Metadata

Description

Dataset name: dataset

The dataset has N=180 rows and 68 columns. 180 rows have no missing values on any column.

Metadata for search engines

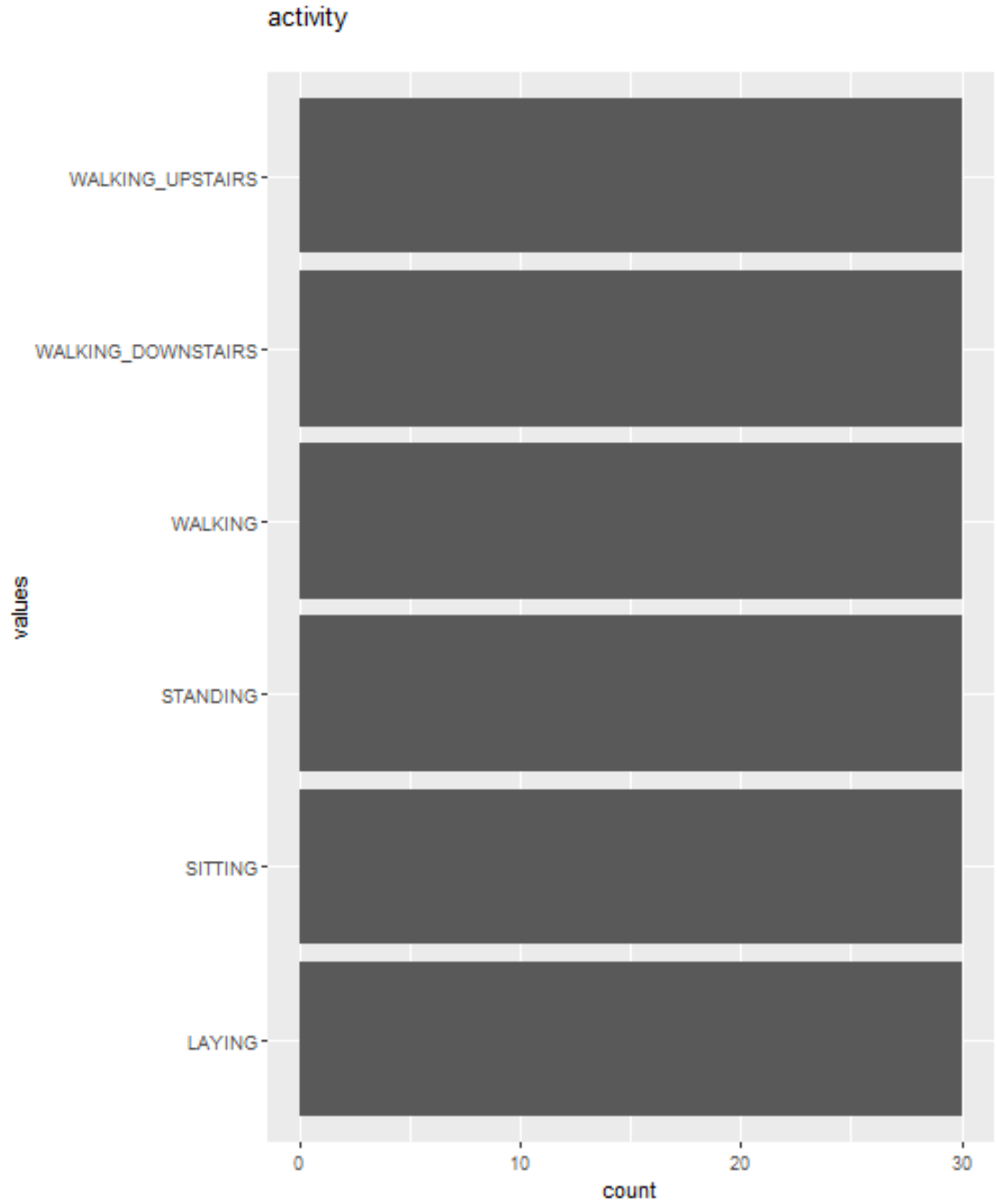
- **Date published**: 2019-05-05
  - **keywords**: *activity*, *subject*, *time Body Accelerometer -mean()-X*, *time Body Accelerometer -mean()-Y*, *time Body Accelerometer -mean()-Z*, *time Body Accelerometer -std()-X*, *time Body Accelerometer -std()-Y*, *time Body Accelerometer -std()-Z*, *time Gravity Accelerometer -mean()-X*, *time Gravity Accelerometer -mean()-Y*, *time Gravity Accelerometer -mean()-Z*, *time Gravity Accelerometer -std()-X*, *time Gravity Accelerometer -std()-Y*, *time Gravity Accelerometer -std()-Z*, *time Body Accelerometer Jerk-mean()-X*, *time Body Accelerometer Jerk-mean()-Y*, *time Body Accelerometer Jerk-mean()-Z*, *time Body Accelerometer Jerk-std()-X*, *time Body Accelerometer Jerk-std()-Y*, *time Body Accelerometer Jerk-std()-Z*, *time Body Gyroscope -mean()-X*, *time Body Gyroscope -mean()-Y*, *time Body Gyroscope -mean()-Z*, *time Body Gyroscope -std()-X*, *time Body Gyroscope -std()-Y*, *time Body Gyroscope -std()-Z*, *time Body Gyroscope Jerk-mean()-X*, *time Body Gyroscope Jerk-mean()-Y*, *time Body Gyroscope Jerk-mean()-Z*, *time Body Gyroscope Jerk-std()-X*, *time Body Gyroscope Jerk-std()-Y*, *time Body Gyroscope Jerk-std()-Z*, *time Body Accelerometer Magnitude -mean()*, *time Body Accelerometer Magnitude -std()*, *time Gravity Accelerometer Magnitude -mean()*, *time Gravity Accelerometer Magnitude -std()*, *time Body Accelerometer JerkMagnitude -mean()*, *time Body Accelerometer JerkMagnitude -std()*, *time Body Gyroscope Magnitude -mean()*, *time Body Gyroscope Magnitude -std()*, *time Body Gyroscope JerkMagnitude -mean()*, *time Body Gyroscope JerkMagnitude -std()*, *frequency Body Accelerometer -mean()-X*, *frequency Body Accelerometer -mean()-Y*, *frequency Body Accelerometer -mean()-Z*, *frequency Body Accelerometer -std()-X*, *frequency Body Accelerometer -std()-Y*, *frequency Body Accelerometer -std()-Z*, *frequency Body Accelerometer Jerk-mean()-X*, *frequency Body Accelerometer Jerk-mean()-Y*, *frequency Body Accelerometer Jerk-mean()-Z*, *frequency Body Accelerometer Jerk-std()-X*, *frequency Body Accelerometer Jerk-std()-Y*, *frequency Body Accelerometer Jerk-std()-Z*, *frequency Body Gyroscope -mean()-X*, *frequency Body Gyroscope -mean()-Y*, *frequency Body Gyroscope -mean()-Z*, *frequency Body Gyroscope -std()-X*, *frequency Body Gyroscope -std()-Y*, *frequency Body Gyroscope -std()-Z*, *frequency Body Accelerometer Magnitude -mean()*, *frequency Body Accelerometer Magnitude -std()*, *frequency BodyBody Accelerometer JerkMagnitude -mean()*, *frequency BodyBody Accelerometer JerkMagnitude -std()*, *frequency BodyBody Gyroscope Magnitude -mean()*,

frequency BodyBody Gyroscope Magnitude -std(), frequency BodyBody Gyroscope JerkMagnitude -mean() and *frequency BodyBody Gyroscope JerkMagnitude -std()*

Variables

activity

Distribution



plot of chunk distribution

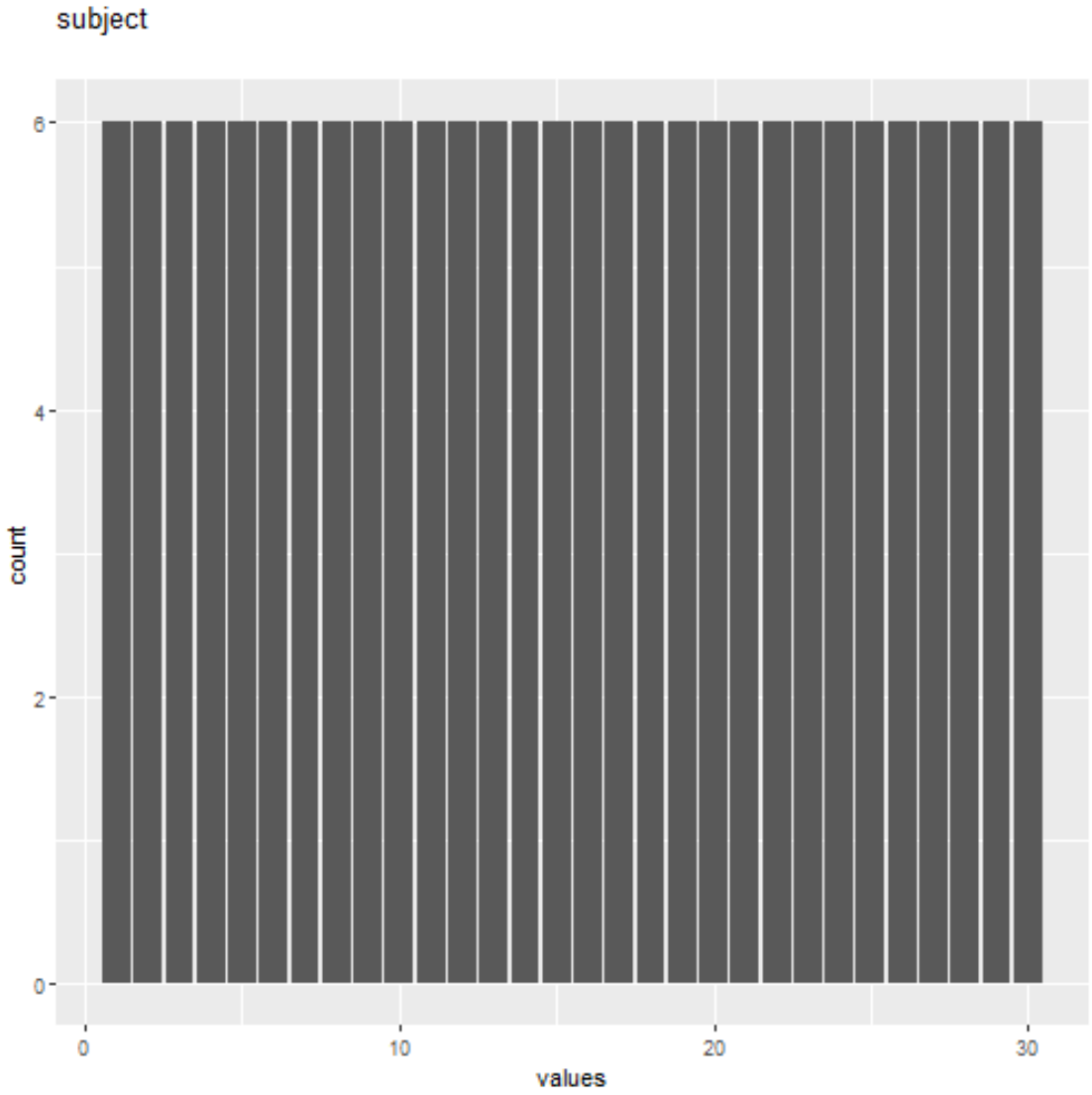
0 missing values.

Summary statistics

name	data_type	missing	complete	n	empty	n_unique	min	max
activity	character	0	180	180	0	6	6	18

subject

Distribution



plot of chunk distribution

0 missing values.

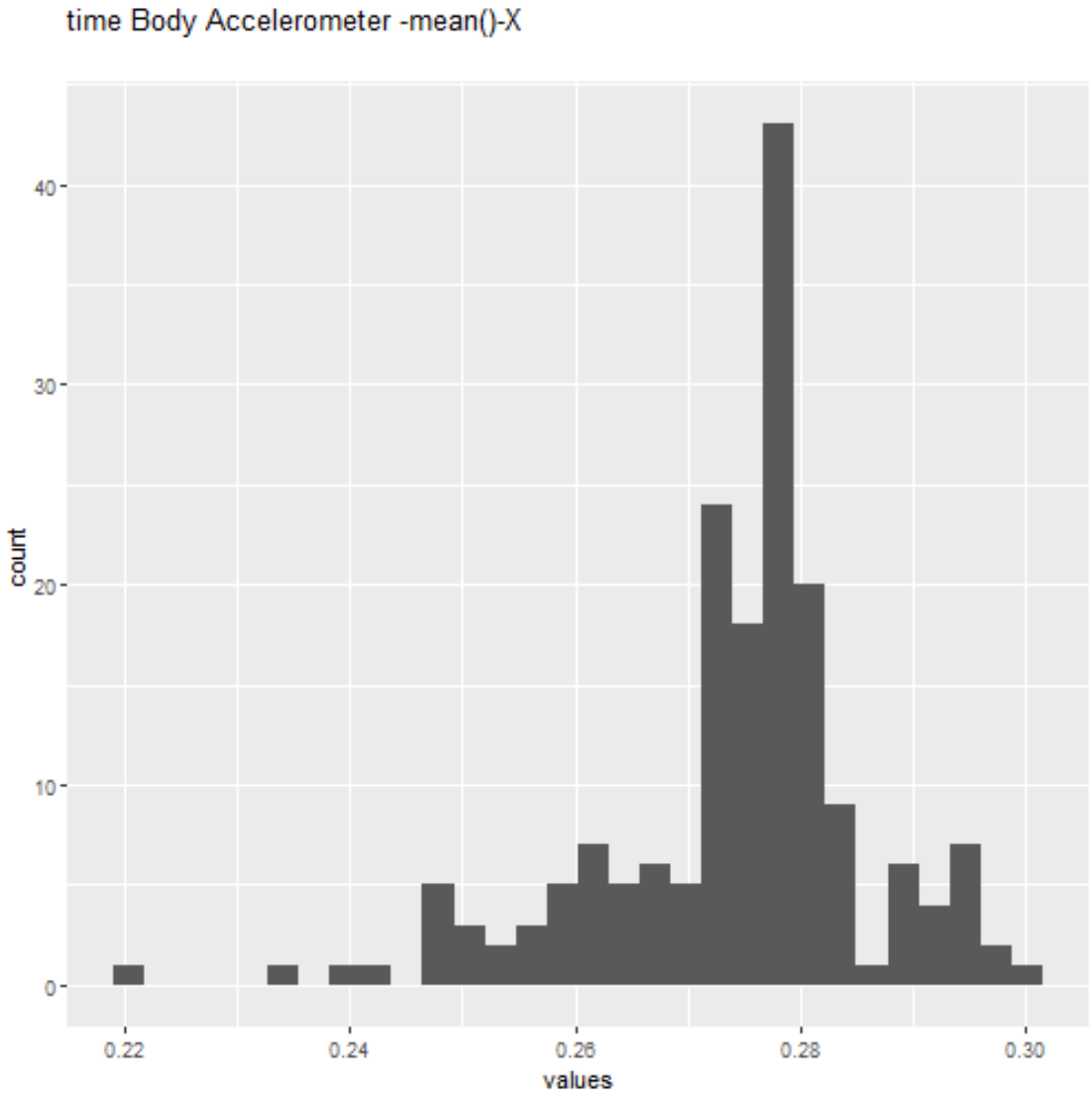
Summary statistics

na	dat a_ty	mi ssi	co mpl	n	m ea	s	p	p 2	p 5	p 7	p 1	hist

me	pe	ng	ete		n	d	0	5	0	5	0 0	
su bje ct	inte ger	0	180	1 8 0	1 5. 5	8. 6 8	1	8	1 5. 5	2 3	3 0	<U+2587><U+2587><U+2586><U+2587><U+2587><U+2586><U+2587><U+2587>

time Body Accelerometer -mean()-X

Distribution



plot of chunk distribution

0 missing values.

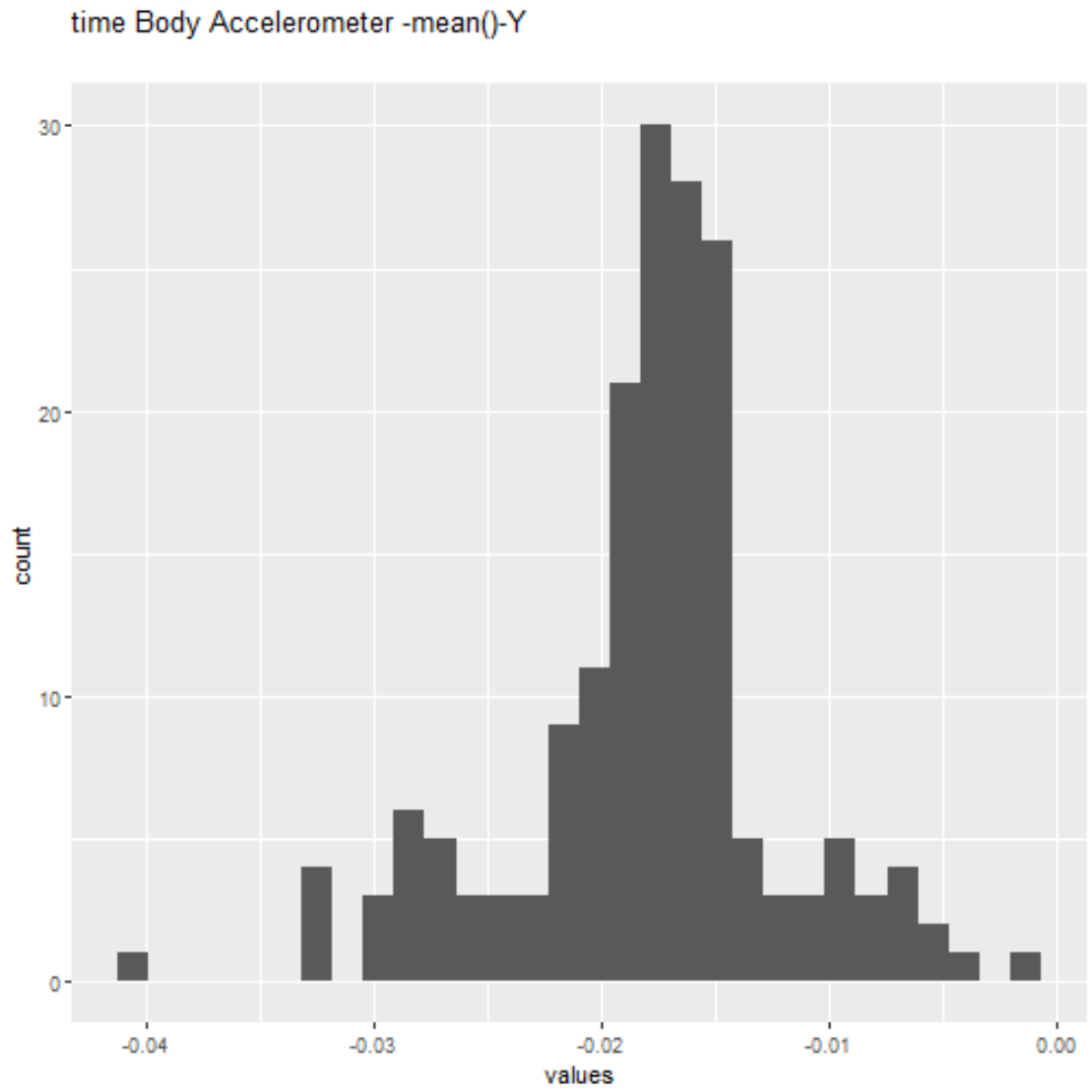
Summary statistics

name	dat	mi	co	n	m	s	p	p	p	p	p	hist

	a_type	ssing	mplete		ean	d	0	25	50	75	100	
time Body Accelerometer -mean()-X	numeric	0	180	180	0.27	0.012	0.22	0.27	0.28	0.28	0.3	<U+2581><U+2581><U+2581><U+2581><U+2582><U+2587><U+2582><U+2581>

time Body Accelerometer -mean()-Y

Distribution



plot of chunk distribution

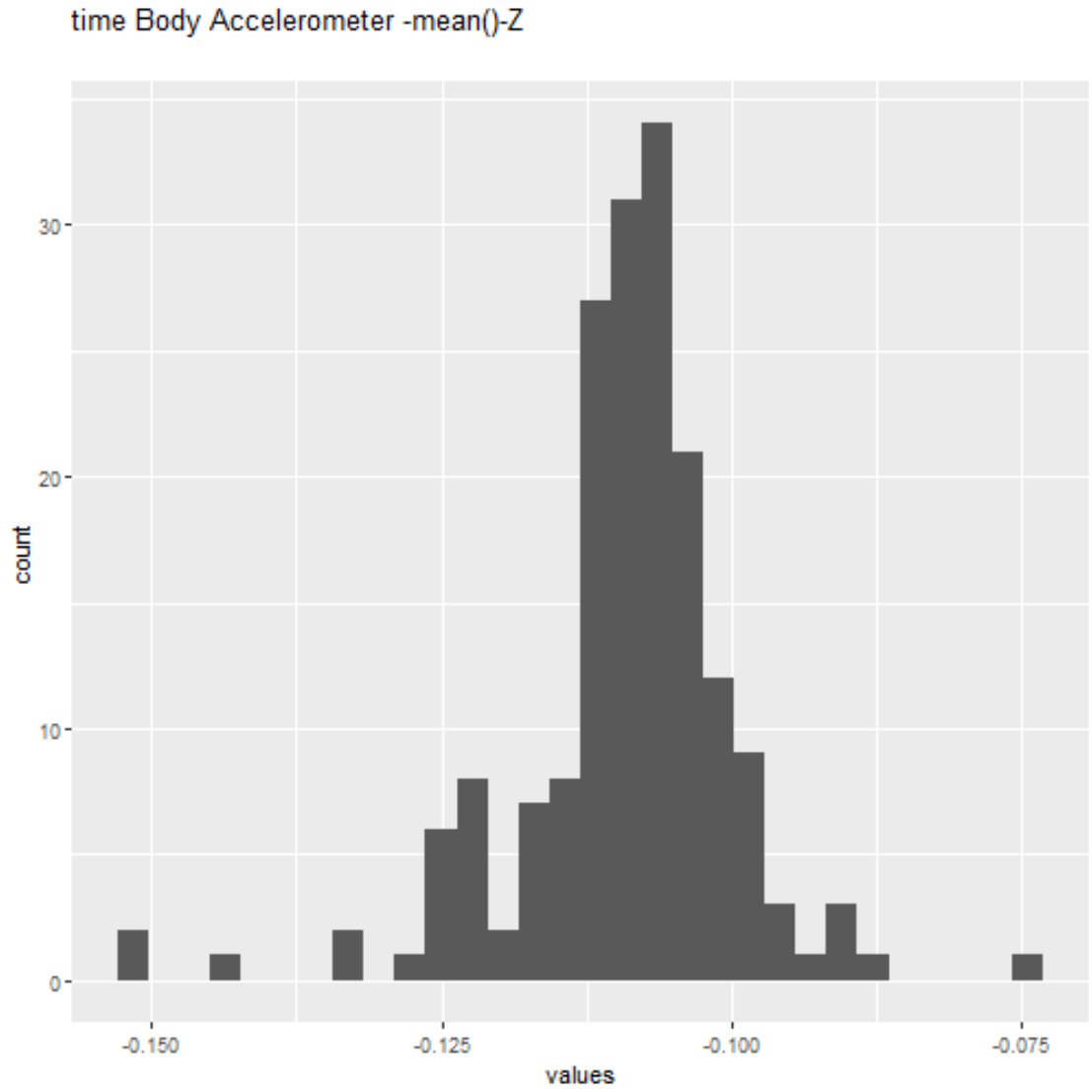
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
timeBodyAccelerometer-mean()-Y	numeric	0	1800	1800	-0.018	0.0058	-0.041	-0.020	-0.017	-0.015	-0.013	<U+2581><U+2581><U+2582><U+2582><U+2587><U+2583><U+2581><U+2581>

time Body Accelerometer -mean()-Z

Distribution



plot of chunk distribution

0 missing values.

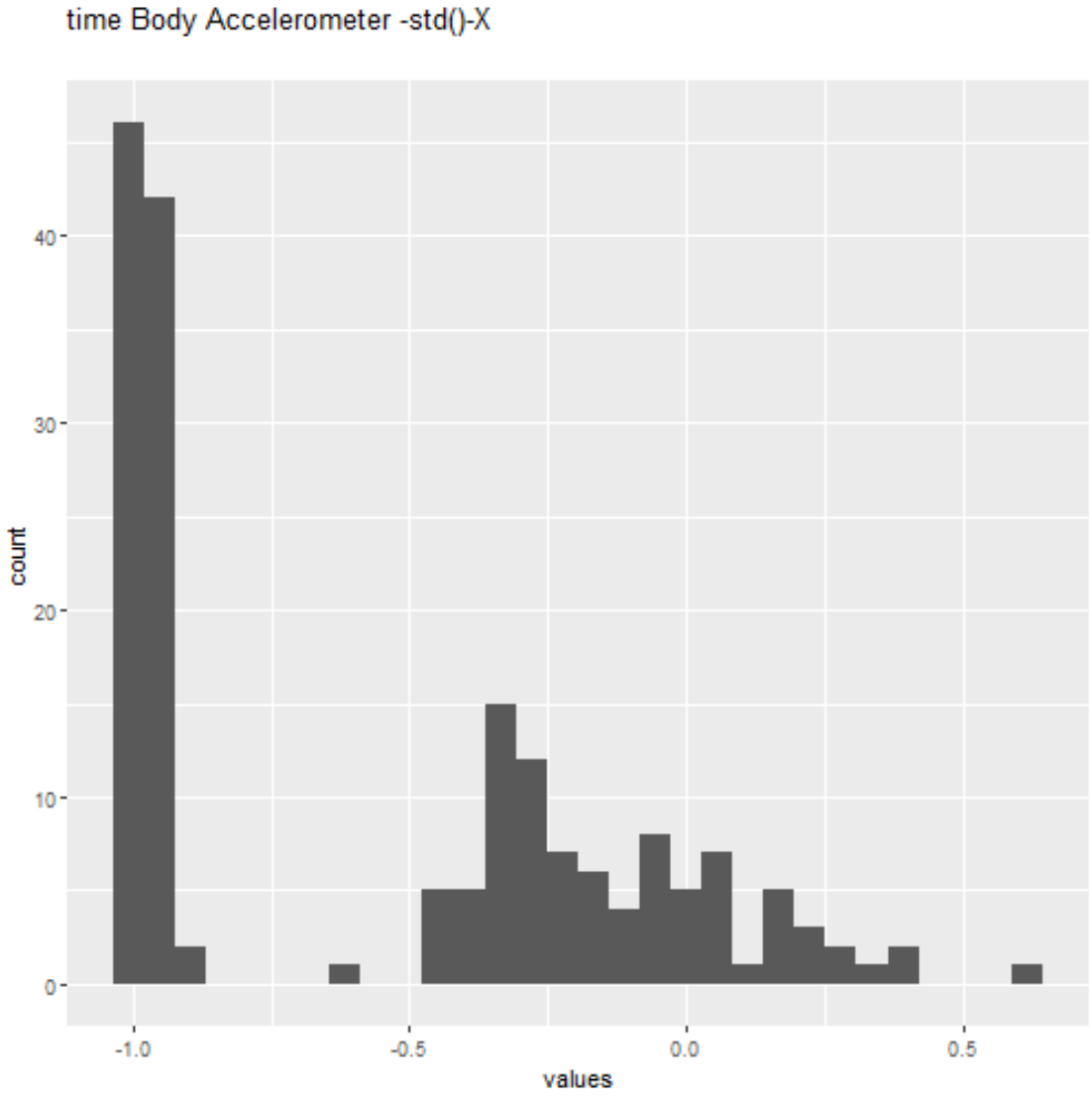
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body Accel	numeric	0	180	180	-0.10	0.01	-0.15	-0.11	-0.10	-0.09	-0.07	<U+2581><U+2581><U+2581><U+2582><U+2587><U+2583><U+2581><U+2581>

erom eter - mean ()-Z				1		1 5	1 1	1 1	1	7 5	

time Body Accelerometer -std()-X

Distribution



plot of chunk distribution

0 missing values.

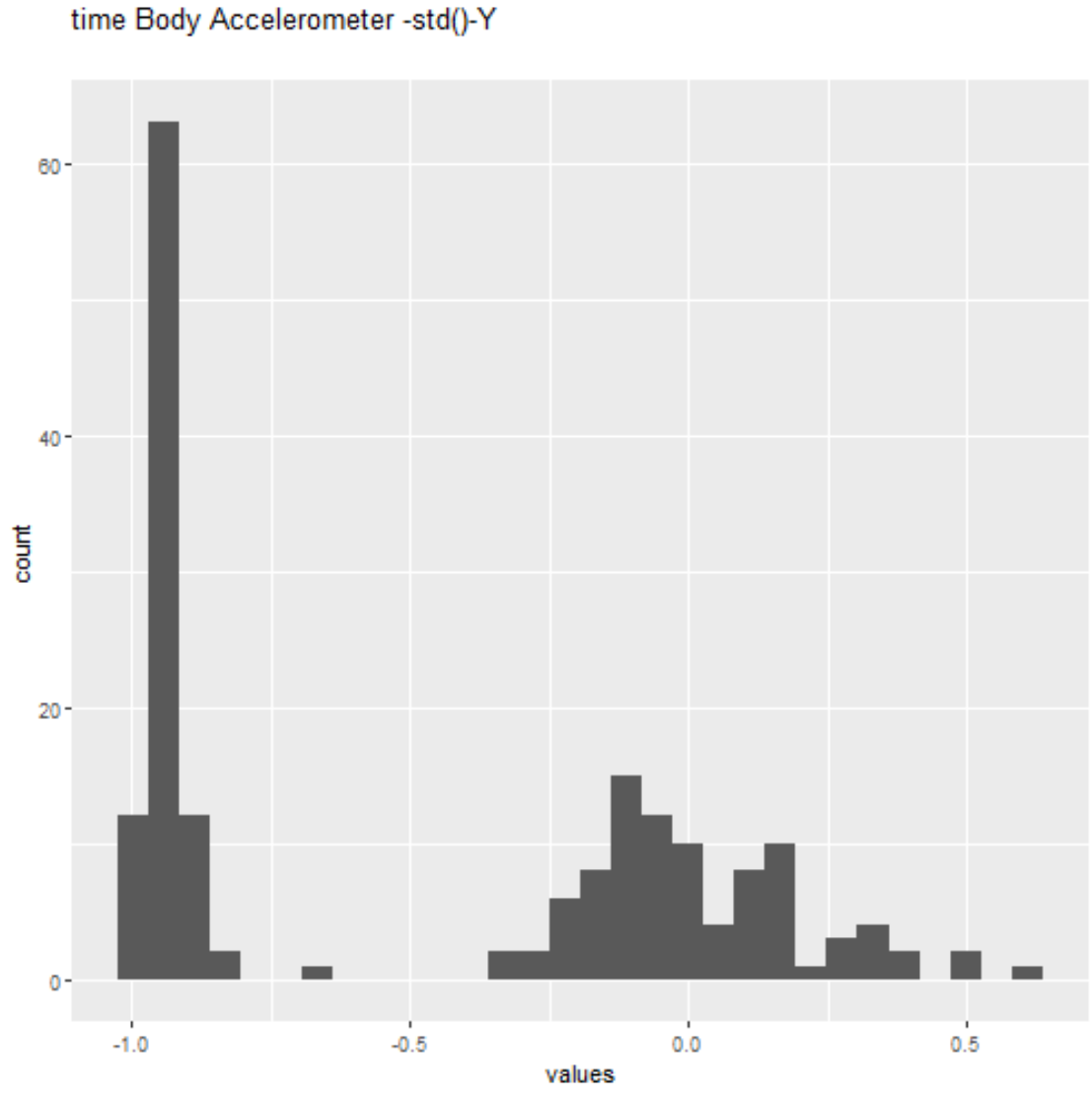
Summary statistics

name	dat a_t ype	mi ssi ng	co mp lete	n	m e a	s d	p 0	p 2 5	p 5 0	p 7 5	p 1 0	hist

					n					0		
time Body Accelerometer -std()-X	numeric	0	180	180	-0.56	0.45	-1	-0.98	-0.75	-0.2	0.63	<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581>

time Body Accelerometer -std()-Y

Distribution



plot of chunk distribution

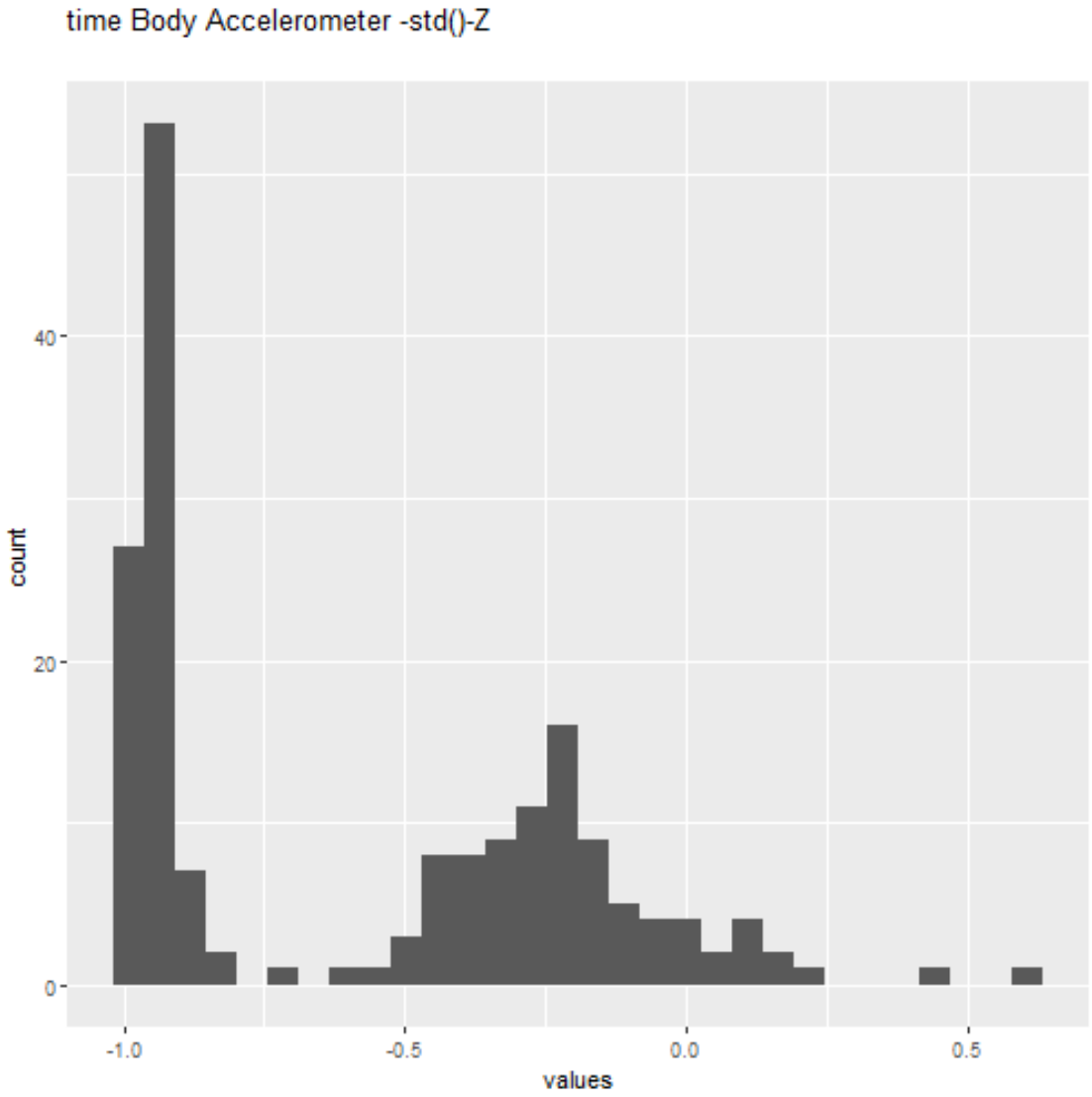
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
timeBodyAccelerometer-std()-Y	numeric	0	180	180	-0.46	0.5	-0.99	-0.94	-0.51	-0.031	0.62	<U+2587><U+2581><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581>

time Body Accelerometer -std()-Z

Distribution



plot of chunk distribution

0 missing values.

