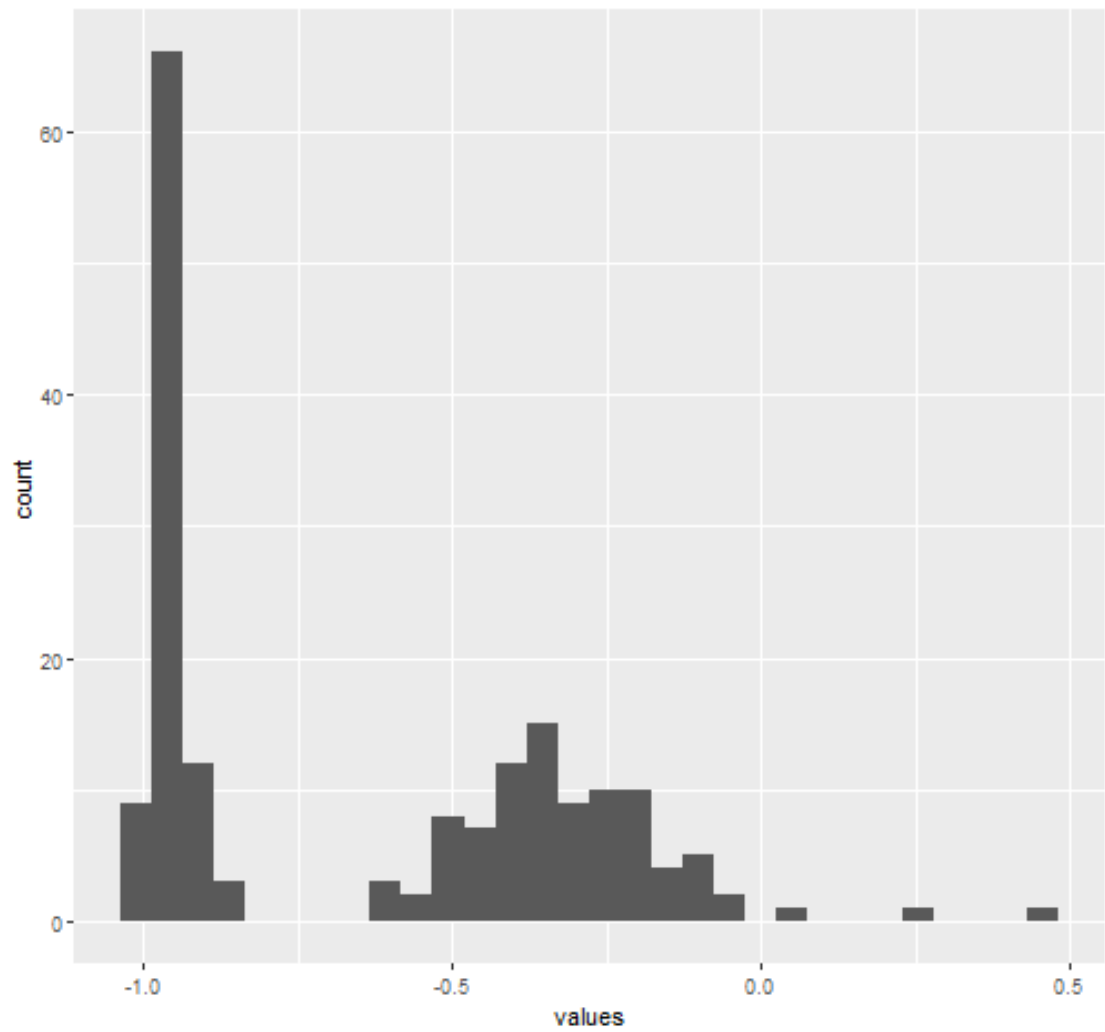
Accelerometer Jerk-std()-Z

6	6	9	9	9	5	62
		9	8		4	

frequency Body Gyroscope -mean()-X

Distribution

frequency Body Gyroscope -mean()-X



plot of chunk distribution

0 missing values.

Summary statistics

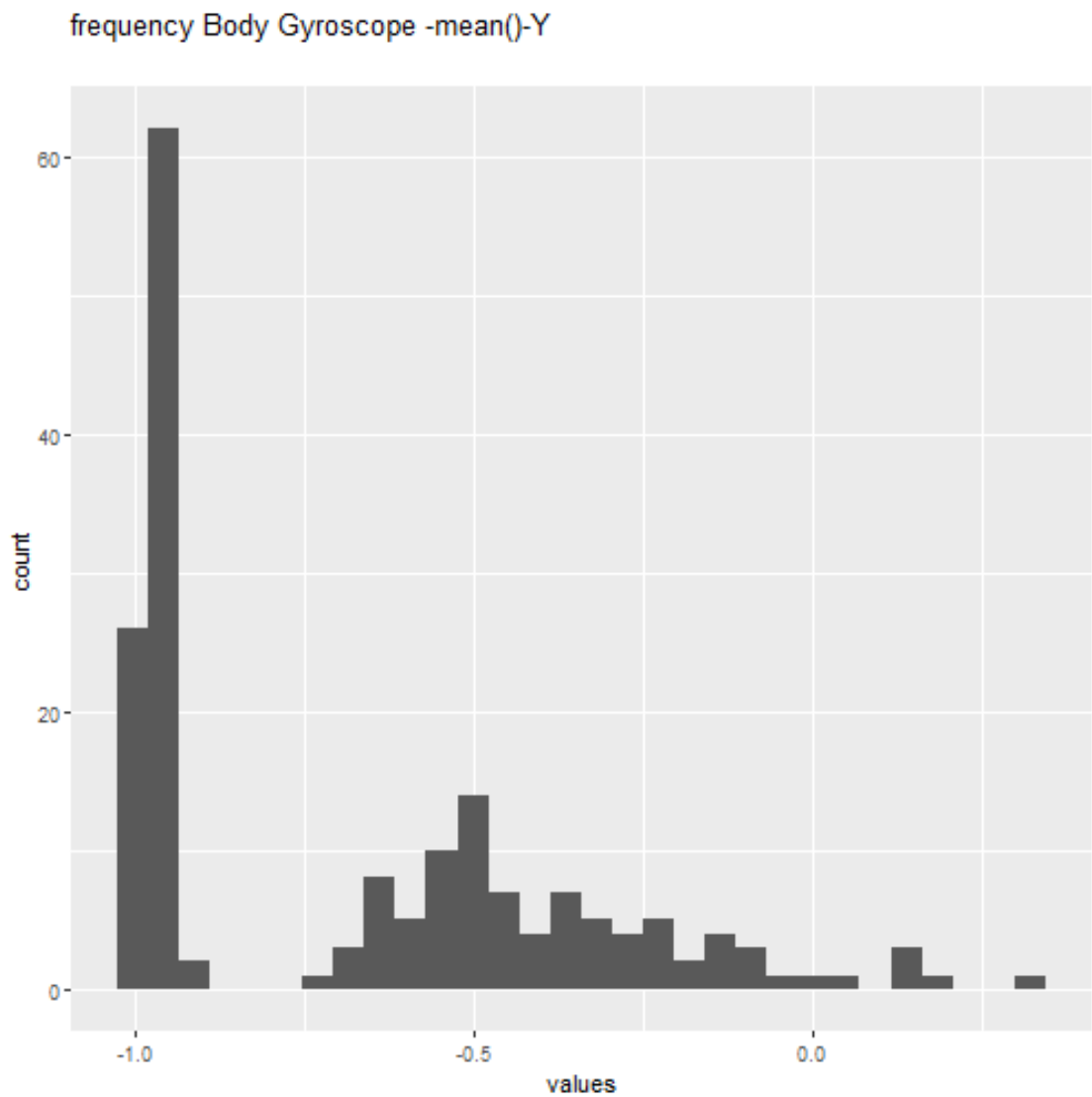
na	dat	mi	co	n	m	s	p	p	p	p	p	hist
----	-----	----	----	---	---	---	---	---	---	---	---	------

---

me	a_ty pe	ssi ng	mp lete		ea n	d	0	2 5	5 0	7 5	1 0	
freq uen cy Bod y Gyr osc ope - mea n()- X	nu me ric	0	18 0	1 8 0	- 0. 6	0. 3 5	- 0. 9	- 0. 9	- 0. 7	- 0. 3	0. 4 7	<U+2587><U+2581><U+2582><U+2583> <U+2582><U+2581><U+2581>

frequency Body Gyroscope -mean()-Y

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

na	dat	mi	co	m	s	p	p	p	p	p	hist
me	a_ty	ssi	mp	n	ea	s	p	2	5	7	0
pe	pe	ng	lete	n	n	d	0	5	0	5	0
freq	nu	0	18	1	-	0.	-	-	-	-	0.
uen	me		0	8	0.	3	0.	0.	0.	0.	3
cy	ric			0	6	3	9	9	8	4	3



