

E9 231: Digital Array Signal Processing

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1 Minutes of Last Lecture

1. MVDR beamformer (maximum likelihood)
2. Bayesian framework LMMSE beamformer
3. MMSE conditional mean estimator
-goes back to (2) for gaussian
4. max. SNR (goes back to (1))
5. MPDR beamformer (\mathbf{S}_x instead of \mathbf{S}_n)

2 Today:

- sensitivity analysis
- LCMV/LCMP beamformers

3 Mismatched MVDR/MPDR

Recall:

$$\begin{aligned}\mathbf{W}_{MVDR} &= \Lambda \mathbf{S}_n^{-1} \mathbf{V}_m \\ \text{where } \Lambda &= (\mathbf{V}_m^H \mathbf{S}_n^{-1} \mathbf{V}_m)^{-1} \\ \mathbf{W}_{MPDR} &= \Lambda_1 \mathbf{S}_x^{-1} \mathbf{V}_m \\ \text{where } \Lambda_1 &= (\mathbf{V}_m^H \mathbf{S}_x^{-1} \mathbf{V}_m)^{-1}\end{aligned}$$

Also,

$$\mathbf{W}_c = \frac{1}{N} \mathbf{V}_m$$

4 Types of errors

1. DOA mismatch

$$\begin{aligned}\mathbf{V}_a &= \text{“actual” DOA} \\ \mathbf{V}_m &= \text{“model” DOA} \\ \mathbf{V}_m &\neq \mathbf{V}_a\end{aligned}$$

2. Array perturbation:

$$\mathbf{V}_m(\mathbf{k}_d) \neq \mathbf{V}_a(\mathbf{k}_d)$$

3. Errors in spatial spectral estimate

$$\hat{\mathbf{S}}_{\mathbf{n}} \neq \mathbf{S}_{\mathbf{n}}$$

$$\hat{\mathbf{S}}_{\mathbf{x}} \neq \mathbf{S}_{\mathbf{x}}$$

5 DOA mismatch

$$\mathbf{X} = \mathbf{V}_a F + \mathbf{N}$$

\mathbf{V}_a = array manifold corresponding to the actual DOA

$$= \mathbf{V}_a(\omega, \mathbf{k}_a) \neq \mathbf{V}_m$$

$\mathbf{S}_{\mathbf{n}}$ = $s_n \rho_{\mathbf{n}}$

$$\begin{aligned} P_o &= |\mathbf{W}^H \mathbf{X}|^2 \\ &= \sigma_s^2 |\mathbf{W}^H \mathbf{V}_a|^2 + \mathbf{W}^H \mathbf{S}_{\mathbf{n}} \mathbf{W} \\ &= P_s + P_n \\ SNR_o = \frac{P_s}{P_n} &= \frac{\sigma_s^2 |\mathbf{W}^H \mathbf{V}_a|^2}{\mathbf{W}^H \mathbf{S}_{\mathbf{n}} \mathbf{W}} \\ \text{array gain} &= \frac{|\mathbf{W}^H \mathbf{V}_a|^2}{\mathbf{W}^H \rho_{\mathbf{n}} \mathbf{W}} \end{aligned}$$

5.1 Conventional beamformer

Recall from chapter 2 :-

$$\begin{aligned} B(\mathbf{V}_m : \mathbf{V}_a) &= \frac{1}{N} \mathbf{V}_m^H \mathbf{V}_a \\ SNR_o = \frac{P_s}{P_n} &= \frac{\sigma_s^2 |\mathbf{W}_c^H \mathbf{V}_a|^2}{\mathbf{W}_c^H \mathbf{S}_{\mathbf{n}} \mathbf{W}_c}; \text{ where } \mathbf{W}_c = \frac{1}{N} \mathbf{V}_m \\ &= \frac{\sigma_s^2 |\mathbf{V}_m^H \mathbf{V}_a|^2}{\mathbf{V}_m^H \mathbf{S}_{\mathbf{n}} \mathbf{V}_m} \\ &= \frac{\sigma_s^2 N^2 |B_c(\mathbf{V}_m : \mathbf{V}_a)|^2}{\mathbf{V}_m^H \mathbf{S}_{\mathbf{n}} \mathbf{V}_m} \\ A_c &= \frac{N^2 |B_c(\mathbf{V}_m : \mathbf{V}_a)|^2}{\mathbf{V}_m^H \rho_{\mathbf{n}} \mathbf{V}_m} \\ \frac{A_c(V_a)}{A_c(V_m)} &= |B_c(\mathbf{V}_m : \mathbf{V}_a)|^2 \end{aligned}$$