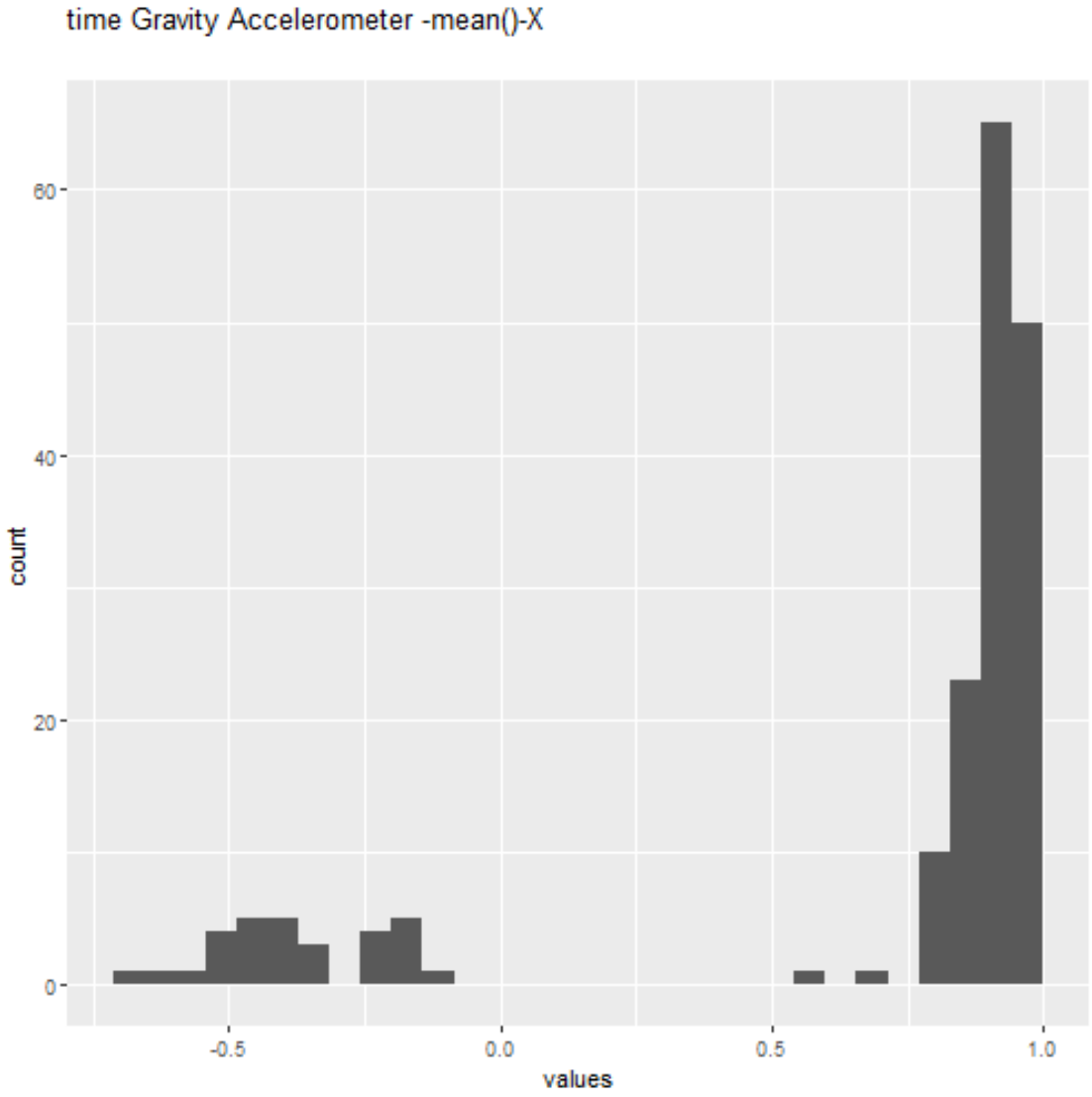
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body Accel	numeric	0	180	180	-0.5	0.4	-0.9	-0.9	-0.6	-0.2	0.61	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

erom eter - std()- Z			8		9	5	5	3			

time Gravity Accelerometer -mean()-X

Distribution



plot of chunk distribution

0 missing values.

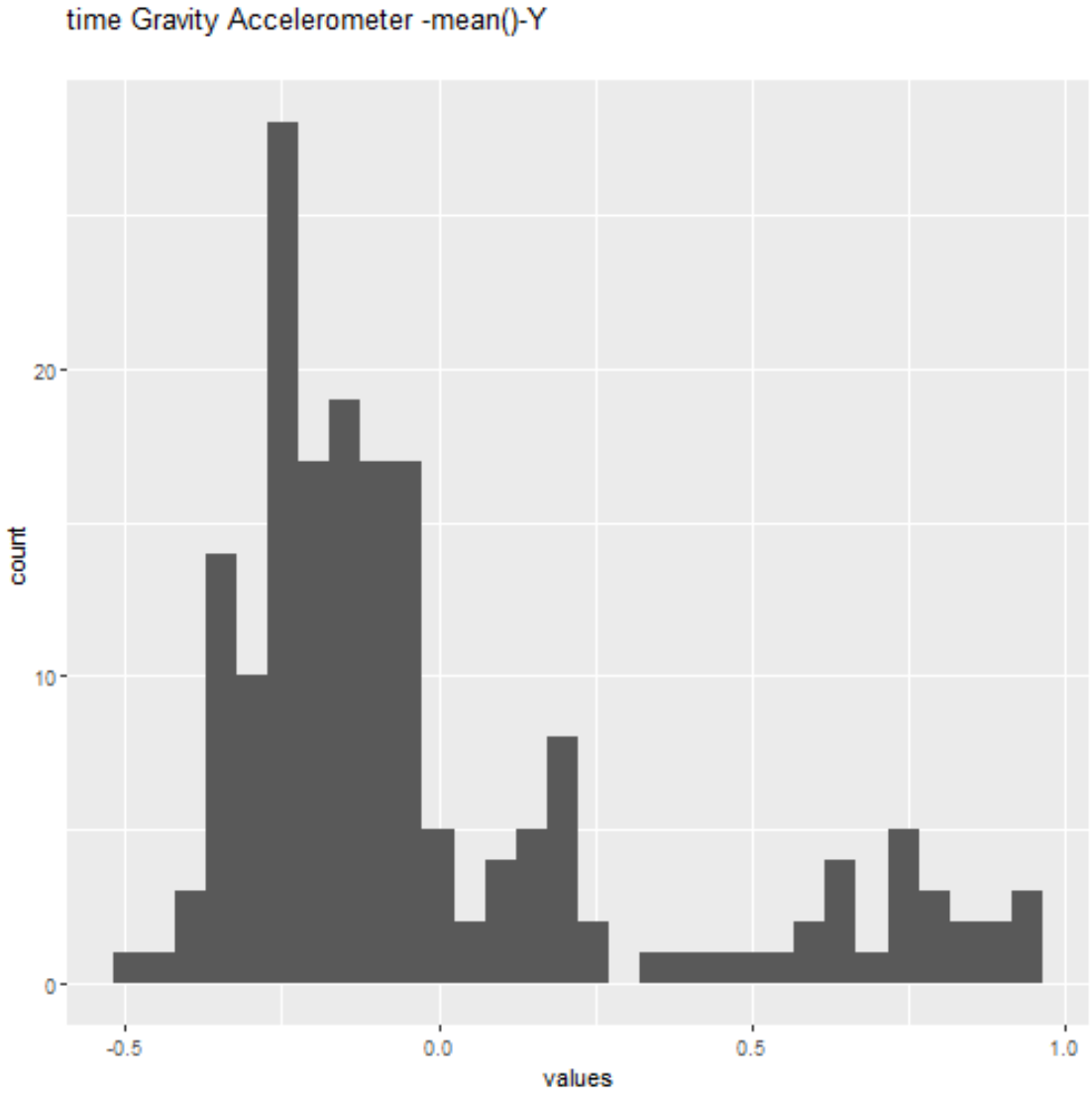
Summary statistics

name	dat a_t ype	mi ssi ng	co mp lete	n	m e a	s d	p 0	p 2 5	p 5 0	p 7 5	p 1 0	hist

					n					0		
time Gravity Accelerometer -mean()-X	numeric	0	180	180	0.7	0.49	-0.68	0.84	0.92	0.94	0.97	<U+2581><U+2581><U+2581><U+2581><U+2581><U+2581><U+2581><U+2587>

time Gravity Accelerometer -mean()-Y

Distribution



plot of chunk distribution

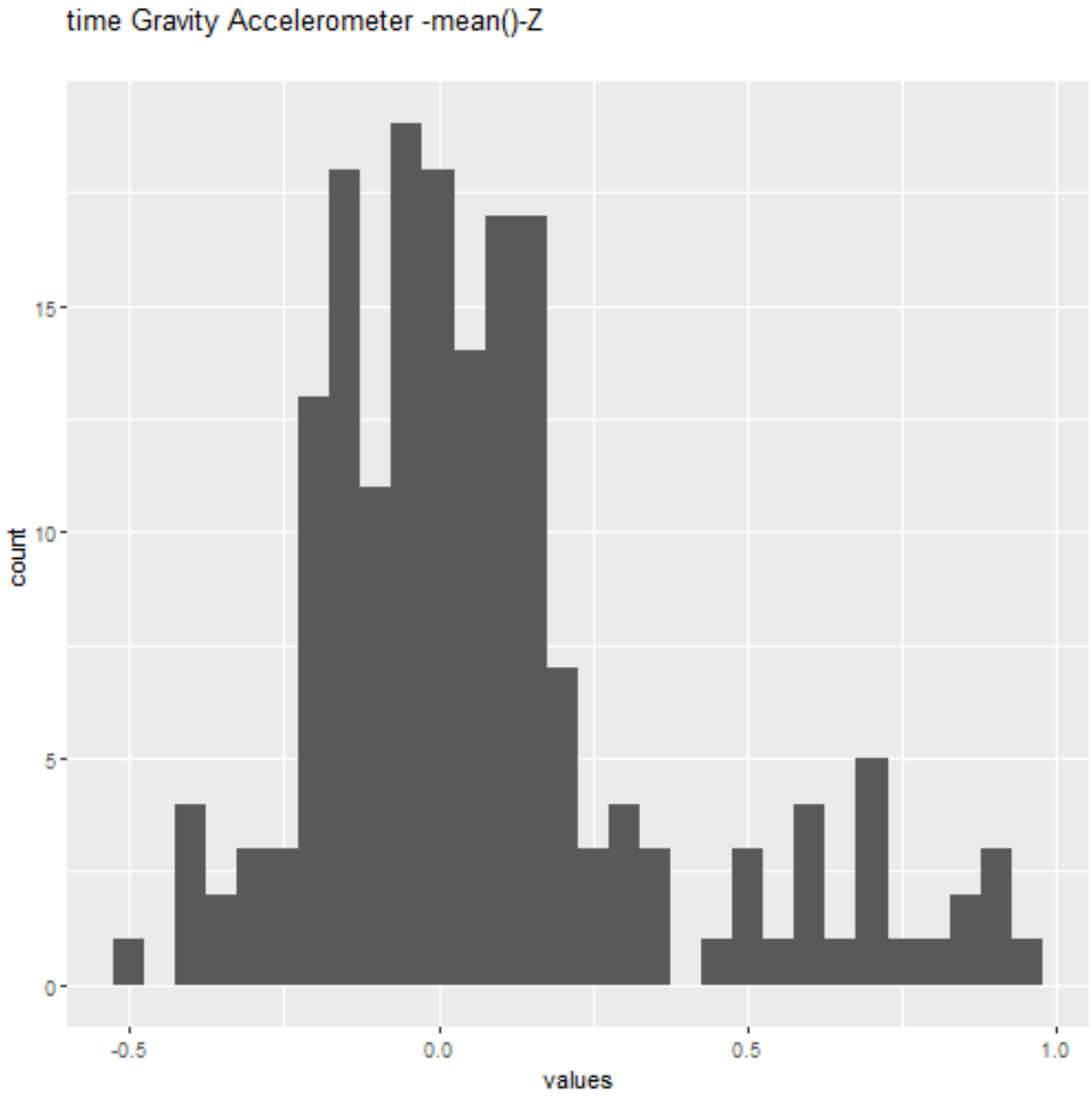
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
timeGravity	numeric	0	180	180	-0.016	0.35	-0.48	-0.23	-0.13	0.088	0.96	<U+2582><U+2587><U+2585><U+2582><U+2581><U+2581><U+2581><U+2581>
Accelerometer - mean()-Y												

time Gravity Accelerometer -mean()-Z

Distribution



plot of chunk distribution

0 missing values.

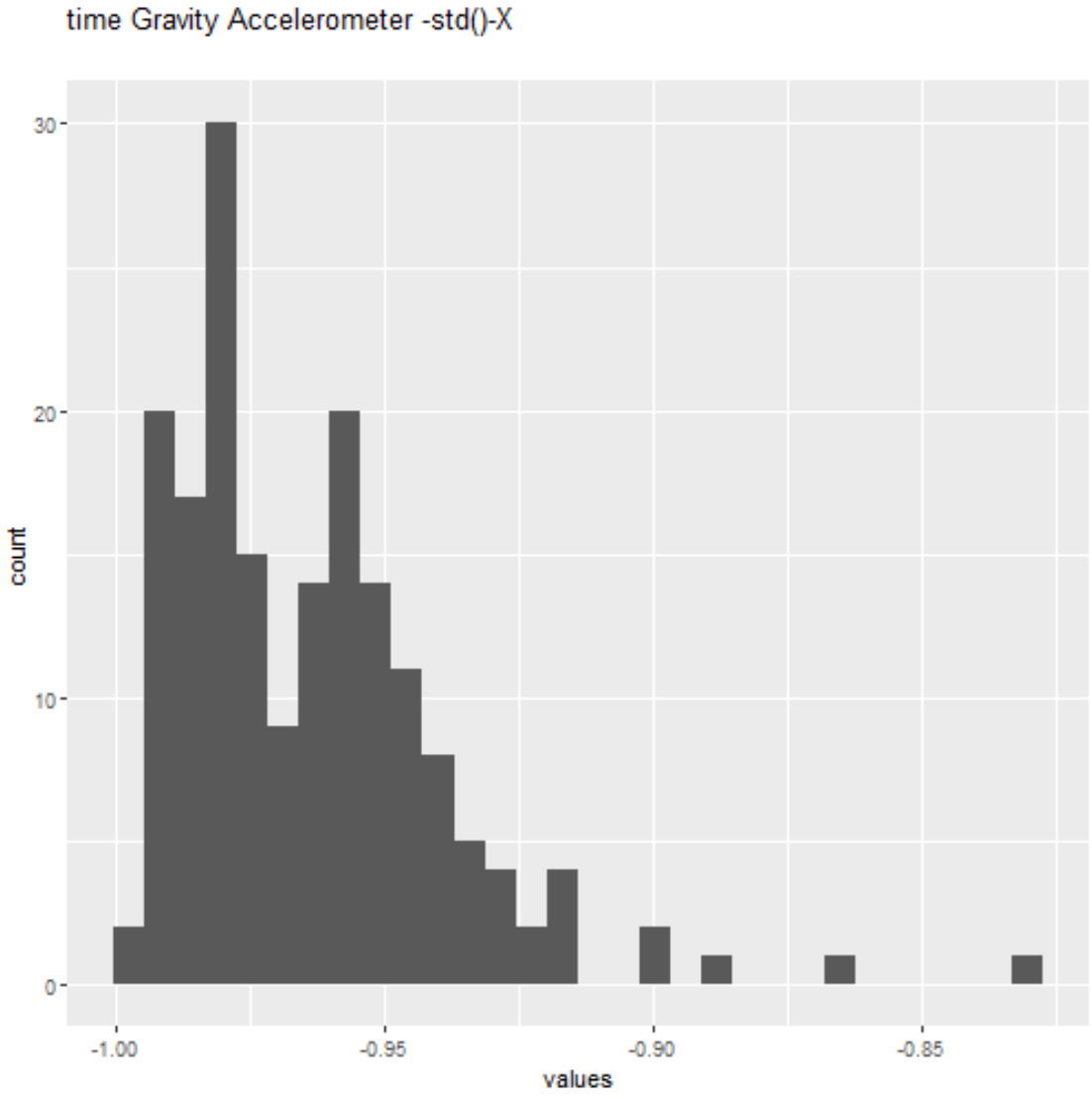
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Gravity	numeric	0	180	180	0.07	0.2	-0.1	-0.0	0.02	0.1	0.96	<U+2581><U+2585><U+2587><U+2586><U+2581><U+2581><U+2581><U+2581>

Accelerometer - mean()-Z			4	9	5	1 2	4	5			

time Gravity Accelerometer -std()-X

Distribution



plot of chunk distribution

0 missing values.

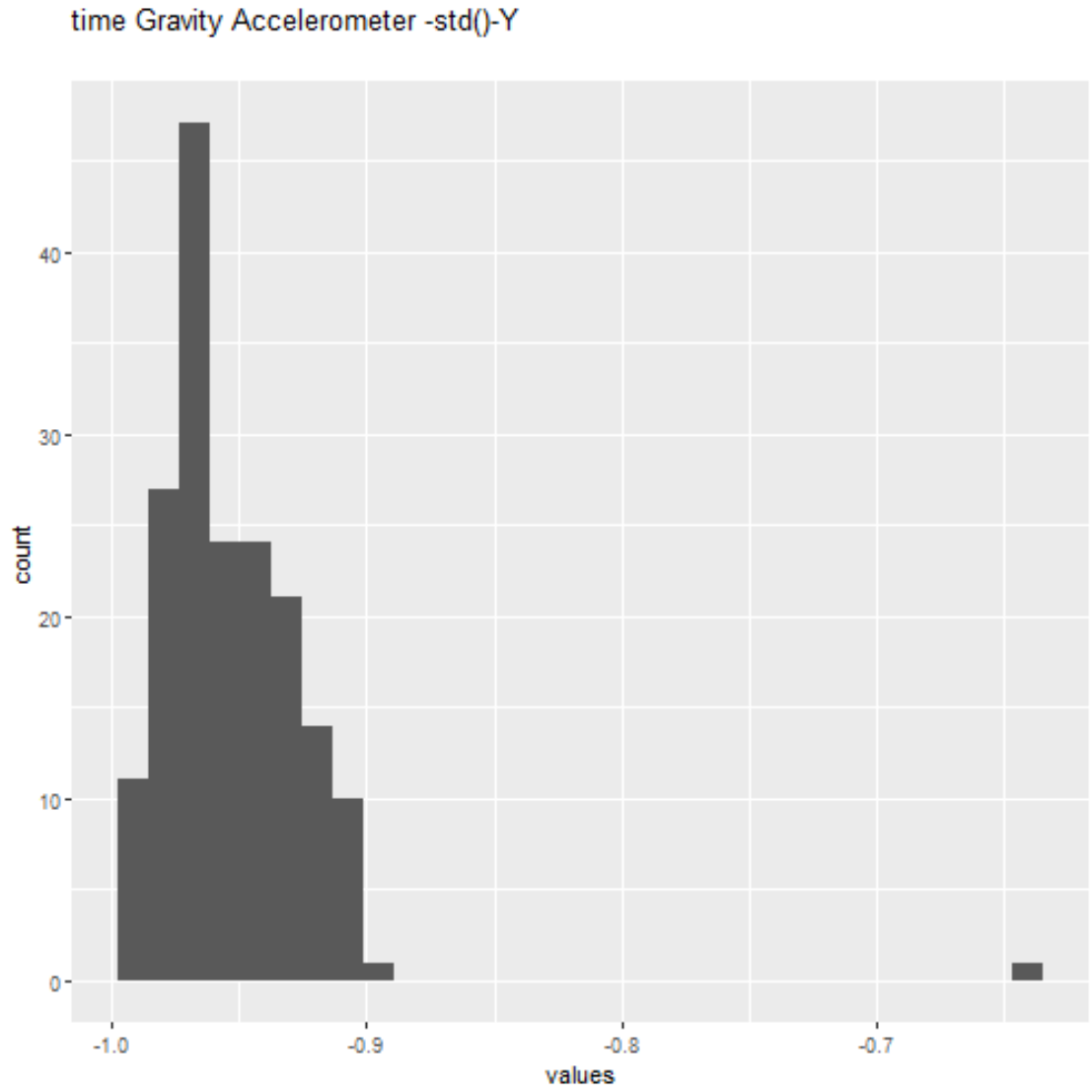
Summary statistics

name	data_t	missi	comp	n	me	sd	p0	p2	p5	p7	p1	hist

	ype	ng	lete		a n		5	0	5	0 0	
time Gravity Accelerometer -std()-X	numeric	0	1800	1800	-0.96	0.025	-1	-0.998	-0.97	-0.95	-0.83	<U+2587><U+2586><U+2585><U+2582><U+2581><U+2581><U+2581><U+2581>

time Gravity Accelerometer -std()-Y

Distribution



plot of chunk distribution

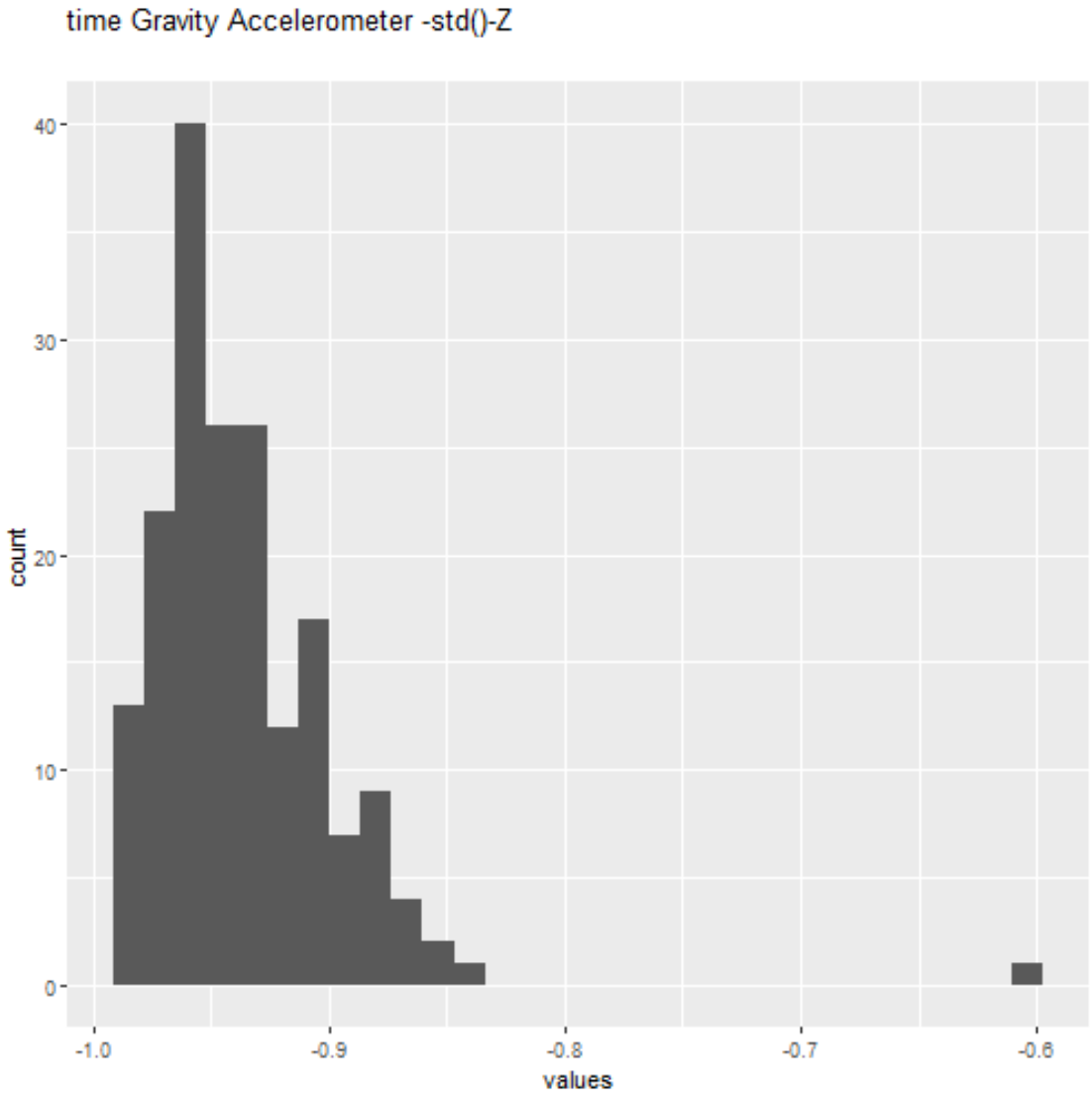
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
timeGravity Accelerometer - std()-Y	numeric	0	180	180	-0.95	0.03	-0.99	-0.97	-0.96	-0.94	-0.64	<U+2587><U+2585><U+2581><U+2581><U+2581><U+2581><U+2581><U+2581>

time Gravity Accelerometer -std()-Z

Distribution



plot of chunk distribution

0 missing values.

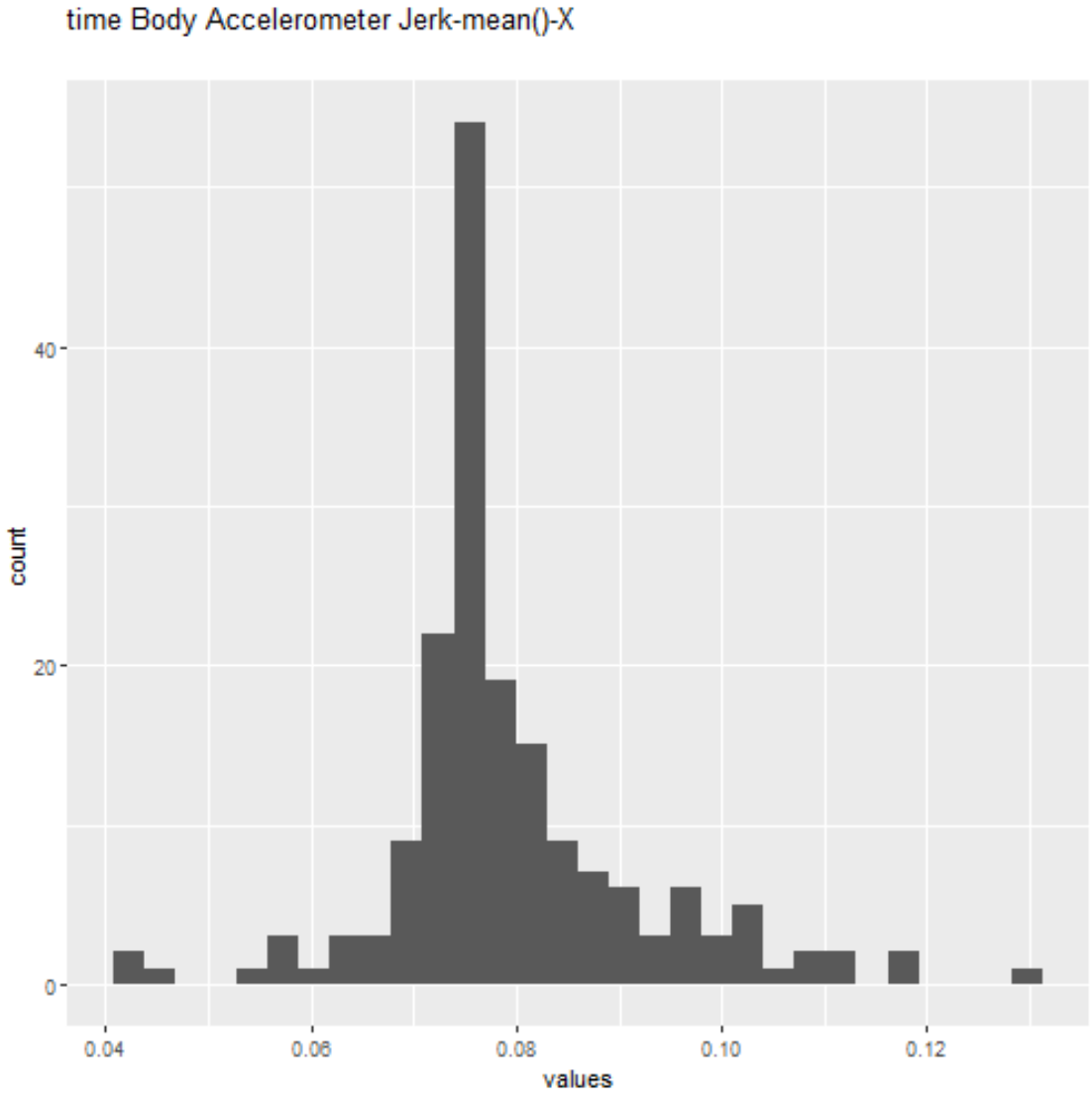
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Gravity	numeric	0	180	180	-0.90	0.0	-1	-0.9	-0.9	-0.8	-0.6	<U+2587><U+2586><U+2582><U+2581><U+2581><U+2581><U+2581><U+2581>

Accelerometer - std()-Z			4	4	9 9	9 6	9 5	9 2	1		

time Body Accelerometer Jerk-mean()-X

Distribution



plot of chunk distribution

0 missing values.

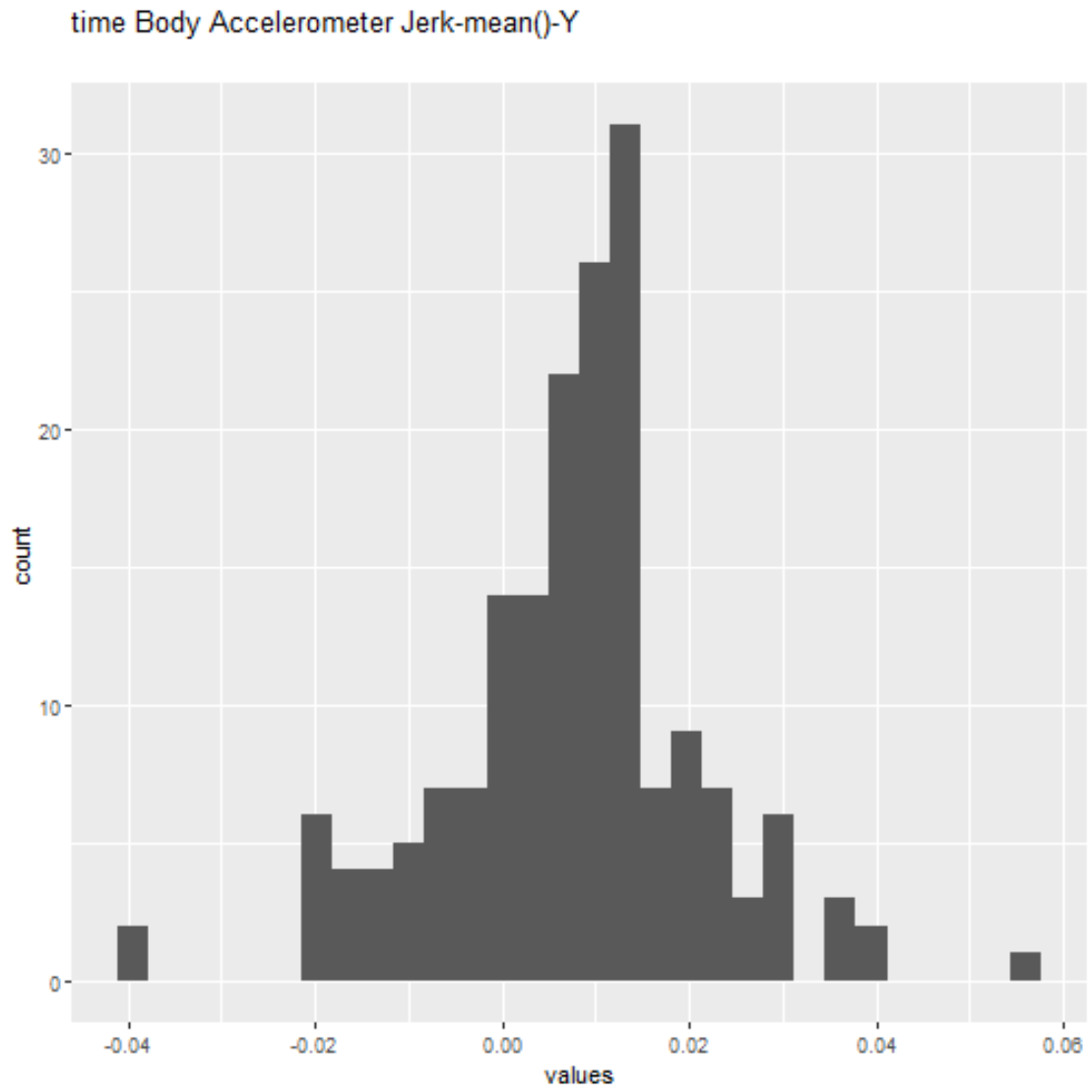
Summary statistics

name	data_t	missi	comp	n	me	sd	p0	p2	p5	p7	p1	hist

	ype	ng	let e		a n			5	0	5	0 0	
time Body Accel erom eter Jerk- mean ()-X	nu me ric	0	18 0	1 8 0	0. 0 7 9	0. 0 1 3	0. 0 4 3	0. 0 7 4	0. 0 7 6	0. 0 8 3	0. 1 3	<U+2581><U+2581><U+2587><U+2587><U+2582><U+2581><U+2581><U+2581>

time Body Accelerometer Jerk-mean()-Y

Distribution



plot of chunk distribution

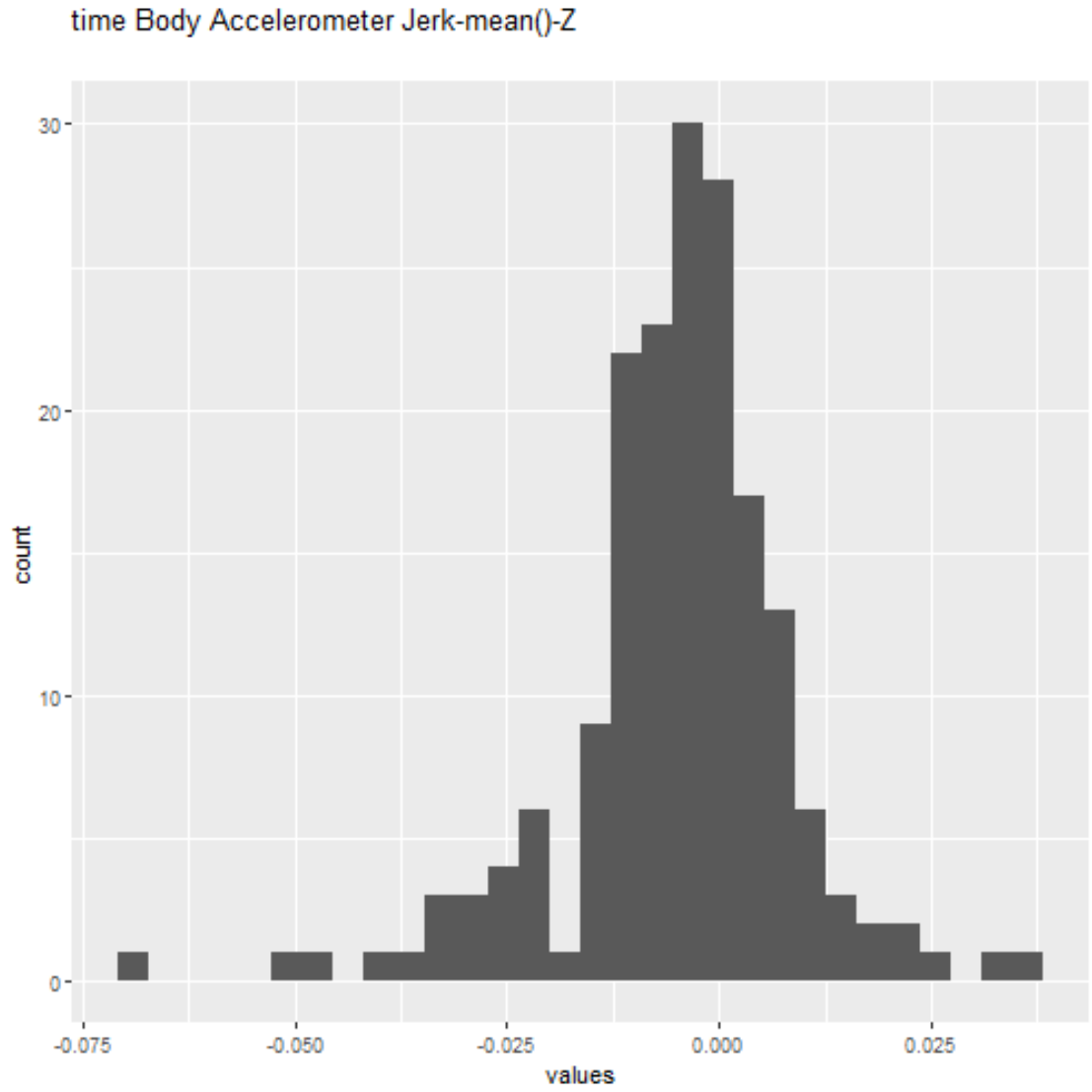
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
timeBodyAccelerometer-Jerk-mean()-Y	numeric	0	1800	1800	0.00076	0.014	-0.039	0.00047	0.00095	0.013	0.057	<U+2581><U+2581><U+2582><U+2586><U+2587><U+2582><U+2581><U+2581>

time Body Accelerometer Jerk-mean()-Z

Distribution



plot of chunk distribution

0 missing values.