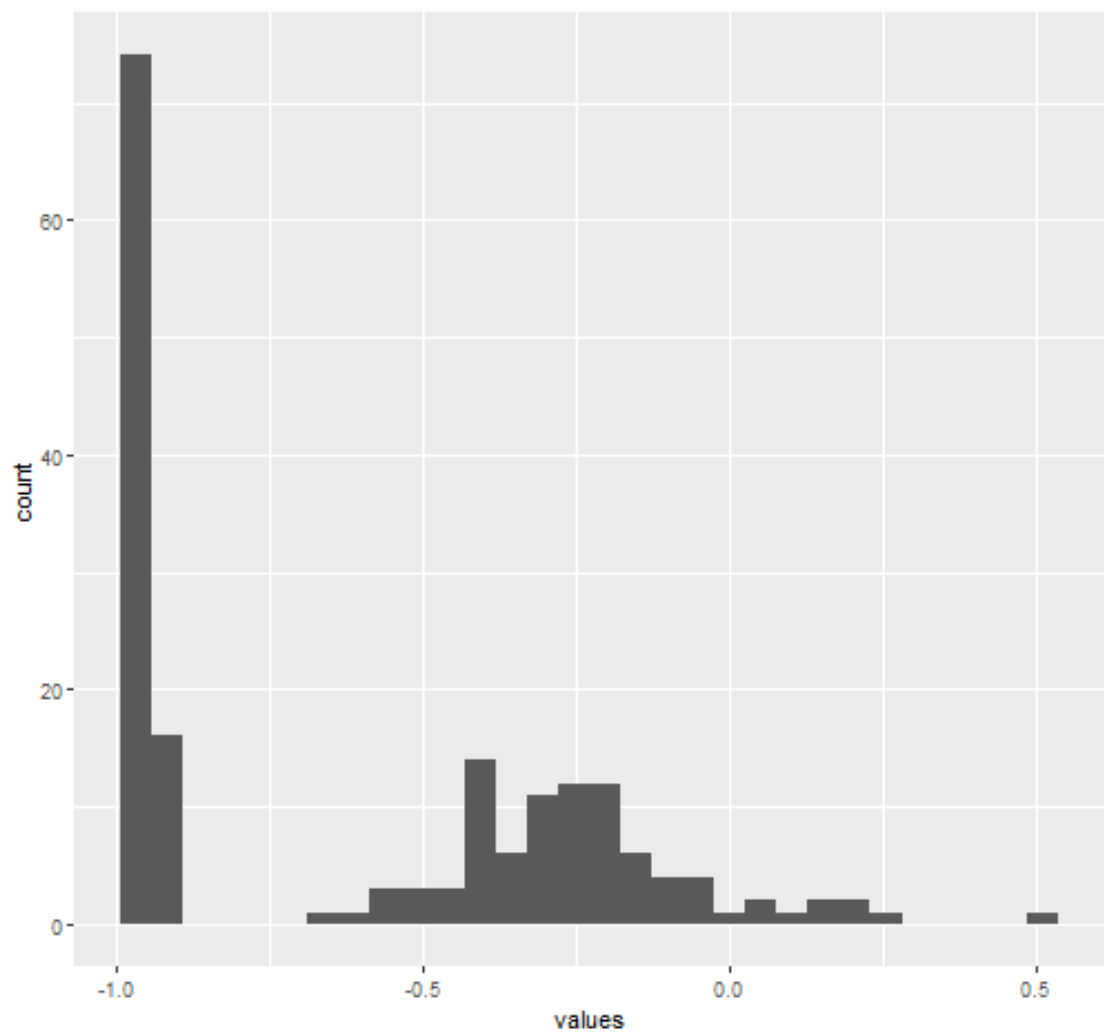
Bod  
y  
Gyr  
osc  
ope  
-  
mea  
n()  
Y

8      9    7    1    5

frequency Body Gyroscope -mean()-Z

Distribution

frequency Body Gyroscope -mean()-Z



plot of chunk distribution

0 missing values.

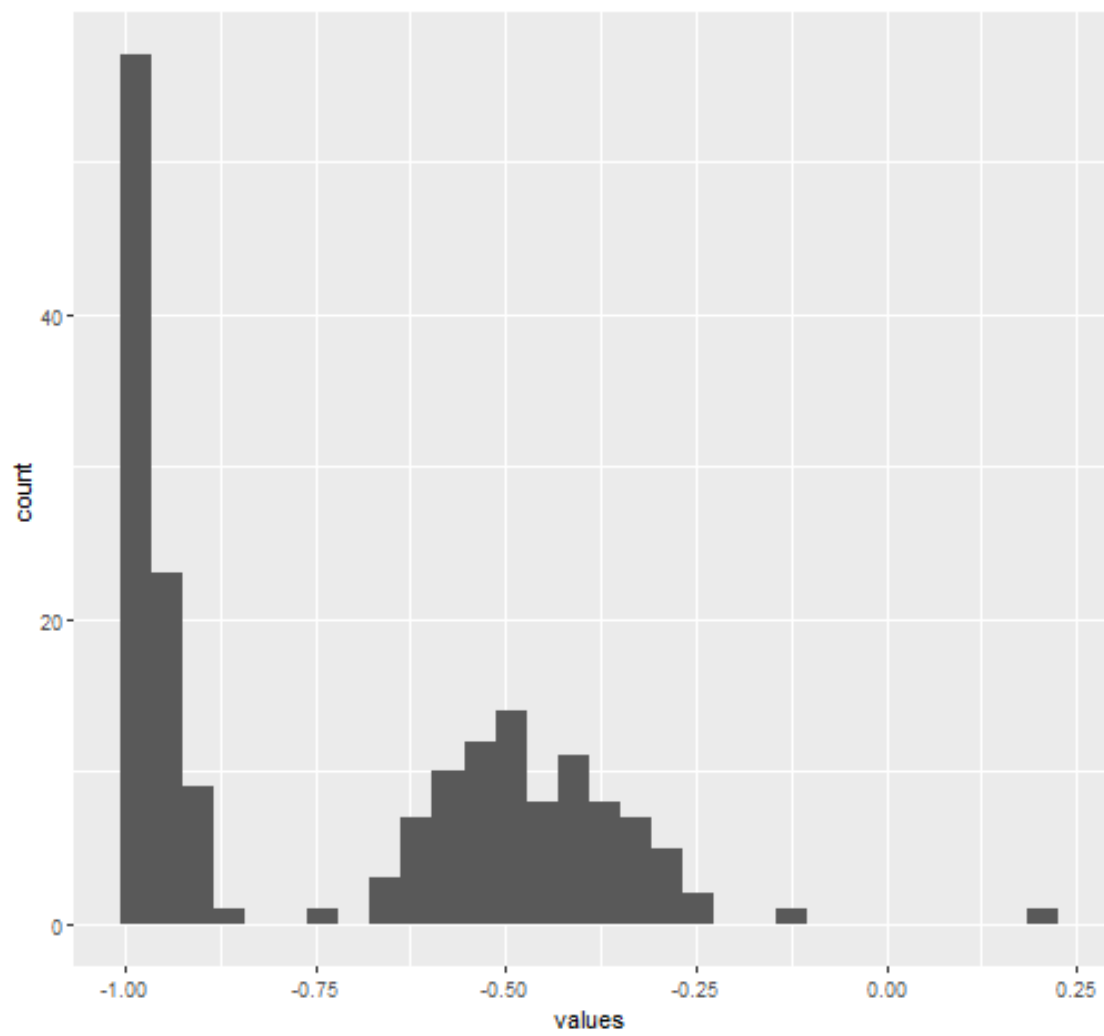
Summary statistics

name	data_type	missing	complete	n	mean	std	p0	p25	p50	p75	p100	hist
frequency	numeric	0	180	18	1.8	0.3	0.9	0.9	0.9	0.9	0.9	<U+2587><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581><U+2581>
Bodysize	numeric	0	180	18	1.8	0.3	0.9	0.9	0.9	0.9	0.9	
Gyr	numeric	0	180	18	1.8	0.3	0.9	0.9	0.9	0.9	0.9	
osc	numeric	0	180	18	1.8	0.3	0.9	0.9	0.9	0.9	0.9	
open	numeric	0	180	18	1.8	0.3	0.9	0.9	0.9	0.9	0.9	
-	numeric	0	180	18	1.8	0.3	0.9	0.9	0.9	0.9	0.9	
mean()	numeric	0	180	18	1.8	0.3	0.9	0.9	0.9	0.9	0.9	
n()	numeric	0	180	18	1.8	0.3	0.9	0.9	0.9	0.9	0.9	
Z	numeric	0	180	18	1.8	0.3	0.9	0.9	0.9	0.9	0.9	

frequency Body Gyroscope -std()-X

Distribution

frequency Body Gyroscope -std()-X



plot of chunk distribution

0 missing values.