5.2 MVDR beamformer

generalized cosine:

$$\begin{aligned}
\cos^2(\mathbf{V}_m, \mathbf{V}_a : \rho_{\mathbf{n}}^{-1}) &\triangleq \frac{|\mathbf{V}_m^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_a|^2}{(\mathbf{V}_m^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_m)(\mathbf{V}_a^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_a)} \\
\mathbf{W}_{MVDR} &= \frac{\mathbf{S}_{\mathbf{n}}^{-1} \mathbf{V}_m}{\mathbf{V}_m^H \mathbf{S}_{\mathbf{n}}^{-1} \mathbf{V}_m} \\
P_s &= \sigma_s^2 |\mathbf{W}_{MVDR}^H \mathbf{V}_a|^2 \\
&= \frac{\sigma_s^2 |\mathbf{V}_m^H \mathbf{S}_{\mathbf{n}}^{-1} \mathbf{V}_a|^2}{(\mathbf{V}_m^H \mathbf{S}_{\mathbf{n}}^{-1} \mathbf{V}_m)^2} \\
&= \frac{\sigma_s^2 (\mathbf{V}_a^H \mathbf{S}_{\mathbf{n}}^{-1} \mathbf{V}_a) \cos^2(\mathbf{V}_m, \mathbf{V}_a : \mathbf{S}_{\mathbf{n}}^{-1})}{(\mathbf{V}_m^H \mathbf{S}_{\mathbf{n}}^{-1} \mathbf{V}_m)} \\
&= \frac{\sigma_s^2 (\mathbf{V}_a^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_a) \cos^2(\mathbf{V}_m, \mathbf{V}_a : \rho_{\mathbf{n}}^{-1})}{(\mathbf{V}_m^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_m)} \\
SNR_o = \frac{P_s}{P_n} &= \frac{\frac{\sigma_s^2 (\mathbf{V}_a^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_a) \cos^2(\mathbf{V}_m, \mathbf{V}_a : \rho_{\mathbf{n}}^{-1})}{(\mathbf{V}_m^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_m)}}{S_n \frac{\mathbf{V}_m^H \rho_{\mathbf{n}}^{-1} \rho_{\mathbf{n}} \rho_{\mathbf{n}}^{-1} \mathbf{V}_m}{(\mathbf{V}_m \rho_{\mathbf{n}}^{-1} \mathbf{V}_m)^2}} \\
SNR_o &= \frac{\sigma_s^2}{s_n} \mathbf{V}_a^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_a \cos^2(\mathbf{V}_m, \mathbf{V}_a : \rho_{\mathbf{n}}^{-1}) \\
A_{MVDR}(\mathbf{V}_a) &= \mathbf{V}_a^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_a \cos^2(\mathbf{V}_m, \mathbf{V}_a : \rho_{\mathbf{n}}^{-1}) \\
\frac{A_{MVDR} |_{\mathbf{V}_m \neq \mathbf{V}_a}}{A_{MVDR} |_{\mathbf{V}_m = \mathbf{V}_a}} &= \frac{|\mathbf{V}_m^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_a|^2}{(\mathbf{V}_m^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_m)(\mathbf{V}_a^H \rho_{\mathbf{n}}^{-1} \mathbf{V}_a)} \\
&= \cos^2(\mathbf{V}_a, \mathbf{V}_m : \rho_{\mathbf{n}}^{-1})
\end{aligned}$$

Ramark: As SNR \uparrow , perfomance significantly degrades with DOA mismatch.