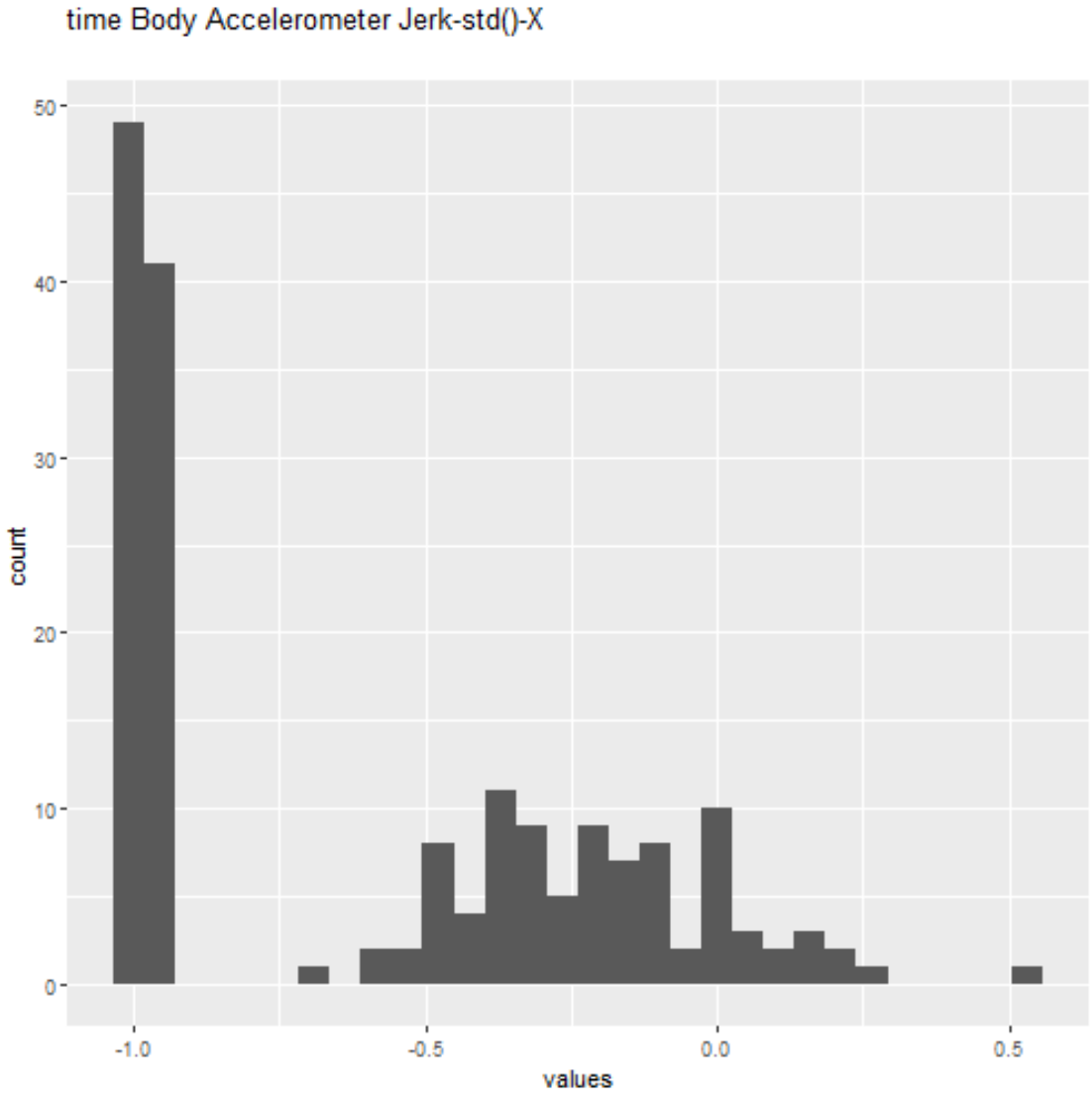
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body Accel	numeric	0	1800	1800	-0.00	0.01	-0.09	-0.00	-0.00	0.00	0.03	<U+2581><U+2581><U+2581><U+2587><U+2586><U+2581><U+2581>

erom eter Jerk- mean ()-Z			0 5	3	6 7	1 1	39	2	8		

time Body Accelerometer Jerk-std()-X

Distribution



plot of chunk distribution

0 missing values.

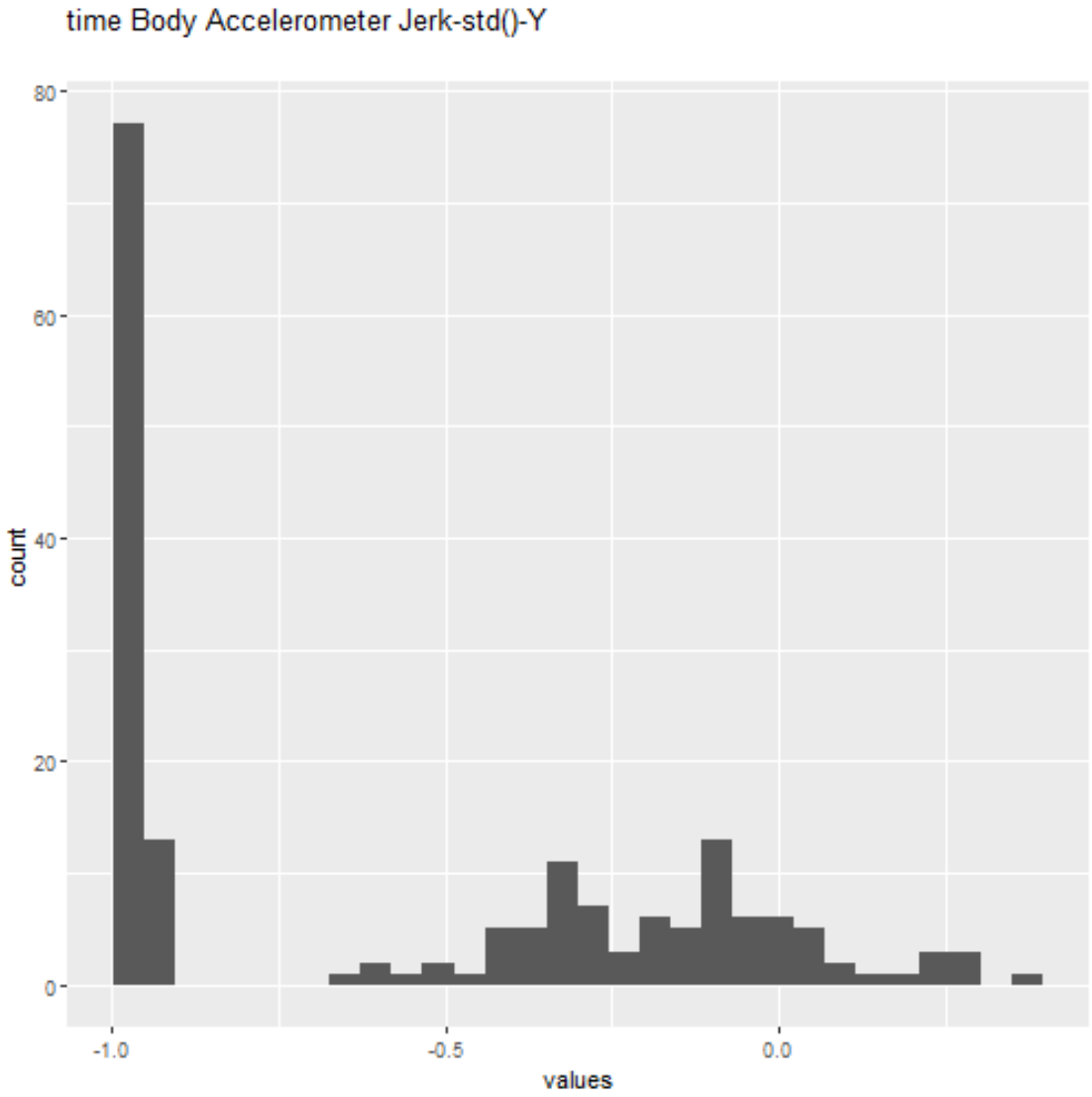
Summary statistics

name	dat a_t	mi ssi	co mp	n	m e	s d	p 0	p 2	p 5	p 7	p 1	hist

	ype	ng	lete		a n			5	0	5	0 0	
time Body Accelerometer Jerk-std()-X	nu me ric	0	18 0	1 8 0	- 0. 5 9	0 . 4 2	- . 9 9	- . 9 8	- . 8 1	- . 2 2	0. 5 4	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>

time Body Accelerometer Jerk-std()-Y

Distribution



plot of chunk distribution

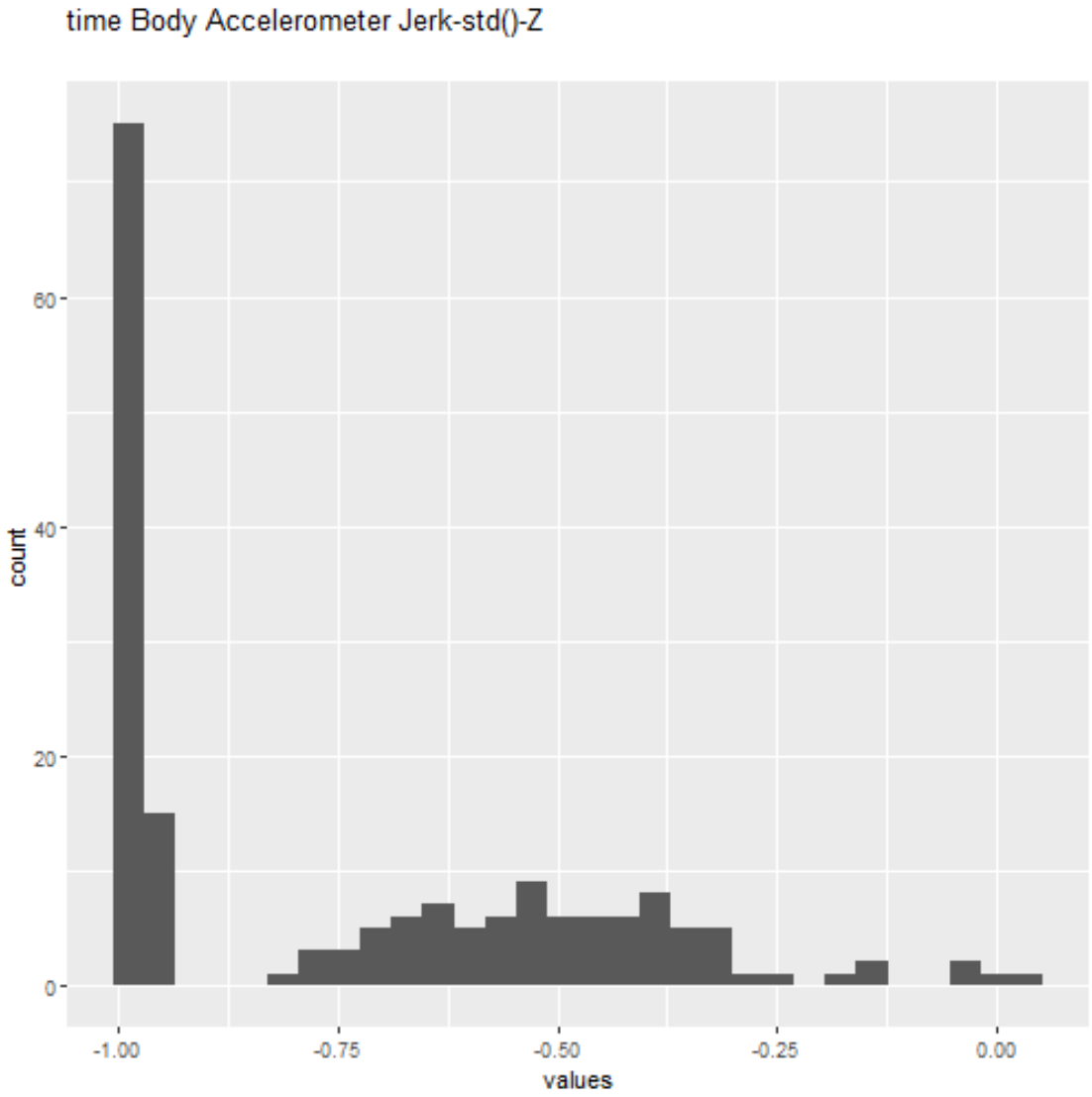
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
timeBodyAccelerometer Jerk-std()-Y	numeric	0	1800	1800	-0.57	0.43	-0.99	-0.97	-0.78	-0.15	0.36	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>

time Body Accelerometer Jerk-std()-Z

Distribution



plot of chunk distribution

0 missing values.

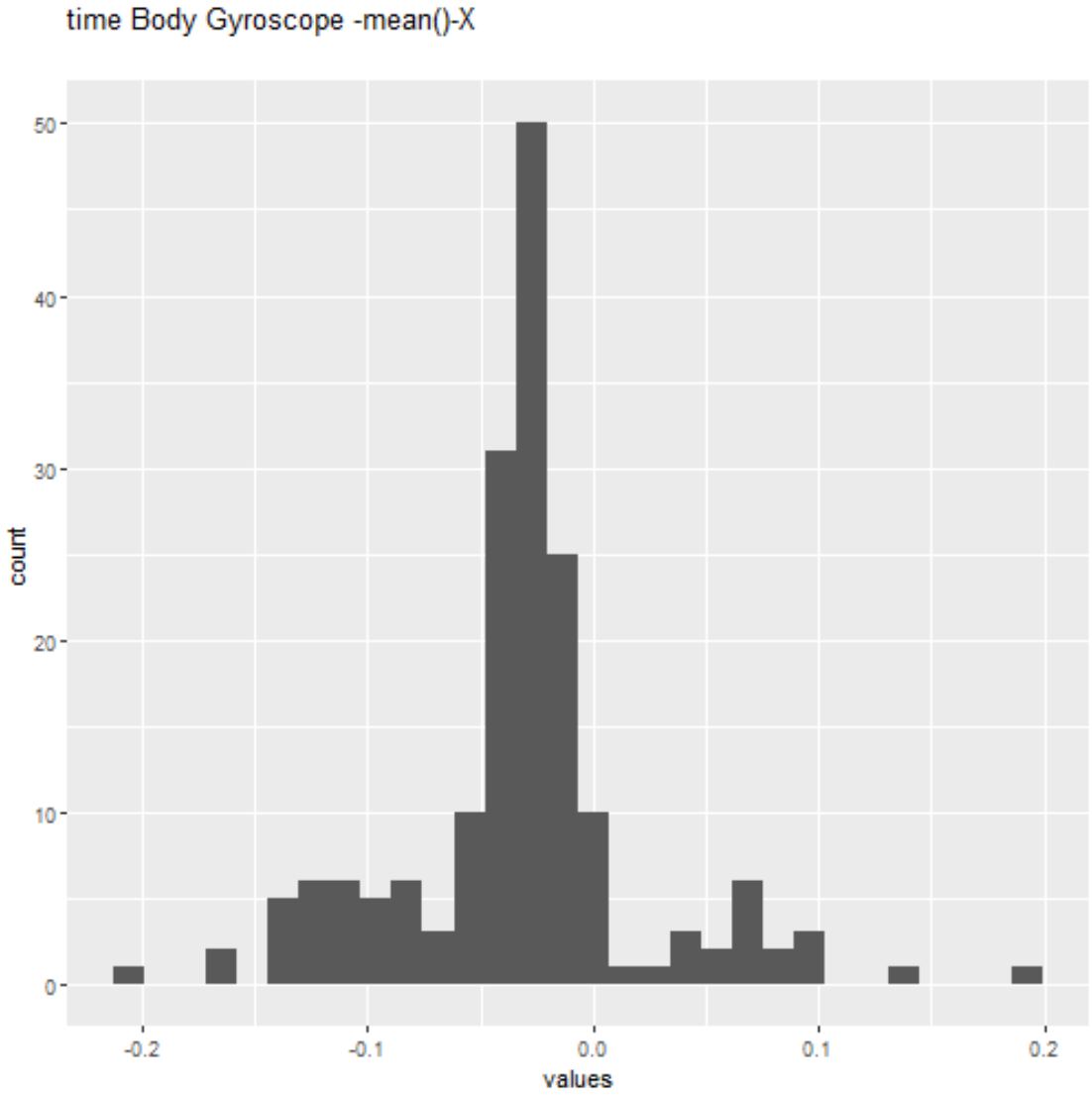
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body Accel	numeric	0	180	180	-0.07	0.2	.	.	.	.	0.3	<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>

erom eter Jerk-std()-Z				4	8	9 9	9 8	8 8	5 1	1		

time Body Gyroscope -mean()-X

Distribution



plot of chunk distribution

0 missing values.

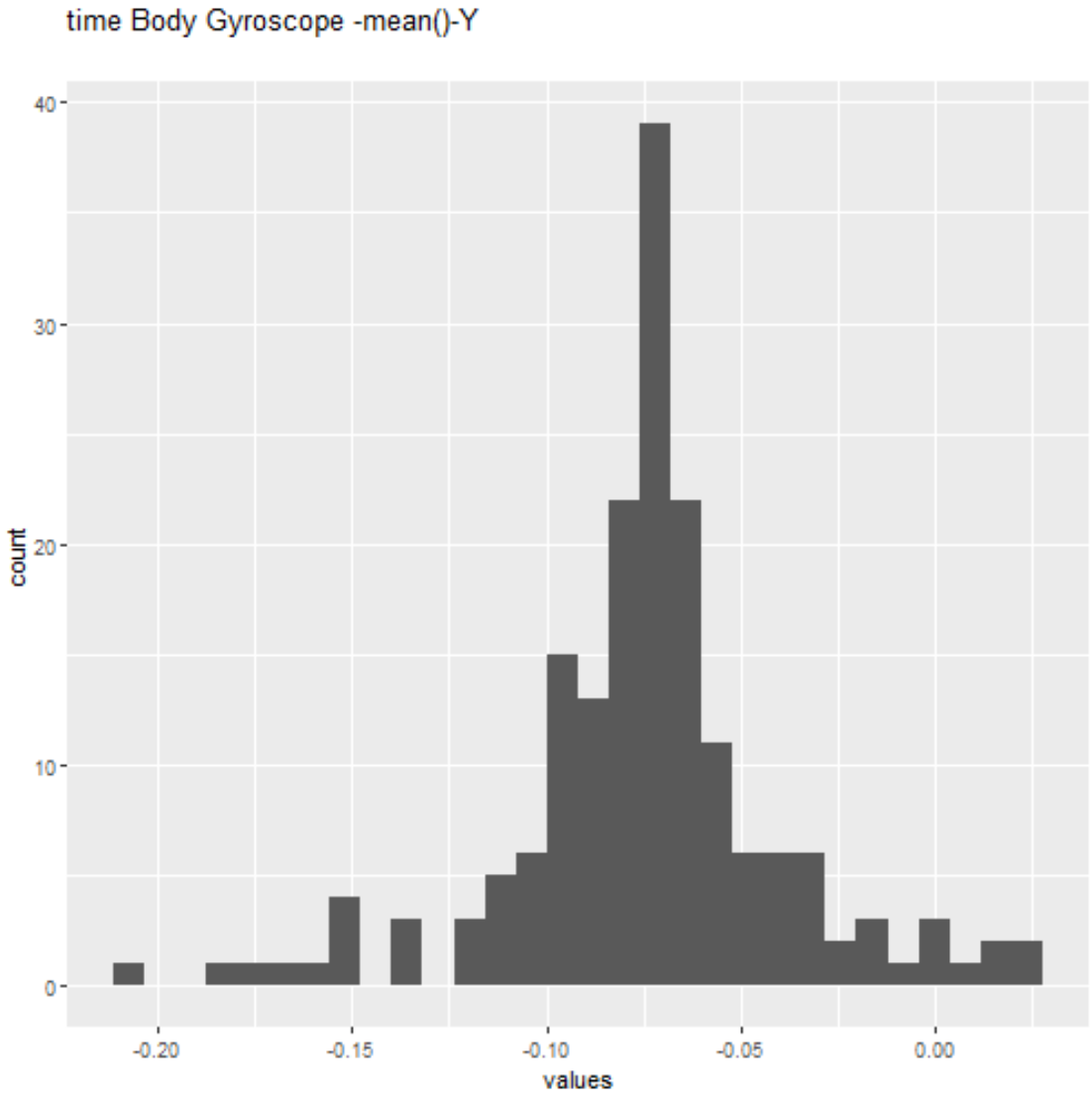
Summary statistics

name	data_t	missing	comp	n	mean	sd	p0	p25	p50	p75	p100	hist

	ype	ng	lete		an			5	0	5	00	
time Body Gyroscope-mean()-X	numeric	0	1800	180	-0.0032	0.054	-0.21	-0.047	-0.029	-0.017	0.19	<U+2581><U+2581><U+2582><U+2587><U+2581><U+2581><U+2581><U+2581>

time Body Gyroscope -mean()-Y

Distribution



plot of chunk distribution

0 missing values.

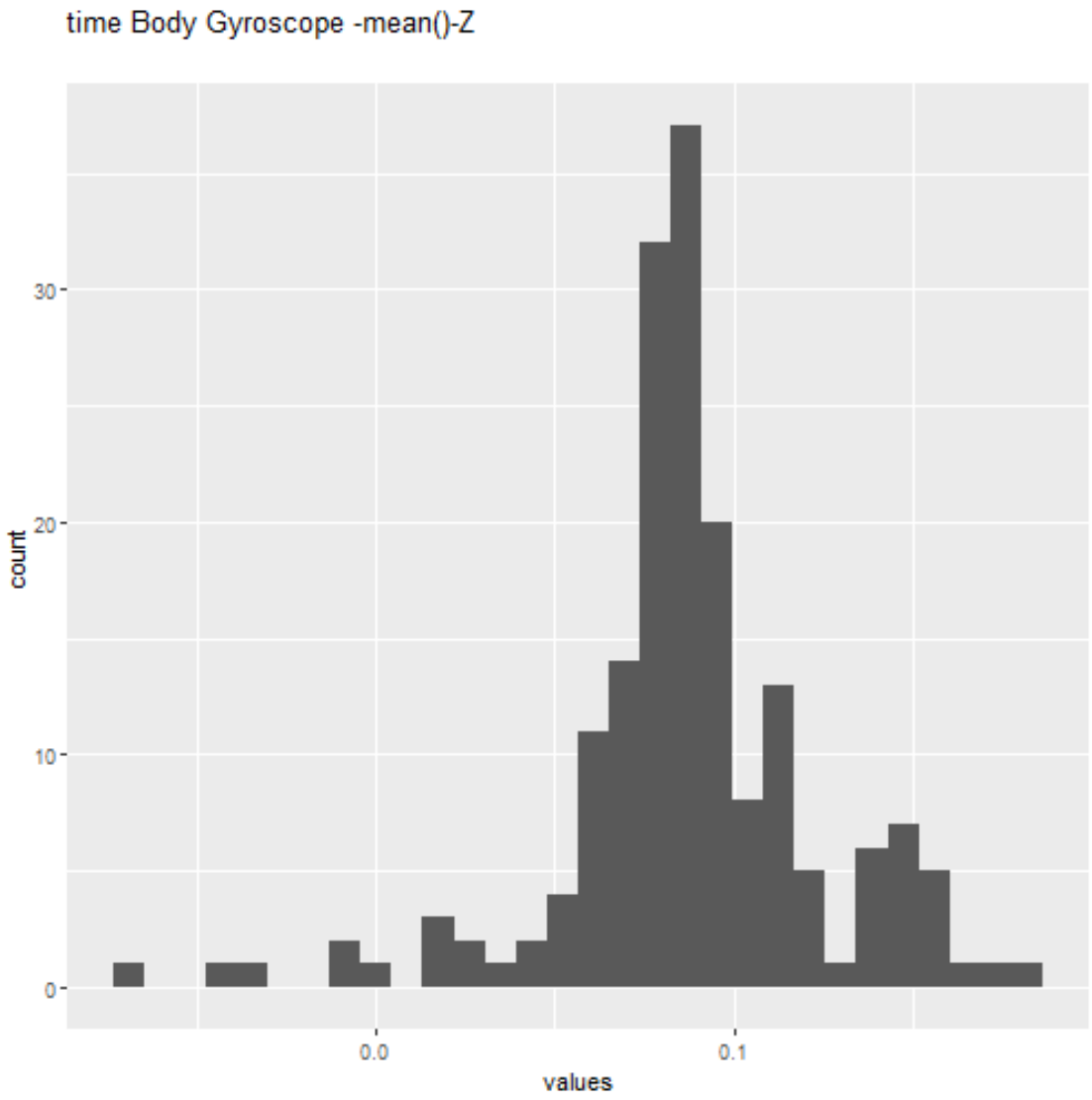
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body	numeric	0	180	180	-0.03	0.03	-0.06	-0.04	-0.03	-0.02	0.02	<U+2581><U+2581><U+2581><U+2583><U+2587><U+2582><U+2581><U+2581>

y	7	6	2	9	7	6	7
Gyroscope-mean()-Y	4				3	1	

time Body Gyroscope -mean()-Z

Distribution



plot of chunk distribution

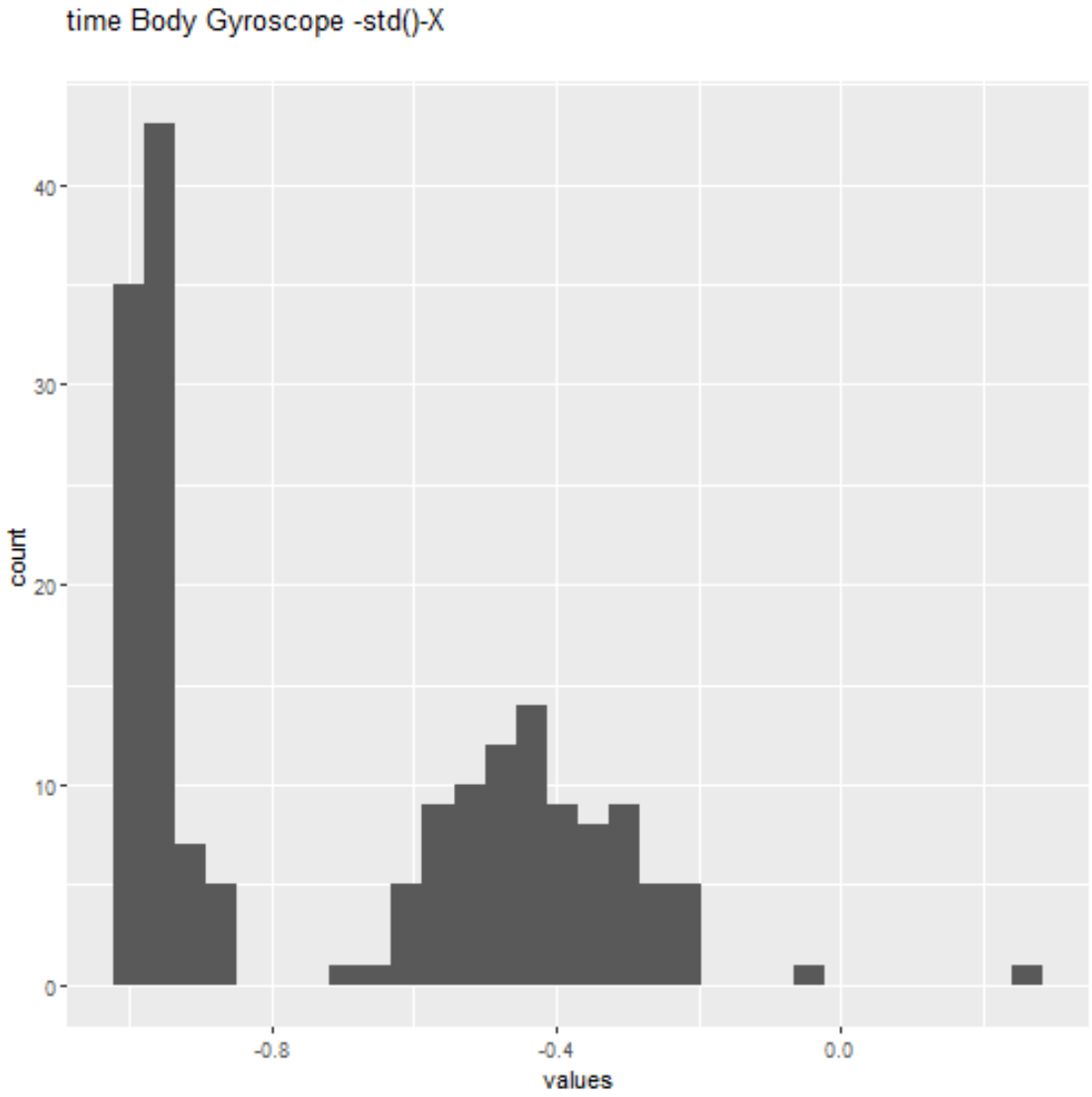
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time	numeric	0	180	180	0.087	0.036	-0.072	0.075	0.085	0.1	0.18	<U+2581><U+2581><U+2581><U+2581><U+2587><U+2587><U+2582><U+2581>
BodyGyroscope-mean()-Z												

time Body Gyroscope -std()-X

Distribution



plot of chunk distribution

0 missing values.

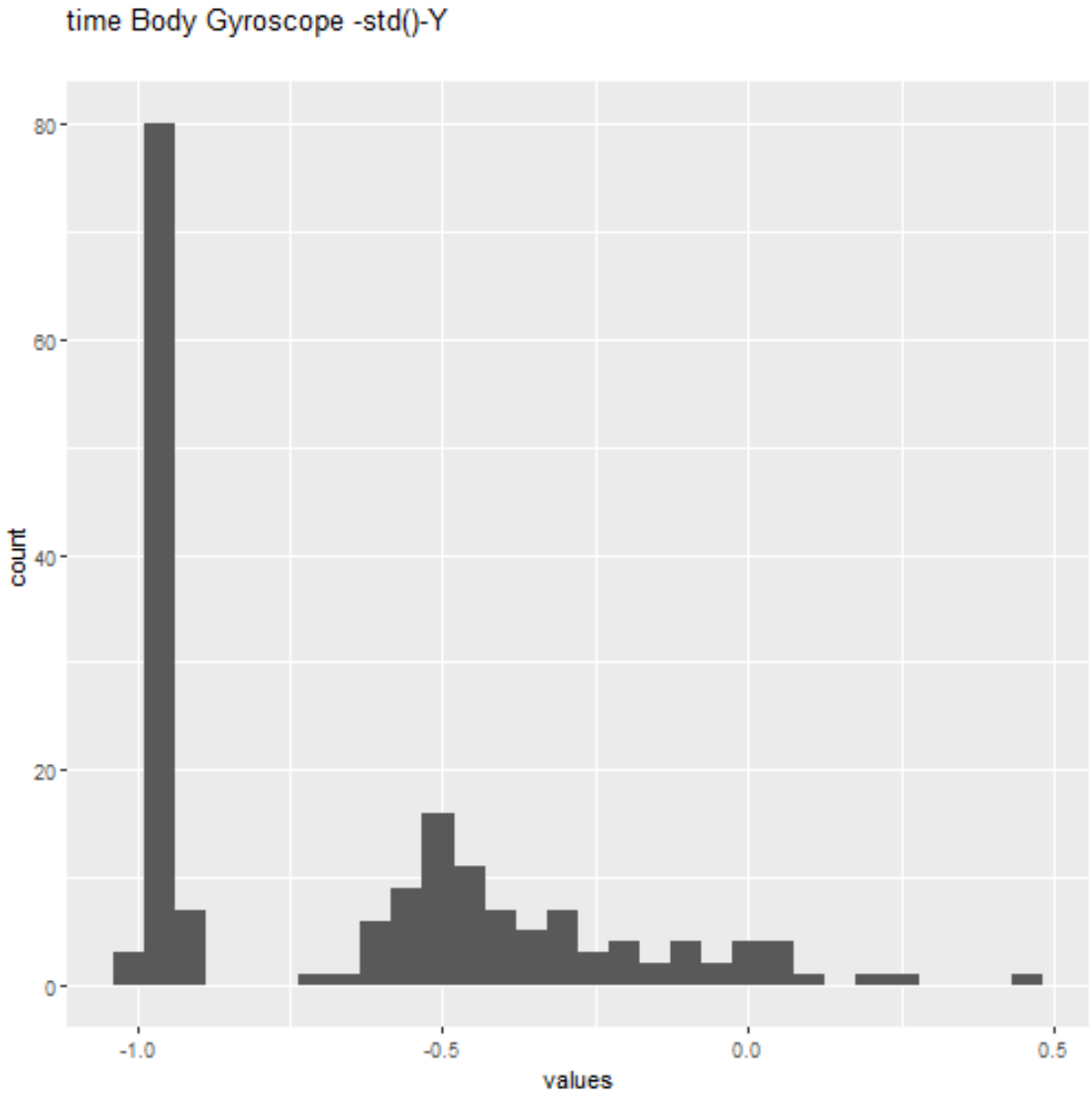
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body	numeric	0	180	180	-0.6	0.29	-0.9	-0.9	-0.7	-0.4	0.27	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

y Gyroscope -std()-X	9	9	7	9	4

time Body Gyroscope -std()-Y

Distribution



plot of chunk distribution

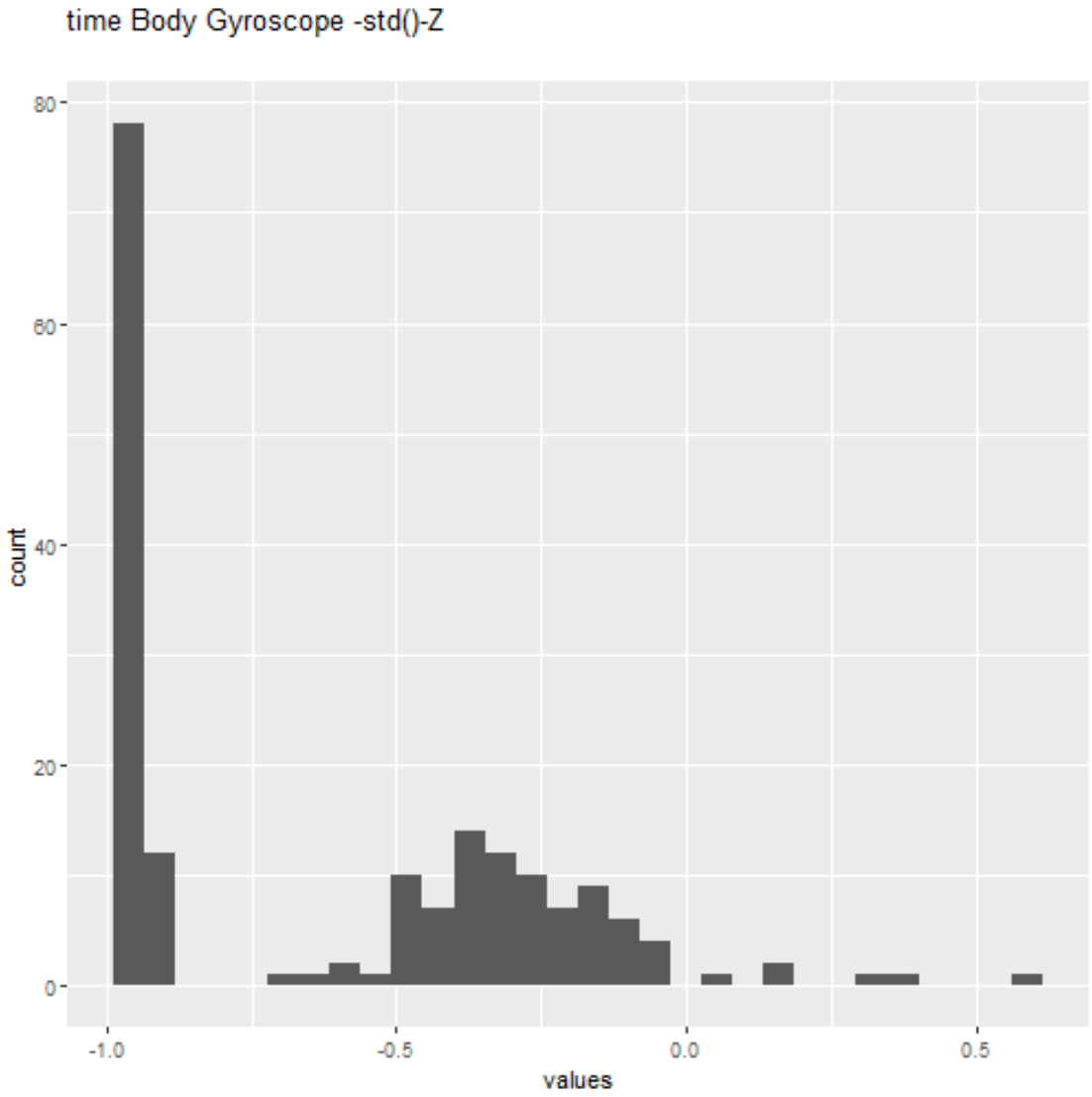
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time	numeric	0	1800	180	-0.65	0.35	-0.99	-0.96	-0.48	-0.42	0.48	<U+2587><U+2581><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581>
BodyGyroscope-std()-Y												

time Body Gyroscope -std()-Z

Distribution



plot of chunk distribution

0 missing values.

