# Lecture 9 – Multiple Linear Regression and Feature Engineering



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#### **Announcements**

- Midterm grades released; submit regrade requests by Friday night.
- Groupwork 4 out later today, due Thursday at 11:59pm.
- Homework 4 out later today, due Monday at 11:59pm.
- Come to the DSC Faculty-Student Mixer at 1pm today!
  - Zoom link: https://ucsd.zoom.us/j/98335299546.

#### **Agenda**

- Recap of Lecture 8.
- Using multiple features.
- ► Practical demo.
- Interpreting weights.
- Feature engineering.

# **Recap of Lecture 8**

#### Regression and linear algebra

Last time, we used linear algebra to fit a prediction rule of the form

$$H(x) = W_0 + W_1 x$$

To do so, we first defined a **design matrix** X, **parameter vector**  $\vec{w}$ , and **observation vector**  $\vec{y}$  as follows:

$$X = \begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \dots & \dots \\ 1 & x_n \end{bmatrix}, \qquad \vec{W} = \begin{bmatrix} W_0 \\ W_1 \end{bmatrix}, \qquad \vec{Y} = \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{bmatrix}$$

We also re-wrote our prediction rule as a matrix-vector multiplication, defining the hypothesis vector  $\vec{h}$  as

$$\vec{h} = X\vec{w}$$

#### Minimizing mean squared error

With our new linear algebra formulation of regression, our mean squared error now looks like:

$$R_{sa}(\vec{w}) = ||\vec{y} - X\vec{w}||^2$$

- To find  $\vec{w}^*$ , the optimal parameter vector, we took the gradient of  $R_{sq}(\vec{w})$  with respect to  $\vec{w}$ , set it equal to 0, and solved.
- ► The result is the **normal equations**:

$$X^T X \vec{w}^* = X^T V$$

 $\triangleright$  When  $X^TX$  is invertible, an equivalent form is

$$\vec{w}^* = (X^T X)^{-1} X^T y$$

This gives the same  $w_0^*$  and  $w_1^*$  as our formulas from Lecture 6.

# Using multiple features

#### **Using multiple features**

- How do we predict salary given multiple features?
- We believe salary is a function of experience and GPA.
- ▶ In other words, we believe there is a function *H* so that:

salary  $\approx$  H(years of experience, GPA)

- Recall: H is a prediction rule.
- Our goal: find a good prediction rule, H.

#### **Example prediction rules**

$$H_1$$
(experience, GPA) = \$2,000 × (experience) + \$40,000 ×  $\frac{GPA}{4.0}$ 

$$H_2$$
(experience, GPA) = \$60,000 × 1.05<sup>(experience+GPA)</sup>

$$H_3$$
(experience, GPA) = cos(experience) + sin(GPA)

#### **Linear prediction rules**

We'll restrict ourselves to linear prediction rules:

$$H(\text{experience}, \text{GPA}) = w_0 + w_1(\text{experience}) + w_2(\text{GPA})$$

- ► This is called multiple linear regression.
- Note that H is linear in the parameters  $w_0$ ,  $w_1$ ,  $w_2$ .
  - ightharpoonup H is a linear combination of features (1, experience, GPA) with ws as the coefficients ( $w_0$ ,  $w_1$ , and  $w_2$ ).
- As a result, we can solve the **normal equations** to find  $w_0^*$ ,  $w_1^*$ , and  $w_2^*$ !
- Linear regression with multiple features is called multiple linear regression.

#### **Geometric interpretation**

Question: The prediction rule

$$H(experience) = w_0 + w_1(experience)$$

looks like a line in 2D.

- 1. How many dimensions do we need to graph  $H(\text{experience, GPA}) = w_0 + w_1(\text{experience}) + w_2(\text{GPA})$
- 2. What is the shape of the prediction rule?

#### **Example dataset**

For each of *n* people, collect each feature, plus salary:

Person #	Experience	GPA	Salary
1	3	3.7	85,000
2	6	3.3	95,000
3	10	3.1	105,000

We represent each person with a feature vector:

$$\vec{x}_1 = \begin{bmatrix} 3 \\ 3.7 \end{bmatrix}$$
,  $\vec{x}_2 = \begin{bmatrix} 6 \\ 3.3 \end{bmatrix}$ ,  $\vec{x}_3 = \begin{bmatrix} 10 \\ 3.1 \end{bmatrix}$ 

#### The hypothesis vector

When our prediction rule is

$$H(\text{experience, GPA}) = w_0 + w_1(\text{experience}) + w_2(\text{GPA}),$$

the hypothesis vector  $\vec{h} \in \mathbb{R}^n$  can be written

$$\vec{h} = \begin{bmatrix} H(\text{experience}_1, \text{GPA}_1) \\ H(\text{experience}_2, \text{GPA}_2) \\ \dots \\ H(\text{experience}_n, \text{GPA}_n) \end{bmatrix} = \begin{bmatrix} 1 & \text{experience}_1 & \text{GPA}_1 \\ 1 & \text{experience}_2 & \text{GPA}_2 \\ \dots & \dots & \dots \\ 1 & \text{experience}_n & \text{GPA}_n \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix}$$