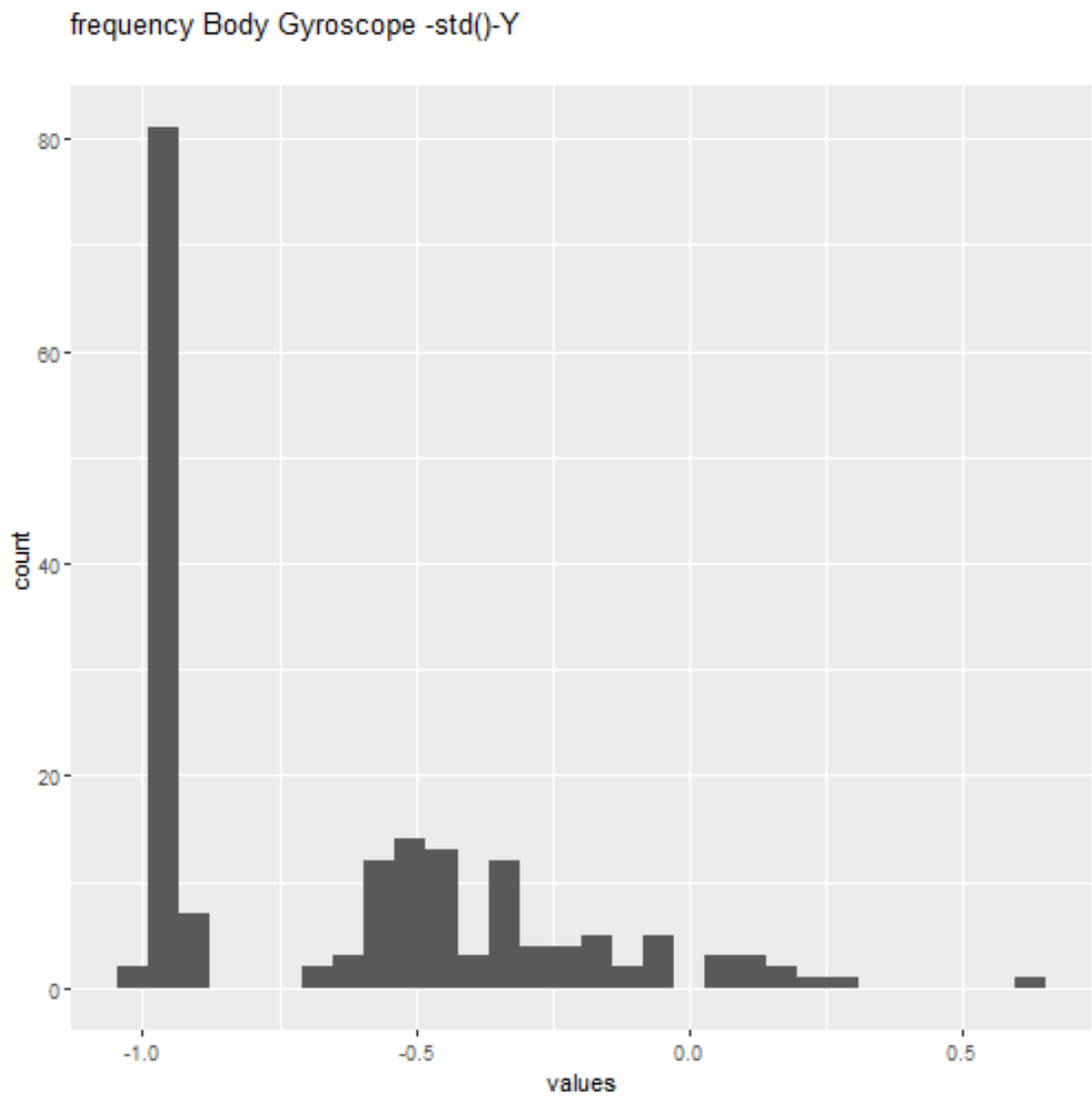
Summary statistics

name	data type	missing	complete	n	mean	std	p0	p25	p50	p75	p100	
frequency	numeric	0	180	180	-0.7	0.2	-0.99	-0.9	-0.8	-0.6	-0.2	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

Bod  
y  
Gyr  
osc  
ope  
-  
std(  
)-X

frequency Body Gyroscope -std()-Y

Distribution



plot of chunk distribution

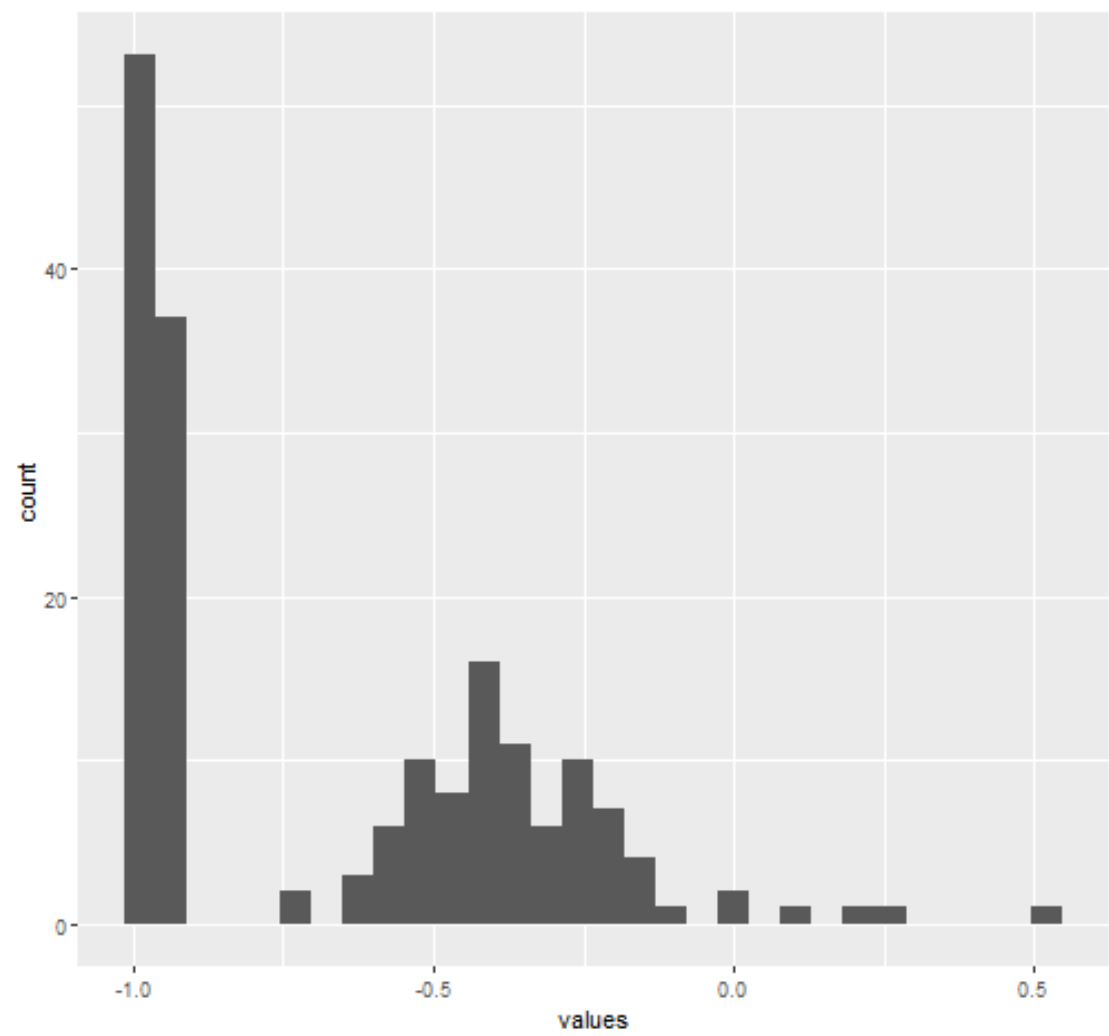
0 missing values.

[illegible]

frequency Body Gyroscope -std()-Z

Distribution

frequency Body Gyroscope -std()-Z



plot of chunk distribution

0 missing values.

Summary statistics

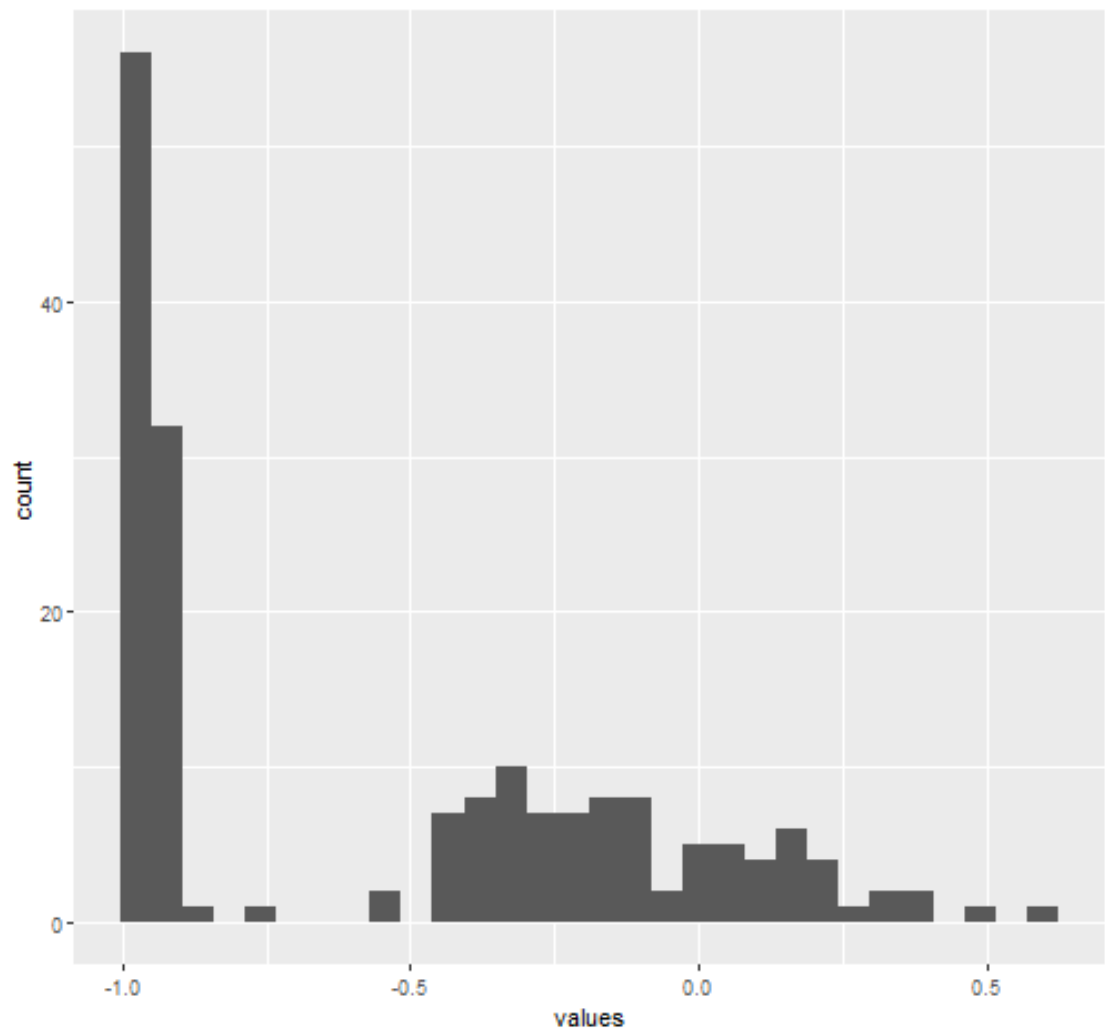
na	dat	mi	co	m	s	p	p	p	p	p	hist
freq	nu	0	18	1	-	0.	-	-	-	-	<U+2587><U+2581><U+2583><U
uen	me		0	8	0.	3	0.	0.	0.	0.	+2583><U+2581><U+2581><U+2
cy	ric			0	6	4	9	9	8	3	581><U+2581>

Bod  
y  
Gyr  
osc  
ope  
-  
std(  
)-Z

frequency Body Accelerometer Magnitude -mean()

Distribution

frequency Body Accelerometer Magnitude -mean()



plot of chunk distribution

0 missing values.