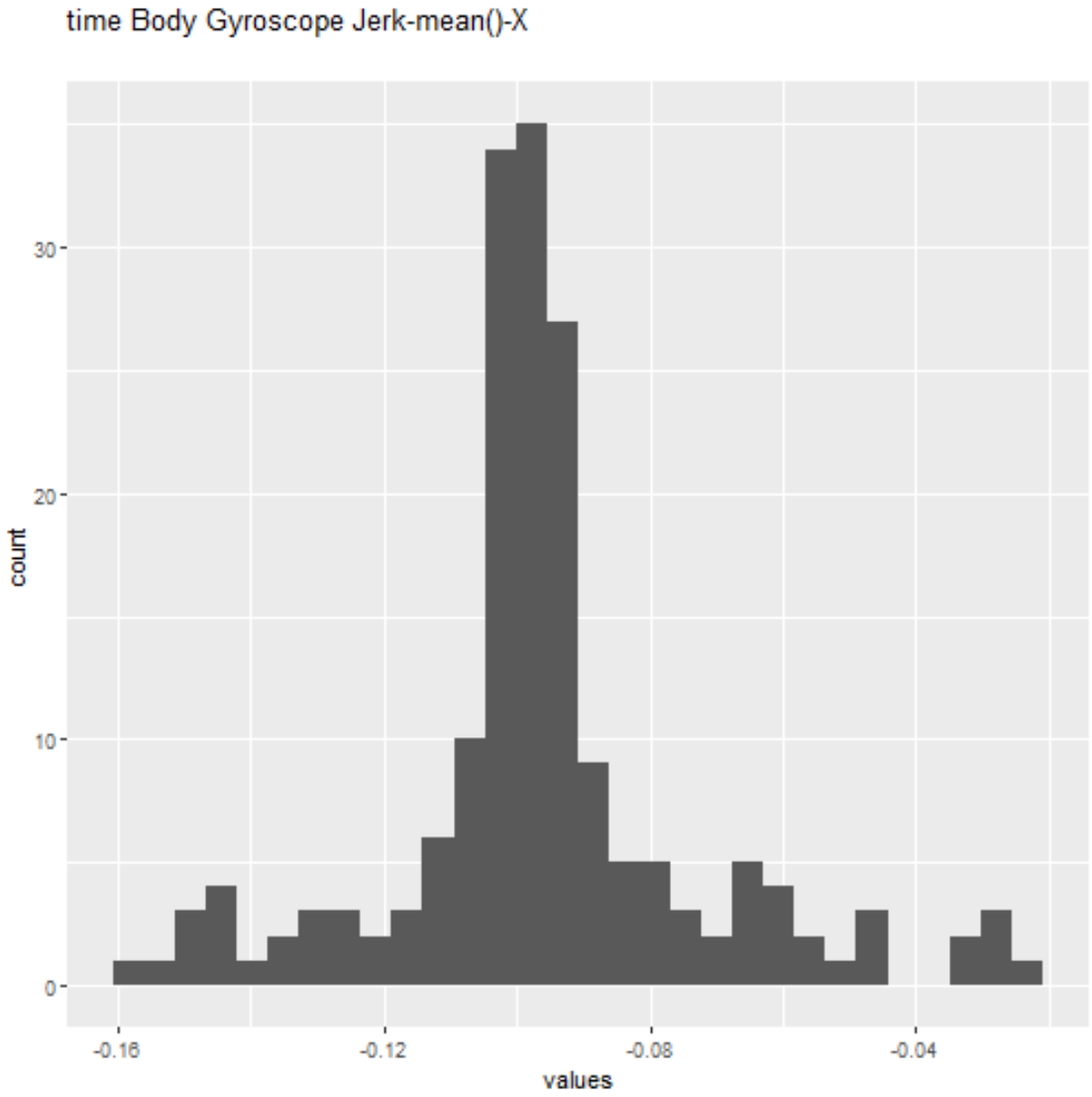
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body	numeric	0	180	180	-0.06	0.37	-0.99	-0.9	0	0.3	0.56	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

y 2 9 6 8 1
Gyr
osc
ope
-
std(
)-Z

time Body Gyroscope Jerk-mean()-X

Distribution



plot of chunk distribution

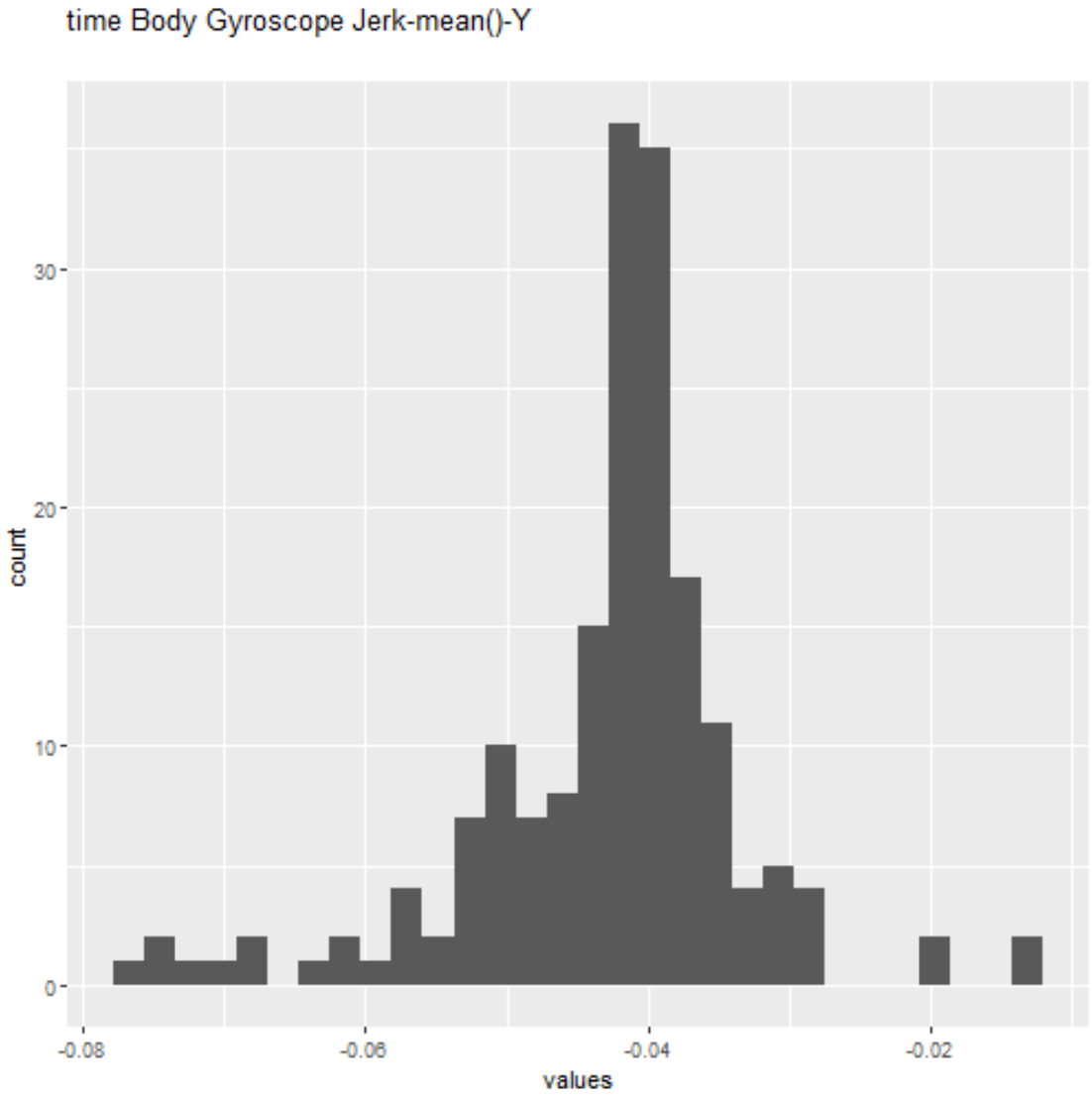
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
timeBodyGyroscopeJerk-mean()-X	numeric	0	180	180	-0.0096	0.023	-0.16	-0.1	-0.0991	-0.0991	-0.022	<U+2581><U+2581><U+2581><U+2587><U+2581><U+2581><U+2581><U+2581>

time Body Gyroscope Jerk-mean()-Y

Distribution



plot of chunk distribution

0 missing values.

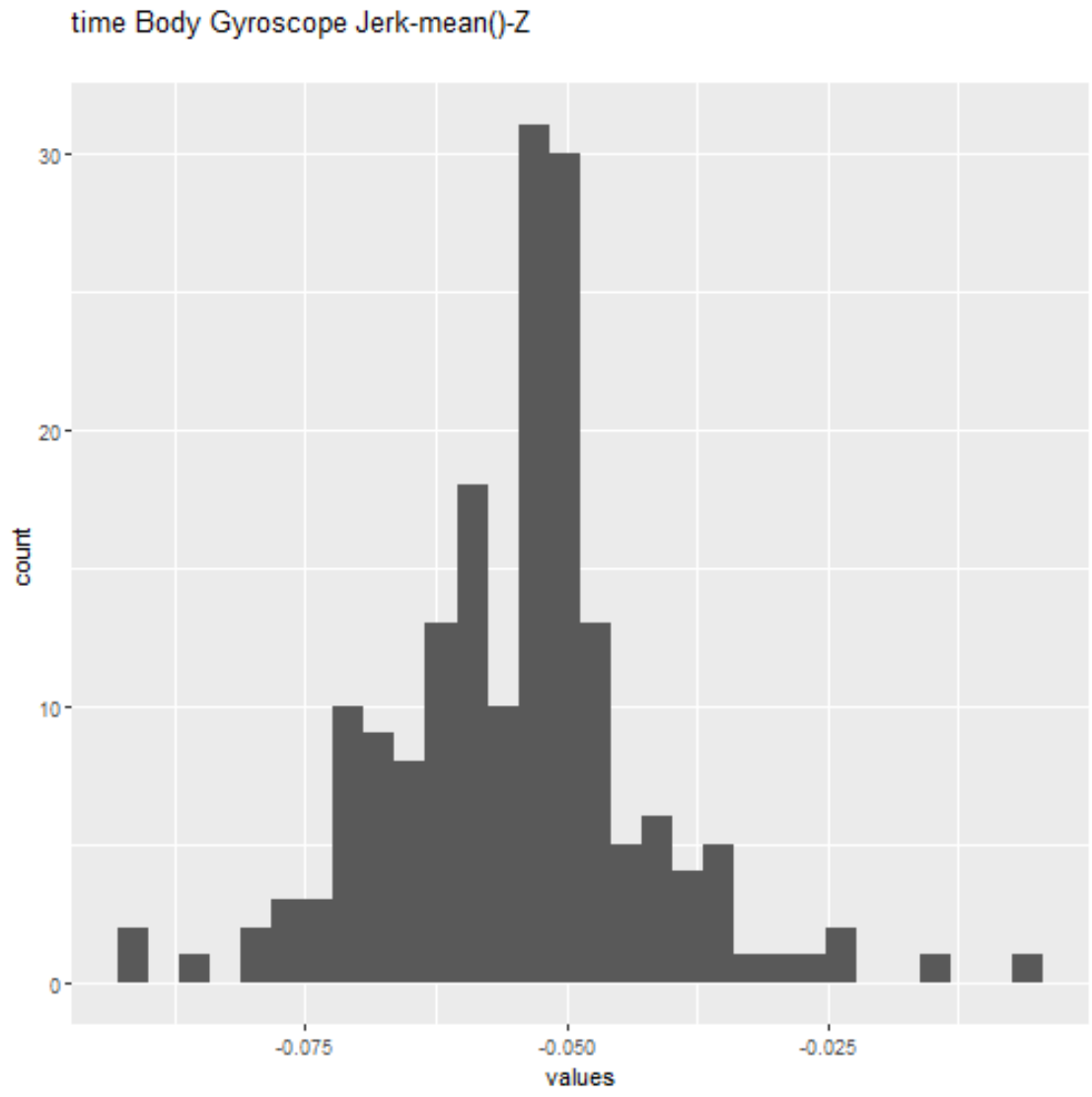
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body	numeric	0	180	180	-0.00	0.095	-0.0	-0.0	-0.0	-0.0	-0.0	<U+2581><U+2581><U+2581><U+2582><U+2587><U+2582><U+2581><U+2581>

y	4	7	4	4	3	1
Gyr	3	7	6	1	8	3
osc						
ope						
Jerk						
-						
me						
an(						
)-Y						

time Body Gyroscope Jerk-mean()-Z

Distribution



plot of chunk distribution

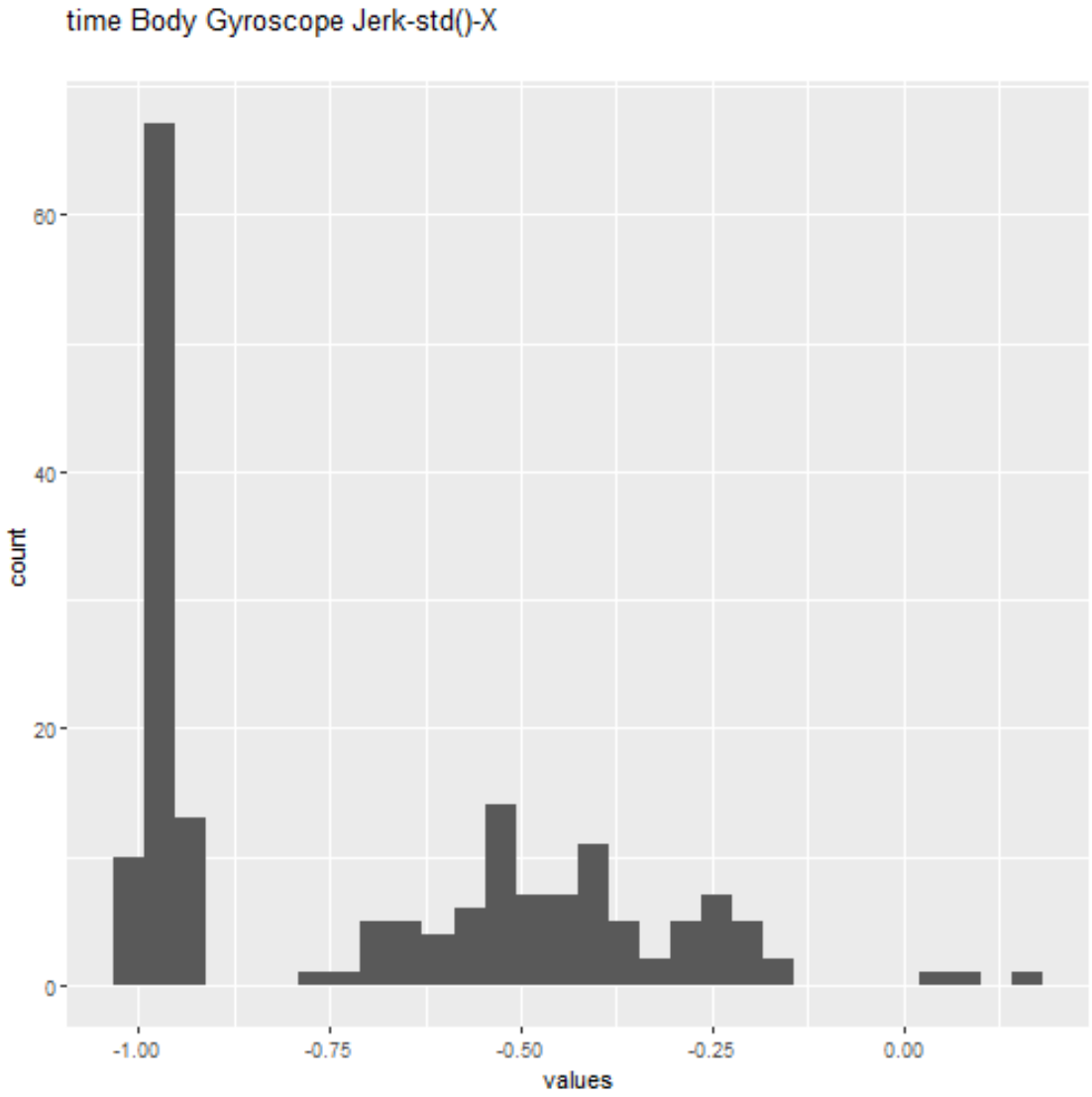
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time	numeric	0	180	180	-0.055	0.012	-0.092	-0.062	-0.053	-0.049	-0.0069	<U+2581><U+2581><U+2583><U+2587><U+2583><U+2581><U+2581>
BodyGyroscopeJerk-mean()-Z												

time Body Gyroscope Jerk-std()-X

Distribution



plot of chunk distribution

0 missing values.

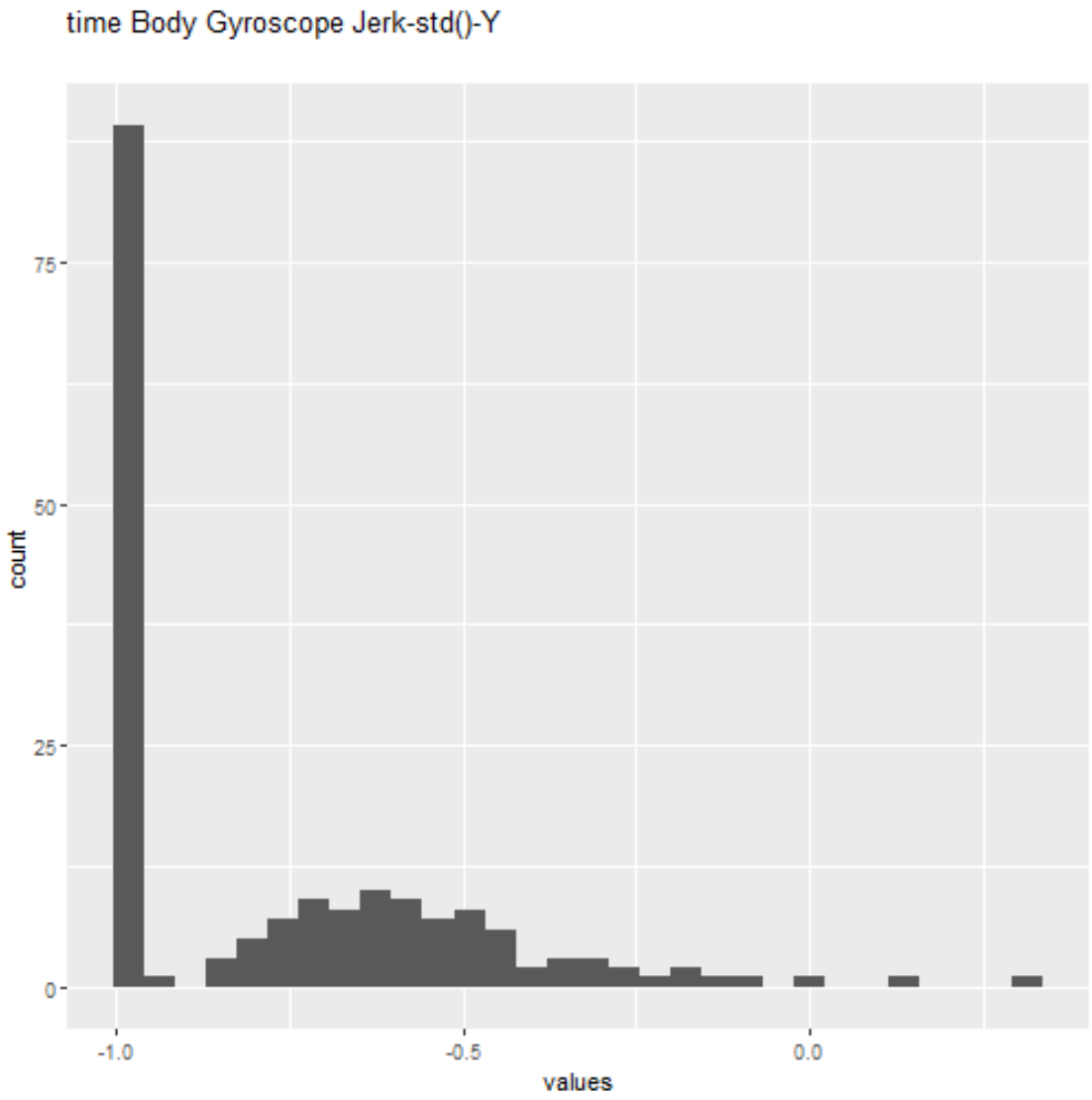
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body	numeric	0	180	180	-0.7	0.3	-1	-0.9	-0.8	-0.4	0.18	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

y 8 4 6
Gyr
osc
ope
Jerk
-
std(
)-X

time Body Gyroscope Jerk-std()-Y

Distribution



plot of chunk distribution

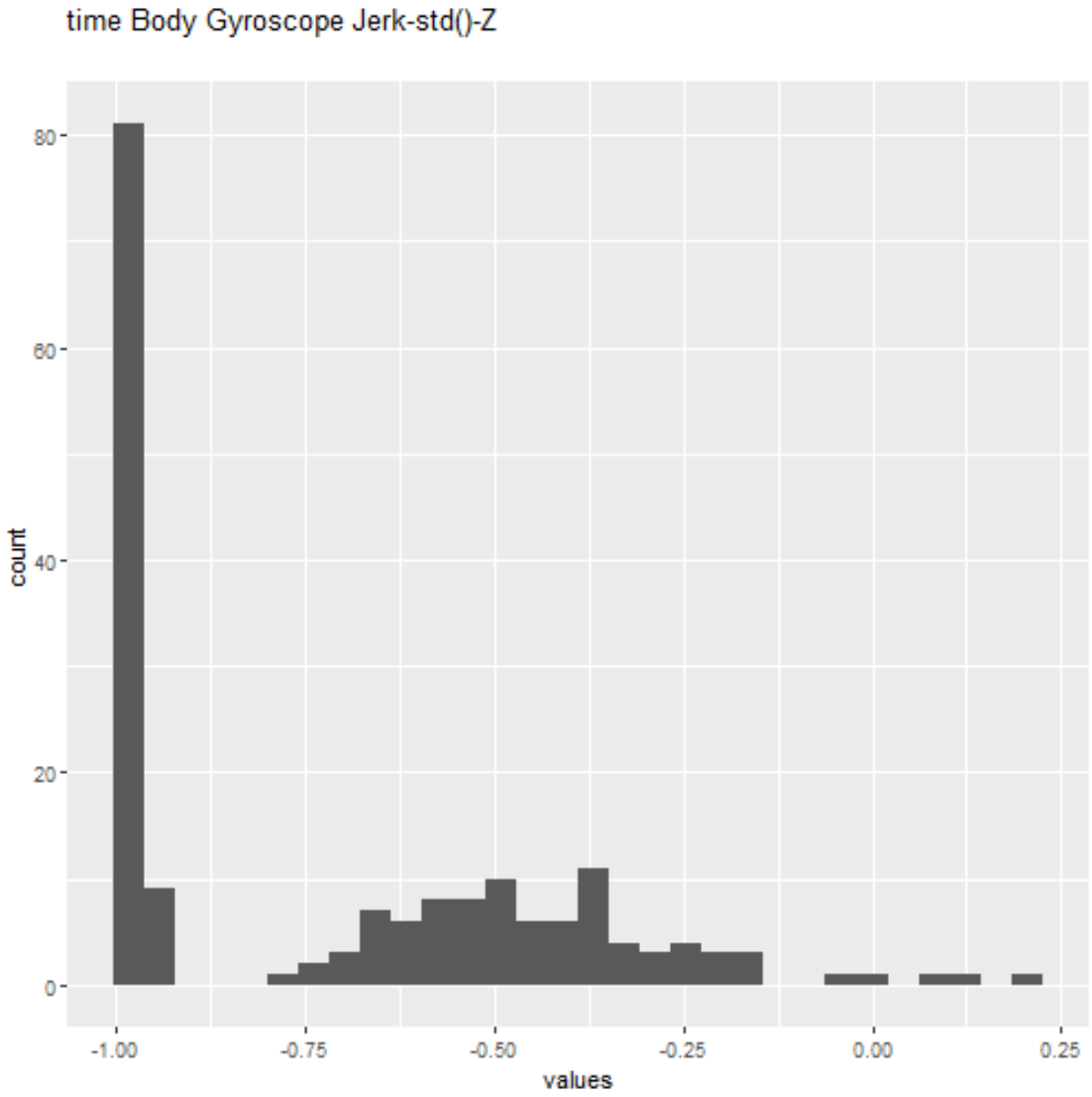
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time	numeric	0	180	180	-0.76	0.27	-1	-0.98	-0.89	-0.59	0.3	<U+2587><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581><U+2581>
BodyGyroscopeJerk-std()-Y												

time Body Gyroscope Jerk-std()-Z

Distribution



plot of chunk distribution

0 missing values.

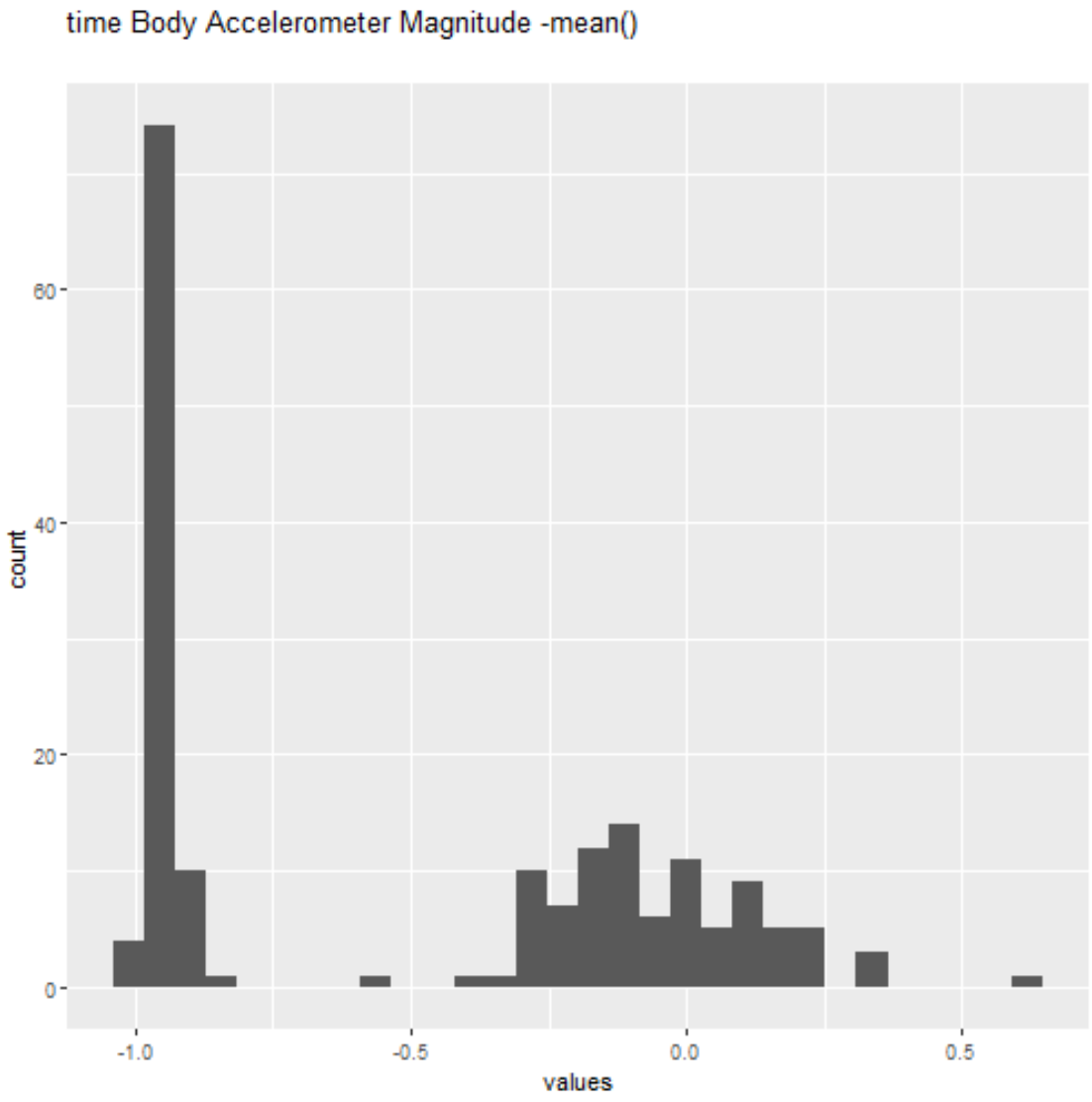
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
tim e Bod	nu mer ic	0	180	1 8 0	- 0. 7	0 . 3	- 1	- 0. 9	- 0. 8	- 0. 4	0. 1 9	<U+2587><U+2581><U+2582><U+ 2582><U+2582><U+2581><U+258 1><U+2581>

y 1 8 6 7
Gyr
osc
ope
Jerk
-
std(
)-Z

time Body Accelerometer Magnitude -mean()

Distribution



plot of chunk distribution

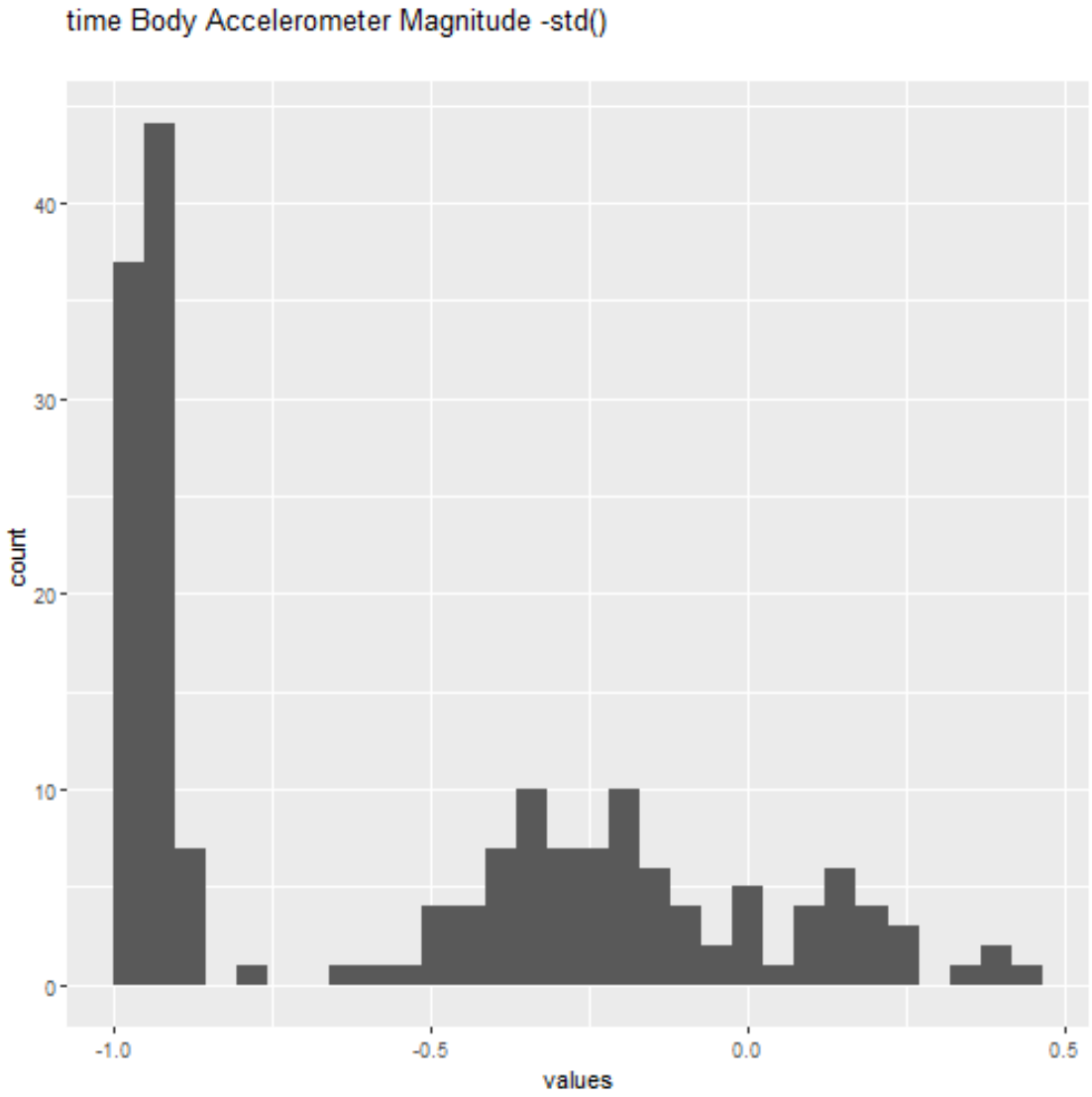
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
timeBodyAccelerometer-Magnitude-mean()	numeric	0	180	180	-0.05	0.47	-0.99	-0.96	-0.48	-0.092	0.64	<U+2587><U+2581><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581>

time Body Accelerometer Magnitude -std()

Distribution



plot of chunk distribution

0 missing values.

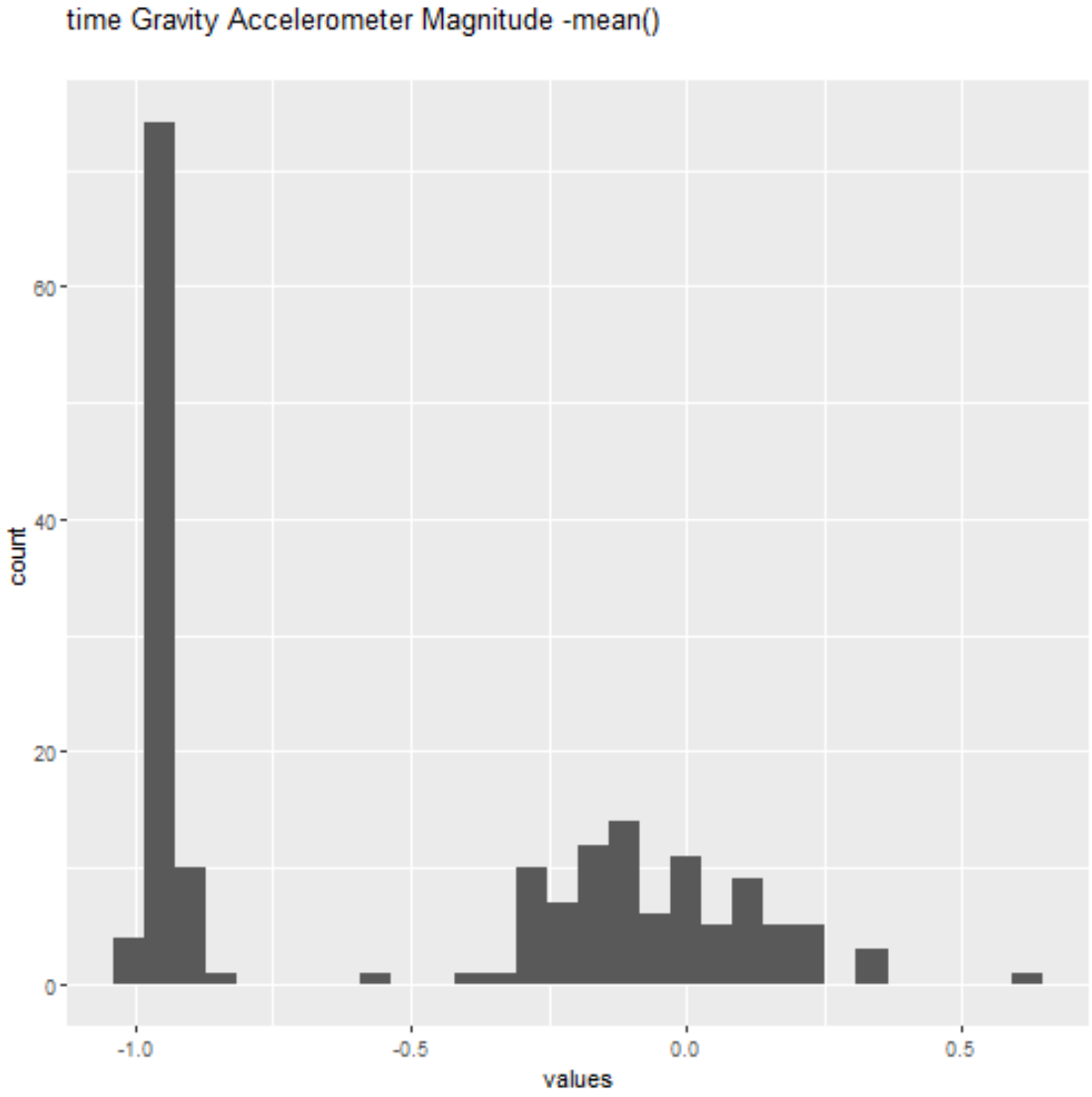
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body Accel	numeric	0	180	180	-0.54	0.42	-1.	-0.	-0.	-0.	0.43	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2582><U+2581>

erom eter Magn itude -std()			4	3	9 9	9 4	6 1	2 1		

time Gravity Accelerometer Magnitude -mean()

Distribution



plot of chunk distribution

0 missing values.

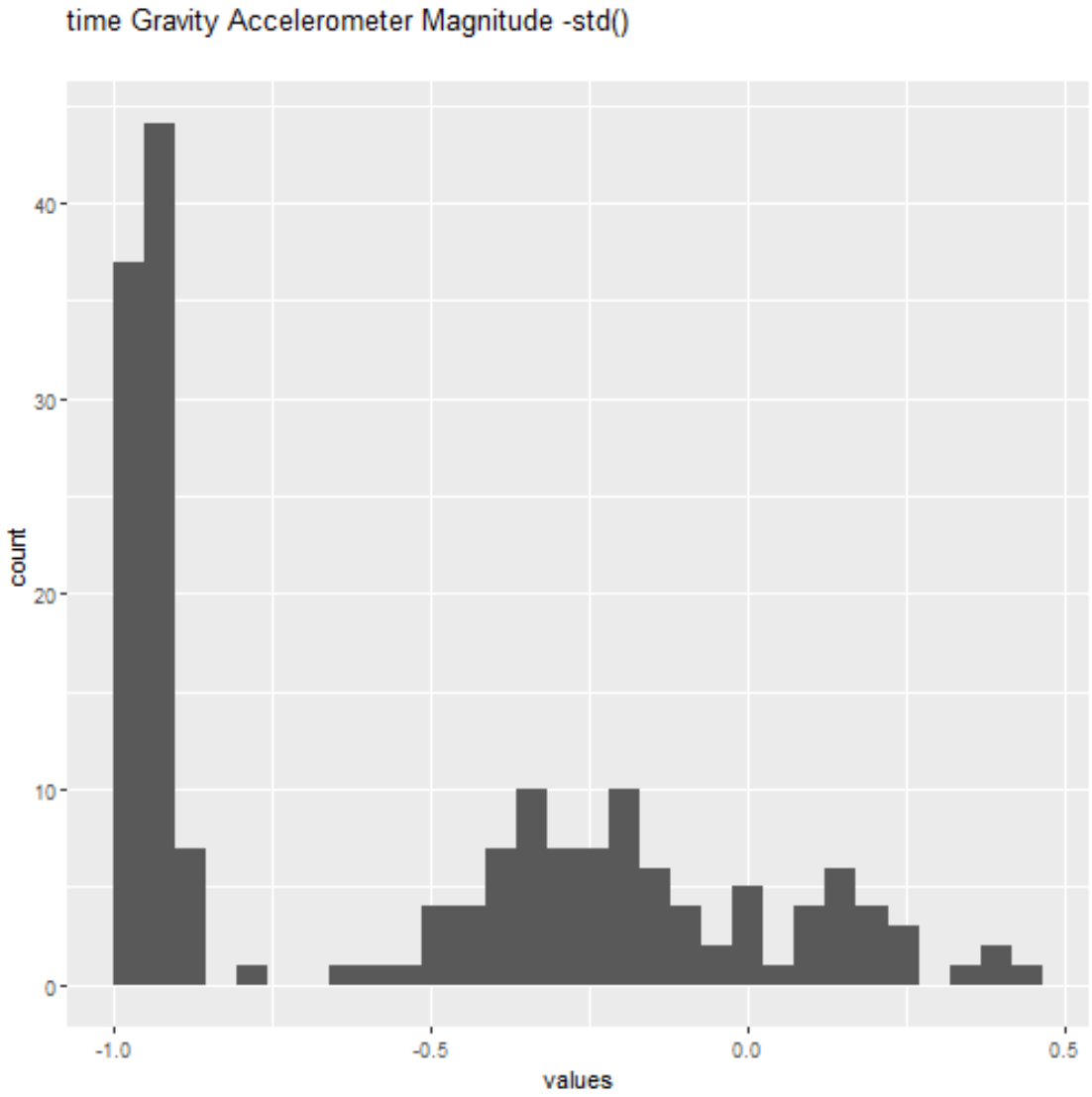
Summary statistics

name	dat a_t	mi ssi	co mp	n	m e	s d	p 0	p 2	p 5	p 7	p 1	hist

	ype	ng	lete		an		5	0	5	00	
time Gravity Accelerometer Magnitude-mean()	numeric	0	1800	180	-0.5	0.47	-0.99	-0.96	-0.48	-0.092	0.64	<U+2587><U+2581><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581>

time Gravity Accelerometer Magnitude -std()

Distribution



plot of chunk distribution

0 missing values.

