Lecture 12 – Multiple Linear Regression and Feature Engineering



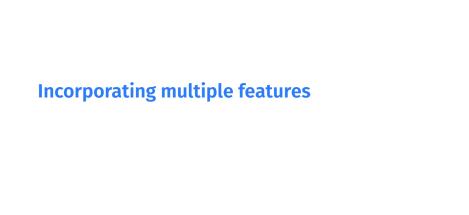
DSC 40A, Spring 2023

Announcements

- ► Homework 4 is out, due Tuesday at 11:59pm.
 - Assign pages to problems for full credit.
- Midterm 1 is next Friday during lecture.
 - Next Wednesday 7-9pm will be a mock exam and review session - save the date! No groupwork next week.
 - Formula sheet will be provided for the exam. No other notes.
 - More details coming soon.

Agenda

- Incorporating multiple features.
- Interpreting parameters.
- Feature engineering.



Last time

We minimized the mean squared error for the prediction rule $H(x) = w_0 + w_1 x$, which was

$$R_{sq}(\vec{w}) = \frac{1}{n} ||\vec{y} - X\vec{w}||^2$$

- We found that the minimizing \vec{w} satisfies the **normal** equations, $X^T X \vec{w} = X^T \vec{y}$.
 - ► If X^TX is invertible, the solution is:

$$\vec{w}^* = (X^T X)^{-1} X^T \vec{y}$$

► These same normal equations can be used to solve the multiple linear regression problem, where we use multiple features to predict an outcome. We simply need to adjust the design matrix *X*.

Multiple linear regression example

We're want to fit a linear prediction rule with two features:

$$H(\text{experience}, \text{GPA}) = w_0 + w_1(\text{experience}) + w_2(\text{GPA})$$

Collect data for each of *n* people:

Person #	Experience	GPA	Salary
1	3	3.7	85,000
2	6	3.3	95,000
3	10	3.1	105,000

We represent each person with a feature vector:

$$\vec{x}_1 = \begin{bmatrix} 3 \\ 3.7 \end{bmatrix}, \qquad \vec{x}_2 = \begin{bmatrix} 6 \\ 3.3 \end{bmatrix}, \qquad \vec{x}_3 = \begin{bmatrix} 10 \\ 3.1 \end{bmatrix}$$

Prediction rule form determines design matrix

When our prediction rule is $H(\text{experience}, \text{GPA}) = (w_0) + (w_1) \text{experience} + (w_2) \text{GPA})$

the hypothesis vector $\vec{h} \in \mathbb{R}^n$ can be written

$$\vec{h} = \begin{bmatrix} H(\text{experience}_1, \text{GPA}_1) \\ H(\text{experience}_2, \text{GPA}_2) \\ \dots \\ H(\text{experience}_n, \text{GPA}_n) \end{bmatrix} = \begin{bmatrix} 1 & \text{experience}_1 & \text{GPA}_1 \\ 1 & \text{experience}_2 & \text{GPA}_2 \\ \dots & \dots & \dots \\ 1 & \text{experience}_n & \text{GPA}_n \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix}$$

Notice that the rows of the design matrix are the (transposed) feature vectors, with an additional 1 in front.

Notation for multiple linear regression

- ► We will need to keep track of multiple¹ features for every individual in our data set.
- As before, subscripts distinguish between individuals in our data set. We have *n* individuals (or training examples).
- Superscripts distinguish between features.² We have d features.
 - \triangleright experience = $x^{(1)}$
 - $Arr GPA = x^{(2)}$

¹In practice, we might use hundreds or even thousands of features.

²Think of them as new variable names, such as new letters.