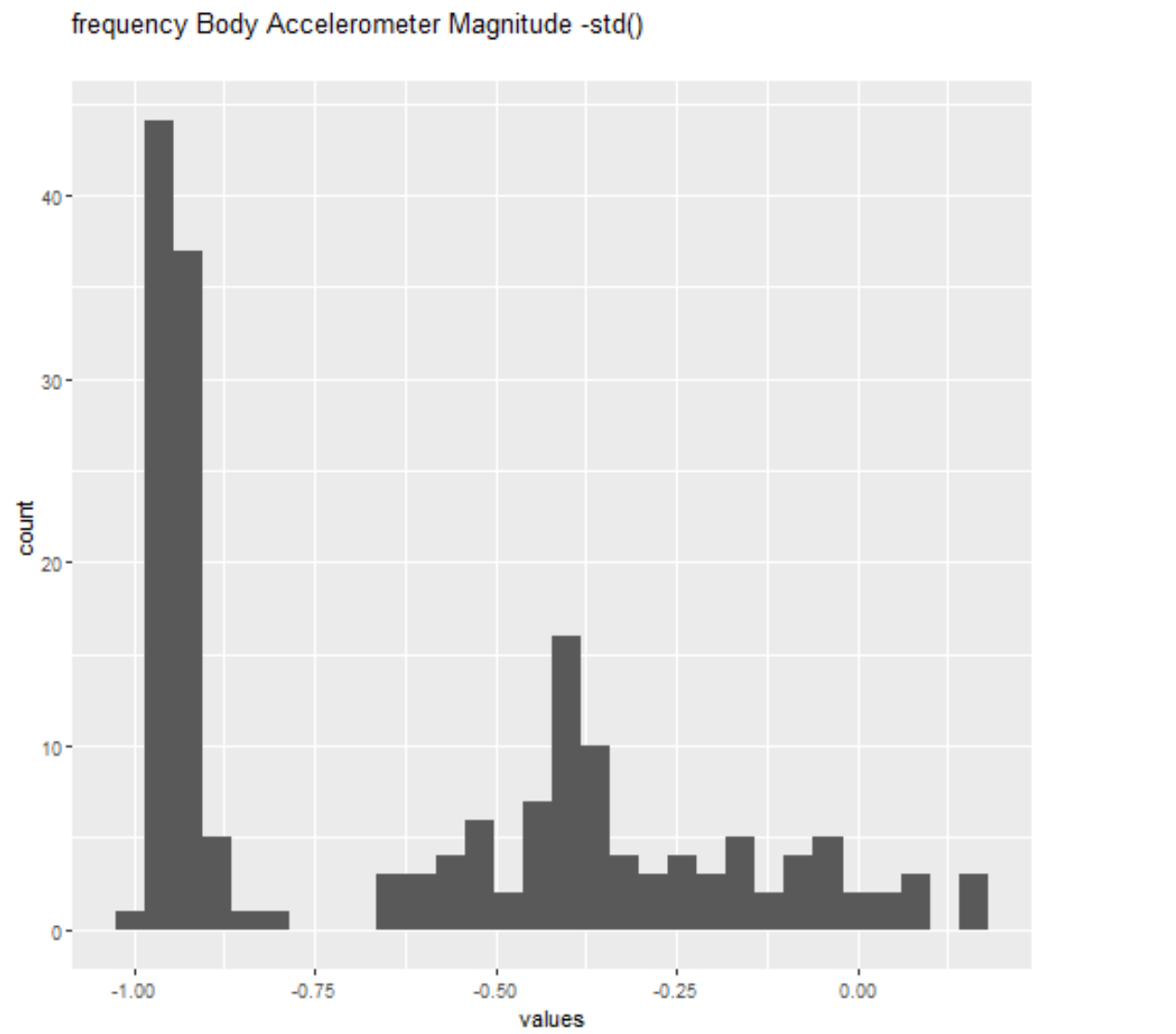
Summary statistics

name	data_type	missing	complete	n	mean	std	p0	p25	p50	p75	p100	hist
frequency	numeric	0	180	18	1.8	0.54	-	-	-	-	0.5	<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581>
Body Accelerometer Magnitude	numeric	0	180	18	1.8	0.54	-	-	-	-	0.5	<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581>
-	numeric	0	180	18	1.8	0.54	-	-	-	-	0.5	<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581>
mean	numeric	0	180	18	1.8	0.54	-	-	-	-	0.5	<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581>
0	numeric	0	180	18	1.8	0.54	-	-	-	-	0.5	<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581>



frequency Body Accelerometer Magnitude -std()

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

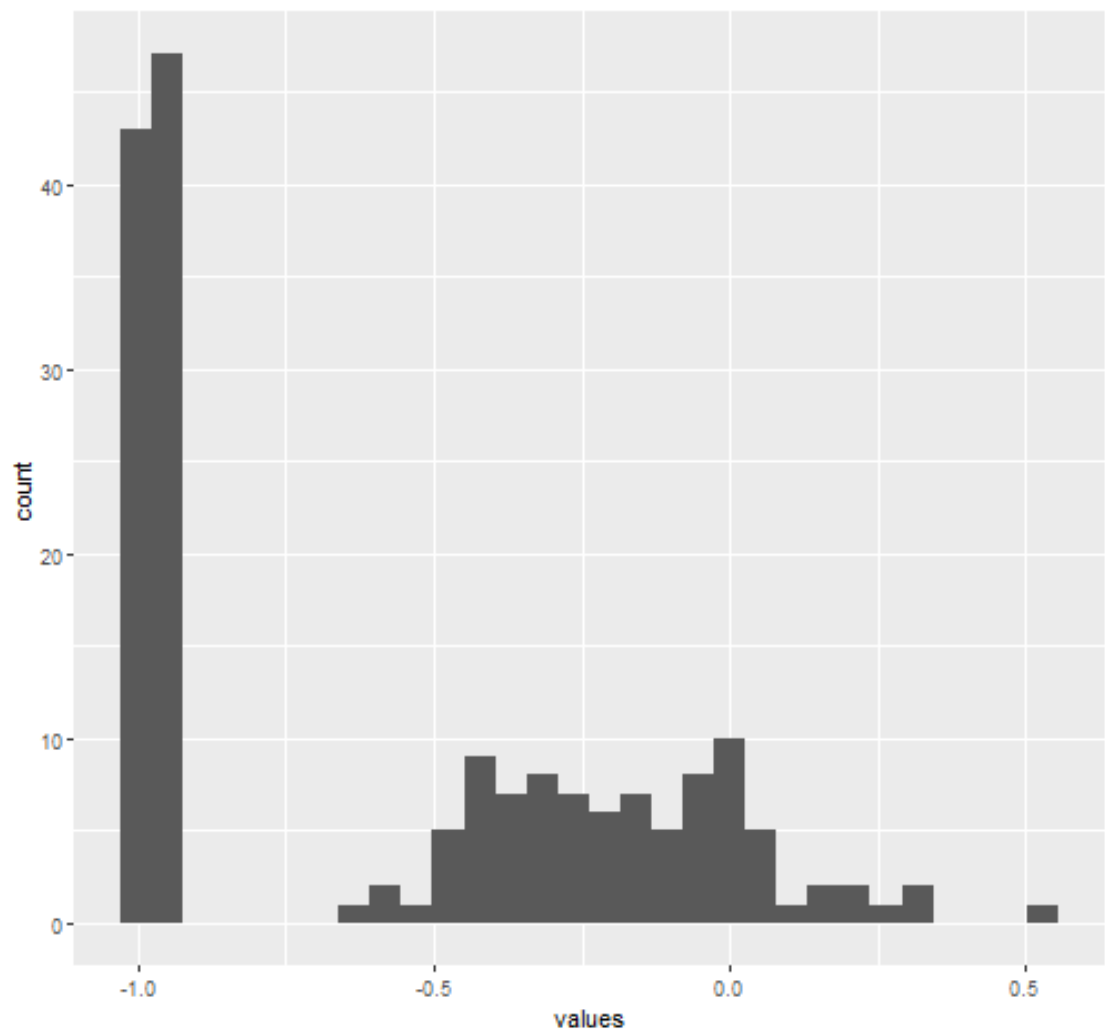
name	type	mi	co	m							p	hist
				n	a	s	p	2	5	7		
frequency	numeric	0	180	18	-0.6	0.3	-0.0	-0.0	-0.0	-0.0	0.1	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2581><U+2581>

Accelerometer JerkMagnitude -std()  
2 5 9 9 6 3  
9 5 5 7

frequency BodyBody Accelerometer JerkMagnitude -mean()

Distribution

frequency BodyBody Accelerometer JerkMagnitude -mean()



plot of chunk distribution

0 missing values.