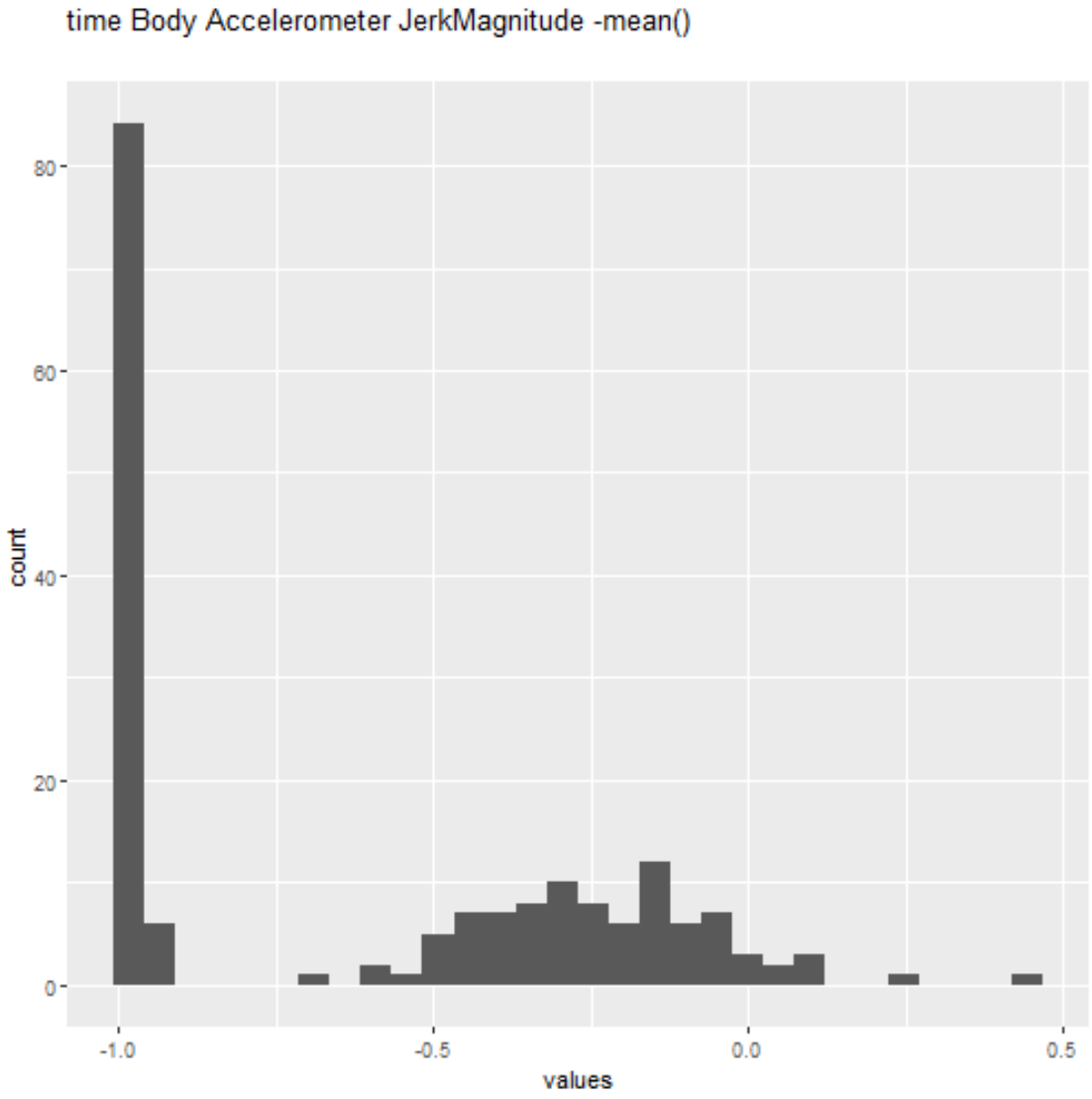
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
timeGravity	numeric	0	180	180	-0.54	0.4	-1	-0.9	-0.6	-0.2	0.43	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2582>

Accelerometer Magnitude -std()				4	3	9	9	6	2			
						9	4	1	1			

time Body Accelerometer JerkMagnitude -mean()

Distribution



plot of chunk distribution

0 missing values.

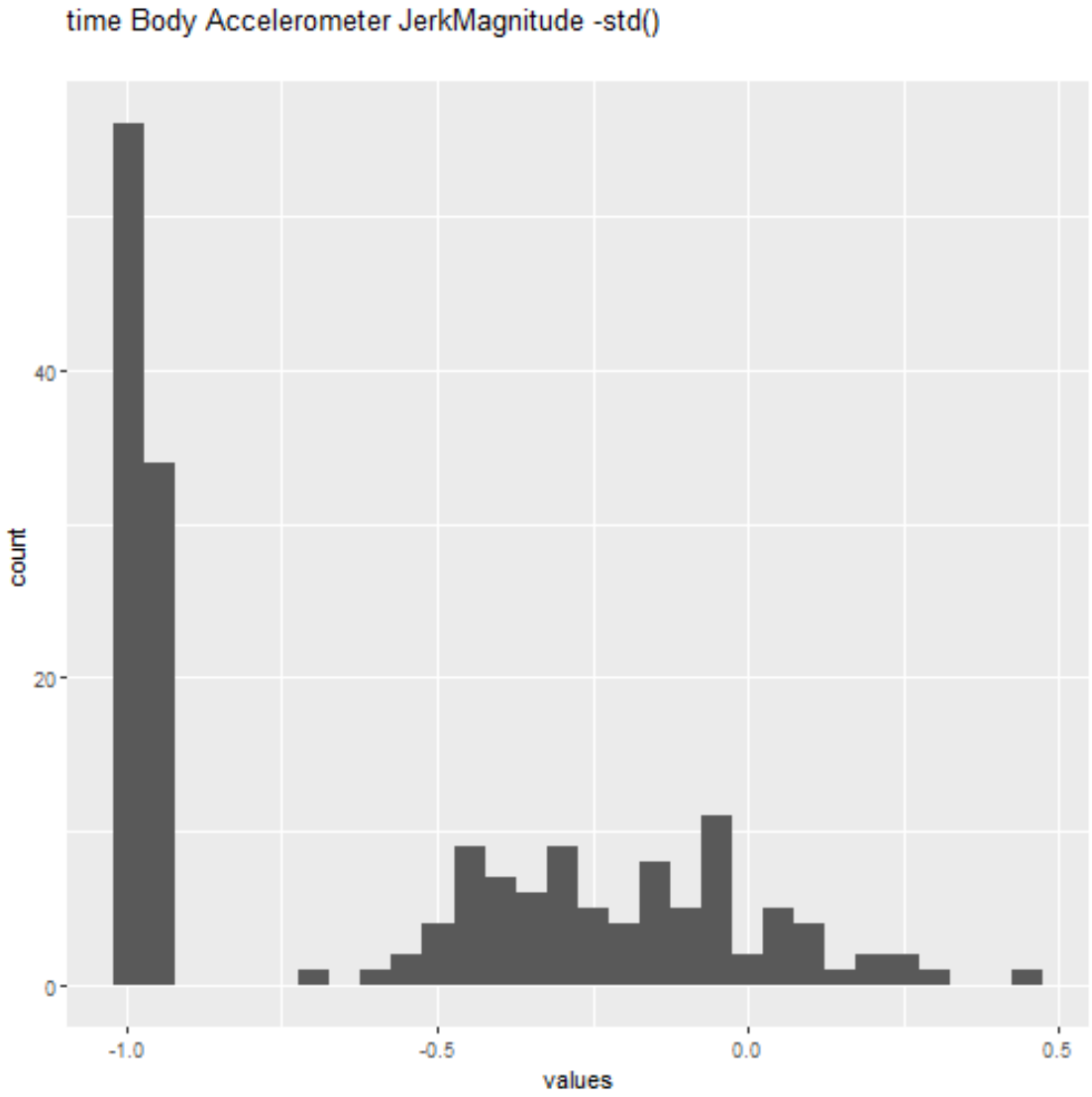
Summary statistics

name	dat	mi	co	n	m	s	p	p	p	p	p	hist

	a_type	ssing	mplete		ean	d	0	25	50	75	100	
timeBodyAccelerometerJerkMagnitude-mean()	numeric	0	1800	180	-0.611	0.4	-0.99	-0.988	-0.82	-0.25	0.43	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2581>

time Body Accelerometer JerkMagnitude -std()

Distribution



plot of chunk distribution

0 missing values.

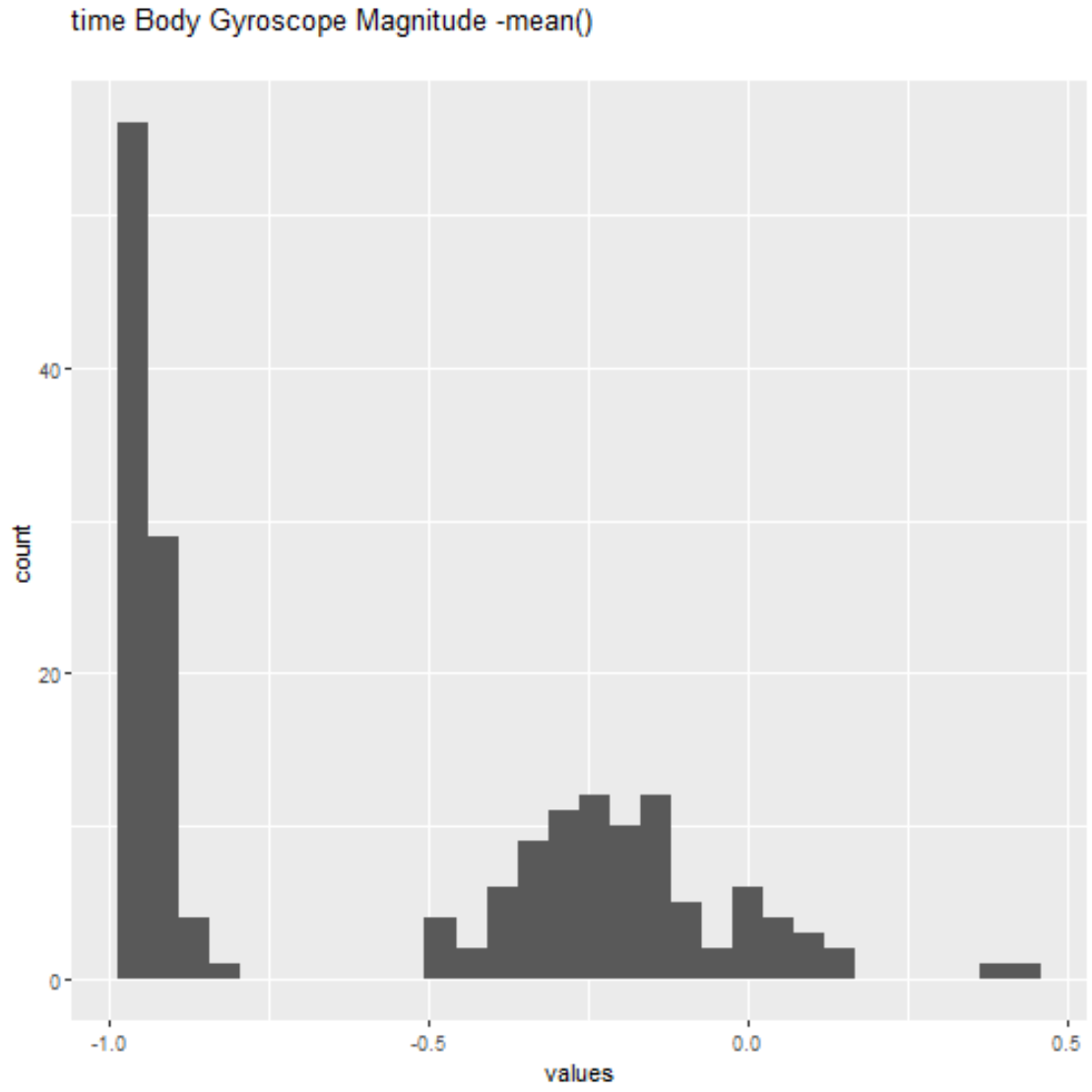
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body Accelerometer JerkMagnitude -std()	numeric	0	1800	1800	-0.54	0.43	-1.	-0.	-0.	-0.	0.45	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>

erom eter JerkM agnit ude - std()				8	2	9 9	9 8	8	2 2			

time Body Gyroscope Magnitude -mean()

Distribution



plot of chunk distribution

0 missing values.

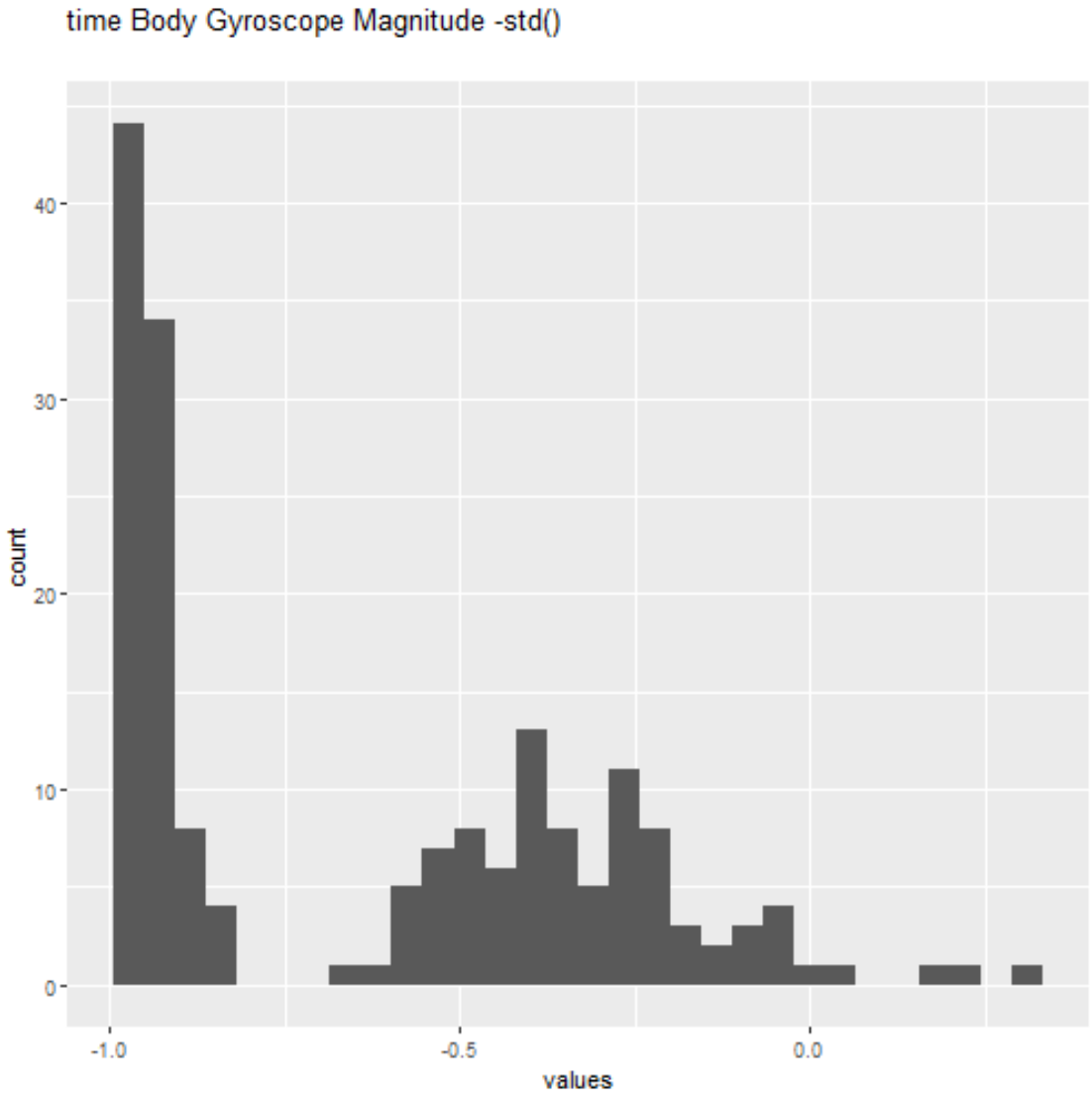
Summary statistics

nam	dat	mi	co	n	m	s	p	p	p	p	p	hist

e	a_type	ssing	mplete		ean	d	0	25	50	75	100	
time Body Gyroscope Magnitude - mean()	numeric	0	1800	180	-0.57	0.4	-0.98	-0.95	-0.66	-0.22	0.42	<U+2587><U+2581><U+2581><U+2582><U+2583><U+2581><U+2581><U+2581>

time Body Gyroscope Magnitude -std()

Distribution



plot of chunk distribution

0 missing values.

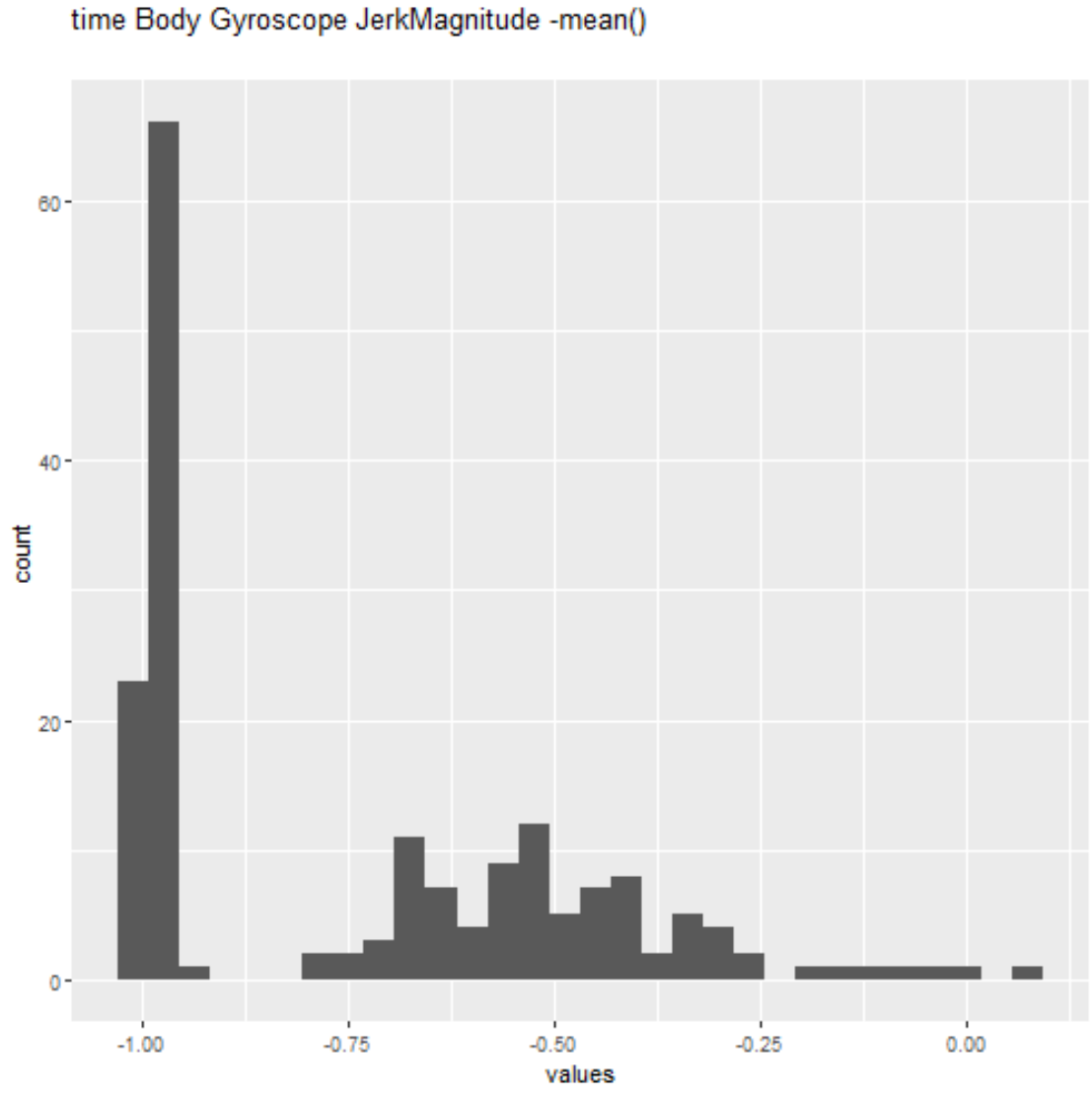
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body	numeric	0	180	180	-0.06	0.34	-0.99	-0.99	-0.97	-0.03	0.3	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

y 3 8 5 4 6
Gyr
osc
ope
Mag
nitu
de -
std(
)

time Body Gyroscope JerkMagnitude -mean()

Distribution



plot of chunk distribution

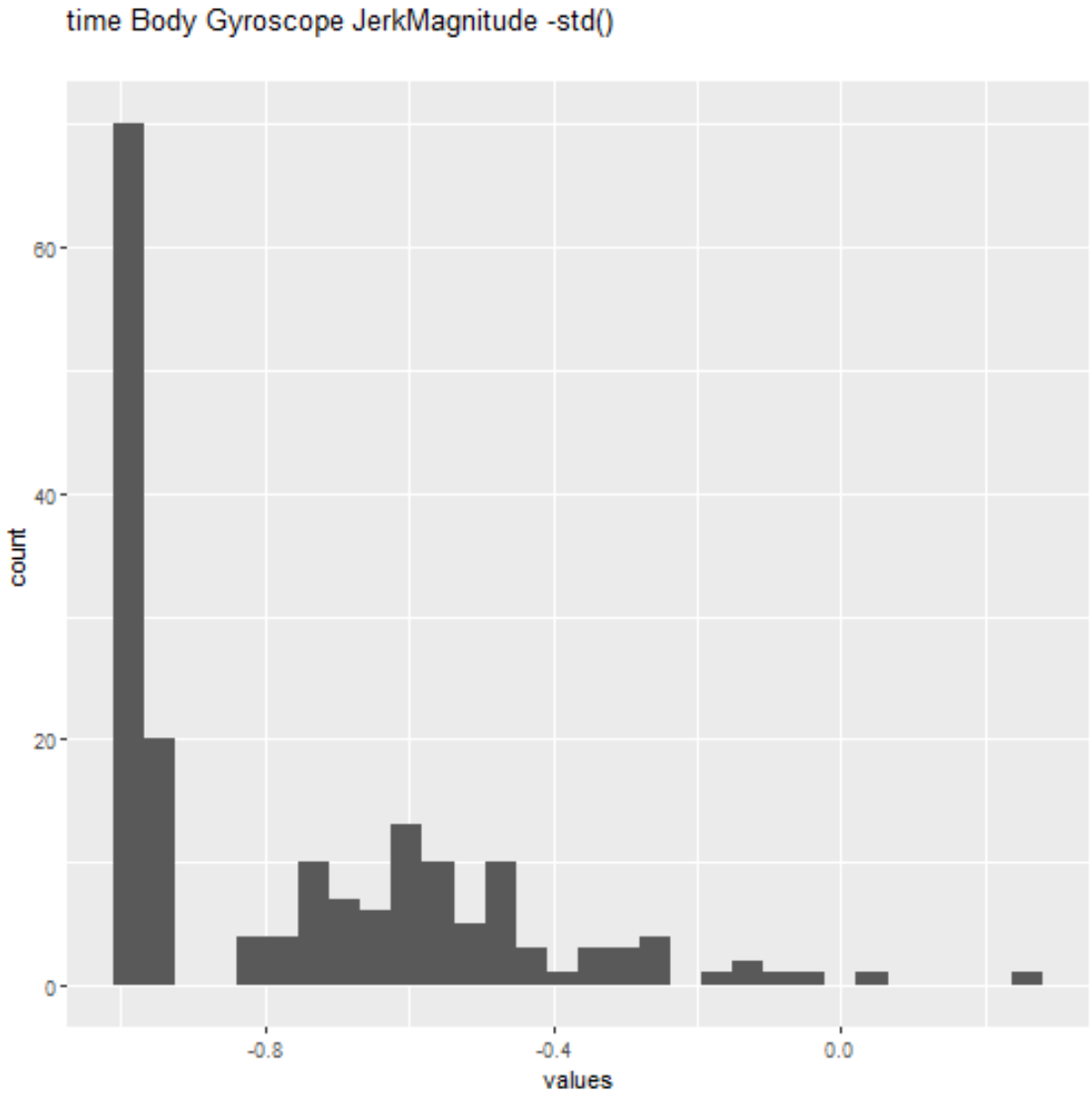
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
timeBodyGyroscopeJerkMagnitude - mean()	numeric	0	180	180	-0.74	0.28	-1	-0.99	-0.86	-0.51	0.08	<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>

time Body Gyroscope JerkMagnitude -std()

Distribution



plot of chunk distribution

0 missing values.

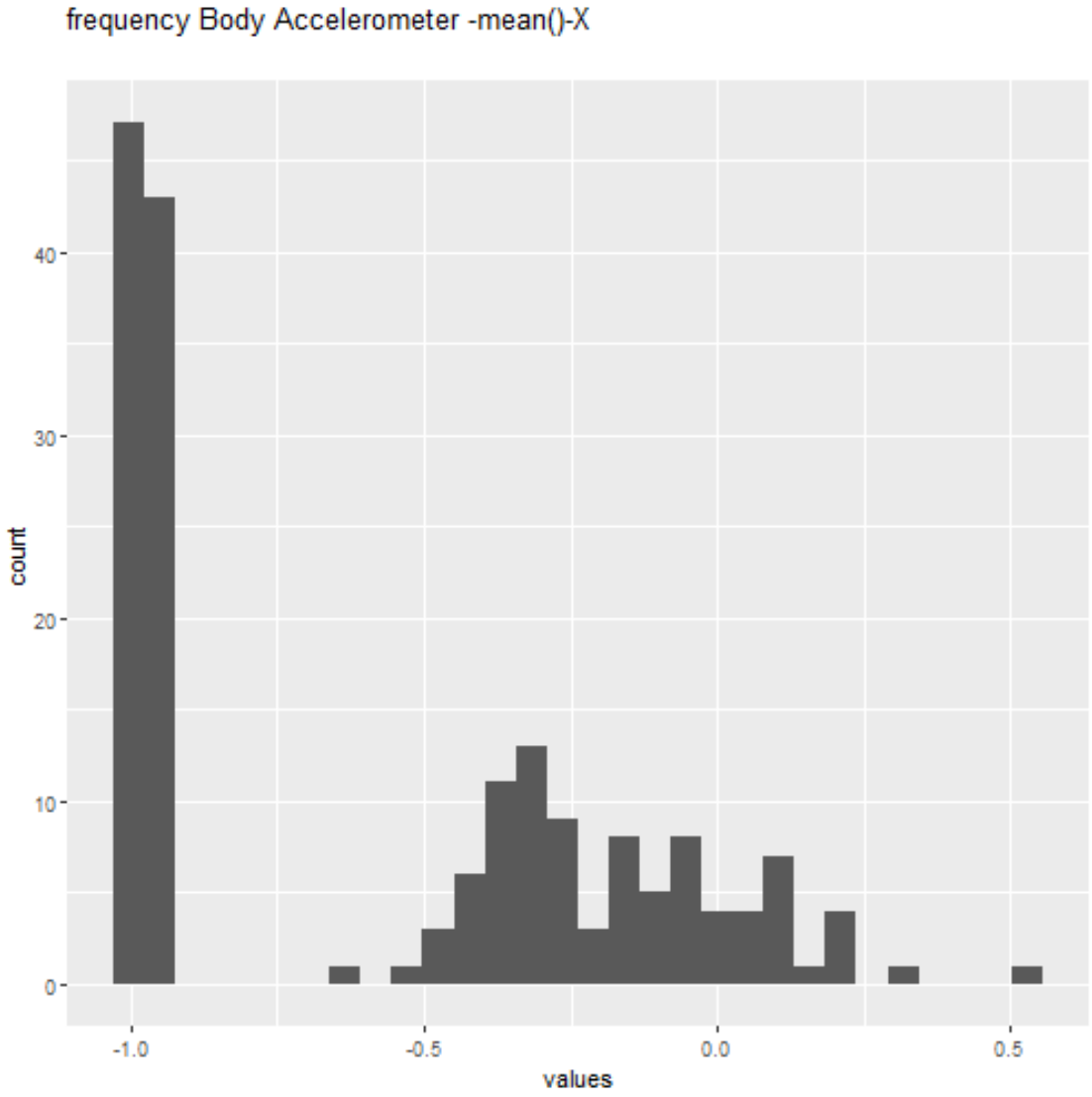
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
time Body Gyros	numeric	0	180	180	-0.07	0.27	-1	-0.9	-0.8	-0.5	0.25	<U+2587><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

cope			6		8	8	8			
JerkM agnit ude - std()										

frequency Body Accelerometer -mean()-X

Distribution



plot of chunk distribution

0 missing values.

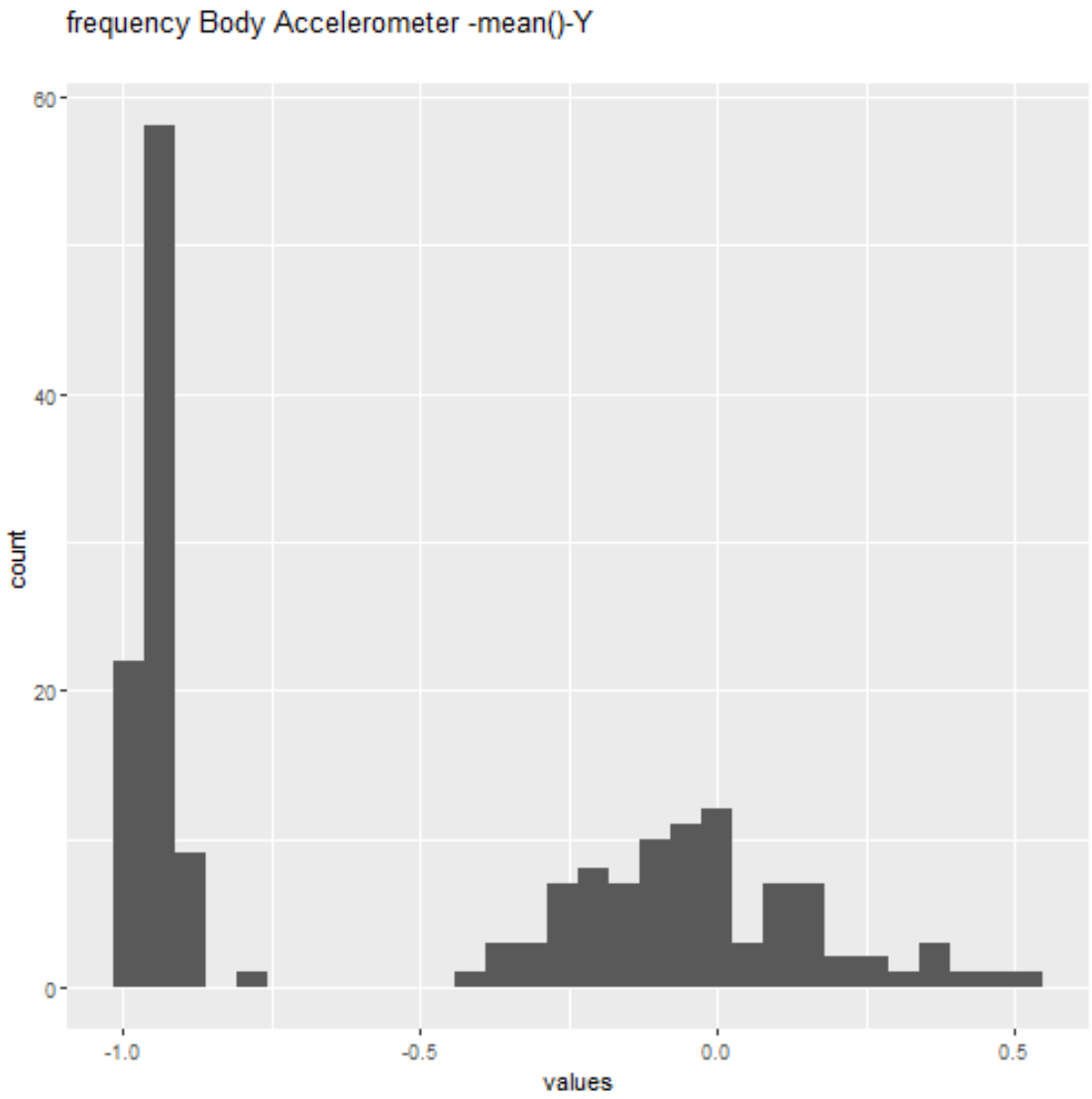
Summary statistics

name	data_t	missi	comp	n	mean	sd	p0	p2	p5	p7	p1	hist

	ype	ng	lete		a n		5	0	5	0 0	
frequ ency Body Accel erom eter - mean ()-X	nu me ric	0	18 0	1 8 0	- 0. 5 8	0. 4 3	- 1	- 0. 9 8	- 0. 7 7	- 0. 2 2	0. 5 4	<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581>

frequency Body Accelerometer -mean()-Y

Distribution



plot of chunk distribution

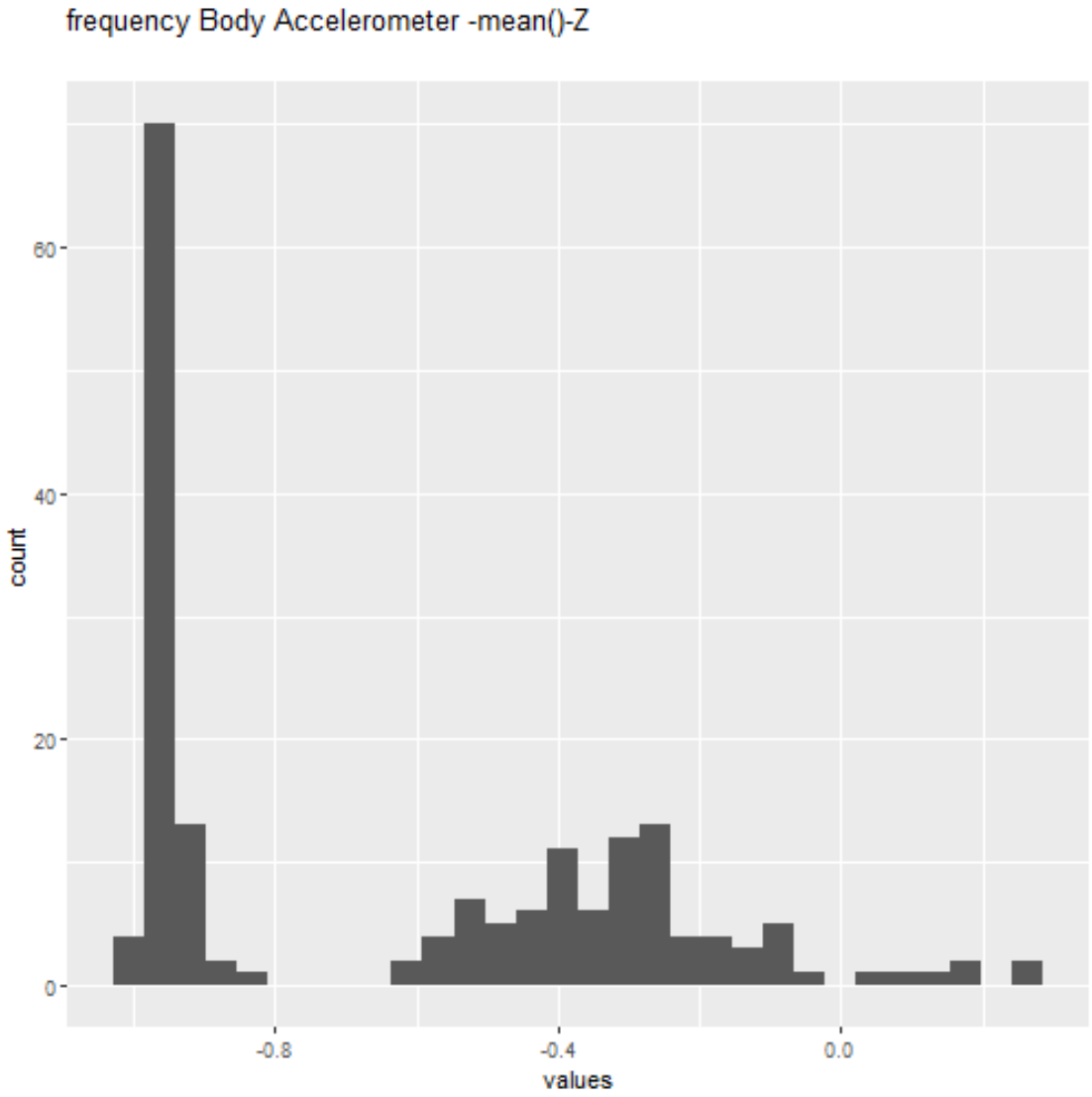
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body Accelerometer - mean ()-Y	numeric	0	180	180	-0.49	0.48	-0.99	-0.95	-0.59	-0.063	0.52	<U+2587><U+2581><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581>

frequency Body Accelerometer -mean()-Z

Distribution



plot of chunk distribution

0 missing values.