Augmented feature vectors

The augmented feature vector $Aug(\vec{x})$ is the vector obtained by adding a 1 to the front of feature vector \vec{x} :

$$\vec{X} = \begin{bmatrix} x^{(1)} \\ x^{(2)} \\ \vdots \\ x^{(d)} \end{bmatrix} \qquad \text{Aug}(\vec{X}) = \begin{bmatrix} 1 \\ x^{(1)} \\ \vdots \\ x^{(d)} \end{bmatrix} \qquad \vec{W} = \begin{bmatrix} w_0 \\ w_1 \\ \vdots \\ x^{(d)} \end{bmatrix}$$

Then, our prediction rule is

$$H(\vec{x}) = w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_d x^{(d)}$$

= $\vec{w} \cdot \text{Aug}(\vec{x})$

The general problem

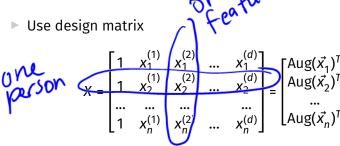
We have n data points (or training examples): $(\vec{x}_1, y_1), ..., (\vec{x}_n, y_n)$ where each \vec{x}_i is a feature vector of d features:

$$\vec{\mathbf{x}}_i = \begin{bmatrix} x_i^{(1)} \\ x_i^{(2)} \\ x_i^{(d)} \\ \dots \\ x_i^{(d)} \end{bmatrix}$$

We want to find a good linear prediction rule:

$$\begin{split} H(\vec{x}) &= w_0 + w_1 x^{(1)} + w_2 x^{(2)} + ... + w_d x^{(d)} \\ &= \vec{w} \cdot \text{Aug}(\vec{x}) \end{split}$$

The general solution



and observation vector to solve the normal equations

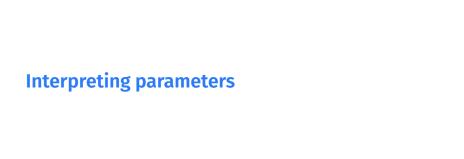
$$X^T X \vec{w}^* = X^T \vec{y}$$

to find the optimal parameter vector.

Terminology for parameters With d features, \vec{w} has d+1 entries.

- \triangleright w_0 is the bias, also known as the intercept.
- \triangleright $w_1, ..., w_d$ each give the weight, i.e. coefficient, of a feature.

$$H(\vec{x}) = W_0 + W_1 x^{(1)} + ... + W_d x^{(d)}$$



Example: predicting sales

For each of 26 stores, we have:

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net sales,
square feet,
inventory,
advertising expenditure,
district size, and
number of competing stores.
```

- Goal: predict net sales given these features
- ► To begin:

 $H(\text{square feet, competitors}) = \underline{w_0} + \underline{w_1}(\text{square feet}) + \underline{w_2}(\text{competitors})$

Example: predicting sales

$$H(\text{square feet, competitors}) = w_0 + w_1(\text{square feet}) + w_2(\text{competitors})$$

Discussion Question

What will be the sign of w_1^* and w_2^* ?

- a) $W_1^* = +$, $W_2^* = -$
- b) $W_1^* = +, W_2^* = +$
- d) $W_1^* = -$, $W_2^* = -$
- d) $W_1^{\frac{1}{2}} = -$, $W_2^{\frac{1}{2}} = +$

Example: predicting sales

 $H(\text{square feet, competitors}) = w_0 + w_1(\text{square feet}) + w_2(\text{competitors})$

Discussion Question

What will be the sign of w_1^* and w_2^* ?

a)
$$W_1^* = +$$
, $W_2^* = -$

b)
$$W_1^{\frac{1}{2}} = +$$
, $W_2^{\frac{1}{2}} = +$

d)
$$W_1^* = -$$
, $W_2^{-} = -$

a)
$$W_1^* = +$$
, $W_2^* = -$
b) $W_1^* = +$, $W_2^* = +$
d) $W_1^* = -$, $W_2^* = -$
d) $W_1^* = -$, $W_2^* = +$

Let's try it out ourselves. Follow along here.

Which features are most "important"?

Discussion Question

Which feature has the greatest effect on the outcome?

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a) square feet: w_1^* = 16.202
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- b) competitors: $w_2^* = -5.311$
- c) inventory: $w_2^{-1} = 0.175$
- d) advertising: $w_3^* = 11.526$ e) district size: $w_4^* = 13.580$

Which features are most "important"?

- ► The most important feature is **not necessarily** the feature with largest weight.
- Features are measured in different units, scales.
 - Suppose I fit one prediction rule, H_1 , with sales in dollars, and another prediction rule, H_2 , with sales in thousands of dollars.
 - Sales is just as important in both prediction rules.
 - ▶ But the weight of sales in H_1 will be 1000 times smaller than the weight of sales in H_2 .
 - ► Intuitive explanation: 5 × 45000 = (5 × 1000) × 45.
- ► **Solution**: before doing regression, **standardize** each feature, i.e. convert each feature to standard units.

Standard units

Recall: to convert a feature $x_1, x_2, ..., x_n$ to standard units,

we use the formula
$$x_{i} \text{ in standard units} = \frac{x_{i} - \bar{x}}{\sigma_{x}}$$
Example: 1, 7, 7, 9
Mean: $\frac{24}{4} = 6$
Standard deviation:

Example: 1, 7, 7, 9

Mean:
$$\frac{24}{4} = 6$$

Standard deviation: $\frac{1}{4} = \frac{1}{4} = \frac$

Standardized data: $\sqrt{ar} = 9 \implies \text{SD} = \sqrt{9}$, ===== s.u., 9-6

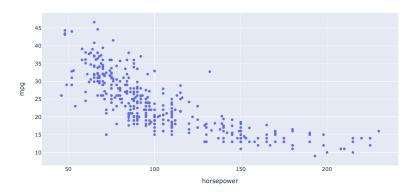
Standard units for multiple linear regression

- ► The result of standardizing each feature (separately!) is that the units of each feature are on the same scale.
 - There's no need to standardize the outcome (net sales), since it's not being compared to anything.
- Then, solve the normal equations. The resulting $w_0^*, w_1^*, ..., w_d^*$ are called the **standardized regression** coefficients.
- Standardized regression coefficients can be directly compared to one another.

Let's try it out in our demo notebook.

Feature engineering

MPG vs. Horsepower



Question: Would a linear prediction rule work well on this dataset?

A quadratic prediction rule

▶ It looks like there's some sort of quadratic relationship between horsepower and mpg in the last scatter plot. We want to try and fit a prediction rule of the form

$$H(x) = w_0 + w_1 x + w_2 x^2$$

- Note that while this is quadratic in horsepower, it is linear in the parameters!
- We can do that, by choosing our two "features" to be x_i and x_i^2 , respectively.
 - ► In other words, $x_i^{(1)} = x_i$ and $x_i^{(2)} = x_i^2$.
 - More generally, we can create new features out of existing features.

A quadratic prediction rule

- Desired prediction rule: $H(x) = w_0 + w_1 x + w_2 x^2$.
- The resulting design matrix looks like this:

$$X = \begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ \dots & & \\ 1 & x_n & x_n^2 \end{bmatrix}$$

To find optimal parameter vector \vec{w}^* : solve the **normal** equations!

$$X^TXw^* = X^Ty$$

More examples

What if we want to use a prediction rule of the form $H(x) = w_0 + w_1 x + w_2 x^2 + w_3 x^3$?

What if we want to use a prediction rule of the form $H(x) = w(\frac{1}{x^2}) + w_2 \sin x + w_3 e^{x^2}$?

$$\begin{bmatrix}
\frac{1}{\chi_1^2} & \sin \chi, & e^{\chi_1} \\
\frac{1}{\chi_2^2} & \sin \chi, & e^{\chi_2}
\end{bmatrix}
\begin{bmatrix}
w_1 \\
w_2 \\
w_3
\end{bmatrix}$$

Feature engineering

- More generally, we can create new features out of existing information in our dataset. This process is called feature engineering.
 - In this class, feature engineering will mostly be restricted to creating non-linear functions of existing features (as in the previous example).
 - In the future you'll learn how to do other things, like encode categorical information.

Summary

Summary

- The normal equations can be used to solve the multiple linear regression problem, where we use multiple features to predict an outcome.
- We can interpret the parameters as weights. The signs of weights give meaningful information, but we can only compare weights if our features are standardized.
- We can create non-linear features out of existing features. This process is called feature engineering.
 - ▶ A prediction rule only needs to be a linear function of the parameters for us to use linear regression. It does not need to be a linear function of the features.