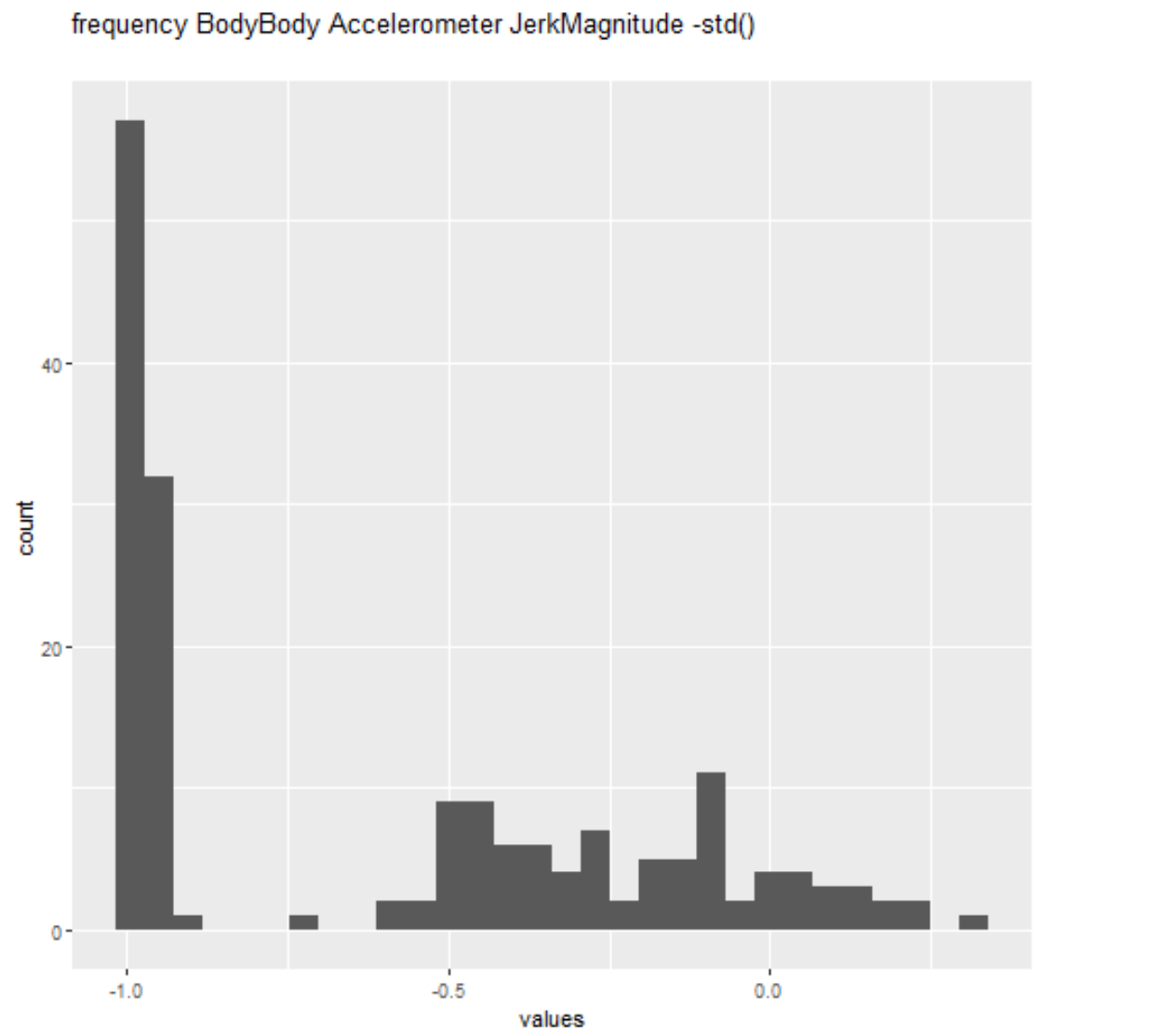
Summary statistics

name	dat	mi	co	n	m	s	p	p	p	p	hist
------	-----	----	----	---	---	---	---	---	---	---	------

	a_t ype	ssi ng	mp lete	e a n	d	0	2	5	7	1	
							5	0	5	0	0
frequ ency Body Body Accel erom eter JerkM agnit ude - mean ()	nu me ric	0	18 0	1 8 0	- 0. 5	0 . 4	- 0 . 9	- 0 . 9	- 0 . 7	- 0 . 1	0. 5 4
											<U+2587><U+2581><U+2581>< U+2582><U+2582><U+2582><U +2581><U+2581>

frequency BodyBody Accelerometer JerkMagnitude -std()

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

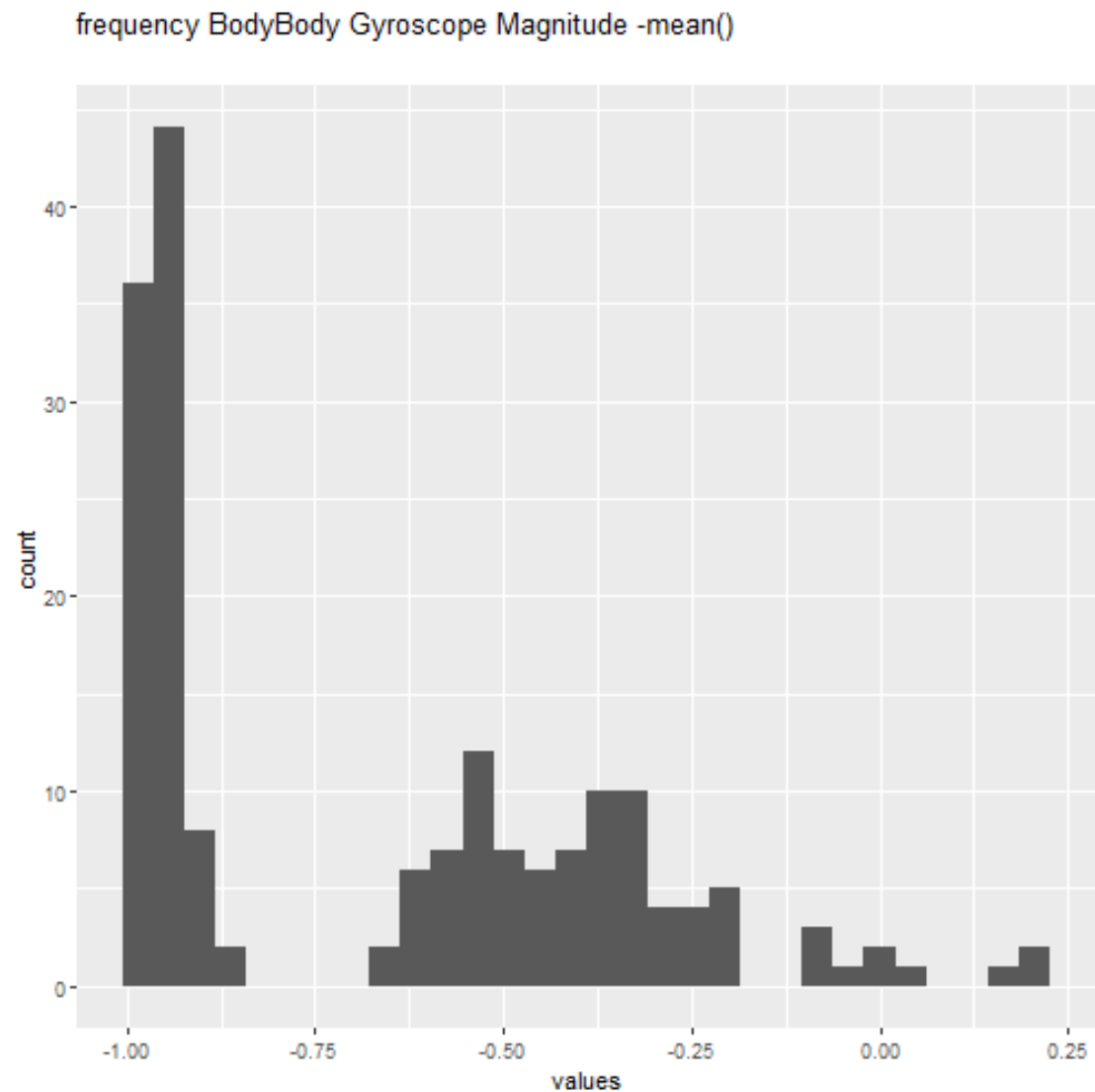
name	data type	missing	complete	measures of central tendency					measures of dispersion			hist
				n	mean	std	var	skew	min	max	range	
frequency Body	numeric	0	180	18	-0.64	0.5	0.25	-0.05	-1.0	0.5	1.5	<U+2587><U+2581><U+2581><U+2582><U+2581><U+2582><U+2581><U+2581>

Body  
Accelerometer  
JerkMagnitude  
std()

1	9	9	8	2
	9	8	1	7

frequency BodyBody Gyroscope Magnitude -mean()