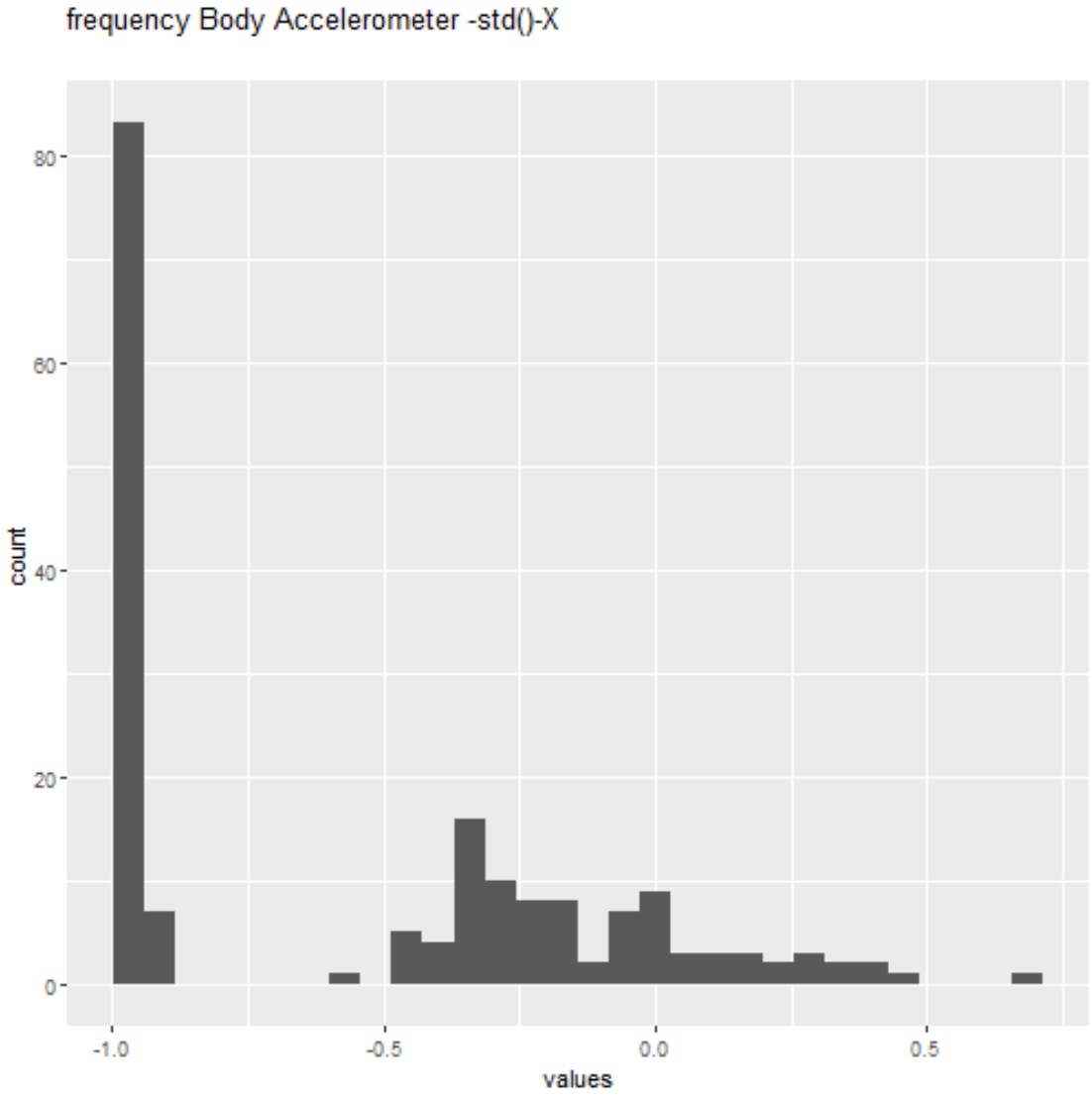
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body	numeric	0	180	180	-0.06	0.3	.	.	.	.	0.28	<U+2587><U+2581><U+2581><U+2582><U+2583><U+2581><U+2581>

Accelerometer - mean()-Z			3	6	9	9	7	3			
					9	6	2	2			

frequency Body Accelerometer -std()-X

Distribution



plot of chunk distribution

0 missing values.

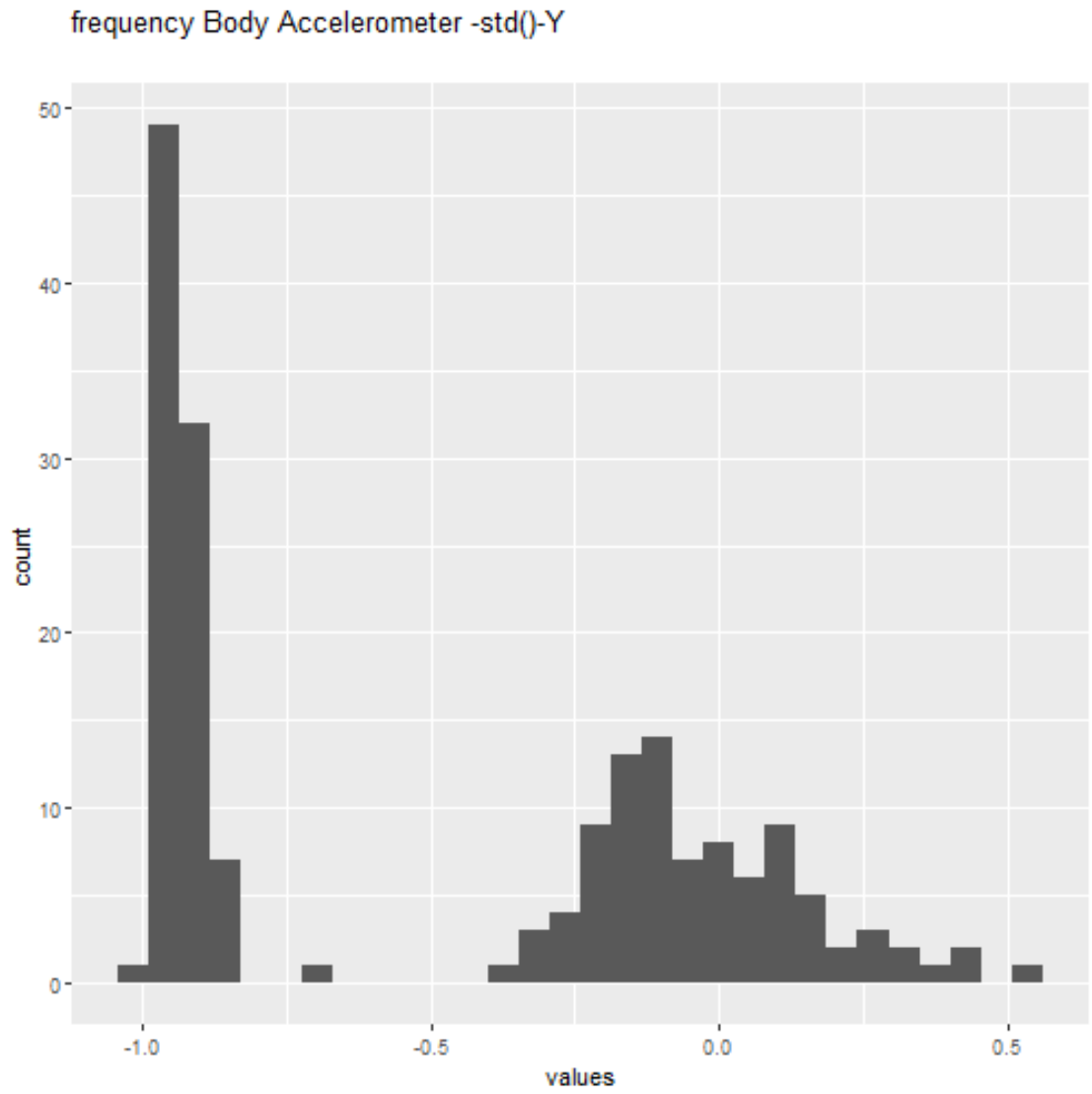
Summary statistics

name	data_t	missi	comp	n	mean	sd	p0	p25	p50	p75	p1	hist

	ype	ng	lete		a n		5	0	5	0 0	
frequency Body Accelerometer -std()-X	numeric	0	1800	1800	-0.555	0.46	-1	-0.98	-0.75	-0.2	0.66	<U+2587><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581><U+2581>

frequency Body Accelerometer -std()-Y

Distribution



plot of chunk distribution

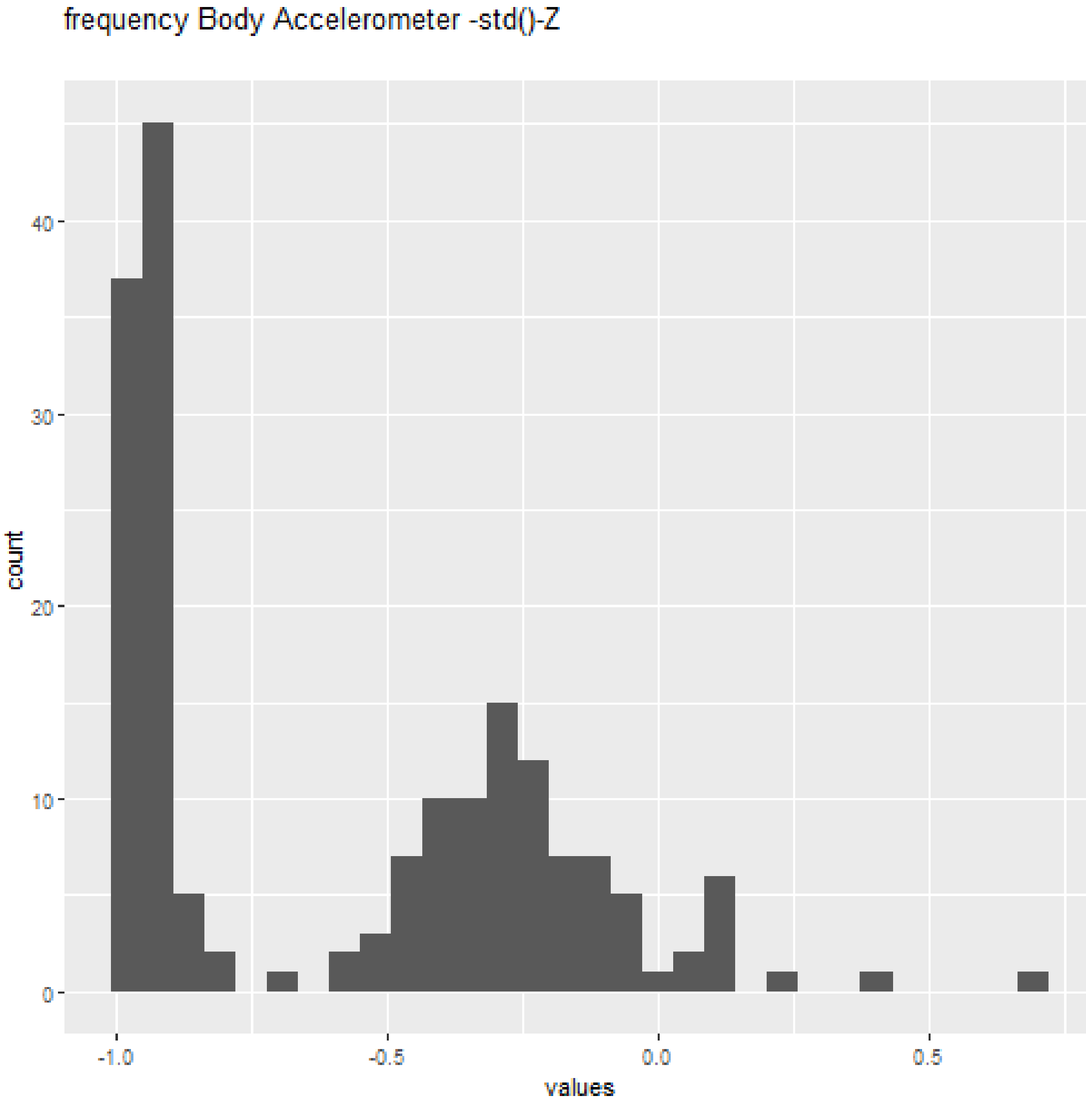
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body Accelerometer -std()-Y	numeric	0	180	180	-0.48	0.47	-0.99	-0.94	-0.51	-0.079	0.56	<U+2587><U+2581><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581>

frequency Body Accelerometer -std()-Z

Distribution



plot of chunk distribution

0 missing values.

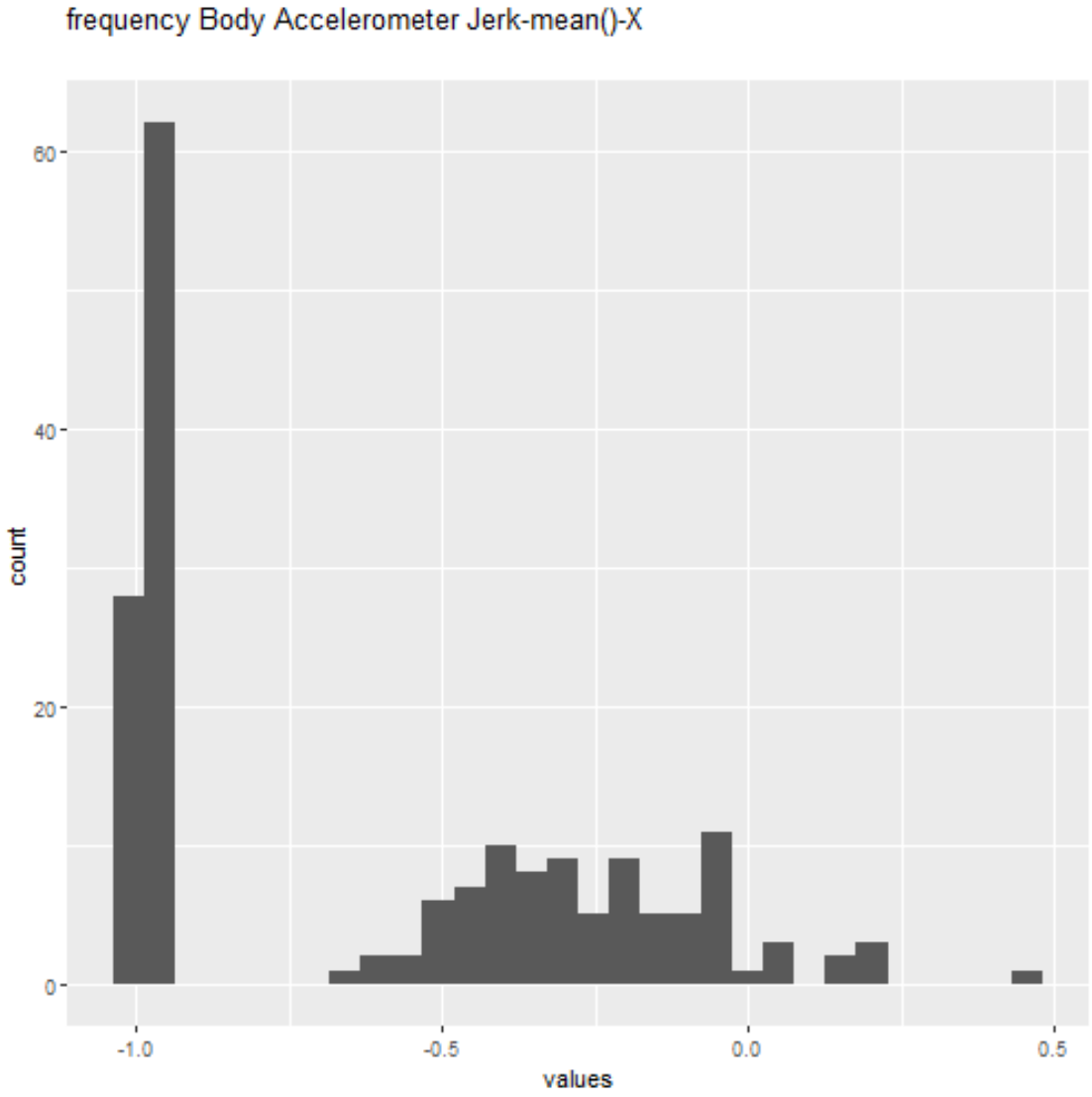
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body	numeric	0	180	180	-0.5	0.3	-0.	-0.	-0.	-0.	0.69	<U+2587><U+2581><U+2582><U+2583><U+2581><U+2581><U+2581><U+2581>

Accelerometer - std()-Z			8	9	99	95	64	27			

frequency Body Accelerometer Jerk-mean()-X

Distribution



plot of chunk distribution

0 missing values.

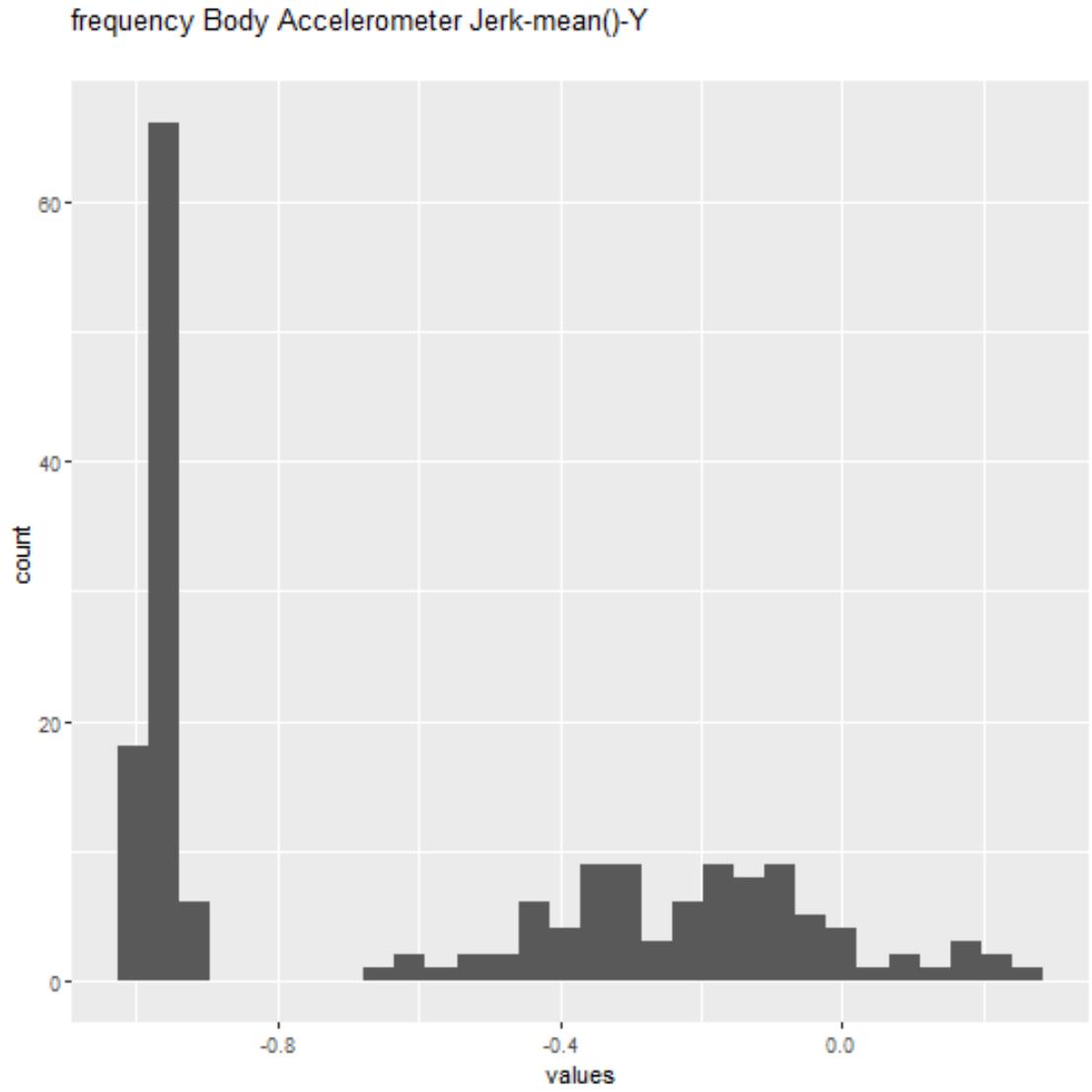
Summary statistics

name	data_t	missi	comp	n	me	sd	p0	p2	p5	p7	p1	hist

	ype	ng	lete		an		5	0	5	00	
frequency Body Accelerometer Jerk-mean()-X	numeric	0	1800	1801	-0.61	0.4	-0.99	-0.981	-0.828	0.47	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2581>

frequency Body Accelerometer Jerk-mean()-Y

Distribution



plot of chunk distribution

0 missing values.

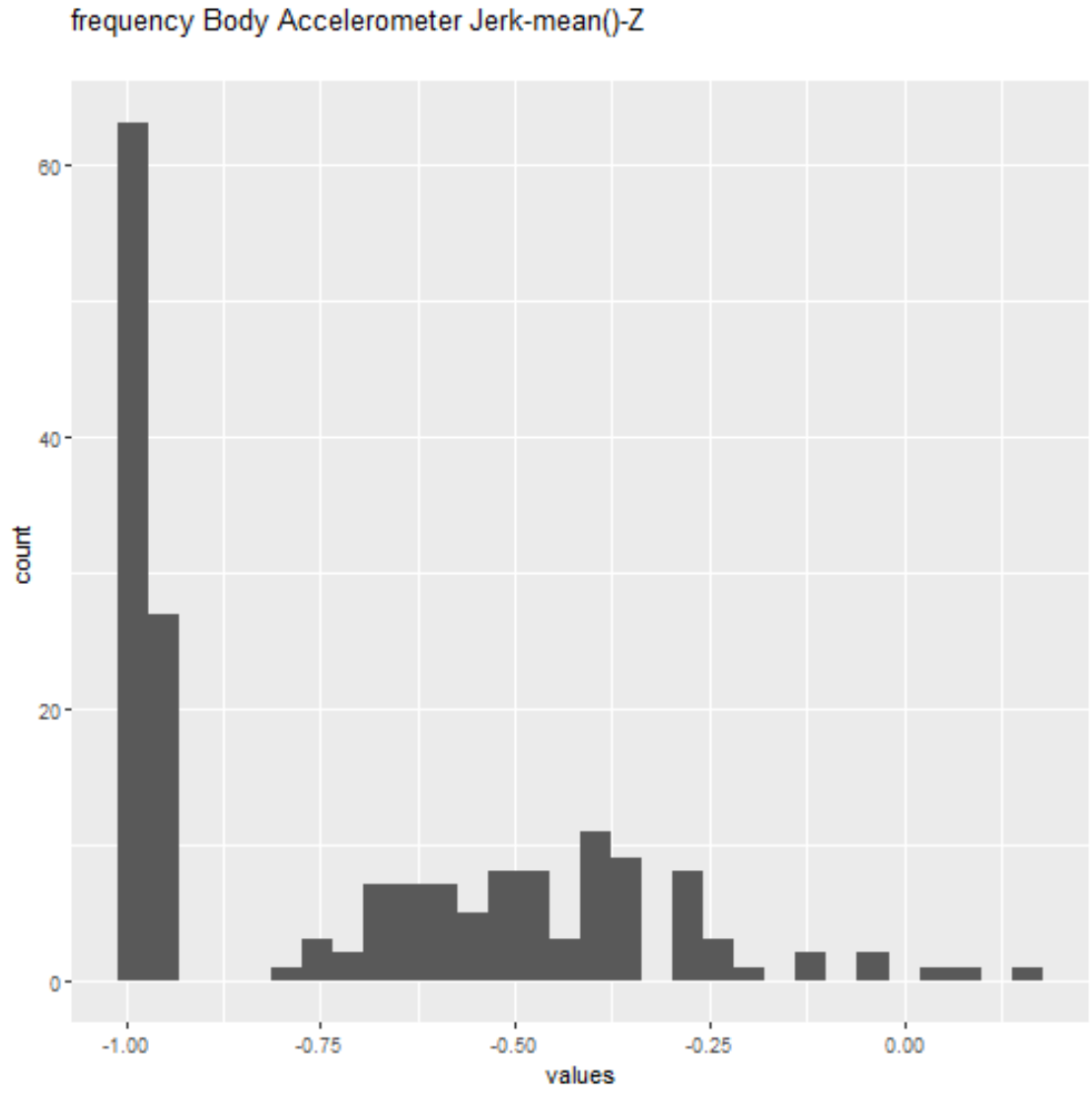
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body	numeric	0	180	180	-0.59	0.41	-0.99	-0.97	-0.70	-0.36	0.28	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581>

Accelerometer Jerk-mean()-Y			9		9	7	8	2			

frequency Body Accelerometer Jerk-mean()-Z

Distribution



plot of chunk distribution

0 missing values.

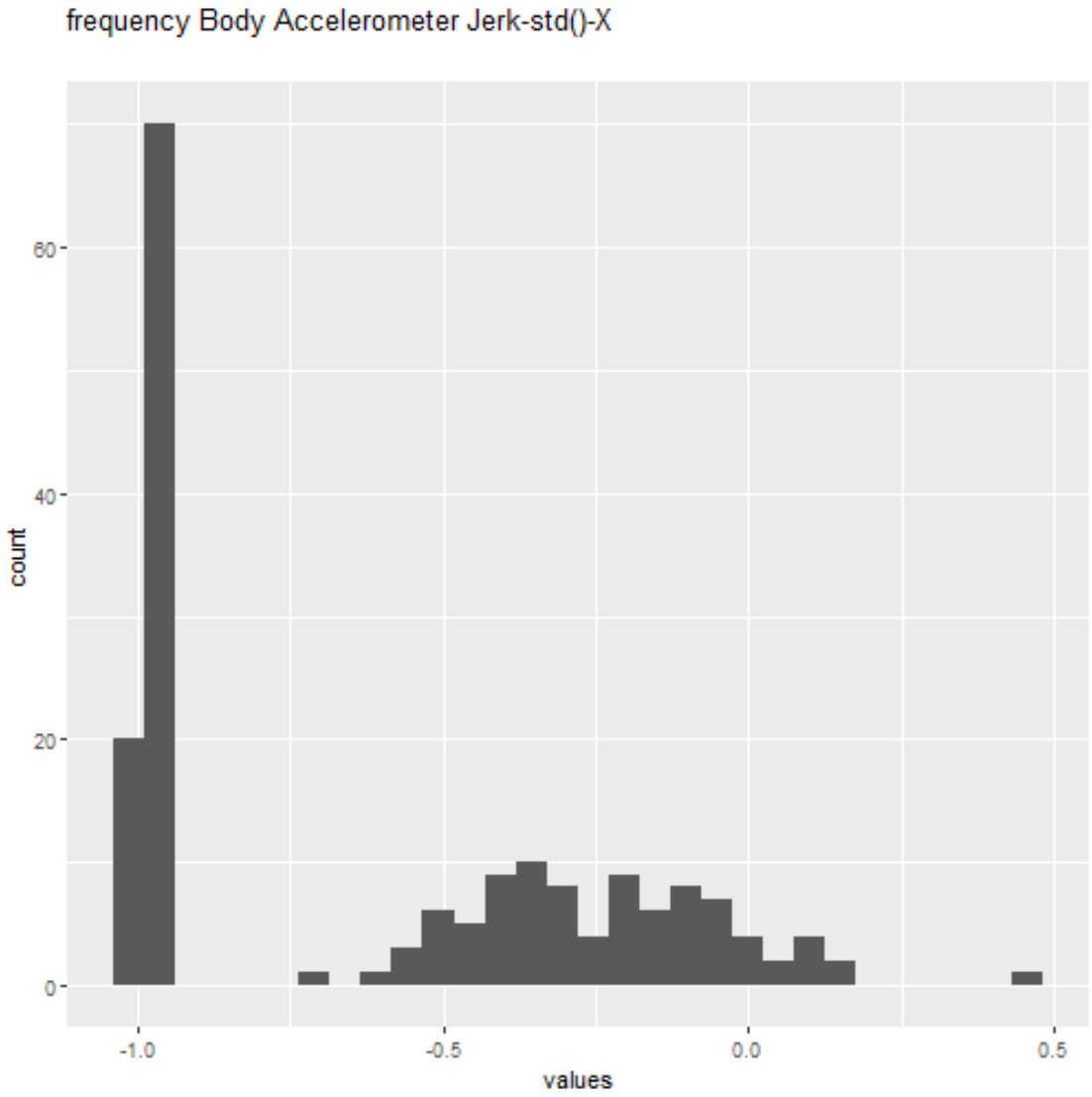
Summary statistics

name	dat	mi	co	n	m	s	p	p	p	p	p	hist

	a_type	ssing	mplete		ean	d	0	25	50	75	100	
frequency Body Accelerometer Jerk-mean()-Z	numeric	0	1800	180	-0.71	0.3	-0.99	-0.988	-0.887	-0.47	0.16	<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2582><U+2581><U+2581>

frequency Body Accelerometer Jerk-std()-X

Distribution



plot of chunk distribution

0 missing values.

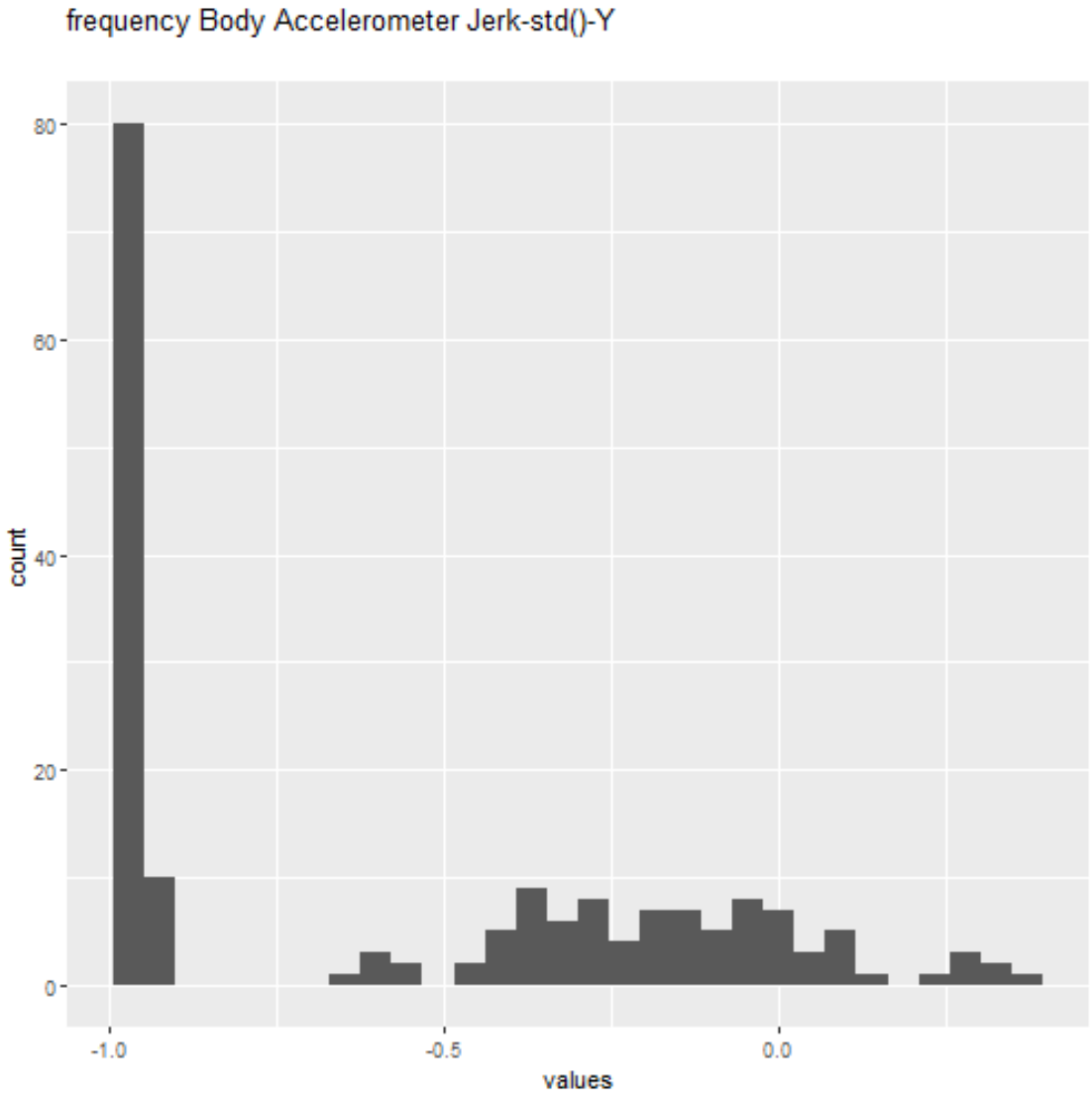
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body	numeric	0	180	180	-0.6	.4	-1	-0.9	-0.8	-0.2	0.48	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>

Accelerometer Jerk-std()-X			1		8	3	5					

frequency Body Accelerometer Jerk-std()-Y

Distribution



plot of chunk distribution

0 missing values.

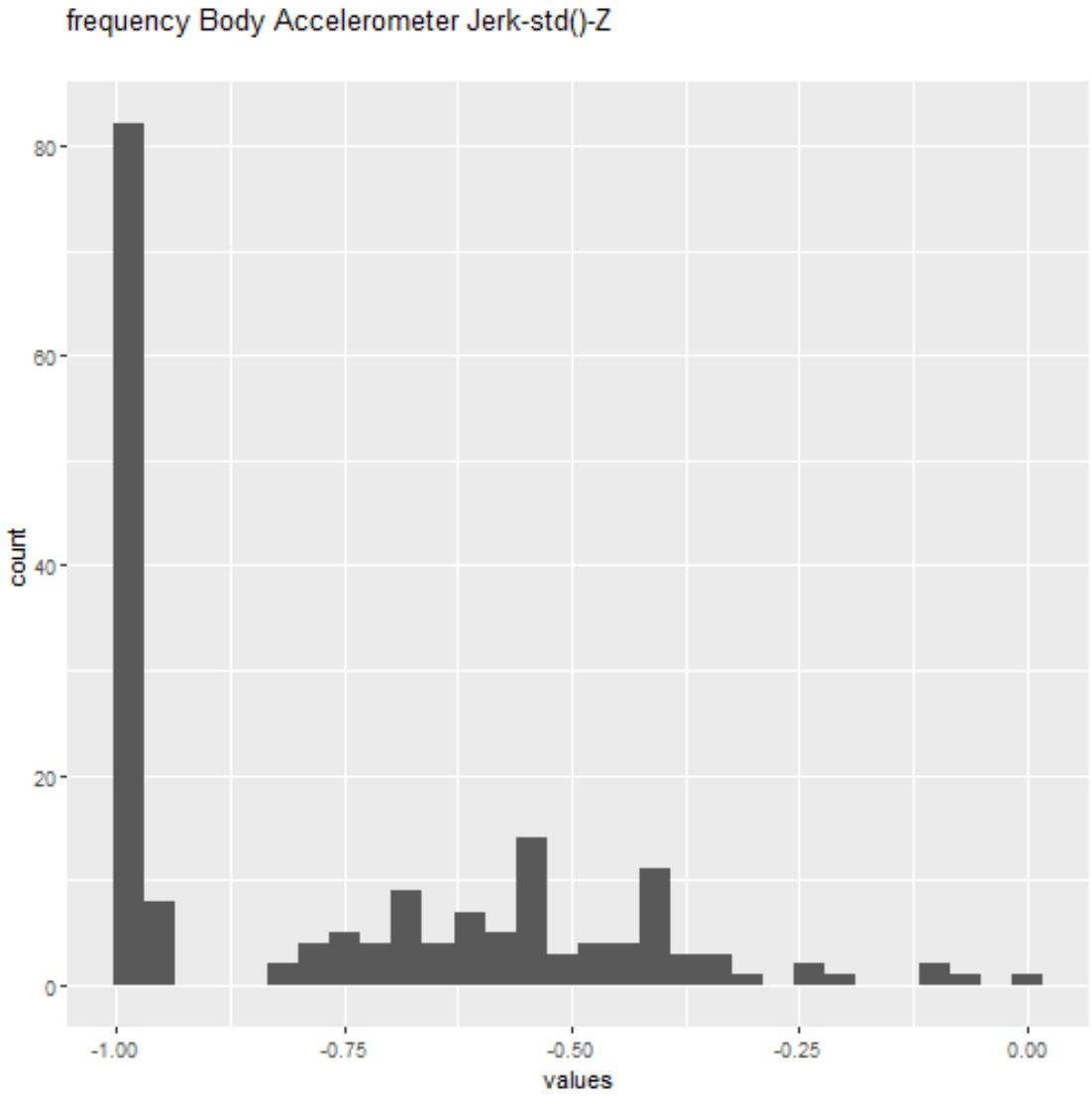
Summary statistics

name	dat	mi	co	n	m	s	p	p	p	p	p	hist

	a_type	ssing	mplete		ean	d	0	25	50	75	100	
frequency BodyAccelerometerJerk-std()-Y	numeric	0	1800	180	-0.57	0.43	-0.99	-0.97	-0.79	-0.17	0.35	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>

frequency Body Accelerometer Jerk-std()-Z

Distribution



plot of chunk distribution

0 missing values.

