Slide 3: Linear Systems and Matrices III MAT2040 Linear Algebra

Three Possible Cases

$$[A|\mathbf{b}] \xrightarrow{\text{row operations}} \begin{bmatrix} \boxed{1} & 0 & 0 & -3 \\ 0 & \boxed{1} & 0 & 5 \\ 0 & 0 & \boxed{1} & 2 \end{bmatrix}$$

Unique solution.

$$[A|\mathbf{b}] \xrightarrow{\text{row operations}} \begin{bmatrix} \boxed{1} & 0 & 1 & 3 \\ 0 & \boxed{1} & -1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Infinitely many solutions.

$$[A|\mathbf{b}] \xrightarrow{\text{row operations}} \begin{bmatrix} \boxed{1} & 0 & 3 & -2 & 0 \\ 0 & \boxed{1} & 1 & -3 & 0 \\ 0 & 0 & 0 & 0 & \boxed{1} \end{bmatrix}$$

No solution.



Definition 3.1 (Consistence) A system of linear equations is **consistent** if it has at least one solution. Otherwise, the system is called **inconsistent**.

Fact 3.2

Let $A\mathbf{x} = \mathbf{b}$ be a linear system with n variables, Suppose $[A|\mathbf{b}]$ is row equivalent to a matrix $[B|\mathbf{c}]$ in reduced row-echelon form. Then by the structure of the the reduced row echelon form, the following conclusion is valid.

- (1) $A\mathbf{x} = \mathbf{b}$ is inconsistent
- \Leftrightarrow the last nonzero row of $[B|\mathbf{c}]$ is $(0,\cdots,0,1)$
- \Leftrightarrow column n+1 is a pivot column.
- (2) $A\mathbf{x} = \mathbf{b}$ is consistent
- \Leftrightarrow column n+1 is not a pivot columm.

$$[A|\mathbf{b}] \xrightarrow{\text{elementary row operations}} \begin{bmatrix} \boxed{1} & 0 & 0 & | & -3 \\ 0 & \boxed{1} & 0 & 5 \\ 0 & 0 & \boxed{1} & | & 2 \end{bmatrix}$$

The corresponding linear system $A\mathbf{x} = \mathbf{b}$ is consistent.

$$[A|\mathbf{b}] \xrightarrow{\text{elementary row operations}} \begin{bmatrix} \boxed{1} & 0 & 1 & 3 \\ 0 & \boxed{1} & -1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The corresponding linear system $A\mathbf{x} = \mathbf{b}$ is consistent.

$$[A|\mathbf{b}] \xrightarrow{\text{elementary row operations}} \begin{bmatrix} \boxed{1} & 0 & 3 & -2 & 0 \\ 0 & \boxed{1} & 1 & -3 & 0 \\ 0 & 0 & 0 & 0 & \boxed{1} \end{bmatrix}$$

The corresponding linear system $A\mathbf{x} = \mathbf{b}$ is inconsistent.

Fact 3.3 (Solution set for consistent linear systems)

Assume the linear system $A\mathbf{x} = \mathbf{b}$ with n variables is consistent. Suppose $[A|\mathbf{b}] \xrightarrow{\text{elementary row operations}} [B|\mathbf{c}](RREF)$ and B has r nonzero rows (B has r pivot columns). Then $r \leq n$.

- (1) r = n, the system has a unique solution.
- (2) r < n, the system has infinitely many solutions and the solution set can be described by n r free/independent variables (corresponding to the nonpivot columns in B).

Remark: For consistent linear system, r = number of pivot columns=number of nonzero rows in the EERF=number of leading 1s. **Note:** r is the number of "true equations" of the linear system, and there are n - r redundant equations.

Example: for the case:

$$[A|\mathbf{b}] \xrightarrow{\text{elementary row operations}} \begin{bmatrix} \boxed{1} & 0 & 0 & | & -3 \\ 0 & \boxed{1} & 0 & 5 \\ 0 & 0 & \boxed{1} & 2 \end{bmatrix}$$

r = n = 3, the system has a unique solution.

Example: for the case:

$$[A|\mathbf{b}] \xrightarrow{\text{elementary row operations}} \begin{bmatrix} \boxed{1} & 0 & 1 & 3 \\ 0 & \boxed{1} & -1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The solution can be described by

$$x_1=3-x_3,$$

$$x_2 = 2 + x_3$$
.

where x_3 is the **free variable** (**independent variable**) corresponding to nonpivot column in B, while x_1, x_2 are **dependent variables** corresponding to pivot columns in B.