Distribution



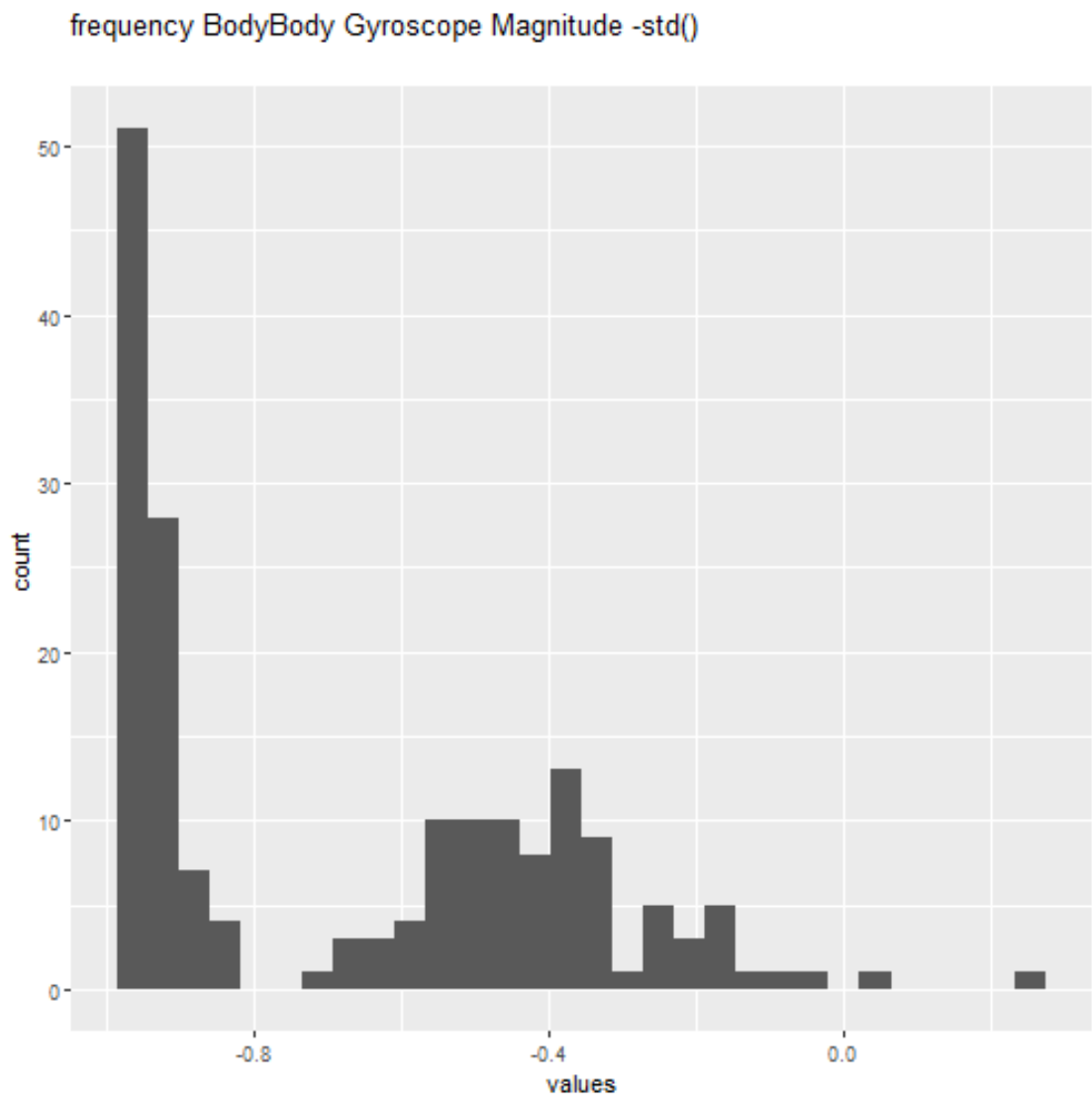
plot of chunk distribution

0 missing values.

[illegible]

frequency BodyBody Gyroscope Magnitude -std()

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

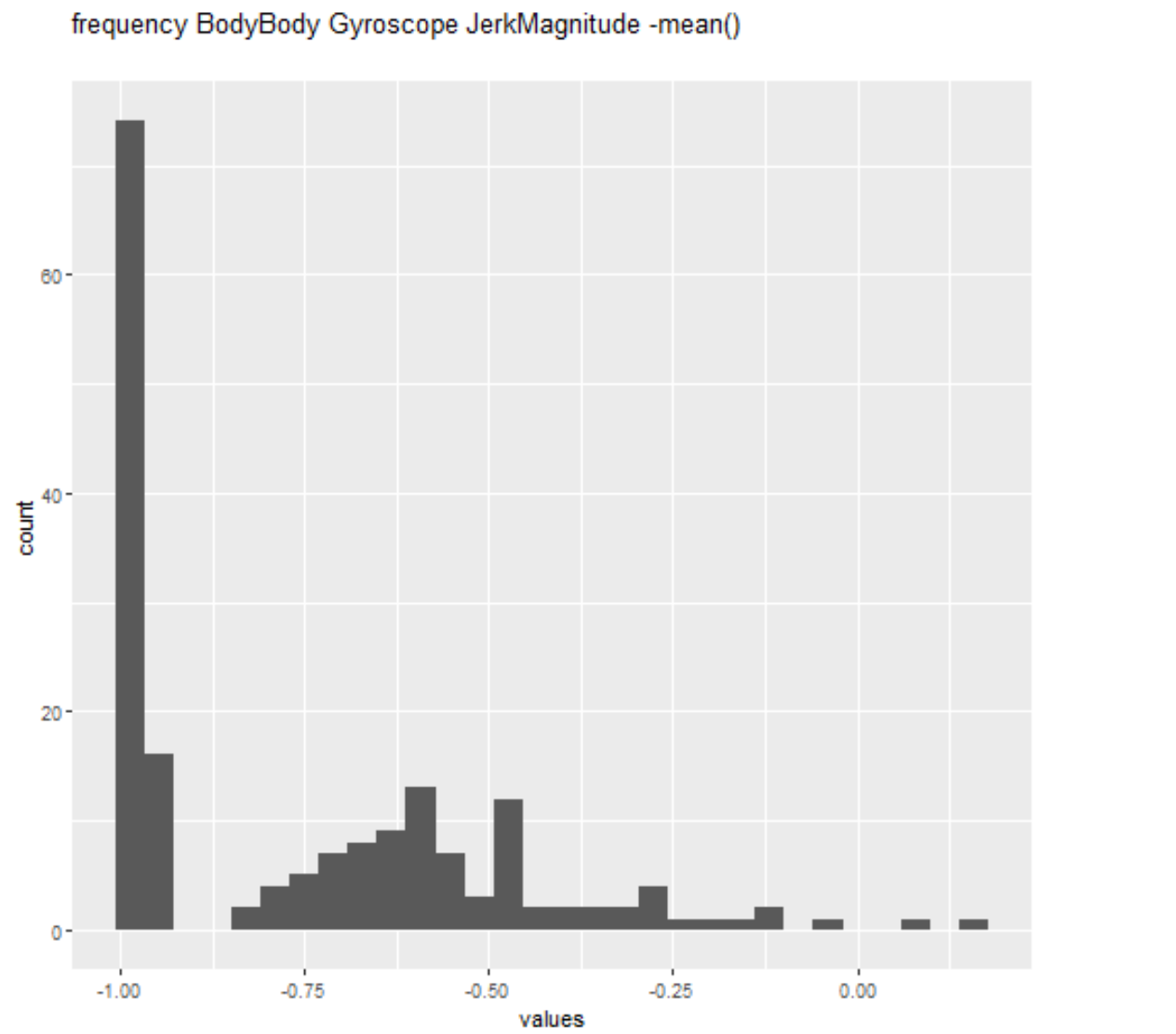
name	datatype	missing	complete	mean	std	p0	p25	p50	p75	p100	hist
frequency	numeric	0	180	1.80	0.69	0.00	0.09	0.09	0.07	0.04	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

Bod	7	8	5	7	3
yBo					
dy					
Gyr					
osc					
ope					
Mag					
nitu					
de -					
std(					
)					



frequency BodyBody Gyroscope JerkMagnitude -mean()

Distribution



plot of chunk distribution

0 missing values.

