

Analysing Algorithms (Part 2 - Examining Algorithms)

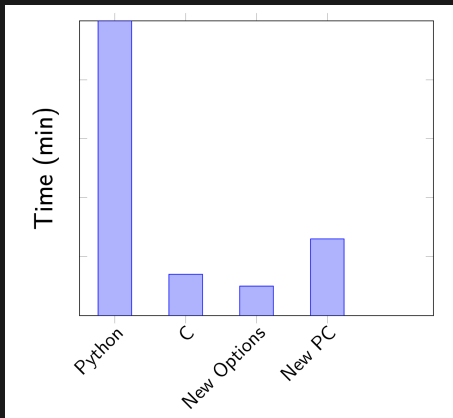
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Lecture 08.1.2 (v1.0.2)

Signposting

- ▶ Analysing Algorithms is split into three parts:
 - ▶ Part 1: Motivation and Algorithmic Complexity
 - ▶ Part 2: Examining algorithms
 - ▶ Part 3: Turing Machines and Complexity Classes
- ▶ This is Part 2
- ▶ Thanks to Turing Fellow and Computer Scientist Dan Martin for Tikz pictures and expertise

Runtime vs Complexity - motivation



- ▶ Consider our algorithm run on data D_1 :
 - ▶ In different programming languages, compile arguments and hardware
- ▶ What can be said in general?

Algorithm Example (I)

- ▶ What is the complexity of the following algorithm?

procedure Example(a, b, n)

$i \leftarrow 1$

while $i \leq n$ **do**

$a \leftarrow f_1(b, n)$

$b \leftarrow f_2(a, n)$

$i \leftarrow i + 1$

end while

return b

end procedure

- ▶ $f_i(a, n)$ has runtime $T_i(n)$
- ▶ Inside loop is $\mathcal{O}(T_1(n) + T_2(n))$
- ▶ Total $\mathcal{O}[n(T_1(n) + T_2(n))]$

Algorithm Example (2)

- Compare to the following algorithm?

procedure Example(a, b, n)

$i \leftarrow 1$

while $i \leq n$ **do**

$a \leftarrow f_1(b, n)$

$b \leftarrow f_2(a, n)$

$i \leftarrow 2 \cdot i$

end while

return b

end procedure

- Inside loop is $\mathcal{O}(T_1(n) + T_2(n))$
- Total $\mathcal{O}[\log(n)(T_1(n) + T_2(n))]$

Sorting examples

- ▶ We have some data: 1, 4, 6, 2, 3, 7, 5, \dots
- ▶ We want to sort the data into ascending order:
1, 2, 3, 4, 5, 6, 7, \dots
- ▶ What is the best¹ algorithm?
 - ▶ **Insertion sort** is $\Theta(n^2)$, but operates in-place.
 - ▶ **Merge sort** is $\Theta(n \log(n))$, but memory requirements grow with data size.
 - ▶ **Heap sort** is $\Theta(n \log(n))$ and sorts in place.
 - ▶ **Quick sort** is $\Theta(n^2)$, but $\Theta(n \log(n))$ expected time, and is often fastest in practice.
 - ▶ **Counting sort** allows array indices to be sorted in $\Theta(n)$ by exploiting knowledge that all integers are present.
 - ▶ **Bucket sort** is $\Theta(n^2)$, though $\Theta(n)$ average case (if data are Uniform!)

¹Cormen et al 2010 Introduction to Algorithms

Quicksort: a Recursion Example

```
procedure QuickSort( $A$ )  
  if  $\text{len}(A) == 1$  then  
    return  $A$   
  else  
     $x \leftarrow A$   
     $A_l \leftarrow \{a \in A : a < x\}$   
     $A_h \leftarrow \{a \in A : a > x\}$   
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What if we can choose the
median element of A ?

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$$T(n)$$

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What if we can choose the
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$$T(n) = 2T\left(\frac{n}{2}\right) + n$$

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$$\begin{aligned} T(n) &= 2T\left(\frac{n}{2}\right) + n \\ &= 2\left(2T\left(\frac{n}{4}\right) + \frac{n}{2}\right) + n \end{aligned}$$

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$$\begin{aligned} T(n) &= T(n-1) + n \\ &= (T(n-2) + n) + n \\ &= \dots \\ &= T(1) + \sum_{i=1}^n i \end{aligned}$$

Quicksort: a Recursion Example

procedure QuickSort(A)

if $\text{len}(A) == 1$ **then**

return A

else

$x \leftarrow A$

$A_l \leftarrow \{a \in A : a < x\}$

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$S_l \leftarrow \text{QuickSort}(A_l)$

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return $[S_l, A_x, S_h]$

end if

end procedure

What if we always choose the
largest element of A ?

$T(n)$

$$= T(n-1) + n$$

$$= (T(n-2) + n) + n$$

$$= \dots$$

$$= T(1) + \sum_{i=1}^n i$$

$$= n(n-1)/2 = \Theta(n^2)$$

Other types of complexity

- ▶ Complexity questions are primarily asked about:
 - ▶ **Computation** (time)
 - ▶ **Space** (memory)
 - ▶ **Communication** (data transfer)
- ▶ They are all studied analogously - it is the unit of counting that changes
- ▶ Despite that, the theory is quite different

Space complexity

- ▶ Simply the amount of memory that an algorithm needs
- ▶ You can calculate it simply by adding the memory allocations
- ▶ Space required is **additional** to the input, which is **not** counted - this can conceptually not be stored at all, as in e.g. streaming algorithms
- ▶ Formally defined in terms of the Turing Machine (8.1.3)
- ▶ It can often be traded for time complexity, e.g. by storing intermediate results vs revisiting the calculation
- ▶ For a Data Scientist, this trade off is critical!
- ▶ We use the same notation

Space complexity example (I)

- ▶ **Problem:** Find x, y in X s.t. $x + y = T$ (known to exist)
- ▶ Solution I:

```
import heapq
heapq.heapsort(X)
i=0; j=n-1;
while(X[i]+X[j] != T):
    if X[i]+X[j] < T:
        i=i+1
    else:
        j=j-1
```

- ▶ Heapsort has $\mathcal{O}(1)$ space complexity
- ▶ Therefore the whole algorithm is $\mathcal{O}(1)$ in space
- ▶ And time complexity $\mathcal{O}(n \log(n) + n) = \mathcal{O}(n \log(n))$

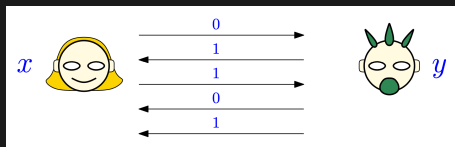
Space complexity example (2)

- ▶ Find x, y in X s.t. $x + y = T$ (known to exist)
- ▶ Solution 2:

```
D={}
for i in range(len(X)):
    D[T-X[i]]=i
for x in X:
    y=T-x
    if y in D:
        return X[D[y]],x
```

- ▶ This is $\mathcal{O}(n)$ in space
- ▶ Hash lookups are $\mathcal{O}(1)$ **average case** complexity ($\mathcal{O}(n)$ worst case - which does not apply here!)
- ▶ So this algorithm is $\mathcal{O}(n)$ in time too

Communication Complexity



- ▶ Alice knows $x \in X$, Bob knows $y \in Y$
- ▶ Together they want to compute $f(x, y)$ where $f \in X \times Y \rightarrow Z$
- ▶ Via a pre-arranged **protocol** P determining what they send
- ▶ The **communication cost** is the number of bits sent ²

²Raznorov 2015 Communication Complexity Lecture

Communication Complexity

- ▶ The **Overall cost** of P is $C(P) = \max_{x,y}[P(x,y)]$, i.e. the maximum possible cost for all data
- ▶ The **Communication complexity** of f is $C(f) = \min_{P \in \mathcal{P}}(C[P(x,y)])$
- ▶ It is the minimum number of bits needed to compute $f(x,y)$ for any x,y
- ▶ Communication Complexity Theory describes $C(f)$, typically by finding **bounds** (upper and lower) for a given f
 - ▶ Again typically as a function of the size of x and y , and always for some well defined spaces X and Y .
- ▶ Note that there is a trivial bound of $n + 1$ for transferring all the data! (and then the answer back)

Communication Complexity Examples

- ▶ $f(x, y) = \text{Parity}([x, y])$
 - ▶ $\text{Parity} = \text{mod}_2(\sum_{i=1}^n x_i)$
 - ▶ $C(f(x, y)) = 2$ because Alice calculates the Parity of x , Bob the Parity of y , and they each communicate their own parity
- ▶ $f(x, y) = \text{Equality}(x, y)$
 - ▶ i.e. 1 if $x_i = y_i \quad \forall i$, and 0 otherwise
 - ▶ $C(f(x, y)) = n$ because every bit must be compared
- ▶ Typically approximate algorithms allow dramatically lower complexity
 - ▶ All the interesting theory is in this space

What is communication complexity theory good for?

- ▶ There are lots of immediate applications
 - ▶ Optimisation of computer networks
 - ▶ **Parallel algorithms**: communication between multiple cores on a CPU, or nodes of a cluster
 - ▶ And basically anything involving the internet!
 - ▶ Especially differential privacy (Block 12)
- ▶ There are many more less immediate applications
 - ▶ Particularly as a tool for algorithm and data structure lower bounds

Reflection

- ▶ What are the main subjects of complexity theory, and in which ways are they similar?
- ▶ By the end of the course, students should be able to:
 - ▶ Define three subjects of complexity theory
 - ▶ Apply each to simple algorithms, including compound algorithms
 - ▶ Reason about their value at a high level

Signposting

- ▶ Next up: Part 3: Turing Machines
- ▶ **References:**
 - ▶ Cormen et al 2010 Introduction to Algorithms
 - ▶ Toniann Pitassi Lecture on Communication Complexity: Applications and New Directions
 - ▶ Raznorov 2015 Communication Complexity Lecture
 - ▶ Arora and Barak Computational Complexity: A Modern Approach
 - ▶ One of few places to give space complexity much time (its always the poor cousin)