#### How do we find $\vec{w}^*$ ?

To find the best parameter vector,  $\vec{w}^*$ , we can use the design matrix and observation vector

$$X = \begin{bmatrix} 1 & \text{experience}_1 & \text{GPA}_1 \\ 1 & \text{experience}_2 & \text{GPA}_2 \\ \dots & \dots & \dots \\ 1 & \text{experience}_n & \text{GPA}_n \end{bmatrix}, \vec{y} = \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{bmatrix}$$

and solve the normal equations

$$X^T X \vec{w}^* = X^T \vec{y}$$

Notice that the rows of the design matrix are the (transposed) feature vectors, with an additional 1 in front.

### Notation for multiple linear regression

- ► We will need to keep track of multiple¹ features for every individual in our data set.
- As before, subscripts distinguish between individuals in our data set. We have *n* individuals (or training examples).
- Superscripts distinguish between features.<sup>2</sup> We have d features.
  - $\triangleright$  experience =  $x^{(1)}$
  - $Arr GPA = x^{(2)}$

<sup>&</sup>lt;sup>1</sup>In practice, we might use hundreds or even thousands of features.

<sup>&</sup>lt;sup>2</sup>Think of them as new variable names, such as new letters.

#### **Augmented feature vectors**

The augmented feature vector  $Aug(\vec{x})$  is the vector obtained by adding a 1 to the front of feature vector  $\vec{x}$ :

$$\vec{x} = \begin{bmatrix} x^{(1)} \\ x^{(2)} \\ \vdots \\ x^{(d)} \end{bmatrix} \qquad \text{Aug}(\vec{x}) = \begin{bmatrix} 1 \\ x^{(1)} \\ x^{(2)} \\ \vdots \\ x^{(d)} \end{bmatrix} \qquad \vec{w} = \begin{bmatrix} w_0 \\ w_1 \\ w_2 \\ \vdots \\ w_d \end{bmatrix}$$

► Then, our prediction rule is

$$H(\vec{x}) = w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_d x^{(d)}$$
  
=  $\vec{w} \cdot \text{Aug}(\vec{x})$ 

#### The general problem

We have n data points (or training examples):  $(\vec{x}_1, y_1), ..., (\vec{x}_n, y_n)$  where each  $\vec{x}_i$  is a feature vector of d features:

$$\vec{X}_i = \begin{bmatrix} x_i^{(1)} \\ X_i^{(2)} \\ X_i^{(d)} \\ \dots \\ X_i^{(d)} \end{bmatrix}$$

We want to find a good linear prediction rule:

$$H(\vec{x}) = w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_d x^{(d)}$$
  
=  $\vec{w} \cdot \text{Aug}(\vec{x})$ 

#### The general solution

Use design matrix

$$X = \begin{bmatrix} 1 & x_1^{(1)} & x_1^{(2)} & \dots & x_1^{(d)} \\ 1 & x_2^{(1)} & x_2^{(2)} & \dots & x_2^{(d)} \\ \dots & \dots & \dots & \dots & \dots \\ 1 & x_n^{(1)} & x_n^{(2)} & \dots & x_n^{(d)} \end{bmatrix} = \begin{bmatrix} \operatorname{Aug}(\vec{x_1})^T \\ \operatorname{Aug}(\vec{x_2})^T \\ \dots \\ \operatorname{Aug}(\vec{x_n})^T \end{bmatrix}$$

and observation vector to solve the normal equations

$$X^T X \vec{w}^* = X^T \vec{y}$$

to find the optimal parameter vector.

#### Interpreting the parameters

- ▶ With *d* features,  $\vec{w}$  has d + 1 entries.
- $\triangleright$   $w_0$  is the bias, also known as the intercept.
- w<sub>1</sub>,..., w<sub>d</sub> each give the weight, i.e. coefficient, of a feature.

$$H(\vec{x}) = W_0 + W_1 x^{(1)} + ... + W_d x^{(d)}$$

The sign of  $w_i$  tells us about the relationship between *i*th feature and the output of our prediction rule.

## **Practical demo**

#### **Example: predicting sales**

- For each of 26 stores, we have:
  - net sales,
  - square feet,
  - inventory,
  - advertising expenditure,
  - district size, and
  - number of competing stores.
- ► Goal: predict net sales given square footage, inventory, etc.
- ► To begin:

 $H(\text{square feet, competitors}) = w_0 + w_1(\text{square feet}) + w_2(\text{competitors})$ 

#### **Example: predicting sales**

 $H(\text{square feet, competitors}) = w_0 + w_1(\text{square feet}) + w_2(\text{competitors})$ 

#### **Discussion Question**

What will be the sign of  $w_1^*$  and  $w_2^*$ ?

