

WILDFIRE SPREADING MODEL USING A PARALLEL IMPLEMENTATION OF CELLULAR AUTOMATA

ADVANCED APPLIED PARALLEL PROGRAMMING

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OUTLINE

1 INTRODUCTION

2 PROBLEM

- Formalization
- Solution

3 RESULTS

- Evaluation
- Validation/Discussion
- Conclusion
- Future Work



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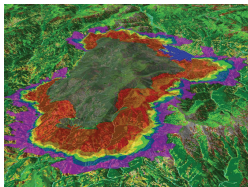
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FORMALIZATION

PROBLEM

Build a suitable model to be incorporated into a video-game-based simulator to allow assessment of decision making during wildfire combat involving different agencies which are part of the response system in Chile.



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- The fire model was constructed integrating environmental factors, forest fuel, topography with a discrete model based in Cellular Automata (CA) which interact and evolve in discrete time steps.
- To include the dynamic component, it was necessary to enhance the computation of the model with parallel computing techniques.



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- **Topography:** It influences over the two above factors, the fuel and weather, modifying or altering them.



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- Neighborhood: This CA model use the Moore Neighborhood, defined as

$$N_{(i_0, j_0)}^M = \{(i, j) : |i - i_0| \leq r, |j - j_0| \leq r\}. \quad (1)$$

for a cell (i_0, j_0) in a radius $r = 1$.



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- Cell States: In this work we use $S_{i,j} \in \{0, 1, 2, 3, 4\}$ where nonflammable = 0; flammable = 1; burning = 2; burnt = 3; extinguished = 4.



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- Transition Function: $F : DW \rightarrow S$ where,

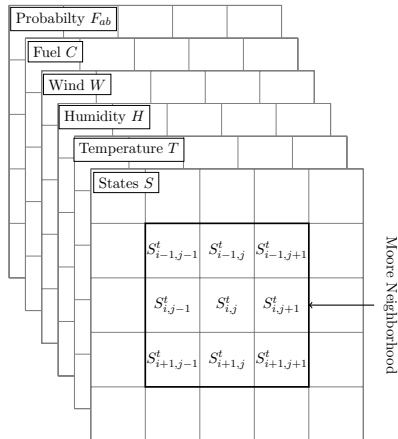


SOLUTION

DW is a discretized world that contains states S , temperature T , humidity H , wind speed W_s and direction W_d , fuel C and the probability threshold of change from state a to b F_{ab} . All this variables are matrices with values between 0 to 1.



SOLUTION

FIGURE: Discrete World DW .

SOLUTION

Formally, we define the transition as

$$S_{i,j}^{t+1} = \begin{cases} 2, & \text{if } S_{i,j}^t = 1 \text{ and } f_{12} \geq F_{12} \\ 2, & \text{if } S_{i,j}^t = 4 \text{ and } f_{42} \leq F_{42} \\ 3, & \text{if } S_{i,j}^t = 2 \text{ and } f_{23} \leq F_{23} \\ 4, & \text{if } S_{i,j}^t = 3 \text{ and } f_{24} \leq F_{24} \end{cases}, \quad (2)$$

where functions f are defined by



SOLUTION

- Function f_{12} :
 - The environmental factors E :

$$E_{i,j} = \frac{W_{d_{i,j}} C_{i,j} T_{i,j} W_{s_{i,j}}}{H_{i,j} P_{i,j}}. \quad (3)$$

- The burning states of neighborhood $p(N_b)$:

$$p(N_b)_{i,j} = \frac{N_b}{8}, \quad (4)$$

where N_b is the number of burning state neighboring cells.
Then, f_{12} is computed by

$$f_{12} = \alpha E_{i,j} + \beta p(N_b)_{i,j}. \quad (5)$$

- Functions f_{23}, f_{24}, f_{42} are random values between 0 and 1
and F_{23}, F_{24}, F_{42} are threshold parameters.



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- The development of the algorithm needs to perform a tessellation of the area to be simulated, where each cell represents the state of a square portion of the terrain.
- The model works with a world discretized by layers (DW), where each layer contains the information of the components described before.



ALGORITHM

Algorithm 1 Main Algorithm

$S^0 \leftarrow$ Initialize cell's states.
 $DW \leftarrow$ Initialize discrete world.
for $t = 0$ to T_{max} **do**
 $S^{t+1} \leftarrow \text{spreading}(S^t, DW)$
end for



ALGORITHM

Algorithm 2 Spreading Algorithm

```
procedure SPREADING( $S^t, DW$ )  
   $N \leftarrow$  number of rows in  $DW$   
  for  $i = 0$  to  $N_{threads} - 1$  do  
     $delta \leftarrow N / N_{threads}$   
     $start \leftarrow i \cdot delta$   
    if  $i = N_{threads} - 1$  then  
       $end \leftarrow N$   
    else  
       $end \leftarrow (i + 1) \cdot delta$   
    end if  
     $S \leftarrow subSpreading(start, end, S^t, DW)$   
  end for  
  for  $i = 0$  to  $N_{threads} - 1$  do  
    Thread's join  
  end for  
  return  $S$   
end procedure
```