6 Condition number related problems

$$\mathbf{W}_{MPDR} = \Lambda_1 \mathbf{S}_{\mathbf{x}}^{-1} \mathbf{V}_m$$

Potential problem:
condition # of $\mathbf{S}_{\mathbf{x}}^{-1}$

$$\triangleq \frac{\lambda_{max}}{\lambda_{min}}$$

If the condition # is large, small errors in $\mathbf{S}_{\mathbf{x}}$ (or even \mathbf{V}_a) could be amplified

$$\begin{aligned}
\mathbf{S}_{\mathbf{x}} &= \sum_{i=1}^N \lambda_i e_i e_i^H \\
\mathbf{S}_{\mathbf{x}}^{-1} &= \sum_{i=1}^N \frac{1}{\lambda_i} e_i e_i^H \\
\mathbf{S}_{\mathbf{x}}^{-1} \mathbf{V}_a &= \sum_{i=1}^N \left(\frac{e_i^H \mathbf{V}_a}{\lambda_i} \right) e_i
\end{aligned}$$

could end up becoming very large if $\frac{\lambda_{max}}{\lambda_{min}}$ is large,

$$\begin{aligned}\lambda_{max} &= 10 \longrightarrow \lambda_{max} \pm \epsilon \\ \lambda_{min} &= 0.01 \longrightarrow \lambda_{min} \pm \epsilon\end{aligned}$$

Another way, $\|\mathbf{W}_{MVDR}\|^2$ could end up very large

This motivates including a norm constraint in beamformer design

$$\|\mathbf{W}_{MVDR}\|^2 = \Lambda_1^2 \|\mathbf{S}_x^{-1} \mathbf{V}_a\|^2 = \frac{\mathbf{V}_a^H \mathbf{S}_x^{-2} \mathbf{V}_a}{(\mathbf{V}_a^H \mathbf{S}_x^{-1} \mathbf{V}_a)^2}$$

7 Robust beamformers

$$\text{constraint } \mathbf{W}^H \mathbf{V}_a = 1$$

$$\min_{\mathbf{W}} \mathbf{W}^H \mathbf{S}_n \mathbf{W} + \beta \|\mathbf{W}\|^2, \quad \text{where } \beta \text{ is the regularization term}$$

$$\begin{aligned}J &= \mathbf{W}^H \mathbf{S}_n \mathbf{W} + \mathbf{W}^H \beta \mathbf{I} \mathbf{W} \\ &= \mathbf{W}^H (\mathbf{S}_n + \beta \mathbf{I}) \mathbf{W}\end{aligned}$$

This is called “diagonal loading”.

$$\mathbf{W}_{reg} = \frac{(\mathbf{S}_n + \beta \mathbf{I})^{-1} \mathbf{V}_a}{\mathbf{V}_a^H (\mathbf{S}_n + \beta \mathbf{I})^{-1} \mathbf{V}_a}$$

$$\text{As } \beta \longrightarrow \infty \quad \mathbf{W}_{reg} \longrightarrow \mathbf{W}_c$$

$$\text{As } \beta \longrightarrow 0 \quad \mathbf{W}_{reg} \longrightarrow \mathbf{W}_{MVDR}$$

Finding the appropriate β is difficult.

condition # of \mathbf{S}_n is improved:

$$\begin{aligned}\mathbf{S}_n : & \quad \lambda_{max} \quad , \lambda_{min} \\ (\mathbf{S}_n + \beta \mathbf{I}) : & \quad \lambda_{max} + \beta \quad , \lambda_{min} + \beta \\ \text{condition \# } (\mathbf{S}_n + \beta \mathbf{I}) &= \frac{\lambda_{max} + \beta}{\lambda_{min} + \beta}\end{aligned}$$