Example 3.4 Find the solution of the following system:

$$2x_1 + x_2 + 7x_3 - 7x_4 = 8$$
$$-3x_1 + 4x_2 - 5x_3 - 6x_4 = -12$$
$$x_1 + x_2 + 4x_3 - 5x_4 = 4$$

$$\begin{bmatrix} 2 & 1 & 7 & -7 & 8 \\ -3 & 4 & -5 & -6 & -12 \\ 1 & 1 & 4 & -5 & 4 \end{bmatrix} \xrightarrow{\text{elemental row operations}} \begin{bmatrix} \boxed{1} & 0 & 3 & -2 & 4 \\ 0 & \boxed{1} & 1 & -3 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

The last column is not a pivot column, so it is a consistent system. Columns 1 and 2 are the pivot columns while columns 3 and 4 are non-pivot columns.

Thus, x_1, x_2 are dependent variables while x_3, x_4 are independent variables. In fact, $x_1 = -3x_3 + 2x_4 + 4$, $x_2 = -x_3 + 3x_4$

Combining the above two facts, one has

Fact 3.5 (Possible Solution Sets for Linear Systems) For a system of linear equations $A\mathbf{x} = \mathbf{b}$, it can can have (1) a unique solution or (2) infinitely many solutions or (3) no solution.

Definition 3.6 (Homogeneous System) A system of linear equations Ax = b is called homogeneous if b = 0 (the zero vector).

A homogeneous system looks like this:

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = 0,$$

$$a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n = 0,$$

$$a_{31}x_1 + a_{32}x_2 + a_{33}x_3 + \dots + a_{3n}x_n = 0,$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + a_{m3}x_3 + \dots + a_{mn}x_n = 0.$$

0 is a solution to such a system, i.e., all variables equal to zero $(x_1 = x_2 = \cdots = x_n = 0)$ is a solution. This solution is called the **trivial** solution.

Property 3.7 (Homogeneous systems are always consistent) Any homogeneous linear system is consistent.

Example 3.8 Determine the solutions for the following linear systems.

$$-7x_1 - 6x_2 - 12x_3 = 0,$$

$$5x_1 + 5x_2 + 7x_3 = 0,$$

$$x_1 + 4x_3 = 0.$$

The reduced row echelon form of the augmented matrix is

$$\left[\begin{array}{cc|cc}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0
\end{array}\right]$$

Hence it has only one solution, i.e., the trivial solution.

Example 3.9 Determine the solutions for the following linear systems.

$$x_1 - x_2 + 2x_3 = 0,$$

 $2x_1 + x_2 + x_3 = 0,$
 $x_1 + x_2 = 0$

The reduced row echelon form of the augmented matrix is

$$\left[\begin{array}{cc|cc|c}
1 & 0 & 1 & 0 \\
0 & 1 & -1 & 0 \\
0 & 0 & 0 & 0
\end{array}\right]$$

The system is consistent. It has n-r=3-2=1 free variable. The solution set is

$$S = \left\{ \left[egin{array}{c} -t \\ t \\ t \end{array} \right] \middle| t \in R
ight\}.$$

Theorem 3.10 (Underdetermined homogeneous systems have infinite solutions)

An underdetermined homogeneous linear system has infinite solutions.

For underdetermined homogeneous linear system (m < n):

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = 0,$$

$$a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n = 0,$$

$$a_{31}x_1 + a_{32}x_2 + a_{33}x_3 + \dots + a_{3n}x_n = 0,$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + a_{m3}x_3 + \dots + a_{mn}x_n = 0.$$

Suppose $[A_{m \times n} | \mathbf{0}] \xrightarrow{\text{elementary row operations}} [B_{m \times n} | \mathbf{0}] (RREF)$ and B has r nonzero rows, also B both have r pivot columns.

of pivot columns in B = # of nonzero rows in $B = r \le m < n$.

Example 3.11 Find the solution for the following homogeneous system.

$$2x_1 + x_2 + 7x_3 - 7x_4 = 0$$
$$-3x_1 + 4x_2 - 5x_3 - 6x_4 = 0$$
$$x_1 + x_2 + 4x_3 - 5x_4 = 0$$

m = 3 < n = 4, thus the above homogeneous linear system must have infinitely many solutions. In fact

$$\begin{bmatrix} 2 & 1 & 7 & -7 \\ -3 & 4 & -5 & -6 \\ 1 & 1 & 4 & -5 \end{bmatrix} \xrightarrow{\text{elementary row operations}} \begin{bmatrix} \boxed{1} & 0 & 3 & -2 \\ 0 & \boxed{1} & 1 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Thus

$$x_1 = -3x_3 + 2x_4$$
, $x_2 = -x_3 + 3x_4$