ALGORITHM

Algorithm 3 Sub-spreading Algorithm

procedure SUBSPREADING($start, end, S^t, DW$) $N \leftarrow$ number of columns in DW .**for** $i = start$ to end **do****for** $j = 0$ to N **do** Compute $S_{i,j}^t$ using equation (2) with S^t and DW . **end for****end for****return** $S_{i,j}^t$ **end procedure**



ALGORITHM

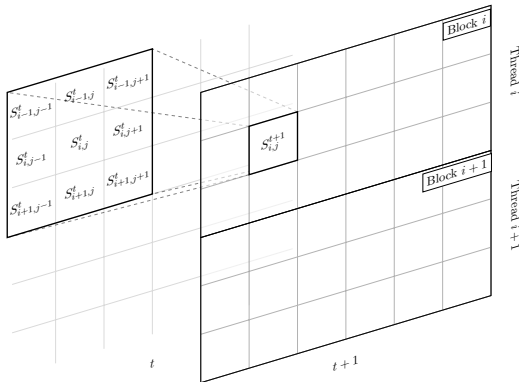


FIGURE: *SubSpreading* computing a matrix block.



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- Using a square grid of size $N \times N$ and defining the maximum number of discrete times T_{max} we estimate a computational complexity of $O(T_{max} \cdot N^2)$.



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- If we choose $T_{max} \ll N$ the complexity is about $O(N^2)$, but it may change a lot if $T_{max} \sim N$ increasing the complexity to $O(N^3)$.
- This is the main motivation of to include the use of threads in the computing of the model.



EVALUATION

The experiments were made using a fixed $T_{max} = 50$, for 1 to 4 number of threads, repeating the simulations 10 times per N .

TABLE: Summary of the average times in seconds.

Threads	$N = 100$	$N = 500$	$N = 1000$	$N = 1500$
1	0.198	8.023	32.861	72.464
2	0.135	5.147	19.695	44.407
3	0.163	4.825	18.852	41.626
4	0.220	4.650	18.055	41.458



EVALUATION

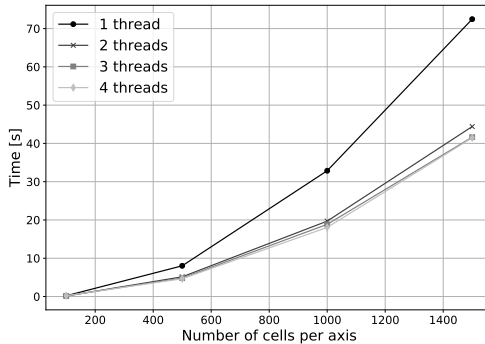


FIGURE: Threads' performance comparison.



EVALUATION

TABLE: Speedups results.

Threads	$N = 100$	$N = 500$	$N = 1000$	$N = 1500$
2	1.47	1.56	1.67	1.63
3	1.21	1.66	1.74	1.74
4	0.90	1.73	1.82	1.75



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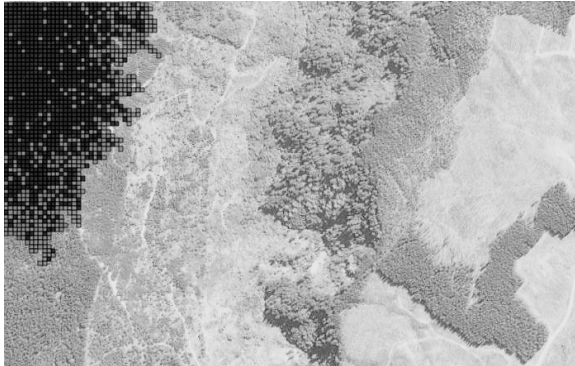


FIGURE: piece of map simulated for $N = 1500$, $T = 30^\circ\text{C}$, $H = 50\%$, $W_s = 40 \text{ km/hr}$, $W_d = 90^\circ$, $P = 50 \text{ hPa}$, $F_{23} = F_{24} = F_{42} = 0.1..$



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- The main problem with wildfire models based on differential equations is the computational cost associated with the resolution of the system of equations.
- The complexity of the models is related to the realism and dynamism they have.



CONCLUSION

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CONCLUSION

- The incorporation of parallel techniques allows the model to compute enough states in discrete times to show a qualitatively realistic result for the specialists' requirements.
- The use of multithreads is a good strategy to apply to this problem given the characteristics of the discrete world and the independence of states between the times t and $t + 1$.
- Model complexity is smaller in comparison to the classical methods based on differential equations.



FUTURE WORK

- Work with more solid components, or finer granularity in some cases, for the core characteristics of the wildfire dynamics, such as the topographic and fuel components.



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- Use a parallel architecture of the pipeline type, taking advantage of the refresh rate in the interface of the simulator.



REFERENCES I

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