7.1 Alternative approach for improving a norm constraint

MPDR formulation

$$\min_{\mathbf{W}} \mathbf{W}^H \mathbf{S}_x \mathbf{W}$$

$$\begin{aligned}\text{s.t. } \mathbf{W}^H \mathbf{V}_a &= 1 \\ \mathbf{W}^H \mathbf{W} &= T_o\end{aligned}$$

$$J = \mathbf{W}^H \mathbf{S}_x \mathbf{W} + \lambda_1 (\mathbf{W}^H \mathbf{W} - T_o) + \lambda_2 (\mathbf{W}^H \mathbf{V}_a - 1) + \lambda_2^* (\mathbf{V}_a^H \mathbf{W} - 1)$$

\implies differentiate w.r.t. \mathbf{W}^H :

$$\mathbf{W}^H = \frac{\mathbf{V}_a^H (\mathbf{S}_n + \lambda_1 \mathbf{I})^{-1}}{\mathbf{V}_a^H (\mathbf{S}_n + \lambda_1 \mathbf{I})^{-1} \mathbf{V}_a}$$

Often set λ_1 to a fixed value and use this as our beamformer vector:

$$\mathbf{W}_{MPDR,dl}^H = \frac{\mathbf{V}_a^H \left[\mathbf{I} + \frac{\mathbf{S}_x}{\sigma_L^2} \right]^{-1}}{\mathbf{V}_a^H \left[\mathbf{I} + \frac{\mathbf{S}_x}{\sigma_L^2} \right]^{-1} \mathbf{V}_a}$$

8 Using more linear constraints:

- Linearly Constrained Minimum Variance (LCMV) Beamformer
- Linearly Constrained Minimum Power (LCMP) Beamformer
- Distortionless constraint
- Null constraints
- Derivative constraints

$$\mathbf{W}_{1 \times N}^H \mathbf{C}_{N \times M} = \mathbf{g}_{1 \times M}^H$$

$M < N$, otherwise there will not be enough degrees of freedom.
columns of \mathbf{C} are linearly independent

$$\mathbf{C}^H \mathbf{W} = \mathbf{g}$$

Optimization problem:

$$\begin{array}{ll} \min & \text{LCMV} \quad \mathbf{W}^H \mathbf{S}_n \mathbf{W} \quad \text{or} \quad \text{LCMP} \quad \mathbf{W}^H \mathbf{S}_x \mathbf{W} \\ \text{s.t.} & \mathbf{C}^H \mathbf{W} = \mathbf{g} \end{array}$$

Solⁿ :

$$\mathbf{W}_{LCMV} = \mathbf{S}_n^{-1} \mathbf{C} (\mathbf{C}^H \mathbf{S}_n^{-1} \mathbf{C})^{-1} \mathbf{g}$$

$$\mathbf{W}_{LCMP} = \mathbf{S}_x^{-1} \mathbf{C} (\mathbf{C}^H \mathbf{S}_x^{-1} \mathbf{C})^{-1} \mathbf{g}$$

If we set $\mathbf{C} = \mathbf{V}_s$ & $\mathbf{g} = 1$, $\mathbf{W}_{LCMV} \rightarrow \mathbf{W}_{MVDR}$

$$J = \mathbf{W}^H \mathbf{S}_n \mathbf{W} + (\mathbf{W}^H \mathbf{C} - \mathbf{g}^H) \lambda + \lambda^H (\mathbf{C}^H \mathbf{W} - \mathbf{g})$$

Differentiate with respect to \mathbf{W}^H :

$$\mathbf{S}_n \mathbf{W} + \mathbf{C} \lambda = 0$$

$$\mathbf{W} = -\mathbf{S}_n^{-1} \mathbf{C} \lambda$$

$$\lambda = -(\mathbf{C}^H \mathbf{S}_n^{-1} \mathbf{C})^{-1} \mathbf{g}$$

$$\mathbf{W}_{LCMV} = \mathbf{S}_n^{-1} \mathbf{C} (\mathbf{C}^H \mathbf{S}_n^{-1} \mathbf{C})^{-1} \mathbf{g}$$