- A)  $W_1^* = +$ ,  $W_2^* = -$ B)  $W_1^* = +$ ,  $W_2^* = +$ C)  $W_1^* = -$ ,  $W_2^* = -$ D)  $W_1^* = -$ ,  $W_2^* = +$ To answer, go to menti.com and enter 5115 8817.

Follow along with the demo by clicking the code link on th	e
course website next to Lecture 9.	

# **Interpreting weights**

#### **Discussion Question**

Which feature has the greatest effect on the outcome?

A) square feet: 
$$w_1^* = 16.202$$
  
B) competing stores:  $w_2^* = -5.311$ 

C) inventory: = 0.175

D) advertising: 
$$w_3^{\frac{1}{3}} = 11.526$$
  
E) district size:  $w_i^{*} = 13.580$ 

= 13.580

To answer, go to menti.com and enter 5115 8817.

#### Which features are most "important"?

- ► The most important feature is **not necessarily** the feature with largest weight.
- Features are measured in different units, scales.
  - Suppose I fit one prediction rule,  $H_1$ , with sales in dollars, and another prediction rule,  $H_2$ , with sales in thousands of dollars.
  - Sales is just as important in both prediction rules.
  - ▶ But the weight of sales in  $H_1$  will be 1000 times smaller than the weight of sales in  $H_2$ .
  - ► Intuitive explanation: 5 × 45000 = (5 × 1000) × 45.
- ► **Solution**: we should **standardize** each feature, i.e. convert each feature to standard units.

#### **Standard units**

Recall from Lecture 6: to convert a feature  $x_1, x_2, ..., x_n$  to standard units, we use the formula

$$x_i$$
 in standard units =  $\frac{x_i - \bar{x}}{\sigma_x}$ 

- Example: 1, 7, 7, 9
  - Mean: 6
  - Standard deviation:

$$\sqrt{\frac{1}{4}((-5)^2 + (1)^2 + (1)^2 + (3)^2)} = 3$$

Standardized data:

$$\frac{1-6}{3} = -\frac{5}{3}$$
,  $\frac{7-6}{3} = \frac{1}{3}$ ,  $\frac{7-6}{3} = \frac{1}{3}$ ,  $\frac{9-6}{3} = 1$ 

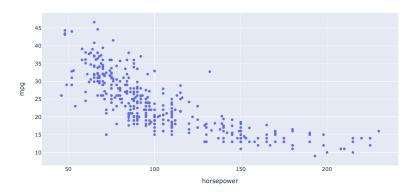
#### Standard units for multiple linear regression

- ► The result of standardizing each feature (separately!) is that the units of each feature are on the same scale.
  - There's no need to standardize the outcome (net sales), since it's not being compared to anything.
- Then, solve the normal equations. The resulting  $w_0^*, w_1^*, ..., w_d^*$  are called the **standardized regression** coefficients.
- Standardized regression coefficients can be directly compared to one another.

Let's jump back to our demo notebook.

# **Feature engineering**

MPG vs. Horsepower



**Question:** Would a linear prediction rule work well on this dataset?

#### A quadratic prediction rule

▶ It looks like there's some sort of quadratic relationship between horsepower and mpg in the last scatter plot. We want to try and fit a prediction rule of the form

$$H(x) = W_0 + W_1 x + W_2 x^2$$

- Note that this still a linear model, because it is linear in the parameters!
- We can do that, by choosing our two "features" to be  $x_i$  and  $x_i^2$ , respectively.
  - ► In other words,  $x_i^{(1)} = x_i$  and  $x_i^{(2)} = x_i^2$ .
  - More generally, we can create new features out of existing features.

#### A quadratic prediction rule

- Desired prediction rule:  $H(x) = w_0 + w_1 x + w_2 x^2$ .
- The resulting design matrix looks like this:

$$X = \begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ \dots & & \\ 1 & x_n & x_n^2 \end{bmatrix}$$

To find optimal parameter vector  $\vec{w}^*$ : solve the **normal** equations!

$$X^TXw^* = X^Ty$$

#### More examples

What if we want to use a prediction rule of the form  $H(x) = w_0 + w_1 x + w_2 x^2 + w_3 x^3$ ?

What if we want to use a prediction rule of the form  $H(x) = w_1 \frac{1}{x^2} + w_2 \sin x + w_3 e^x$ ?

#### **Feature engineering**

- More generally, we can create new features out of existing information in our dataset. This process is called feature engineering.
  - In this class, feature engineering will mostly be restricted to creating non-linear functions of existing features (as in the previous example).
  - In the future you'll learn how to do other things, like encode categorical information.

# **Summary**

#### **Summary**

- The normal equations can be used to solve the multiple linear regression problem, where we use multiple features to predict an outcome.
- We can interpret the parameters as weights. The signs of weights give meaningful information, but we can only compare weights if our features are standardized.
- We can create non-linear features out of existing features. This process is called feature engineering.
  - ► A prediction rule is linear as long as it is **linear in the parameters**. The features themselves don't have to be linear.

#### **Next time**

- ► A few more examples of feature engineering.
- ► A high-level overview of machine learning.
- New idea: clustering.