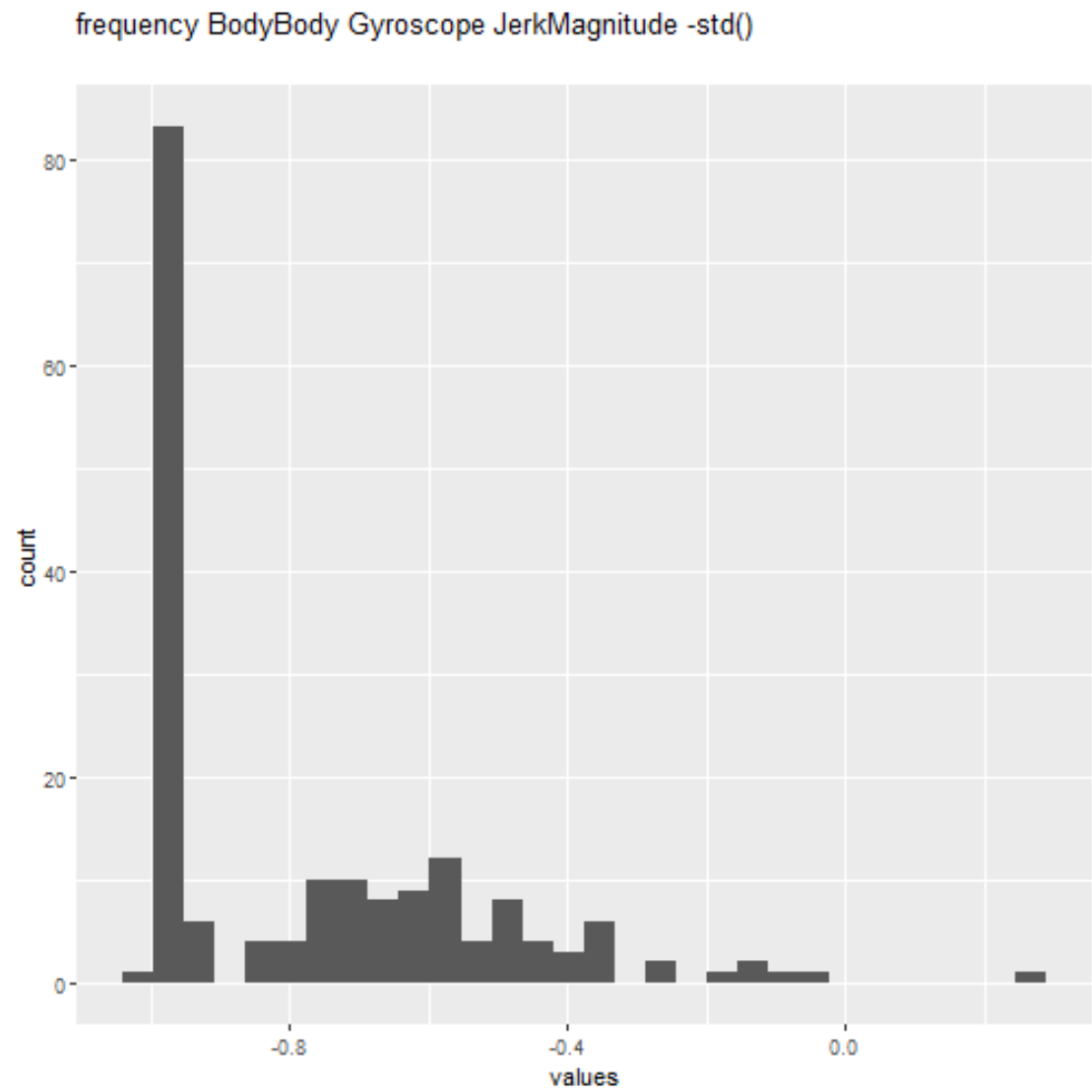
Summary statistics

				m					p					
	dat	mi	co	e		p		p	p	p	1			
	a_t	ssi	mp	a	s	p	2	5	7	0				
name	type	ng	lete	n	n	d	0	5	0	5	0	hist		
frequ	nu	0	18	1	-	0.	-	-	-	-	0.	<U+2587><U+2582><U+2583><U		
ency	me		0	8	0.	2	1	0.	0.	0.	1	+2582><U+2581><U+2581><U+2		
Body	ric			0	7	6		9	8	5	5	581><U+2581>		

Body Gyroscopes JerkMagnitude -std()  
0

frequency BodyBody Gyroscope JerkMagnitude -std()

Distribution



plot of chunk distribution

0 missing values.

## Summary statistics

name	data_type	missing	complete	n	empty	n_unique	min	max	mean	sd	hist
frequency	numeric	0	180	180	0.7	9	-0.2	0.9	-0.05	0.2	<U+2587><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581>
Body	numeric			7		8		9		1	
Body											
Gyros											
cope											
JerkM											
agnit											
ude -											
std()											

## Missingness report

### Codebook table

```
## PhantomJS not found. You can install it with webshot::install_phantomjs().  
If it is installed, please make sure the phantomjs executable can be found  
via the PATH variable.
```

```
## Warning in normalizePath(path.expand(path), winslash, mustWork):  
## path[1]="webshot3d28ac16c0a.png": The system cannot find the file  
specified
```

```
## Warning in file(con, "rb"): cannot open file 'C:  
##  
\Users\dendluri\AppData\Local\Temp\Rtmp4imiJj\file3d281363290b\webshot3d28ac1  
6c0a.png':  
## No such file or directory
```

```
## Error in file(con, "rb"): cannot open the connection
```

JSON-LD metadata The following JSON-LD can be found by search engines, if you share this codebook publicly on the web.

```
{  
  "name": "dataset",  
  "datePublished": "2019-05-05",  
  "description": "The dataset has N=180 rows and 68 columns.\n180 rows have  
no missing values on any column.\n\n\n## Table of variables\nThis table  
contains variable names, labels, their central tendencies and other  
attributes.\n\n|name  
|data_type |missing |complete |n |empty |n_unique |min |max |mean |sd  
|p0 |p25 |p50 |p75 |p100 |hist | \n|:-----  
-----|:-----|:-----|:-----|:---|:-----
```

```

|:-----|:---|:---|:-----|:-----|:-----|:-----|:-----|:-----|:-----
--|:-----|\n|activity
|character |0          |180          |180 |0          |6          |6 |18 |NA      |NA
|NA        |NA          |NA          |NA  |NA          |NA          |\n|subject
|integer    |0          |180          |180 |NA          |NA          |NA |NA |15.5    |8.68
|1          |8          |15.5        |23  |30
|<U+2587><U+2587><U+2586><U+2587><U+2587><U+2586><U+2587><U+2587> |\n|time
Body Accelerometer -mean()-X          |numeric |0          |180
|180 |NA    |NA          |NA |NA |0.27    |0.012    |0.22    |0.27    |0.28
|0.28    |0.3
|<U+2581><U+2581><U+2581><U+2581><U+2582><U+2587><U+2582><U+2581> |\n|time
Body Accelerometer -mean()-Y          |numeric |0          |180
|180 |NA    |NA          |NA |NA |-0.018   |0.0058   |-0.041   |-0.02    |-0.017   |-
0.015   |-0.0013
|<U+2581><U+2581><U+2582><U+2582><U+2587><U+2583><U+2581><U+2581> |\n|time
Body Accelerometer -mean()-Z          |numeric |0          |180
|180 |NA    |NA          |NA |NA |-0.11    |0.0096   |-0.15    |-0.11    |-0.11    |-
0.1     |-0.075
|<U+2581><U+2581><U+2581><U+2582><U+2587><U+2583><U+2581><U+2581> |\n|time
Body Accelerometer -std()-X          |numeric |0          |180
|180 |NA    |NA          |NA |NA |-0.56    |0.45     |-1        |-0.98    |-0.75     |-
0.2     |0.63
|<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581> |\n|time
Body Accelerometer -std()-Y          |numeric |0          |180
|180 |NA    |NA          |NA |NA |-0.46    |0.5       |-0.99     |-0.94     |-0.51     |-
0.031   |0.62
|<U+2587><U+2581><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581> |\n|time
Body Accelerometer -std()-Z          |numeric |0          |180
|180 |NA    |NA          |NA |NA |-0.58    |0.4       |-0.99     |-0.95     |-0.65     |-
0.23    |0.61
|<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581> |\n|time
Gravity Accelerometer -mean()-X          |numeric |0          |180
|180 |NA    |NA          |NA |NA |0.7       |0.49     |-0.68     |0.84     |0.92
|0.94     |0.97
|<U+2581><U+2581><U+2581><U+2581><U+2581><U+2581><U+2581><U+2587> |\n|time
Gravity Accelerometer -mean()-Y          |numeric |0          |180
|180 |NA    |NA          |NA |NA |-0.016   |0.35     |-0.48     |-0.23     |-0.13
|0.088    |0.96
|<U+2582><U+2587><U+2585><U+2582><U+2581><U+2581><U+2581><U+2581> |\n|time
Gravity Accelerometer -mean()-Z          |numeric |0          |180
|180 |NA    |NA          |NA |NA |0.074    |0.29     |-0.5       |-0.12     |0.024
|0.15     |0.96
|<U+2581><U+2585><U+2587><U+2586><U+2581><U+2581><U+2581><U+2581> |\n|time
Gravity Accelerometer -std()-X          |numeric |0          |180
|180 |NA    |NA          |NA |NA |-0.96    |0.025     |-1         |-0.98     |-0.97     |-
0.95     |-0.83
|<U+2587><U+2586><U+2585><U+2582><U+2581><U+2581><U+2581><U+2581> |\n|time
Gravity Accelerometer -std()-Y          |numeric |0          |180
|180 |NA    |NA          |NA |NA |-0.95    |0.033     |-0.99     |-0.97     |-0.96     |-
0.94     |-0.64

```

```

|<U+2587><U+2585><U+2581><U+2581><U+2581><U+2581><U+2581><U+2581> |\\n|time
Gravity Accelerometer -std()-Z |numeric |0 |180
|180 |NA |NA |NA |NA |-0.94 |0.04 |-0.99 |-0.96 |-0.95 |-
0.92 |-0.61
|<U+2587><U+2586><U+2582><U+2581><U+2581><U+2581><U+2581><U+2581> |\\n|time
Body Accelerometer Jerk-mean()-X |numeric |0 |180
|180 |NA |NA |NA |NA |0.079 |0.013 |0.043 |0.074 |0.076
|0.083 |0.13
|<U+2581><U+2581><U+2587><U+2587><U+2582><U+2581><U+2581><U+2581> |\\n|time
Body Accelerometer Jerk-mean()-Y |numeric |0 |180
|180 |NA |NA |NA |NA |0.0076 |0.014 |-0.039 |0.00047 |0.0095
|0.013 |0.057
|<U+2581><U+2581><U+2582><U+2586><U+2587><U+2582><U+2581><U+2581> |\\n|time
Body Accelerometer Jerk-mean()-Z |numeric |0 |180
|180 |NA |NA |NA |NA |-0.005 |0.013 |-0.067 |-0.011 |-0.0039
|0.002 |0.038
|<U+2581><U+2581><U+2581><U+2581><U+2587><U+2586><U+2581><U+2581> |\\n|time
Body Accelerometer Jerk-std()-X |numeric |0 |180
|180 |NA |NA |NA |NA |-0.59 |0.42 |-0.99 |-0.98 |-0.81 |-
0.22 |0.54
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581> |\\n|time
Body Accelerometer Jerk-std()-Y |numeric |0 |180
|180 |NA |NA |NA |NA |-0.57 |0.43 |-0.99 |-0.97 |-0.78 |-
0.15 |0.36
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581> |\\n|time
Body Accelerometer Jerk-std()-Z |numeric |0 |180
|180 |NA |NA |NA |NA |-0.74 |0.28 |-0.99 |-0.98 |-0.88 |-
0.51 |0.031
|<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581> |\\n|time
Body Gyroscope -mean()-X |numeric |0 |180
|180 |NA |NA |NA |NA |-0.032 |0.054 |-0.21 |-0.047 |-0.029 |-
0.017 |0.19
|<U+2581><U+2581><U+2582><U+2587><U+2581><U+2581><U+2581><U+2581> |\\n|time
Body Gyroscope -mean()-Y |numeric |0 |180
|180 |NA |NA |NA |NA |-0.074 |0.036 |-0.2 |-0.09 |-0.073 |-
0.061 |0.027
|<U+2581><U+2581><U+2581><U+2583><U+2587><U+2582><U+2581><U+2581> |\\n|time
Body Gyroscope -mean()-Z |numeric |0 |180
|180 |NA |NA |NA |NA |0.087 |0.036 |-0.072 |0.075 |0.085
|0.1 |0.18
|<U+2581><U+2581><U+2581><U+2581><U+2587><U+2587><U+2582><U+2581> |\\n|time
Body Gyroscope -std()-X |numeric |0 |180
|180 |NA |NA |NA |NA |-0.69 |0.29 |-0.99 |-0.97 |-0.79 |-
0.44 |0.27
|<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581> |\\n|time
Body Gyroscope -std()-Y |numeric |0 |180
|180 |NA |NA |NA |NA |-0.65 |0.35 |-0.99 |-0.96 |-0.8 |-
0.42 |0.48
|<U+2587><U+2581><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581> |\\n|time
Body Gyroscope -std()-Z |numeric |0 |180