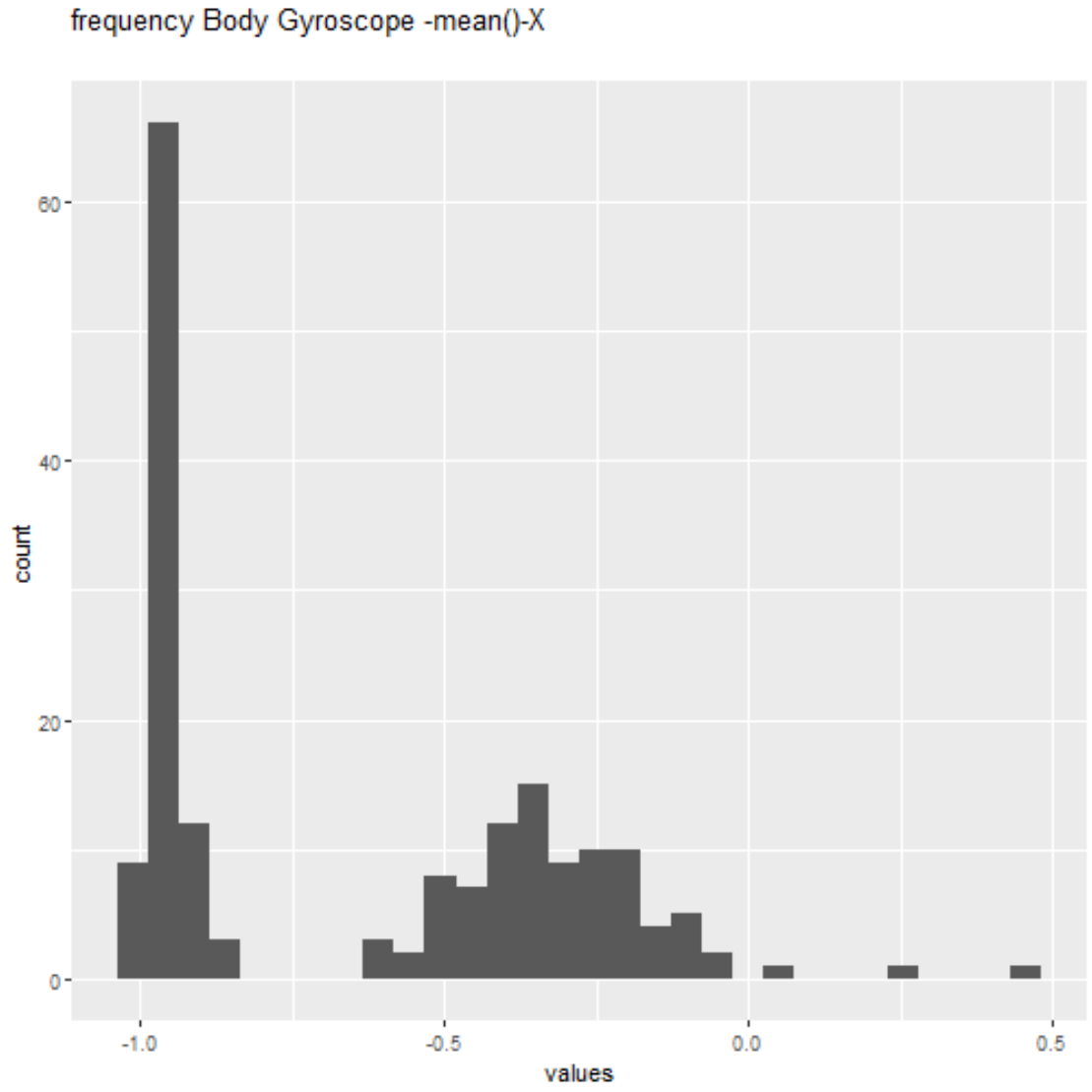
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body	numeric	0	180	180	-0.72	0.2	-1.	-0.	-0.	-0.	-0.	<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>

Accelerometer Jerk-std()-Z			6	6	9 9	9 8	9	5 4	62			

frequency Body Gyroscope -mean()-X

Distribution



plot of chunk distribution

0 missing values.

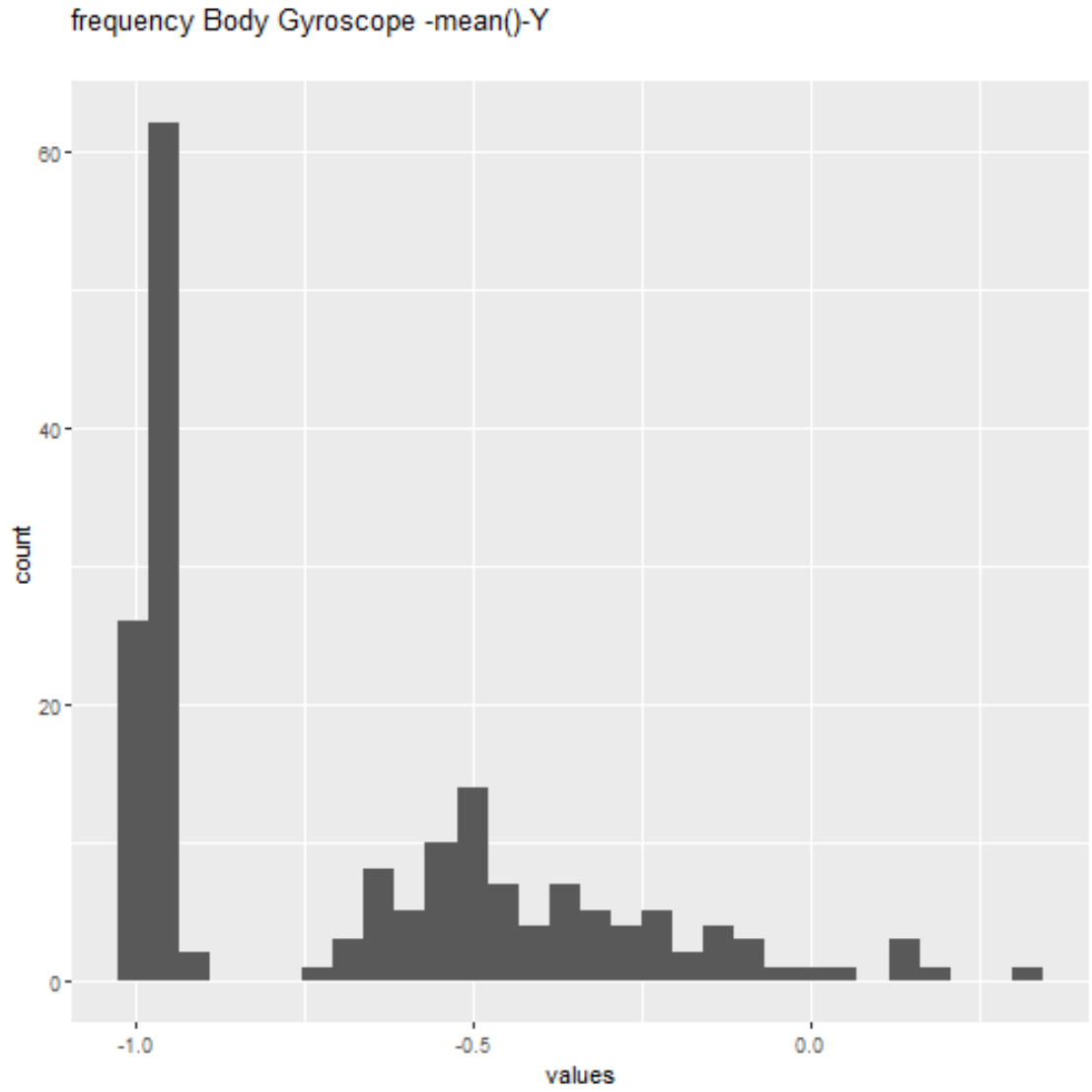
Summary statistics

na	dat	mi	co	n	m	s	p	p	p	p	p	hist

me	a_type	ssing	mplete		ean	d	0	25	50	75	100	
frequency BodyGyroscope-mean()-X	numeric	0	1800	180	-0.64	0.35	-0.99	-0.97	-0.73	-0.34	0.47	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

frequency Body Gyroscope -mean()-Y

Distribution



plot of chunk distribution

0 missing values.

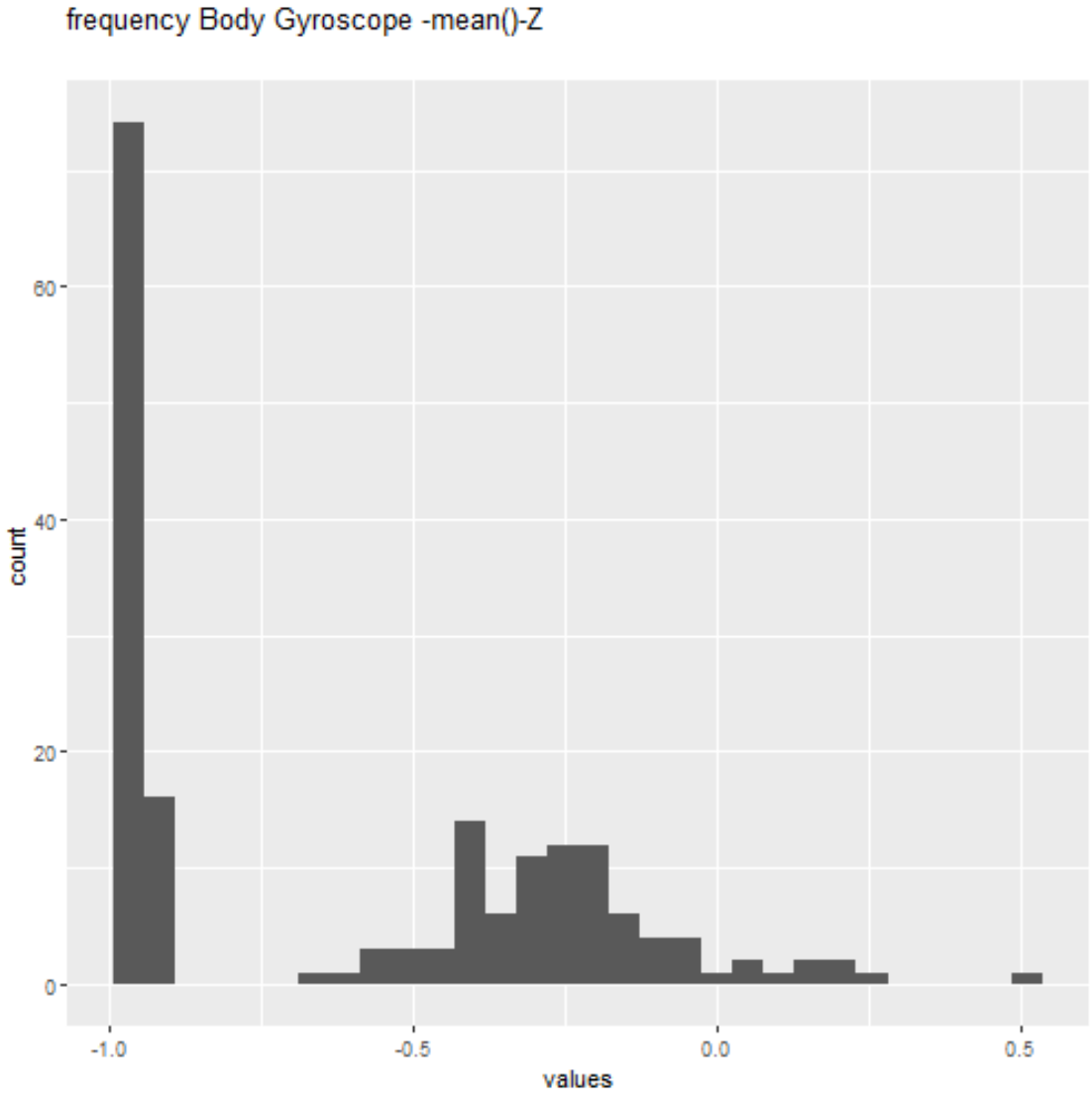
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency	numeric	0	180	180	-0.06	0.33	-0.99	-0.98	-0.84	-0.43	0.33	<U+2587><U+2581><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581>

Body Gyroscope -mean()-Y	8	9	7	1	5

frequency Body Gyroscope -mean()-Z

Distribution



plot of chunk distribution

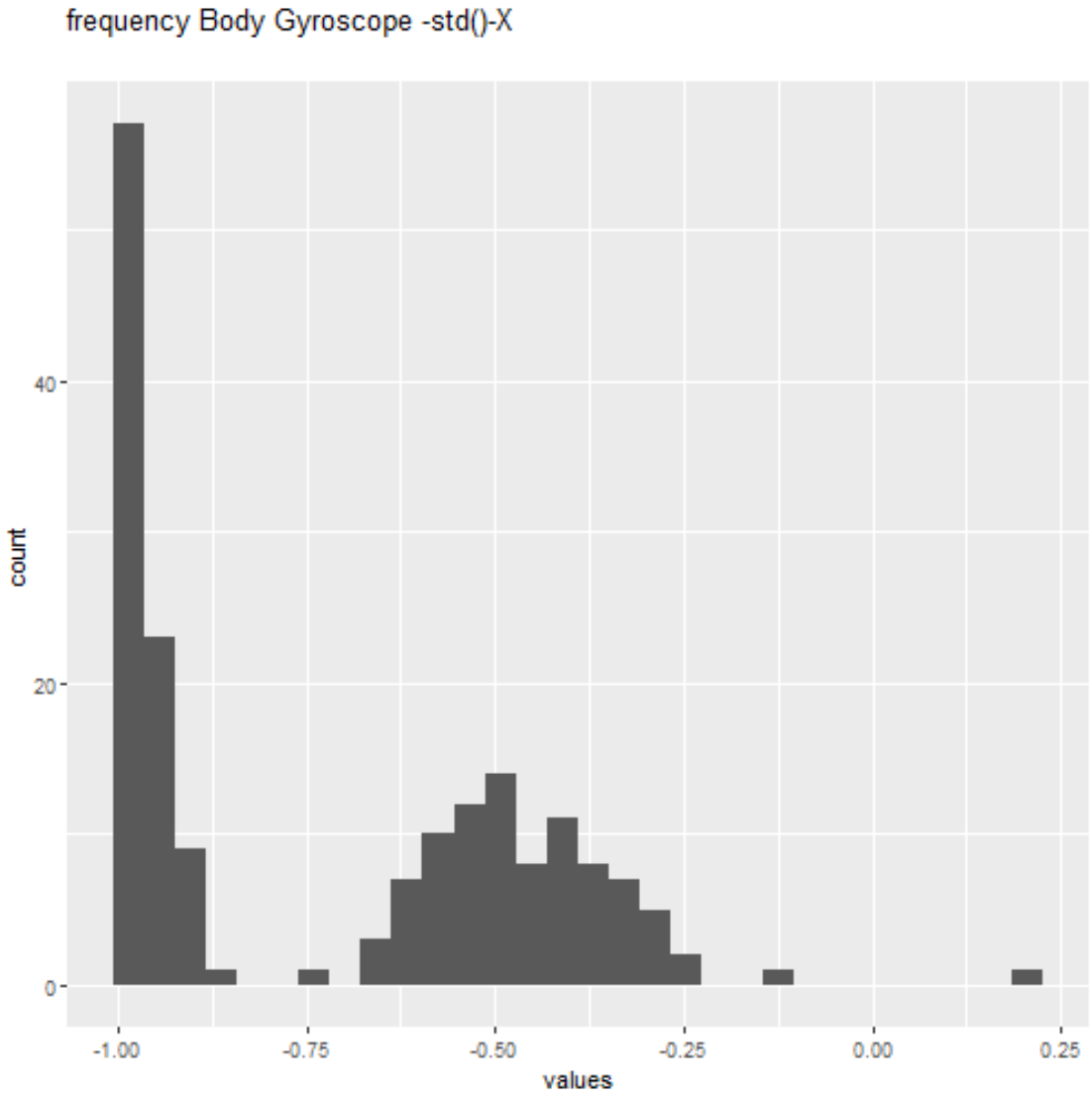
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body Gyroscope-mean()-Z	numeric	0	180	180	-0.6	0.38	-0.999	-0.996	-0.979	-0.26	0.49	<U+2587><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581>

frequency Body Gyroscope -std()-X

Distribution



plot of chunk distribution

0 missing values.

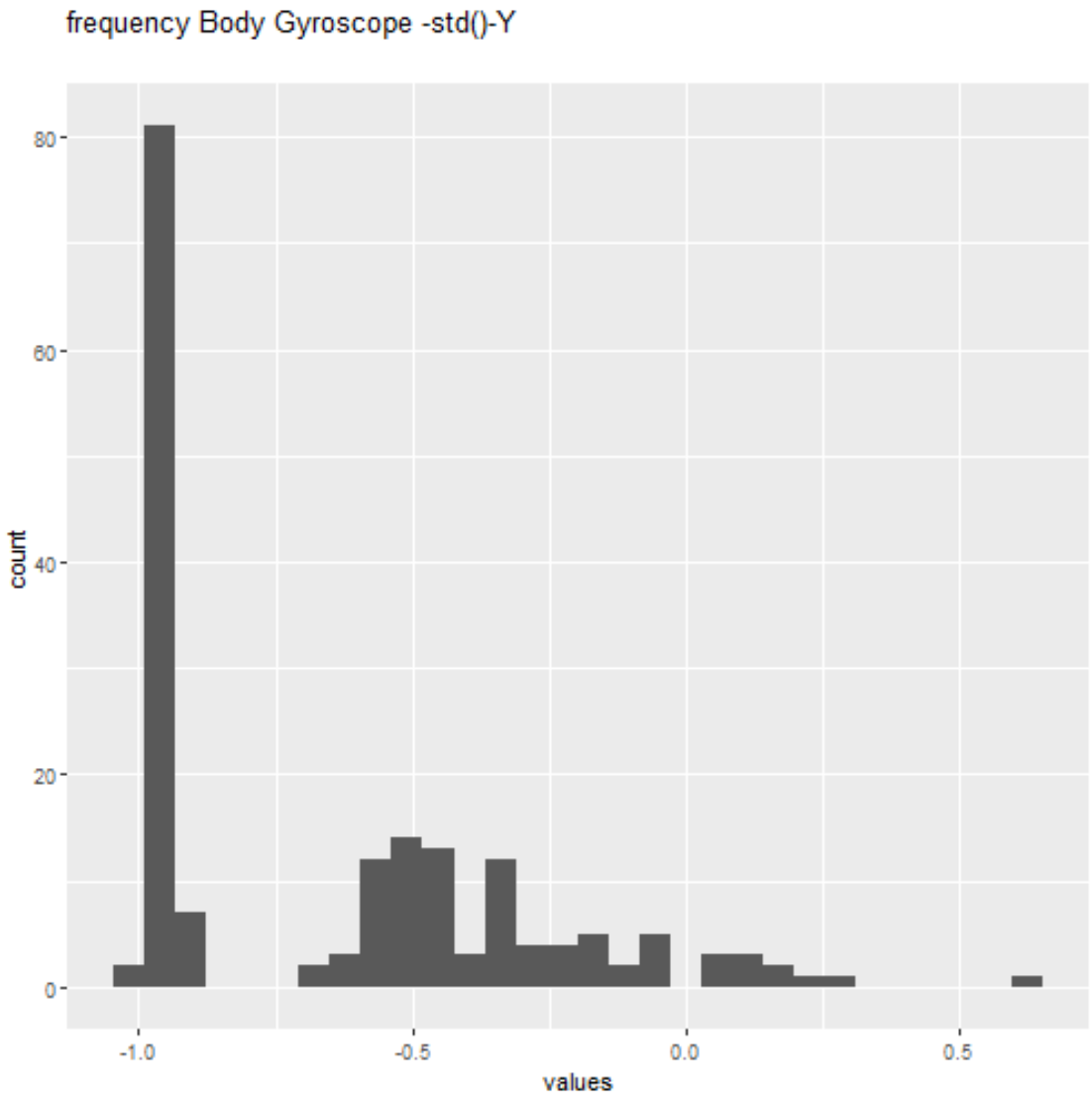
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency	numeric	0	180	180	-0.07	0.27	-0.9	-0.9	-0.8	-0.4	0.2	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

Body Gyroscope -std()-X	1	9	8	1	8	

frequency Body Gyroscope -std()-Y

Distribution



plot of chunk distribution

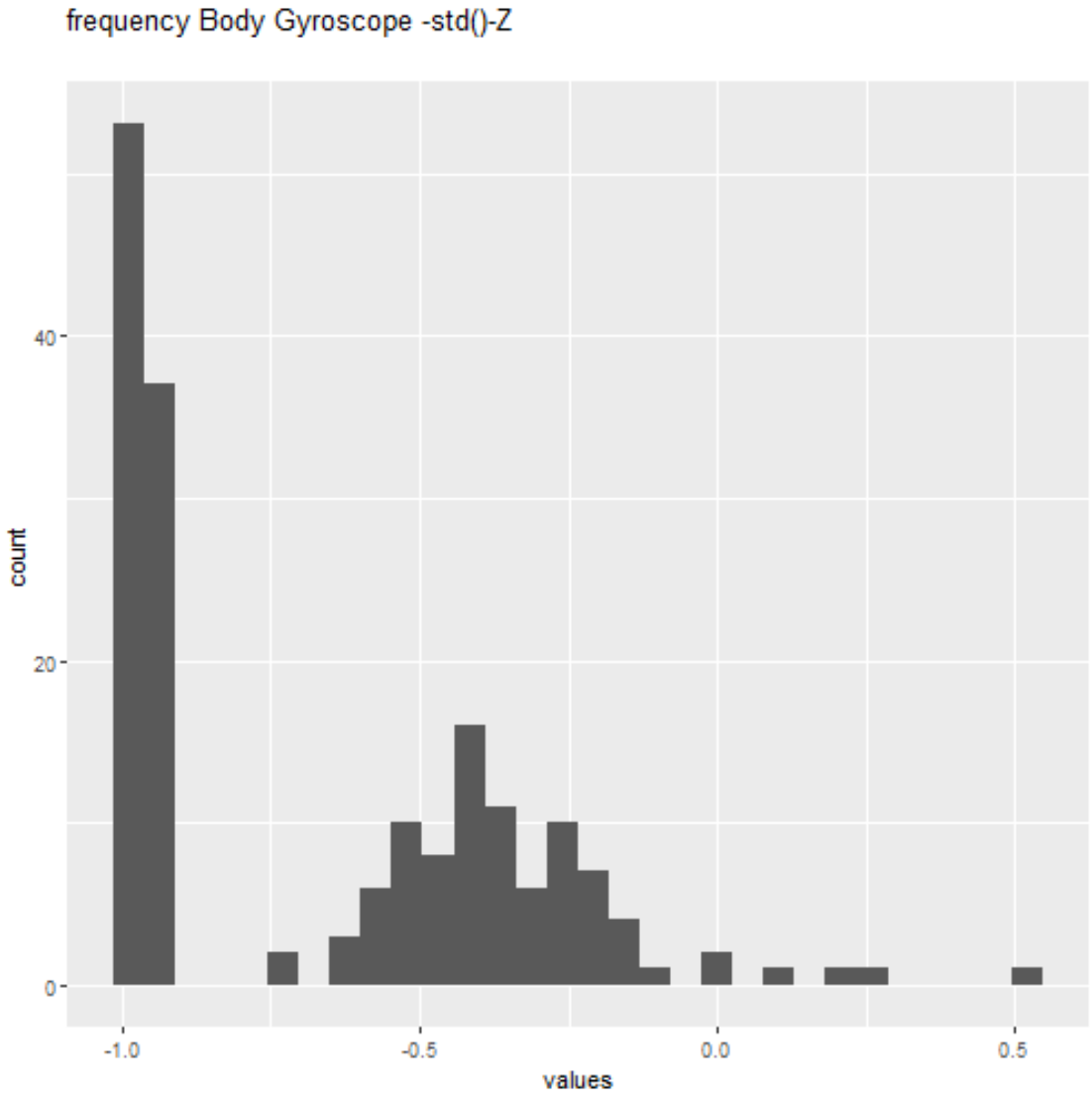
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body Gyroscope-std()-Y	numeric	0	180	180	-0.065	0.36	-0.99	-0.996	-0.8	-0.42	0.65	<U+2587><U+2581><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581>

frequency Body Gyroscope -std()-Z

Distribution



plot of chunk distribution

0 missing values.

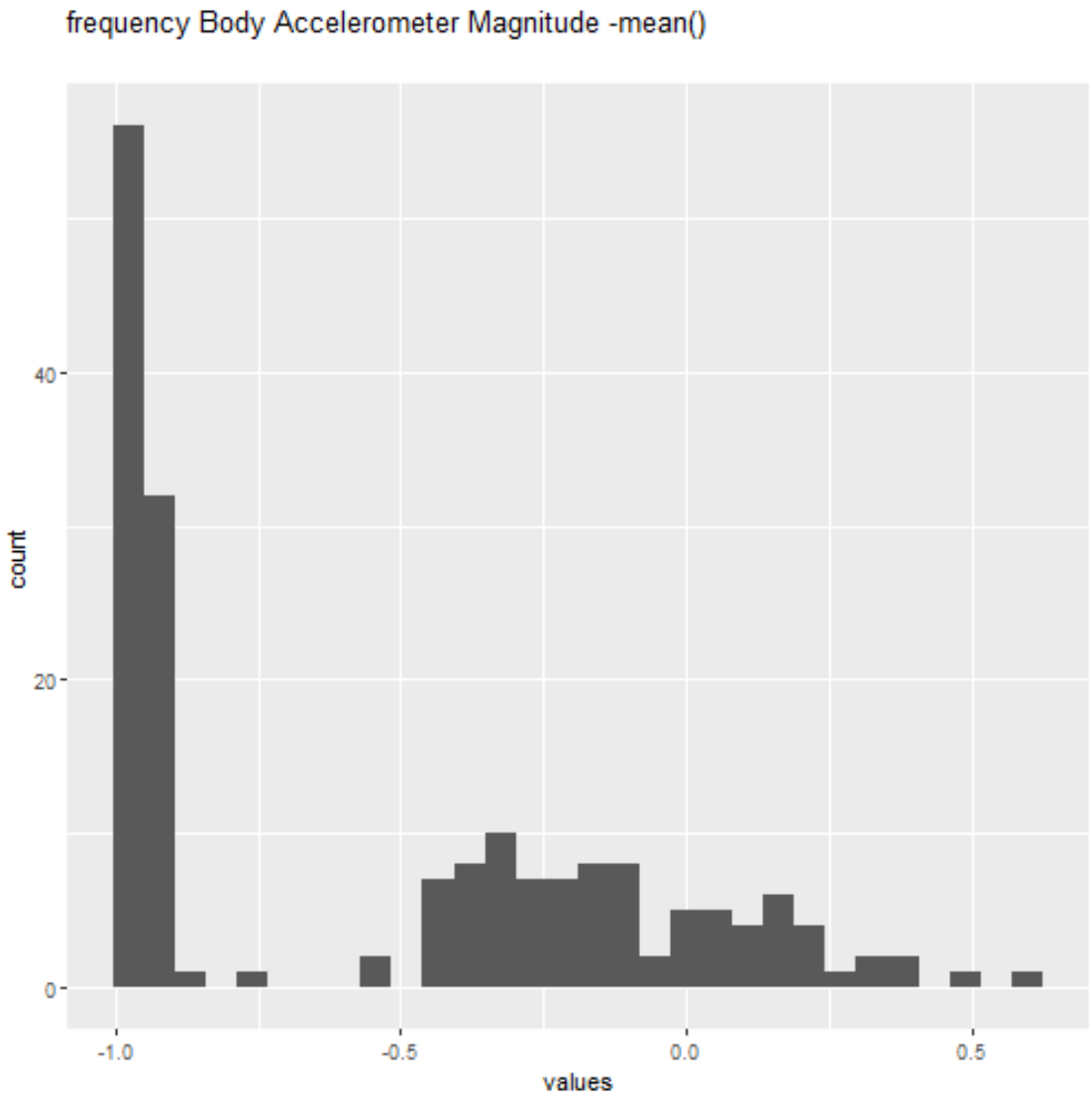
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency	numeric	0	180	180	-0.06	0.34	-0.99	-0.98	-0.83	-0.32	0.52	<U+2587><U+2581><U+2583><U+2583><U+2581><U+2581><U+2581>

Body Gyroscope-std()-Z	6	9	6	2	9	

frequency Body Accelerometer Magnitude -mean()

Distribution



plot of chunk distribution

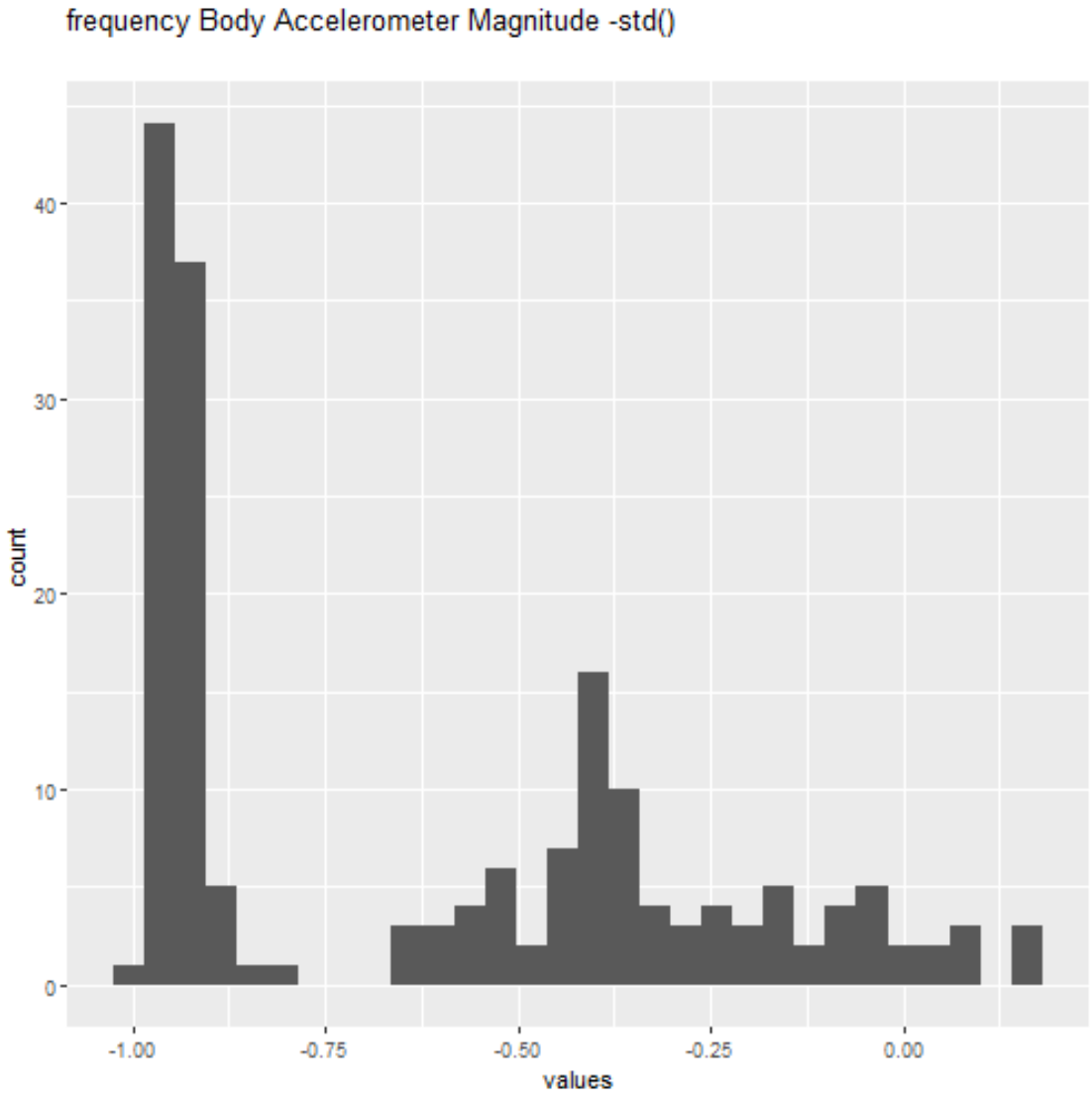
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body Accelerometer Magnitude-mean()	numeric	0	180	180	-0.54	0.45	-0.99	-0.96	-0.67	-0.16	0.59	<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581>

frequency Body Accelerometer Magnitude -std()

Distribution



plot of chunk distribution

0 missing values.

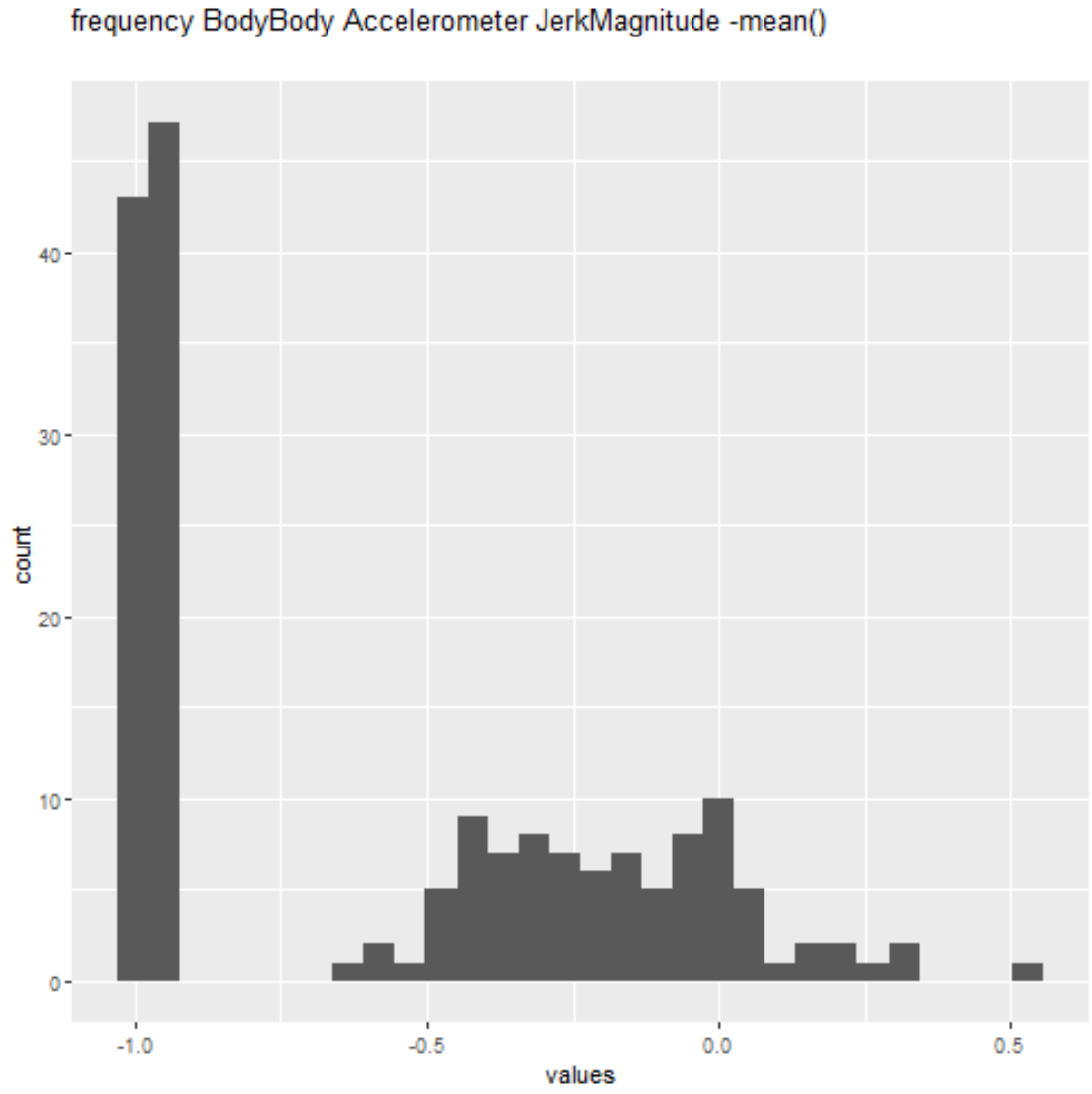
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body	numeric	0	180	180	-0.63	0.31	-1	-0.85	-0.71	-0.48	0.18	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2581><U+2581>

Accelerometer Magnitude -std()			2	5	9 9	9 5	6 5	3 7			

frequency BodyBody Accelerometer JerkMagnitude -mean()

Distribution



plot of chunk distribution

0 missing values.