```

180	NA	NA	NA	NA	-0.62	0.37	-0.99	-0.96	-0.8	-0.31	0.56
<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>   \n  time											
Body Gyroscope Jerk-mean()-X  numeric  0  180											
180	NA	NA	NA	NA	-0.096	0.023	-0.16	-0.1	-0.099	-0.091	-0.022
<U+2581><U+2581><U+2581><U+2587><U+2581><U+2581><U+2581><U+2581>   \n  time											
Body Gyroscope Jerk-mean()-Y  numeric  0  180											
180	NA	NA	NA	NA	-0.043	0.0095	-0.077	-0.046	-0.041	-0.038	-0.013
<U+2581><U+2581><U+2581><U+2582><U+2587><U+2582><U+2581><U+2581>   \n  time											
Body Gyroscope Jerk-mean()-Z  numeric  0  180											
180	NA	NA	NA	NA	-0.055	0.012	-0.092	-0.062	-0.053	-0.049	-0.0069
<U+2581><U+2581><U+2583><U+2587><U+2583><U+2581><U+2581><U+2581>   \n  time											
Body Gyroscope Jerk-std()-X  numeric  0  180											
180	NA	NA	NA	NA	-0.7	0.3	-1	-0.98	-0.84	-0.46	0.18
<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>   \n  time											
Body Gyroscope Jerk-std()-Y  numeric  0  180											
180	NA	NA	NA	NA	-0.76	0.27	-1	-0.98	-0.89	-0.59	0.3
<U+2587><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581><U+2581>   \n  time											
Body Gyroscope Jerk-std()-Z  numeric  0  180											
180	NA	NA	NA	NA	-0.71	0.3	-1	-0.98	-0.86	-0.47	0.19
<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581>   \n  time											
Body Accelerometer Magnitude -mean()  numeric  0  180											
180	NA	NA	NA	NA	-0.5	0.47	-0.99	-0.96	-0.48	-0.092	0.64
<U+2587><U+2581><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581>   \n  time											
Body Accelerometer Magnitude -std()  numeric  0  180											
180	NA	NA	NA	NA	-0.54	0.43	-0.99	-0.94	-0.61	-0.21	0.43
<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2582><U+2581>   \n  time											
Gravity Accelerometer Magnitude -mean()  numeric  0  180											
180	NA	NA	NA	NA	-0.5	0.47	-0.99	-0.96	-0.48	-0.092	0.64
<U+2587><U+2581><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581>   \n  time											
Gravity Accelerometer Magnitude -std()  numeric  0  180											
180	NA	NA	NA	NA	-0.54	0.43	-0.99	-0.94	-0.61	-0.21	0.43
<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2582><U+2581>   \n  time											
Body Accelerometer JerkMagnitude -mean()  numeric  0  180											
180	NA	NA	NA	NA	-0.61	0.4	-0.99	-0.98	-0.82	-0.25	0.43
<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2581><U+2581>   \n  time											
Body Accelerometer JerkMagnitude -std()  numeric  0  180											
180	NA	NA	NA	NA	-0.58	0.42	-0.99	-0.98	-0.8	-0.22	0.45

```

|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581> |\\n|time
Body Gyroscope Magnitude -mean() |numeric |0 |180
|180 |NA |NA |NA |NA |-0.57 |0.4 |-0.98 |-0.95 |-0.66 |-
0.22 |0.42
|<U+2587><U+2581><U+2581><U+2582><U+2583><U+2581><U+2581><U+2581> |\\n|time
Body Gyroscope Magnitude -std() |numeric |0 |180
|180 |NA |NA |NA |NA |-0.63 |0.34 |-0.98 |-0.95 |-0.74 |-
0.36 |0.3
|<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581> |\\n|time
Body Gyroscope JerkMagnitude -mean() |numeric |0 |180
|180 |NA |NA |NA |NA |-0.74 |0.28 |-1 |-0.99 |-0.86 |-
0.51 |0.088
|<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581> |\\n|time
Body Gyroscope JerkMagnitude -std() |numeric |0 |180
|180 |NA |NA |NA |NA |-0.76 |0.27 |-1 |-0.98 |-0.88 |-
0.58 |0.25
|<U+2587><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581>
|\\n|frequency Body Accelerometer -mean()-X |numeric |0
|180 |180 |NA |NA |NA |NA |-0.58 |0.43 |-1 |-0.98 |-
0.77 |-0.22 |0.54
|<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581>
|\\n|frequency Body Accelerometer -mean()-Y |numeric |0
|180 |180 |NA |NA |NA |NA |-0.49 |0.48 |-0.99 |-0.95 |-
0.59 |-0.063 |0.52
|<U+2587><U+2581><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581>
|\\n|frequency Body Accelerometer -mean()-Z |numeric |0
|180 |180 |NA |NA |NA |NA |-0.63 |0.36 |-0.99 |-0.96 |-
0.72 |-0.32 |0.28
|<U+2587><U+2581><U+2581><U+2582><U+2583><U+2581><U+2581><U+2581>
|\\n|frequency Body Accelerometer -std()-X |numeric |0
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0.75 |-0.2 |0.66
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|\\n|frequency Body Accelerometer -std()-Y |numeric |0
|180 |180 |NA |NA |NA |NA |-0.48 |0.47 |-0.99 |-0.94 |-
0.51 |-0.079 |0.56
|<U+2587><U+2581><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581>
|\\n|frequency Body Accelerometer -std()-Z |numeric |0
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0.64 |-0.27 |0.69
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|\\n|frequency Body Accelerometer Jerk-mean()-X |numeric |0
|180 |180 |NA |NA |NA |NA |-0.61 |0.4 |-0.99 |-0.98 |-
0.81 |-0.28 |0.47
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2581><U+2581>
|\\n|frequency Body Accelerometer Jerk-mean()-Y |numeric |0
|180 |180 |NA |NA |NA |NA |-0.59 |0.41 |-0.99 |-0.97 |-
0.78 |-0.2 |0.28
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>
|\\n|frequency Body Accelerometer Jerk-mean()-Z |numeric |0

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180	180	NA	NA	NA	NA	0.71	0.3	0.99	0.98	
0.87	-0.47	0.16								
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\n frequency Body Accelerometer Jerk-std()-X										
180	180	NA	NA	NA	NA	-0.61	0.4	-1	-0.98	
0.83	-0.25	0.48								
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180	180	NA	NA	NA	NA	-0.57	0.43	-0.99	-0.97	
0.79	-0.17	0.35								
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0.73	-0.34	0.47								
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0.81	-0.45	0.33								
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180	180	NA	NA	NA	NA	-0.6	0.38	-0.99	-0.96	
0.79	-0.26	0.49								
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\n frequency Body Gyroscope -std()-X										
180	180	NA	NA	NA	NA	-0.71	0.27	-0.99	-0.98	
0.81	-0.48	0.2								
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0.8	-0.42	0.65								
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\n frequency Body Gyroscope -std()-Z										
180	180	NA	NA	NA	NA	-0.66	0.34	-0.99	-0.96	
0.82	-0.39	0.52								
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\n frequency Body Accelerometer Magnitude -mean()										
180	180	NA	NA	NA	NA	-0.54	0.45	-0.99	-0.96	
0.67	-0.16	0.59								
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180	180	NA	NA	NA	NA	-0.62	0.35	-0.99	-0.95	
0.65	-0.37	0.18								
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\n frequency BodyBody Accelerometer JerkMagnitude -mean()										
180	180	NA	NA	NA	NA	-0.58	0.43	-0.99	-0.98	
0.79	-0.19	0.54								



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|180 |180 |NA |NA |NA |NA |-0.6 |0.41 |-0.99 |-0.98 |-
0.81 |-0.27 |0.32
|<U+2587><U+2581><U+2581><U+2582><U+2581><U+2582><U+2581><U+2581>
|\n|frequency BodyBody Gyroscope Magnitude -mean() |numeric |0
|180 |180 |NA |NA |NA |NA |-0.67 |0.32 |-0.99 |-0.96 |-
0.77 |-0.41 |0.2
|<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581>
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0.77 |-0.43 |0.24
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|\n|frequency BodyBody Gyroscope JerkMagnitude -mean() |numeric |0
|180 |180 |NA |NA |NA |NA |-0.76 |0.26 |-1 |-0.98 |-
0.88 |-0.58 |0.15
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|\n|frequency BodyBody Gyroscope JerkMagnitude -std() |numeric |0
|180 |180 |NA |NA |NA |NA |-0.77 |0.25 |-1 |-0.98 |-
0.89 |-0.61 |0.29
|<U+2587><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581> |\n\n###
Note\nThis dataset was automatically described using the [codebook R
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