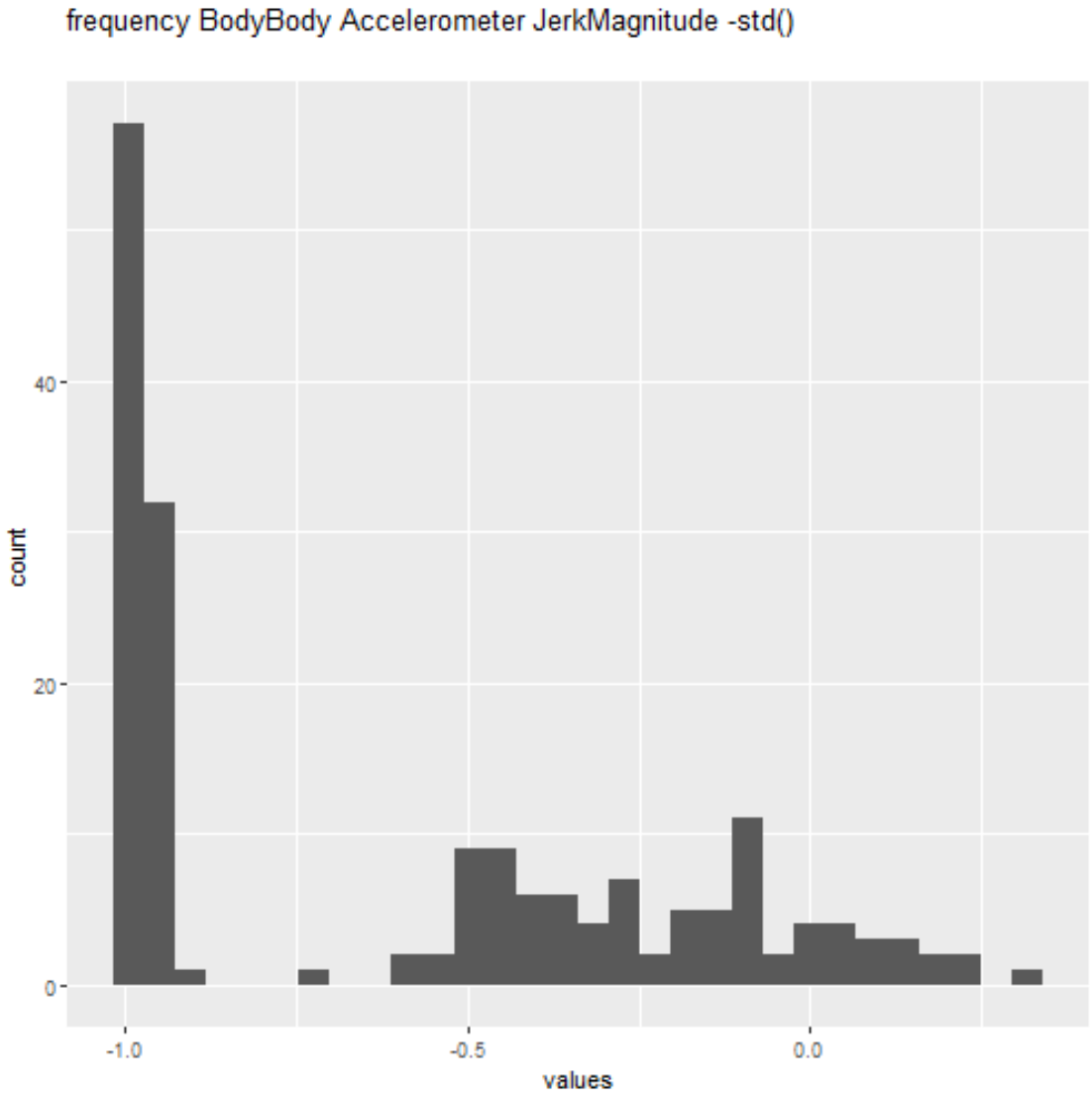
Summary statistics

name	dat	mi	co	n	m	s	p	p	p	p	p	hist

	a_type	ssing	mplete		ean	d	0	25	50	75	100	
frequency BodyBodyAccelerometerJerkMagnitude-mean()	numeric	0	1800	180	-0.58	0.43	-0.99	-0.98	-0.79	-0.19	0.54	<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>

frequency BodyBody Accelerometer JerkMagnitude -std()

Distribution



plot of chunk distribution

0 missing values.

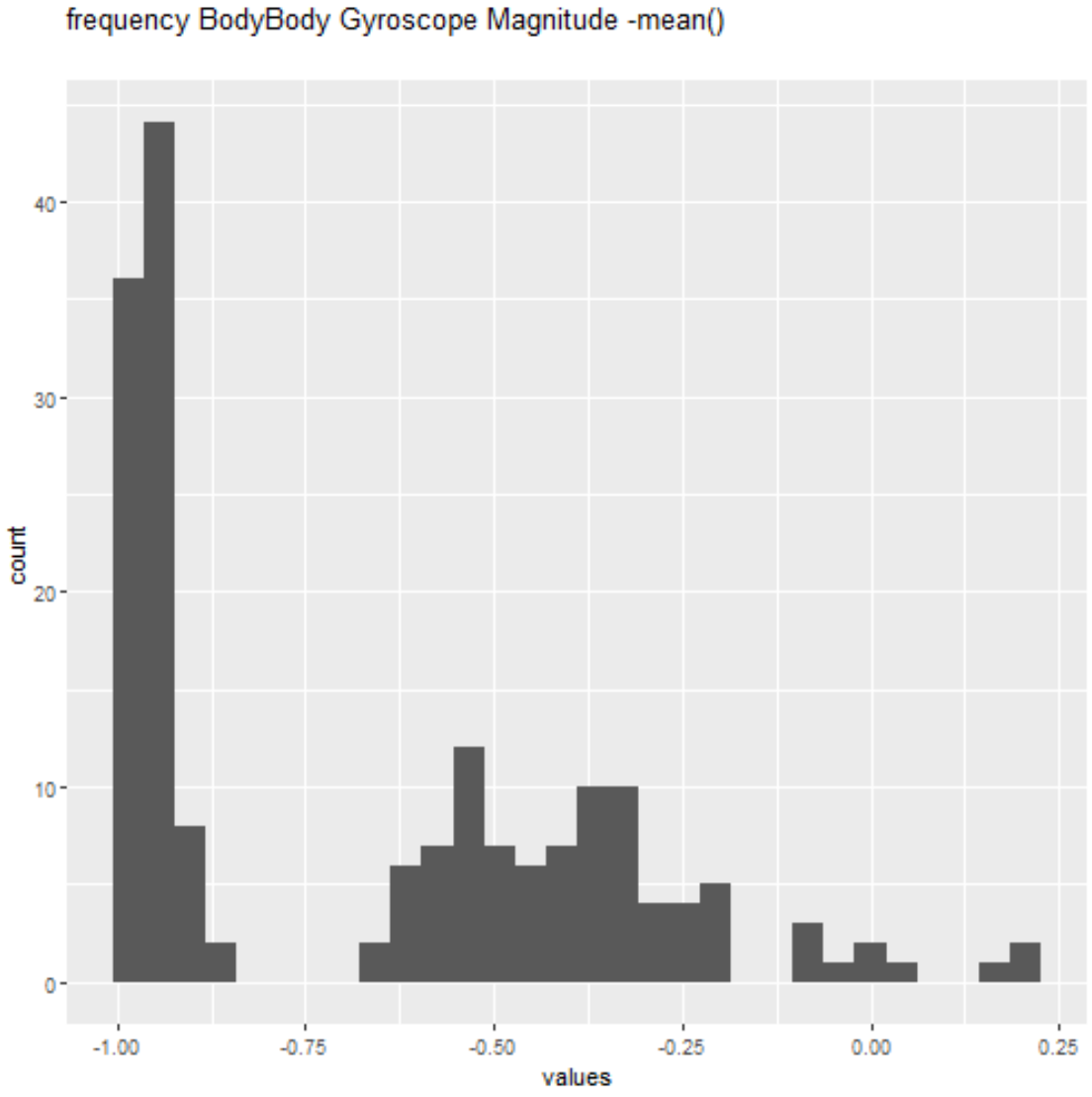
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body	numeric	0	180	180	-0.606	0.4	.	.	.	.	0.32	<U+2587><U+2581><U+2581><U+2582><U+2581><U+2582><U+2581><U+2581>

Body Accelerometer JerkMagnitude -std()	1	9	9	8	2	
		9	8	1	7	

frequency BodyBody Gyroscope Magnitude -mean()

Distribution



plot of chunk distribution

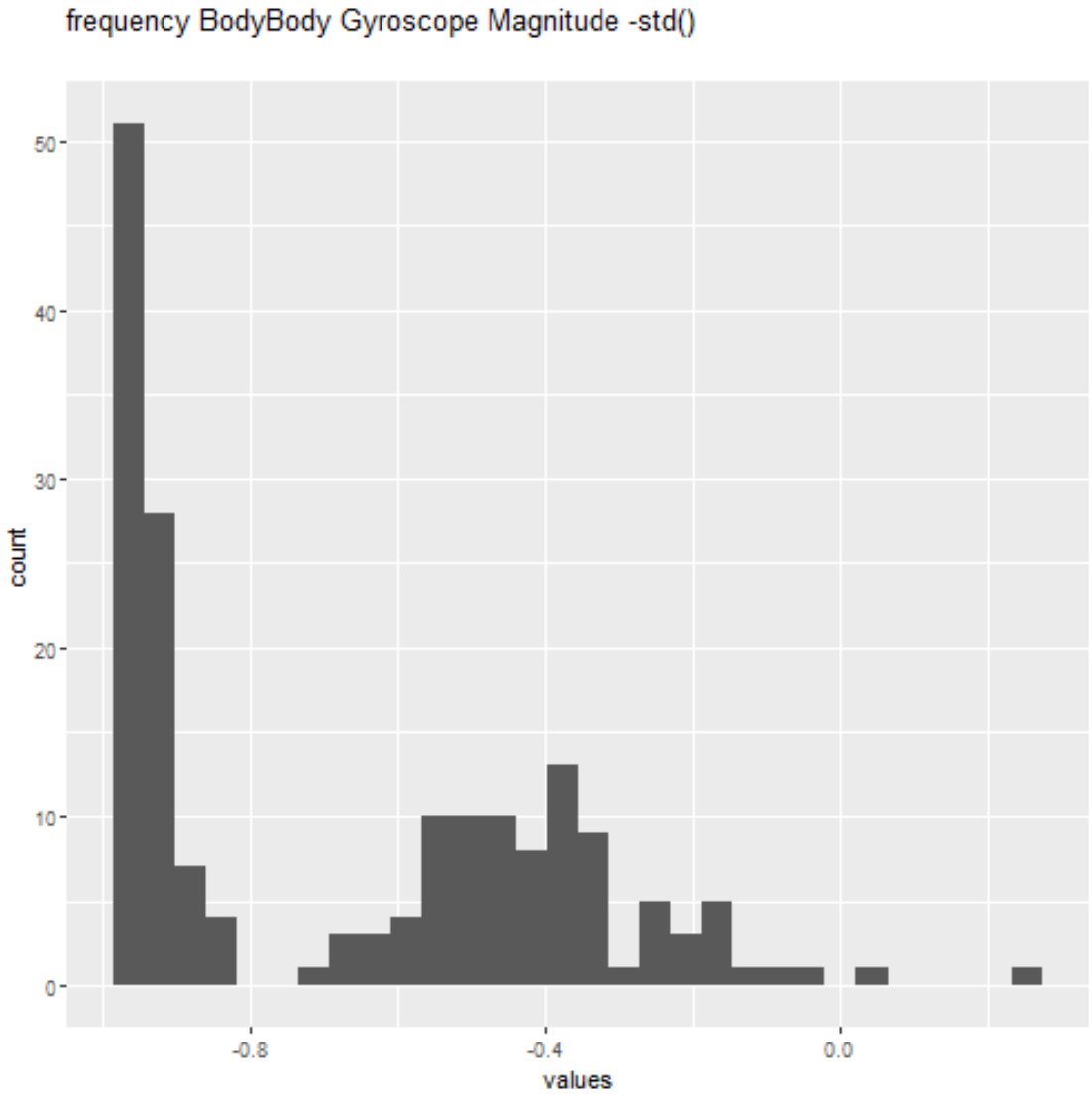
0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency BodyBody GyroscopeMagnitude - mean()	numeric	0	180	180	-0.67	0.32	-0.99	-0.96	-0.77	-0.41	0.2	<U+2587><U+2581><U+2582><U+2582><U+2582><U+2582><U+2581><U+2581>

frequency BodyBody Gyroscope Magnitude -std()

Distribution



plot of chunk distribution

0 missing values.

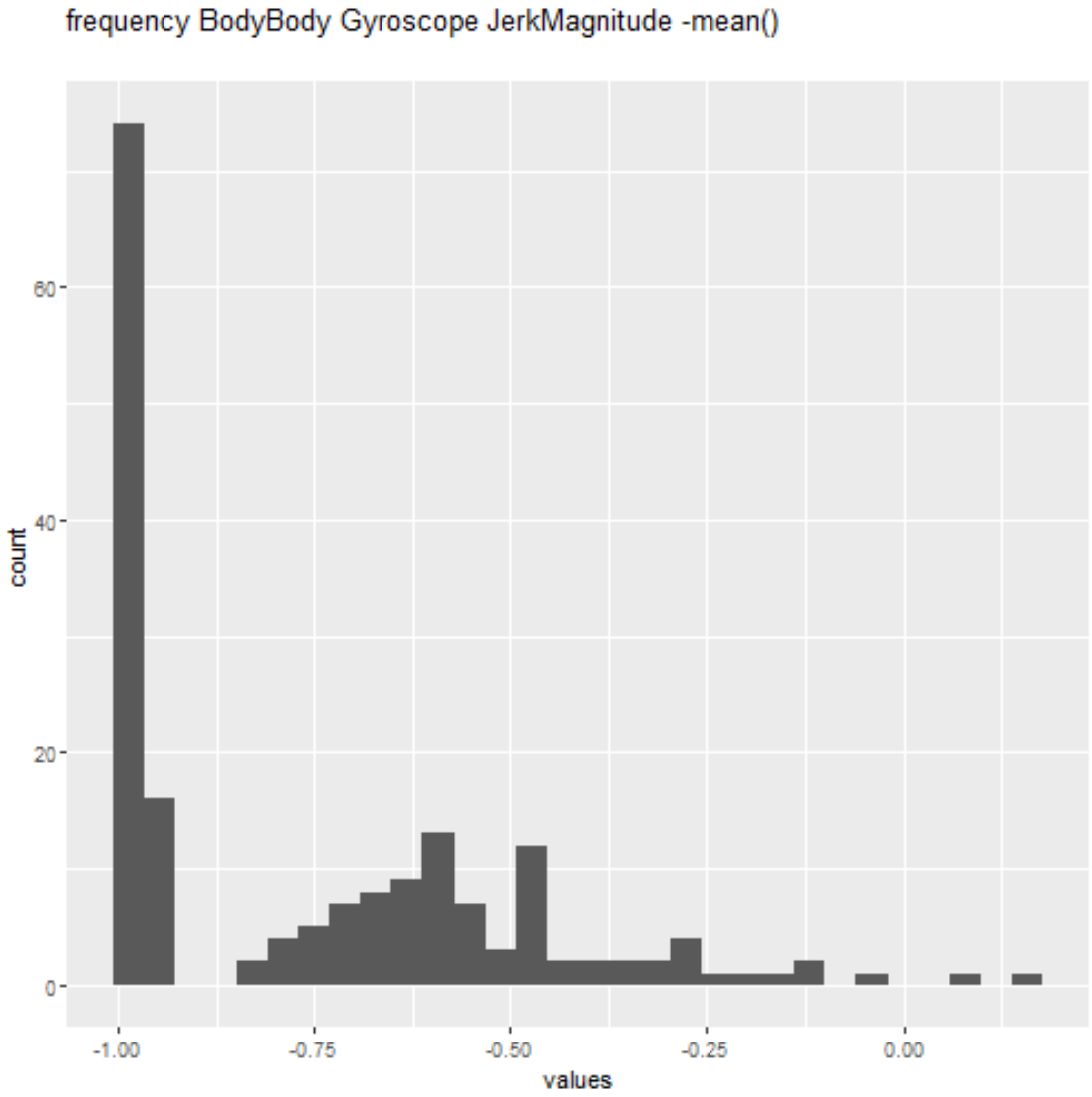
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency	numeric	0	180	180	-0.06	0.29	-0.9	-0.9	-0.7	-0.4	0.24	<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

BodyBodyGyroscopeMagnitude-std()	7	8	5	7	3	

frequency BodyBody Gyroscope JerkMagnitude -mean()

Distribution



plot of chunk distribution

0 missing values.

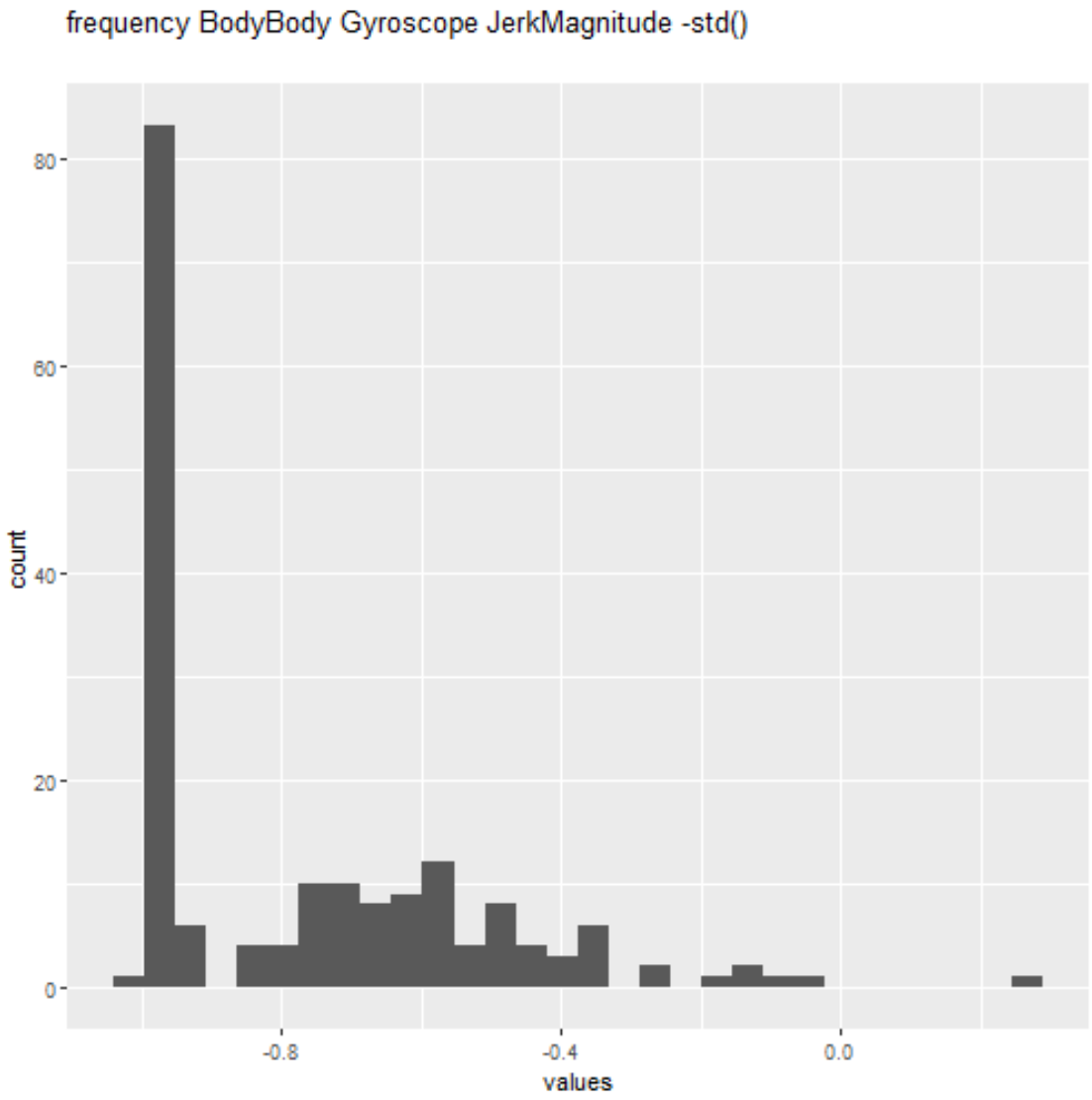
Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency BodyBody Gyroscope JerkMagnitude -mean()	numeric	0	180	180	-0.76	0.26	-1	-0.99	-0.98	-0.55	0.15	<U+2587><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

Body Gyroscope JerkMagnitude - mean() 6 8 8 8

frequency BodyBody Gyroscope JerkMagnitude -std()

Distribution



plot of chunk distribution

0 missing values.

Summary statistics

name	data_type	missing	complete	n	mean	sd	p0	p25	p50	p75	p100	hist
frequency Body Body Gyroscope JerkMagnitude - std()	numeric	0	180	180	-0.77	0.25	-1	-0.98	-0.89	-0.61	0.29	<U+2587><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>

Missingness report

Codebook table

```
## PhantomJS not found. You can install it with webshot::install_phantomjs().
If it is installed, please make sure the phantomjs executable can be found
via the PATH variable.

## Warning in normalizePath(path.expand(path), winslash, mustWork):
## path[1]="webshot3d28ac16c0a.png": The system cannot find the file
specified

## Warning in file(con, "rb"): cannot open file 'C:
##
\Users\dendluri\AppData\Local\Temp\Rtmp4imiJj\file3d281363290b\webshot3d28ac1
6c0a.png':
## No such file or directory

## Error in file(con, "rb"): cannot open the connection
```

JSON-LD metadata The following JSON-LD can be found by search engines, if you share this codebook publicly on the web.


```
{
  "name": "dataset",
  "datePublished": "2019-05-05",
  "description": "The dataset has N=180 rows and 68 columns.\n180 rows have
no missing values on any column.\n\n\n## Table of variables\nThis table
contains variable names, labels, their central tendencies and other
attributes.\n\n|name
|data_type |missing |complete |n   |empty |n_unique |min |max |mean   |sd
|p0     |p25     |p50     |p75    |p100    |hist     |\n|:-------------------
-----------------------------------|:---------|:-------|:--------|:---|:-----
```

```
|:--------|:---|:---|:------|:------|:------|:-------|:-------|:------|:------|:--------|\n|activity
|character |0       |180      |180 |0     |6        |6   |18  |NA     |NA
|NA     |NA      |NA      |NA      |NA      |NA       |\n|subject
|integer   |0       |180      |180 |NA    |NA       |NA  |NA  |15.5   |8.68
|1      |8       |15.5    |23     |30
|<U+2587><U+2587><U+2586><U+2587><U+2587><U+2586><U+2587><U+2587> |\n|time
Body Accelerometer -mean()-X                       |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |0.27   |0.012  |0.22   |0.27    |0.28
|0.28   |0.3
|<U+2581><U+2581><U+2581><U+2581><U+2582><U+2587><U+2582><U+2581> |\n|time
Body Accelerometer -mean()-Y                       |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.018 |0.0058 |-0.041 |-0.02   |-0.017  |-
0.015 |-0.0013
|<U+2581><U+2581><U+2582><U+2582><U+2587><U+2583><U+2581><U+2581> |\n|time
Body Accelerometer -mean()-Z                       |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.11  |0.0096 |-0.15  |-0.11   |-0.11   |-
0.1   |-0.075
|<U+2581><U+2581><U+2581><U+2582><U+2587><U+2583><U+2581><U+2581> |\n|time
Body Accelerometer -std()-X                        |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.56  |0.45   |-1     |-0.98   |-0.75   |-
0.2   |0.63
|<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581> |\n|time
Body Accelerometer -std()-Y                        |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.46  |0.5    |-0.99  |-0.94   |-0.51   |-
0.031 |0.62
|<U+2587><U+2581><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581> |\n|time
Body Accelerometer -std()-Z                        |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.58  |0.4    |-0.99  |-0.95   |-0.65   |-
0.23  |0.61
|<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581> |\n|time
Gravity Accelerometer -mean()-X                    |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |0.7    |0.49   |-0.68  |0.84    |0.92
|0.94   |0.97
|<U+2581><U+2581><U+2581><U+2581><U+2581><U+2581><U+2581><U+2587> |\n|time
Gravity Accelerometer -mean()-Y                    |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.016 |0.35   |-0.48  |-0.23   |-0.13
|0.088  |0.96
|<U+2582><U+2587><U+2585><U+2582><U+2581><U+2581><U+2581><U+2581> |\n|time
Gravity Accelerometer -mean()-Z                    |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |0.074  |0.29   |-0.5   |-0.12   |0.024
|0.15   |0.96
|<U+2581><U+2585><U+2587><U+2586><U+2581><U+2581><U+2581><U+2581> |\n|time
Gravity Accelerometer -std()-X                     |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.96  |0.025  |-1     |-0.98   |-0.97   |-
0.95  |-0.83
|<U+2587><U+2586><U+2585><U+2582><U+2581><U+2581><U+2581><U+2581> |\n|time
Gravity Accelerometer -std()-Y                     |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.95  |0.033  |-0.99  |-0.97   |-0.96   |-
0.94  |-0.64
```

```
|<U+2587><U+2585><U+2581><U+2581><U+2581><U+2581><U+2581><U+2581> |\n|time
Gravity Accelerometer -std()-Z                    |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.94  |0.04   |-0.99  |-0.96   |-0.95   |-
0.92  |-0.61
|<U+2587><U+2586><U+2582><U+2581><U+2581><U+2581><U+2581><U+2581> |\n|time
Body Accelerometer Jerk-mean()-X                  |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |0.079  |0.013  |0.043  |0.074   |0.076
|0.083  |0.13
|<U+2581><U+2581><U+2587><U+2587><U+2582><U+2581><U+2581><U+2581> |\n|time
Body Accelerometer Jerk-mean()-Y                  |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |0.0076 |0.014  |-0.039 |0.00047 |0.0095
|0.013  |0.057
|<U+2581><U+2581><U+2582><U+2586><U+2587><U+2582><U+2581><U+2581> |\n|time
Body Accelerometer Jerk-mean()-Z                  |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.005 |0.013  |-0.067 |-0.011  |-0.0039
|0.002  |0.038
|<U+2581><U+2581><U+2581><U+2581><U+2587><U+2586><U+2581><U+2581> |\n|time
Body Accelerometer Jerk-std()-X                   |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.59  |0.42   |-0.99  |-0.98   |-0.81   |-
0.22  |0.54
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581> |\n|time
Body Accelerometer Jerk-std()-Y                   |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.57  |0.43   |-0.99  |-0.97   |-0.78   |-
0.15  |0.36
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581> |\n|time
Body Accelerometer Jerk-std()-Z                   |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.74  |0.28   |-0.99  |-0.98   |-0.88   |-
0.51  |0.031
|<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581> |\n|time
Body Gyroscope -mean()-X                          |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.032 |0.054  |-0.21  |-0.047  |-0.029  |-
0.017 |0.19
|<U+2581><U+2581><U+2582><U+2587><U+2581><U+2581><U+2581><U+2581> |\n|time
Body Gyroscope -mean()-Y                          |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.074 |0.036  |-0.2   |-0.09   |-0.073  |-
0.061 |0.027
|<U+2581><U+2581><U+2581><U+2583><U+2587><U+2582><U+2581><U+2581> |\n|time
Body Gyroscope -mean()-Z                          |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |0.087  |0.036  |-0.072 |0.075   |0.085
|0.1    |0.18
|<U+2581><U+2581><U+2581><U+2581><U+2587><U+2587><U+2582><U+2581> |\n|time
Body Gyroscope -std()-X                           |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.69  |0.29   |-0.99  |-0.97   |-0.79   |-
0.44  |0.27
|<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581> |\n|time
Body Gyroscope -std()-Y                           |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.65  |0.35   |-0.99  |-0.96   |-0.8    |-
0.42  |0.48
|<U+2587><U+2581><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581> |\n|time
Body Gyroscope -std()-Z                           |numeric   |0       |180
```

```
|180 |NA    |NA       |NA  |NA  |-0.62  |0.37   |-0.99  |-0.96   |-0.8    |-
0.31  |0.56
|<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581> |\n|time
Body Gyroscope Jerk-mean()-X                      |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.096 |0.023  |-0.16  |-0.1    |-0.099  |-
0.091 |-0.022
|<U+2581><U+2581><U+2581><U+2587><U+2581><U+2581><U+2581><U+2581> |\n|time
Body Gyroscope Jerk-mean()-Y                      |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.043 |0.0095 |-0.077 |-0.046  |-0.041  |-
0.038 |-0.013
|<U+2581><U+2581><U+2581><U+2582><U+2587><U+2582><U+2581><U+2581> |\n|time
Body Gyroscope Jerk-mean()-Z                      |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.055 |0.012  |-0.092 |-0.062  |-0.053  |-
0.049 |-0.0069
|<U+2581><U+2581><U+2583><U+2587><U+2583><U+2581><U+2581><U+2581> |\n|time
Body Gyroscope Jerk-std()-X                       |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.7   |0.3    |-1     |-0.98   |-0.84   |-
0.46  |0.18
|<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581> |\n|time
Body Gyroscope Jerk-std()-Y                       |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.76  |0.27   |-1     |-0.98   |-0.89   |-
0.59  |0.3
|<U+2587><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581><U+2581> |\n|time
Body Gyroscope Jerk-std()-Z                       |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.71  |0.3    |-1     |-0.98   |-0.86   |-
0.47  |0.19
|<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581> |\n|time
Body Accelerometer Magnitude -mean()              |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.5   |0.47   |-0.99  |-0.96   |-0.48   |-
0.092 |0.64
|<U+2587><U+2581><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581> |\n|time
Body Accelerometer Magnitude -std()               |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.54  |0.43   |-0.99  |-0.94   |-0.61   |-
0.21  |0.43
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2582><U+2581> |\n|time
Gravity Accelerometer Magnitude -mean()           |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.5   |0.47   |-0.99  |-0.96   |-0.48   |-
0.092 |0.64
|<U+2587><U+2581><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581> |\n|time
Gravity Accelerometer Magnitude -std()            |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.54  |0.43   |-0.99  |-0.94   |-0.61   |-
0.21  |0.43
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2582><U+2581> |\n|time
Body Accelerometer JerkMagnitude -mean()          |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.61  |0.4    |-0.99  |-0.98   |-0.82   |-
0.25  |0.43
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2581><U+2581> |\n|time
Body Accelerometer JerkMagnitude -std()           |numeric   |0       |180
|180 |NA    |NA       |NA  |NA  |-0.58  |0.42   |-0.99  |-0.98   |-0.8    |-
0.22  |0.45
```

|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581> |\n|time Body Gyroscope Magnitude -mean() |numeric |0 |180 |180 |NA |NA |NA |-0.57 |0.4 |-0.98 |-0.95 |-0.66 |-0.22 |0.42
|<U+2587><U+2581><U+2581><U+2582><U+2583><U+2581><U+2581><U+2581> |\n|time Body Gyroscope Magnitude -std() |numeric |0 |180 |180 |NA |NA |NA |-0.63 |0.34 |-0.98 |-0.95 |-0.74 |-0.36 |0.3
|<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581> |\n|time Body Gyroscope JerkMagnitude -mean() |numeric |0 |180 |180 |NA |NA |NA |-0.74 |0.28 |-1 |-0.99 |-0.86 |-0.51 |0.088
|<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581> |\n|time Body Gyroscope JerkMagnitude -std() |numeric |0 |180 |180 |NA |NA |NA |-0.76 |0.27 |-1 |-0.98 |-0.88 |-0.58 |0.25
|<U+2587><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581> |\n|frequency Body Accelerometer -mean()-X |numeric |0 |180 |180 |NA |NA |NA |-0.58 |0.43 |-1 |-0.98 |-0.77 |-0.22 |0.54
|<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581> |\n|frequency Body Accelerometer -mean()-Y |numeric |0 |180 |180 |NA |NA |NA |-0.49 |0.48 |-0.99 |-0.95 |-0.59 |-0.063 |0.52
|<U+2587><U+2581><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581> |\n|frequency Body Accelerometer -mean()-Z |numeric |0 |180 |180 |NA |NA |NA |-0.63 |0.36 |-0.99 |-0.96 |-0.72 |-0.32 |0.28
|<U+2587><U+2581><U+2581><U+2582><U+2583><U+2581><U+2581><U+2581> |\n|frequency Body Accelerometer -std()-X |numeric |0 |180 |180 |NA |NA |NA |-0.55 |0.46 |-1 |-0.98 |-0.75 |-0.2 |0.66
|<U+2587><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581><U+2581> |\n|frequency Body Accelerometer -std()-Y |numeric |0 |180 |180 |NA |NA |NA |-0.48 |0.47 |-0.99 |-0.94 |-0.51 |-0.079 |0.56
|<U+2587><U+2581><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581> |\n|frequency Body Accelerometer -std()-Z |numeric |0 |180 |180 |NA |NA |NA |-0.58 |0.39 |-0.99 |-0.95 |-0.64 |-0.27 |0.69
|<U+2587><U+2581><U+2582><U+2583><U+2581><U+2581><U+2581><U+2581> |\n|frequency Body Accelerometer Jerk-mean()-X |numeric |0 |180 |180 |NA |NA |NA |-0.61 |0.4 |-0.99 |-0.98 |-0.81 |-0.28 |0.47
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2581><U+2581> |\n|frequency Body Accelerometer Jerk-mean()-Y |numeric |0 |180 |180 |NA |NA |NA |-0.59 |0.41 |-0.99 |-0.97 |-0.78 |-0.2 |0.28
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581> |\n|frequency Body Accelerometer Jerk-mean()-Z |numeric |0

```
|180      |180 |NA    |NA       |NA  |NA  |-0.71  |0.3    |-0.99  |-0.98   |-
0.87   |-0.47  |0.16
|<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581>
|\n|frequency Body Accelerometer Jerk-std()-X              |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.61  |0.4    |-1     |-0.98   |-
0.83   |-0.25  |0.48
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>
|\n|frequency Body Accelerometer Jerk-std()-Y              |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.57  |0.43   |-0.99  |-0.97   |-
0.79   |-0.17  |0.35
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>
|\n|frequency Body Accelerometer Jerk-std()-Z              |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.76  |0.26   |-0.99  |-0.98   |-
0.9    |-0.54  |-0.0062
|<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581>
|\n|frequency Body Gyroscope -mean()-X                     |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.64  |0.35   |-0.99  |-0.97   |-
0.73   |-0.34  |0.47
|<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>
|\n|frequency Body Gyroscope -mean()-Y                     |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.68  |0.33   |-0.99  |-0.97   |-
0.81   |-0.45  |0.33
|<U+2587><U+2581><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581>
|\n|frequency Body Gyroscope -mean()-Z                     |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.6   |0.38   |-0.99  |-0.96   |-
0.79   |-0.26  |0.49
|<U+2587><U+2581><U+2581><U+2583><U+2582><U+2581><U+2581><U+2581>
|\n|frequency Body Gyroscope -std()-X                      |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.71  |0.27   |-0.99  |-0.98   |-
0.81   |-0.48  |0.2
|<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>
|\n|frequency Body Gyroscope -std()-Y                      |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.65  |0.36   |-0.99  |-0.96   |-
0.8    |-0.42  |0.65
|<U+2587><U+2581><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581>
|\n|frequency Body Gyroscope -std()-Z                      |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.66  |0.34   |-0.99  |-0.96   |-
0.82   |-0.39  |0.52
|<U+2587><U+2581><U+2583><U+2583><U+2581><U+2581><U+2581><U+2581>
|\n|frequency Body Accelerometer Magnitude -mean()         |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.54  |0.45   |-0.99  |-0.96   |-
0.67   |-0.16  |0.59
|<U+2587><U+2581><U+2581><U+2583><U+2582><U+2582><U+2581><U+2581>
|\n|frequency Body Accelerometer Magnitude -std()          |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.62  |0.35   |-0.99  |-0.95   |-
0.65   |-0.37  |0.18
|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2581><U+2581><U+2581>
|\n|frequency BodyBody Accelerometer JerkMagnitude -mean() |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.58  |0.43   |-0.99  |-0.98   |-
0.79   |-0.19  |0.54
```

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|<U+2587><U+2581><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581>
|\n|frequency BodyBody Accelerometer JerkMagnitude -std()  |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.6   |0.41   |-0.99  |-0.98   |-
0.81   |-0.27  |0.32
|<U+2587><U+2581><U+2581><U+2582><U+2581><U+2582><U+2581><U+2581>
|\n|frequency BodyBody Gyroscope Magnitude -mean()         |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.67  |0.32   |-0.99  |-0.96   |-
0.77   |-0.41  |0.2
|<U+2587><U+2581><U+2582><U+2582><U+2582><U+2581><U+2581><U+2581>
|\n|frequency BodyBody Gyroscope Magnitude -std()          |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.67  |0.29   |-0.98  |-0.95   |-
0.77   |-0.43  |0.24
|<U+2587><U+2581><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581>
|\n|frequency BodyBody Gyroscope JerkMagnitude -mean()     |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.76  |0.26   |-1     |-0.98   |-
0.88   |-0.58  |0.15
|<U+2587><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581>
|\n|frequency BodyBody Gyroscope JerkMagnitude -std()      |numeric   |0
|180      |180 |NA    |NA       |NA  |NA  |-0.77  |0.25   |-1     |-0.98   |-
0.89   |-0.61  |0.29
|<U+2587><U+2582><U+2583><U+2582><U+2581><U+2581><U+2581><U+2581> |\n\n###
Note\nThis dataset was automatically described using the [codebook R
package](https://rubenarslan.github.io/codebook/) (version 0.8.0.9000).",
  "keywords": ["activity", "subject", "time Body Accelerometer -mean()-X",
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Jerk-std()-Y", "time Body Accelerometer Jerk-std()-Z", "time Body Gyroscope -
mean()-X", "time Body Gyroscope -mean()-Y", "time Body Gyroscope -mean()-Z",
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mean()-Z", "frequency Body Accelerometer -std()-X", "frequency Body
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Body Accelerometer Jerk-mean()-X", "frequency Body Accelerometer Jerk-mean()-
Y", "frequency Body Accelerometer Jerk-mean()-Z", "frequency Body
```

```
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"frequency Body Accelerometer Jerk-std()-Z", "frequency Body Gyroscope -
mean()-X", "frequency Body Gyroscope -mean()-Y", "frequency Body Gyroscope -
mean()-Z", "frequency Body Gyroscope -std()-X", "frequency Body Gyroscope -
std()-Y", "frequency Body Gyroscope -std()-Z", "frequency Body Accelerometer
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Accelerometer JerkMagnitude -std()", "frequency BodyBody Gyroscope Magnitude
-mean()", "frequency BodyBody Gyroscope Magnitude -std()", "frequency
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